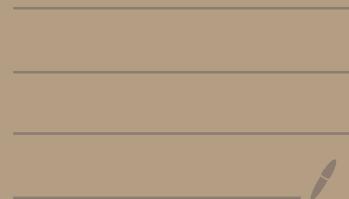


MIT open course : Linear Algebra

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Lecturer: Gilbert Strang



# Lec 1: The geometry of linear equations.

n linear equations, n unknowns.

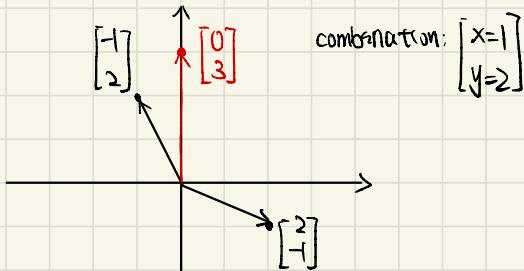
Row pictures : merge of lines

\* Column pictures : combination of vectors  
matrix form

column picture

$$x \begin{bmatrix} 2 \\ -1 \end{bmatrix} + y \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}$$

Linear combination of columns



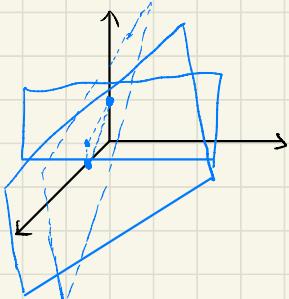
Q: What are all the combinations?

A 3x3 Example:

$$\begin{aligned} 2x - y &= 0 \\ -x + 2y - z &= 1 \\ -3y + 4z &= 4 \end{aligned}$$

$$A = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -3 & 4 \end{bmatrix} \quad b = \begin{bmatrix} 0 \\ 1 \\ 4 \end{bmatrix}$$

Row picture.

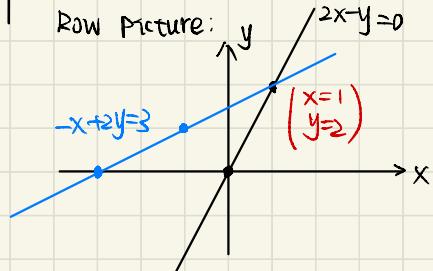


3 planes meet at point, the solution.

Hard to see and imagine the geometry.

$$\begin{aligned} 2x - y &= 0 \\ -x + 2y &= 3 \end{aligned} \Rightarrow \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \end{bmatrix} \quad A \quad x = b$$

Row Picture:



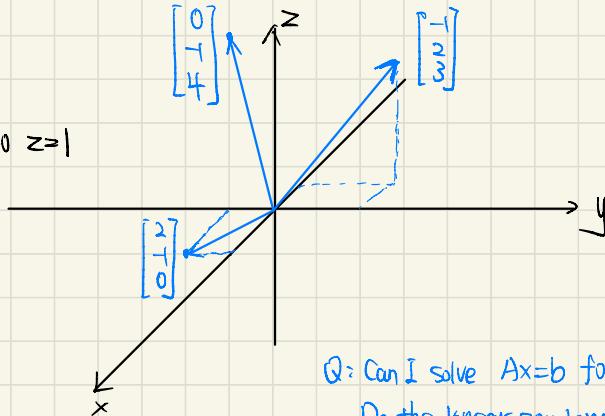
column picture:

$$x \begin{bmatrix} 2 \\ -1 \\ 0 \end{bmatrix} + y \begin{bmatrix} -1 \\ 2 \\ 3 \end{bmatrix} + z \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix}$$

A is nonsingular here.

solution:

$$x=0 \quad y=0 \quad z=1$$



Q: Can I solve  $Ax=b$  for every  $b$ ?  
Do the linear combination of the columns fill 3-D space?

If A is singular, for example,  $\text{rank}(A)=2$ , then I can only solve  $Ax=b$  for some  $b$ . The ones in the same plane of A's columns.

Matrix  $\times$  vector

$$\begin{bmatrix} 2 & 5 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = 1 \begin{bmatrix} 2 \\ 1 \end{bmatrix} + 2 \begin{bmatrix} 5 \\ 3 \end{bmatrix} = \begin{bmatrix} 12 \\ 7 \end{bmatrix} \quad \text{column way.}$$

$Ax$  is a combinations of columns in A!

$$\begin{bmatrix} 2 & 5 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} \Rightarrow 1 \begin{bmatrix} 2 \\ 1 \end{bmatrix} + 2 \begin{bmatrix} 5 \\ 3 \end{bmatrix} = \begin{bmatrix} 12 \\ 7 \end{bmatrix} \Rightarrow \begin{bmatrix} 12 & 19 \\ 7 & 11 \end{bmatrix}$$
  
 $\Downarrow 2 \begin{bmatrix} 2 \\ 1 \end{bmatrix} + 3 \begin{bmatrix} 5 \\ 3 \end{bmatrix} = \begin{bmatrix} 19 \\ 11 \end{bmatrix} \Rightarrow$

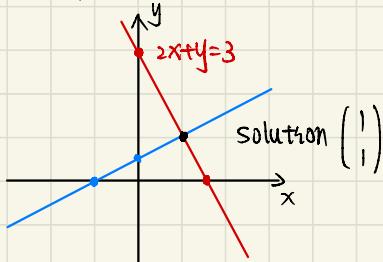
### Exercise

solve  $\begin{cases} 2x+y=3 \\ x-2y=-1 \end{cases}$ , and find out its "row picture" and "column picture".

$$x = 2y - 1 \Rightarrow 2(2y-1) + y = 3 \Rightarrow 4y - 2 + y = 3 \Rightarrow 5y = 5$$

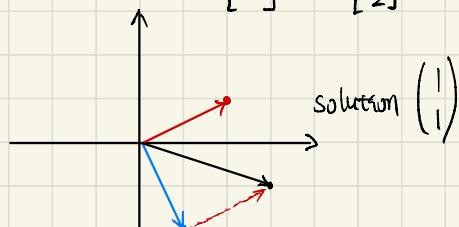
$$\therefore y=1, \Rightarrow x-2=-1 \Rightarrow x=1, \text{ solution } \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

Row picture



column picture

$$\begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \end{bmatrix}$$



$$\text{Matrix form: } A = [V_1 \ V_2] = \begin{bmatrix} 2 & 1 \\ 1 & -2 \end{bmatrix}$$

$$\text{Linear system: } \begin{bmatrix} 2 & 1 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \end{bmatrix}$$

$$\text{Scalar system: } Ax=b \Rightarrow x = \frac{b}{a} = a^{-1}b \Rightarrow a^{-1}a = I$$

$$\text{same idea: } A^{-1}A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad \therefore \text{solution is } \begin{bmatrix} x \\ y \end{bmatrix} = A^{-1} \begin{bmatrix} 3 \\ -1 \end{bmatrix}$$

$$A^{-1}A = I$$

# Mathematical methods for engineers

## Vectors / matrices / subspaces

Vectors  $u, v, w$ .

linear combination:

scalars

$$x_1 u + x_2 v + x_3 w = b$$

$$\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$



3 vectors are independent.

All the combinations of  $u, v$  form a plane in 3-D space.

$$Ax = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 - x_1 \\ x_3 - x_2 \end{bmatrix} = b = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

difference matrix

combination of columns

$$A \begin{bmatrix} 1 \\ 4 \\ 9 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}$$

Given  $x$ , solve  $b$

Reverse: given  $b$ , find  $x$ .

$$\text{solution: } \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_1 + b_2 \\ b_1 + b_2 + b_3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

$$Ax=b$$

$$x=A^{-1}b$$

An different perspective:

A matrix multiplies  $b$ .

Matrix  $A$  transforms vector  $x$  to  $b$ .

Inverse matrix:  $A x = b$ ,  $x = A^{-1}b$ . perfectly only one solution.

Example 2:

$$C = \begin{bmatrix} 1 & 0 & -1 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}$$

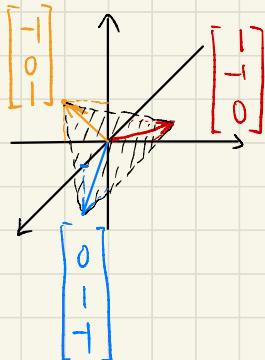
$$Cx = \begin{bmatrix} 1 & 0 & -1 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 - x_3 \\ x_2 - x_1 \\ x_3 - x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

OK if  $0 = b_1 + b_2 + b_3$

If  $Cx = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$  and  $x \neq 0$ , it means, these 3 vectors are at the same plane,  $C$  is singular.  
 solution:  $x = \begin{bmatrix} a \\ a \\ a \end{bmatrix}$   $a$  is any number.

No  $C^{-1}$  such that  $x = C^{-1}0$  ! An big problem.

Column picture of C



These 3 vectors are in one plane.

3 vectors are dependent.

dependent

Do we know an equation for this plane?  $\Rightarrow$  all combinations of  $U, V, W^*$   
 $=$  all vectors  $CX$ .

What  $b = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$  do we get?

$b_1 + b_2 + b_3 = 0$ , this is the equation of this plane.

Vector space: the place that are able to take all the combinations.

subspace: e.g. a 2-D subspace in 3-D space.

Within  $\mathbb{R}^3$ , subspace could be a plane (2D), a line (1D), and a point (0-D)  
3D is also a subspace.  $\underbrace{\text{origin}}$ .

$0 \cdot x = 0$  if it is not  $\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$ , e.g.  $\begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix}$ , then multiply something

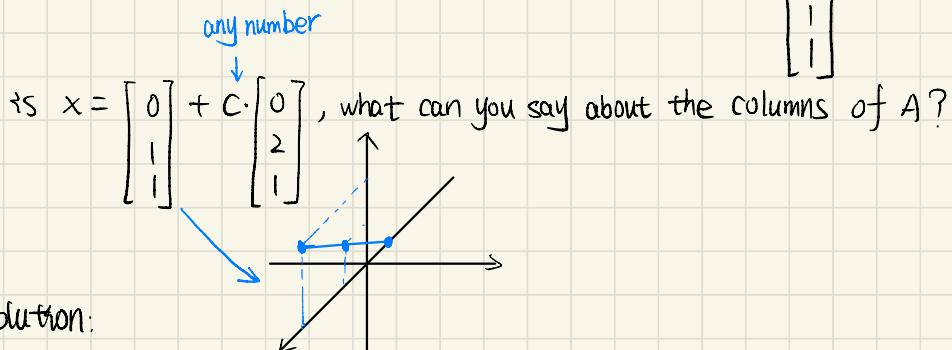
will be away from  $\begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix}$ .

