CSC 226

Algorithms and Data Structures: II
Prims
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ECS 466

Two basic properties for minimum spanning trees

- Cycle property
- Cut property

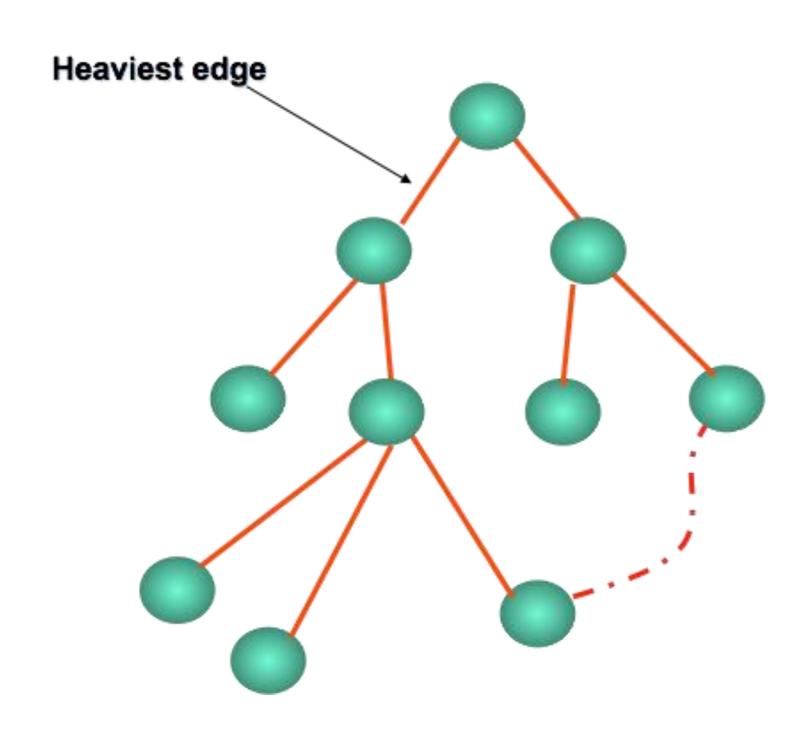
Cycle property

- Let C be any cycle in weighted graph G with distinct edge weights. Let e be the heaviest edge in the cycle.
- Then the minimum spanning tree for *G* does not contain *e*.

Proof. (Cycle property)

- Assume that all edges in the graph are of distinct weight
- We proof by contradiction: the MST T for G does not contain edge e
- Assume e does belong to MST T. Then deleting e from T disconnects T into two trees, T_1 and T_2 .
- Consider cycle C. C consists of some vertices that belong to T_1 and the other vertices of C belong to T_2 .
- There is an edge in C, say f, that connects a vertex from T_1 to a vertex T_2 .
- Merge T_1 and T_2 using f to spanning tree T^* . The new tree, T^* , is lighter than T. A contradiction.

Cycle property



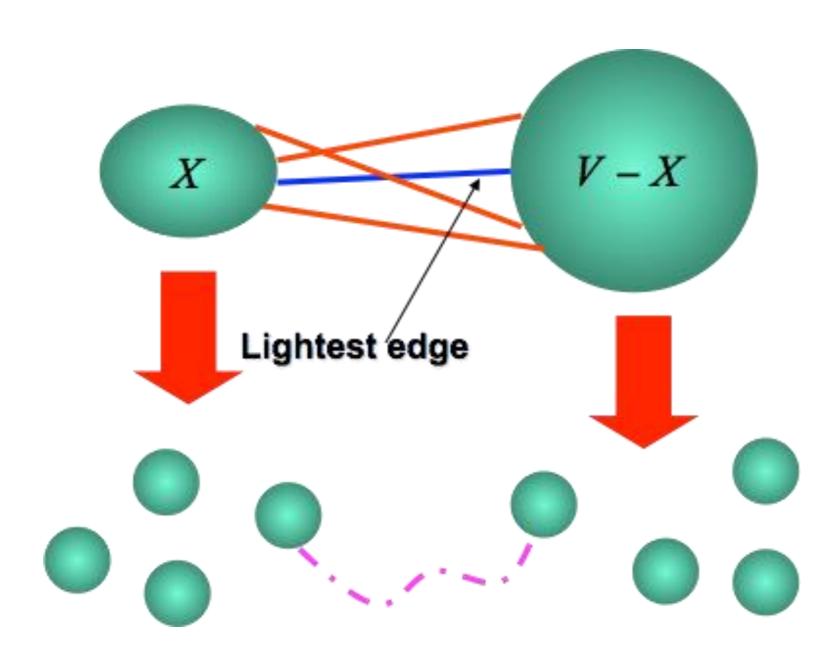
Cut Property

- Let V' be any proper subset of vertices in weighted graph G = (V, E), and let e be the lightest edge that has exactly one endpoint in V'
- Then the minimum spanning tree T for G contains e.

Proof (Cut property)

- Assume that all edges in the graph are of distinct weight
- We prove by contradiction: MST T for G contains edge e
- Assume it does not
- Add e to T creating cycle C
- Consider edge f in C that has exactly one endpoint in V'
- Create spanning tree T* by replacing e with f, but T* is lighter than T. Contradiction.

Cut Property



Prim's Algorithm Correctness

Initialize tree with single chosen vertex

Cut property

- Grow tree by finding lightest edge not yet in tree and expanding the tree, and connect it to tree; repeat until all vertices are in the tree
- Example of greedy algorithm

Pseudocode: Prim's Algorithm

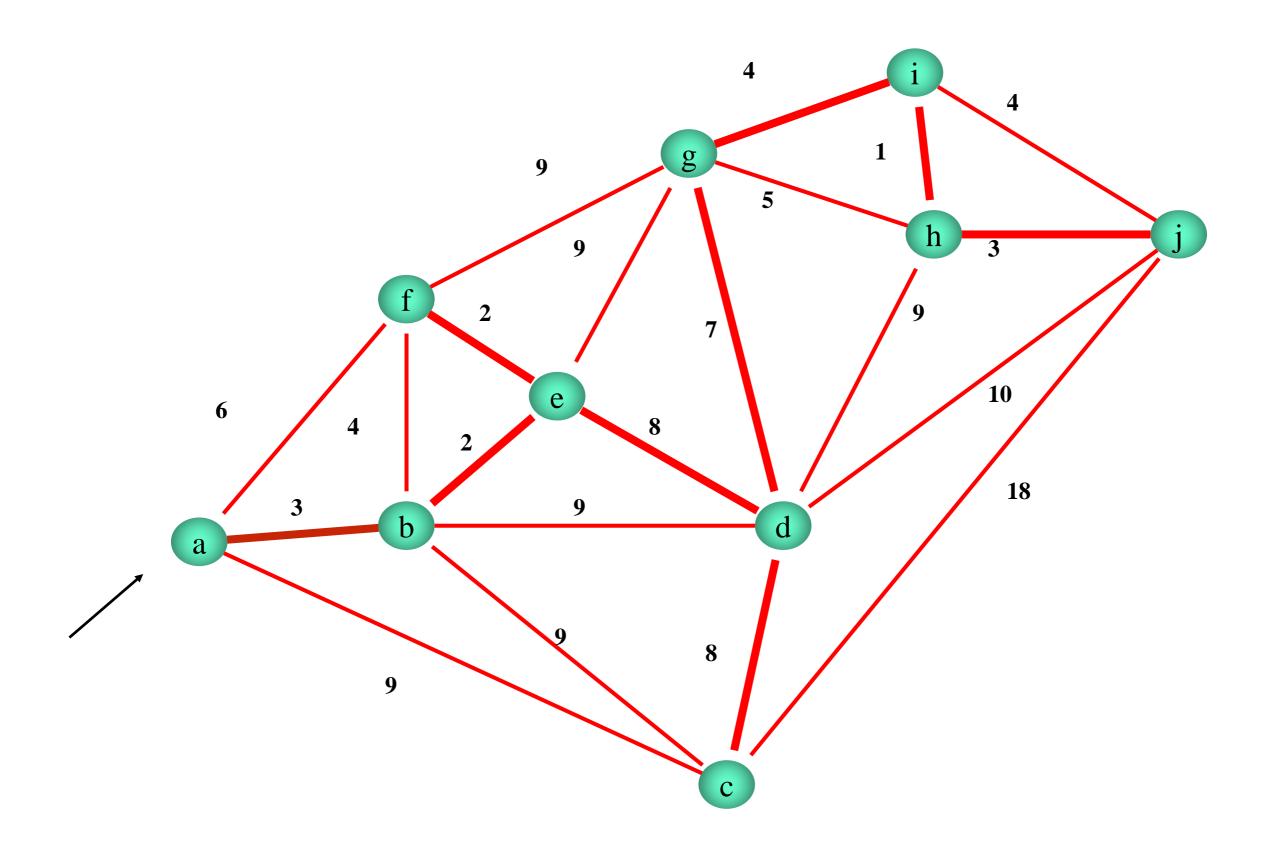
```
Input: a weighted connected graph G = (V, E)
Output: an MST T for G
Data structure: array D; Priority Queue PQ; and tree T
pick an arbitrary vertex v in G; D[v] \leftarrow 0
for each vertex u \neq v do D[u] \leftarrow +\infty end
T \leftarrow \emptyset
for each vertex u do PQ.insert(\{(u, (null), D[u]\}) end // including v
// for each vertex u, (u, edge) is the element and D[u] is the key in PQ
while not PQ.empty() do
  (u, e) \leftarrow PQ.deleteMin()
  add vertex u and edge e to T
  for each vertex z adjacent to u such that z is in PQ do
    if weight((u, z) < D[z] then
      D[z] \leftarrow \mathsf{weight}((u, z))
      in PQ, change element and key of z to \{z, (u, z), D[z]\}
      update PQ
    end
  end
end
```

