

# A Random Matrix Approach to Graph Convolutional Networks

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## 1 Introduction and system model

Graph convolutional networks (GCNs) proposed by [Kipf and Welling \(2017\)](#) is an efficient way to mine graph-type data. Its theoretical properties, however, remain less clear.

Consider an undirected graph  $G$  having  $n$  nodes, with symmetric adjacency matrix  $\mathbf{A} \in \{0, 1\}^{n \times n}$ . A GCN is constructed by considering the following layer-wise propagation rule: The output feature  $\Sigma_{\ell+1} \in \mathbb{R}^{d_{\ell+1} \times n}$  of layer  $\ell + 1$  is given by

$$\Sigma_{\ell+1} = \sigma(\mathbf{W}_\ell \Sigma_\ell \mathbf{D}_\gamma^{-\alpha} \mathbf{A}_\gamma \mathbf{D}_\gamma^{-\alpha}) \equiv \sigma(\mathbf{W}_\ell \Sigma_\ell \mathbf{L}_\alpha), \quad (1)$$

with  $\Sigma_\ell \in \mathbb{R}^{d_\ell \times n}$  the input feature of layer  $\ell + 1$  (with the convention that  $\Sigma_0 = \mathbf{X} \in \mathbb{R}^{d_0 \times n}$ ), (trainable) output weights  $\mathbf{W}_\ell \in \mathbb{R}^{d_{\ell+1} \times d_\ell}$  of layer  $\ell$ ,

$$\mathbf{L}_{\alpha, \gamma} \equiv \mathbf{D}_\gamma^{-\alpha} \mathbf{A}_\gamma \mathbf{D}_\gamma^{-\alpha}, \quad (2)$$

the so-called  $\alpha$ -normalized Laplacian of [A Ali and Couillet \(2018\)](#), and

$$\mathbf{A}_\gamma \equiv \mathbf{A} + \gamma \mathbf{I}_n \in \mathbb{R}^{n \times n}, \quad (3)$$

the adjacency with added self-connections of strength  $\gamma \in \mathbb{R}$ , diagonal  $\mathbf{D}_\gamma \equiv \text{diag}(\mathbf{d}_\gamma) \in \mathbb{R}^{n \times n}$  that contains the degrees  $\mathbf{d}_\gamma \equiv \mathbf{A}_\gamma \mathbf{1}_n \in \mathbb{R}^n$  of  $\mathbf{A}_\gamma$  so that  $\mathbf{D}_\gamma = \mathbf{D} + \gamma \mathbf{I}_n$ , for  $\mathbf{D} \equiv \text{diag}(\mathbf{d})$  containing the degree of  $\mathbf{A}$ .

Under the propagation rule in (1), the  $n$ -dimensional output of the layer  $\ell$  of all  $n$  nodes is given by  $\beta^\top \Sigma_\ell \mathbf{L}_{\alpha, \gamma} \in \mathbb{R}^n$ , for  $\beta \in \mathbb{R}^{d_\ell}$  the output weight vector. We consider the ridge regressor  $\beta_r \in \mathbb{R}^{d_\ell}$  that minimizes the following MSE

$$L(\beta) = \|\mathbf{y}^\top \text{diag}(\mathbf{1}_{\text{train}}) - \beta^\top \Sigma_\ell \mathbf{L}_{\alpha, \gamma} \text{diag}(\mathbf{1}_{\text{train}})\|^2 + r \|\beta\|^2, \quad (4)$$

with target/label vector  $\mathbf{y} \in \mathbb{R}^n$  associated to  $\mathbf{X} \in \mathbb{R}^{d_0 \times n}$  composed of both training  $\mathbf{y}_{\text{train}} \in \mathbb{R}^{n_{\text{train}}}$  and test (unknown)  $\mathbf{y}_{\text{test}} \in \mathbb{R}^{n_{\text{test}}}$  as

$$\mathbf{y}^\top = \begin{bmatrix} \mathbf{y}_{\text{train}}^\top & \mathbf{y}_{\text{test}}^\top \end{bmatrix}, \quad (5)$$

