view\_frames Result Recorded at time: 25.568 robot\_footprint Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (25.568 sec old) Buffer length: 0.000 sec chassis Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.204 Hz Average rate: 10.204 Hz Most recent transform: 25.500 (0.068 sec old) Most recent transform: 0.000 (25.568 sec old) Most recent transform: 0.000 (25.568 sec old) Most recent transform: 25.500 (0.068 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.900 sec Buffer length: 4.900 sec hokuyo  $L_{wheel}$ R\_wheel camera