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## **Pyramidal Central Configurations** for Spatial 5-Body Problems

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Abstract: In this paper, classifications are studied for all pyramidal central configurations with a regular trapezoid base. In fact, there are two such central configurations that the base is a regular trapezoid. From the results it is easy to obtain the classfications of pyramidal central configurations with rectangular base.

Key words: N-body problems; pyramidal central configuration; classification

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## Introduction and Main Results

N-body problems ([1,2]) are related with the motion of masses  $m_1, \cdots, m_N$  under the action of Newton' s gravitation:

$$m_i \, \overline{q_i} = \frac{\partial U(\overline{q})}{\partial \overline{q_i}} \quad 1 \leqslant i \leqslant N$$
 (1)

where  $\overline{q}_i \in R^3$ ,  $\overline{q} = (\overline{q}_1, \dots, \overline{q}_N)$  and

$$U(\overline{q}) = \sum_{1 \le i < j \le N} \frac{m_i m_j}{|\overline{q}_i - \overline{q}_j|}$$
 (2)

is the potential engergy of the system

Define

$$X = \{\overline{q} = (\overline{q}_1, \dots, \overline{q}_N) \in R^{3N} : \sum_{i=1}^N m_i \overline{q}_i = 0\}(3)$$

$$\Delta_{ij} = \{ \overline{q} = (\overline{q}_1, \dots, \overline{q}_N) \in R^{3N} : \overline{q}_i = \overline{q}_j \}$$

$$1 \leq i, j \leq N$$

$$\Delta = U_{i < j} \Delta_{ij} \tag{5}$$

The set  $X \setminus \Delta$  is called the configuration space.

Definition 1([3 ~ 6]) A point  $\overline{q} = (\overline{q}_1, \dots, \overline{q}_N)$  $\in X \setminus \Delta$  is a central configuration (c.c.) if there exists a constant \( \lambda \) such that

$$\sum_{j=1,j\neq i}^{N} \frac{m_j m_i}{|\overline{q}_j - \overline{q}_i|^3} (\overline{q}_j - \overline{q}_i) = -\lambda m_i \overline{q}_i$$

$$1 \leqslant i \leqslant N \tag{6}$$

Where

$$\lambda = \frac{U}{I} \tag{7}$$

$$I = \sum_{i=1}^{N} m_i \mid \overline{q}_i \mid^2 \tag{8}$$

**Definition** 2([2]) A central configuration of Nbodies, N-1 of which are coplanar, the  $N \, {\rm th}$  being off the plane, is called a pyramidal central configuration(p. c.c). Equivalently, we will say that the c.c. has the shape of a pyramid.

Theorem 1 The necessary and sufficient conditions that the configuration with a regular trapezoid base is a pyramidal central configuration of five bodies are

1) The mutual distances are such that  $D_{5i} = D_{5j}$ , 1  $\leq i, j \leq 4$  and

$$h + l - 2g = 0 \tag{9}$$

where  $D_{ij} = |\overline{q}_i - \overline{q}_j|$  for  $1 \le i, j \le 5$ 

$$h = \frac{1}{D_{21}^3} = \frac{1}{D_{34}^3}$$
  $l = \frac{1}{D_{31}^3} = \frac{1}{D_{24}^3}$ 

$$g = \frac{1}{D_{5i}^3} \qquad D_{41} = 2b \qquad D_{23} = 2a$$

and h.l.g can be represented by a, b.

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2) The masses are such that  $m_1 = m_4$ ,  $m_2 = m_3$ ,  $m_5$  is arbitary and

$$m_2 a (h - g) = m_1 b \left( \frac{1}{(2b)^3} - g \right)$$
 (10)

$$m_2 a = \left(\frac{1}{(2a)^3} - g\right) = m_1 b(h - g)$$
 (11)

#### 2 Some general lemmas

Lemma 1 Let  $\overline{q}=(\overline{q}_1,\cdots,\overline{q}_N)$  be a p.c.c such that  $\overline{q}_N$  is at the top vertex which is off the plane containing  $m_1,\cdots,m_{N-1}$ , then  $m_N$  is equidistant from  $m_1,\cdots,m_{N-1}$ .