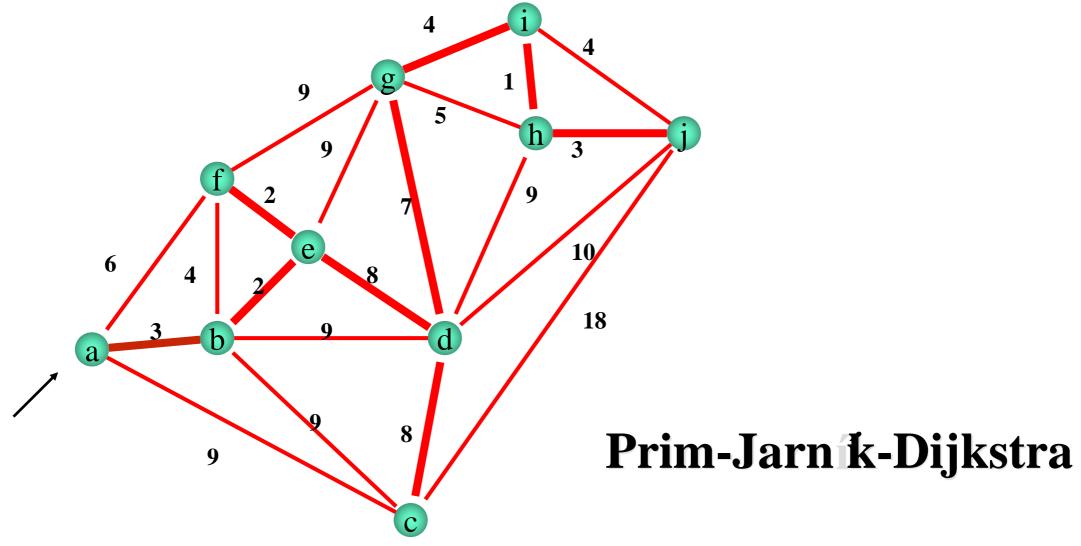
Algorithm Prim-Jarník-Dijkstra

return T

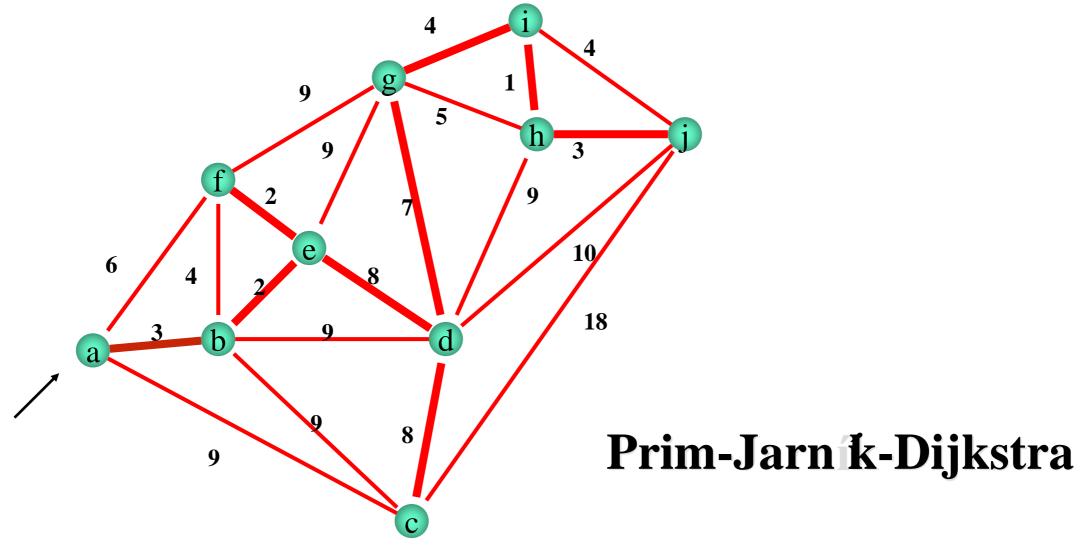
D:distance vector, maintains reachable vertices