Rectangular matrix A.  $7 \times 3$

$A^T A : 3 \times 3$ . always square and symmetric.

### Exercise

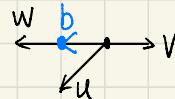
Suppose A is a matrix, s.t. the complete solution to  $AX = \begin{bmatrix} 1 \\ 4 \\ 1 \\ 1 \end{bmatrix}$



my solution:

$$b = 4 \times 1, x = 3 \times 1 \therefore A = 4 \times 3 \Rightarrow A = \begin{bmatrix} u & v & w \\ a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \\ a_{41} & a_{42} & a_{43} \end{bmatrix}$$

- A does not have inverse.
- The column vectors of A are not independent, otherwise, there will be no solution or only one solution.
- $V + W + C(2V + W) = b \Rightarrow 2V + W = 0$



Answer

$$A = [C_1, C_2, C_3] \quad C_1, C_2, C_3 \text{ are in } \mathbb{R}^4$$

$$x = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + c \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix} \quad A(x_p + cx_s) = b \text{ for } c \in \mathbb{R}$$

$$\left. \begin{array}{l} c=0 : Ax_p=b \\ c=1 : Ax_p + Ax_s = b \end{array} \right\} Ax_s = 0$$

$$[C_1, C_2, C_3] \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \\ 1 \\ 1 \end{bmatrix} = [C_2 + C_3] = b$$

$$\begin{bmatrix} C_1 & C_2 & C_3 \end{bmatrix} \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix} = 0 \Rightarrow 2C_2 + C_3 = 0 \Rightarrow \begin{aligned} C_2 &= -b \\ C_3 &= 2b \end{aligned}$$

what about the first column?  $A = \begin{bmatrix} -1 & 2 \\ -4 & 8 \\ C_1 & -1 & 2 \\ -1 & 2 \end{bmatrix}$

$$\left. \begin{array}{l} A(Cx_p + Cx_s) = b \\ A[Cx_s] = 0 \end{array} \right\} A \cdot C \begin{bmatrix} 0 \\ z \\ 1 \end{bmatrix} = 0 \Rightarrow \text{Null}(A) = \left\{ C \cdot \begin{bmatrix} 0 \\ z \\ 1 \end{bmatrix} \mid \forall z \in \mathbb{R} \right\}$$

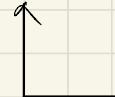
A line.



$$\dim(\text{Null}(A)) = 1$$

$$\therefore \text{rank}(A) = 3 - 1 = 2$$

$\therefore C_1$  is not a multiple of  $b$ .



## Lec 2 : Elimination with matrices (purpose: solve the system).

① Elimination

success

Failure: singular case.

$$x + 2y + z = 2$$

$$3x + 8y + z = 12$$

$$4y + z = 2$$

$$Ax = b$$

② Back substitution

③ Elimination matrices

④ Matrix multiplication

1st pivot

$$A = \begin{bmatrix} 1 & 2 & 1 \\ 3 & 8 & 1 \\ 0 & 4 & 1 \end{bmatrix}$$

2nd pivot

$$\rightarrow \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & -2 \\ 0 & 4 & 1 \end{bmatrix}$$

U

$$\rightarrow \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & -2 \\ 0 & 0 & 5 \end{bmatrix}$$

3rd pivot

U: upper triangular

pivot can't be 0.

$$\det |A| = 1 \times 2 \times 5 = 10$$

② Back substitution

$$\text{Augmented matrix} \quad \left[ \begin{array}{ccc|c} 1 & 2 & 1 & 2 \\ 3 & 8 & 1 & 12 \\ 0 & 4 & 1 & 2 \end{array} \right] \xrightarrow{\text{Row operations}} \left[ \begin{array}{ccc|c} 1 & 2 & 1 & 2 \\ 0 & 2 & -2 & 6 \\ 0 & 4 & 1 & 2 \end{array} \right] \xrightarrow{\text{Row operations}} \left[ \begin{array}{ccc|c} 1 & 2 & 1 & 2 \\ 0 & 2 & -2 & 6 \\ 0 & 0 & 5 & -10 \end{array} \right]$$

A      b

U      C

$$A \rightarrow U$$

$$b \rightarrow C$$



$$\left. \begin{array}{l} x + 2y + z = 2 \\ 2y - 2z = 6 \\ 5z = -10 \end{array} \right\} \begin{array}{l} x=2 \\ y=1 \\ z=-2 \end{array} \quad \begin{array}{l} x=2 \\ y=1 \\ z=-2 \end{array} \quad \begin{array}{l} \text{back} \end{array}$$

Columns: geometric interpretation.

Rows : solving this system.

③ Elimination matrices

step 1:

$$\left[ \begin{array}{ccc|c} 1 & 0 & 0 & 1 \\ -3 & 1 & 0 & 3 \\ 0 & 0 & 1 & 0 \end{array} \right] \left[ \begin{array}{ccc|c} 1 & 2 & 1 \\ 0 & 2 & -2 \\ 0 & 4 & 1 \end{array} \right] = \left[ \begin{array}{ccc|c} 1 & 2 & 1 \\ 0 & 2 & -2 \\ 0 & 4 & 1 \end{array} \right]$$

E<sub>12</sub>

elimination matrix

The whole elimination process:

step 2: subtract 2x Row 2

$$\left[ \begin{array}{ccc|c} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & -2 & 1 & 0 \end{array} \right] \left[ \begin{array}{ccc|c} 1 & 2 & 1 \\ 0 & 2 & -2 \\ 0 & 4 & 1 \end{array} \right] = \left[ \begin{array}{ccc|c} 1 & 2 & 1 \\ 0 & 2 & -2 \\ 0 & 0 & 5 \end{array} \right]$$

E<sub>32</sub>

$$E_{32}(E_{21}A) = U \quad \text{Let } E = E_{32}E_{21}, \quad EA = U$$

$$(E_{32}E_{21})A = U$$

Inverses.

$$\begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{E^{-1}} \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{E} I$$

permutation matrices : Exchange rows 1 and 2.

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} c & d \\ a & b \end{bmatrix}$$

P: permutation matrix

How about change columns?

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} b & a \\ d & c \end{bmatrix}$$

**Exercise:**

solve, using the method of elimination:

$$\begin{array}{l} x - y - z + u = 0 \\ 2x + 2z = 8 \\ -y - 2z = -8 \\ 3x - 3y - 2z + 4u = 7 \end{array}$$

Augmented matrix

$$\left[ \begin{array}{ccccc} 1 & -1 & -1 & 1 & 0 \\ 2 & 0 & 2 & 0 & 8 \\ 0 & -1 & -2 & 0 & -8 \\ 3 & -3 & -2 & 4 & 7 \end{array} \right] \xrightarrow{r_2 - 2r_1} \left[ \begin{array}{ccccc} 1 & -1 & -1 & 1 & 0 \\ 0 & 2 & 4 & -2 & 8 \\ 0 & -1 & -2 & 0 & -8 \\ 3 & -3 & -2 & 4 & 7 \end{array} \right] \xrightarrow{r_4 - 3r_1} \left[ \begin{array}{ccccc} 1 & -1 & -1 & 1 & 0 \\ 0 & 2 & 4 & -2 & 8 \\ 0 & -1 & -2 & 0 & -8 \\ 0 & 0 & 1 & 1 & 7 \end{array} \right]$$

$$\xrightarrow{\quad} \left[ \begin{array}{ccccc} 1 & -1 & -1 & 1 & 0 \\ 0 & 2 & 4 & -2 & 8 \\ 0 & 0 & 1 & 1 & 7 \\ 0 & -1 & -2 & 0 & -8 \end{array} \right] \xrightarrow{r_4 + \frac{1}{2}r_2} \left[ \begin{array}{ccccc} 1 & -1 & -1 & 1 & 0 \\ 0 & 2 & 4 & -2 & 8 \\ 0 & 0 & 1 & 1 & 7 \\ 0 & 0 & 0 & -1 & -4 \end{array} \right] \Rightarrow \begin{array}{l} x - y - z + u = 0 \\ 2y + 4z - 2u = 8 \\ z + u = 7 \\ -u = -4 \end{array}$$

$$\begin{aligned} \therefore u &= 4 \\ z &= 3 \\ y &= 2 \\ x &= 1 \end{aligned} \quad \text{back substitution} \quad \downarrow$$

### Lec 3: Multiplication and inverse matrices

- Matrix multiplication (5 ways!)
- Inverse of A  $AB = A^{-1}$
- Gauss-Jordan / find  $A^{-1}$

- Matrix multiplication

$$\textcircled{1} \quad r_3 \begin{bmatrix} & & \\ & \cdots & \\ & & \end{bmatrix} \begin{bmatrix} & C_4 \\ & | \\ & | \\ & | \\ & C_{34} \end{bmatrix} \begin{bmatrix} & \\ & \\ & \\ & \\ & C^{m \times p} = AB \end{bmatrix} \quad C_{34} = r_3(A) \cdot C_4(B) \\ = a_{31} \cdot b_{14} + a_{32} \cdot b_{24} + \dots \\ = \sum_{k=1}^n a_{3k} b_{k4}$$

$$\textcircled{2} \quad \begin{bmatrix} & & \\ & \cdots & \\ & & \end{bmatrix} \begin{bmatrix} & | \\ & | \\ & | \\ & | \\ & C^{m \times p} = AB \end{bmatrix} = \begin{bmatrix} & \\ & \\ & \\ & \\ & \end{bmatrix} = \begin{bmatrix} Ax_1(C_1(B)), Ax_2(C_2(B)), \dots \\ \uparrow \\ \text{column} \end{bmatrix}$$

Each column of C is a combination of columns in A.

