

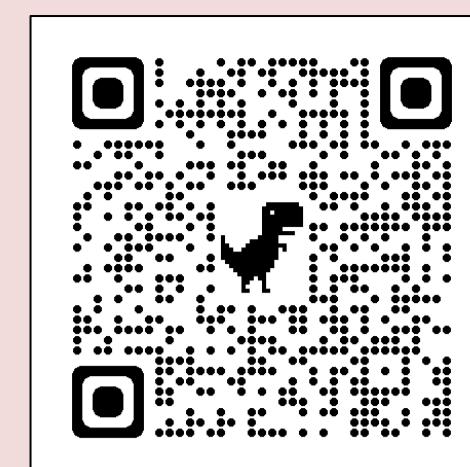
BOTM: Echocardiography Segmentation via Bi-directional Optimal Token Matching

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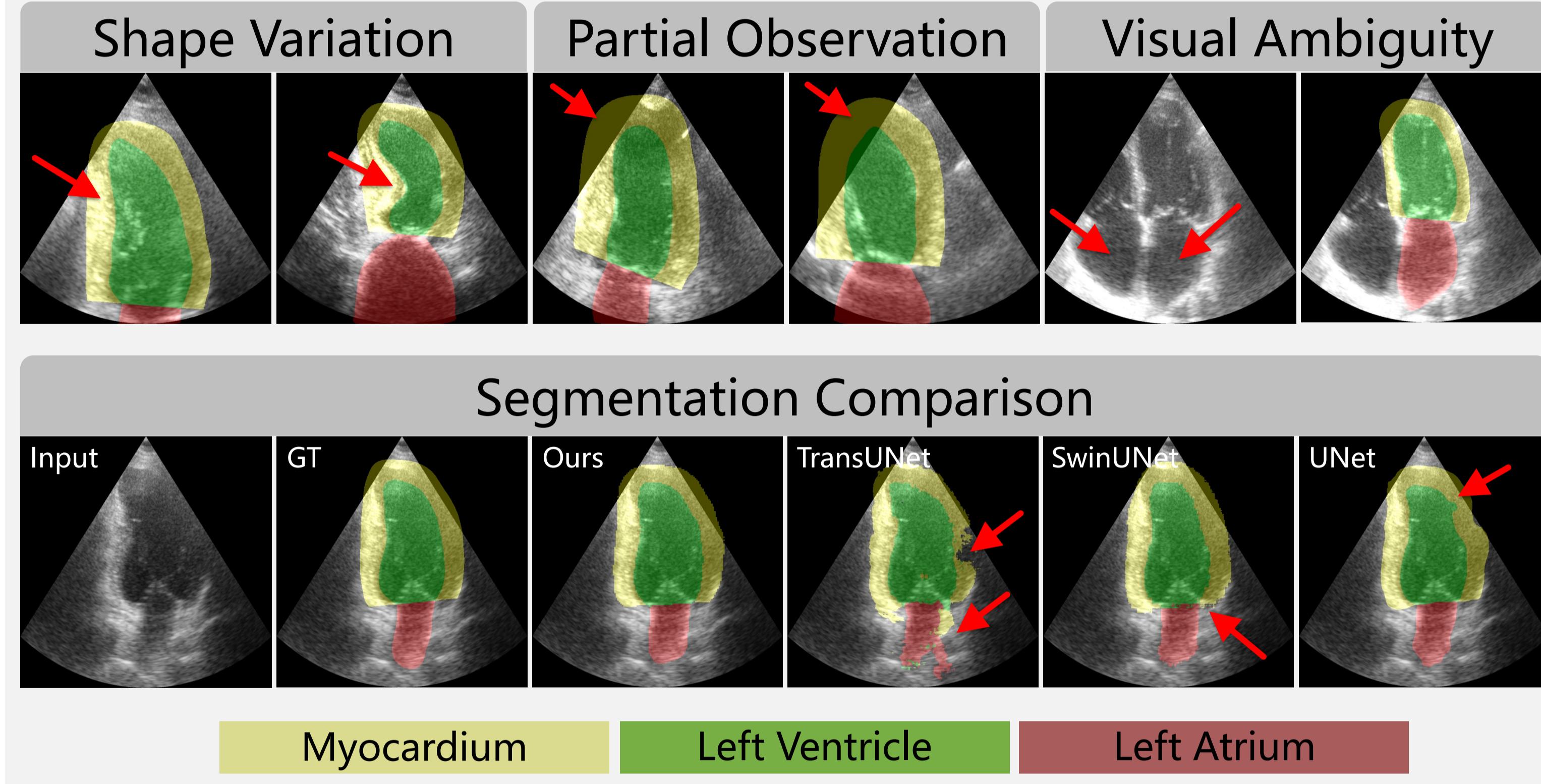
Echocardiography Segmentation