PQ: a priority queue for the edges according to values in D

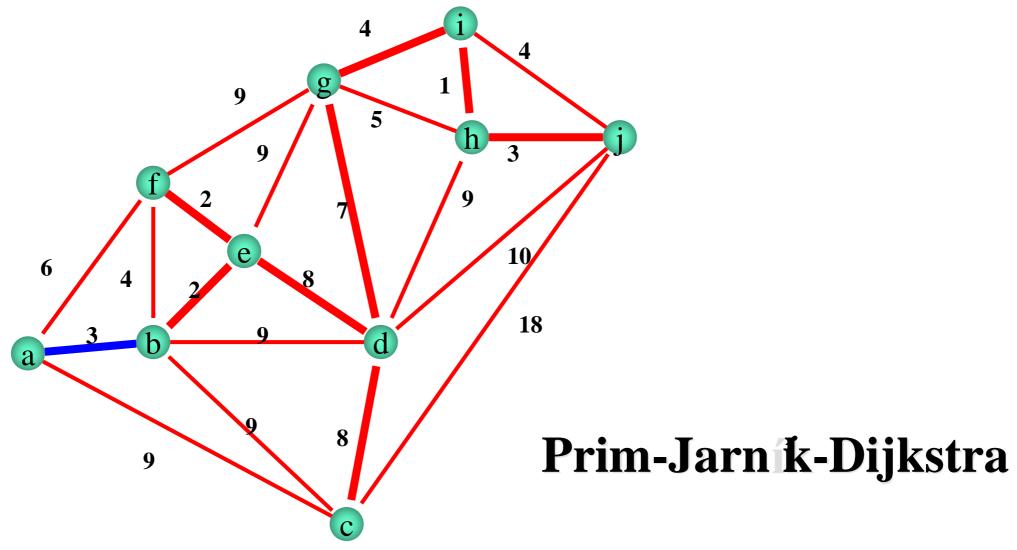




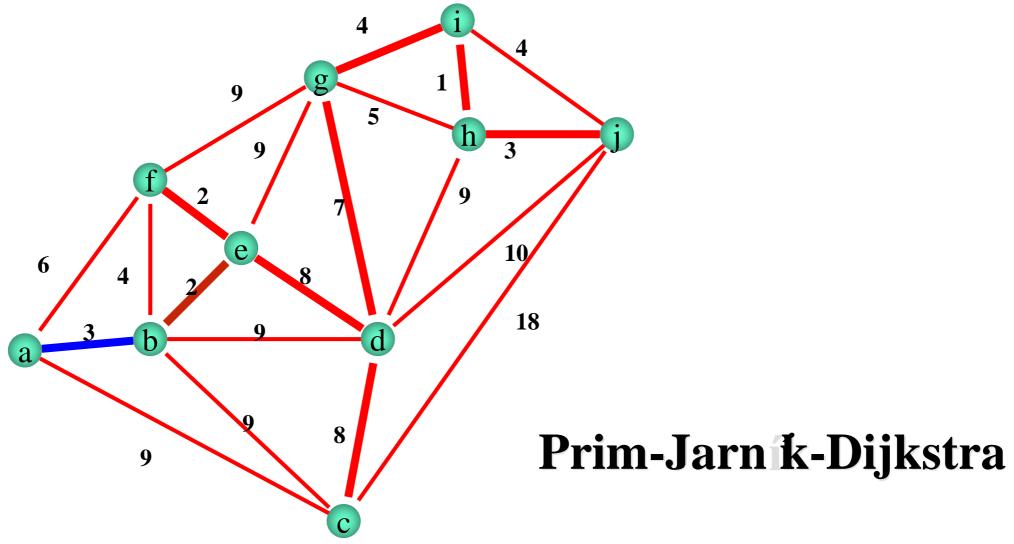
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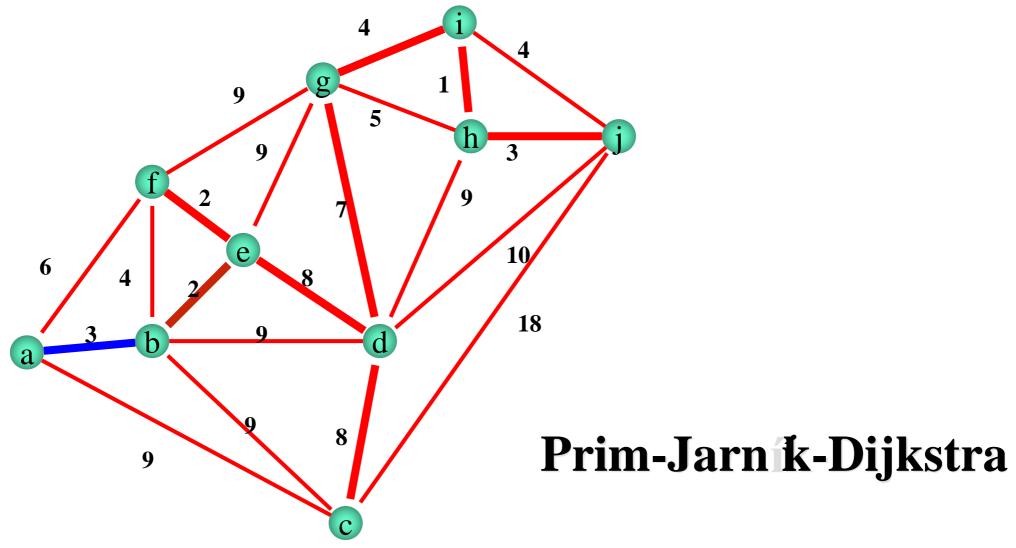
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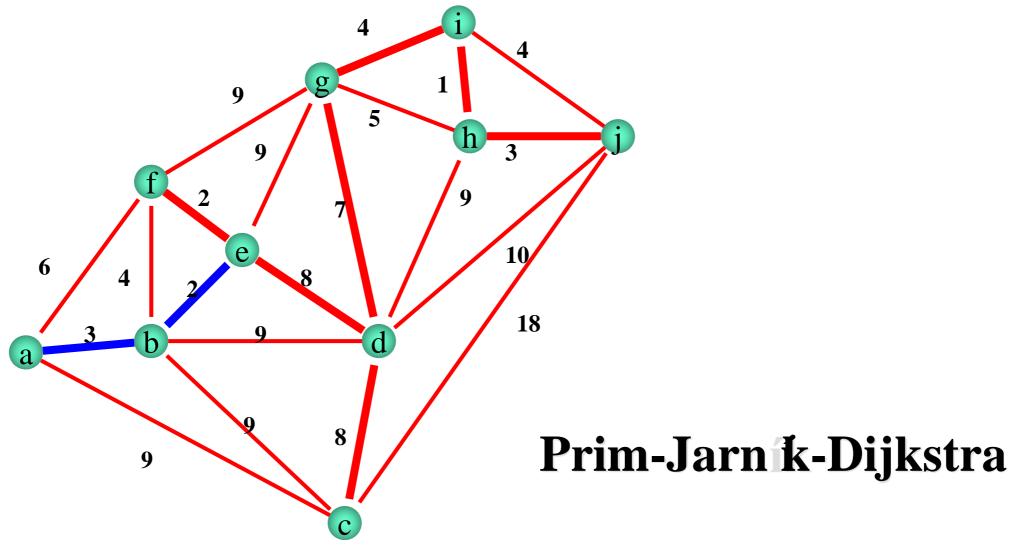
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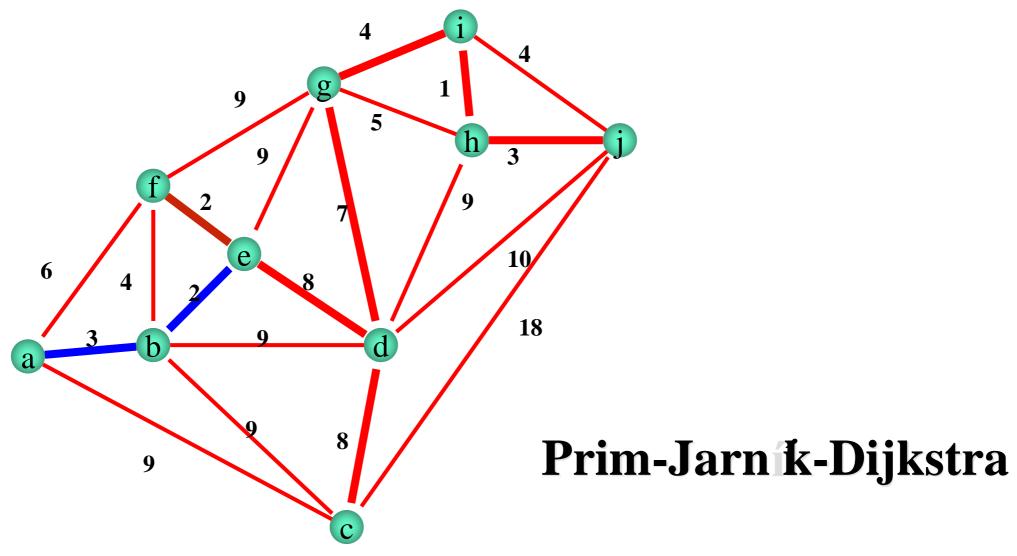
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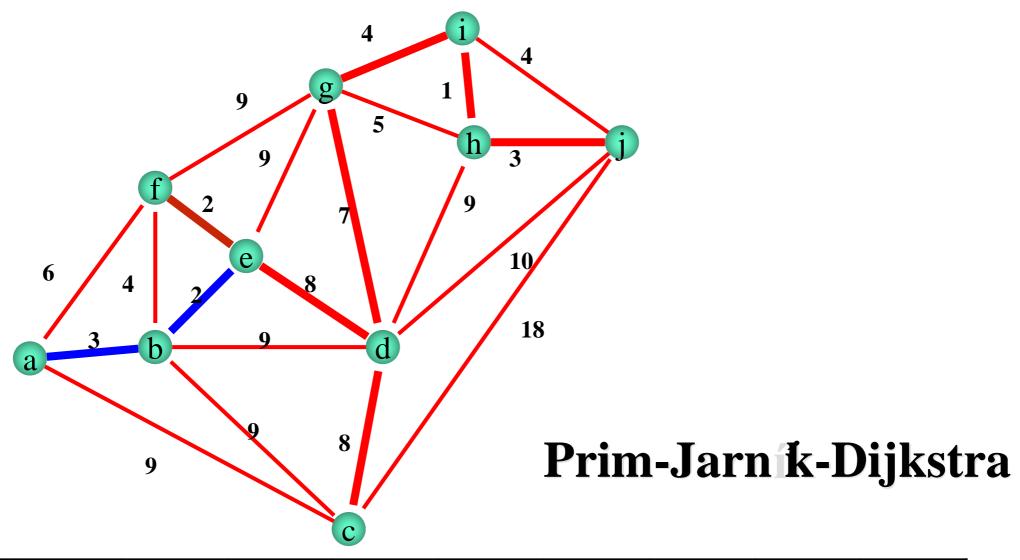
a	b	С	d	e	f	g	h	i	j
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0	3	9	9	2	4	+∞	+∞	+∞	+∞



