

```
> POLS = plm(lnGDP ~ D, data = panel_dataFrame, model = "pooling")> summary(POLS)
```

Pooling Model

```
Call:
plm(formula = lnGDP ~ D, data = panel_dataFrame, model = "pooling")
```

Balanced Panel: n = 86, T = 51, N = 4386

Residuals:

Min.	1st Qu.	Median	3rd Qu.	Max.
-365.6384	-97.2957	5.5567	115.1742	379.9918

Coefficients:

	Estimate	Std. Error	t-value	Pr(> t)
(Intercept)	659.0082	2.9815	221.033	< 2.2e-16 ***
D	175.6802	4.1673	42.156	< 2.2e-16 ***

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Total Sum of Squares: 117260000

Residual Sum of Squares: 83436000

R-Squared: 0.28845

Adj. R-Squared: 0.28828

F-statistic: 1777.16 on 1 and 4384 DF, p-value: < 2.22e-16

```
> FE = plm(lnGDP ~ D, data = panel_dataFrame, model = "within")> summary(FE)
```

Oneway (individual) effect within Model

```
Call:
plm(formula = lnGDP ~ D, data = panel_dataFrame, model = "within")
```

Balanced Panel: n = 86, T = 51, N = 4386

Residuals:

Min.	1st Qu.	Median	3rd Qu.	Max.
-176.3868	-18.4393	2.2376	20.2982	200.6431

Coefficients:

	Estimate	Std. Error	t-value	Pr(> t)
D	18.7419	1.6888	11.098	< 2.2e-16 ***

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Total Sum of Squares: 5888000

Residual Sum of Squares: 5724000

R-Squared: 0.027852

Adj. R-Squared: 0.0084043

F-statistic: 123.165 on 1 and 4299 DF, p-value: < 2.22e-16

```
> RE = plm(lnGDP ~ D, data = panel_dataFrame, model = "random")> summary(RE)
```

Oneway (individual) effect Random Effect Model
(Swamy-Arora's transformation)

```
Call:
plm(formula = lnGDP ~ D, data = panel_dataFrame, model = "random")
```

Balanced Panel: n = 86, T = 51, N = 4386

Effects:

	var	std.dev	share
idiosyncratic	1331.47	36.49	0.09
individual	13437.73	115.92	0.91

theta: 0.956

Residuals:

Min.	1st Qu.	Median	3rd Qu.	Max.
-183.2031	-19.8349	1.0469	20.4884	193.5872

Coefficients:

	Estimate	Std. Error	z-value	Pr(> z)
(Intercept)	738.9733	12.6379	58.473	< 2.2e-16 ***
D	19.4544	1.6995	11.447	< 2.2e-16 ***

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Total Sum of Squares: 6103900
Residual Sum of Squares: 5926800
R-Squared: 0.029023
Adj. R-Squared: 0.028802
Chisq: 131.042 on 1 DF, p-value: < 2.22e-16

```
> pFtest(FE, POLS)
```

F test for individual effects

data: lnGDP ~ D
F = 686.66, df1 = 85, df2 = 4299, p-value < 2.2e-16
alternative hypothesis: significant effects

```
> phtest(FE, RE)
```

Hausman Test

data: lnGDP ~ D
chisq = 14.007, df = 1, p-value = 0.0001821
alternative hypothesis: one model is inconsistent

```
>pbgtest(FE, order = 1)
```

Breusch-Godfrey/Wooldridge test for serial correlation in panel models

```
data: lnGDP ~ D
chisq = 3638, df = 1, p-value < 2.2e-16
alternative hypothesis: serial correlation in idiosyncratic errors
```

What is the dynamic impact of a change in $D_{i,t}$ on $\ln y_{i,t}$?

Since this is a static model and no lag term, so the coefficient on D_{it} would be the **long run permanent impact**. with one unit shock on D_{it} , the response of $\ln y_{it}$ would be 19.4544 on random effect estimation, 18.7419 on fixed effect estimation, and 175.6802 on pooled OLS estimation, which is significant different than others very likely incorrect. These three estimations need to be tested to choose.

What are the statistical properties of each of the estimators ?

By theory, The fixed effect estimator is the “within estimator” and we do this by the so-called “demean approach”. **For consistency**, when N goes to infinity, it need the D_{it} is strictly exogenous which means D_{it} need to be independent to error term with any i and t . when T goes to infinity, the mean of D_{it} is 0 so it just need the D_{it} is weakly exogenous which means D_{it} still need to be independent to error term w.r.t any i but just contemporaneously independent with respect to t . **For biased or not**, It's unbiased if it's strictly exogenous. **For efficiency**, because we only use information from within dimension, so it's not efficient. And it's **asymptotically normal** under some regularity conditions.

The Random effect estimator is the combination of “between estimator and within estimator”. **For consistency**, when N goes to infinity, we need consistency for both between estimator and within estimator. D_{it} still need to be strictly exogenous but also need to be uncorrelated with the individual effect. when T goes to infinity, the between variation has been dropped and random effect same as fixed effect, so we just need weak exogenous. **For efficiency**, we both use between and within dimension, so it's efficient.

The pooled OLS estimator is the OLS version of random effect estimator ignoring the individual effect. So no demean approach there. **For consistency** we just need D_{it} weak exogenous both for N goes to infinity and T goes to infinity and we still need it uncorrelated with error term. **For efficiency**, it is not **efficient** because of ignoring the individual effect.

And these statistical properties are supported by our test. Based on my result, from the **F-test** we reject the H_0 of there is no individual effect and from the **Hausman test** we reject the H_0 of the two estimators are no significant differences. So econometrically, we can not ignore the individual effect and the individual effect is correlated with Dit . **so the pooled OLS and random effect is inconsistent** and we are going to choose fixed effect estimator which are in line of the economical view that the countries as individuals are “one of a kind”

In addition, if the Dit is not exogenous and it is also determined by the $\ln GDP_{it}$, then all the pooled OLS, fixed effect estimator and random effect estimator is not consistent because of endogenous problem. We then need an instrument or panel VAR to solve it. Or the Dit can be determined by the lag term of $\ln GDP_{it}$. then it is fine with our model.

What are the implication of your conclusion of autocorrelation test for the statistical properties of your preferred estimator ?

From the autocorrelation test, we reject the H_0 of there is no autocorrelation in the error term. But it's still unbiased and consistent for the explanatory variable Dit is still independent with the error term. But it is not efficient because there is still information left in the error term and the variance of the coefficient is not minimum anymore, changing to dynamic panel model may solve this problem.

```
> POLS_inGrowth = plm(GDPgrowth ~ D, data = panel_dataFrame, model = "pooling")> summary(POLS_inGrowth)
```

Pooling Model

```
Call:
plm(formula = GDPgrowth ~ D, data = panel_dataFrame, model = "pooling")
```

Balanced Panel: n = 86, T = 50, N = 4300

Residuals:

Min.	1st Qu.	Median	3rd Qu.	Max.
-71.32422	-2.02422	0.30578	2.40833	64.11578

Coefficients:

	Estimate	Std. Error	t-value	Pr(> t)
(Intercept)	1.42422	0.11574	12.3057	< 2.2e-16 ***
D	0.66745	0.16151	4.1325	3.657e-05 ***

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Total Sum of Squares: 120920

Residual Sum of Squares: 120440

R-Squared: 0.0039576

Adj. R-Squared: 0.0037259

F-statistic: 17.0775 on 1 and 4298 DF, p-value: 3.6568e-05

```
> FE_inGrowth = plm(GDPgrowth ~ D, data = panel_dataFrame, model = "within")> summary(FE_inGrowth)
```

Oneway (individual) effect within Model

```
Call:
plm(formula = GDPgrowth ~ D, data = panel_dataFrame, model = "within")
```

Balanced Panel: n = 86, T = 50, N = 4300

```
Residuals:
    Min.    1st Qu.    Median    3rd Qu.    Max.
-67.00164  -1.89850    0.24409    2.29066    68.43836
```

```
Coefficients:
      Estimate Std. Error t-value Pr(>|t|)
D    0.34546    0.24004   1.4392  0.1502
```

```
Total Sum of Squares:    111200
Residual Sum of Squares: 111140
R-Squared:    0.00049139
Adj. R-Squared: -0.019912
F-statistic: 2.07124 on 1 and 4213 DF, p-value: 0.15017
```

```
> RE_inGrowth = plm(GDPgrowth ~ D, data = panel_dataFrame, model = "random")> summary(RE_inGrowth)
```

Oneway (individual) effect Random Effect Model
(Swamy-Arora's transformation)

```
Call:
plm(formula = GDPgrowth ~ D, data = panel_dataFrame, model = "random")
```

Balanced Panel: n = 86, T = 50, N = 4300

```
Effects:
              var std.dev share
idiosyncratic 26.381    5.136 0.941
individual     1.667    1.291 0.059
theta: 0.5096
```

```
Residuals:
    Min.    1st Qu.    Median    3rd Qu.    Max.
-69.15798  -1.88010    0.31068    2.37279    66.28202
```

```
Coefficients:
      Estimate Std. Error z-value Pr(>|z|)
(Intercept)  1.51909    0.19234   7.8979 2.836e-15 ***
D             0.48269    0.20864   2.3135  0.0207 *
```

```
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

```
Total Sum of Squares:    113530
Residual Sum of Squares: 113390
R-Squared:               0.0012437
Adj. R-Squared: 0.0010113
Chisq: 5.35216 on 1 DF, p-value: 0.020697
```

```
> pFtest(FE_inGrowth, POLS_inGrowth)
```

F test for individual effects

```
data: GDPgrowth ~ D
F = 4.1468, df1 = 85, df2 = 4213, p-value < 2.2e-16
alternative hypothesis: significant effects
```

```
> phtest(FE_inGrowth, RE_inGrowth)
```

Hausman Test

```
data: GDPgrowth ~ D
chisq = 1.3368, df = 1, p-value = 0.2476
alternative hypothesis: one model is inconsistent
```

```
> pbgtest(RE_inGrowth, order = 1)
```

Breusch-Godfrey/Wooldridge test for serial correlation in panel models

```
data: GDPgrowth ~ D
chisq = 261.18, df = 1, p-value < 2.2e-16
alternative hypothesis: serial correlation in idiosyncratic errors
```

What is the dynamic impact of a change in $D_{i,t}$ on $\Delta \ln y_{i,t}$ and $\ln y_{i,t}$?

This is still a static model with no lag terms so the response of $\Delta \ln y_{i,t}$ to the shock of $D_{i,t}$ is still long run and permanent, it is the coefficient of $D_{i,t}$ which is 0.66745 by pooled OLS estimator, 0.34546 by fixed effect estimator and 0.48269 on random effect. And these three estimations still need to be tested to choose.

The response of $\ln y_{i,t}$ to $D_{i,t}$ now is the cumulative impulse response of $\Delta \ln y_{i,t}$, so now the estimation result of this specification indicates that the response of the $\ln y_{i,t}$ is also permanent and it is upper trend because the impact of $D_{i,t}$ on GDP growth rate now is permanent. This is no

It's really possible so we may need to extend the static model to dynamic model to capture more dynamic behavior.

What are the statistical properties of each of the estimators ?

As theory is mentioned above, **For consistency**, with N goes to infinity we need D_{it} to be strictly exogenous both fixed effect estimator and random effect estimator and one more condition for random effect estimator is D_{it} need to be uncorrelated. when T goes to infinity, the fixed effect and random effect is pretty much same, both of this two just need to be weakly exogenous. pooled OLS ignore the individual effect so just need D_{it} to be weakly exogenous and uncorrelated with error term. **For efficiency**, fixed effect estimator and pooled OLS is still inefficient and random effect estimator is efficient.

By statistical test, it is still in line with theory. From the F-test we reject the H_0 of there is no individual effect. From the Hausman test, the p-value is 0.2476 and we can not reject the H_0 of there is no significant difference between this two estimations under 95% significance level or even 90% significance level. **So pooled OLS estimator is consistent but not efficient, (clearly it's not that different with the fixed effect and random effect unlike the first model in level)** fixed effect estimator is consistent but not efficient, and random effect estimator is consistent and efficient. so we are going to choose random effect estimations.

By economic view, the reason might be there is no very big changing of GDP growth rate within one country over time. But the variations between different countries are relevant big. So there might be more information on between dimension rather than within dimension.

In addition, like above, it still need to be considered if the D_{it} is endogenous.

What are the implication of your conclusion of autocorrelation test for the statistical properties of your preferred estimator ?

From the autocorrelation test, we still reject the H_0 of there is no autocorrelation in the error term. And also it is still unbiased and consistent, but it is inefficient for there is information still left in the error term and its variance is not minimum now. We need to change our specification might to dynamic model.

```
> POLS__inlevel_lag <- plm(lnGDP ~ D+lag1+lag2+lag3+lag4, data = panel_dataFrame, model = "pooling") > summary(POLS__inlevel_lag)
```

Pooling Model

```
Call:
plm(formula = lnGDP ~ D + lag1 + lag2 + lag3 + lag4, data = pa
nel_dataFrame,
     model = "pooling")
```

Unbalanced Panel: n = 86, T = 43-44, N = 3783

Residuals:

Min.	1st Qu.	Median	3rd Qu.	Max.
-542.5601	-4.5566	2.8309	8.4306	399.4034

Coefficients:

	Estimate	Std. Error	t-value	Pr(> t)	
(Intercept)	26.653660	2.841798	9.3792	< 2.2e-16	***
D	12.529858	1.332774	9.4013	< 2.2e-16	***
lag1	1.608782	0.069454	23.1633	< 2.2e-16	***
lag2	-0.727217	0.112891	-6.4418	1.33e-10	***
lag3	0.135656	0.111079	1.2213	0.2221	
lag4	-0.062679	0.068757	-0.9116	0.3620	

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Total Sum of Squares: 103530000

Residual Sum of Squares: 4663800

R-Squared: 0.95495

Adj. R-Squared: 0.95489

F-statistic: 16013 on 5 and 3777 DF, p-value: < 2.22e-16

```
> FE_inlevel_lag <- plm(lnGDP ~ D+lag1+lag2+lag3+lag4, data =
panel_dataFrame, model = "within")> summary(FE_inlevel_lag)
```

Oneway (individual) effect within Model

Call:

```
plm(formula = lnGDP ~ D + lag1 + lag2 + lag3 + lag4, data = pa
nel_dataFrame,
     model = "within")
```

Unbalanced Panel: n = 86, T = 43-44, N = 3783

Residuals:

Min.	1st Qu.	Median	3rd Qu.	Max.
-248.1745	-8.6546	1.7160	11.4553	128.8817

Coefficients:

	Estimate	Std. Error	t-value	Pr(> t)	
D	10.438922	1.206476	8.6524	< 2.2e-16	***
lag1	0.922245	0.050345	18.3184	< 2.2e-16	***
lag2	-0.471716	0.077406	-6.0941	1.214e-09	***
lag3	0.042053	0.076057	0.5529	0.5804	
lag4	-0.060180	0.048802	-1.2331	0.2176	

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Total Sum of Squares: 3819600

Residual Sum of Squares: 2130700

R-Squared: 0.44218

Adj. R-Squared: 0.42858

F-statistic: 585.314 on 5 and 3692 DF, p-value: < 2.22e-16

