

Diffusion-Weighted Imaging with Learned Nonlinear Latent Space Modeling and Self-Supervised Reconstruction (DeepDWI)

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Abstract—Keep the abstract to 250 words or less.

Index Terms—Diffusion-weighted imaging, Image reconstruction, Neural network, Latent space, Self-supervised learning

I. INTRODUCTION

HIGH-dimensional magnetic resonance imaging (HD-MRI) has been an emerging and flourishing field, which has achieved substantial improvements in terms of spatiotemporal fidelity. Instead of the conventional two-dimensional static single-contrast-weighted imaging, HD-MRI acquires and reconstructs multi-dimensional information. For instance, Brown et al. [1] proposed magnetic resonance spectroscopic imaging (MRSI), which uses multiple readout gradients to acquire multiple echo images for the computation of spatially resolved metabolic distribution. Le BiHan et al. [2] proposed diffusion-weighted imaging (DWI), which utilizes spatially and angularly varying diffusion encoding gradients in combination with fast echo-planar imaging (EPI) readouts [3] to obtain multi-contrast diffusion-weighted images as a probe into tissue microstructure. Ma et al. [4] proposed magnetic resonance fingerprinting (MRF) which consists of a T_1 - and T_2 -prepared pseudo-randomized sequence to acquire time-resolved transient-state images and a Bloch-equation-based

dictionary matching algorithm [5] for simultaneous quantitative T_1 and T_2 mapping.

HD-MRI, however, conventionally requires long scan time. Advances in parallel imaging [6]–[10] and compressed sensing [11]–[13] have enabled accelerated acquisition for HD-MRI. In particular, the low-rank modeling and regularization [14] has been a powerful tool in reducing the dimensionality of high-dimensional data, which enables accelerated acquisition and high spatiotemporal-resolution reconstruction. Usually, singular value decomposition (SVD) is used to learn a truncated temporal basis function from a large-scale physics-informed dictionary [15]–[17]. The temporal basis function is then integrated with the MRI forward model, i.e. the sensitivity encoding operator [9], for joint reconstruction of the corresponding spatial basis images. In addition, low-rank regularization can be added to the joint reconstruction [18].

Beyond the low-rank technique, advanced neural networks, e.g. autoencoder [19], have been explored for HD-MRI reconstruction and proven to supply more accurate representations of high-dimensional data than SVD. Lam et al. [20], [21] proposed to first learn a denoising autoencoder (DAE) model from a physics-informed simulated dictionary and then incorporate the learned DAE model as a regularizer in iterative reconstruction. Further, Arefeen et al. [22] proposed to replace the conventional SVD-based linear subspace modeling [15] by the latent decoder model within DAE for improved T_2 -weighted image reconstruction. The capability of DAE to learn diffusion MRI models, however, is open to questions. DAE is composed of sequential fully connected layers with nonlinear activation functions. This simple architecture may fail to learn complicated functions. DWI signal is such an example. The standard diffusion tensor model [23] consists of six tensor elements, and forms DWI signals based on the multiplication of exponential functions. Moreover, DWI signals can be described with more complicated models, e.g. the ball-and-stick model [24], which involves even more parameters.

Besides learning a *prior* based on simulated data for regularization or latent space modeling, Hammernik et al. [25] and Aggarwal et al. [26] proposed supervised learning unroll reconstruction networks, which are trained by fully sampled in vivo data. Yaman et al. [27], [28] proposed the self-supervised learning unroll network without fully-sampled data, which builds upon the concept of cross-validation in machine learning. However, in the case of DWI, it is rather challenging to acquire fully-sampled data for the training of a regularization

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functional. First, fully-sampled DWI requires a longer echo train in EPI, which not only elongates the scan time but also increases off-resonance-induced geometric distortion. Second, there exists a wide range of diffusion modes, thereby requiring a larger dataset than the two-dimensional imaging scenario.

In this work, we aim to develop a generalized DWI reconstruction framework with learned nonlinear latent space modeling and self-supervised reconstruction, dubbed DeepDWI.

II. THEORY

III. METHODS

A. Learning a VAE

IV. RESULTS

V. DISCUSSION

VI. CONCLUSION

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