★ What about the rank?  $\text{rank}(AB) \leq \min\{\text{rank}(A), \text{rank}(B)\}$

$$\textcircled{3} \quad \begin{bmatrix} & & \\ & \cdots & \\ & & \end{bmatrix} \begin{bmatrix} & \\ & \\ & \\ & \\ & B^{n \times p} \end{bmatrix} = \begin{bmatrix} & \\ & \\ & \\ & \\ & C^{m \times p} \end{bmatrix} = \begin{bmatrix} r_1(A) \times B \\ r_2(A) \times B \\ \vdots \end{bmatrix}$$

Each row of C is a combination of rows in B.

\textcircled{4} column of A  $\times$  row of B  
 $m \times 1 \quad 1 \times p$

$AB = \text{sum}(\text{cols of } A \times \text{rows of } B)$

e.g.  $\begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} \begin{bmatrix} 1 & 6 \end{bmatrix} = \begin{bmatrix} 2 & 12 \\ 3 & 18 \\ 4 & 24 \end{bmatrix}$

$$\begin{bmatrix} 2 & 7 \\ 3 & 8 \\ 4 & 9 \end{bmatrix} \begin{bmatrix} 1 & 6 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} \begin{bmatrix} 1 & 6 \end{bmatrix} + \begin{bmatrix} 7 \\ 8 \\ 9 \end{bmatrix} \begin{bmatrix} 0 & 0 \end{bmatrix} = \begin{bmatrix} 2 & 12 \\ 3 & 18 \\ 4 & 24 \end{bmatrix}$$

## (S) Block multiplication

$$\begin{bmatrix} A_1 & A_2 \\ A_3 & A_4 \end{bmatrix} \begin{bmatrix} B_1 & B_2 \\ B_3 & B_4 \end{bmatrix} = \begin{bmatrix} \downarrow & \\ & C \end{bmatrix}$$

$A$        $B$        $C$

$$A_1B_1 + A_2B_3$$

- Inverse (square matrices)

- Invertible = nonsingular

$$A^{-1}A = I = AA^{-1}$$

↑

If this matrix exists.

A left inverse is also a right inverse.

$$\text{Analogy: } \frac{1}{3} \times 3 = 3 \times \frac{1}{3}$$

$$\begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix} \begin{bmatrix} a & c \\ b & d \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$A$        $A^{-1}$        $I$

$A \times \text{column } j \text{ of } A^{-1} = \text{column } j \text{ in } I$   
 $\therefore \text{get inverse} = \text{solve a linear system.}$

Gauss-Jordan (solve 2 equations at once)

$$\text{Eq. 1} \quad \begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

Augmented matrix

$$\begin{array}{c|cc} 1 & 2 & | & 1 & 0 \\ 3 & 7 & | & 0 & 1 \end{array} \xrightarrow{\quad} \begin{array}{c|cc} 1 & 3 & | & 1 & 0 \\ 0 & 1 & | & -2 & 1 \end{array} \xrightarrow{\quad} \begin{array}{c|cc} 1 & 0 & | & 7 & -3 \\ 0 & 1 & | & 2 & 1 \end{array}$$

$A$        $I$        $I$        $A^{-1}$

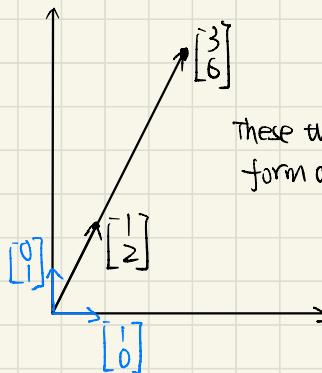
$$\text{Eq. 2} \quad \begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix} \begin{bmatrix} c \\ d \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$[A | I] \Rightarrow [A^{-1}A | A^{-1}I] = [I | A^{-1}]$$

$$[A | I] = [I | A^{-1}]$$

- singular case, no inverse

$$\begin{bmatrix} 1 & 3 \\ 2 & 6 \end{bmatrix}$$



These two columns can never form an identity matrix.

I can find a <sup>non-zero</sup> vector  $x$  that  $Ax=0$ ,  $x = \begin{bmatrix} 3 \\ -1 \end{bmatrix}$

prove by contradiction:

If  $A$  is invertible and there is a non-zero vector  $x$  such that  $Ax=0$ .

$$\therefore A^{-1}Ax = A^{-1}0$$

$\therefore x = 0$  contradict  $x$  is non-zero.

### Exercise

Find the condition on  $a$  and  $b$  that make the matrix  $A$  invertible, and find  $A^{-1}$  when it exists.

$$A = \begin{bmatrix} a & b & b \\ a & a & b \\ a & a & a \end{bmatrix}$$

Solution:

The columns should be independent, i.e.  $Ax=0 \Leftrightarrow x=0$ .

$$A \Rightarrow \begin{bmatrix} a & b & b \\ 0 & a-b & 0 \\ 0 & a-b & a-b \end{bmatrix} \Rightarrow \begin{bmatrix} a & b & b \\ 0 & a-b & 0 \\ 0 & 0 & a-b \end{bmatrix} \quad \det = a(a-b)^2 \neq 0$$

$$\therefore a \neq 0, a \neq b$$

Inverse of this matrix, Gauss-Jordan method:

$$\left[ \begin{array}{ccc|ccc} a & b & b & 1 & 0 & 0 \\ a & a & b & 0 & 1 & 0 \\ a & a & a & 0 & 0 & 1 \end{array} \right] \Rightarrow \left[ \begin{array}{ccc|ccc} a & b & b & 1 & 0 & 0 \\ 0 & a-b & 0 & -1 & 1 & 0 \\ 0 & a-b & a-b & -1 & 0 & 1 \end{array} \right] \Rightarrow \left[ \begin{array}{ccc|ccc} a & b & b & 1 & 0 & 0 \\ 0 & a-b & 0 & -1 & 1 & 0 \\ 0 & 0 & a-b & 0 & -1 & 1 \end{array} \right]$$

$$\frac{b}{a-b} \Rightarrow \left[ \begin{array}{ccc|ccc} a & 0 & b & \frac{a}{a-b} & -\frac{b}{a-b} & 0 \\ 0 & a-b & 0 & -1 & 1 & 0 \\ 0 & 0 & a-b & 0 & -1 & 1 \end{array} \right] \Rightarrow \left[ \begin{array}{ccc|ccc} a & 0 & 0 & \frac{a}{a-b} & 0 & -\frac{b}{a-b} \\ 0 & a-b & 0 & -1 & 1 & 0 \\ 0 & 0 & a-b & 0 & -1 & 1 \end{array} \right] \Rightarrow \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & \frac{1}{a-b} & 0 & -\frac{b}{a(a-b)} \\ 0 & 1 & 0 & \frac{-1}{a-b} & \frac{1}{a-b} & 0 \\ 0 & 0 & 1 & 0 & \frac{-1}{a-b} & \frac{1}{a-b} \end{array} \right]$$

inverse matrix

$$A^{-1} = \frac{1}{a-b} \begin{bmatrix} 1 & 0 & -b \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}$$

## LEC 4: Factorization into $A=LU$

- Inverse of  $AB$ ,  $A^T$
- Product of elimination matrices  $A=LU$  (no row exchanges)

① Inverse.

$$A^T A = I = AA^{-1}$$

$$ABB^{-1}A^{-1} = I \quad \therefore \text{For } AB, \quad B^{-1}A^{-1} \text{ is its inverse matrix.}$$

$$B^{-1}A^{-1}AB = I$$

transpose

$$(AB)^T = B^T A^T$$

$\begin{smallmatrix} \textcolor{red}{-} \\ \textcolor{blue}{-} \end{smallmatrix} \begin{smallmatrix} \textcolor{blue}{\boxed{1}} \\ \textcolor{red}{\boxed{1}} \end{smallmatrix} \quad \begin{smallmatrix} \textcolor{blue}{\boxed{-}} \\ \textcolor{red}{\boxed{-}} \end{smallmatrix} \begin{smallmatrix} \textcolor{red}{\boxed{1}} \end{smallmatrix}$

$$AA^{-1} = I \quad (AA^{-1})^T = (A^{-1})^T A^T = I$$

②  $A=LU$

elementary matrix

$$\begin{bmatrix} E_{21} & A \\ 1 & 0 \\ -4 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 8 & 7 \end{bmatrix} = \begin{bmatrix} U \\ 2 & 1 \\ 0 & 3 \end{bmatrix}$$

$$\begin{bmatrix} A \\ 2 & 1 \\ 8 & 7 \end{bmatrix} = \begin{bmatrix} L \\ 1 & 0 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} U \\ 2 & 1 \\ 0 & 3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & \frac{1}{2} \\ 0 & 1 \end{bmatrix}$$

L      D      U

Eliminate

$$E_{32} E_{31} E_{21} A = U \quad (\text{assume no row exchange})$$

$$\Downarrow$$

$$A = \underbrace{E_{21}^{-1} E_{31}^{-1} E_{32}^{-1}}_L U$$

Suppose

$$\begin{bmatrix} E_{32} & E_{31} & E_{21} \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -5 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 10 & -5 & 1 \end{bmatrix} = E \quad EA = U$$

product of interfering

Inverses, reverse order

$$\begin{bmatrix} E_2^{-1} & & \\ & E_3^{-1} & \\ & & E_{32}^{-1} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 5 & 1 \end{bmatrix} = L \quad A = LU$$

right order, no interfere

$A = LU$ . If no row exchanges, the multipliers go directly into L.

