Duration: 120 minutes (estimated)

University of Toronto at Scarborough CSCC37—Numerical Algorithms for Computational Mathematics, Fall 2020

Term Test

Date and Time: Saturday 14 N	lovember, 4:00–8:00 p.r	n.		
Aids allowed: Open-book. All	aids are allowed.			
This is a take-home test. Compl for the test, following the instru you are given more than the estimates the state of the control of the co	ctions given on the ter	m test page of th		
This test consists of 7 questions. answers in the spaces provided. Your long rambling ones. Please write	You will be rewarded for		_	•
Take a few minutes before you question(s) you find easiest.	begin the test to read t	hrough each ques	stion, and then	start with the
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YOU MUST SIGN THE FOLI	LOWING:			
I declare that this test was written	n by the person whose n	name and student	# appear above.	
Signature:				
	Your gr	ade		
	1	/ 10	5	/ 10
	2	/ 5	6	/10
	3	/ 15	7	/ 15
	4	/ 15		
			Total	/ 80
Graded by				

[10 marks]

Design a computer that is able to store $(0.1)_{10}$ exactly. A floating point number on your computer must be represented internally in a base less than 10, and must have a mantissa with a finite number of digits. (**Hint:** Is this possible?)

[5 marks]

What numbers are representable with a finite expression in the binary system but are not finitely representable in the decimal system? **Justify your answer.**

[15 marks]

We wish to evaluate $f(x) = \beta - \sqrt{\beta^2 - x^2}$ where $\beta \gg 0$ and $|x| < \beta$.

a. Identify the range of x where f(x) suffers from potential subtractive cancellation. An approximate range will suffice.

b. Evaluate $\lim_{x\to\alpha} \operatorname{cond}(f(x))$, where α is the smallest number, in absolute value, within the range you identified in (a). Does the condition number reflect the potential for subtractive cancellation? **Explain.**

c. Derive an alternate form of f(x), stable for evaluation in the range you identified in (a).

[15 marks]

Consider the linear system Ax = b where

$$A = \begin{bmatrix} 2 & 6 & 6 \\ 3 & 5 & 12 \\ 6 & 6 & 12 \end{bmatrix}, \quad b = \begin{bmatrix} 20 \\ 25 \\ 30 \end{bmatrix}.$$

a. Compute the PA = LU factorization of A. Use exact arithmetic. Show all intermediate calculations, including Gauss transforms and permutation matrices.

b. Use the factorization computed in (a) to solve the system.

c. Why is Gaussian Elimination usually implemented as in this question (i.e., PA = LU is computed separately, and then the factorization is used to solve Ax = b)?

[10 marks]

Recall in lecture we discussed the geometric interpretation of the manifestation of round-off error during the Gaussian Elimination/LU factorization process. We drew two graphs depicting the intersection of lines which represented, respectively, the solution of a poorly conditioned and a perfectly conditioned linear system $Ax = b, A \in \mathbb{R}^{2 \times 2}, x, b \in \mathbb{R}^2$.

a. Reproduce the graphs below. As in lecture, draw the true systems with solid lines and the systems resulting from roundoff error with dashed lines. Clearly label the true solution and the approximate solutions on each graph.

b. Copy the graph representing the poorly conditioned system to the space below. Show how the residual vector $r = b - A\hat{x}$ manifests on the graph. (**Note:** This was not discussed in lecture.)

c. The solution of a linear system $Ax = b, A \in \mathcal{R}^{3\times 3}, x, b \in \mathcal{R}^3$ is the line or point of intersection of three planes. In the space below, either draw a graph representing a *perfectly* conditioned 3-dimensional linear system, or, if you are not able to easily depict a 3-dimensional graph, describe the graph in 25 words or less.

[10 marks]

Consider the linear system Ax = b where

$$A = \begin{bmatrix} 2 & 4 \\ 1 & 2 + \epsilon \end{bmatrix}, \quad b = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}, \tag{1}$$

and $0 \le \epsilon < 1$.

a. Derive a formula for cond₁(A), the 1-norm condition number of A. What is $\lim_{\epsilon \to 0} \operatorname{cond}_1(A)$?

b. Sketch a graph illustrating the general trend of (1) as $\epsilon \to 0$. (Since you are not given specific values for the right-hand side b, you cannot pin down exact x and y intercepts.) Also show on the graph the potential effect(s) of small perturbations in the coefficients of A, such as those introduced when (1) is solved on a computer using Gaussian Elimination with partial pivoting.

[15 marks]

Consider the iterative improvement algorithm discussed in lecture:

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Solve Ax = b for initial approximation \hat{x}_0.

for i = 0, 1, \ldots until convergence

compute r_i = b - A\hat{x}_i

solve Az_i = r_i

update \hat{x}_{i+1} = \hat{x}_i + z_i

end for
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We gave an intuitive explanation of why this algorithm could improve the initial approximate solution \hat{x}_0 , but we were vague on the conditions required for convergence. In this question, you will attempt to derive the precise conditions required for convergence.

Starting with $Az_i = r_i$ and $(A+E)\hat{z}_i = r_i$, derive a formula showing how the absolute error in the (i+1)-st iterate $\|\hat{x}_{i+1} - x\|$ is bound by a multiple of the absolute error in the i-th iterate $\|\hat{x}_i - x\|$. Argue that the magnitude of this multiple is dependent on the condition of A, and is less than one (hence convergence) if A is well-conditioned.

[...continue your answer to #7 here.]