Background: Cardiac dysfunction, Echocardiography

- A primary cause for hospital admissions, growing global health concern
- Measuring of left ventricle changes to identify eligible patients
- Low-cost, rapid-acquisition, radiation-free, and non-invasiveness
- Supporting diagnostic decisions, risk stratification, surgical preparation

Challenge: Manual vs. Automated Segmentation

- Manual cardiac segmentation is time-consuming
- Highly depend on professional experiences, suffering observer varieties
- Speckle noise, shape variation, partial observation and visual ambiguity
- Disconnected boundaries, ambiguous localization and topological defect

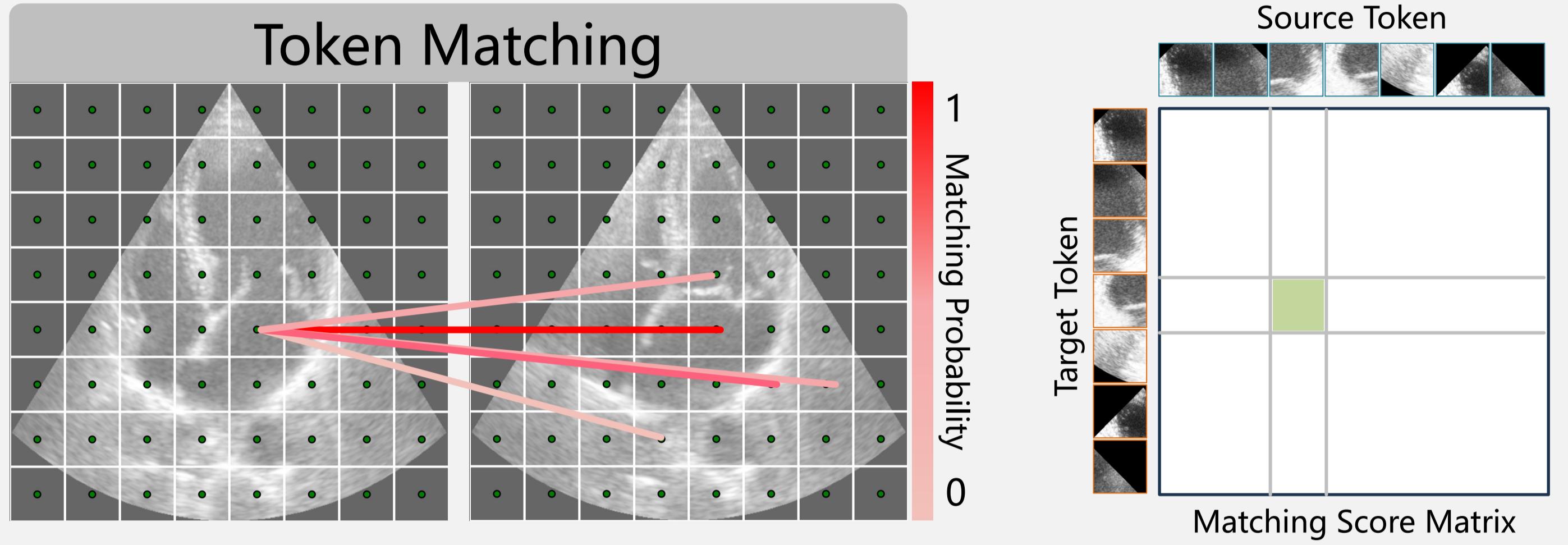


Anatomical Consistency

- Our motivation stems from the clinical need to ensure anatomical consistency
- Preserving intricate anatomical details, corresponding objects can retain identity across frame