$$EA = \begin{bmatrix} x & x & x \\ x & x & x \\ x & x & x \end{bmatrix} \Rightarrow \begin{bmatrix} x & x & x \\ 0 & x & x \\ 0 & x & x \end{bmatrix} \Rightarrow \begin{bmatrix} x & x & x \\ 0 & x & x \\ 0 & 0 & x \end{bmatrix}$$

interfere

$$LU = \begin{bmatrix} x & x & x \\ 0 & x & x \\ 0 & 0 & x \end{bmatrix} \Rightarrow \begin{bmatrix} x & x & x \\ 0 & x & x \\ 0 & x & x \end{bmatrix} \Rightarrow \begin{bmatrix} x & x & x \\ x & x & x \\ x & x & x \end{bmatrix}$$

no interfere

How many operations on  $n \times n$  matrix A? Time complexity.  $n?$   $n^2?$   $n^3?$   $n!?$

$$n=100 \quad \begin{array}{c} \text{about } n^2 \\ \xrightarrow{\text{full of non-zeros}} \end{array} \begin{array}{c} \text{about } (n-1)^2 \\ \xrightarrow{\quad} \end{array} \begin{array}{c} \text{about } (n-1)^2 \\ \xrightarrow{\quad} \end{array}$$

$$\begin{bmatrix} \dots & \dots & \dots \\ \dots & \dots & \dots \\ \dots & \dots & \dots \end{bmatrix} \xrightarrow{\quad} \begin{bmatrix} \square & \dots & \dots \\ 0 & \dots & \dots \\ 0 & \dots & \dots \end{bmatrix} \xrightarrow{\quad} \begin{bmatrix} \square & \dots & \dots \\ 0 & \square & \dots \\ 0 & 0 & \dots \end{bmatrix}$$

$$\text{count: } n^2 + (n-1)^2 + \dots + 2^2 + 1^2 \asymp \frac{1}{3}n^3 \iff \int_1^n x^2 dx \quad \int_1^n x^2 dx = \frac{2}{3}x^3$$

cost of b  $\asymp n^2$

Permutation matrix

row exchanges

6 P's

 $A_3^3$  $P^{-1} = P^T$ 

3x3

$$1 \quad 1 \quad 1 \\ 123 \quad 1 \quad 23 \\ \quad 1 \quad 1$$

$$P_{12} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$P_{13} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

$$P_{23} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$231 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}, \quad 312 = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

A group of 6 matrices. multiplication and inverse are still in the group.

multi-permutation

undo permutation

4x4, how many P's?  $A_4^4 = 4 \times 3 \times 2 \times 1 = 24$

### Exercise

Find the LU-decomposition of the matrix

$$A = \begin{pmatrix} 1 & 0 & 1 \\ a & a & a \\ b & b & a \end{pmatrix}$$

when it exists. For which real numbers a and b does it exist?

Solution:

$$\therefore EA = U \quad A = LU$$

$$\therefore E^{-1} = L$$

$$A = \begin{bmatrix} 1 & 0 & 1 \\ a & a & a \\ b & b & a \end{bmatrix} \xrightarrow{E_{21}} \begin{bmatrix} 1 & 0 & 1 \\ 0 & a & 0 \\ b & b & a \end{bmatrix} \xrightarrow{E_{31}} \begin{bmatrix} 1 & 0 & 1 \\ 0 & a & 0 \\ 0 & b & a-b \end{bmatrix} \xrightarrow{E_{32}} \begin{bmatrix} 1 & 0 & 1 \\ 0 & a & 0 \\ 0 & 0 & a-b \end{bmatrix} = U$$

$$\begin{array}{c} U \\ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -\frac{b}{a} & 1 \end{bmatrix} \xrightarrow{E_{32}} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -b & 0 & 1 \end{bmatrix} \xrightarrow{E_{31}} \begin{bmatrix} 1 & 0 & 0 \\ -a & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{E_{21}} \begin{bmatrix} 1 & 0 & 0 \\ -a & 1 & 0 \\ 0 & -\frac{b}{a} & 1 \end{bmatrix} = E \end{array}$$

$$L = \begin{bmatrix} 1 & 0 & 0 \\ a & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{E_{21}^{-1}} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ b & 0 & 1 \end{bmatrix} \xrightarrow{E_{31}^{-1}} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & \frac{b}{a} & 1 \end{bmatrix} \xrightarrow{E_{32}^{-1}} \begin{bmatrix} 1 & 0 & 0 \\ a & 1 & 0 \\ b & \frac{b}{a} & 1 \end{bmatrix}$$

requirement  $a \neq 0$

comment: if  $a=b$ ,  $U$  is singular.

Singular matrices can have LU decompositions.

LU decomposition comes with Gauss elimination naturally.

## Lec S: Transposes, Permutations, Spaces $\mathbb{R}^n$

- $PA = LU$
- Vector spaces and subspaces

Permutations  $P$ : execute row exchanges. (shift away 0 on pivot position)

$$A = LU = \left[ \begin{array}{cc|c} 1 & 0 & \\ -1 & 1 & \\ 0 & 1 & \end{array} \right] \left[ \begin{array}{ccc} & & \\ & & \\ & & \end{array} \right]$$

becomes  $\xrightarrow{\text{row exchange}}$   
 $\xrightarrow{\text{permutation matrix}}$   $PA = LU$  for any invertible  $A$

$P =$  identity matrix with reordered rows.

Counts reorderings: all  $n \times n$  permutations.  $n! = n(n-1) \cdots (3)(2)(1)$

$$P^{-1} = P^T \quad P^T P = I$$

### Transpose matrix

$$(A^T)_{ij} = A_{ji}$$

### Symmetric matrix

$$A^T = A$$

E.g.  $\begin{bmatrix} 1 & 3 \\ 2 & 3 \\ 4 & 1 \end{bmatrix}^T = \begin{bmatrix} 1 & 2 & 4 \\ 3 & 3 & 1 \end{bmatrix}^{R^T}$

$R^T R$  is always symmetric.

$$\begin{bmatrix} 1 & 3 \\ 2 & 3 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 4 \\ 3 & 3 & 1 \end{bmatrix} = \begin{bmatrix} 10 & 11 & 7 \\ 11 & 13 & 11 \\ 7 & 11 & 17 \end{bmatrix}$$

why?

$$(R^T R)^T = R^T R^{TT} = R^T R$$

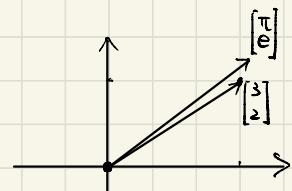
### Vector spaces

Examples:  $\mathbb{R}^2 =$  all 2-dimensional real vectors.  
 $= "xy"$  plane

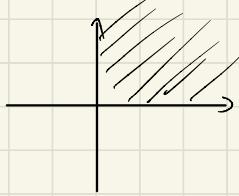
$\mathbb{R}^3 =$  all 3-dimensional real vectors.

$\mathbb{R}^n =$  all column vectors with real numbers.

$$\begin{bmatrix} 3 \\ 2 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix} \begin{bmatrix} \pi \\ e \end{bmatrix}$$



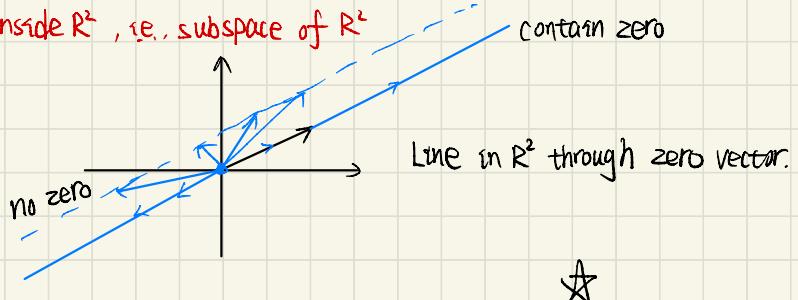
not a vector space



addition ✓

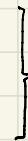
multiplication with real number  $\times$   
(may go out)

A Vector space inside  $\mathbb{R}^2$ , i.e., subspace of  $\mathbb{R}^2$



subspaces of  $\mathbb{R}^2$ :

- ① all of  $\mathbb{R}^2$
- ② any line through  $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$
- ③ zero vector only.



Pick any vector in these subspaces, do some simple operations, the product is still in that subspace.



subspaces of  $\mathbb{R}^3$ :

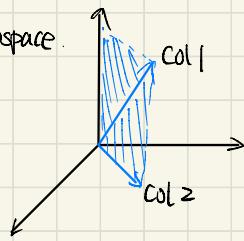
- ① all of  $\mathbb{R}^3$
- ② planes through origin
- ③ lines through origin
- ④ zero vector only

$$A = \begin{bmatrix} 1 & 3 \\ 2 & 3 \\ 4 & 1 \end{bmatrix}$$

columns are in  $\mathbb{R}^3$

How to create a subspace?

All their linear combinations form a subspace.  
called column space.  $C(A)$



give a plane through origin

Exercise:

$$x_1 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix}$$

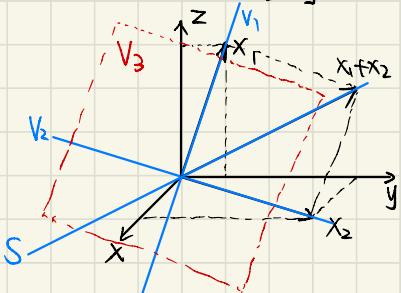
$$x_2 = \begin{bmatrix} 2 \\ 4 \\ 0 \end{bmatrix}$$

- Find  $V_1$  = subspace generated by  $x_1$ ,  
 $V_2$  = subspace generated by  $x_2$   
 Describe  $V_1 \cap V_2$ .

- Find  $V_3$  = subspace generated by  $\{x_1, x_2\}$   
 Is  $V_3$  equal to  $V_1 \cup V_2$ ?

Find a subspace  $S$  of  $V_3$ , s.t.  $x_1 \notin S$ ,  $x_2 \notin S$ .

- What is  $V_3 \cap \{x-y \text{ plane}\}$ ?



Solution:

two conditions: preserve addition  
 preserve multiplication

In short: linear combination

- $V_1 = \{ax_1, \forall a \in \mathbb{R}\}$  line

$$V_2 = \{ax_2, \forall a \in \mathbb{R}\} \text{ line}$$

$$V_1 \cap V_2 = \{(0,0,0)^T\} \text{ zero vector}$$

- $V_3 = \{ax_1 + bx_2, \forall a, b \in \mathbb{R}\}$  plane

$V_3 \neq \underline{V_1 \cup V_2}$  not a subspace     $x_1 + x_2 \notin V_1 \cup V_2$   
 plane                  two lines

A subspace of  $V_3$ :  $S = \{ax_1 + bx_2, \forall a, b \in \mathbb{R}\}$  a line.

Or zero vector

- $V_3 \cap \{x-y \text{ plane}\} = V_2$

## Lec 6: column space and nullspace

- vector spaces and subspaces
- column space of  $A$ : solving  $Ax=b$
- Null space of  $A$

vector space requirements:

V+W and CV are in the space or all combinations CV+DW are in the space  
 sum multiplication

2 subspaces:  $P$  and  $L$  (plane and line in  $\mathbb{R}^3$ )

$P \cup L =$  all the vectors in  $P$  and  $L$ . This is not a subspace.

