

One-dimensional Classical Gas in a Harmonic Trap with Repulsive Interaction

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Abstract – to be written last

I. INTRODUCTION

Will write Introduction after everything else is written.

Stat-mech from the ‘bottom up’. Find papers that do the same.

More detailed citations of breathing mode. There are also papers on classical breathing mode, e.g., by Bonitz.

Controlled and tunable experimental realizations of confined quantum systems with ultracold atoms enable nonequilibrium studies of quantum many-body states in novel geometries. A common feature of many cold-atom experiments is the confinement of a many-body system in a harmonic trap. Trapping introduces many distinctive features which have no analog in uniform many-body states, including collective excitations such as breathing modes, dipole modes, and scissors modes. Such trap-related collective modes have been widely studied both experimentally and theoretically for continuum systems, especially in the mean-field regime, since the early days after quantum degeneracy was achieved with trapped atoms [2][3].

In mean-field perspective, the physics of atom gas in Bose-Einstein Condensation can be described by the Gross-Pitaevskii equation[4][5], where the breathing frequency for 1D Bose gas is calculated to be $\Omega_{GP} = \sqrt{3}\omega_0$. Meanwhile, the experiment of Ref.[6] has found a regime of interactions where the breathing-mode frequency approaches the Gross-Pitaevskii prediction. However, since mean-field approach which generally omit quantum fluctuation is successful in this problem, one may wonder how quantum effects play the role in the breathing mode. Thus, a natural question would be asked is that how breathing frequency is dependent on interaction for classical gas. Though generated in BEC, the breathing mode phenomenon is not restricted to BEC. For a classical gas, the breathing mode still can be excited with a quench. Usually, a good knowledge of the classical version may help us understand the quantum one better. David Guery-Odelin, Francesca Zambelli, Jean Dalibard, and Sandro Stringari answered this question in ref.[7]. They used the Boltzmann equation as well as molecular dynamics simulation to study the monopole mode and quadrupole mode of the 2-D classical gas in a harmonic trap. But in that work, the interaction is elastic collision, i.e. zero-range-infinite-strength interaction. We think introducing a finite range for the repulsive interaction will definitely enrich the physics in this system which looks simple, thus producing a different equilibrium and non-equilibrium behaviour. Surprisingly, to the best of our knowledge, there is no in-depth study of this case. For this reason, more study is necessary.

On the other hand, in a non-equilibrium many-body system, a more intriguing question is about its thermalization or relaxation property. Thermalization is among the most fundamental processes for a many-body interacting system. All systems do not thermalize. An example is the Fermi-Pasta-Ulam paradox [] which shows confinement in phase-space so that the system stay non-thermalized for a long time. A lot of research on thermalization property has been done in other classical system. Ref.[8][9] studied the one dimensional gravitational system with Lyapunov exponents. Ref.[10] studied the ring of harmonic oscillators and magnetic moment by examine the canonical distribution of a subsystem. In our paper, we will also probe the system’s thermalization time scales from the perspective of canonical distribution as well as Lyapunov exponent.

Breathing frequency, comparison to quantum case —

Usually, to see the response of quantum gas to a quench, one begin simulation with the ground state and then suddenly vary some parameter by a little, for instance, $\omega'_0 \rightarrow \omega_0 = \omega'_0 + \Delta\omega$. In that case, one will observe the radius R of the cloud oscillating at a certain frequency, which is usually called “breathing mode”.

However, it is quite different in the classical version. Firstly, it is no longer necessary to focus on ground state. In quantum case, the reason why we care about ground state and low lying excitations is that BEC occur at low temperature. But in classical case, there is no BEC. So it is not necessary to focus on low lying excitations in classical case. Besides, since classical limit is $\hbar \rightarrow 0$, no matter how low the kT is, \hbar/kT is always zero so even in low energy regime, the classical behaviors could be quite different from the quantum one. Secondly, it is no longer necessary to vary parameters “by a little” in the quench. In quantum case, the small quench $\omega'_0 \rightarrow \omega_0 = \omega'_0 + \Delta\omega$ means the spectrum of Hamiltonian is shifted slightly, thus one may expect to see some beat phenomenon(?). But in classical case, since \hbar vanishes, no matter how small the quench is, the reason that cause beats in quantum case no longer work in classical context. Thus it is not necessary to limit ourselves to small quench.

Let’s consider quenching the harmonic potential, i.e., $\omega_0 \rightarrow \omega'_0 = \omega_0 + \Delta\omega_0$. We notice that X and P (scaled) are symmetric for simple harmonic oscillator. In weak interaction limit, the distribution cloud should be circular when the gas is completely thermalized. The difference between thermalized cloud before and after quench is that they are circular under different scaling ratio of P and X axis. If we look at both of them in the phase-space rescaled according to ω'_0 , we will find shape of the cloud before the quench is an ellipse while the final one is a circle.

The words ergodic, relaxation and thermalization

Loss of memory of initial state — our two definitions

This paper is organized as follows: In Section II, we perform a scaling to reduce the number of parameters of the system. In addition, we briefly observe the ground state and reveal two dynamically distinct regime of the system, i.e. strong interaction regime and weak interaction regime. In Section III, we evaluate the breathing frequency according to its mechanism, and compare that with our numerical simulation result. Besides, we also introduce a rotating frame method of treating this problem, which is a convenient tool to analyze simple harmonic systems. In section IV, we focus on the thermalization property. We first examine the canonical distribution of energy to find out the threshold of thermalization, i.e. under what parameter the thermalization time scale is very large. In the end of this section, we measure the Lyapunov Exponent to quantify the time scales and confirm the former discussion. Then we point out that there are two kind of thermalization behavior that could be measured in this system, one is about energy distribution while another is about shape of cloud in phase-space. Since here we find two sense of “thermalizing”, we will redefine our terms – When a system’s energy distribution goes to equilibrium, we still call it “thermalized”. But when a system’s distribution in phase-space goes to equilibrium, we call it “relaxed” to distinguish it from “thermalized”. So in section V we actually study the “thermalizing” of the shape of the cloud in phase-space, or the “relaxation” behavior of the system. There we discovered a long-lasting mode, which turns out to be a quadruple mode in phase-space.

II. THE MODEL AND ITS EQUILIBRIUM PROPERTIES

A. Model and Scaling

Our model for the interacting classical gas involves particles with a simple finite-range repulsive interaction. Two particles repel each other whenever they are within a distance σ from each other. The force of repulsion is a constant, F_0 , within this distance and zero when the distance is larger.

$$|F(|x|)| = \begin{cases} F_0 & |x| < \sigma \\ 0 & |x| > \sigma \end{cases} \quad (1)$$

where $|x|$ is the distance between two particles. This equation describes the magnitude of the interparticle force; the direction is always repulsive.

The gas contains N such identical particles, each of mass m , in a harmonic trap. The Hamiltonian describing the gas is

$$H = \frac{1}{2}m\omega_0^2 \sum_i x_i^2 + \frac{1}{2}m \sum_i v_i^2 + \sum_{|x_i - x_j| < \sigma} F_0 (\sigma - |x_i - x_j|) \quad (2)$$

It is useful to rescale the quantities. We will measure distance, time, energy and force in units of σ , $1/\omega$, $m\omega_0^2\sigma^2$ and $m\omega_0^2\sigma$ respectively:

$$\tilde{x}_i = \frac{x_i}{\sigma}, \quad \tilde{H} = \frac{H}{m\omega_0^2\sigma^2}, \quad \tilde{t} = \omega_0 t, \quad \tilde{F}_0 = \frac{F_0}{m\omega_0^2\sigma}. \quad (3)$$

Eq. 2 is then rewritten as

$$\tilde{H} = \frac{1}{2} \sum_i \tilde{x}_i^2 + \frac{1}{2} \sum_i \left(\frac{d\tilde{x}_i}{d\tilde{t}} \right)^2 + \sum_{|\tilde{x}_i - \tilde{x}_j| < 1} \tilde{F}_0 (1 - |\tilde{x}_i - \tilde{x}_j|) \quad (4)$$

Through this rescaling, we have reduced the number of the parameters in our model to three: the energy \tilde{H} , the interaction strength \tilde{F}_0 , and the number of particles N . The rescaling is equivalent to setting σ , ω_0 and m to 1; this is what we do in our numerical simulation. In the rest of this paper, we will use “E” and “ F_0 ” to denote the reduced versions \tilde{H} and \tilde{F}_0 .