```
> RE_inlevel_lag <- plm(lnGDP ~ D+lag1+lag2+lag3+lag4, data =  
panel_dataFrame, model = "random")> summary(RE_inlevel_lag)
```

Oneway (individual) effect Random Effect Model
(Swamy-Arora's transformation)

```
Call:  
plm(formula = lnGDP ~ D + lag1 + lag2 + lag3 + lag4, data = pa  
nel_dataFrame,  
      model = "random")
```

Unbalanced Panel: n = 86, T = 43-44, N = 3783

Effects:

	var	std.dev	share
idiosyncratic	577.111	24.023	0.995
individual	2.671	1.634	0.005

theta:

	Min.	1st Qu.	Median	Mean	3rd Qu.	Max.
	0.08674	0.08850	0.08850	0.08848	0.08850	0.08850

Residuals:

	Min.	1st Qu.	Median	Mean	3rd Qu.	Max.
	-537.43	-4.90	2.88	0.00	8.82	394.84

Coefficients:

	Estimate	Std. Error	z-value	Pr(> z)
(Intercept)	33.370159	3.053057	10.9301	< 2.2e-16 ***
D	13.374865	1.374072	9.7337	< 2.2e-16 ***
lag1	1.590397	0.069436	22.9045	< 2.2e-16 ***
lag2	-0.719355	0.112230	-6.4096	1.459e-10 ***
lag3	0.132355	0.110420	1.1987	0.2307
lag4	-0.058292	0.068694	-0.8486	0.3961

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Total Sum of Squares: 86676000

Residual Sum of Squares: 4606700

R-Squared: 0.94685

Adj. R-Squared: 0.94678

Chisq: 67277.4 on 5 DF, p-value: < 2.22e-16

```
> pFtest(FE_inlevel_lag, POLS__inlevel_lag)
```

F test for individual effects

data: lnGDP ~ D + lag1 + lag2 + lag3 + lag4
F = 51.639, df1 = 85, df2 = 3692, p-value < 2.2e-16
alternative hypothesis: significant effects

```
> phtest(FE_inlevel_lag, RE_inlevel_lag)
```

Hausman Test

```
data: lnGDP ~ D + lag1 + lag2 + lag3 + lag4
chisq = 4389.5, df = 5, p-value < 2.2e-16
alternative hypothesis: one model is inconsistent
```

```
> FE_inlevel_lag_adjust <- plm(lnGDP ~ D+lag1+lag2, data = panel_dataFrame, model = "within")> summary(FE_inlevel_lag_adjust)
```

Oneway (individual) effect within Model

```
Call:
plm(formula = lnGDP ~ D + lag1 + lag2, data = panel_dataFrame,
     model = "within")
```

Unbalanced Panel: n = 86, T = 47-48, N = 4127

```
Residuals:
    Min.    1st Qu.    Median    3rd Qu.    Max.
-282.4355   -8.2967    2.1184   11.6292   162.9124
```

```
Coefficients:
            Estimate Std. Error t-value Pr(>|t|)
D      10.590942    1.175124   9.0126 < 2.2e-16 ***
lag1    0.948318    0.048088  19.7205 < 2.2e-16 ***
lag2   -0.451443    0.047620  -9.4801 < 2.2e-16 ***
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

```
Total Sum of Squares:    4910200
Residual Sum of Squares: 2428800
R-Squared:    0.50537
Adj. R-Squared: 0.49459
F-statistic: 1375.22 on 3 and 4038 DF, p-value: < 2.22e-16
```

```
> pbgttest(FE_inlevel_lag_adjust, order = 1)
```

Breusch-Godfrey/Wooldridge test for serial correlation in panel models

```
data: lnGDP ~ D + lag1 + lag2
chisq = 883.53, df = 1, p-value < 2.2e-16
alternative hypothesis: serial correlation in idiosyncratic errors
```

```
> pbgttest(FE_inlevel_lag, order = 1)
```

Breusch-Godfrey/Wooldridge test for serial correlation in panel models

```
data: lnGDP ~ D + lag1 + lag2 + lag3 + lag4
chisq = 936.9, df = 1, p-value < 2.2e-16
alternative hypothesis: serial correlation in idiosyncratic errors
```

```
> TFE_inlevel_lag_adjust <- plm(lnGDP ~ D+lag1+lag2, data = panel_dataFrame, model = "within", effect = "twoways")> summary(TFE_inlevel_lag_adjust)
```

Twoways effects within Model

```
Call:
plm(formula = lnGDP ~ D + lag1 + lag2, data = panel_dataFrame,
     effect = "twoways", model = "within")
```

Unbalanced Panel: n = 86, T = 47-48, N = 4127

```
Residuals:
      Min.      1st Qu.      Median      3rd Qu.      Max.
-182.404110   -7.405776   -0.077214    7.750292   196.750535
```

```
Coefficients:
      Estimate Std. Error t-value Pr(>|t|)
D      -3.653130   1.079523  -3.384 0.0007212 ***
lag1    0.910859   0.040995  22.219 < 2.2e-16 ***
lag2   -0.483570   0.040844 -11.840 < 2.2e-16 ***
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

```
Total Sum of Squares: 3094100
Residual Sum of Squares: 1618900
R-Squared: 0.47676
Adj. R-Squared: 0.45906
F-statistic: 1212.17 on 3 and 3991 DF, p-value: < 2.22e-16
```

```
> pFtest(TFE_inlevel_lag_adjust, FE_inlevel_lag_adjust)
```

F test for twoways effects

```
data: lnGDP ~ D + lag1 + lag2
F = 42.477, df1 = 47, df2 = 3991, p-value < 2.2e-16
alternative hypothesis: significant effects
```

```
> pbgtest(TFE_inlevel_lag_adjust, order = 1)
```

Breusch-Godfrey/wooldridge test for serial correlation in panel models

```
data: lnGDP ~ D + lag1 + lag2
chisq = 1363.7, df = 1, p-value < 2.2e-16
alternative hypothesis: serial correlation in idiosyncratic errors
```

```
> CCEP<- pcce(lnGDP ~ D+lag1+lag2, data = panel_dataFrame, model = "p")> summary(CCEP)
```

Common Correlated Effects Pooled model

```
Call:
pcce(formula = lnGDP ~ D + lag1 + lag2, data = panel_dataFrame,
      model = "p")
```

Unbalanced Panel: n = 86, T = 47-48, N = 4127

```
Residuals:
      Min.      1st Qu.      Median      3rd Qu.      Max.
-62.83554146  -3.02347397   0.06535095   3.27259385  60.386926
34
```

```
Coefficients:
      Estimate Std. Error z-value Pr(>|z|)
D      0.696297   1.009302   0.6899   0.49027
lag1    0.727282   0.094967   7.6582 1.885e-14 ***
lag2   -0.299151   0.085811  -3.4861   0.00049 ***
```

```
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
Total Sum of Squares: 111410000
Residual Sum of Squares: 169500
HPY R-squared: 0.96224
```

```
> pbgtest(CCEP, order = 1)
```

Breusch-Godfrey/Wooldridge test for serial correlation in panel models

```
data: lnGDP ~ D + lag1 + lag2
chisq = 3227.4, df = 1, p-value < 2.2e-16
alternative hypothesis: serial correlation in idiosyncratic errors
```

```
> CCEMG<- pcce(lnGDP ~ D+lag1+lag2, data = panel_dataFrame, model = "mg")> summary(CCEMG)Common Correlated Effects Mean Groups model
```

```
Call:
pcce(formula = lnGDP ~ D + lag1 + lag2, data = panel_dataFrame,
      model = "mg")
```

Unbalanced Panel: n = 86, T = 47-48, N = 4127

```
Residuals:
      Min.      1st Qu.      Median      3rd Qu.      Max.
-60.47077338  -2.51719699   0.09631358   2.79365840  54.526641
71
```

```
Coefficients:
      Estimate Std. Error z-value Pr(>|z|)
D      0.057980   0.774774   0.0748   0.9403
lag1    0.624131   0.033152  18.8262 <2e-16 ***
lag2   -0.233573   0.025709  -9.0854 <2e-16 ***
```

```

---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
Total Sum of Squares: 111410000
Residual Sum of Squares: 132200
HPY R-squared: 0.96835

```

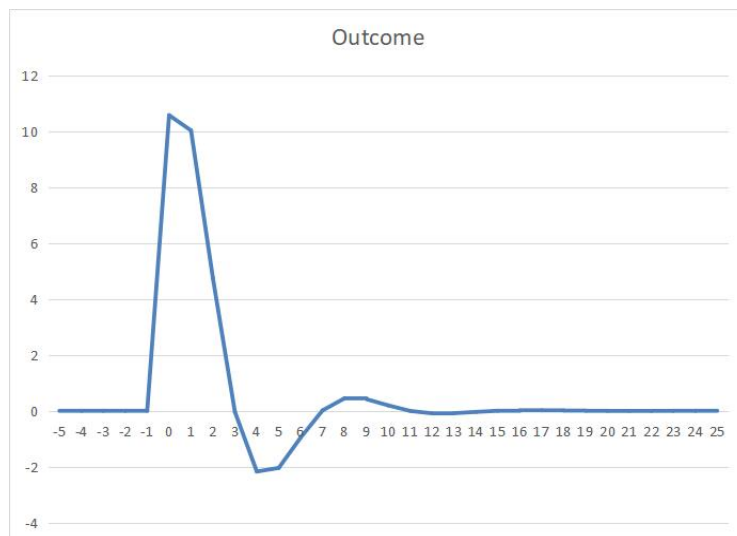
```
> pbgtest(CCEMG, order = 1)
```

Breusch-Godfrey/Wooldridge test for serial correlation in panel models

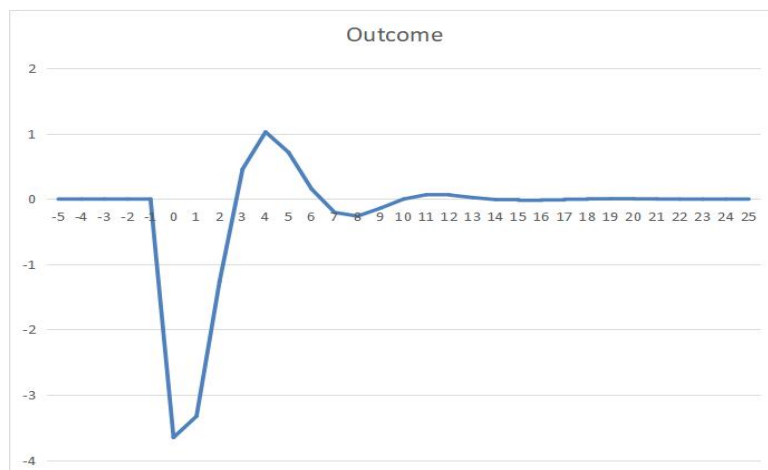
```

data: lnGDP ~ D + lag1 + lag2
chisq = 3227.4, df = 1, p-value < 2.2e-16
alternative hypothesis: serial correlation in idiosyncratic er
rors

```



FE_inlevel_lag_adjust



TFE_inlevel_lag_adjust

What is your choice of p?

From the economic intuition, I firstly choose to set the $p=4$, because most of countries' presidential term is 4 years. So there may be a economic cycle due to this. the president may impose policies with a 4-year goal. And with F-test and Hausman test, I choose fixed effect to estimate my model. However, From the estimation result, we can see that the lag3 and lag4 is not significant. So I change my specification to the order of $p=2$. And all the coefficients now are significant.

Then I do the autocorrelation test, it shows that there is still autocorrelation in the error term on $p=2$, which means that the model may not adequate. then I do the autocorrelation test of $p=4$, but it is still strongly reject the H_0 of no autocorrelation in error term. So adding more lag term may not the way to solve autocorrelation problem and may bring overfitting problem.

So I try to adjust the specification by considering time effect. By Twoway fixed effect model, all the coefficient is significant and the F-test show that the we reject the H_0 of no significant time effect. So the Twoway fixed effect is better. But as for autocorrelation test it's still reject the H_0 of there is no autocorrelation when $p=2$ and even in $p=4$. And same when I change it to common correlated effects model and when I add slope heterogeneity. So we may need another approach like GMM to estimate this model.

What is the dynamic impact of Dit on $\ln GDP_{it}$?

From the impulse response function above, we can know that when considering time effect, the response of $\ln GDP_{it}$ to one transitory shock of Dit firstly be negative and then the negative impact gradually decrease, about 3 years after, the impact become positive and increasing till 4 years after, then it start to decrease and become negative a bit again at 7 years after the shock, then back to positive and finally gradually goes to 0.

And if we just use fixed effect do not consider the time effect, it is opposite with the twoway fixed effect, the impact firstly be positive and then start to decrease, at 3 years after the shock, the impact become negative and back to positive at 7 years and finally gradually goes to 0.

What are the statistical properties of each of the estimators ?

While for Dit , it is still same with the static model, **For consistency**, weakly exogenous for the pooled OLS estimator both for N and T goes to infinity and uncorrelated with the error term. fixed effect estimator and random effect estimator need both strictly exogenous when N goes to infinity and weakly exogenous when T goes to infinity. And also, random effect need Dit is not correlated with the individual effect. That is for Dit . and **now we also have the lag term of $\ln y_{it}$, so we also need $\ln y_{it-1}$ and $\ln y_{it-2}$ is not correlated with the error term. For efficiency**, still only random effect estimator is efficient because it use information from both within dimension and between dimension. **For unbiasedness**, the model is biased because the explanatory is not completely uncorrelated with error term.

It is supported by the statistical test, from the F-test, we reject H_0 of there is no individual effect, and the pooled OLS is inconsistent. from the Hausman test, we reject the H_0 of there is

no significant difference between fixed effect estimations and random effect estimations. So the DIT is correlated with the individual effect. The random effect is not consistent. And we choose fixed effect. From economic view, the country as individuals is one of a kind, not arbitrarily random draws.

Also, like mentioned above, if the DIT is endogenous and determined by the LNYIT, the model will not be consistent. And if the DIT is determined just by the lag term of LNYIT, there might be multicollinearity in model but since all the coefficient is significant, and the model is still consistent, so it is still valid.

In addition, we further add the time effect and do the F-test and we reject H0 of there is no time effect. So we choose twoway fixed effect finally.

```
> POLS_GDPgrowth_lag <- plm(GDPgrowth ~ D+lag_1+lag_2, data =
panel_dataFrame, model = "pooling")> summary(POLS_GDPgrowth_lag)
```

Pooling Model

```
Call:
plm(formula = GDPgrowth ~ D + lag_1 + lag_2, data = panel_data
Frame,
      model = "pooling")
```

Balanced Panel: n = 86, T = 46, N = 3956

Residuals:

Min.	1st Qu.	Median	3rd Qu.	Max.
-70.72353	-1.92882	0.31762	2.25130	66.88238

Coefficients:

	Estimate	Std. Error	t-value	Pr(> t)	
(Intercept)	1.060179	0.123727	8.5687	< 2.2e-16	***
D	0.552004	0.165610	3.3332	0.0008666	***
lag_1	0.164564	0.015754	10.4460	< 2.2e-16	***
lag_2	0.032148	0.015457	2.0799	0.0375968	*

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Total Sum of Squares: 110450

Residual Sum of Squares: 106710

R-Squared: 0.033879

Adj. R-Squared: 0.033146

F-statistic: 46.1954 on 3 and 3952 DF, p-value: < 2.22e-16

```
> FE_GDPgrowth_lag <- plm(GDPgrowth ~ D+lag_1+lag_2, data = pa
nel_dataFrame, model = "within")> summary(FE_GDPgrowth_lag)
```

Oneway (individual) effect within Model

```
Call:
plm(formula = GDPgrowth ~ D + lag_1 + lag_2, data = panel_data
Frame,
```

```

      model = "within")

Balanced Panel: n = 86, T = 46, N = 3956

Residuals:
      Min.      1st Qu.        Median      3rd Qu.       Max.
-66.86243  -1.79309    0.29183    2.15417   67.93701

Coefficients:
              Estimate Std. Error t-value Pr(>|t|)
D              0.470333   0.247211   1.9026   0.05717 .
lag_1          0.094269   0.015960   5.9066 3.793e-09 ***
lag_2         -0.032831   0.015635  -2.0998   0.03581 *
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Total Sum of Squares:    100490
Residual Sum of Squares: 99437
R-Squared:                0.010502
Adj. R-Squared:          -0.012016
F-statistic: 13.6805 on 3 and 3867 DF, p-value: 7.1032e-09

```

```

> RE_GDPgrowth_lag <- plm(GDPgrowth ~ D+lag_1+lag_2, data = pa
nel_dataFrame, model = "random")> summary(RE_GDPgrowth_lag)

```

Oneway (individual) effect Random Effect Model
(Swamy-Arora's transformation)

```

Call:
plm(formula = GDPgrowth ~ D + lag_1 + lag_2, data = panel_data
Frame,
      model = "random")

```

Balanced Panel: n = 86, T = 46, N = 3956

```

Effects:
              var std.dev share
idiosyncratic 25.714   5.071    1
individual      0.000   0.000    0
theta: 0

```

```

Residuals:
      Min.      1st Qu.        Median      3rd Qu.       Max.
-70.72353  -1.92882    0.31762    2.25130   66.88238

```

```

Coefficients:
              Estimate Std. Error z-value Pr(>|z|)
(Intercept)  1.060179   0.123727   8.5687 < 2.2e-16 ***
D              0.552004   0.165610   3.3332 0.0008587 ***
lag_1          0.164564   0.015754  10.4460 < 2.2e-16 ***
lag_2          0.032148   0.015457   2.0799 0.0375325 *
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

```

```

Total Sum of Squares:    110450
Residual Sum of Squares: 106710
R-Squared:                0.033879
Adj. R-Squared:          0.033146

```


Chisq: 138.586 on 3 DF, p-value: < 2.22e-16

```
> pFtest(FE_GDPgrowth_lag, POLS_GDPgrowth_lag)
```

F test for individual effects

```
data: GDPgrowth ~ D + lag_1 + lag_2
F = 3.3282, df1 = 85, df2 = 3867, p-value < 2.2e-16
alternative hypothesis: significant effects
```

```
> phtest(FE_GDPgrowth_lag, RE_GDPgrowth_lag)
```

Hausman Test

```
data: GDPgrowth ~ D + lag_1 + lag_2
chisq = 391.95, df = 3, p-value < 2.2e-16
alternative hypothesis: one model is inconsistent
```

```
> pbgttest(FE_GDPgrowth_lag)
```

Breusch-Godfrey/Wooldridge test for serial correlation in panel models

```
data: GDPgrowth ~ D + lag_1 + lag_2
chisq = 372.98, df = 46, p-value < 2.2e-16
alternative hypothesis: serial correlation in idiosyncratic errors
```

```
> FE_GDPgrowth_lag_adjust <- plm(GDPgrowth ~ D+lag_1+lag_2+lag_3+lag_4, data = panel_dataFrame, model = "within")> summary(FE_GDPgrowth_lag_adjust)
```

Oneway (individual) effect within Model

```
Call:
plm(formula = GDPgrowth ~ D + lag_1 + lag_2 + lag_3 + lag_4,
     data = panel_dataFrame, model = "within")
```

Balanced Panel: n = 86, T = 42, N = 3612

Residuals:

	Min.	1st Qu.	Median	3rd Qu.	Max.
	-66.47239	-1.78733	0.28224	2.18673	66.90491

Coefficients:

	Estimate	Std. Error	t-value	Pr(> t)	
D	0.549837	0.256032	2.1475	0.031819	*
lag_1	0.095684	0.016348	5.8529	5.272e-09	***
lag_2	-0.039753	0.016258	-2.4451	0.014530	*
lag_3	-0.042268	0.016022	-2.6381	0.008373	**
lag_4	-0.035776	0.015805	-2.2636	0.023658	*

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

```

Total Sum of Squares:    88647
Residual Sum of Squares: 87166
R-Squared:              0.016715
Adj. R-Squared: -0.0084187
F-statistic: 11.9708 on 5 and 3521 DF, p-value: 1.6354e-11

```

```
> pbgtest(FE_GDPgrowth_lag_adjust)
```

Breusch-Godfrey/Wooldridge test for serial correlation in panel models

```

data: GDPgrowth ~ D + lag_1 + lag_2 + lag_3 + lag_4
chisq = 335.21, df = 42, p-value < 2.2e-16
alternative hypothesis: serial correlation in idiosyncratic errors

```

```
> TFE_GDPgrowth_lag_adjust <- plm(GDPgrowth ~ D+lag1+lag2, data = panel_dataFrame, model = "within", effect = "twoways")> summary(TFE_GDPgrowth_lag_adjust)
```

Twoways effects within Model

```

Call:
plm(formula = GDPgrowth ~ D + lag1 + lag2, data = panel_dataFrame,
     effect = "twoways", model = "within")

```

Balanced Panel: n = 86, T = 47, N = 4042

Residuals:

	Min.	1st Qu.	Median	3rd Qu.	Max.
	-64.45748	-1.83081	0.21081	2.09663	63.12833

Coefficients:

	Estimate	Std. Error	t-value	Pr(> t)
D	0.526150	0.264344	1.9904	0.04662 *
lag1	0.024659	0.010011	2.4633	0.01381 *
lag2	-0.054865	0.009978	-5.4985	4.074e-08 ***

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

```

Total Sum of Squares:    95414
Residual Sum of Squares: 92130
R-Squared:              0.034416
Adj. R-Squared: 0.001299
F-statistic: 46.4187 on 3 and 3907 DF, p-value: < 2.22e-16

```

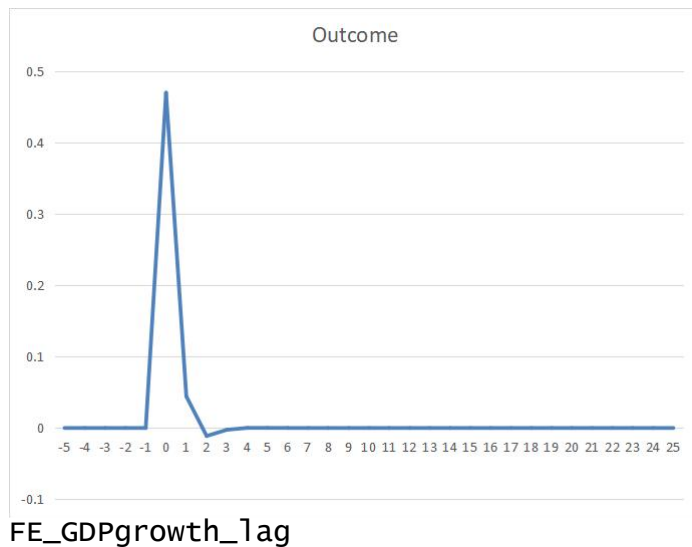
```
> pbgtest(TFE_GDPgrowth_lag_adjust)
```

Breusch-Godfrey/Wooldridge test for serial correlation in panel models

```

data: GDPgrowth ~ D + lag1 + lag2
chisq = 291.69, df = 47, p-value < 2.2e-16
alternative hypothesis: serial correlation in idiosyncratic errors

```



What is your choice of p?

As for the GDP in level, the choice of $p=2$, so for GDP growth I also set my specification starting from $p=2$ and the pooled OLS, fixed effect and random effect all show that the lag1 is significant, and the lag 2 term is only significant at 0.01 significant level. So I think $p=2$ may already be adequate.

Then I do the autocorrelation test, it rejects the H_0 of no autocorrelation in the error term. So I extend the model to $p=4$ and test for autocorrelation again. The Dit becomes less significant and there is still an autocorrelation problem.

So I believe like GDP in level, there may be the issue that cannot eliminate the autocorrelation by just extending the lag which will also bring overfitting problem. Then I try to adjust my specification to a more proper model by adding time effect. I use the twoway fixed effect to estimate and test for autocorrelation again, and it still rejects H_0 of no autocorrelation, so we may need another more valid approach.

What is the dynamic impact of Dit on $\Delta \ln GDP_{it}$ and $\ln GDP_{it}$?

From the impulse response function above, the dynamic response of $\Delta \ln GDP_{it}$ to the one unit transitory shock of Dit will be first positive and then after two years the influence becomes near 0. It is negative very little and then goes back to positive also very little and then converges to 0.

And the response of the $\ln GDP_{it}$ is the cumulative response of the $\Delta \ln GDP_{it}$ to the impact of the Dit now. and **from the impulse response function above, it shows that the cumulative response of $\Delta \ln GDP_{it}$ is large than 0. put differently, even the unit shock of Dit is transitory, it still has a permanent impact on $\ln GDP_{it}$.**

This is in line with our expectation because by this model, it imposes that the $\ln y_{it}$ have a unit root. So it will not converge to 0.

What are the statistical properties of each of the estimators ?

In theory, always same story, **For consistency**, pooled OLS need D_{it} weakly exogenous for both N goes to infinity and T goes to infinity and uncorrelated with the error term. The lag term need to be contemporaneously uncorrelated with the error term. fixed effect estimator and random effect estimator both need to be weakly exogenous when T goes to infinity and strictly exogenous when N goes to infinity and random effect estimator also need D_{it} uncorrelated with the individual effect, the lag term contemporaneously uncorrelated. **For efficiency**, only the random effect estimator is efficient. **For unbiasedness**, this is dynamic model so it is all biased.

By statistical test, it's in line of the theory, from the F-test we reject the H_0 of no individual effect, from the Hausman test we reject the H_0 of there is no significant difference between fixed effect estimator and random effect estimator. so we know the pooled OLS is not consistent and random effect is not consistent. We choose fixed effect estimator. From the economic view, the country as individuals is one of a kind, not arbitrary random draws.

Further questions:

Compute the dynamic impact of democratization on both economic growth and the level of GDP over a 30 years horizon after the shock towards a democracy.

See the impulse response function above.

Which of the above model do you prefer (and why)?

I would choose the model of Inyit's dynamic model on D_{it} (model(3)). static model can not be the case because GDP can always be influenced by the lag term and indeed it is significant in the dynamic model. static model will miss many dynamic behavior.

And if I use GDP in first difference, I impose the $\ln GDP_{it}$ have a unit root without test if it is stationary or not. And even let say it is $I(1)$, it still might be misspecification if there is cointegration relationship between $\ln GDP_{it}$ and D_{it} , which can not be reparameterization to error correction model, so it miss the error correction term. Also, $\Delta \ln GDP_{it}$ will be $I(0)$, and D_{it} is $I(1)$, in general this cannot be estimated, the error term will be $I(1)$.

However, as a matter of fact, the $\Delta \ln GDP_{it}$ is non-stationary by construction (true reason might be structural break), **but we can never know**, the unit root test now is not reliable for it can not identify the structural break.

And also the dynamic impact of transitory shock on D_{it} will be permanent on $\ln GDP_{it}$ in level which would not really happening in the real world.

By using $\ln GDP$ in level, **the real DGP will nested in my specification, I will get consistent estimates. and in panel model, my model will be consistent even if the variable is non-stationary and no cointegration by adding common correlated factor to absorb the cross-sectional dependence.**

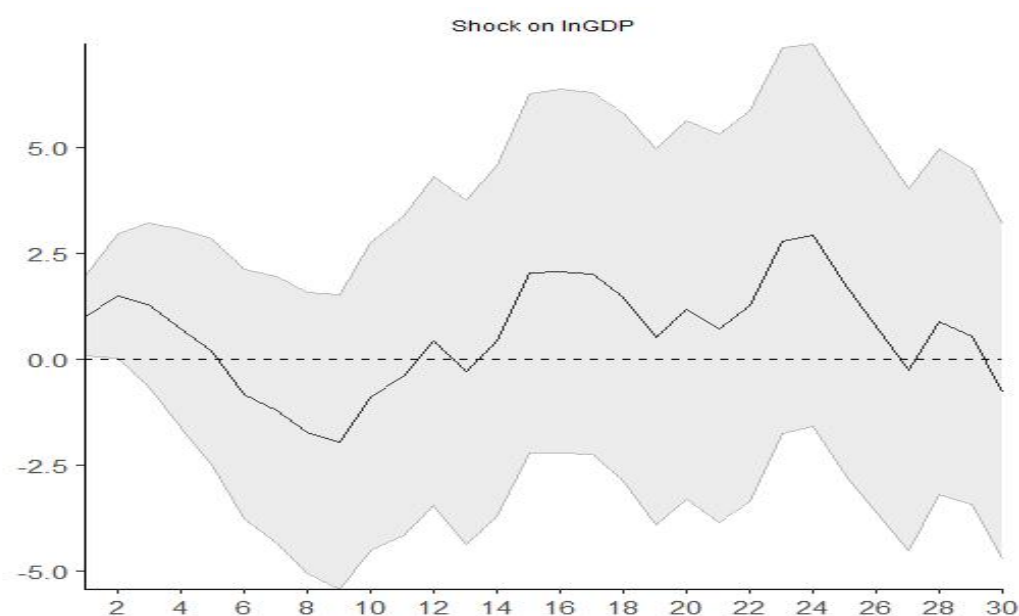
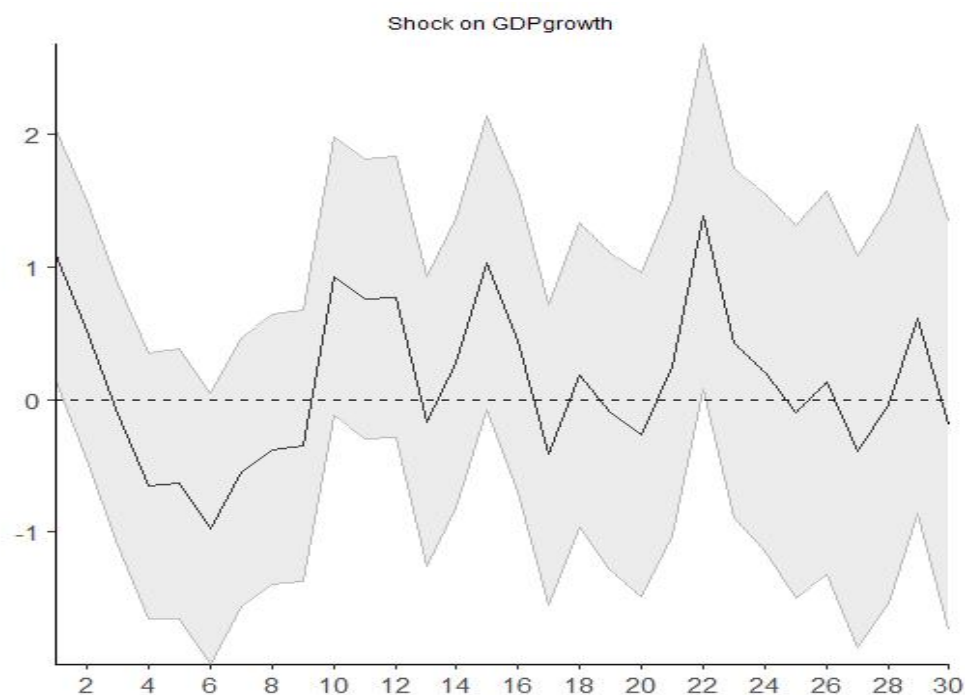
In addition, I choose fixed effect estimator both this two dynamic model which will use only information from within dimension. And the $\ln GDP$ in first difference may reduce lots of within information for there may not be much variation in GDP growth within one country.

Suppose we replace D_{it} by ΔD_{it} in eqs. (1)-(4). How does this change the dynamic impact of democratization? Does this make sense?

The model become to in first differences in (2) and (4) and it only valid when there is no cointegration between $\ln GDP_{it}$ and D_{it} . And it only reflect the short run dynamics.

Also the meaning of the coefficient will change, as the D_{it} is a dummy variable, its in differences **capture more changes in democratic status rather than the democratic status.** So this will be the dynamic impact of the democratic changes to the $\ln y_{it}$ or $\Delta \ln y_{it}$ instead of how the democratic status impact the $\ln y_{it}$ or $\Delta \ln y_{it}$. If we use D_{it} , it is more capturing the **impact of being democracy on $\ln y_{it}$ or $\Delta \ln y_{it}$** , it is typically considered **long run and persistent.**

And if we use ΔD_{it} , it explained how the **change from democratic status to non democracy** or other way round impact economic and it is usually short run and temporary.



What are the statistical properties of the FE estimator ?

For consistency, when N goes to infinity, the D_{it} need to be strictly exogenous and when T goes to infinity, the D_{it} need to be weakly exogenous, and also the lag term of $\Delta \ln y_{it}$ need to be contemporaneously uncorrelated with the error term. Also, **this is the GDP growth with D_{it}**

t in first difference, so this is all stationary and local projection even if we miss the error term, it also can be consistent.

And for efficiency, Fixed effect estimator is not efficient because it only use information from within dimension. And this is **biased** because in dynamic model explanatory variable is not completely independent from error term.

What is the dynamic impact of democratization on GDP ?

From the impulse response function of $\ln GDP$ above, we know that it is the cumulated impulse response of the GDP growth, and it's firstly positive to the five years after the change to the democratization, and then it become negative till near 12 years after, with a small fluctuation, starting from 14 years it become positive again, then, it basically keep positive to the 30 years after.

Would you rather use $\Delta \ln y_{it}$ (instead of $\Delta \ln y_{it}$) in equation (5) ?

No, because the local projection is more robust in first difference form, even if there is cointegration relationship between $\ln y_{it}$ and $\Delta \ln y_{it}$. It is consistent and I can do standard inference.

But if I switch to $\Delta \ln y_{it}$, then I can not do standard inference and the bias will lead it to inconsistent. The performance of local projection will deteriorates with the h increases for t here might be spurious-regression-like problem in error term if the $\Delta \ln y_{it}$ have a unit root.

Consider the following alternative models, which model do you prefer and why ?

I prefer the model 2, because from the left hand side, it is cumulative $\ln y_{it}$ in first difference (i.e. cumulative GDP growth rate). and on the right hand side, they are $\Delta \ln y_{it}$ in difference and lag term of $\Delta \ln y_{it}$ in first difference and $\ln y_{it}$ in first difference. **All the variables are stationary.** So compared to model 1 and 3 in level. **model 2 is consistent even if there is cointegration relationship.** What is more, model 2 also contain the lag term of $\Delta \ln y_{it}$ in first difference, and the $\ln y_{it}$ may also be impacted with that. **so it can capture more comprehensive dynamic impact compared to model 4.** only problem is there by doing so there might be some multicollinearity in the model, but it need to be test with that and if all the parameters are significant, then it can be ignored.

```
> purtest(panel_dataFrame$lnGDP, exo= "trend", test = "levinlin")
```

Levin-Lin-Chu Unit-Root Test (ex. var.: Individual Intercepts and Trend)

```
data: panel_dataFrame$lnGDP
z = -3.22, p-value = 0.000641
alternative hypothesis: stationarity
```

```
> purtest(panel_dataFrame$lnGDP, exo= "trend", test = "ips", index = c("CountryID", "TimeID"))
```

Im-Pesaran-Shin Unit-Root Test (ex. var.: Individual Intercepts and Trend)

```
data: panel_dataFrame$lnGDP
wtbar = 0.66795, p-value = 0.7479
alternative hypothesis: stationarity
```

```
> purtest(panel_dataFrame$lnGDP, pmax = 4, exo = "trend", test = "madwu")
```

Maddala-Wu Unit-Root Test (ex. var.: Individual Intercepts and Trend)

```
data: panel_dataFrame$lnGDP
chisq = 161.48, df = 172, p-value = 0.7065
alternative hypothesis: stationarity
```

```
> purtest(panel_dataFrame[, "GDPgrowth"], exo = "intercept", test = "levinlin")
```

Levin-Lin-Chu Unit-Root Test (ex. var.: Individual Intercepts)

```
data: panel_dataFrame[, "GDPgrowth"]
z = -42.532, p-value < 2.2e-16
alternative hypothesis: stationarity
```

```
> purtest(panel_dataFrame[, "GDPgrowth"], test = "ips", exo = "intercept")
```

Im-Pesaran-Shin Unit-Root Test (ex. var.: Individual Intercepts)

```
data: panel_dataFrame[, "GDPgrowth"]
wtbar = -43.857, p-value < 2.2e-16
alternative hypothesis: stationarity
```



```
> purtest(panel_dataFrame[, "GDPgrowth"], pmax = 4, exo = "intercept", test = "madwu")
```

Maddala-Wu Unit-Root Test (ex. var.: Individual Intercepts)

```
data: panel_dataFrame[, "GDPgrowth"]
chisq = 2648.4, df = 172, p-value < 2.2e-16
alternative hypothesis: stationarity
```

