

Interpretation of fracture spacing and intensity

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ABSTRACT: A class of fracture intensity measures in one, two, and three dimensions has been defined that allows for the definition of fracture frequency without requiring reference to specific sets or orientations. Measure P_{32} (fracture area per unit volume) was found to be the most useful measure for fracture intensity in three dimensions. Relationships between intensity measures are described based on solutions from the field of stochastic geometry. The use of these measures significantly improves the consistency of discrete fracture analysis and modelling for mechanical and hydrologic applications.

1. INTRODUCTION

Fracture patterns are described in terms of distributions for orientation, size, shape, spatial location, and intensity (Dershowitz and Einstein, 1988). Of these, intensity is one of the most important, but the least well characterized. Fracture intensity is generally noted in terms of fracture spacing S_r , the mean distance between fractures within a given set, as measured along a particular line such as a borehole or scanline (Figure 1). This measure is relatively easy to determine in

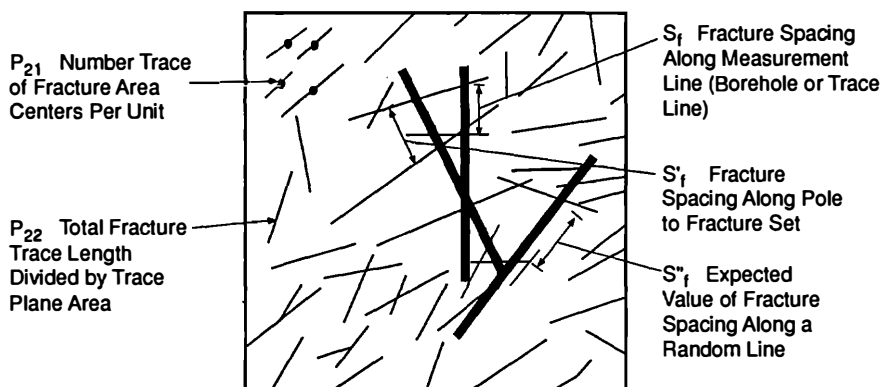


Figure 1. One and Two Dimensional Fracture Intensity Measures

the field, but is not useful for describing fractures in two or three dimensions. It is also dependent upon the subjective definition of fracture sets in the field.

In three dimensional analysis, fracture intensity is generally defined as the number of fracture centers per unit volume, P_{31} . This measure is useful only where fractures are much smaller than the region being analyzed, such that fracture centers represent individual fractures, rather than fragments of fractures that may be within or outside the region. In addition, P_{31} can only be related to fracture spacing S_f through the fracture size and orientation distributions.

The goal of this paper is to define a consistent set of fracture intensity measures in one, two, and three dimensions, together with the relationships between them.

2. FRACTURE INTENSITY MEASURES

Fracture intensity measures are classified based upon the dimension of the measurement region, and the dimension of the fracture (Table 1). The formats for fracture intensity measures are based upon the designation P ("persistence"), followed by subscripts designating the dimension of the measurement region and the fracture attribute (Dershowitz, 1984). The measurement region dimension is specified as P_1 (one dimensional line), P_2 (two dimensional trace plane), or P_3

Table 1: Measures for Fracture Intensity			
Dimension of Measurement Region -->	1: Line Measure (Borehole or Scan line)	2: Area Measure (Traceplane)	3: Volume (Rock Mass)
Dimension of Fracture Measure			
1: Number of Fractures	P_{11} : Number of fractures per unit length of scan line or borehole (inverse spacing) $[L^{-1}]$	P_{21} : Number of fractures per unit area of trace plane $[L^{-2}]$	P_{31} : Number of fractures per unit volume of rock $[L^{-3}]$
2: Dimension one less than that of measurement region		P_{22} : Length of fracture traces per unit area of trace plane $[L^{-1}]$	P_{32} : Area of Fractures per unit volume of rock $[L^{-1}]$
3: Dimension equal to that of measurement region			P_{33} : Volume of Fractures per unit volume of rock $[-]$

(three dimensional volume). The fracture dimension is specified by the relationship between the dimension used for describing fractures and the dimension used for the region.

2.1 One Dimensional Intensity Measures

Fracture spacing S_f is the most commonly used measure for fracture intensity (Figure 1). Unfortunately, fracture spacing is a very difficult measure to interpret because it is closely coupled with the definition of sub-parallel fracture sets, and is dependent upon the relationship between the orientation of fractures and the orientation of the line along which spacing is measured.

For sets of parallel fractures, attempts have been made (Einstein et al., 1980) to define a corrected mean spacing S_f' as a measure along the line perpendicular to the fractures. The spacing measured in the field is then corrected based on the angle θ between the mean pole of the fractures and the line along which the fracture spacing was measured,

$$S_f' = S_f \cos \theta \quad (1)$$

However, for sub-parallel fractures or fractures with significant orientation dispersion, the angle θ becomes increasingly difficult to define. Further, the definition of sets is frequently subjective and irreproducible, further diminishing the usefulness of S_f and S_f' .

Intensity measure P_{11} is directly related to fracture spacing S_f by,

$$P_{11} = \frac{1}{S_f} \quad (2)$$

Like S_f , P_{11} is directly dependent upon the relative orientations of the fractures and the line along which orientation is measured. Another approach to normalizing S_f is to specify S_f'' not for a given orientation, but as the expected value of spacing for a randomly oriented measurement line. In this case,

$$S_f'' = S_f \int_{-\pi/2}^{\pi/2} f_{\theta}(\theta) \cos \theta d\theta \quad (3)$$

where $f_{\theta}(\theta)$ is the distribution of the fracture orientations. For a Fisher orientation distribution,

$$S_f'' = S_f \int_{-\pi/2}^{\pi/2} e^{\kappa \cos(\theta - \bar{\theta})} \sin(\theta - \bar{\theta}) \cos(\theta) d\theta \quad (4)$$

Intensity measure P_{11} has the same characteristics as S_f and must also be defined in terms of the relative orientations of the fractures and the line along which P_{11} is defined. In general, however, when dealing with anything except parallel fracture sets, the definition of P_{11} should be based upon a random line orientation as in equation 4.

It is important to note that while P_{11} and S_f are dependent upon the orientation of fractures, they are independent of fracture size (Figure 2). For a given fracture orientation, P_{11} and S_f do not change when the fracture size is doubled and the number of fractures is cut in half. As a result, P_{11} and S_f are scale independent — they do not depend on the region in which they are defined.

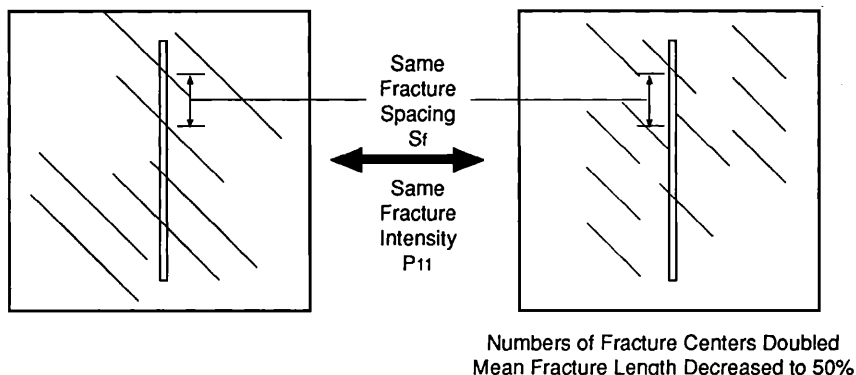


Figure 2. Scale Independent Fracture Intensity Measures S_f and P_{11}

2.2 Two Dimensional Fracture Intensity Measures

Fracture intensity on a two dimensional surface is measured by either P_{21} , the number of traces per unit area or P_{22} , the length of traces per unit area (Figure 1). Intensity measure P_{21} depends upon the distribution of fracture size, and as a result is scale dependent at scales smaller than the maximum fracture trace length. Figure 3 illustrates the change in intensity measure P_{21} for decreasing analysis regions.

Intensity measure P_{22} is not scale dependent, since it directly incorporates fracture size.

$$P_{22} = \frac{\int_0^{\infty} L f_L(L) dL}{A} \quad (5)$$

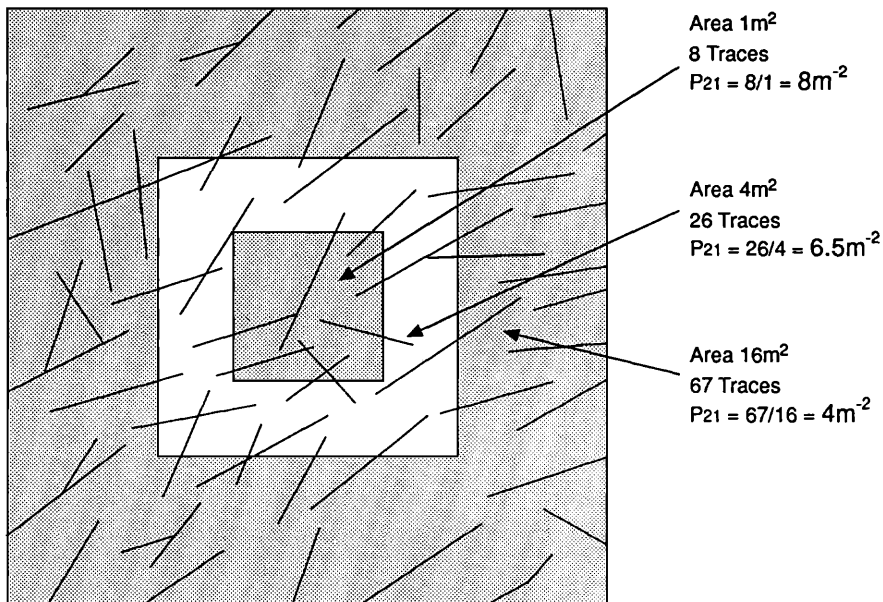


Figure 3. Scale Dependent Fracture Intensity Measure P_{21}

Both P_{21} and P_{22} are dependent upon the relative orientation of the fractures and the trace plane on which the measures are defined.

Intensity measure P_{21} can be related to P_{22} through the distribution of fracture size,

$$P_{22} = P_{21} \int_0^{\infty} L f_L(L) dL \quad (6)$$

$$P_{22} = P_{21} \bar{L}$$

2.3 Three Dimensional Fracture Intensity Measures

In three dimensions, fracture intensity can be defined in terms of P_{31} , the number of fractures in a volume, P_{32} , the area of fractures in a volume, or P_{33} , the volume of fractures in a volume (Figure 4). Like P_{21} , P_{31} is scale dependent, and changes with the size of the region being analyzed for regions smaller than the maximum fracture size. P_{32} and P_{33} are not scale dependent, since they directly incorporate fracture size,

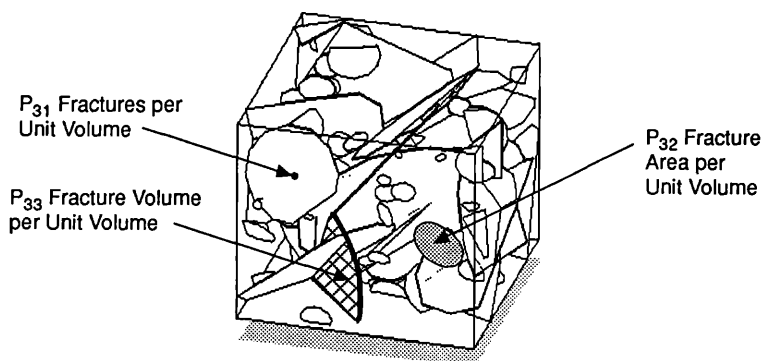


Figure 4. Three Dimensional Fracture Intensity Measures

$$P_{32} = \frac{\int A f_A(A) dA}{V} \quad (7)$$

$$P_{33} = \frac{\int A t f_A(A) f_t(t) dA dt}{V} \quad (8)$$

Intensity measure P_{31} can be related to P_{32} through the distribution of fracture size,

$$\begin{aligned} P_{32} &= P_{31} \int_0^{\infty} A f_A(A) dA \\ P_{32} &= P_{31} \bar{A} \end{aligned} \quad (9)$$

Intensity measure P_{33} is equivalent to fracture porosity and requires information on fracture thickness. Like P_{32} , it is not scale dependent, and can be defined without respect to fracture orientation. However, it requires additional information on fracture thickness, and is therefore most useful for features in which thickness is significant. Note that P_{32} is scale dependent if the maximum fracture thickness is comparable to the size of the region being analyzed.

P_{33} can be related to P_{32} by the equation,

$$P_{33} = P_{32} \frac{\int_0^{\infty} A t f_A(A) f_t(t) dA dt}{\bar{A}} \quad (10)$$

3. RELATIONSHIPS AMONG INTENSITY MEASURES OF DIFFERENT DIMENSIONS

Intensity measures with the dimension $[L^{-1}]$ are scale independent, and can be interrelated by removing the effect of the orientation of the scan line (P_{11}) or trace plane (P_{22}), without additional information. The distribution of fracture size does not affect this transformation unless there is a correlation between orientation and size. As a result, the most useful measure of intensity for three dimensional fracture modelling is P_{32} , since it does not reflect any orientation effects and can be directly related to fracture spacing S_f and P_{11} without specification of fracture size. When P_{32} is used to define intensity, size can be defined independently. The transformation between fracture spacing S_f and P_{32} is,

$$P_{32} = \frac{C_{P_3}}{S_f} \quad (11)$$

C_P is a constant dependent upon the distribution of the orientation of features relative to the line along which the spacing S_f was measured.

A similar relationship can be defined between S_f and P_{22} ,

$$P_{22} = \frac{C_{P_2}}{S_f} \quad (12)$$

For simple fracture geometries, C_{P_2} and C_{P_3} can be found by the methods of stochastic geometry (Santalo, 1976). For a uniform distribution of fracture orientation, Dershowitz (1984) found a value of C_{P_3} of 2.0. For most fracture geometries, C_{P_3} will vary between 1.0 and 3.0. Values of C_{P_3} and C_{P_2} for different fracture geometries are shown in Figures 5 and 6. These values were obtained by simulation of boreholes with different orientations within fracture networks simulated with the FracMan discrete fracture model (Dershowitz et al., 1991). Fracture networks were defined with a vertical mean pole, a constant fracture radius of 5 meters, and location defined by a Poisson Point Process of fracture centers (Baecher and Lanney, 1978). The trace plane for calculation of C_{P_2} was defined by a vertical plane containing the 6 boreholes with trends from 0° to 90° .

Intensity measures P_{21} and P_{31} are dependent upon the distribution of fracture size. As a result, conversions between these measures and scale independent intensity measures such as fracture spacing S_f , P_{22} , and P_{32} can only be made by specifying the fracture size distribution. Conversions between P_{21} and P_{22} , and between P_{31} and P_{32} are given in equations 6 and 9.

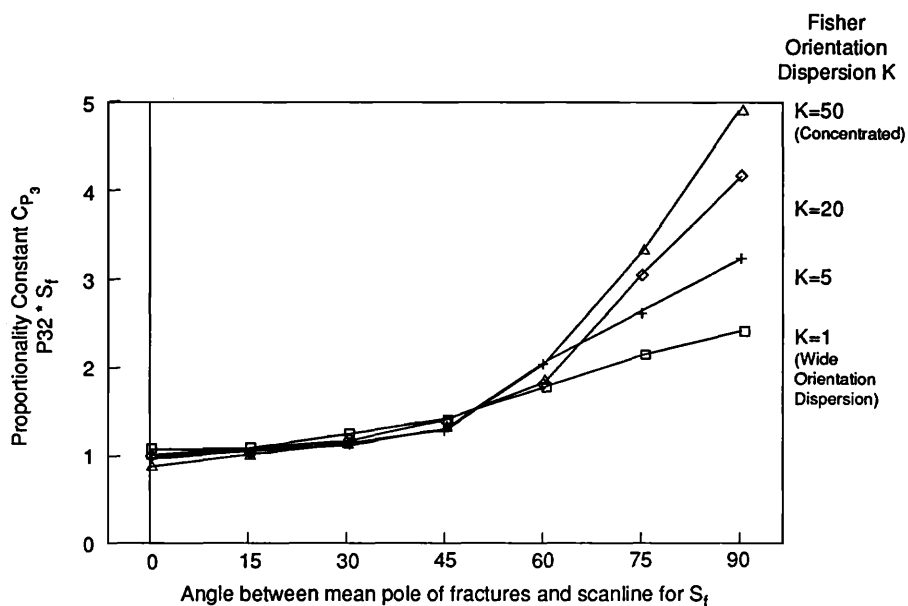


Figure 5. Proportionality Constant C_{P_3} (from FracMan Simulation)