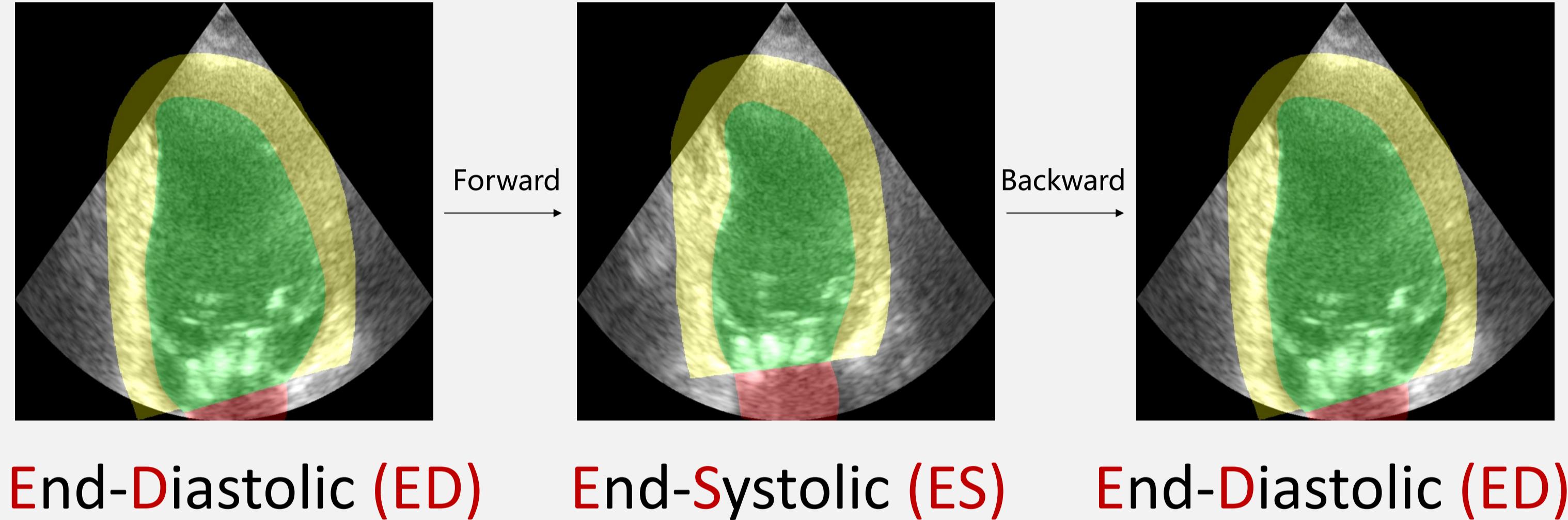
Anatomical Consistency as Optimal Token Matching

Token-level anatomical consistency through a novel optimal transport (OT) perspective, without complicated pre/post-processing