$P \cap L =$  all the vectors in both  $P$  and  $L$ . This is a subspace.

Subspaces  $S$  and  $T$ . intersection  $S \cap T$  is a subspace.

• Column space of  $A$  is a subspace of  $\mathbb{R}^4$ .  $C(A)$

For  $A$

$$A = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \\ 3 & 1 & 4 \\ 4 & 1 & 5 \end{bmatrix} \quad C(A) = \text{all linear combinations of columns.}$$

Does  $Ax=b$  have a solution for every  $b$ ? No.

4 equations 3 unknowns

$$A = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \\ 3 & 1 & 4 \\ 4 & 1 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix} \quad \text{which } b\text{'s allow this system can be solved?}$$

+ ↗

Answer:  $b \in C(A)$

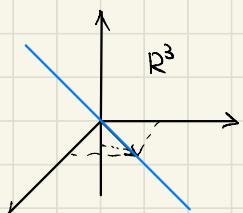
$C(A)$  is a 2-dimensional subspace in  $\mathbb{R}^4$ .

- Null space of  $A$  = all solutions  $x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$  to  $Ax=0$ , in  $\mathbb{R}^3$

For  $x$ .

$$AX = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \\ 3 & 1 & 4 \\ 4 & 1 & 5 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \\ X_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$N(A)$  contains  $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ -1 \end{bmatrix}, \begin{bmatrix} c \\ c \\ -c \end{bmatrix}$



$$\Rightarrow c \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} \text{ line in } \mathbb{R}^3$$

check that solutions to  $Ax=0$  always give a subspace.

If  $AV=0$  and  $Aw=0$  then  $A(V+w)=0$

- consider another condition of solution space

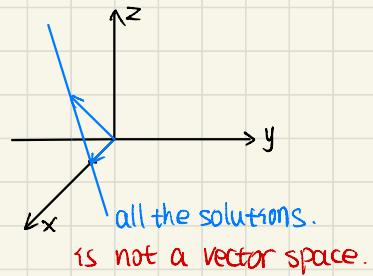
$$AX = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \\ 3 & 1 & 4 \\ 4 & 1 & 5 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \\ X_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$$

Does this have a solution? ✓

Do the solutions form a vector space? ✗  
consider zero vector.

$$X = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} -2 \\ -3 \\ 3 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + c \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}$$



### Exercise

which are subspaces of  $\mathbb{R}^3 = \left\{ \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} \right\}$  ?

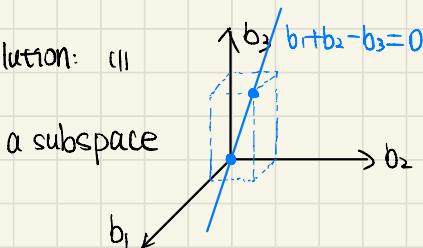
$$(1) b_1 + b_2 - b_3 = 0$$

$$(2) b_1, b_2 - b_3 = 0$$

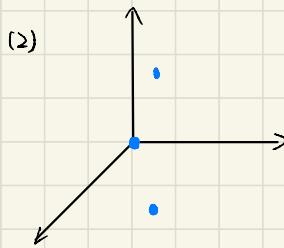
$$(3) \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + c_1 \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

$$(4) \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + c_1 \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

solution: (1)



$$(1 \ 1 \ -1) \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} = 0 \text{ null space of } (1 \ 1 \ -1)$$



not a subspace.

$$\begin{pmatrix} 2 \\ 2 \\ 4 \end{pmatrix} \Rightarrow b_1, b_2 - b_3 = 0$$

$$\begin{pmatrix} 4 \\ 4 \\ 8 \end{pmatrix} \Rightarrow b_1, b_2 - b_3 \neq 0$$

$$(3) \text{ is a subspace } -1 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \text{ can get } \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

a plane through origin in  $\mathbb{R}^3$

(4) not a subspace. can not return to zero vector.

a plane does not through origin in  $\mathbb{R}^3$

## Lec 7: solving $Ax=0$ : Pivot variables, special solutions

- computing the nullspace ( $Ax=0$ )
- pivot variables - free variables
- special solutions - rref ( $A=R$ )

Echelon matrix: step matrix

- computing the nullspace ( $Ax=0 \Rightarrow Ux=0 \Rightarrow Rx=0$ )

$\square$ : pivot

2 pivots

$$A = \begin{bmatrix} 1 & 2 & 2 & 2 \\ 2 & 4 & 6 & 8 \\ 3 & 6 & 8 & 10 \end{bmatrix} \xrightarrow{\text{elimination}} \begin{bmatrix} 1 & 2 & 2 & 2 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 2 & 4 \end{bmatrix} \xrightarrow{\quad} \begin{bmatrix} 1 & 2 & 2 & 2 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix} = U$$

↑  
2 pivot columns  
↓  
free columns

Rank of  $A = \# \text{ of pivots in } U$ .

# free variables = # of variables - # of pivot variables

Compared to invertible square matrix, this require:

- fix the free columns
- backward substitution.

$$x_i = c \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}^{\text{fix}} + d \begin{bmatrix} 2 \\ 0 \\ -2 \\ 1 \end{bmatrix}^{\text{fix}}$$

2 special solutions

An algorithm for finding null space

$R$  = reduced row echelon form : zeros above and below pivots

Matlab operation:  $R = \text{rref}(A)$

$$U = \begin{bmatrix} 1 & 2 & 2 & 2 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{\quad} \begin{bmatrix} 1 & 2 & 0 & -2 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{\quad} \begin{bmatrix} 1 & 2 & 0 & -2 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} = R$$

Pivot rows, pivots columns

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

free columns

$$\begin{bmatrix} 2 & -2 \\ 0 & 2 \end{bmatrix}$$

$$\begin{aligned} 1x_1 + 2x_2 - 2x_4 &= 0 \\ x_3 + 2x_4 &= 0 \end{aligned}$$

group the pivot columns  
and free columns.

rref form

$$R = \left[ \begin{array}{cc|cc} I & F \\ 0 & 0 \end{array} \right] \quad \begin{matrix} \leftarrow r \text{ pivot rows} \\ \leftarrow m-r \text{ free columns} \\ \uparrow r \text{ pivot columns} \end{matrix}$$

Pivot columns, free columns

$$= \left[ \begin{array}{cc|cc} 1 & 0 & 2 & -2 \\ 0 & 1 & 0 & 2 \\ 1 & 3 & 2 & 4 \end{array} \right] \quad \begin{matrix} I \\ F: \text{free part} \end{matrix}$$

$$RX=0 \Rightarrow RN=0$$

$N$  is null space matrix (columns = special solutions)

$$\therefore N = \left[ \begin{array}{c} -F \\ I \end{array} \right] \quad RN = \left[ \begin{array}{cc} I & F \\ 0 & 0 \end{array} \right] \left[ \begin{array}{c} -F \\ I \end{array} \right] = \left[ \begin{array}{c} 0 \\ 0 \end{array} \right]$$

$$\therefore N = \left[ \begin{array}{cc} -2 & 2 \\ 0 & -2 \\ 1 & 0 \\ 0 & 1 \end{array} \right] \quad \begin{matrix} \Rightarrow x = C \\ + d \end{matrix} \left[ \begin{array}{c} 2 \\ 1 \\ 2 \\ 0 \\ 3 \\ 3 \\ -2 \\ 4 \\ 4 \end{array} \right] \quad \begin{matrix} \text{match the } UX=0 \\ \text{solution.} \end{matrix}$$

null space matrix , columns are null bases

Another example :

$$A = \left[ \begin{array}{ccc} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 2 & 6 & 8 \\ 2 & 8 & 10 \end{array} \right] \rightarrow \left[ \begin{array}{ccc} 1 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 2 & 2 \\ 0 & 4 & 4 \end{array} \right] \rightarrow \left[ \begin{array}{ccc} 1 & 2 & 3 \\ 0 & 2 & 2 \\ 0 & 0 & 0 \\ 0 & 4 & 4 \end{array} \right] \rightarrow \left[ \begin{array}{ccc} 1 & 2 & 3 \\ 0 & 2 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

$\cup \text{ rank}(A)=2$

↑  
pivot columns      ↓  
free column. (one special solution)

$$X = C \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} \quad \begin{matrix} x_1 + 2x_2 + 3x_3 = 0 \\ 2x_2 + 2x_3 = 0 \\ \text{fix} \end{matrix}$$

$$U = \left[ \begin{array}{ccc} 1 & 2 & 3 \\ 0 & 2 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right] \rightarrow \left[ \begin{array}{ccc|c} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] = R \quad RX=0 \quad X = C \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} = C \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

↑  
null space matrix

### Exercise:

The set  $S$  of points  $P(x, y, z)$  s.t.  $x - 5y + 2z = 9$  is a ① in  $\mathbb{R}^3$ .

It is ② to the ③ so of  $P(x, y, z)$  s.t.  $x - 5y + 2z = 0$ .

All points of  $S$  have the form:

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} + c_1 \cdot \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + c_2 \cdot \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

### Solution:

① A plane without origin point.

② parallel    ③ plane

$$x - 5y + 2z = 0$$

$$A = [1 \ -5 \ 2] \quad A \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 0 \quad \therefore R = \begin{bmatrix} 1 & -5 & 2 \end{bmatrix}$$

↓

Pivot variable  
free columns.

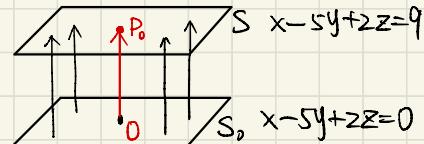
$$\begin{bmatrix} I & F \\ I & -F \end{bmatrix} = 0$$

$$\therefore \text{the null space matrix is } \begin{bmatrix} 5 & -2 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} \quad \therefore \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} ? \\ 0 \\ 0 \end{bmatrix} + c_1 \begin{bmatrix} 5 \\ 1 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix}$$

↑  
null basis

$P_0$

? = 9 if we take  $c_1=0$  and  $c_2=0$ .