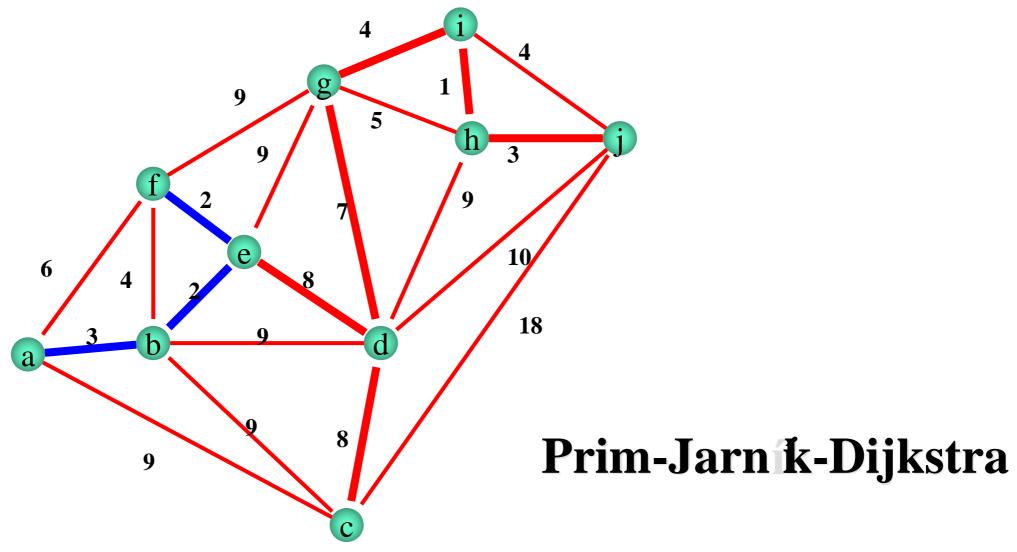
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0	3	9	9	2	4	+∞	+∞	+∞	$+\infty$



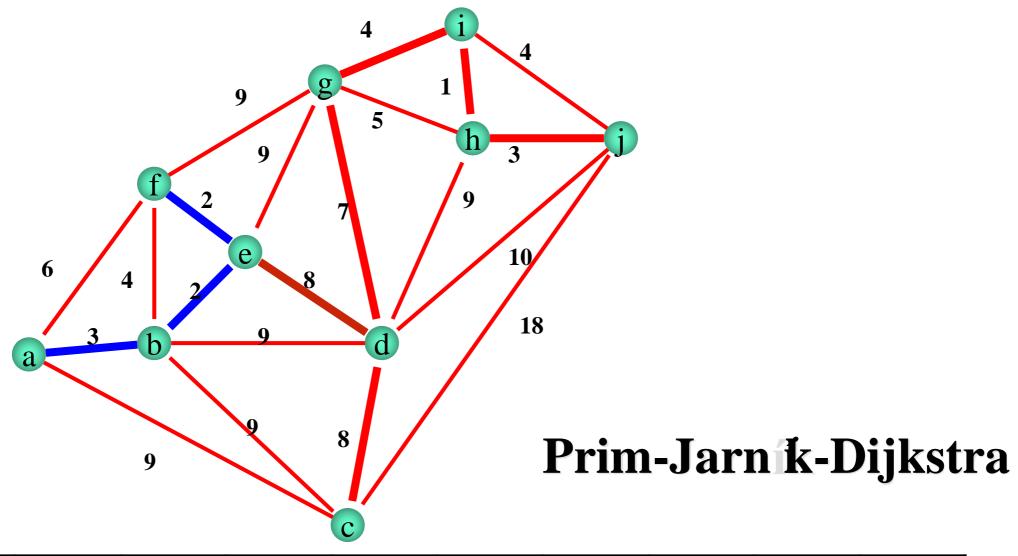
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0	3	9	8	2	2	9	+∞	+∞	+∞



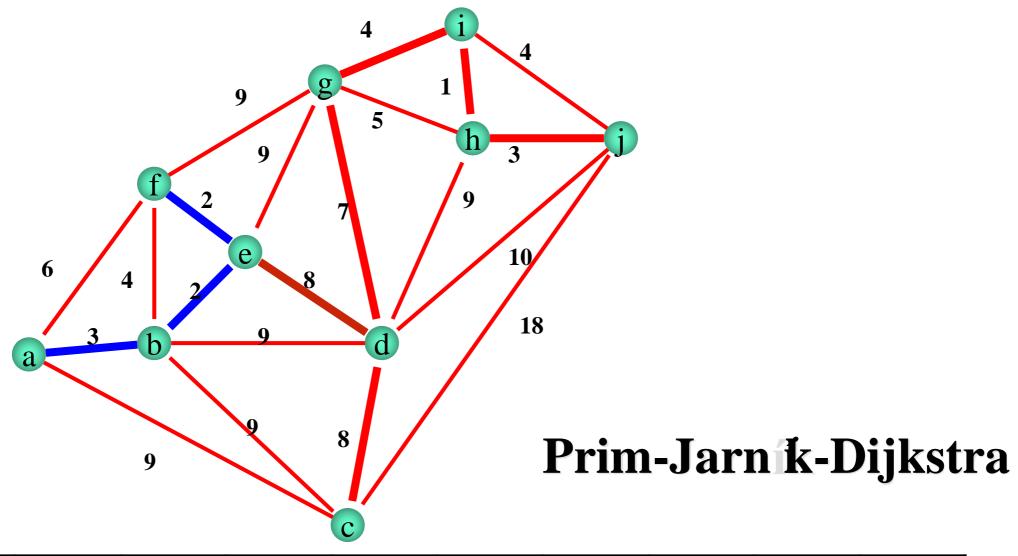
a	b	С	d	e	f	g	h	i	j
0	3	9	+∞	+∞	6	+∞	+∞	+∞	+∞
0	3	9	9	2	4	+∞	+∞	+∞	+∞
0	3	9	8	2	2	9	+∞	+∞	+∞