We will be concerned with the size of the cloud. We quantify the size through the root-mean-square of particle positions $\{x_i\}$,

$$R \equiv \left(\overline{x_i^2} \right)^{\frac{1}{2}}, \quad (5)$$

and refer to this quantity as the ‘radius’ or ‘cloud radius’.

In the dilute gas limit, there are few or no interactions occurring at most times. Thus the energy E is dominated by the trap energy, i.e., $E \approx m\omega_0^2 \sum_i x_i^2 = Nm\omega_0^2 R^2$, or, in our units,

$$E \approx NR^2. \quad (6)$$

This is a good approximation at large F_0 because, for very large interactions, the particles behave as hard rods which bounce off each other very rapidly, so that at most instants one can expect no collisions to be taking place. It is also expected to be a good approximation at very small F_0 since we can then simply neglect the interaction energy. Thus, we will use this as a common estimate for R in terms of the energy.

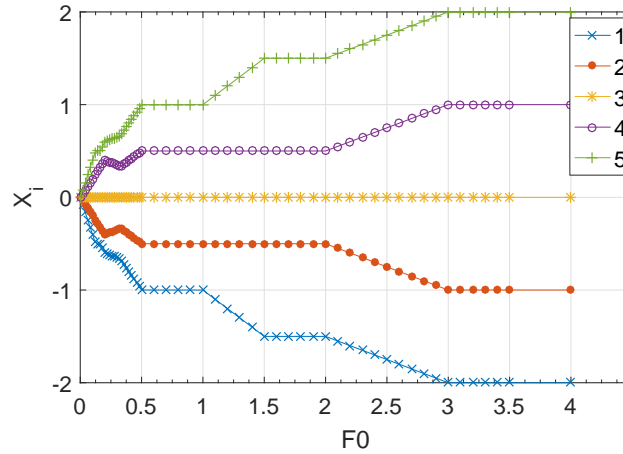


FIG. 1. The ground state of a system with $N = 5$ particles, shown via the positions of each particle, labeled 1 through 5. At large interactions, the particles position themselves just outside the range of interactions of the neighboring particles.

B. Ground states

The lowest-energy state of the system has zero kinetic energy; in this state the particles find stationary positions which minimize the trap (potential) and interaction energies. The trap potential tries to squeeze the particles towards the trap center, while the interaction tries to push them apart.

Because of the ‘Heaviside theta’ form of our interaction, at large enough interactions (large F_0) the particles are spaced exactly at distance equal to the range σ , which is distance 1 in our rescaled units. The interaction is then effectively a ‘hard-core’ interaction.

At very small F_0 , the particles in the ground state are close enough to the trap center that each particle interacts with every other particle. Equating the interaction force due to all the other particles with the trapping force, one finds that the position of the i -th particle is

$$x_i = \frac{2F_0}{m\omega_0^2} \left(i - \frac{N+1}{2} \right) = 2F_0 \left(i - \frac{N+1}{2} \right) \quad (7)$$

where the particles are labeled $i = 1$ to $i = N$ from left to right. Thus the particles are equidistant in this regime. In this ‘solid-like’ state, the low-lying excitation involves independent oscillation of the particles around their equilibrium position.

In this regime, the distance between the leftmost and rightmost particles is at most $\sigma = 1$. Thus, this situation extends up to $F_0 = \frac{1}{2(N-1)}$. For the $N = 5$ case shown in Figure 1, this behavior is seen up to $F_0 < 1/8$.

In Figure 1, we can see this crossover from the “solid-like” limit (left) to the “hardcore gas” limit (right). In between, there is a rich staircase-like structure, as the particles attempt to minimize the interaction by being at distance > 1 from as many other particles as is compatible with the trap energy.

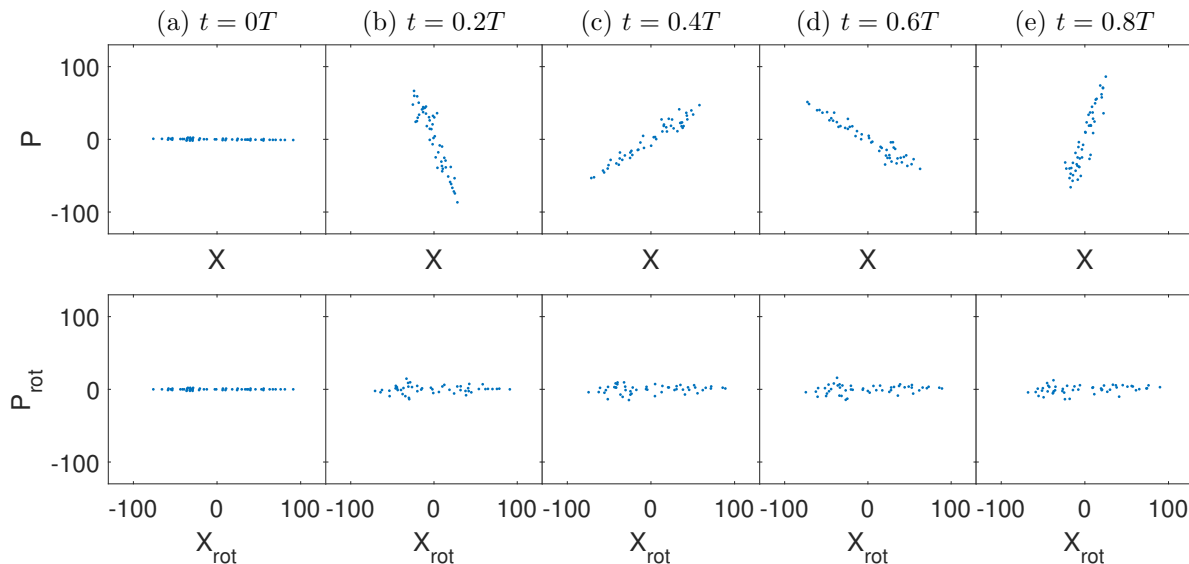


FIG. 2. Upper (lower) panels are snapshots of the cloud configuration in phase space in the stationary (rotating) frame, at instants within the first trap period. Here $N = 50$, $F_0 = 100$, and $E = 50000$.

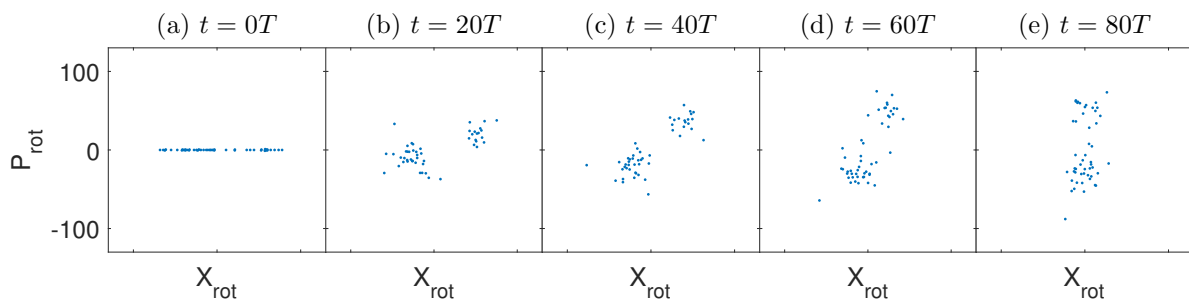


FIG. 3. Phase space snapshots of the cloud dynamics viewed in the rotating frame, at longer timescales. The broadening and rotation observed here are interaction effects: in the non-interacting gas the particles are stationary in this frame.

C. Phase space snapshots

A useful way to visualize the state and evolution of the gas is to plot the position and momentum of each particle, i.e., to plot the locations of the particles in the single-particle phase space. This will be useful for visualizing both the breathing mode and relaxation.

Figures 2 and 3 show such phase space snapshots. We generally start with particles distributed at random positions around the trap center, initially with no velocity (zero momentum). The initial state thus has the points lined up along the X axis. In the absence of interactions, each particle would undergo simple harmonic oscillation with period $T = 2\pi/\omega_0 = 2\pi$. The point corresponding to each particle executes clockwise elliptical motion around the X - P plane. (In our units, the elliptical trajectory is actually circular.) This results in the initial line remaining a straight line and rotating clockwise with exact period T . The effect of the interaction is to smear out the line and spread the points out toward a rotationally invariant distribution in the X - P plane. The top panel of Figure 2 shows this during the first period and Figure 3 shows this process over a much longer timescale.

Since the rotation of the initial line of points is simple to understand as a single-particle (non-interacting) effect, we can focus on interaction effects by viewing the phase space in a ‘rotating’ frame. The rotating frame is used in the lower panel of Figure 2 and in Figure 3. In this picture, the ‘real’ X and P axes are rotating counter-clockwise. This rotating frame picture may be regarded as a classical version of the “interaction picture” of quantum dynamics. This picture highlights effects of interactions because the other effects are already encoded in the frame rotation.

In the absence of interactions, each point (each particle) is stationary in the rotating-frame phase-space picture.

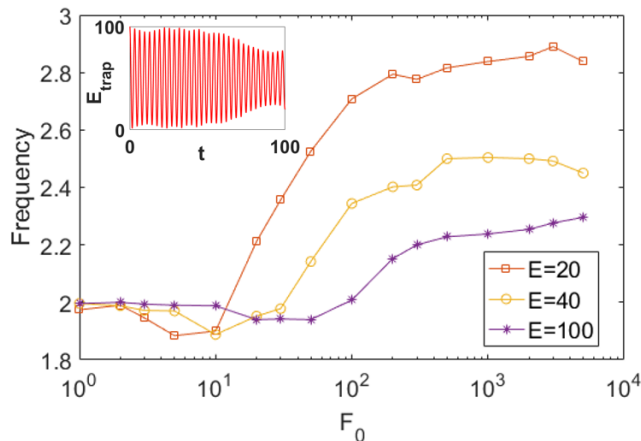


FIG. 4. Breathing mode frequency measured at different E and F_0 , for $N = 5$ particles. Inset: a demonstration of the oscillation of E_{trap} , the total potential energy of particles in the trap, Since $E_{trap} \propto \sum_{is} x_i^2$, it manifests the oscillation behavior of the radius $R(t)$ as defined in Eq. 5. The breathing frequency is obtained from the Fourier transform of $R(t)$.

As seen in lower panel of Figure 2 and in Figure 3, interactions cause a gradual distortion of the line as well as some degree of rotation. The rotation that is visible in the already rotating $X_{rot}-P_{rot}$ frame is the interaction-induced shift of the breathing frequency from the noninteracting value, $\omega_B = 2\omega_0$. The distortion of the line toward an eventually rotationally invariant distribution may be regarded as thermalization or ergodicity. In the next sections we explore these two interaction-induced effects.

D. Numerical calculations

We use the Verlet algorithm (molecular dynamics) to numerically simulate the cloud, using particle numbers between 5 and 50. Our force is simple, so that calculating the force at each step is inexpensive, however, the theta function dependence of the force on particle positions requires the use of fine timesteps at the beginning and end of each collision process.

The initial state is taken to have particles with zero velocity and random positions; hence the line distribution in the phase space picture. This has the advantage that the breathing motion is prominently visible. In addition, the question of long-time relaxation has the simple interpretation of evolving from the line distribution to a circularly symmetric distribution.

III. BREATHING FREQUENCY

We are interested in the oscillations of the size $R(t)$ of the cloud. It is convenient that our finite-size simulations start with a line distribution in phase space. If we started with a state whose configuration in phase-space deviates only slightly from circular symmetry, the oscillating amplitude would be too small to be distinguished from noise.

Without interaction, the breathing mode frequency is exactly 2. This is visualized readily from the top panel of 2, where $R(t)$ is the extent of the distribution in the horizontal (X) direction. As the line rotates clockwise with frequency $\omega_0 = 1$, within each period the line is twice horizontally aligned (maximum R) and twice vertically aligned (minimum R), so that the frequency of $R(t)$ is $\omega_B = 2$. When there is interaction, the frequency will get shifted: $\omega_B = 2 + \delta$. We measure the radius of the cloud $R(t)$ and get the frequency spectrum of its oscillation behavior by Fourier transform. Then we take the peak frequency near 2 as the breathing mode frequency.

The frequency measured in this way for different E and F_0 is shown in the Fig.4, plotted as a function of F_0 . The points each correspond to breathing-mode dynamics following from a single initial state; there is no averaging. The curves therefore show some randomness. However, two prominent features are clear from these curves. At large interactions, $F_0 \gg E$, the breathing frequency is larger than 2, and saturates around a value which decreases with the system energy E . At small interactions, the breathing frequency is actually smaller than the non-interacting value 2.

Below, we will provide a detailed phase-space argument for these behaviors. However, a simple real-space picture explains both effects qualitatively as well. For very large F_0 , when the interaction is ‘hard-core’-like, two particles exchange momentum immediately at a collision. By exchanging the labels of the particles during the collision, this

can be interpreted as follows: particle A carrying momentum P_A jumps by distance σ to the right, while particle B carries its momentum P_B and jumps by distance σ to the left. In this manner, every collision will save a particle some time, $\frac{\sigma}{v}$. This translates into an increase of the breathing frequency. The speed v per particle is on average $\sim \sqrt{E/N}$, and the number of collision each particle experiences in one period of harmonic oscillation is $\sim N$; hence we obtain $\delta \sim N^{\frac{3}{2}} E^{-\frac{1}{2}}$. When F_0 is smaller, we can no longer think of the particles as hard rods; the collisions now take finite time during which the speeds of the particles are actually slowed down and then sped up again, as they either cross paths or bounce from each other. When F_0 is small enough, this approaching time will at some critical value of F_0 consume the time saved by the finite range of the interaction. This explains why there is a small- F_0 regime for which the shift δ is negative. Figure 4 shows that this critical value of F_0 , where δ changes sign and ω_B crosses 2, increases with energy.

A. Estimates using the rotating phase space

Since we are interested in the deviation $\delta = \omega_B - 2$ from the non-interacting breathing frequency, it is useful to work in the rotating frame, in which a non-interacting cloud would be stationary (non-rotating). The rotation frequency of the cloud in this frame is then δ .

