Divide-and-Conquer

CS3230: Design and Analysis of Algorithms

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Chapter 4: Divide-and-Conquer

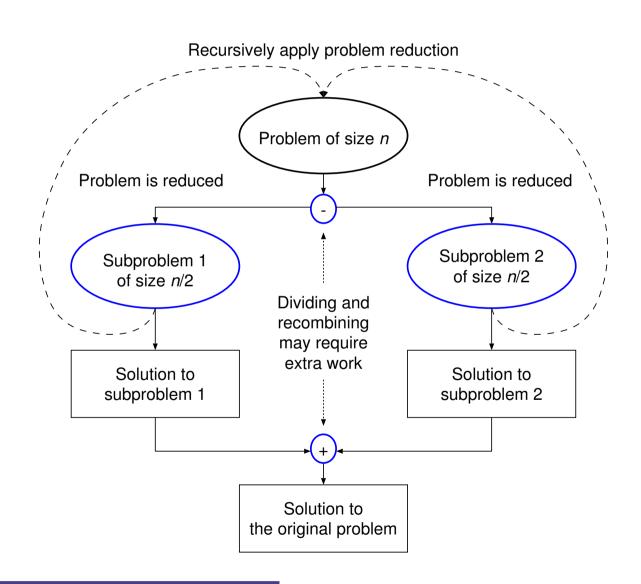
Topics: What we will cover today

- Mergesort
- Quicksort
- Binary search
- Binary tree traversals and related properties
- Large integer multiplication and Strassen's matrix multiplication
- Closest-pair problem and convex-hull problem (not discussed)

The Divide-and-Conquer Design Strategy (1)

- A problem instance is divided into smaller instances of the same problem. Preferably the smaller instances have about the same input size.
- 2. The smaller instances are solved, usually either recursively again by divide-and-conquer or directly when the input size is small enough.
- 3. If necessary, the solutions of the smaller instances are combined to become a solution for the original problem.

The Divide-and-Conquer Design Strategy (2)



Notes on the Divide-and-Conquer Design Strategy

- In many typical cases a problem's instance of size n is divided into two sub-instances of size n/2.
- The divide-and-conquer method is well suited for parallel computers.

Recurrence for Analysis of Divide-and-Conquer Alg.

- Let a problem of input size n be divided into $a \ge 1$ subproblems of size n/b, $b \ge 1$. (We may assume n is a power of b.)
 - E.g., for binary search: a = 2 and b = 2.
- