VG 101 Project Group 40 Proposal

- 1. Group 40
- 2. Group member:
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- 4. Dancing Robot
- 5. MATLAB
- 6. Summary
- 1. An on-screen robot that can dance. Its movement can be either automatically generated or customized.
- 2. Motivation:
- 1. Make a funny game that helps people relax
- 2. Help people design dance
- 3. Tentative Design of your project (several paragraphs and some figures if you would like)
- 1. Features of your software and its corresponding description
 - 1. 2D or 3D dancing robot
 - 2. Automatic dancing: The robot can dance with random movements
 - 3. Customizable dancing: User can design some movements for the robot
 - Customizable skin: User can change colour or shape of the robot. Imported images can also be attached to the robot
 - 5. Multiple robots dancing together
- 2. Data dictionary or datagram demonstrating the structure or the interaction of different building blocks
 - 2D and 3D robots will have similar model, but the control of 3D robot is more complicated
 - 2. Automatic dancing and customizable dancing will share a control function, but the input of the former is randomized
- 3. Expected outcome
- 1. Bottom-line: List of features that you will accomplish before the deadline no matter what
- 2. 2D dancing robot with
 - 1. Customizable skin
 - 2. Customizable movement
 - 3. Random movement
- 1. Expected: List of features that you think you can accomplish before the deadline
 - 1. Adjustable pace of movements
 - 2. 3D dancing robot with all features above

- 3. Scene effect (e.g. flame)
 - 4. Multiple robots dancing together
- 2. Potential: List of features that you hope to accomplish before the deadline
 - 1. Automatically dancing with given music
- 3. Timetable:

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Tasks	Scheduled start time	Planned time	Actual start time	Completion	day 1	2 3	4	5	6 7	7 8	3 9	10	11	12	13	14	15	16 1	17 1	8 1	9 20	21	22	23 7	24 2	5 2	27	28	29	30
2D dancing robot	1	20	1	25%																										
Customizable skin	1	10	1	10%																										
GUI	1	20	1	25%																										
Scene effect	16	25	0	0%																										
Customizable movement	10	25	0	0%																										
Movement Design	1	20	1	25%																										
3D dancing robot	20	30	0	0%																										
Random movement	10	25	0	0%																										

- 4. Extra preparations: To accomplish your goal, what extra topics or knowledge you plan to learn
 - 1. Figure in 3D
 - 2. GUI
 - 3. Image processing and display
 - 4. Audio processing (potential)
- 5. Task assignment: Who will accomplish which part, we expect every group member has the equal workload.

1. Su Zhenxuan: model constructing

2. Tang Yuxuan: Image3. Wei Xiwen: GUI