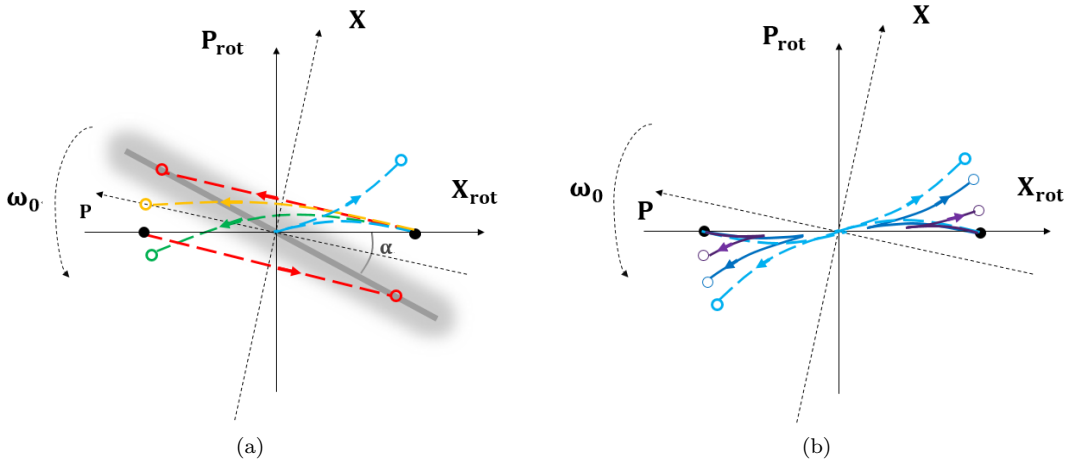


FIG. 5. Schematic diagrams of two-particle collision process in the $X_{\text{rot}}-P_{\text{rot}}$ plane. (a) When F_0 is large, particles cannot pass each other. Being subject to a constant repulsive force, their trajectories during collision are circular arcs. For very strong interactions (red dashed line, straight), they exchange momenta instantaneously. The yellow, green, and blue dashed curves are for successively weaker interactions. (b) When F_0 is small, particles pass each other, so that the force they feel is not continuous. Their trajectory has a turning point. The dashed bright blue trajectory is identical with the one in (a), which is the critical situation between passing and bouncing. In that case, particles have zero relative velocity when they collide.

To analyze the rotation relative to the $X_{\text{rot}}-P_{\text{rot}}$ frame, we consider two-particle collisions. In Figure 5(a), we show schematics of such a collision near the trap center at strong interactions. For very large F_0 , the particles simply exchange momentum when they are at distance σ from each other; this process is shown in red as two straight lines. (The particles are initially at $X = \pm \frac{1}{2}\sigma$ and remain at these X values, but exchange their momenta.) For smaller F_0 , there is change of both position and momentum, as shown in yellow, green and blue for successively weaker interactions. The blue line shows a case where F_0 is smaller enough such that the particles can actually cross each other.

In Figure 5(a) we show collisions for small F_0 , so that the particles pass each other. The force changes direction discontinuously when the particles cross. In the $X_{\text{rot}}-P_{\text{rot}}$ plane, this is seen as a sharp turning point in the trajectory.

We now estimate δ at large F_0 . The relevant collision process is that shown by the red lines in Figure 5(a). The two particles, which are initially on the X_{rot} axis, are moved to two other points, on the thick gray line, which deviates a small angle α away from original configuration. In every period of the harmonic oscillation, each particle meets each of the other particles twice. Half of these collisions (about N collisions) are between particles with large difference in momentum, which is the process shown in Fig.5. (As for the remaining half of the collisions, colliding particles have smaller difference in their momenta. In this estimate we ignore the effects of these collisions, as they clearly contribute far less to the rotation of the particle distribution.)

The precession angle is $\alpha \sim \sigma/P$. In our rescaled units, the typical momenta of interacting particles is of the order R . (In phase space R can be interpreted either as the extent in real space when the velocities are small, or as the extent in momentum space when the particles approach $x = 0$, i.e. when the distribution is along the P direction.) Thus, we can estimate $\alpha \sim \sigma/R$, i.e., $\alpha \sim 1/R$, since our unit of length is σ . This is the rotation per unit collision. Since there are $\sim N$ collisions per period $T = 2\pi$, we have the estimate for the interaction-induced rotation per unit time as

$$\delta = 2 \frac{N}{2\pi} \frac{1}{R} = \frac{1}{\pi} N^{3/2} E^{-1/2} \quad (8)$$

The factor 2 accounts for the fact that each rotation of the elongated cloud in phase space corresponds to two breathing mode periods. In the last step we have used the estimate $E \sim NR^2$.

The effect of interaction on breathing frequency is more complicated at smaller F_0 . As we have seen in Figure 4, the effect of a small F_0 is to *decrease* the breathing frequency from its non-interacting value $\omega_B = 2$. This can also be understood using phase-space pictures of collision processes. For F_0 is not very big, the finite interaction time needs to be taken into consideration. During this time, the motion of each particle in phase-space is moving exactly along the direction of the real P axis at the rate F_0/m . Since the real P axis is rotating counter-clockwise, the particle will follow a circular trajectory, e.g., following the orange or green dashed lines in Fig. 5(a). The angle α that we used above to estimate δ thus decreases with the increase of interaction time; it is smaller for the yellow line and even opposite for the green line. This explains the negative contribution of interaction to δ , for small enough values of F_0 . At even smaller values of F_0 , shown in Fig. 5(b), the particles cross each other. The resulting final values are such that the line joining the post-interaction locations of the two particles has negative α , i.e., is tilted clockwise with respect to the X_{rot} axis, meaning a negative contribution to the breathing frequency.

We can also estimate the critical value of F_0 for a given energy (or alternatively the critical value of E for a given F_0) between positive and negative contributions to the breathing frequency. Since the P axis rotates with frequency $\omega_0 = 1$ in the $X_{\text{rot}}-P_{\text{rot}}$ plane, the post-collision position of the particle in the $X_{\text{rot}}-P_{\text{rot}}$ plane makes angle $\omega_0\tau$ with the red line in Figure 5(a). Here τ is the time over which the interaction acts. The crossover between positive and negative δ is found by comparing this angle to α :

$$\omega_0\tau = \alpha \quad (9)$$

The time τ is approximately the time it takes for the momentum to change sign due to a constant force F_0 , since the momentum is $\sim R$, this means $\tau \sim R/F_0$. Using our previous estimate $\alpha \sim \sigma/R$, together with $E \sim NR^2$, gives us the condition

$$\frac{E}{N} \sim F_0 \quad (10)$$

for the breathing frequency to cross the non-interacting value $\omega_B = 2$. This is roughly the same criterion for whether two particles will bounce or cross each other in a typical collision.

The condition (10) is consistent with Figure 4, where we noted that the critical F_0 grows with increasing energy.

B. Comparisons with numerical data

In Figure 6 we show a quantitative test of the main rotating-phase-space prediction, Eq. (8). For large F_0 , the frequency indeed scales as $E^{-1/2}$ and for $F_0 = 10^5$ is quite close to the actual numerical values prediction (8). Even for smaller F_0 , at small enough energies (larger $E^{-1/2}$ values) the breathing mode becomes proportional to $E^{-1/2}$.

One might ask whether the breathing frequency predictions are also valid at late times, after the system has ‘relaxed’ from the initial line distribution in phase space to a more spread-out cloud, as we have seen in Figure 3. In 6 we show the breathing frequency calculated from $R(t)$ oscillations in the first 100 time units, and also the frequency from data in a later time window. The frequencies appear to be overall stable and dependent primarily on F_0 and E .