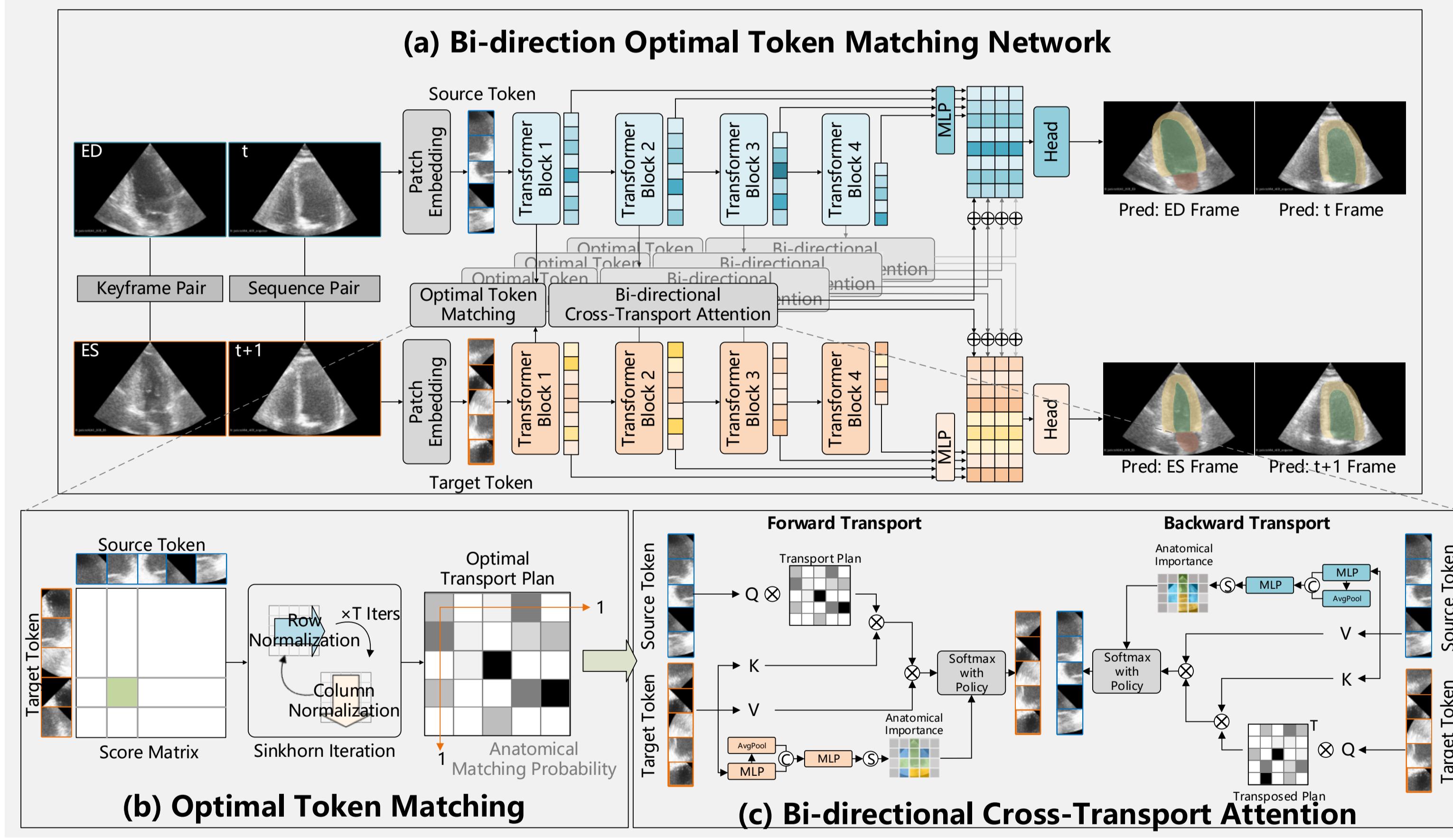
Bi-directional Transport Process

Temporal regulation by mimic cyclic cardiac motion



BOTM Pipeline

1. Paired Echocardiographic Image
2. Matching Score Estimation
3. Proxy Module with Attention Policy



Transport Plan Estimation with Sinkhorn

strongly convex by resorting to the original OT with entropy regularization

$$\mathbf{T}_l^* = \underset{\mathbf{T} \in \mathbb{R}^{h_s^l w_s^l \times h_t^l w_t^l}}{\operatorname{argmin}} \sum_{ij} \mathbf{T}_{ij}^l C_{ij}^l + \epsilon H(\mathbf{T}^l) \quad \text{where } C = 1 - \frac{\mathbf{X}_s^l \cdot \mathbf{X}_t^l}{\|\mathbf{X}_s^l\| \cdot \|\mathbf{X}_t^l\|}$$

OT Plan Minimize matching difference Matching Cost Entropy Regularization Anatomical Similarity