Any point in  $S = P_0 + \text{any point in } S_0$

## LEC 8: solving $Ax=b$ : Row reduced form R

- complete solution of  $Ax=b$
- Rank  $r$   $x = x_p + x_n$  particular solution + null space
- $r=m$ : solution exists .  $r=n$ : solution is unique

$$x_1 + 2x_2 + 2x_3 + 2x_4 = b_1$$

$$2x_1 + 4x_2 + 6x_3 + 8x_4 = b_2$$

$$3x_1 + 6x_2 + 8x_3 + 10x_4 = b_3$$

pivots

$$\left[ \begin{array}{cccc|c} 1 & 2 & 2 & 2 & b_1 \\ 2 & 4 & 6 & 8 & b_2 \\ 3 & 6 & 8 & 10 & b_3 \end{array} \right] \rightarrow \left[ \begin{array}{cccc|c} 1 & 2 & 2 & 2 & b_1 \\ 0 & 0 & 2 & 4 & b_2 - 2b_1 \\ 0 & 0 & 2 & 4 & b_3 - 3b_1 \end{array} \right] \rightarrow \left[ \begin{array}{cccc|c} 1 & 2 & 2 & 2 & b_1 \\ 0 & 0 & 2 & 4 & b_2 - 2b_1 \\ 0 & 0 & 0 & 0 & b_3 - b_2 - b_1 \end{array} \right]$$

$b_1 = 1$   
 $b_2 - 2b_1 = 3$   
 $b_3 - b_2 - b_1 = 0$

Augmented matrix =  $[A \ b]$

$$0 = b_3 - b_2 - b_1$$

If  $b = \begin{bmatrix} 1 \\ 5 \\ 6 \end{bmatrix}$ , OK, it allows a solution

solvability: condition on  $b$

$Ax=b$  is solvable when  $b$  is in  $C(A)$ , column space of  $A$ .

If a combination of rows of  $A$  gives zero row, then the same combination of entries of  $b$  must give 0.

To find the complete solution to  $Ax=b$

①  $x_{\text{particular}}$  : set all free variables to zero, and solve  $Ax=b$  for pivot variables.

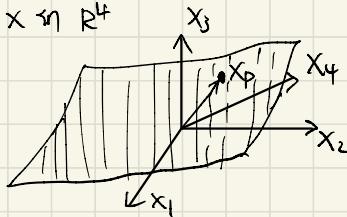
$$+ \quad x_1 + 2x_3 = 1 \Rightarrow x_3 = \frac{3}{2} \Rightarrow x_p = \begin{bmatrix} -2 \\ 0 \\ \frac{3}{2} \\ 0 \end{bmatrix} \quad \begin{aligned} Ax_p &= b \\ Ax_n &= 0 \\ A(x_p + x_n) &= b \end{aligned} \quad \boxed{\star}$$

②  $x_{\text{null space}}$

$$x = x_p + x_n$$

$$x_{\text{complete}} = \begin{bmatrix} -2 \\ 0 \\ \frac{3}{2} \\ 0 \end{bmatrix} + c_1 \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

Plot all solutions  $x$  in  $\mathbb{R}^4$



$m \times n$  matrix  $A$  of rank  $r$  (know  $r \leq m$ ,  $r \leq n$ )

- Full column rank means  $r=n$ : no free variables

$N(A) = [\text{zero vector}]$  solution to  $Ax=b$  :  $x=x_p$ . Unique solution if it exists.

An example:

$$A = \begin{bmatrix} 1 & 3 \\ 2 & 1 \\ 6 & 1 \\ 5 & 1 \end{bmatrix} \quad R = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \quad \text{if } b = \begin{bmatrix} 4 \\ 3 \\ 7 \\ 6 \end{bmatrix} \Rightarrow x = x_p = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

rref

- Full row rank means  $r=m < n$

Can solve  $Ax=b$  for every  $b$ . Exists.  
 $n-r$  free variables.

$$A = \begin{bmatrix} 1 & 2 & 6 & 5 \\ 3 & 1 & 1 & 1 \end{bmatrix} \quad R = \begin{bmatrix} 1 & 0 & \underline{\quad} & \underline{\quad} \\ 0 & 1 & \underline{= \quad} & \underline{=} \end{bmatrix} \quad F$$

- $r = m = n$ , full rank, invertible

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 1 \end{bmatrix} \quad R = I \quad \text{rref}$$

$$\begin{array}{|c|} \hline r = m = n \\ R = I \\ 1 \text{ solution} \\ \hline \end{array}$$

$$\begin{array}{|c|} \hline r = n < m \\ R = \begin{bmatrix} I \\ 0 \end{bmatrix} \\ 0 \text{ or } 1 \text{ solution} \\ \hline \end{array}$$

$$\begin{array}{|c|} \hline r = m < n \\ R = [I \ F] \\ \infty \text{ solutions} \\ \hline \end{array}$$

$$\begin{array}{|c|} \hline r < m, r < n \\ R = \begin{bmatrix} I & F \\ 0 & 0 \end{bmatrix} \\ 0 \text{ or } \infty \text{ solutions} \\ \hline \end{array}$$

### Exercise:

Find all solutions, depending on  $b_1, b_2, b_3$ :

$$x - 2y - 2z = b_1$$

$$2x - 5y - 4z = b_2$$

$$4x - 9y - 8z = b_3$$

### Solution:

$$[AX] = \begin{bmatrix} 1 & -2 & -2 & b_1 \\ 2 & -5 & -4 & b_2 \\ 4 & -9 & -8 & b_3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & -2 & b_1 \\ 0 & -1 & 0 & b_2 - 2b_1 \\ 0 & -1 & 0 & b_3 - 4b_1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & -2 & b_1 \\ 0 & 1 & 0 & 2b_1 - b_2 \\ 0 & 0 & 0 & b_3 - b_2 - 2b_1 \end{bmatrix}$$

If  $b_3 - b_2 - 2b_1 \neq 0$ , no solution; If  $b_3 - b_2 - 2b_1 = 0$ , continue.

rref:  $R = \left[ \begin{array}{ccc|c} 1 & 0 & -2 & b_1 \\ 0 & 1 & 0 & 2b_1 - b_2 \\ 0 & 0 & 0 & b_3 - b_2 - 2b_1 \end{array} \right] = \left[ \begin{array}{cc|c} 1 & 0 & b_1 \\ 0 & 1 & 2b_1 - b_2 \\ 0 & 0 & b_3 - b_2 - 2b_1 \end{array} \right]$

$Ax_p = b \quad (1)$   
 $Ax_n = 0 \quad (2)$

① get the particular solution by setting all free variables as zero.

$$\begin{aligned} x - 2y &= b_1 \\ y &= 2b_1 - b_2 \end{aligned} \Rightarrow x = 5b_1 - 2b_2 \Rightarrow x_p = \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 5b_1 - 2b_2 \\ 2b_1 - b_2 \\ 0 \end{bmatrix}$$

② get the null space, i.e. get the special solution.

$$R \left[ \begin{array}{c} -F \\ I \end{array} \right] = 0 \Rightarrow \text{null matrix } x = \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} = x_s$$

$$\therefore \text{solution} = \begin{bmatrix} 5b_1 - 2b_2 \\ 2b_1 - b_2 \\ 0 \end{bmatrix} + c \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} = x_p + c x_s$$

This is the case  $m \times n = 3 \times 3$ ,  $r = 2$ ,  $r < m$ ,  $r < n$   
 cause no unique  
 may cause no solution

## LEC 9: Independence, Basis, and Dimension

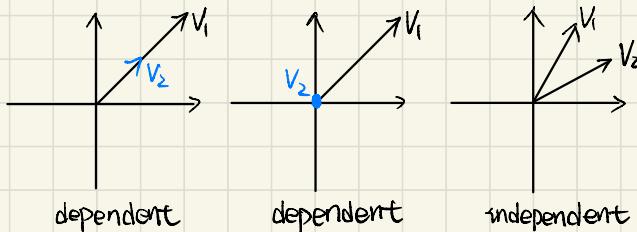
- Linear independence
- spanning a space
- Basis and dimension

Suppose  $A$  is  $m$  by  $n$  with  $m < n$ , i.e., more unknowns than equations, then there are nonzero solutions to  $AX=0$ .

Reason: There will be free variable!! Think about the rref.

Independence: Vectors  $x_1, x_2, \dots, x_n$  are independent if no combination give zero vector, except the zero combination.

$$c_1x_1 + c_2x_2 + \dots + c_nx_n \neq 0 \text{ except } c_1=c_2=\dots=c_n=0$$



Repeat when  $v_1, \dots, v_n$  are columns of  $A$ , they are independent if nullspace of  $A$  is  $\{\text{zero vector}\}$ .  $\text{Rank}(A)=n$ , no free variables.

They are dependent if  $Ac=0$  for some nonzero  $c$ .  $\text{Rank}(A) < n$ , has free variable.

Vectors  $v_1, \dots, v_k$  span a space means: The space consists of all combinations of those vectors.

Basis for a vector space is a sequence of vectors  $v_1, v_2, \dots, v_k$  with 2 properties:

- ① they are independent.
- ② they span the space.

Example:

Space is  $\mathbb{R}^3$

One basis is

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

another basis

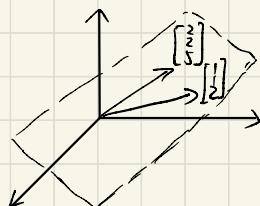
$$\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 3 \\ 5 \\ 8 \end{bmatrix}$$

$\mathbb{R}^n$ :  $n$  vectors give basis if the  $n \times n$  matrix with those columns is invertible.

Consider:

$$\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 5 \end{bmatrix}$$

is the basis of a plane in  $\mathbb{R}^3$ .



Given a space  $\mathbb{R}^n$ , every basis for the space has  $n$  vectors.



The dimension of the space.

Example:

$$A = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 1 & 1 & 2 & 1 \\ 1 & 2 & 3 & 1 \end{bmatrix}$$

↑  
another basis  
↑

space is  $C(A)$ .

$$\begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \\ 1 \\ 0 \end{bmatrix} \in N(A)$$

a basis of null space

They span  $C(A)$ .

They are not independent.