IV. THERMALIZATION

For any nonzero interaction, the system is expected to be ergodic for $N > 2$. Once there are many particles, one expects thermalization in the long-time limit. From the few-particle perspective, several interesting questions pose themselves. First, although we expect ergodicity, the question of how long it takes to thermalize is an open question for small N . We treat below a coarse-grained version of this question: namely, we ask whether particles show ergodic

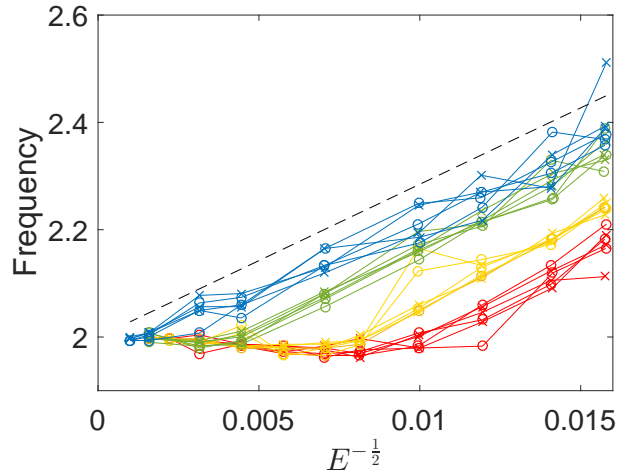


FIG. 6. Dependence of breathing frequency, calculated for $N = 20$ particles, on energy. Different colors represent different F_0 — red for $F_0 = 2 \times 10^3$, yellow for $F_0 = 3 \times 10^3$, green for $F_0 = 1 \times 10^4$, and blue for $F_0 = 1 \times 10^5$. Runs with three different initial states are shown in each case. In each run, the frequency is measured both in the time window 0-100 (labeled as crosses) and in the time window 900-1000 (labeled as circles). The black dashed line is the prediction of Eq. (8).

behavior within reasonable timescales chosen to be (somewhat arbitrarily) in the timestep range of 10^3 – 10^4 . Another question is the connection between thermalization, as defined by the appearance of a Boltzmann distribution and other intuitive characteristics of ergodic behavior such as whether the single-particle phase space is isotropically occupied. We find cases where one aspect is seen while the other is not.

In the subsections below, we first *** then ****

A. Few-particle considerations

Since we are interested in thermalization within finite timescales, it is useful to consider mechanisms which hinder relaxation or thermalization. We begin with considerations of few-particle motion. Since ergodicity and relaxation are generally expected to be more robust and efficient with larger particle numbers, consideration of small particle numbers will highlight effects which slow down relaxation.

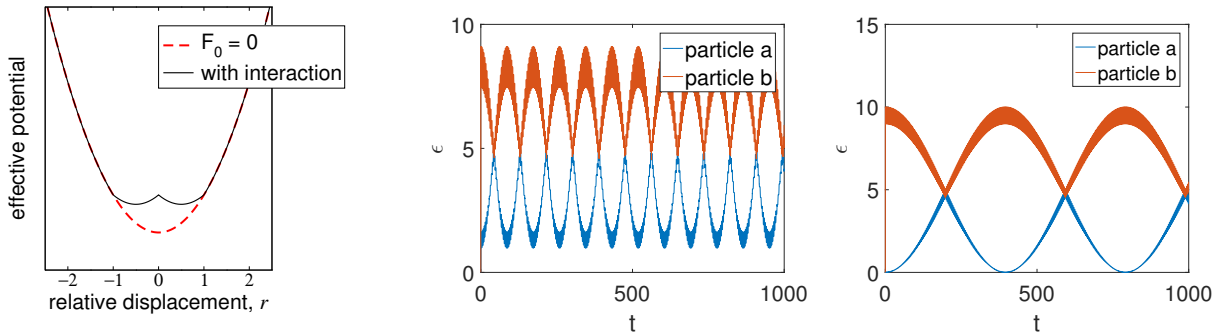


FIG. 7. Two-particle dynamics. Left: Effective potential for relative motion. Center and right: evolution of the individual energies of the two particles. The two panels correspond to internal energy $E_i = 2$ and $E_i = 5$; the interaction is $F_0 = 1$. The beat frequency is lower for larger E_i .

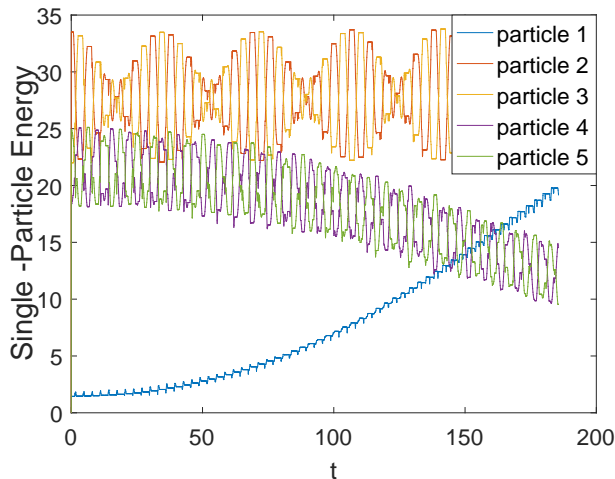


FIG. 8. Time evolution of single-particle energies in a system of five particles, showing a case of inefficient energy redistribution. The energies of the two particles with highest energy (4 & 5) show a clear beating similar to the two-particle case, as does the pair 2 & 3, although less visible. The ‘unpaired’ particle 1 performs slow beating dynamics with the center of mass of the 2 & 3 pair.

1. Two particles

We consider the two-particle motion in their center of mass frame. The center of mass itself executes simple harmonic oscillation. In the absence of interactions ($F_0 = 0$), the effective potential within the center of mass frame is itself parabolic, with the same frequency. So their relative motion is also a harmonic oscillation, with the same frequency ω_0 .

With interactions, a term $F_0(1 - |r|)\theta(1 - |r|)$ is added, where r is the relative displacement; as shown in Figure 7. Now, the relative motion is no longer harmonic. When the internal energy is much larger than F_0 , one could regard the resulting motion as having a slightly different frequency, or a collection of frequencies whose center is shifted slightly from ω_0 . Since the center-of-mass motion is still of frequency ω_0 , we have a superposition of slightly different frequencies, resulting in beating dynamics. This is clearly seen in the time evolution of individual energies shown in Figure 7. The two panels correspond to different internal energy E_i (defined as the total energy minus the center-of-mass energy). For larger E_i , the distortion of the effective potential (at constant F_0) plays a smaller role in shifting the effective frequency of relative motion; hence the beat frequency is smaller.

This illustrates a simple mechanism hindering the redistribution of energy between particles, which is necessary for thermalization or relaxation. As seen in the example dynamics shown in Figure 7, the difference in energy between the two particles is sustained over time. Of course thermalization is not expected anyway in a two-particle system, but we will see below how this basic effect continues to play a role for larger N .

2. More particles

Once we have more than two particles, we expect chaotic or ergodic behavior. However, it is easy to imagine mechanisms which drastically slow down redistribution of energy.

Generally, whenever we have some particles with energy very different from others, the dynamics occurs mostly independently within particle groups of different energies. For example, considering a situation with three particles, consider the situation where two of them, say A and B, have small internal energy, which means their mutual distance and relative velocity are both small, whereas the third particle (C) has some energy quite different from A and B. Then, A and B will often be interacting, and if their internal energy is smaller than F_0 , significant energy exchange can occur between them. C will generally exchange little energy with the pair during interactions, in which (due to larger internal energy between C and either A or B), the interaction is not effective in energy exchange. An example is shown in Figure 8, showing the dynamics of $N = 5$ particles. Two pairs of particles persist in performing ‘internal’ dynamics. The lone particle participates only in some slow beating motion with the center of mass of one of the pairs. Clearly, the energy mismatch acts as a hurdle to the relaxation process.

B. Relaxation condition and the Boltzmann distribution

Our consideration of few-particle motion has shown that relaxation is slow when the internal energy of pairs is large compared to F_0 . This allows us to conjecture a condition for relaxation in reasonable time. Although it is impossible to express the internal energy of every pair in terms of the total energy E , we can estimate the typical internal energy by the average energy, $\frac{E}{N}$. At least they are of the same order. Thus we have the condition

$$F_0 \gtrsim \frac{E}{N} \quad (11)$$

for relaxation. This is the same condition we obtained for the breathing frequency to be increased (rather than decreased) by the interaction.

