The Dynamics of Learning: A Random Matrix Approach ICML 2018, Stockholm, Sweden

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Outline

Motivation

- Problem Statement
- Main Results
- Summary

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- (explicit or implicit) regularization: early stopping, l_2 -penalization

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A toy model of binary classification:

Gaussian mixture data

Consider data \mathbf{x}_i drawn from a two-class Gaussian mixture model: for a=1,2

$$\mathbf{x}_i \in \mathcal{C}_a \Leftrightarrow \mathbf{x}_i = (-1)^a \boldsymbol{\mu} + \mathbf{z}_i$$

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Random Matrix Theory is the answer!

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- \bullet Cauchy's integral formula to express the functional $\exp(\cdot)$ via contour integration
 - ⇒ Network performance at any time is in fact deterministic and predictable!

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Proposed analysis framework

Resolvent and deterministic equivalents

Consider an $n \times n$ Hermitian random matrix M. Define its resolvent $\mathbf{Q}_{\mathbf{M}}(z)$, for $z \in \mathbb{C}$ not eigenvalue of M

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Cauchy's integral formula

Example: for $f(\mathbf{M}) = \mathbf{a}^{\mathsf{T}} e^{\mathbf{M}} \mathbf{b}$,

$$f(\mathbf{M}) = -\frac{1}{2\pi i} \oint_{\gamma} \exp(z) \mathbf{a}^{\mathsf{T}} \mathbf{Q}_{\mathbf{M}}(z) \mathbf{b} dz$$

with γ a positively oriented path circling around all the eigenvalues of M.

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For certain simple distributions of M, define a so-called deterministic equivalent \bar{Q}_M of Q_M : a deterministic matrix such that

- $\frac{1}{n} \operatorname{tr} (\mathbf{A} \mathbf{Q}_{\mathbf{M}}) \frac{1}{n} \operatorname{tr} (\mathbf{A} \bar{\mathbf{Q}}_{\mathbf{M}}) \to 0$
- $\mathbf{a}^{\mathsf{T}} \left(\mathbf{Q}_{\mathbf{M}} \bar{\mathbf{Q}}_{\mathbf{M}} \right) \mathbf{b} \to 0$

almost surely as $n \to \infty$, with $\mathbf{A}, \mathbf{a}, \mathbf{b}$ of bounded norm (operator and Euclidean).

 \Rightarrow Study $\bar{\mathbf{Q}}_{\mathbf{M}}$ instead of the random $\mathbf{Q}_{\mathbf{M}}$ for n large!

However, for more sophisticated functionals of M:

Cauchy's integral formula

Example: for $f(\mathbf{M}) = \mathbf{a}^{\mathsf{T}} e^{\mathbf{M}} \mathbf{b}$,

$$f(\mathbf{M}) = -\frac{1}{2\pi i} \oint_{\gamma} \exp(z) \mathbf{a}^{\mathsf{T}} \mathbf{Q}_{\mathbf{M}}(z) \mathbf{b} dz \approx -\frac{1}{2\pi i} \oint_{\gamma} \exp(z) \mathbf{a}^{\mathsf{T}} \bar{\mathbf{Q}}_{\mathbf{M}}(z) \mathbf{b} dz.$$

with γ a positively oriented path circling around all the eigenvalues of M.

To evaluate test performance: $\mathbf{w}(t)^\mathsf{T} \hat{\mathbf{x}} \sim \mathcal{N}(\pm \mathbf{w}(t)^\mathsf{T} \boldsymbol{\mu}, \|\mathbf{w}(t)\|^2)$ with $\mathbf{w}(t) = e^{-\frac{\alpha t}{n} \mathbf{X} \mathbf{X}^\mathsf{T}} \mathbf{w}_0 + \left(\mathbf{I}_p - e^{-\frac{\alpha t}{n} \mathbf{X} \mathbf{X}^\mathsf{T}}\right) (\mathbf{X} \mathbf{X}^\mathsf{T})^{-1} \mathbf{X} \mathbf{y}$. For $\mathbf{w}(t)^\mathsf{T} \boldsymbol{\mu}$:

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Not really understandable, nor interpretable. . .

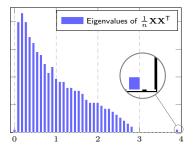


Figure: Eigenvalue distribution of $\frac{1}{n}\mathbf{X}\mathbf{X}^{\mathsf{T}}$ for $\boldsymbol{\mu}=[1.5;\mathbf{0}_{p-1}],\,p=512,\,n=1\,024$ and $c_1=c_2=1/2$.

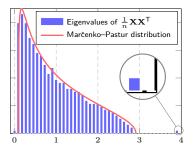


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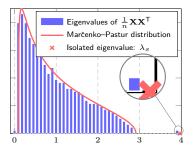


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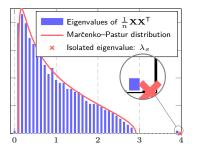


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- **9** How much we over-fit? As $t \to \infty$, the performance drop by a factor $\sqrt{1 \min(c, c^{-1})}$, with $p/n \to c \in (0, \infty)$.

Numerical validations

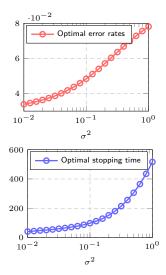
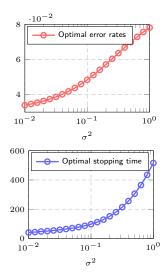


Figure: Optimal performance and stopping time as function of σ^2 with c=1/2, $\|\mu\|^2=4$ and $\alpha=0.01.$

Numerical validations



O.5 Simulation: training performance

× Theory: training performance

Simulation: generalization performance

Theory: generalization performance

O.2

O.1

O.2

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O.2

Training time (t)

Figure: Training and generalization performance for MNIST data (number 1 and 7) with $n=p=784,\,c_1=c_2=1/2,\,\alpha=0.01$ and $\sigma^2=0.1.$ Results averaged over 100 runs.

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Outline

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- Problem Statement
- Main Results

Summary

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- easily extended to more elaborate data models: e.g., Gaussian mixture model with different means and covariances
- ullet a byproduct: choose the initialization variance σ^2 even smaller!

Thank you

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Any question? Poster # 189!