

## 1. Eigen ~~Vec~~ Values

(1)  $A$  is a matrix, if  $\lambda$  is ~~an eigen value~~ a solution to  $\det(\lambda I - A) = 0$ , then  $\lambda$  is an eigenvalue.

(2) If  $\vec{v} \neq 0$ , satisfies  $A\vec{v} = \lambda\vec{v}$  (or  $(A - \lambda I)\vec{v} = 0$ ), then  $\vec{v}$  is an eigenvector corresponds to  $\lambda$ .

(i)  $A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$   $\det A = a_{11}a_{22} - a_{12}a_{21}$

(ii)  $A = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}$   $A = \begin{aligned} & (a_{11}a_{22}a_{33} + a_{13}a_{32}a_{21} + a_{12}a_{23}a_{31}) \\ & - (a_{21}a_{32}a_{13} + a_{13}a_{22}a_{31} + a_{11}a_{32}a_{23}) \end{aligned}$

$$A = \begin{pmatrix} -3 & -2 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & -2 \end{pmatrix} \quad \det(\lambda I - A) = \begin{vmatrix} \lambda+3 & 2 & 0 \\ -1 & \lambda+1 & 0 \\ 0 & 0 & \lambda+2 \end{vmatrix}$$

$$= (\lambda+2)(\lambda^2+4\lambda+3+2)$$

$$= (\lambda+2)[(\lambda+2)^2+1]$$

$$\lambda_1 = -2, \lambda_2 = -2-i, \lambda_3 = -2+i$$



$$x' = Ax$$

Case 1: If  $\lambda_1 \neq \lambda_2 \neq \dots \neq \lambda_n$  are eigenvalues of  $A$ ,  
 $\vec{r}_1, \dots, \vec{r}_n$  are corresponding eigenvectors,

$$\text{then } \vec{x} = c_1 e^{\lambda_1 t} \vec{r}_1 + \dots + c_n e^{\lambda_n t} \vec{r}_n$$

Case 2:  $\lambda$  is repeated

~~Case 2a:  $\lambda = \lambda_1 = \lambda_2$  is repeated for 2~~

1° We can find linearly independent eigenvectors  
 $\vec{r}_1, \dots, \vec{r}_m$  corresponding to the repeated eigenvalue

$\lambda = \lambda_1 = \dots = \lambda_m$ , then

$$\vec{x} = c_1 \vec{r}_1 e^{\lambda t} + c_2 \vec{r}_2 e^{\lambda t} + \dots + c_m \vec{r}_m e^{\lambda t}$$

is a solution.

2°  $A \in \mathbb{R}^{2 \times 2}$ , and  $\lambda_1 = \lambda_2$ , but matrix  
 is degenerate (can not find two linearly  
 independent eigenvectors).

$$(1) (A - \lambda I) \vec{r}_1 = \vec{r}_2$$

$$(2) (A - \lambda I) \vec{r}_2 = \vec{r}_1$$

then  $c_1 k_1 e^{\lambda t} + c_2 (k_2 + t k_1) e^{\lambda t}$  is a solution



$$x' = \begin{pmatrix} 0 & -9 \\ 1 & 0 \end{pmatrix} x$$

Step 1:  $\det(\lambda I - A) = \begin{vmatrix} \lambda & 9 \\ -1 & \lambda \end{vmatrix} = \lambda^2 + 9 = 0$

$$\Rightarrow \lambda_1 = 3i, \lambda_2 = -3i$$

Step 2: (1)  $(3i - A) \vec{k}_1 = \begin{pmatrix} 3i & 9 \\ -1 & 3i \end{pmatrix} \begin{pmatrix} k_{11} \\ k_{12} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$$\begin{cases} 3ik_{11} + 9k_{12} = 0 \\ -k_{11} + 3ik_{12} = 0 \end{cases} \Rightarrow k_{11} = 3ik_{12} \quad \vec{k}_1 = \begin{pmatrix} 3i \\ 1 \end{pmatrix}$$

(2)  $(-3i - A) \vec{k}_2 = \begin{pmatrix} -3i & 9 \\ -1 & -3i \end{pmatrix} \begin{pmatrix} k_{21} \\ k_{22} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$$k_{21} = -3ik_{22} \quad \vec{k}_2 = \begin{pmatrix} -3i \\ 1 \end{pmatrix}$$

