

### Brouwer Fixed Point Theorem

Now, we introduce some interesting results and prove some special cases using the fact that  $S^1$  is not contractible.

**Theorem 3.133** (No retraction). *There is no retraction  $D^n \rightarrow S^{n-1}$  for  $n \geq 1$ .*

*Proof.* We prove the case when  $n = 2$ . Suppose there is a retraction  $r : D^2 \rightarrow S^1$ . Then, we define  $H : S^1 \times I \rightarrow S^1$  as follows:

$$H(x, t) = r(tx).$$

Then,  $H(x, 0) = r(0)$  is a constant map and  $H(x, 1) = r(x) = x$ . So  $H$  is a homotopy from the identity map on  $S^1$  to a constant map. This contradicts Lemma 3.130.  $\square$

*Proof.* If  $r : D^n \rightarrow S^{n-1}$  were a retraction, compose any map  $S^{n-1} \rightarrow D^n$  extending  $\text{id}_{S^{n-1}}$  with  $r$  to obtain a fixed-point-free self map of  $D^n$ , contradicting Brouwer.  $\square$

**Corollary 3.134** (Brouwer Fixed Point). *For every  $n \geq 1$ , any continuous map  $F : D^n \rightarrow D^n$  has a fixed point, i.e. there exists  $x \in D^n$  with  $F(x) = x$ .*

*Proof.* Assume  $F$  has no fixed point. For each  $x \in D^n$  draw the ray starting at  $F(x)$  through  $x$  and let  $r(x)$  be the first intersection of that ray with  $S^{n-1} = \partial D^n$ . This gives a continuous map  $r : D^n \rightarrow S^{n-1}$  which restricts to the identity on  $S^{n-1}$ , hence a retraction. But  $S^{n-1}$  is not a retract (indeed not a deformation retract) of  $D^n$  (proved earlier using homotopy ideas). Contradiction.  $\square$

### Homotopy equivalence = embedding + retraction

If there is one thing that you need to remember, that is homotopy equivalence is basically embedding + retraction.

First of all, we introduce the notion of embeddings.

**Definition 3.135** (Embedding). A continuous map  $f : X \rightarrow Y$  is an *embedding* if it is a homeomorphism onto its image  $f(X)$  (with the subspace topology inherited from  $Y$ ). In particular,  $f$  is injective.

**Definition 3.136.** Let  $X$  and  $Y$  be two disjoint topological spaces. Then, the *disjoint union* of  $X$  and  $Y$  is the topological space

$$X \sqcup Y$$

whose underlying set is the disjoint union of sets  $X$  and  $Y$  and whose topology is given by

$$U \subseteq X \sqcup Y \text{ is open} \iff U \cap X \text{ is open in } X \text{ and } U \cap Y \text{ is open in } Y.$$

Equivalently, the topology is given by

$$\tau_{X \sqcup Y} = \{U \sqcup V \mid U \in \tau_X, V \in \tau_Y\}.$$

**Definition 3.137** (Mapping cylinder). Given a continuous map  $f : X \rightarrow Y$ , the *mapping cylinder* of  $f$  is

$$M_f = (X \times [0, 1]) \sqcup Y / \sim$$

where  $(x, 1) \sim f(x)$  for all  $x \in X$ . Write  $[x, t]$  for the class of  $(x, t)$  and  $[y]$  for  $y \in Y$ . There are canonical embeddings

$$i_X : X \hookrightarrow M_f, \quad x \mapsto [x, 0], \quad \text{and} \quad i_Y : Y \hookrightarrow M_f, \quad y \mapsto [y].$$

There is a deformation retraction  $H : M_f \times I \rightarrow M_f$  onto  $i_Y(Y)$  given by  $H([x, t], s) = [x, (1-s)t + s]$  and  $H([y], s) = [y]$ , so  $M_f$  deformation retracts onto  $Y$ .

**Lemma 3.138.** *For any continuous map  $f : X \rightarrow Y$ , the map  $H : M_f \times I \rightarrow M_f$  defined by  $H([x, t], s) := [x, (1-s)t + s]$  and  $H([y], s) := [y]$  is a deformation retraction of  $M_f$  onto  $i_Y(Y)$ .*

**Lemma 3.139.**  *$f : X \rightarrow Y$  is a homotopy equivalence if and only if  $i_X(X)$  is a deformation retract of  $M_f$ .*

**Theorem 3.140** (Common deformation–retract envelope). *For topological spaces  $X$  and  $Y$ , the following are equivalent:*

1.  $X$  and  $Y$  are homotopy equivalent.
2. There exists a space  $Z$  and embeddings  $i_X : X \hookrightarrow Z$ ,  $i_Y : Y \hookrightarrow Z$  such that  $i_X(X)$  and  $i_Y(Y)$  are each deformation retracts of  $Z$  (possibly via two different homotopies).

*Proof.* (2)  $\Rightarrow$  (1): If  $Z$  deformation retracts onto  $i_X(X)$  and onto  $i_Y(Y)$ , then  $Z \simeq X$  and  $Z \simeq Y$ , hence  $X \simeq Y$  by transitivity.

(1)  $\Rightarrow$  (2): Suppose  $f : X \rightarrow Y$  is a homotopy equivalence. Form the mapping cylinder  $M_f$ , which admits deformation retractions onto  $Y$  and  $X$ .  $\square$