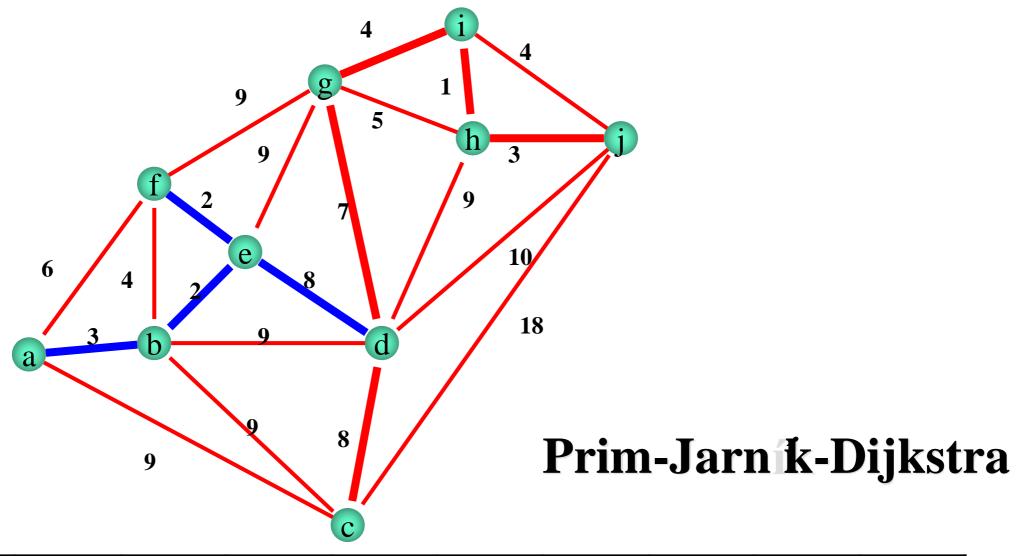
a	b	С	d	e	f	g	h	i	j
0	3	9	+∞	+∞	6	+∞	+∞	+∞	+∞
0	3	9	9	2	4	+∞	+∞	+∞	$+\infty$
0	3	9	8	2	2	9	+∞	+∞	$+\infty$



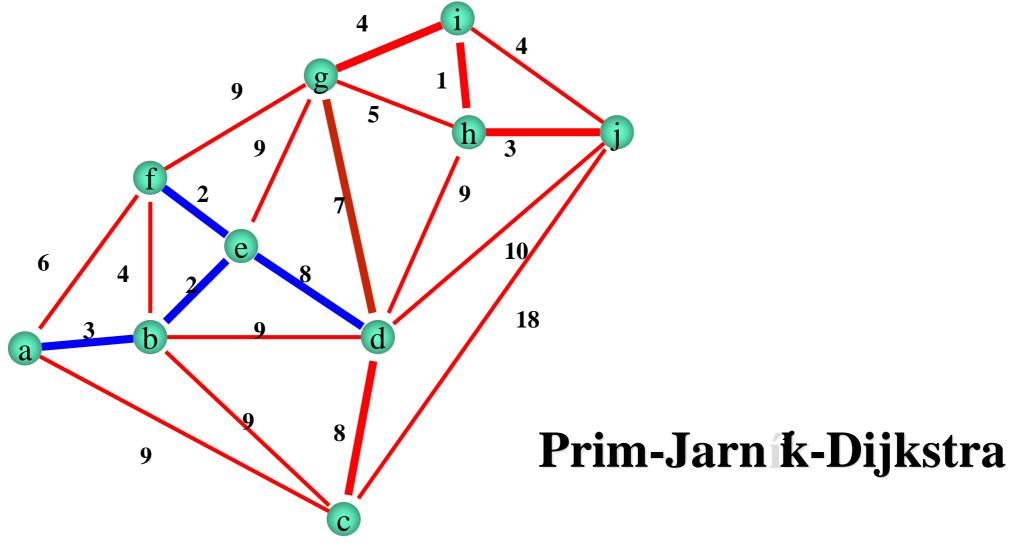
a	b	С	d	e	f	g	h	i	j
0	3	9	+∞	+∞	6	+∞	+∞	+∞	$+\infty$
0	3	9	9	2	4	+∞	+∞	+∞	$+\infty$
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0	3	9	8	2	2	9	+∞	+∞	+∞



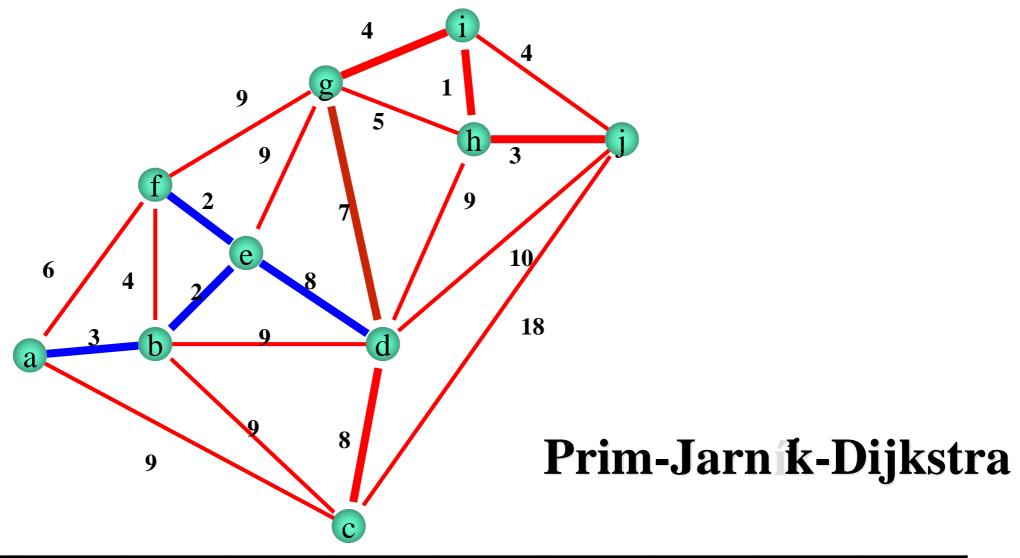
a	b	С	d	e	f	g	h	i	j
0	3	9	+∞	+∞	6	+∞	+∞	+∞	+∞
0	3	9	9	2	4	+∞	+∞	+∞	+∞
0	3	9	8	2	2	9	+∞	+∞	+∞
0	3	9	8	2	2	9	+∞	+∞	+∞



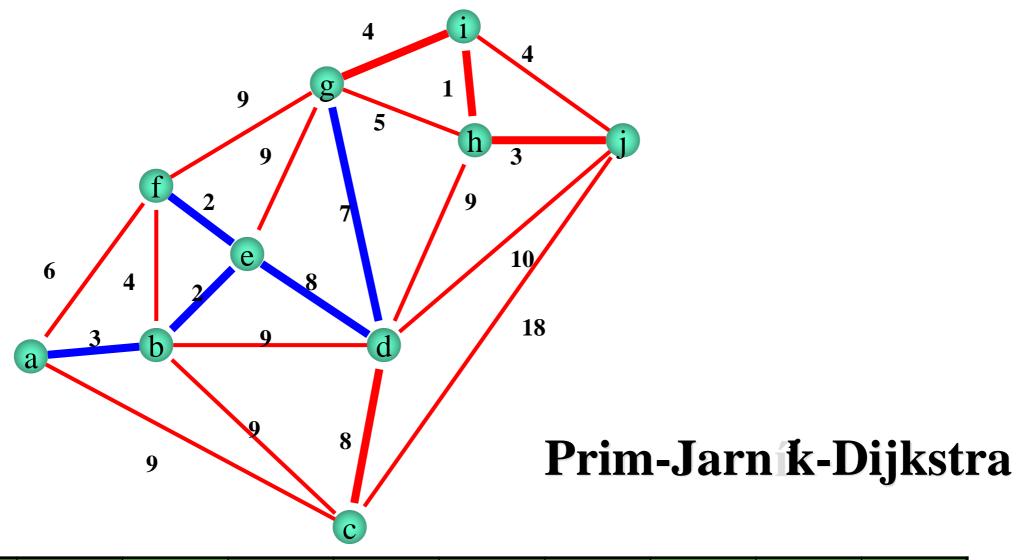
a	b	С	d	e	f	g	h	i	j
0	3	9	+∞	+∞	6	+∞	+∞	+∞	+∞
0	3	9	9	2	4	+∞	+∞	+∞	+∞
0	3	9	8	2	2	9	+∞	+∞	+∞
0	3	9	8	2	2	9	+∞	+∞	+∞



