

Zhiquan Wang

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EDUCATION

Purdue University
Ph.D. Student in Computer Science
University of California, Davis
Exchange Student in Computer Science
Nanjing Tech University
Bachelor of Science in Computer Science

West Lafayette, IN, USA
08/2019 - Present
Davis, CA, USA
08/2018 - 01/2019
Jiangsu, China
09/2015 - 05/2019

PUBLICATIONS

- **Wang, Z.**, Benes, B., Qureshi, A. H., & Mousas, C. (2022). Co-design of Embodied Neural Intelligence via Constrained Evolution. arXiv preprint arXiv:2205.10688.
- Mousas, C., Krogmeier, C., & **Wang, Z.** (2021). Photo Sequences of Varying Emotion: Optimization with a Valence-Arousal Annotated Dataset. ACM Transactions on Interactive Intelligent Systems (**TiiS**), 11(2), 1-19.
- Liu, H., **Wang, Z.**, Mazumdar, A., & Mousas, C. (2021). Virtual reality game level layout design for real environment constraints. Graphics and Visual Computing, 4, 200020.
- Liu, H., **Wang, Z.**, Mousas, C., & Kao, D. (2020, November). Virtual reality racket sports: Virtual drills for exercise and training. In 2020 IEEE International Symposium on Mixed and Augmented Reality (**ISMAR**) (pp. 566-576). IEEE.

RESEARCH EXPERIENCE

Virtual Agent Editor West Lafayette, IN, USA
Software Development 2022

- Developed a virtual creature editor for fast robot prototyping and interactive motion planning with **OpenGL** and **C++**.
- Designed a novel robot description with pre-defined body parts for rapid crafting and compatibility with URDF and MJCF.

Co-design of Virtual Creatures via Evolution West Lafayette, IN, USA
Research Assistant **Purdue Research Foundation Graduate Fellowship Grant, 2022**

- Developed a virtual creature generator supporting random generation based on input rules and user constraints with **Python**.
- Implemented a **reinforcement learning** algorithm (**PPO**) on **Pytorch** for parallel training of arbitrary creatures' locomotion.
- Proposed a novel pipeline for the parallel co-design of large-scale population creatures with evolution methods.
- **Doubled the performance** of creatures in locomotion while **significantly reducing computational resources**.

Gait Analysis Using Transformers and Reinforcement Learning West Lafayette, IN, USA
Research Assistant 2021

- Designed and Developed robot locomotion task environments based on **Isaac Gym** with real-time attention visualization.
- Implemented a reinforcement learning algorithm PPO aims at **large-scale experience sampling** from parallel environments.
- Designed an **Transformer-based** policy net with **self-attention** mechanisms that capture the relationship between joints
- Analyzed the importance of joints and their relationships in a locomotion task with self-attention matrix from policy net.

Bird Retina Droplet Detection West Lafayette, IN, USA
Research Assistant **Purdue Polytechnic Institute, 2020**

- Developed a tool for data cleaning for an unorganized dataset with different resolutions, backgrounds, and formats.
- Designed and implemented a bird retina droplet VGG - based detection model with high accuracy (**86%**) on average.
- Deployed the detection model on a local machine, integrating it into an application for easy real-time result editing.

Emotion Recognition and Classification From Real-Time Video West Lafayette, IN, USA
Research Assistant **Purdue Polytechnic Institute, 2019**

- Designed and Implemented a VGG - based model for classification on Russell's model with accuracy up to **87.5%** on average.
- Develop a real-time emotion recognition system to capture the emotion of audiences in a virtual classroom.

Virtual Racket Sports Study in VR West Lafayette, IN, USA
Research Assistant **Purdue Polytechnic Institute, 2019**

- Designed and Implemented different virtual Racket Sports (e.g., ping-pong, tennis ball) on VR device with **Unity3D**.
- Proposed a novel optimization method for game-level control in racket sports with **Markov chain Monte Carlo (MCMC)**.

ADDITIONAL INFORMATION

- Programming: C/C++, CUDA, Python
- Development: Pytorch, OpenGL, Unity3D, Git, Linux