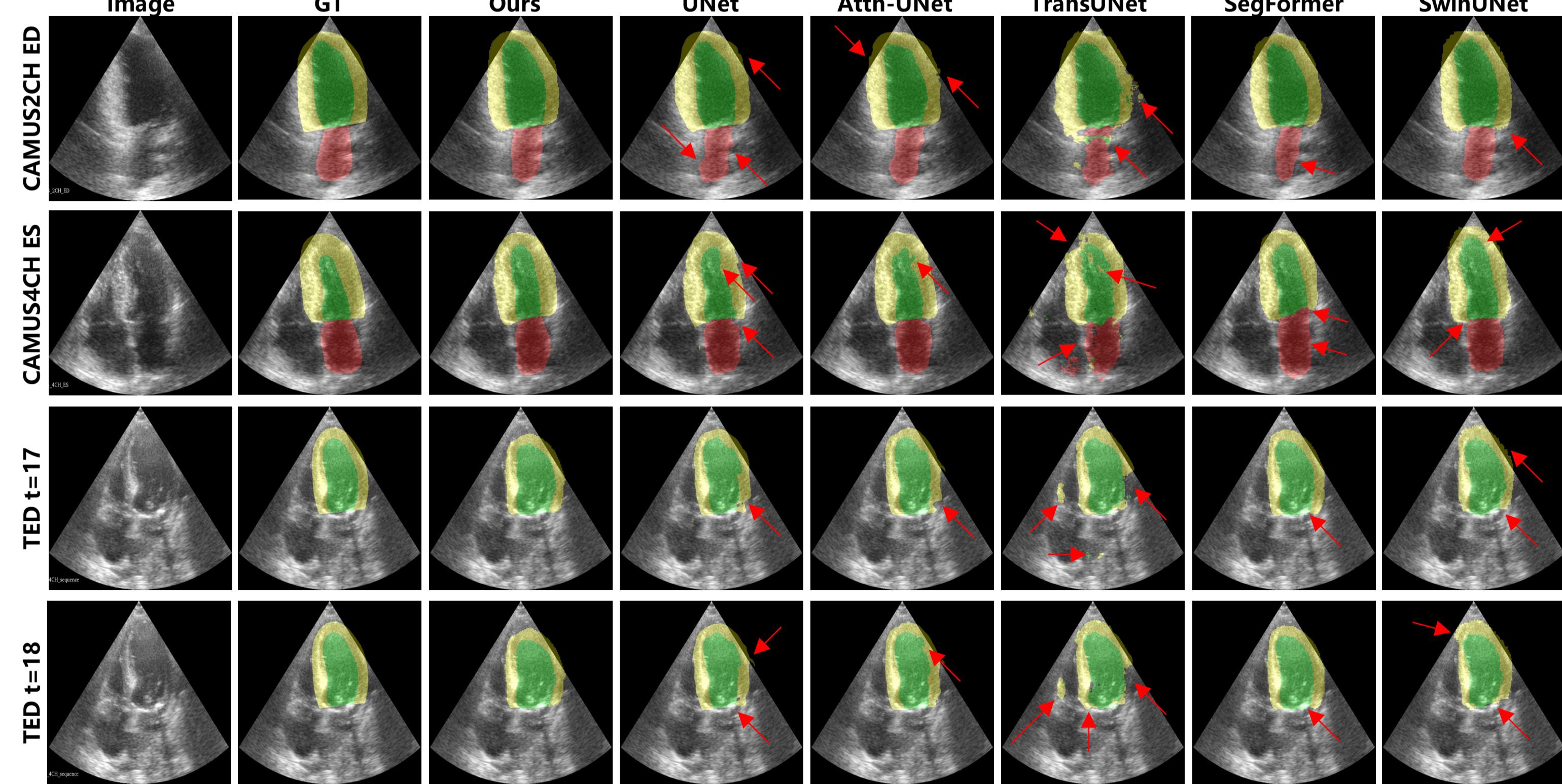
Training Settings

- A single NVIDIA A100 GPU, BatchSize of 8
- SGD (lr=0.001, momentum=0.9), 500 Epochs, Dice and Cross Entropy loss

