

COMP 530

Introduction to Operating Systems

Notes on HW3

Implementing Producer/Consumer systems

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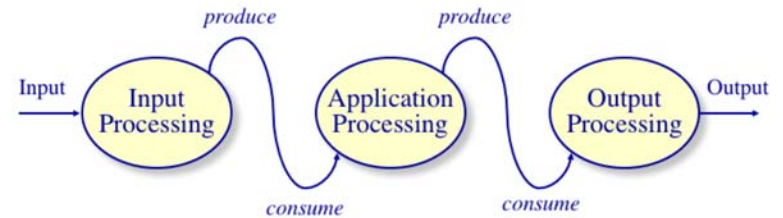
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HW 3

A multi-threaded producer/consumer system



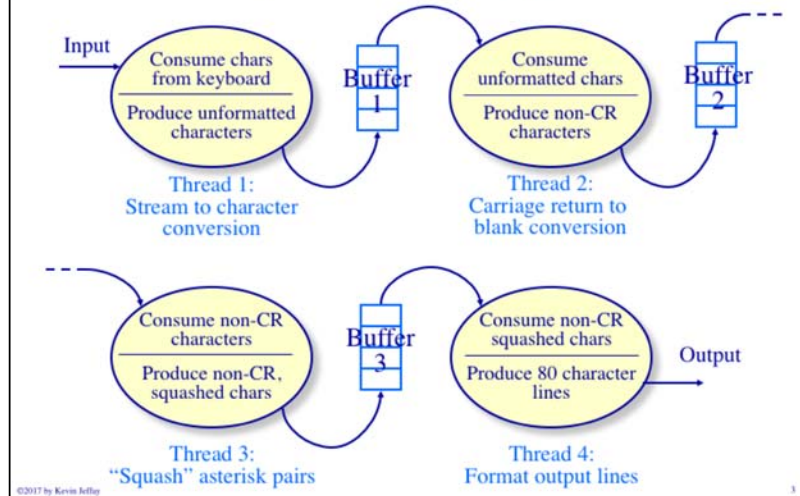
- ◆ Re-implement your solution to HW 1 as a pipeline of C threads
 - » Use the *ST* (“State Threads”) open source thread package for C
 - » Implement a sequence of producer/consumer systems using *ST* threads and semaphores

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HW 3

A multi-threaded producer/consumer system



HW 3

Details

- ◆ Use semaphores to synchronize producer/consumer pairs

```

/* semaphore.h
 * An ST extension implementing classical general/counting semaphores
 *
 * Public Interface -
 *
 * typedef semaphore
 *
 * void down(semaphore* s) - blocks the calling thread if the
 *                           value of the of the semaphore is 0,
 *                           otherwise the value of the semaphore
 *                           is decremented.
 *
 * void up(semaphore* s) - increments the value of the semaphore.
 *                        If a thread is blocked on the semaphore
 *                        it is woken up.
 *
 * void createSem(semaphore* s, int value) - sets the initial
 *                                           integer value of the semaphore. 'value'
 *                                           must be nonnegative.
 */

```

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HW 3 Notes

Asserting synchronization conditions

```
globals
fullBuffers : semaphore := 0    buf : array [0..n-1] of char
emptyBuffers : semaphore := n   nextIn,nextOut : 0..n-1 := 0
```

```
process Producer
begin
loop
  <produce a character "c">
  emptyBuffers.down()
  <assert that the awaited
  condition is true>

  buf[nextIn] := c
  nextIn := nextIn+1 mod n

  <assert that the synchronization
  condition is true>
  fullBuffers.up()
  <assert ??>
end loop
end Producer

process Consumer
begin
loop
  fullBuffers.down()
  <assert that the awaited
  condition is true>

  c := buf[nextOut]
  nextOut := nextOut+1 mod n

  <assert that the synchronization
  condition is true>
  emptyBuffers.up()

  <consume a character "c">
end loop
end Consumer
```

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HW 3 Notes

Asserting synchronization conditions

```
globals
fullBuffers : semaphore := 0    buf : array [0..n-1] of char
emptyBuffers : semaphore := n   nextIn,nextOut : 0..n-1 := 0
```

```
process Producer
begin
loop
  <produce a character "c">
  emptyBuffers.down()
  <assert that the awaited
  condition is true>

  buf[nextIn] := c
  nextIn := nextIn+1 mod n

  <assert that the synchronization
  condition is true>
  fullBuffers.up()
  <assert ??>
end loop
end Producer
```

- ◆ In C there's a simple function for stating assertions:

```
#include<assert.h>

void foo(char* string)
{
  assert(string != NULL);
  :
  :
}
```

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HW 3 Notes

Software engineering issues

```
globals
  fullBuffers : semaphore := 0   buf : array [0..n-1] of char
  emptyBuffers : semaphore := n  nextIn, nextOut : 0..n-1 := 0
```

```
process Producer
begin
  loop
    <produce a character "c">
    deposit {
      emptyBuffers.down()
      buf[nextIn] := c
      nextIn := nextIn+1 mod n
      fullBuffers.up()
    }
  end loop
end Producer

process Consumer
begin
  loop
    remove {
      fullBuffers.down()
      c := buf[nextOut]
      nextOut := nextOut+1 mod n
      emptyBuffers.up()
    }
    <consume a character "c">
  end loop
end Consumer
```

- ◆ Modularity and information hiding principles dictate that all the buffer management should be part of an abstract buffer class

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HW 3 Notes

Software engineering issues

```
globals
  fullBuffers : semaphore := 0   buf : array [0..n-1] of char
  emptyBuffers : semaphore := n  nextIn, nextOut : 0..n-1 := 0
```

```
process Producer
begin
  loop
    <produce a character "c">
    deposit {
      emptyBuffers.down()
      buf[nextIn] := c
      nextIn := nextIn+1 mod n
      fullBuffers.up()
    }
  end loop
end Producer

process Consumer
begin
  loop
    remove {
      fullBuffers.down()
      c := buf[nextOut]
      nextOut := nextOut+1 mod n
      emptyBuffers.up()
    }
    <consume a character "c">
  end loop
end Consumer
```

- ◆ Construct a bounded buffer abstract data type with functions *deposit* and *remove*
 - » Implement your buffer data type in a separate file called *buffer.c* (with definitions in the file *buffer.h*)

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HW 3

Grading

- ◆ Your program should behave *exactly* as a correct version of HW1 would
 - » Your HW3 program will be tested the same way your HW1 program was tested
 - » Thus, you can use your HW1 program to evaluate the correctness of HW3
- ◆ For extra credit, use the *condition variable* structures in *ST* to implement your own version of semaphores
 - » Put your semaphore implementation in files *semaphore.c* and *semaphore.h*
 - » DON'T ATTEMPT THE EXTRA CREDIT UNTIL YOU HAVE A FULLY FUNCTIONING SOLUTION TO THE "BASE" ASSIGNMENT!!

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