**Proof** Since  $\overline{q}=(\overline{q}_1,\cdots,\overline{q}_N)$  forms a c. c then there exists a scalar  $\lambda$  such that

$$\sum_{j=1,j\neq i}^{N} \frac{m_j m_i}{|\overline{q}_j - \overline{q}_i|^3} (\overline{q}_j - \overline{q}_i) = -\lambda m_i \overline{q}_i$$

$$\begin{array}{c}
\mathbf{1} \leqslant i \leqslant N \\
-
\end{array} \tag{12}$$

Writing  $\overline{q}_i = (\overline{x}_i, \overline{y}_i, \overline{z}_i) \in R^3$  in terms of its coordinate, and  $D_{ji} = |\overline{q}_j - \overline{q}_i|$  for  $1 \leq i, j \leq N$ . Since the masses  $m_1, \dots, m_{N-1}$  lie on a common plane, we may assume then, whithout loss of generality, that this plane is parallel to  $G_{\overline{x}}$ , hence  $\overline{y}_1 = \overline{y}_2 = \dots = \overline{y}_{N-1}$ . Multiplying (12) by  $\overline{y}$  which is the unit vector of  $\overline{y}$ -direction. We obtain

$$\sum_{j=1, j\neq i}^{N} \frac{m_{j}m_{i}}{D_{ji}^{3}} (\overline{q_{j}} - \overline{q_{i}}) \overline{y} = -\lambda m_{i}\overline{q_{i}} \overline{y},$$

$$1 \leqslant i \leqslant N \tag{13}$$

From (13), for i = 1, i = 2, obviously we can get

$$\frac{m_N m_1}{D_{N1}^3} (\overline{y}_N - \overline{y}_1) = -\lambda m_1 \overline{y}_1 \tag{14}$$

$$\frac{m_N m_2}{D_{N2}^3} (\bar{y}_N - \bar{y}_2) = -\lambda m_2 \bar{y}_2$$
 (15)

Hence (14), (15) give

$$m_N \left( \frac{1}{D_{N1}^3} - \frac{1}{D_{N2}^3} \right) (\bar{y}_N - \bar{y}_1) = 0$$
 (16)

Since  $\overline{y}_N - \overline{y}_1 \neq 0$  otherwise  $m_1, \dots, m_N$  are coplanar which is contradict to definition 2 then

$$D_{N1} = D_{N2}$$

Similarily, we readily obtain

$$D_{Ni} = D_{Nj}$$
  $1 \leqslant i, j \leqslant N-1$ 

i.e.  $m_N$  is equidistant from  $m_1, \dots, m_{N-1}$ .

**Remark** The masses  $m_1, \dots, m_{N-1}$  are concyclic.

In fact, they lie on the intersection of a plane with a sphere, for they are coplanar by assumption, and they

belong to a sphere centered at  $m_N$  by Lemma 1.

Lemma 2 If  $\overline{q} = (\overline{q}_1, \dots, \overline{q}_N)$  is a p.c.c then  $\lambda$  mg, where  $m = m_1 + \dots + m_N$  is the total masse and  $= \frac{1}{D_{Ni}^3}, 1 \leqslant i \leqslant N - 1$ .

**Proof** Denote by Oxyz, the coordinate system of tained from  $G \, \overline{x} \, y \, \overline{z}$  by parallel than slation to a new or gin  $O \in P$  containing  $m_1, \cdots, m_{N-1}$ . Let  $q_1, \cdots, q_N$  the position vectors of  $m_1, \cdots, m_N$  in Oxyz. Obviously

$$\overline{OG} = \frac{1}{m} \sum_{i=1}^{N} m_i q_i \tag{1}$$

Since  $\overline{q} = (\overline{q}_1, \cdots, \overline{q}_N)$  is a c.c., there exists a  $\lambda$  such that

$$\sum_{j=1, j \neq i}^{N} \frac{m_j m_i}{|\overline{q}_j - \overline{q}_i|^3} (\overline{q}_j - \overline{q}_i) = -\lambda m_i \overline{q}_i$$

$$1 \leqslant i \leqslant N$$
(18)

Taking the scalar multiple of upper equation with which is a unit vector in  $\overline{y}$ -direction for  $i=1,\cdots,N$  an using  $\overline{q}_i=q_i-\overline{O}\overline{G}$ . We get

$$\sum_{j=1,j\neq i}^{N} \frac{m_{j}m_{i}}{|q_{j}-q_{i}|^{3}} (q_{j}-q_{i}) = -\lambda m_{i} (q_{i}-\overline{OG})$$