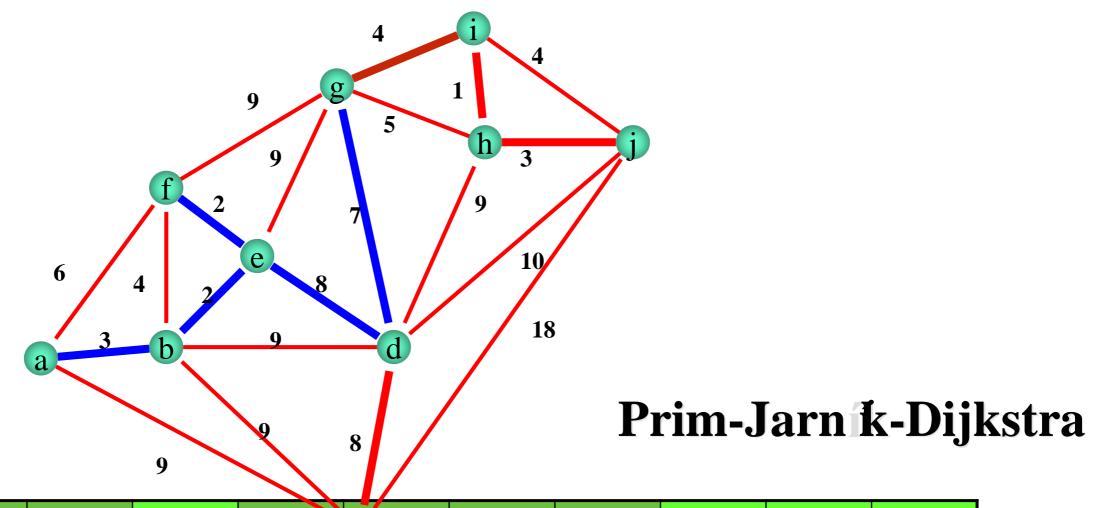
a	b	С	d	e	f	g	h	i	j
0	3	9	+∞	$+\infty$	6	+∞	+∞	$+\infty$	+∞
0	3	9	9	2	4	+∞	+∞	$+\infty$	$+\infty$
0	3	9	8	2	2	9	+∞	$+\infty$	+∞
0	3	9	8	2	2	9	9	$+\infty$	+∞
0	3	8	8	2	2	7	9	+∞	10



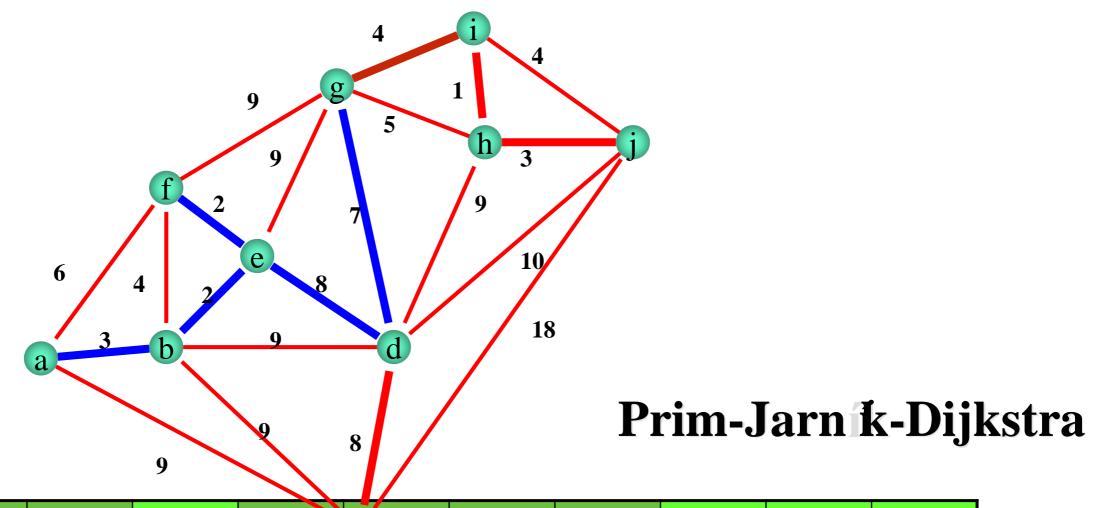
a	b	С	d	e	f	g	h	i	j
0	3	9	+∞	+∞	6	+∞	+∞	+∞	+∞
0	3	9	9	2	4	+∞	+∞	+∞	$+\infty$
0	3	9	8	2	2	9	+∞	+∞	$+\infty$
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0	3	8	8	2	2	7	9	+∞	10



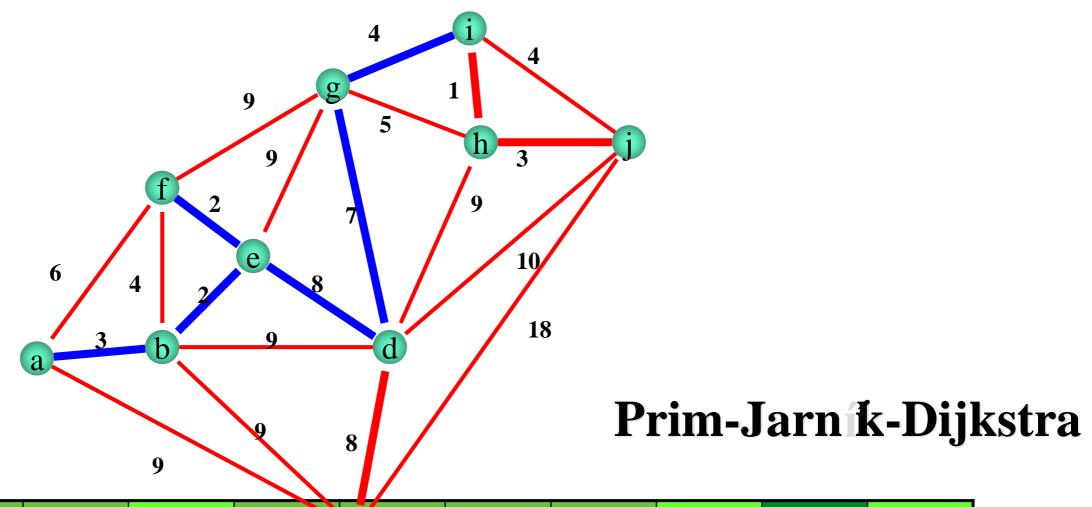
a	b	С	d	e	f	g	h	i	j
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0	3	9	9	2	4	+∞	+∞	+∞	+∞
0	3	9	8	2	2	9	+∞	+∞	+∞
0	3	9	8	2	2	9	9	+∞	+∞
0	3	8	8	2	2	7	9	+∞	10