```
. xtunitroot llc d, demean lags(bic 1)
```

Levin-Lin-Chu unit-root test for **d**

Ho: Panels contain unit roots	Number of panels =	86
Ha: Panels are stationary	Number of periods =	51
AR parameter: Common	Asymptotics: N/T -> 0	
Panel means: Included		
Time trend: Not included	Cross-sectional means removed	

ADF regressions: **0.02** lags average (chosen by **BIC**)
 LR variance: **Bartlett** kernel, **11.00** lags average (chosen by **LLC**)

	Statistic	p-value
Unadjusted t	-1.8265	
Adjusted t*	6.6896	1.0000

```
. xtunitroot ips d, demean lags(bic 1)
```

Im-Pesaran-Shin unit-root test for **d**

Ho: All panels contain unit roots	Number of panels =	86
Ha: Some panels are stationary	Number of periods =	51
AR parameter: Panel-specific	Asymptotics: T,N -> Infinity	
Panel means: Included	sequentially	
Time trend: Not included	Cross-sectional means removed	

ADF regressions: **0.02** lags average (chosen by **BIC**)

	Statistic	p-value
W-t-bar	6.0960	1.0000

```
. xtunitroot fisher d, dfuller demean lags(1)
```

Fisher-type unit-root test for **d**

Based on augmented Dickey-Fuller tests

Ho: All panels contain unit roots	Number of panels =	86
Ha: At least one panel is stationary	Number of periods =	51
AR parameter: Panel-specific	Asymptotics: T -> Infinity	
Panel means: Included		
Time trend: Not included	Cross-sectional means removed	
Drift term: Not included	ADF regressions: 1 lag	

	Statistic	p-value
Inverse chi-squared(172) P	150.3921	0.8813
Inverse normal Z	5.0010	1.0000
Inverse logit t(434) L*	4.8840	1.0000
Modified inv. chi-squared Pm	-1.1650	0.8780

P statistic requires number of panels to be finite.

Other statistics are suitable for finite or infinite number of panels.

```
. xtunitroot llc diff_d , demean lags(bic 1)
```

Levin-Lin-Chu unit-root test for **diff_d**

Ho: Panels contain unit roots	Number of panels =	86
Ha: Panels are stationary	Number of periods =	50
AR parameter: Common	Asymptotics: N/T -> 0	
Panel means: Included		
Time trend: Not included	Cross-sectional means removed	

ADF regressions: **0.05** lags average (chosen by **BIC**)

LR variance: **Bartlett** kernel, **11.00** lags average (chosen by **LLC**)

	Statistic	p-value
Unadjusted t	-62.1569	
Adjusted t*	-57.4304	0.0000

```
. xtunitroot ips diff_d , demean lags(bic 1)
```

Im-Pesaran-Shin unit-root test for **diff_d**

Ho: All panels contain unit roots	Number of panels =	86
Ha: Some panels are stationary	Number of periods =	50
AR parameter: Panel-specific	Asymptotics: T,N -> Infinity	
Panel means: Included	sequentially	
Time trend: Not included	Cross-sectional means removed	

ADF regressions: **0.05** lags average (chosen by **BIC**)

	Statistic	p-value
W-t-bar	-54.6772	0.0000

```
. xtunitroot fisher diff_d , dfuller demean lags(1)
```

Fisher-type unit-root test for **diff_d**
Based on augmented Dickey-Fuller tests

Ho: All panels contain unit roots	Number of panels =	86
Ha: At least one panel is stationary	Number of periods =	50
AR parameter: Panel-specific	Asymptotics: T -> Infinity	
Panel means: Included		
Time trend: Not included	Cross-sectional means removed	
Drift term: Not included	ADF regressions: 1 lag	

	Statistic	p-value
Inverse chi-squared(172) P	1915.0303	0.0000
Inverse normal Z	-37.9527	0.0000
Inverse logit t(434) L*	-56.8834	0.0000
Modified inv. chi-squared Pm	93.9779	0.0000

P statistic requires number of panels to be finite.
Other statistics are suitable for finite or infinite number of panels.

```
> pcdtest(lnGDP)
```

Pesaran CD test for cross-sectional dependence in panels

data: lnGDP

z = 187.73, p-value < 2.2e-16

alternative hypothesis: cross-sectional dependence

```
> pcdtest(GDPgrowth)
```

Pesaran CD test for cross-sectional dependence in panels

```
data: GDPgrowth
z = 41.304, p-value < 2.2e-16
alternative hypothesis: cross-sectional dependence
```

```
> CCEP_forcointegration<- pcce(lnGDP ~ D, data = panel_dataFra
me, model = "p")> summary(CCEP_forcointegration)
```

Common Correlated Effects Pooled model

```
Call:
pcce(formula = lnGDP ~ D, data = panel_dataFrame, model = "p")
```

Balanced Panel: n = 86, T = 51, N = 4386

```
Residuals:
      Min.      1st Qu.      Median      3rd Qu.      Max.
-94.8164036  -4.6671682   0.0574923   4.7848192   57.3585377
```

```
Coefficients:
      Estimate Std. Error z-value Pr(>|z|)
D      1.9877    38.3573   0.0518   0.9587
Total Sum of Squares: 117260000
Residual Sum of Squares: 411960
HPY R-squared: 0.9271
```

```
> paneldata_residuals_cce <- pdata.frame(residuals_df_cce, ind
ex = c("individual_id","time_id"))
```

```
> purtest(paneldata_residuals_cce$residuals, test = "madwu")
```

Maddala-Wu Unit-Root Test (ex. var.: None)

```
data: paneldata_residuals_cce$residuals
chisq = 725.72, df = 172, p-value < 2.2e-16
alternative hypothesis: stationarity
```

What do the results of your cross-sectional dependence test imply for the properties of the considered panel unit root tests ?

From the cross-sectional dependence test, it reject the H_0 of there is no cross-sectional dependence. And this will lead all the first generation unit root test(LLC test, IPS test and Maddala Wu test have a nontrivial size distortion. There will always be type I error for the significance level has been distorted.

What do the results of your unit root tests imply for the properties of the estimates of equations (1)-(5) ?

From the unit root test, I reject that all the ΔD_i and $\Delta \ln GDP_i$ contain at least one unit root and I accept that all the $\ln GDP_i$ and D_i contain at least one unit root. Put differently, $\ln GDP_i$ is $I(1)$ and D_i is also $I(1)$, Also there is cross-sectional dependence in $\ln GDP_i$ and $\Delta \ln GDP_i$.

For model (1), it may be spurious regression like in time series if there is no cointegration between $\ln GDP_i$ and D_i bring the unbiased but inconsistent result. However, we can add common correlated factor to absorb the cross-sectional dependence, then we will get consistent result.

For model (2), because $\Delta \ln GDP_i$ is 'stationary' by test (in fact they may not hold because there might be structural break) and D_i is non-stationary so the error term will also be non-stationary. The model would be inconsistent it may also be the spurious regression.

For model (3), it is consistent if there is cointegration relationship, if there is no cointegration, I can also add common correlated factor can absorb the cross-sectional dependence which will give me consistent result. Or I can add the lag term of D_i then my model will be consistent because the real DGP will be nested in my model so in general my model will be right.

For model (4), it is not consistent because $\Delta \ln GDP_i$ is $I(0)$ and D_i is $I(1)$, and this will bring $I(1)$ in error term. Also same problem like model (2), we can not identify the structural break by unit root test.

For model (5), it is consistent, because all the variable is stationary and local projection is robust to misspecification if there is cointegration relationships.