

Chapter 1

FDTD scheme of electromagnetic field and cold plasma current.

1.1 Update Equations

1.1.1 Maxwell's equations

$$\partial_t \mathbf{E} = \frac{1}{c^2} \nabla \times \mathbf{B} - \frac{1}{\varepsilon_0} \sum_s \mathbf{J}_s - \mathbf{J}_{ext} \quad (1.1)$$

$$\partial_t \mathbf{B} = -\nabla \times \mathbf{E} \quad (1.2)$$

1.1.2 Cold plasma

The update equation of each linear current are

$$\partial_t \mathbf{J}_{s1} = \frac{Z_s}{m_s} (Z_s n_{s0} \mathbf{E}_1 + \mathbf{J}_{s1} \times \mathbf{B}_0), \quad (1.3)$$

where \mathbf{B}_0 and n_{s0} are background magnetic field and density, \mathbf{E}_1 and \mathbf{J}_{s1} are linear electric field and current density, and ν is an artificial damping coefficient.

1.2 Time domain difference scheme

The time difference equation of Ampere's law, Eq.1.1, is given by

$$\varepsilon_0 \frac{E^1 - E^0}{\Delta t} = \frac{1}{\mu_0} \nabla \times B_1^{1/2} - J_{ext}^{1/2} - \sum_s \frac{J_s^1 + J_s^0}{2} \quad (1.4)$$

$$\varepsilon_0 \frac{E^+ - E^-}{\Delta t} = - \sum_s \frac{J_s^1 + J_s^0}{2}$$

where

$$E^- = E^0 + \frac{\Delta t}{2\varepsilon_0} \left(\frac{1}{\mu_0} \nabla \times B_1^{1/2} - J_{ext}^{1/2} \right) \quad (1.5)$$

$$E^+ = E^1 - \frac{\Delta t}{2\varepsilon_0} \left(\frac{1}{\mu_0} \nabla \times B_1^{1/2} - J_{ext}^{1/2} \right) \quad (1.6)$$

The linear cold plasma currents \mathbf{J}_{s1} and electric field \mathbf{E}_1 are put at full time steps, the hot plasma current J_p , which are obtained from the kinetic simulation, and linear magnetic field B_1 are put at the half time steps. The time difference equation is given by

$$\frac{J_s^1 - J_s^0}{\Delta t} = \frac{Z_s}{m_s} \left(Z_s n_{0s} \frac{E^1 + E^0}{2} + \frac{J_s^1 + J_s^0}{2} \times \mathbf{B}_0 \right) \quad (1.7)$$

$$J_s^1 - J_s^0 = \underbrace{\frac{\Delta t Z_s}{2m_s}}_{\alpha_s} (Z_s n_{0s} (E^+ + E^-) + (J_s^1 + J_s^0) \times \mathbf{B}_0)$$

$$\alpha_s \equiv \frac{\Delta t Z_s}{2m_s}$$

$$J_s^1 - \alpha_s J_s^1 \times \mathbf{B} = \underbrace{J_s^0 + \alpha_s J_s^0 \times \mathbf{B} + \alpha_s Z_s n_s E^-}_{K_s^0} + \alpha_s Z_s n_s E^+$$

Eq.1.7 can be wrote as a linear equation of J_s^1

$$J_s^1 - \alpha_s J_s^1 \times \mathbf{B} = K_s^0 + \alpha_s Z_s n_{0s} E^+ \quad (1.8)$$

where

$$K_s^0 \equiv J_s^0 + \alpha_s J_s^0 \times \mathbf{B} + \alpha_s Z_s n_s E^-$$

Solve it we get,

$$J_s^1 = \overleftrightarrow{M}_s \cdot (K_s^0 + \alpha_s Z_s n_s E^+) \quad (1.9)$$

where

$$\overleftrightarrow{M}_s \equiv \frac{\overleftrightarrow{I} + \alpha \overleftrightarrow{I} \times \mathbf{B} + \alpha^2 \overleftrightarrow{I} \cdot \mathbf{B} \mathbf{B}}{1 + \alpha^2 \mathbf{B} \cdot \mathbf{B}}$$

Substituting Eq.1.9 into Eq.1.4 yields

$$\varepsilon_0 \frac{E^+ - E^-}{\Delta t} = - \sum_s \frac{J_s^1 + J_s^0}{2}$$

$$\begin{aligned}
E^+ - E^- &= -\frac{\Delta t}{2\varepsilon_0} \sum_s \left[\vec{M}_s \cdot (K_s^0 + \alpha_s Z_s n_s E^+) + J_s^0 \right] \\
E^+ + \frac{\Delta t}{2\varepsilon_0} \sum_s \vec{M}_s (\alpha_s Z_s n_s) \cdot E^+ &= \underbrace{E^- - \frac{\Delta t}{2\varepsilon_0} \sum_s \left(\vec{M}_s \cdot K_s^0 + J_s^0 \right)}_Q
\end{aligned}$$

where

$$aE^+ + bE^+ \times B + cE^+ \cdot BB = Q$$

$$\begin{aligned}
a &\equiv \frac{\Delta t}{2\varepsilon_0} \sum_s \frac{Z_s n_s \alpha_s}{\alpha_s^2 B \cdot B + 1} + 1 \\
b &\equiv \frac{\Delta t}{2\varepsilon_0} \sum_s \frac{Z_s n_s \alpha_s^2}{\alpha_s^2 B \cdot B + 1} \\
c &\equiv \frac{\Delta t}{2\varepsilon_0} \sum_s \frac{Z_s n_s \alpha_s^3}{\alpha_s^2 B \cdot B + 1}
\end{aligned}$$

$$E^+ = \left(aQ - bQ \times B + \frac{b^2 - ca}{a + cB^2} Q \cdot BB \right) / (a^2 + b^2 B^2)$$

Then, E_1^1 is solved from Eq.?? as Substituting Eq. ?? back to Eq.??, we get J_{s1}^1