A basis for  $C(A)$  is  $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix}$

$\text{Rank}(A) = \# \text{ of pivot columns} = \text{dimension of } C(A) = 2$

$\dim[N(A)] = \# \text{ of free variables} = n - \text{rank}(A)$

### Exercise

Find the dimension of the vector space spanned by the vectors

$$\left[ \begin{array}{c|c|c|c} 1 & 1 & 0 & 2 \\ 1 & 2 & 1 & 3 \\ -2 & 0 & 3 & 0 \\ 0 & -4 & -3 & -2 \\ 1 & 1 & 2 & 0 \end{array} \right]$$

and find a basis for that space.

Solution:

Are they independent? Do elimination to find the number of pivots.

$$\left[ \begin{array}{c|c|c|c} 1 & 1 & 0 & 2 \\ 1 & 2 & 1 & 3 \\ -2 & 0 & 3 & 0 \\ 0 & -4 & -3 & -2 \\ 1 & 1 & 2 & 0 \end{array} \right] \xrightarrow{\text{basis}} \left[ \begin{array}{c|c|c|c} 1 & 1 & 0 & 2 \\ 0 & 1 & 1 & 1 \\ 0 & 2 & 3 & 4 \\ 0 & -4 & -3 & -2 \\ 0 & 2 & 2 & 2 \end{array} \right] \xrightarrow{\quad} \left[ \begin{array}{c|c|c|c} 1 & 1 & 0 & 2 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{array} \right] \xrightarrow{\quad} \left[ \begin{array}{c|c|c|c} 1 & 0 & 2 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

note: column space has changed.

These 4 vectors are dependent.

A basis is:

$$\left[ \begin{array}{c|c|c} 1 & 1 & 0 \\ 1 & 2 & 1 \\ -2 & 0 & 3 \\ 0 & -4 & -3 \\ 1 & 1 & 2 \end{array} \right]_{V_1 \ V_2 \ V_3}$$

A basis of a 3-dimensional subspace in  $\mathbb{R}^5$ .

$$\dim [\text{span}(V_1, V_2, V_3)] = 4$$

## Lec 10: The four fundamental subspaces. (for matrix A)

Example:

space is  $\mathbb{R}^3$

one basis is

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Another is

$$\begin{bmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \\ 2 & 5 & 8 \end{bmatrix}$$

$\times$  they are not independent

rows are dependent

### 4 subspaces

- column space  $C(A)$
- null space  $N(A)$
- row space = all combinations of rows = all combinations of columns of  $A^T = C(A^T)$
- null space of  $A^T = N(A^T)$  left null space of A

If  $A = m \times n$ ,  $C(A)$  is in  $\mathbb{R}^m$

$N(A)$  is in  $\mathbb{R}^n$

$C(A^T)$  is in  $\mathbb{R}^n$

$N(A^T)$  is in  $\mathbb{R}^m$

$C(A)$	$N(A)$
basis? pivot columns dimension? rank(A)	special solution $n - \text{rank}(A)$

4 subspaces

$\dim C(A^T) = \text{rank}(A)$

$\mathbb{R}^n$   
row space

column space

$\mathbb{R}^m$

$\dim C(A) = \text{rank}(A)$

$\dim = n - \text{rank}(A)$

null space

$\dim = m - \text{rank}(A)$

$$A = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 1 & 1 & 2 & 1 \\ 1 & 2 & 3 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} I & F \\ \boxed{1 & 0 & 1 & 1} & \boxed{0 & 1 & 1 & 0} \\ \boxed{0 & 1 & 1 & 0} & \boxed{0 & 0 & 0 & 0} \end{bmatrix} = R$$

$C(R) \neq C(A)$  different column space

same row space

$$E = \begin{bmatrix} 1 & 2 & 0 \\ 1 & -1 & 0 \\ -1 & 0 & 1 \end{bmatrix}$$

basis for  $N(A^T)$

Basis for row space is first r rows in R.

$$\begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 0 \end{bmatrix}$$

$$N(A^T) : A^T y = 0 \xrightarrow{\text{Transpose}} y^T A = 0^T \text{ left null space}$$

$$\left[ \begin{array}{c|c} & \\ \hline & \\ & \end{array} \right] = \left[ \begin{array}{c} 0 \\ \vdots \\ 0 \end{array} \right]$$

$$\text{ref } [A_{m \times n} \ I_{m \times m}] \rightarrow [R_{m \times n} \ E_{m \times m}]$$

$$E [A_{m \times n} \ I_{m \times m}] = [R_{m \times n} \ E_{m \times m}]$$

**new vector space M**

All  $3 \times 3$  matrices !!

$A + B, CA$  (not  $AB$ )  
for now

$$\begin{array}{c||c||c||c} \text{subspaces of } M & \text{upper triangular} & \text{symmetric} & \text{diagonal} \\ & \text{matrices} & \text{matrices} & \text{matrices} \end{array}$$

$\dim = 3$



$$\text{basis: } \underbrace{\left[ \begin{array}{ccc} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right], \left[ \begin{array}{ccc} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 0 \end{array} \right], \left[ \begin{array}{ccc} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 7 \end{array} \right]}_{\text{They span the subspace of } 3 \times 3 \text{ diagonal matrices.}}$$

They span the subspace of  $3 \times 3$  diagonal matrices.

**Exercise:**

$$\text{Suppose } B = \begin{pmatrix} 1 & & \\ 2 & 1 & \\ -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 5 & 0 & 3 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 5 & 0 & 3 \\ 10 & 1 & 7 \\ -5 & 0 & -3 \end{pmatrix}$$

Find a basis for and compute the dimension of each of the 4 fundamental subspaces.

**Solution:**

- $C(B)$ : a basis is  $\begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$   $\dim=2$ .

- $N(B)$ :  $B = \begin{pmatrix} 5 & 0 & 3 \\ 10 & 1 & 7 \\ -5 & 0 & -3 \end{pmatrix} \xrightarrow{\text{Row reduction}} \begin{pmatrix} 1 & 0 & 3 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix} = R \Rightarrow$  a null basis is  $\begin{bmatrix} -F \\ I \end{bmatrix} = \begin{bmatrix} -\frac{3}{5} \\ -1 \\ 1 \end{bmatrix}$   $\dim=1$

- $C(B^T)$ : a basis is  $\begin{bmatrix} 5 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$   $\dim=2$

- $N(B^T)$   $E_B = R$ , where  $E_B = \begin{bmatrix} \frac{1}{5} & 0 & 0 \\ -2 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \begin{pmatrix} 5 & 0 & 3 \\ 10 & 1 & 7 \\ -5 & 0 & -3 \end{pmatrix} = \begin{bmatrix} 1 & 0 & \frac{3}{5} \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

$$\therefore \text{a basis is } \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \quad \dim=1$$

Vedio answer:

$$\begin{pmatrix} 1 & & \\ -2 & 1 & \\ 1 & 0 & 1 \end{pmatrix} B = \begin{pmatrix} 5 & 0 & 3 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix} \quad \text{a basis is } \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

## Lec 11 : Matrix space ; Rank 1 ; small world graphs

- Basis of new vector spaces  $\rightarrow M = \text{all } 3 \times 3 \text{ matrices}$
- Rank one matrices  $\rightarrow$  subspaces | symmetric | upper triangular
- Small world graphs  $S: 3 \times 3 \quad U: 3 \times 3$

Basis for  $M = \text{all } 3 \times 3 \text{ matrices}$   $\dim M = 9$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \dots \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Basis for symmetric matrices  $\dim S = 6$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$\dim U = 6$$

$S \cap U = \text{symmetric and upper triangular}$   
 $= \text{diagonal } 3 \times 3 \text{ matrices}$

$$\dim(S \cap U) = 3$$

$S \cup U$  is not a subspace

$U \neq \emptyset$

$S + U = \text{any element of } S + \text{any element of } U = \text{all } 3 \times 3 \text{ matrices}$

$$\dim(S+U) = 9$$

e.g.

$\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$	$\begin{bmatrix} 0 & 2 & 3 \\ 0 & 3 & 1 \\ 0 & 0 & 4 \end{bmatrix}$	$\begin{bmatrix} 1 & 3 & 3 \\ 1 & 3 & 1 \\ 0 & 0 & 4 \end{bmatrix}$
$S$	$U$	

here  $S+U \notin SUU$  ★

$$\dim S = 6 + \dim U = 6 = \dim(S \cap U) = 3 + \dim(S+U) = 9$$

An example of differential equation:

$$\frac{d^2y}{dx^2} + y = 0 \quad \text{sol: } y = \underline{\cos x}, \underline{\sin x}$$

basis

$$\dim(\text{solution space}) = 2$$

find null space

The complete solution  $y = C_1 \cos x + C_2 \sin x$

- Rank 1 matrices

$$A = \begin{bmatrix} 1 & 4 & 5 \\ 2 & 8 & 10 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 4 & 5 \end{bmatrix}$$

$2 \times 3 \quad r=1 \quad 2 \times 1 \quad 1 \times 3$

rank 1 matrix has the form

$$A = UV^T$$

a column  $\times$  a row

$M = \text{all } 5 \times 7 \text{ matrices, subset of rank 1 matrices, is it a subspace?}$

$\text{rank}(A)=1, \text{rank}(B)=1, \text{rank}(A+B) \text{ may be } 2, \text{ not a subspace}$

In  $\mathbb{R}^4$ ,  $V = \begin{bmatrix} V_1 \\ V_2 \\ V_3 \\ V_4 \end{bmatrix}$

$S = \text{all } v \text{ in } \mathbb{R}^4 \text{ with } V_1 + V_2 + V_3 + V_4 = 0$   
 $= \text{null space of } [1, 1, 1, 1]$   
 $AV = 0$

$$m \times n = 1 \times 4$$

$S$  is a subspace  
 $\dim(S) = 3 \quad \left. \right\} 3+1=4$   
 $\text{rank}(A)=1$

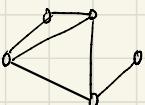
Basis for  $S$ :

$$\begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

$C(A)$  is  $\mathbb{R}^1$   
 $N(A^T) = \{0\} \quad \left. \right\} 1+0=1$

- small world graph

Graph = {nodes, edges}



### Exercise:

Show that the set of  $2 \times 3$  matrices whose nullspace contains  $\begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}$  is a vector subspace, and find a basis for it.

What about the set of those whose column space contains  $\begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}$ ?

