# Variational Graph Recurrent Neural Networks

## Introduction

- Existing dynamic graph embedding approaches represent each node by a deterministic vector in
  - a low-dimensional space
- Such deterministic representations lack the capability of modeling uncertainty of node embedding
- This paper first introduces dynamic graph autoencoder (**GRNN**), then to increase the expressive power of GRNN in addition to modeling the uncertainty of node latent representations, variational graph recurrent neural network (**VGRNN**) is introduced

## **Background**

- GCRN aims to model dynamic node attributes defined over a static graph whereas GRNN applies on dynamic graph
- GRNN reconstruct the graph at time t by **decoding** hidden state  $h_t$
- By introducing VGRNN, we can capture time dependencies between graphs, but also each node is represented with a distribution in the latent space (similar to variational autoencoder).

## **VGRNN** model

- VGAE in our VGRNN learns the prior distribution parameters based on the hidden states in previous time steps.
- Hence, our VGRNN allows more flexible latent representations with greater expressive power that captures dependencies between and within topological and node attribute evolution processes

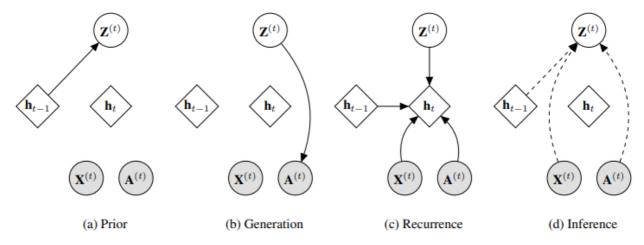


Figure 1: Graphical illustrations of each operation of VGRNN; (a) computing the conditional prior by (2); (b) decoder function (3); (c) updating the GRNN hidden states using (4); and (d) inference of the posterior distribution for latent variables by (3.2).

Objective functions:
The first term is the reconstruction lost, while second term is approximating prior to posterior

$$\mathcal{L} = \sum_{t=1}^{T} \left\{ \mathbb{E}_{\mathbf{Z}^{(t)} \sim q\left(\mathbf{Z}^{(t)} \mid \mathbf{A}^{(\leq t)}, \mathbf{X}^{(\leq t)}, \mathbf{Z}^{(< t)}\right)} \log p\left(\mathbf{A}^{(t)} \mid \mathbf{Z}^{(t)}\right) - \mathbf{KL}\left(q\left(\mathbf{Z}^{(t)} \mid \mathbf{A}^{(\leq t)}, \mathbf{X}^{(\leq t)}, \mathbf{Z}^{(< t)}\right) \mid\mid p\left(\mathbf{Z}^{(t)} \mid \mathbf{A}^{(< t)}, \mathbf{X}^{(< t)}, \mathbf{Z}^{(< t)}\right)\right) \right\}.$$
(7)

#### Reference

Original paper