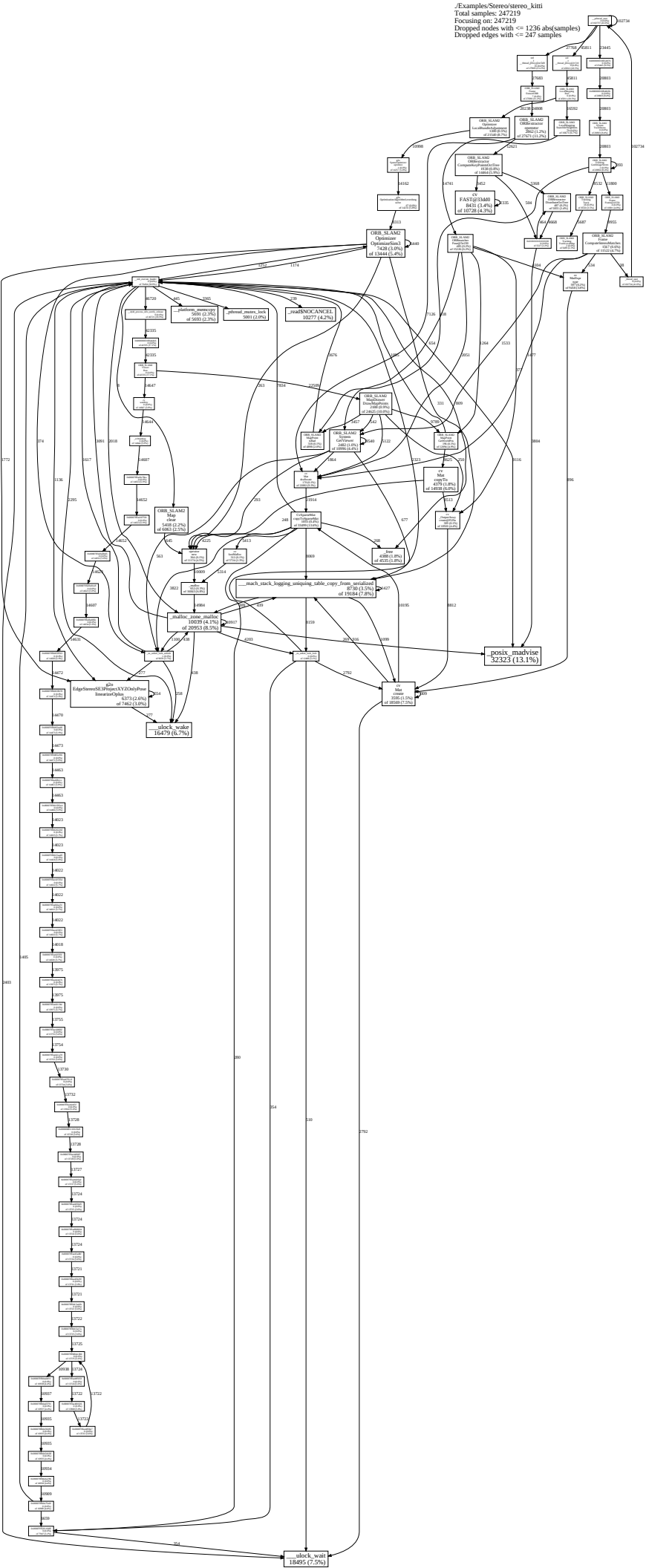
./Examples/Stereo/stereo_kitti
Total samples: 247219
Focusing on: 247219
Dropped nodes with <= 1236 abs(samples)
Dropped edges with <= 247 samples


ORB_SLAM2 Optimizer OptimizeSim3 7428 (3.0%) of 13444 (5.4%)
__pthread_mutex_lock 5691 (2.3%) of 5691 (2.3%)
__pthread_mutex_lock 5001 (2.0%)
__read$NOCANCEL 10277 (4.2%)
ORB_SLAM2 Map 5418 (2.2%) of 6063 (2.5%)
__malloc_zone_malloc 10039 (4.1%) of 20953 (8.5%)
__mach_stack_logging_uniquing_table_copy_from_serialized 8730 (3.5%) of 19184 (7.8%)
__posix_madvise 32323 (13.1%)
g2o EdgeStereoSE3ProjectXYZOnlyPoseLinearizeOplus 6373 (2.6%) of 7462 (3.0%)
__ulock_wake 16479 (6.7%)
__ulock_wait 18495 (7.5%)
cv Mat copyTo 4379 (1.8%) of 14938 (6.0%)
cv Mat create 3595 (1.5%) of 18688 (7.5%)
cv FAST@33d40 8431 (3.4%) of 10728 (4.3%)
ORB_SLAM2 ORBextractor operator 3862 (1.5%) of 27671 (11.2%)
ORB_SLAM2 Optimizer LocalBundleAdjustment 4 (0.0%) of 11695 (4.7%)
ORB_SLAM2 ORBmatcher ComputeFundamental3Dline 19 (0.0%) of 14464 (5.9%)
ORB_SLAM2 Optimizer OptimizeEssentialGraph 2160 (0.9%) of 12822 (5.0%)
ORB_SLAM2 Tracking GrabImageStereo 487 (0.2%) of 6891 (2.8%)
ORB_SLAM2 Tracking Track 1 (0.0%) of 6891 (2.8%)
ORB_SLAM2 Tracking Track 1 (0.0%) of 6891 (2.8%)
ORB_SLAM2 Frame ComputeStereoMatches 4367 (0.0%) of 10320 (4.2%)
ORB_SLAM2 ORBmatcher SearchForMatches 1 (0.0%) of 4 (0.0%)
ORB_SLAM2 MapPoint IncreaseVisible 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 MapPoint IncreaseFound 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 MapPoint GetFoundRatio 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 Tracking GetMapPoints 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 Tracking UpdateLocalMap 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 Tracking UpdateLocalPoints 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 Tracking UpdateLocalKeyFrames 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 Tracking TrackLocalMap 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 Tracking SearchLocalPoints 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrameDB add 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame UpdateConnections 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame AddConnection 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame UpdateBestCovisibles 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame SetBestCovisibleOrder 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame SetNotErase 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame SetFlagVisited 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame GetVectorCovisibleKeyFrames 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame GetBestCovisibilityKeyFrames 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame GetCovisibleKeyFrames 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame GetWeight 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame AddMapPoint 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame EraseMapPointMatch 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame EraseConnection 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame UpdateConnections 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame UpdateBestCovisibles 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame GetMapPoints 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame GetMapPoint 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame IsInImage 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame UnlinkMapPoint 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame ComputeSceneMedianDepth 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame GetLeftPosition 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame GetRightPosition 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame GetPose 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame GetStereoCenter 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame GetCamera 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame GetRotation 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame GetTranslation 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame ComputeCentroid 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame GetIndexes 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame GetNeighbors 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame GetBestCovisibilityKeyFrames 1 (0.0%) of 1 (0.0%)
ORB_SLAM2 KeyFrame GetVector