Solution:

$$A = \begin{bmatrix} & & \\ & & \\ v_1 & v_2 & v_3 \end{bmatrix} \quad \text{Let } M = \text{set of } 2 \times 3 \text{ matrices whose nullspace contains } \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}$$

$\therefore M$  is the set of matrices with rank  $\leq 2$  and  $2v_1 + v_2 + v_3 = 0$ .

hint: sum, multiply.

sum

$$A \neq B \in M = \text{set of } 2 \times 3 \text{ matrices whose nullspace contains } \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}$$

$$\left\{ \begin{array}{l} A = [v_1, v_2, v_3] \\ 2v_1 + v_2 + v_3 = [0] \end{array} \right. \quad \left\{ \begin{array}{l} B = [w_1, w_2, w_3] \\ 2w_1 + w_2 + w_3 = [0] \end{array} \right. \Rightarrow A + B = [v_1 + w_1, v_2 + w_2, v_3 + w_3] \\ [A + B] \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} = A \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} + B \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} = [0]$$

multiply:

$$c \cdot A \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} = [0]$$

$\therefore M$  is a vector space, or matrix space more precisely.

$$A \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} = [0] \quad \text{Each row of } A \text{ must be } [a \ b \ c] \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} = 0 \quad 2a + b + c = 0 \\ c = -2a - b$$

$$\therefore \text{Must be } [a, b, -2a - b] = [a, 0, -2a] + [0, b, -b] \\ = \text{linear combination of } [1, 0, -2] \text{ and } [0, 1, -1]$$

$\therefore$  basis is  $\begin{bmatrix} 1 & 0 & -2 \\ 0 & 0 & 0 \end{bmatrix}$   $\begin{bmatrix} 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$   $\begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & -2 \end{bmatrix}$   $\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & -1 \end{bmatrix}$

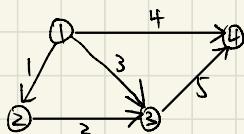
The set of those whose column space contains  $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$

$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$  is not in the set.  $\therefore$  not a vector space.

## Lec 12: Graphs, Networks, Incidence Matrices

- Graphs and networks
- Incidence matrices
- Kirchhoff's laws

Graph : nodes, edges



$m=5$  edges       $n=4$  nodes

Incidence matrix

$$A = \begin{bmatrix} \text{node} & 1 & 2 & 3 & 4 \\ \text{edge} & \begin{bmatrix} -1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ -1 & 0 & 1 & 0 \\ -1 & 0 & 0 & 1 \\ 0 & 0 & -1 & 1 \end{bmatrix} & \begin{array}{l} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{array} \end{bmatrix}$$

loop  $\rightarrow$  dependence  $r_1 + r_2 = r_3$

Questions : 1. null space ?  $Ax=0$        $x=[x_1, x_2, x_3, x_4]$       potentials at nodes.

$$Ax = \begin{bmatrix} x_2 - x_1 \\ x_3 - x_2 \\ x_3 - x_1 \\ x_4 - x_1 \\ x_4 - x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad x = C \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

$AX$ : the difference of potentials on different edges.

$C$   $\downarrow$  OHM's law

current  $[y_1, y_2, y_3, y_4, y_5]$  on edges

$\dim NCA=1$

$\downarrow$  Kirchhoff's currency law

2. rank of  $A$  ?       $\text{rank}(A) = 3$

$$ATy=0$$

3. null space of  $A^T$ .       $A^T y = 0$        $\dim NCAT = m - r = 5 - 3 = 2$

$\uparrow$

pivot columns

edge 1, 2, 4

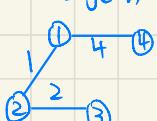
$$\begin{bmatrix} -1 & 0 & -1 & -1 & 0 \\ 1 & -1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & -1 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

# of independent loops

= # edges - (#nodes - 1)

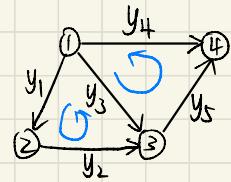
# nodes - # edges + # loops =

Euler's formulation



A tree.

$$\begin{array}{l} -y_1 - y_3 - y_4 = 0 \\ y_1 - y_2 = 0 \\ y_2 + y_3 - y_5 = 0 \\ y_4 + y_5 = 0 \end{array} \quad \left| \begin{array}{l} \text{Basis for } N(CA^T) \\ \begin{array}{c|c} \begin{bmatrix} 1 \\ 1 \\ -1 \\ 0 \\ 0 \end{bmatrix} & \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \\ -1 \end{bmatrix} \\ \text{loop1} & \text{loop2} \end{array} \end{array} \right.$$



AX

Potential difference

$y = Ce$

OHM's law

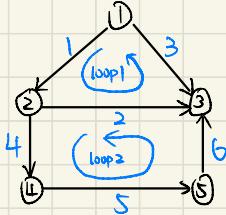
$A^T y = f$

out sources

$$A^T C A X = f$$

Kirchhoff's circuit law: for any node (junction) in an electric circuit, the sum of currents flowing into that node is equal to the sum of currents flowing out of that node.

### Exercise:



- Find incidence matrix A
- $N(A)$ ,  $N(A^T) = ?$
- Trace  $(A^T A) = ?$

Solution:

Link-node incidence matrix  $A =$

$$A = \begin{bmatrix} -1 & 1 & 0 & 0 & 0 \\ 0 & -1 & 1 & 0 & 0 \\ 0 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & 0 & -1 \end{bmatrix} \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \end{matrix} \quad \text{rank}(A) = 4$$

$$N(A) : Ax = 0 \quad x \in \mathbb{R}^{5x1}$$

$$Ax = \begin{bmatrix} x_2 - x_1 \\ x_3 - x_2 \\ x_3 - x_1 \\ x_4 - x_2 \\ x_5 - x_4 \\ x_3 - x_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad x = c \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

The node potential difference is zero. Then all nodes should have the same potential.  $\dim N(A) = 1$

$$N(A^T) : A^T y = 0 \quad y \in \mathbb{R}^{6x1}$$

$$A^T y = \begin{bmatrix} -y_1 - y_3 \\ y_1 - y_2 - y_4 \\ y_2 + y_3 + y_6 \\ y_4 - y_5 \\ y_5 - y_6 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad y = c_1 \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

↑                      ↑  
loop 1          loop 2

y: current on edges.

$A^T y$  represents Kirchhoff's circuit laws, i.e., current conservation.

$A^T A$  is a symmetric matrix.  $\text{tr}(A) = \text{sum of diagonal elements}$ .

$$A^T A = \begin{bmatrix} -1 & -1 \\ 1 & -1 & -1 \\ 1 & 1 & 1 \\ 1 & -1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} -1 & 1 \\ -1 & 1 \\ -1 & 1 \\ -1 & 1 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & -1 & -1 & 0 & 0 \\ -1 & 3 & -1 & -1 & 0 \\ -1 & -1 & 3 & 0 & 0 \\ 0 & -1 & 0 & 2 & -1 \\ 0 & 0 & -1 & -1 & 2 \end{bmatrix}$$

$$\therefore \text{tr}(A^T A) = 2 + 3 + 3 + 2 + 2 = 12$$

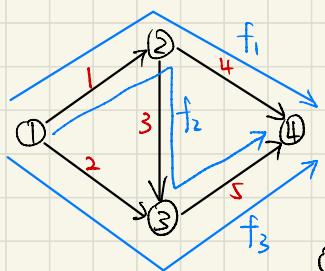
$$\begin{aligned} \text{tr}(A^T A) &= \text{sum}(\text{col } 1 \times \text{row } 1) + \text{sum}(\text{col } 2 \times \text{row } 2) + \dots \\ &= \sum_{i=1}^{\text{cols}} \|\text{col}_i\|_2^2 \end{aligned}$$

In this case,  $(\text{column of } A^T)^2$  is node degree.

$$\begin{aligned} \text{tr}(A^T A) &= \text{degree of node 1} + \text{degree of node 2} + \dots \\ &= 2 + 3 + 3 + 2 + 2 = 12 \end{aligned}$$

Lec 13 : Review for Exam 1  
Emphasizes Chapter 3

# Some thoughts on network flow problem



node-link incidence matrix  $A = \begin{bmatrix} 1 & 1 \\ -1 & 1 & 1 \\ -1 & -1 & 1 \\ -1 & -1 \\ 1 & 2 & 3 & 4 & 5 \end{bmatrix}$

S.P.:

$$\text{Traffic: } Ax = b$$

Network flow:

Q1:  $N(A)$ ? find the combination that forms a loop.

$$N(A) = C_1 \begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + C_2 \begin{bmatrix} 0 \\ 0 \\ 1 \\ -1 \\ 1 \end{bmatrix} \quad \dim N(A) = 2$$

$$\dim N(A^T) = 1$$

$$\dim C(A^T) = 3 \text{ in } \mathbb{R}^5$$

$$\text{rank}(A) = 3$$

solution to  $Ax = b \Rightarrow x = \begin{bmatrix} \cdot \\ \cdot \\ \cdot \end{bmatrix} + N(A)$

flow problem is to search the best solution for  $C_1$  and  $C_2$ .

$$A^T y = \begin{bmatrix} y_1 - y_2 \\ y_1 - y_3 \\ y_2 - y_3 \\ y_2 - y_4 \\ y_3 - y_4 \end{bmatrix} \quad N(A^T) = C \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

$\min C^T x$  link flow  
 $\max b^T y \leftarrow$  node potential

$$AX = b$$

$$A^T y \leq C$$

$$x \geq 0$$

$$\top = [1 \ 1 \ 1]$$

$$x = \Delta f \quad \top f = d$$

link-path incidence matrix:

$$\Delta = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 1 \\ 1 & 2 & 3 \end{bmatrix}$$

Q1:  $\text{rank}(A) = 3$

Q2:  $N(A)$ ?

$$\Delta f = \begin{bmatrix} f_1 + f_2 \\ f_3 \\ f_2 \\ f_1 \\ f_2 + f_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow N(A) = \left\{ \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\} \Rightarrow x = \Delta f \text{ solution is unique.}$$

Q3:  $N(A^\top)$ ?

$$\Delta^\top x = \begin{bmatrix} x_1 + x_4 \\ x_1 + x_3 + x_5 \\ x_2 + x_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad \dim N(A^\top) = 2$$

这个表示什么?

Q: In CP, are the generated paths between an OD pair independent?