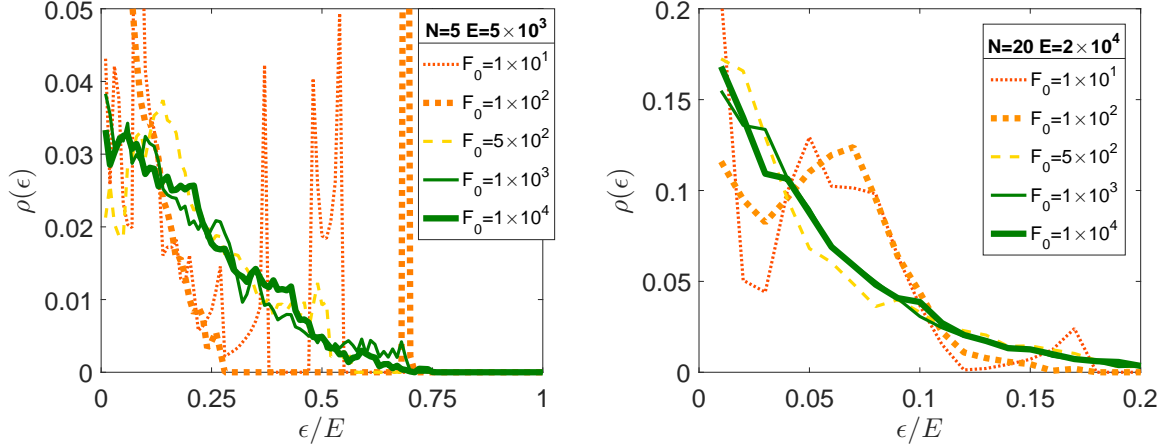


FIG. 9. The distribution of single-particle energies measured in ~ 10000 time units. Green curves obey the relaxation condition (11), and yellow/orange corresponds to smaller F_0 . In each panel (different N), we choose E/N identical ($= 1000$), so that the threshold interaction between the two behaviors is $F_0 \sim 1000$.

Because the model is expected to be ergodic for $N > 2$ particles, we expect the same condition to lead to thermalization. In fact, the proposed condition works even quantitatively, as we show in Figure 9. Here, the distribution of energies among the different particles is presented. Given our small particle number, a single snapshot of the energies will not yield enough statistics to investigate the distribution of single-particle energies. Therefore, single-particle energies are recorded at once every time unit (i.e., at time intervals of $1/\omega_0$) as the simulation evolves, up to around $t \sim 10^4$. The distribution of these observed values then shows whether or not the system has thermalized to a Boltzmann distribution. In the two panels of Figure 9, we show the distributions obtained for a $N = 5$ system and a $N = 20$ system. In both cases, we choose the total energy to be $E = 1000N$. In accordance with our conjectured condition, we find that the observed single-particle distributions are qualitatively different for $F_0 \gtrsim 10^3$ and for smaller interactions. When the “thermalization condition” $F_0 \gtrsim E/N$ is satisfied, the distribution is roughly exponential ($\sim e^{-\beta\epsilon}$). For smaller F_0 , thermalization in this sense is not seen in the single-particle energy distribution. Since the systems are expected to be ergodic, it is assumed that the smaller- F_0 systems will also eventually show a Boltzmann distribution of energy, but that this appears only at (much) longer timescales.

In several ‘thermalizing’ situations, $F_0 \gtrsim E/N$, we display the agreement with the Boltzmann distribution in Figure 10. In each panel, the calculated distributions from simulations is plotted against the Boltzmann distribution. The overall agreement shows that the energy is well-thermalized among the particles on average within the timescales under consideration.

There are some small deviations from the Boltzmann distribution visible in Figure 10. Most of the deviation is probably due to numerical noise, and unsurprising given our small system sizes. However, some deviation is also expected due to the contribution of the density of states (DOS). The probability of finding an energy is actually proportional to the Boltzmann exponential factor multiplied by the DOS. For the simple harmonic oscillator, the DOS is constant. The interaction deforms the energy shell in the small region $|x_i - x_j| < \sigma$; so that the DOS is no longer a constant. The effect of interaction is conspicuous in low energy part: when interaction is weak, particles prefer to stay near zero energy according to Boltzmann distribution, but when interaction grows, they are no longer allowed to accumulate near zero energy, in another word DOS at low energy decreases with the increase of interaction. Therefore, counts at the low energy part of Fig.10 is slightly lower than the Boltzmann prediction. The correction

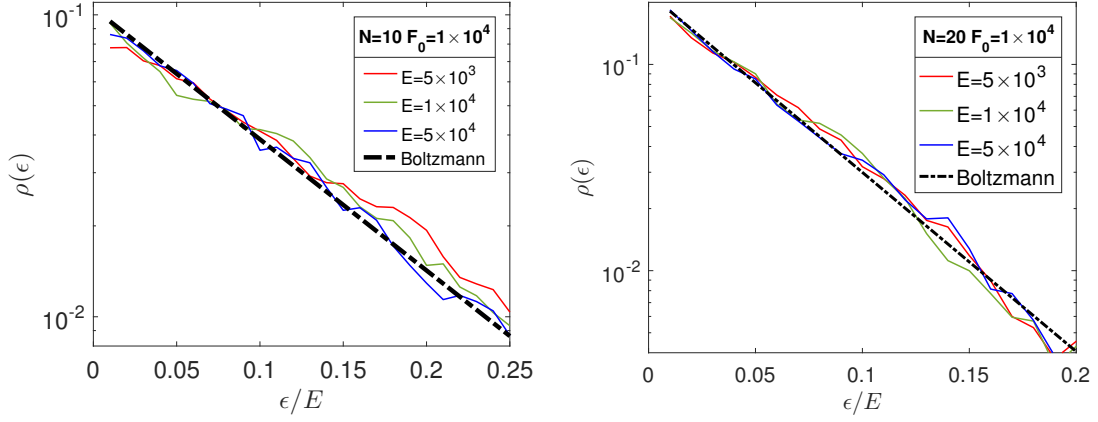


FIG. 10. Comparing the single-particle energy distribution $\rho(\epsilon)$ with the Boltzmann distribution. The energy values all satisfy the relaxation condition (11). The Boltzmann distribution $\propto e^{-\beta\epsilon}$, with the temperature defined as $\beta^{-1} = E/N$, is the thick dashed line.

to the density of states is not simple to calculate explicitly. Since we are in the regime of a dilute gas ($\sigma \ll R$), the effect is very small.

C. Lyapunov Exponents

The general idea that thermalization is faster for larger F_0 can be seen through the Lyapunov exponents. For high-dimensional systems, there is a spectrum of exponents which manifests the instability of the trajectory along each direction. The largest Lyapunov exponent (LLE) reflects the shortest time scale for the system lose memory of the initial state. We follow the method described in Ref. [1]. If the calculation is carried out upto sufficiently late times, the LLE for an ergodic system is uniquely defined and independent of the starting state. We would like to deal with parameter regimes both within and outside our relaxation condition $E < F_0 N$ and $E > F_0 N$, and in the latter case we have seen that ergodicity does not become apparent at reasonable timescales. Therefore, we carry out the computation of the LLE upto $t \sim 10^3$, which means that we can only get initial-configuration-dependent estimates. The collection of these estimates forms a distribution which we show in Figure 11.