(19

that is

$$\sum_{j=1, j \neq i}^{N} \frac{m_j m_i}{|\overline{q}_j - \overline{q}_i|^3} (\overline{q}_j - \overline{q}_i) =$$

$$- \lambda m_i \left( \frac{1}{m} \sum_{i=1}^{N} m_j q_i - \frac{1}{m} \sum_{i=1}^{N} m_j q_j \right)$$
(20)

or

$$\sum_{j=1, j \neq i}^{N} \frac{m_j m_i}{|q_j - q_i|^3} (q_j - q_i) = \frac{\lambda}{m} m_i \sum_{j=1, j \neq i}^{N} m_j (q_j - q_i)$$
(21)

or

$$\sum_{i=1, i \neq i}^{N} m_i m_i \left( \frac{1}{D_{ii}^3} - \frac{\lambda}{m} \right) (q_j - q_i) = 0$$
 (22)

then

$$\sum_{j=1, j \neq i}^{N} m_{j} m_{i} \left( \frac{1}{D_{ji}^{3}} - \frac{\lambda}{m} \right) (q_{j} - q_{i}) \overline{y} = 0$$
 (23)

But  $\overline{y}$  is perpendicular to the plane P containing the vectors  $q_1, \dots, q_{N-1}$  then

$$m_N m_i \left( \frac{1}{D_{ii}^3} - \frac{\lambda}{m} \right) q_N \bar{y} = 0 \tag{24}$$

Hence

$$\lambda = \frac{m}{D_{Ni}^3} \qquad 1 \leqslant i \leqslant N - 1 \tag{25}$$

Note: The equation (18) holds if and only if the equation (22) holds.

## 3 Necessary Conditions of Pyramidal Central Configuration for Five-bodies

Assume  $m_1, m_2, m_3, m_4$  be coplanar and counterclockwise and  $P_1P_4$  parallel to  $P_2P_3$ . Since  $m_1, \cdots, m_4$  are concyclic, then  $D_{21} = D_{34}$ ,  $D_{42} = D_{31}$ . Denote by Oxyz, the coordinate system obtained from Gxyz by parallel translation to a new origin  $O \in P$  containing  $m_1, \cdots, m_4$ , at the middle point between  $P_1$  and  $P_4$  (see Figure 1). Let  $q_1, \cdots, q_5$  be the position vectors of  $m_1, \cdots, m_5$  in Oxyz. Then

$$q_1 = (0,0,b), q_2 = (c,0,a),$$
  
 $q_3 = (c,0,-a), q_4 = (0,0,-b)$ 

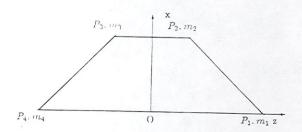


Figure 1 The regular trapezoid base

where c is distance between the line  $P_1P_4$  and the line  $P_2P_3$ . Obviously c>0, otherwise if c=0, then  $m_1$ ,  $m_2$ ,  $m_3$ ,  $m_4$  are colinear. But  $m_5$  is equidistant from  $m_1, \dots, m_4$ , then  $q_1=q_2, q_3=q_4$ . This is contradict to the definition of configuration space.

If  $\overline{q}=(\overline{q}_1,\cdots,\overline{q}_5)$  is a p.c.c., we have had

1) 
$$D_{5i} = D_{5j}$$
,  $1 \le i$ ,  $j \le 4$ 

2) 
$$\lambda = mg = \frac{m}{D_{5i}^3}, 1 \le i \le 4$$

By definition of p.c.c. we get

$$\sum_{j=1, j \neq i}^{5} \frac{m_j}{D_{ji}^3} (\bar{q}_j - \bar{q}_i) = -\lambda \bar{q}_i \qquad 1 \leqslant i \leqslant 5 \qquad (26)$$
that is

$$\sum_{j=1, j \neq i}^{5} \frac{m_{j}}{D_{ji}^{3}} (q_{j} - q_{i}) = -\lambda (q_{i} - \overline{OG})$$
 (27)

or

$$\sum_{j=1, j \neq i}^{5} m_{j} \left( \frac{1}{D_{ji}^{3}} - \frac{\lambda}{m} \right) (q_{j} - q_{i}) = 0$$
 (28)

using  $\frac{1}{D_{5i}^3} = \frac{\lambda}{m}$ ,  $1 \le i \le 4$ 

$$\sum_{j=1, j\neq i}^{4} m_j \left( \frac{1}{D_{ji}^3} - \frac{\lambda}{m} \right) (q_j - q_i) = 0$$
 (29)