Datasets*

- CAMUS: ES/ED Key Frame Segmentation
 - Apical 2 chamber (2CH) / 4 chamber view (4CH)
 - 450 patients (Training) / 50 patients (Test)
- TED: Video Segmentation
 - Apical 4 chamber view
 - 78 patients (Training) / 20 patients (Test)

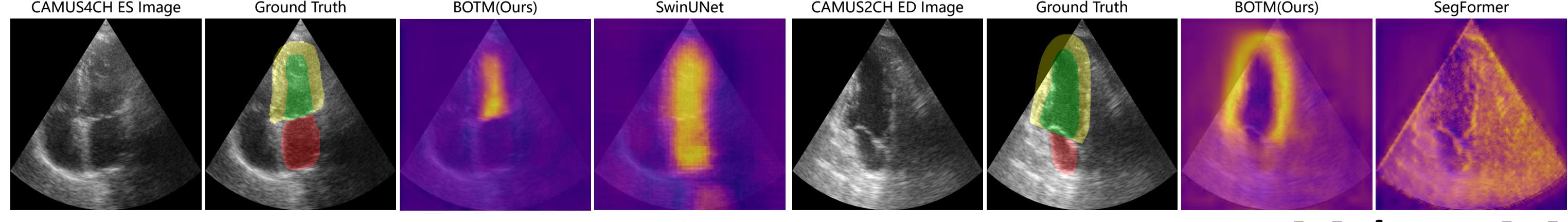
Qualitative Analysis: Segmentation Comparison



Quantitative Analysis: Strong Learning Ability

Methods	mDice ↑	mHD ↓	mIoU ↑	Spe ↑	MAE ↓
CAMUS2CH	UNet [23]	0.893/0.900	10.112/7.509	0.855/0.850	0.989/0.990
	Attn-UNet [19]	0.894/0.901	10.362/10.091	0.838/0.853	0.989/0.990
	TransUNet [5]	0.889/0.875	9.718/12.313	0.832/0.770	0.978/0.979
	SegFormer [27]	0.845/0.840	18.741/20.064	0.741/0.731	0.990/0.990
	BOTM(Ours)	0.908/0.934	7.334/5.861	0.887/0.884	0.994/0.990
CAMUS4CH	UNet [23]	0.891/0.894	10.526/11.027	0.873/0.864	0.993/0.992
	Attn-UNet [19]	0.886/0.902	13.506/9.786	0.865/0.871	0.992/0.992
	TransUNet [5]	0.850/0.859	13.627/17.522	0.774/0.789	0.986/0.987
	SegFormer [27]	0.875/0.885	15.786/10.759	0.795/0.802	0.991/0.992
	BOTM(Ours)	0.872/0.890	9.425/11.872	0.860/0.856	0.988/0.987
TED	UNet [23]	0.901	11.316	0.844	0.986
	Attn-UNet [19]	0.904	9.570	0.858	0.987
	TransUNet [5]	0.850	13.627	0.774	0.986
	SegFormer [27]	0.886	14.289	0.736	0.987
	BOTM(Ours)	0.872	13.149	0.792	0.984

Qualitative Segmentation Uncertainty: LV [L] / Myo [R]



Generalization Study: CAMUS4CH [L] / TED [R]

Methods	RandomBlur			RandomGaussNoise			Methods	RandomFrameDropout			
	10%	30%	50%	10%	30%	50%		10%	30%	50%	70%
UNet [23]	0.902/0.897	0.802/0.839	0.712/0.698	0.897/0.885	0.804/0.767	0.674/0.625	UNet [23]	0.901	0.877	0.849	0.810
TransUNet [5]	0.869/0.874	0.778/0.813	0.693/0.742	0.881/0.879	0.769/0.803	0.712/0.794	TransUNet [5]	0.869	0.833	0.802	0.734
BOTM(Ours)	0.906/0.892	0.895/0.887	0.862/0.858	0.900/0.907	0.873/0.887	0.832/0.841	BOTM(Ours)	0.912	0.893	0.875	0.851