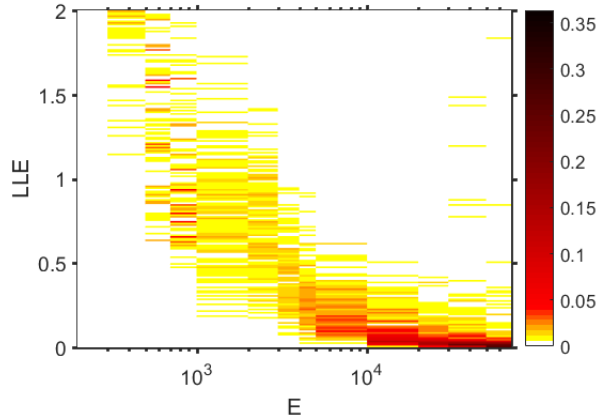


FIG. 11. The distribution of largest Lyapunov exponents, for $N = 5$, $F_0 = 1000$, at different energies. The color indicates the probability of a measured LLE value being found in a bin; the bins are of size 0.01

The LLE decreases with the growth of energy. The critical part is near $E = 5000$. The most probable value of LLE goes down from around 1 to around 0.1, which indicates that the shortest time scale becomes longer than an oscillation period when $E \gtrsim 5000$. This is consistent with our predicted thermalization threshold. As E increases far beyond the thermalization threshold value, the LLE distribution is close to zero, suggesting a divergence of relaxation time. We have thus shown a correspondence between energy thermalization and LLE.

D. Shape of distribution in single-particle phase space

We have studied thermalization in terms of energy. More generally, thermalization may be taken to mean that a many-body system loses memory of its initial state. In the single-particle phase-space picture, Figures 2 and 3, our initial state is very special: The particles are lined up along the X axis. The effect of interaction is to distort this line toward a circularly symmetric distribution. Thus, we would consider that the memory of the initial state is lost when the distribution of points in the X - P plane are not elongated in any one direction.

To quantify the shape of distribution in phase-space, we define a shape parameter S measuring the degree of ellipticity:

$$S = \frac{a - b}{a + b} \quad (12)$$

where a and b are long axis and short axis of inertia ellipse in phase space respectively. These can be calculated by diagonalizing the inertia tensor I : $I_{xx} = \sum p^2$, $I_{xp} = I_{px} = -\sum xp$, $I_{pp} = \sum x^2$. The shape parameter is $S = 1$ for line-shaped distributions and $S = 0$ for circularly symmetric distributions.

V. SHAPE OF DISTRIBUTION IN PHASE-SPACE

When describing simple harmonic motion, it is usually convenient to use the language of phase-space (of single particle). In the phase-space, the motion becomes circular, so each of these particles has two independent degrees of freedom, i.e., modulus and phase angle. Here, “independent” means that the simple harmonic oscillation never “mix” these two degrees of freedom. In view of this, when it comes to “thermalization”, one will expect that the thermalization of energy, which is just the modulus, does not ensure the thermalization of phase angle. As ins explained in the Introduction part, in order to distinguish two kinds of meanings of “thermalization”, we will call the process of energy distribution going to equilibrium “thermalization”, while the process of phase angle going to equilibrium “relaxation”. The time scale of thermalization and relaxation could be quite different in principle. We will start with the configuration where particles’ velocities are set to be zero, which means in phase-space the cloud is a rotating narrow ellipse at the beginning. If the time scale of thermalization is much longer than that of relaxation, we will see cloud going to some stable shape in a short time (a circle if interaction is not significant compared to total energy) while the distribution of particle number along radius slowly evolves to Boltzmann distribution. If the relaxation time is longer than the thermalization time, the cloud will maintain elliptical shape or some oscillation between different shapes for a long time while the energy distribution is already Boltzmann.

To quantify the shape of distribution in phase-space, we defined a shape polarization S :

$$S = \frac{a - b}{a + b} \quad (13)$$

where a and b are long axis and short axis of inertia ellipse in phase space respectively. a, b can be calculated by diagonalizing the inertia tensor I : $I_{xx} = \sum p^2$, $I_{xp} = I_{px} = -\sum xp$, $I_{pp} = \sum x^2$. $S=1$ for line-shape distribution, $S=0$ for circular distribution. The advantage of defining the S lies in that S is independent of all rotating behavior of the cloud in phase-space and thus extract the information of shape alone. One could also use eigenvalues of quadrupole moment Q to define S . Two choice of definition is equivalent, since I and Q are only different up to a factor and an identity matrix.

The time evolution of S is shown in Fig.12. The top three pannels are the overall value of S , where every data point is the average value of original data over several period (about 2π time unit). The lower six pannels are the original data measured in the beginning and after thousands of time units, which shows the finer structure in one period.

The original data can be decomposed into two components: the background value and the frequent fluctuation(sharp peaks and dips) on the background. The fluctuation is generated from the two-particle transportation process(See Fig.5), e.g. a pair transportation event along the long-axis of the cloud makes a dip. In the thermalized regime (Fig.12), the background value of S is oscillating with an amplitude of 0.2-0.4 and does not decay to zero over 4000 time unit. In the high-energy case, the amplitude of background oscillation is small compared with fluctuation. We assume that over a long enough time, all macroscopic quantity should be constant because the randomness has wash out all possible orders to make entropy as large as possible. Since we see a periodical behavior of S , we know the whole system doesn’t relax to its equilibrium state.

The oscillating background value of S indicate that the shape of the cloud in phase space is deformed periodically between a circle and an ellipse($S = 0.4$ means $\frac{a}{b} \sim 2.5$). To further reveal the nature of this oscillating mode, we