and  $\mathbf{1}_{\text{train}} \in \mathbb{R}^n$  the indicator vector of labelled nodes, with its  $i$ th entry given by  $[\mathbf{1}_{\text{train}}]_i = \delta_{\mathbf{x}_i \in \mathbf{X}_{\text{train}}}$ . The

solution to (4) is explicitly given by

$$\beta_r = \left( \Sigma_\ell \mathbf{L}_{\alpha, \gamma} \text{diag}(\mathbf{1}_{\text{train}}) \mathbf{L}_{\alpha, \gamma} \Sigma_\ell^\top + r \mathbf{I}_{d_\ell} \right)^{-1} \Sigma_\ell \mathbf{L}_{\alpha, \gamma} \text{diag}(\mathbf{1}_{\text{train}}) \mathbf{y}. \quad (6)$$

## 2 Research objective

We aim to characterize the asymptotic behavior of the following quantities

1. Training MSE  $E_{\text{train}} = \|\mathbf{y}^\top \text{diag}(\mathbf{1}_{\text{train}}) - \beta_r^\top \Sigma_\ell \mathbf{L}_{\alpha, \gamma} \text{diag}(\mathbf{1}_{\text{train}})\|^2$  with  $\beta_r$  given in (6).
2. Test MSE  $E_{\text{test}} = \|\mathbf{y}^\top \text{diag}(\mathbf{1}_{\text{test}}) - \beta_r^\top \Sigma_\ell \mathbf{L}_{\alpha, \gamma} \text{diag}(\mathbf{1}_{\text{test}})\|^2$  with  $\beta_r$  given in (6).
3. And possibly the misclassification error rate on a test datum if we put additional statistical assumption on the data.

We propose to perform theoretical studies of the above GCN model under the following assumptions:

1. High-dimensional asymptotics: the graph size  $n$  and the dimension  $d_\ell$ ,  $\ell = 0, \dots$ , all go to infinity.
- 2.1 The underlying graph follows a Contextual Stochastic Block Model (CSBM) in the sense that, or
- 2.2 The underlying graph follows a Degree-Correlated Stochastic Block Model (DC-SBM), or the hierarchical stochastic block model, or the mixed-membership block model, and the data at each node is deterministically given and satisfy  $\|\mathbf{X}\| < \infty$ .

We wish the proposed theoretical results could shed some novel light on

1. double descent on GCN
2. optimal choice of  $\alpha$ -normalized Laplacian in GCN
3. impact of nonlinear activation in nonlinear GCN
4. heterophily, homophily versus positive and negative self-loops in GCNs
5. over-squashing and over-smoothing in deep GCNs
6. invariance and/or equivalence properties of GCNs [Keriven and Peyré \(2019\)](#)

We would like to cover both the shallow nonlinear case and the deep linear case with random weights, as well as a possible extension to deep nonlinear setting via the NTK approach [Du et al. \(2019\)](#).

## 3 Related reading

1. [Kipf and Welling \(2017\)](#): the original paper that introduces GCNs;
2. [Shi et al. \(2022\)](#) on a statistical mechanics approach to large-dimensional analysis of GCNs;
3. [Esser et al. \(2021\)](#); [Keriven et al. \(2020\)](#); [Li et al. \(2018\)](#); [Verma and Zhang \(2019\)](#); [Zhou and Wang \(2021\)](#) for some statistical learning theory of GCN model
4. [Cai and Wang \(2020\)](#); [Wu et al. \(2022\)](#) on theoretical and/or empirical perspective of over-smoothing, and [Di Giovanni et al. \(2023\)](#); [Giraldo et al. \(2022\)](#); [Topping et al. \(2022\)](#) on over-squashing in deep GCNs

5. Ali and Couillet (2018); Couillet et al. (2016) and (Couillet and Liao, 2022, Chapter 2) for related works as well as technical tools on the topic of random matrix theory.

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