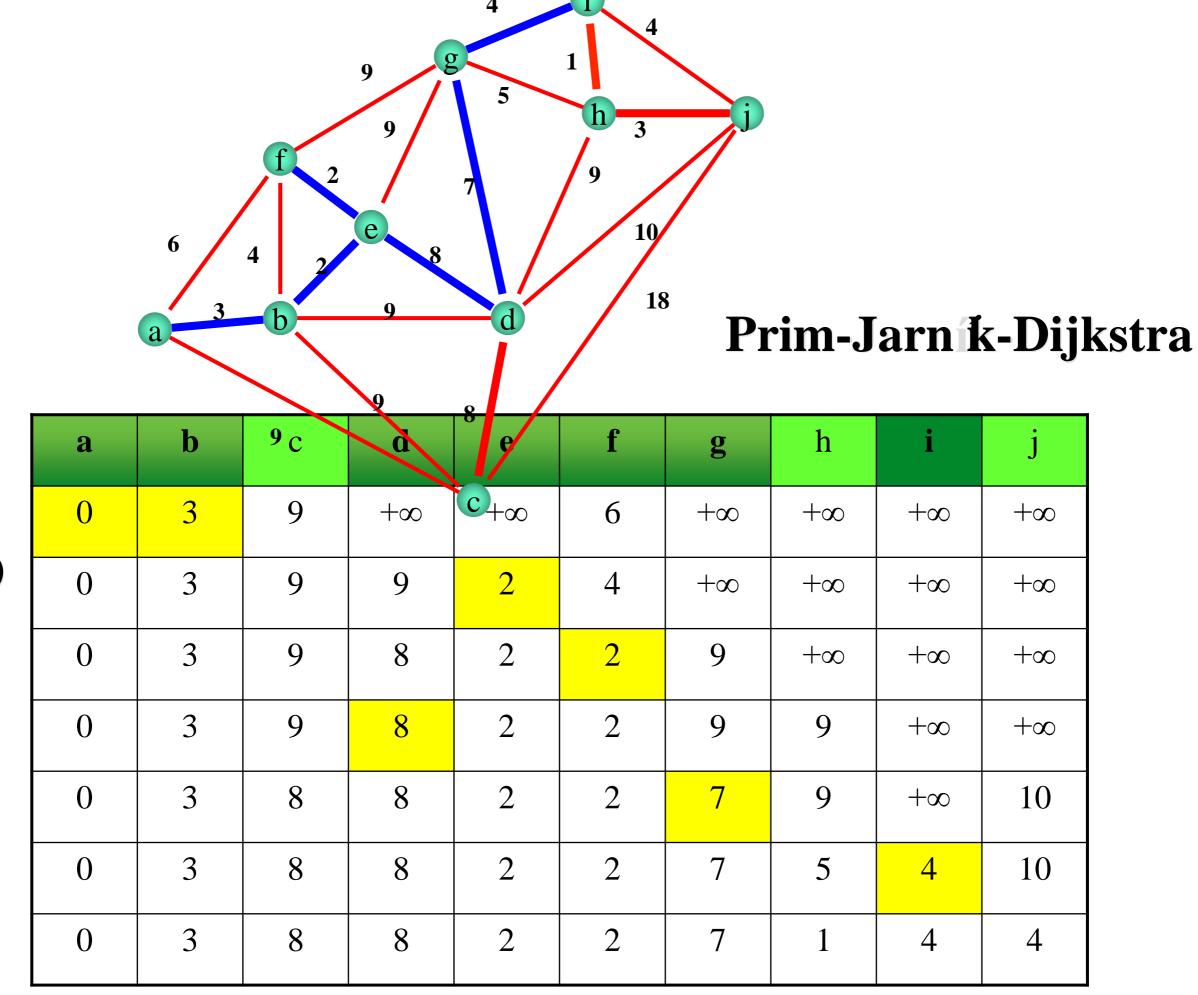
a	b	c	d	c e	f	g	h	i	j
0	3	9	+∞	+∞	6	+∞	+∞	+∞	+∞
0	3	9	9	2	4	+∞	$+\infty$	+∞	+∞
0	3	9	8	2	2	9	+∞	+∞	+∞
0	3	9	8	2	2	9	9	+∞	+∞
0	3	8	8	2	2	7	9	+∞	10
0	3	8	8	2	2	7	5	4	10