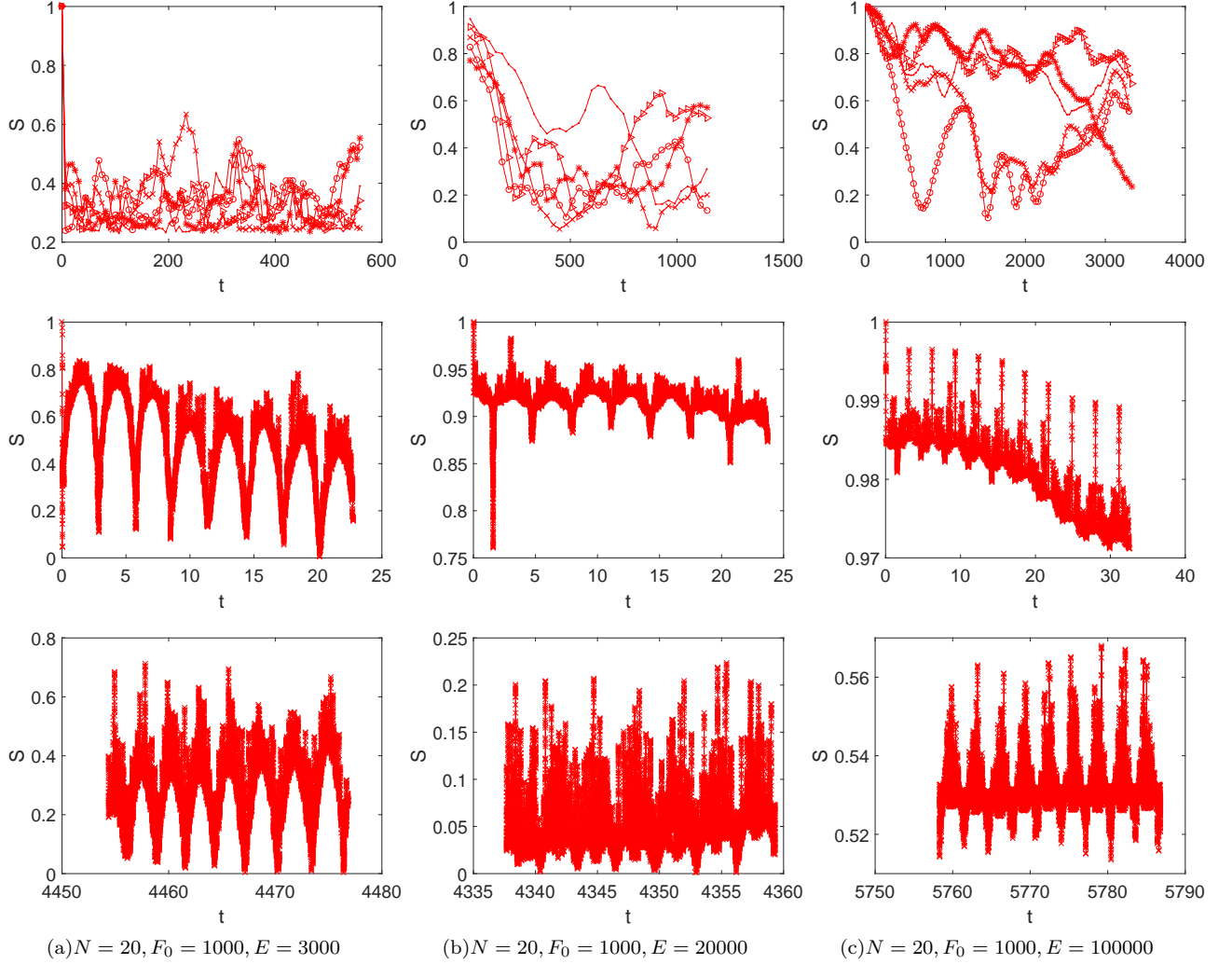


FIG. 12. Time evolution of S in low-energy regime(a), intermediate(b), high-energy regime(c). The overall value (top three panels), where every point represent the average of original data over several periods, show that S decays to a low value in a short time in low-energy case, but persist for a relative long time in high-energy case. The snapshots of original data at beginning and after thousands of periods evolution are shown in the lower six panels. The finer structure of $S(t)$ indicates that there is some long-lasting oscillating mode. Especially in low-energy case, the amplitude is more conspicuous.

focus on the low-energy case and plot the distribution of the cloud in the phase-space as Fig.13. The time interval between each panels is $0.1 * 2\pi$ time units. The direction of the yellow arrows and red arrows are the eigenvector of inertia tensor, while their lengths are the square root of correspondent eigenvalue (I take the squareroot to maintain the length unit). In most of the panels in Fig.13, the long and short axis are rotating and extending or contracting continuously. The exception is the 3rd and 4th panel in the first row, 2nd and 3rd panel in the second row, 1st and 2nd panel in the third row. At those moment, the long and short axis are almost equal, giving the system a chance to choose a new preferred axis to polarize. The whole picture of this collective mode can be described by Fig.14, which is consistent with the pattern of time evolution of S shown in Fig.15.

To sum up, the existence of the long-lasting oscillation of S indicate that the system does not relax to its equilibrium state in terms of shape although it is already thermalized in terms of energy distribution. With this long-lasting mode, the radius R of the cloud will keep oscillating, enabling the breathing mode to last for a long time.

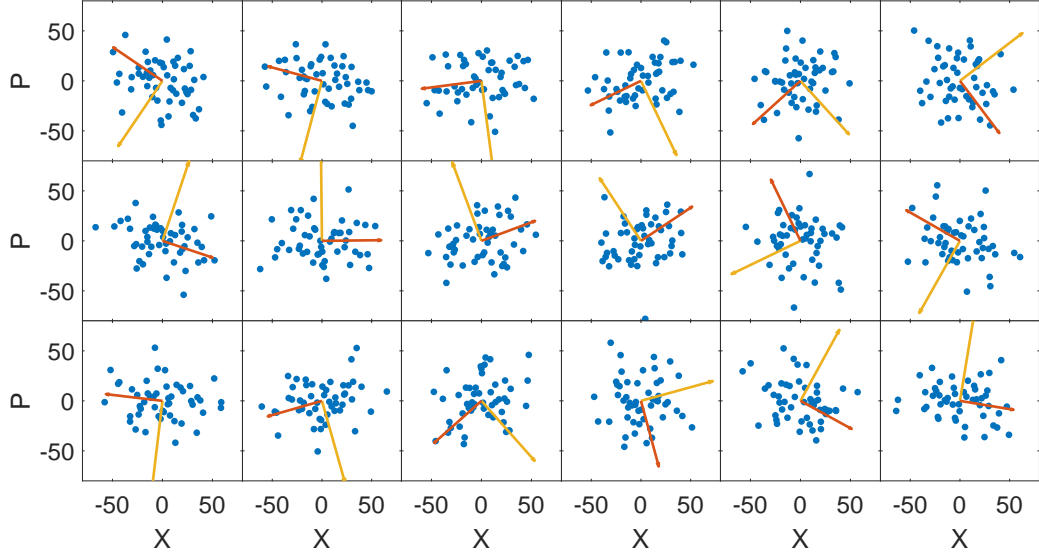


FIG. 13. Distribution in phase-space after evolving for about 500 time units ($N = 50, F_0 = 1000, E = 30000$). Please notice that the yellow(red) arrows shows the length of long(short) axis of inertia ellipse, which is perpendicular to the long(short) axis of distribution cloud. For instance, if the yellow arrow lies in p-axis, it means the long axis of distribution cloud is lying along x-axis.

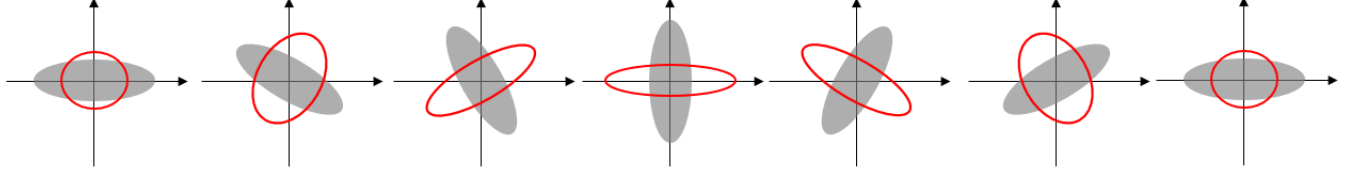


FIG. 14. Schematic description of the excited mode. Red ellipse is the shape of cloud in low-energy regime when there is repulsive interaction. Gray cloud is the imaginary shape of cloud when there is no interaction, which is plotted here as a reference. One may think of the effect of interaction as a kind of potential that prefer to place particles along x axis, because in low energy regime the system is not allowed to be squeezed too much along x axis since doing this cost a large amount of interaction energy.

VI. CONCLUSION

We studied the nonequilibrium property of one-dimensional classical gas with finite range repulsive interaction. We first studied the relation between breathing mode frequency and interaction parameter as well as total energy. We found the breathing frequency could be estimated by eq.8. And the mechanism behind this relation is that the momentum transfer which happens instantly in collision saves the particles some time from traveling this distance. So the physics is completely the same as hardcore particle. We found that the thermalization behavior is controlled by the competition between the interaction strength and the average energy. We point out that there could be two independent time scales in simple harmonic system in principle. One of them corresponds to the relaxation time of the energy distribution. The other one corresponds to the relaxation time of the angular distribution in phase space, which will determine the decay rate of the amplitude of the breathing mode. We have shown that in the low-energy regime, although the energy distribution reach Boltzmann distribution within several periods of oscillation, the shape keep oscillating for thousands of periods.

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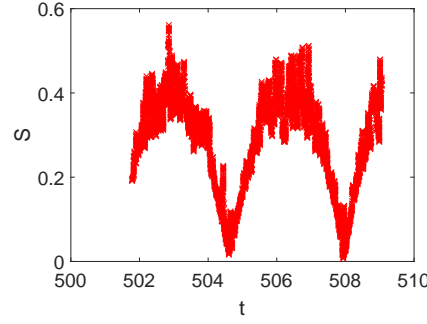


FIG. 15. Time evolution of S after evolving for about 500 time units ($N = 50, F_0 = 1000, E = 30000$). The oscillating behaviour of S persists over 500 time units.

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