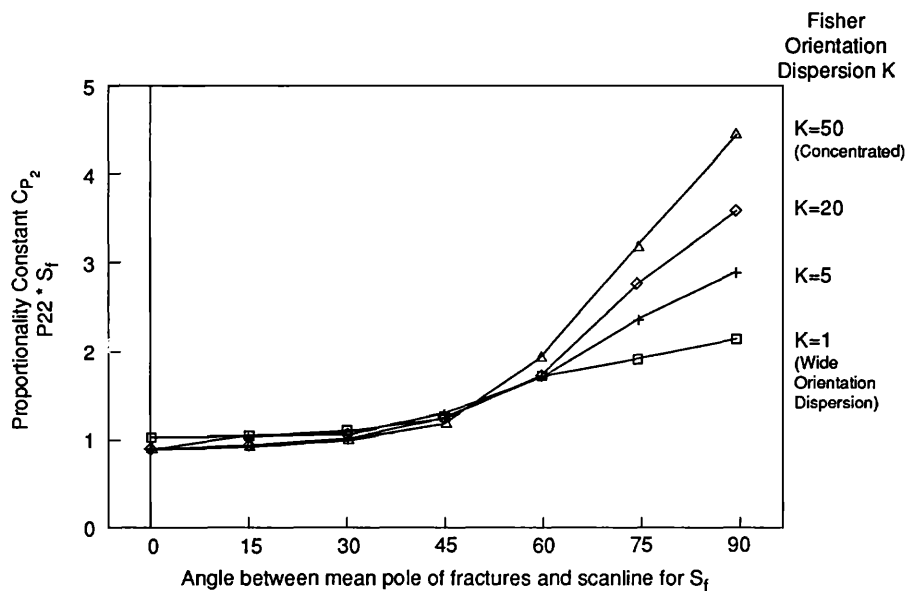


Figure 6. Proportionality Constant C_{P_2} (from FracMan Simulation)

4. APPLICATION OF INTENSITY MEASURES

The above theoretical development has demonstrated the utility of intensity measures P_{22} and P_{32} for two and three dimensional rock mechanics applications. In fracture mapping, collection of P_{22} has been shown to be a more versatile measure of fracture intensity than either P_{21} or S_f .

Most three dimensional discrete fracture simulation published to date has been carried out based upon constant values of P_{31} . However, when this procedure is used, fracture intensity as measured by mean spacing S_f' , P_{22} , or P_{32} will vary with the variance of fracture area. The second moment approximation for this is given by,

$$P_{32} \approx [P_{31}^2 A_{\sigma} + A_{\mu}^2 P_{31} + P_{31} A_{\sigma}]^{1/2} \quad (13)$$

The coefficient of variation in P_{32} for a constant value of P_{31} is therefore given by,

$$\left(\frac{P_{32}}{P_{32}}\right) \approx \left(\frac{A_{\sigma}}{A_{\mu}}\right) \quad (14)$$

This degree of variability is sufficient to cause the hydraulic properties of the networks to range from poorly connected to well beyond the percolation threshold. This demonstrates the danger of relying on P_{31} as a specification of fracture intensity.

5. CONCLUSIONS

Both fracture spacing (S_f) and fracture length per unit area on a trace plane (P_{22}) can be used to derive three dimensional measures for intensity. Intensity measure P_{32} provides a useful three dimensional measure of intensity which is independent of fracture size, and is not affected by the scale of the region analyzed. Definition of intensity in terms of fractures per unit area (P_{21}) or fractures per unit volume (P_{31}) can produce a variety of problems in interpretation and simulation. The collection of intensity measure P_{22} in the field provides a more reliable measure of intensity than fracture spacing S_f .

The use of P_{21} and P_{31} as intensity measures in numerical modelling should be discouraged, due to the scale and fracture size dependence of these measures.

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SYMBOLS

P_{11} - P_{33}	Fracture Intensity Measures
S_f	Fracture spacing as measured on a borehole or scanline
S'_f	Fracture spacing as measured on the normal to a fracture set
S''_f	Expected value of fracture spacing as measured on a random line
θ	Angle between measurement line and mean orientation pole
$\bar{\theta}$	Mean angle between measurement line and mean orientation pole
C_{P2}	Constant of proportionality between spacing and intensity measure P_{22}
C_{P3}	Constant of proportionality between spacing and intensity measure P_{32}
A	Fracture Area
t	Fracture Thickness
$f_x(x)$	Probability Density Function ("distribution")
μ	Mean (as subscript)
σ	Standard deviation (as subscript)
σ^2	Variance (standard deviation squared), (as subscript)