Taking the scalar multiple with x which is a unit vector in x-direction we get for i = 1

$$m_2 \left( \frac{1}{D_{21}^3} - \frac{\lambda}{m} \right) c + m_3 \left( \frac{1}{D_{31}^3} - \frac{\lambda}{m} \right) c = 0$$
 (30)

for i = 2

$$m_1 \left( \frac{1}{D_{12}^3} - \frac{\lambda}{m} \right) (-c) + m_4 \left( \frac{1}{D_{42}^3} - \frac{\lambda}{m} \right) (-c) = 0$$
(31)

for i = 3

$$m_1 \left( \frac{1}{D_{13}^3} - \frac{\lambda}{m} \right) (-c) + m_4 \left( \frac{1}{D_{43}^3} - \frac{\lambda}{m} \right) (-c) = 0$$
(32)

for i = 4

$$m_2 \left(\frac{1}{D_{24}^3} - \frac{\lambda}{m}\right) c + m_3 \left(\frac{1}{D_{43}^3} - \frac{\lambda}{m}\right) c = 0$$
 (33)

Using c > 0, and

$$\frac{1}{D_{21}^3} = \frac{1}{D_{34}^3} = h; \frac{1}{D_{24}^3} = \frac{1}{D_{31}^3} = l; g = \frac{\lambda}{m} = \frac{1}{D_{5i}^3}$$
(34)

We have

for 
$$i = 1$$
  $m_2(h - g) + m_3(l - g) = 0$  (35)

for 
$$i = 2$$
  $m_1(h - g) + m_4(l - g) = 0$  (36)

for 
$$i = 3$$
  $m_1(l - g) + m_4(h - g) = 0$  (37)

for 
$$i = 4$$
  $m_2(l - g) + m_3(h - g) = 0$  (38)

Summing all the equation (35~38), obtain

$$(m_1 + m_2 + m_3 + m_4)(h + l - 2g) = 0$$
  
that is  $h + l - 2g = 0$  (39)

By 
$$(35-37)$$
, we obtain  $m_2(h-l) + m_3(l-h) = 0$ 

That is 
$$(m_2 - m_3)(h - l) = 0$$

Since h is not equal to l, hence

$$m_2 = m_3 \tag{40}$$

Similarily, (36), (37) which gives

$$m_1 = m_4 \tag{41}$$

Taking the scalar multiple with z which is a unit vector in z-direction for (29), we obtain

for i = 1

$$m_2 \left( \frac{1}{D_{21}^3} - \frac{\lambda}{m} \right) (a - b) + m_3 \left( \frac{1}{D_{31}^3} - \frac{\lambda}{m} \right) (-a - b) +$$

$$m_4 \left( \frac{1}{D_{41}^3} - \frac{\lambda}{m} \right) (-2b) = 0 \tag{42}$$

for i=2

$$m_1 \left( \frac{1}{D_{21}^3} - \frac{\lambda}{m} \right) (b - a) + m_3 \left( \frac{1}{D_{32}^3} - \frac{\lambda}{m} \right) (-2a) +$$

$$m_4 \left( \frac{1}{D_{42}^3} - \frac{\lambda}{m} \right) (-b - a) = 0 \tag{43}$$

for i = 3

$$m_1\left(\frac{1}{D_{31}^3}-\frac{\lambda}{m}\right)(b+a)+m_2\left(\frac{1}{D_{32}^3}-\frac{\lambda}{m}\right)(2a)+$$

$$m_4 \left( \frac{1}{D_{42}^3} - \frac{\lambda}{m} \right) (-b + a) = 0 \tag{44}$$

for i = 4

$$m_1 \left( \frac{1}{D_{41}^3} - \frac{\lambda}{m} \right) (2b) + m_2 \left( \frac{1}{D_{42}^3} - \frac{\lambda}{m} \right) (a + b) +$$

$$m_3\left(\frac{1}{D_{43}^3} - \frac{\lambda}{m}\right)(b-a) = 0 \tag{45}$$

that is

$$m_2(h-g)(a-b) + m_2(l-g)(-a-b) +$$

$$m_1 \left( \frac{1}{(2b)^3} - g \right) (-2b) = 0 \tag{46}$$

$$m_1(h-g)(b-a) + m_2\left(\frac{1}{(2a)^3}-g\right)(-2a) +$$

$$m_1(l-g)(-b-a) = 0 (47)$$

$$m_1(l-g)(b+a) + m_2\left(\frac{1}{(2a)^3} - g\right)(2a) +$$

$$m_1(h-g)(-b+a) = 0 (48)$$

$$m_1\left(\frac{1}{(2b)^3}-g\right)(2b)+m_2(l-g)(a+b)+$$

$$m_2(h-g)(b-a)=0$$
 (49)