Step 3:  $y = c_1 e^{3it} \vec{k}_1 + c_2 e^{-3it} \vec{k}_2$

$$= c_1 (\cos 3t + i \sin 3t) \begin{pmatrix} 3i \\ 1 \end{pmatrix} + c_2 (\cos 3t - i \sin 3t) \begin{pmatrix} -3i \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} -3(c_1 + c_2) \sin 3t \\ (c_1 + c_2) \cos 3t \end{pmatrix} + i \begin{pmatrix} 3(c_1 - c_2) \cos 3t \\ (c_1 - c_2) \sin 3t \end{pmatrix}$$



$$y = \hat{c}_1 \begin{pmatrix} 3 \sin 3t \\ \cos 3t \end{pmatrix} + \hat{c}_2 \begin{pmatrix} 3 \cos 3t \\ \sin 3t \end{pmatrix} = x$$

$$0 = A^T x = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} x = (A - I)x = 0 \quad \therefore 1 \text{ gets } 2$$

$$x' = \begin{pmatrix} -2 & 1 \\ 0 & -2 \end{pmatrix} x, \quad x(0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\text{Step 1: } \det(\lambda I - A) = \begin{vmatrix} \lambda + 2 & -1 \\ 0 & \lambda + 2 \end{vmatrix} = (\lambda + 2)^2 = 0$$

$$\lambda_1 = \lambda_2 = -2$$

$$\text{Step 2: (1) } (\lambda I - A) \vec{r}_1 = 0 \quad \begin{pmatrix} 0 & -1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} r_{11} \\ r_{12} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow r_{12} = 0 \quad \text{One can not find 2 linearly independent eigenvectors}$$

$$\vec{r}_1 = \begin{pmatrix} r_{11} \\ 0 \end{pmatrix} \Rightarrow \vec{r}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$(2) (\lambda I - A) \vec{r}_2 = \vec{r}_1 \Rightarrow \begin{pmatrix} 0 & -1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} r_{21} \\ r_{22} \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$r_{22} = -1, \quad \vec{r}_2 = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

$$\text{Step 3: } x = c_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} e^{-2t} + c_2 \left( \begin{pmatrix} 0 \\ -1 \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \end{pmatrix} t \right) e^{-2t} = \begin{pmatrix} c_1 e^{-2t} + c_2 t e^{-2t} \\ -c_2 e^{-2t} \end{pmatrix}$$

$$x(0) = \begin{pmatrix} c_1 \\ -c_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \Rightarrow x = \begin{pmatrix} e^{-2t} \\ 0 \end{pmatrix}$$

$$X = \begin{pmatrix} 0 & 1 & -1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix} X = (A - I) X$$

$$\text{Step 1: } \det(\lambda I - A) = \begin{vmatrix} \lambda - 1 & -1 & 1 \\ 1 & \lambda & -1 \\ -1 & -1 & \lambda \end{vmatrix} = \lambda^3 - 3\lambda - 2$$

$$= \lambda^2 - \lambda - 2\lambda - 2$$

$$= \lambda(\lambda^2 - 1) - 2(\lambda + 1)$$

$$= \lambda(\lambda + 1)(\lambda - 1) - 2(\lambda + 1)$$

$$= (\lambda + 1)(\lambda^2 - 2)$$

$$= (\lambda + 1)^2(\lambda - 2)$$

$$\lambda_1 = \lambda_2 = -1, \lambda_3 = 2$$

$$\text{Step 2: (i)} \quad (\lambda_1 I - A) \vec{r}_1 = \begin{pmatrix} 0 & 1 & -1 \\ 1 & 0 & 1 \\ -1 & -1 & 0 \end{pmatrix} \begin{pmatrix} r_{11} \\ r_{12} \\ r_{13} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow r_{11} = -(r_{12} + r_{13}), \vec{r}_1 = \begin{pmatrix} -r_{12} - r_{13} \\ r_{12} \\ r_{13} \end{pmatrix}$$

two linearly independent eigenvector

$$\vec{r}_1 = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}, \vec{r}_2 = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$



$$12) (\lambda I - A) \vec{k}_3 = \begin{pmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{pmatrix} \vec{k}_3 = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow k_{31} = k_{32} = k_{33} = (A - I) \text{ to } 0.1 \text{ per}$$

$$\Rightarrow \vec{k}_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

Step 3:  $X = c_1 \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} e^{-t} + c_2 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} e^{-t} + c_3 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} e^{2t}$

$$= \begin{pmatrix} -c_1 e^{-t} - c_2 e^{-t} + c_3 e^{2t} \\ c_1 e^{-t} + c_3 e^{2t} \\ c_2 e^{-t} + c_3 e^{2t} \end{pmatrix}$$

Step 1: Get eigenvalues

Step 2: Calculate eigenvectors,

and if there are not enough eigenvectors, calculate  $(\lambda I - A) \vec{k}_2 = \vec{k}_1$

Step 3:  $\vec{X} = \underline{\hspace{2cm}}$