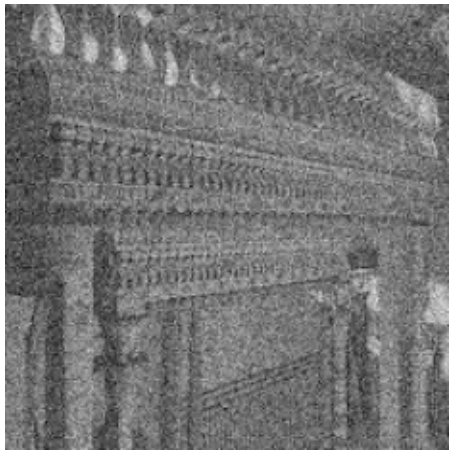


$S'_L(x, y)$ 

Noisy Images

 $S'_R(x, y)$ 