Since h + l - 2g = 0, then

$$m_2 a(l-g) + m_1 b \left(\frac{1}{(2h)^3} - g\right) = 0$$
 (50)

$$m_2 a \left( \frac{1}{(2a)^3} - g \right) + m_1 b (l - g) = 0$$
 (51)

$$m_1 a (l - g) + m_2 a \left( \frac{1}{(2a)^3} - g \right) = 0$$
 (52)

$$m_1 b \left( \frac{1}{(2b)^3} - g \right) + m_2 a (l - g) = 0$$
 (53)

That is

$$m_2 a(h-g) = m_1 b \left(\frac{1}{(2b)^3} - g\right)$$
 (54)

$$m_2 a \left(\frac{1}{(2a)^3} - g\right) = m_1 b (h - g)$$
 (55)

Thus we have proved:

Theorem 2 Given  $m_1, \dots, m_5$  such that  $m_5$  is at the top vertex of the pyramid and  $m_1, \dots, m_4$  are at the vertices of the base, then

1) mutual distances satisfy:

$$D_{5i} = D_{5i} 1 \le i, j \le 4 (56)$$

$$h + l - 2g = 0 (57)$$

2) the masses satisfy:

 $m_5$  is arbitrary,  $m_1 = m_4$ ,  $m_2 = m_3$  and

$$m_2 a (h - g) = m_1 b \left( \frac{1}{(2b)^3} - g \right)$$
 (58)

$$m_2 a \left( \frac{1}{(2a)^3} - g \right) = m_1 b (h - g)$$
 (59)

where  $\frac{1}{D_{5i}^3} = g$ ,  $\frac{1}{D_{21}^3} = \frac{1}{D_{34}^3} = h$ ,  $\frac{1}{D_{31}^3} = \frac{1}{D_{42}^3} = l$ ,  $D_{41} = 2b$ ,  $D_{23} = 2a$ .

# 4 Sufficient Conditions of Pyramidal Central Configuration for Five-bodies

**Theorem** 3 If the mutual distances among  $m_1$ ,  $\cdots$ ,  $m_4$  at the vertices of a regular trapezoid and  $m_5$  at the top vertex are given by Theorem 2 (1) and the masses  $m_1, \cdots, m_5$  are given by Theorem 2(2), then  $\overline{q} = (\overline{q}_1, \cdots, \overline{q}_5)$  forms a pyramidal central configuration.

**Proof** Consider a coordinate system  $G \times y \times z$  with origin at the center of the masses  $m_1, \dots, m_5$  such that  $G \times z$  is parallel to P containing  $m_1, \dots, m_4$ . Let  $q_i$  be the position vector of  $m_i, 1 \le i \le 5$ , in the coordinate system  $G \times y \times z$ . And let Oxyz be the parallel translate of  $G \times y \times z$  with origin O at the middle point of  $P_1 P_4$ .

By lemma 2, we can choose

$$\lambda = \frac{m}{D_{5i}^3}, 1 \leqslant i \leqslant 4 \tag{60}$$

Since(the proof can be seen in the proof lemma 2)

$$\sum_{j=1, j \neq i}^{5} \frac{m_{j} m_{i}}{D_{ji}^{3}} (\bar{q}_{j} - \bar{q}) = -\lambda m_{i} \bar{q}_{i}$$
 (61)

holds if and only if

$$\sum_{i=1, i \neq i}^{4} m_i \left( \frac{1}{D_{ii}^3} - \frac{\lambda}{m} \right) (q_i - q_i) = 0$$
 (62)

Thus we only need prove that

$$\sum_{i=1, i \neq i}^{4} m_{i} \left( \frac{1}{D_{ii}^{3}} - \frac{\lambda}{m} \right) (q_{i} - q_{i}) = 0$$
 (63)

Since  $q_1 = (0,0,b)$ ,  $q_2 = (c,0,a)$ ,  $q_3 = (c,0,-a)$ ,  $q_4 = (0,0,-b)$ 

Obviously

$$\sum_{i=1, i \neq i}^{4} m_{i} \left( \frac{1}{D_{ji}^{3}} - \frac{\lambda}{m} \right) (q_{i} - q_{i}) y = 0$$
 (64)

and seeing (35~38) we can get

$$\sum_{i=1, i \neq j}^{4} m_{j} \left( \frac{1}{D_{ji}^{3}} - \frac{\lambda}{m} \right) (q_{j} - q_{i}) x = 0$$
 (65)

and seeing from (42) to (53) we can get

$$\sum_{j=1, j\neq i}^{4} m_{j} \left( \frac{1}{D_{ji}^{3}} - \frac{\lambda}{m} \right) (q_{j} - q_{i}) z = 0$$
 (66)