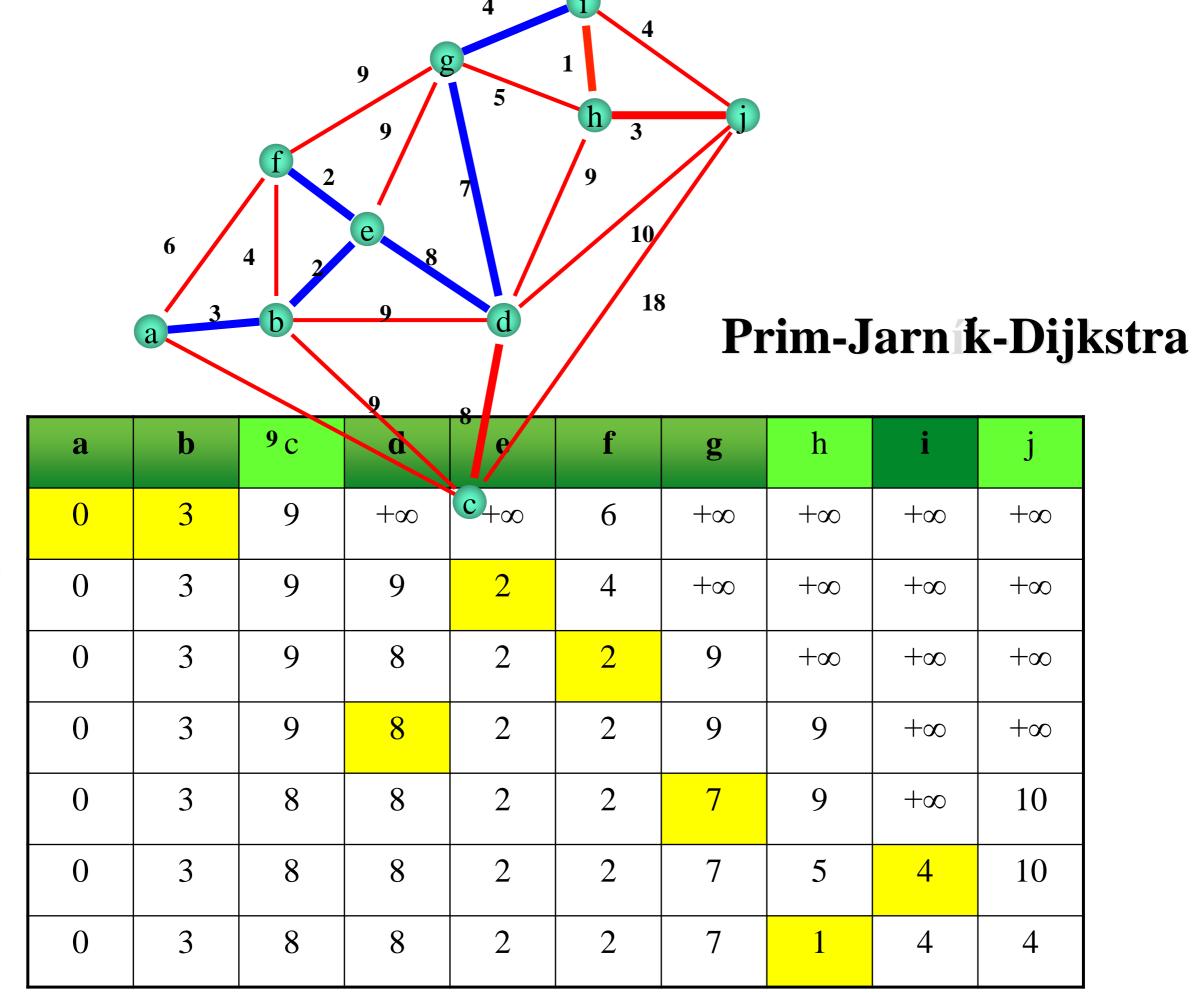


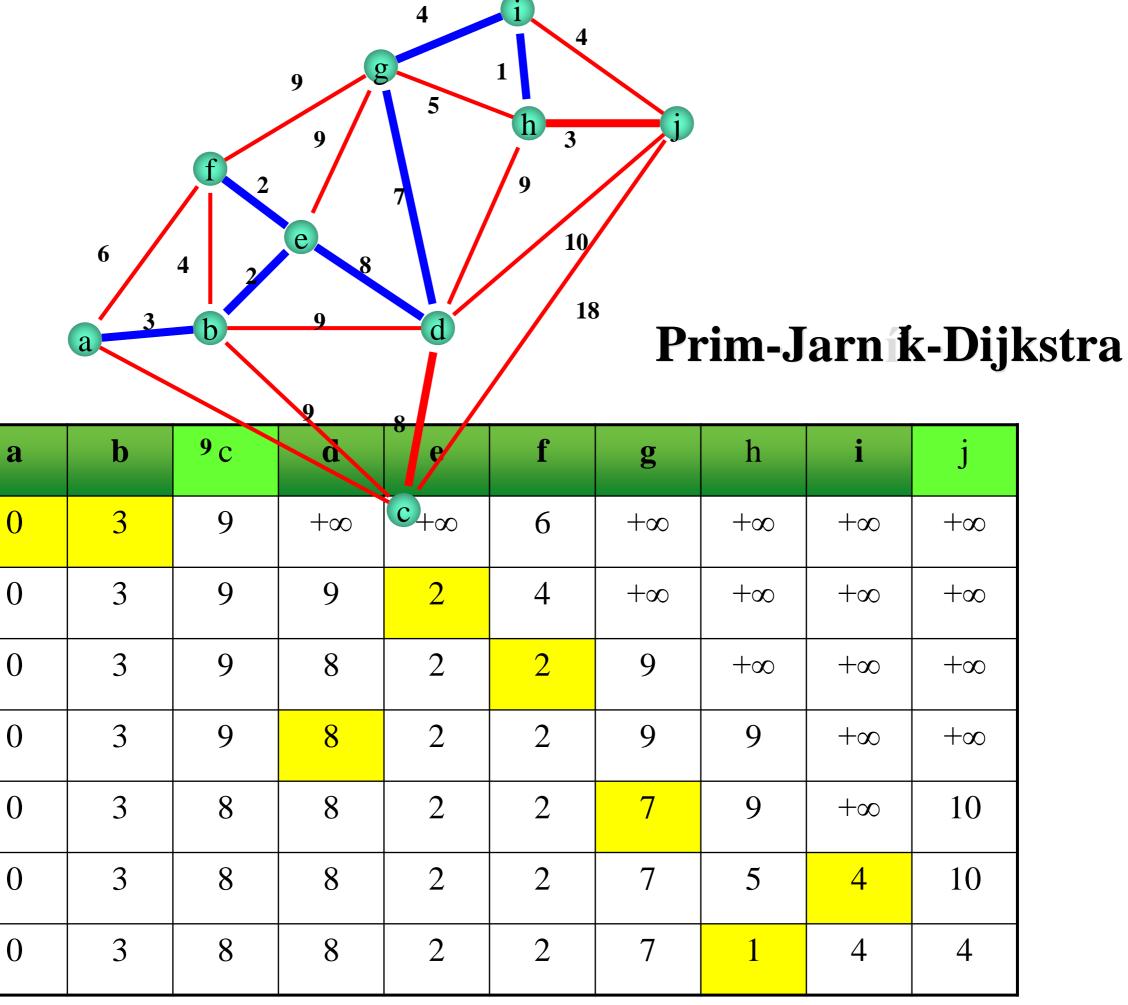
a	b	С	d	c e	f	g	h	i	j
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0	3	9	9	2	4	+∞	+∞	+∞	+∞
0	3	9	8	2	2	9	+∞	+∞	+∞
0	3	9	8	2	2	9	9	+∞	+∞
0	3	8	8	2	2	7	9	+∞	10
0	3	8	8	2	2	7	5	4	10



a	b	С	d	d c e		g	h	i	j
0	3	9	+∞	+∞	6	+∞	+∞	+∞	+∞
0	3	9	9	2	4	+∞	+∞	+∞	+∞
0	3	9	8	2	2	9	$+\infty$	+∞	+∞
0	3	9	8	2	2	9	9	+∞	+∞
0	3	8	8	2	2	7	9	+∞	10
0	3	8	8	2	2	7	5	4	10







Prim-Jarník-Dijkstra h a g 0 a $+\infty$ $+\infty$ $+\infty$ $+\infty$ $+\infty$ $+\infty$ 9 8 $+\infty$ $+\infty$ $+\infty$ $+\infty$ $+\infty$ $+\infty$ $+\infty$ $+\infty$ $+\infty$ $+\infty$

Prim-Jarník-Dijkstra h a g 0 a $+\infty$ $+\infty$ $+\infty$ $+\infty$ $+\infty$ $+\infty$ 9 8 $+\infty$ $+\infty$ $+\infty$ $+\infty$ $+\infty$ $+\infty$ $+\infty$ $+\infty$ $+\infty$ $+\infty$

9 g 1 1 3 9 Prim-Jarník-Dijkst											
a	b 4	2c e	84	e	10/f 18	g	h	i	j		
0 a	3	9	+∞	$d + \infty$	6	+∞	+∞	+∞	+∞		
0	3 9	9 9	9 8	/2	4	+∞	+∞	+∞	+∞		
0	3	9	8 c	2	2	9	+∞	+∞	+∞		
0	3	9	8	2	2	9	9	+∞	+∞		
0	3	8	8	2	2	7	9	+∞	10		
0	3	8	8	2	2	7	1	4	4		
0	3	8	8	2	2	7	1	4	4		
0	3	8	8	2	2	7	1	4	3		
0	3	8	8	2	2	7	1	4	3		

Pseudocode: Prim's Algorithm

```
Input: a weighted connected graph G = (V, E)
Output: an MST T for G
Data structure: array D; Priority Queue PQ; tree T
pick an arbitrary vertex v in G; D[v] \leftarrow 0
for each vertex u \neq v do D[u] \leftarrow +\infty end
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      in PQ, change element and key of z to \{z, (u,z), D[z]\}
      update PQ
    end
  end
end
```

Algorithm Prim-Jarník-Dijkstra

return T

D: distance vector, maintains reachable vertices

PQ: priority queue (heap) for the edges, according to their values in D

Prim-Jarník Time Complexity

Theorem. The Prim-Jarník algorithm constructs a minimum spanning tree for a connected weighted graph G = (V, E) with n vertices and m edges in $O(m \log(n))$ time.

Prim's algorithm: eager implementation

```
public class PrimMST {
                                              // shortest edge from tree to vertex
   private Edge[] edgeTo;
                                              // distTo[w] = edgeTo[w].weight()
   private double[] distTo;
                                              // true if v in mst
   private boolean[] marked;
                                             // eligible crossing edges
   private IndexMinPQ<Edge> pq;
    public PrimMST(WeightedGraph G) {
        edgeTo = new Edge[G.V()];
        distTo = new double[G. V()];
        marked = new boolean[G.V()];
        for (int v = 0; v < G.V(); v++)
              distTo[v] = Double.POSITIVE INFINITY;
        pq = new IndexMinPQ<Double>(G.V());
        distTo[0] = 0.0;
                                                                              assume G is connected
        pq. insert (0, 0.0);
        while(!pq.isEmpty())
                                                                                 repeatedly delete the
                visit(G, pq.delMin());
                                                                            min weight edge e = v-w from PQ
```

Prim's algorithm: eager implementation

```
private void visit(WeightedGraph G, int v) {
   marked[v] = true;
                                                                                          add v to T
   for (Edge\ e\ :\ G.\ adj(v)) {
                                                                                  for each edge e = v-w, add to
      int w = e.other(v);
                                                                                      PQ if w not already in T
      if (marked[w]) continue;
      if (e.weight() < distTo[w]) {</pre>
            edgeTo[w] = e;
                                                                                     add edge e to tree
            distTo[w] = e.weight();
            if (pq.contains(w)) pq.changeKey(w, distTo[w]);
                                                                                   Update distance to w or
            else pq.insert(w, distTo[w]);
                                                                                     Insert distance to w
public Iterable < Edge > edges () {
                                                                                       Create the mst
   Queue < Edge > mst = new Queue < Edge > ();
   for (int v = 0; v < edgeTo.length; <math>v++)
      Edge e = edgeTo[v];
      if (e != null) {
         mst.enqueue(e);
   return mst; }
```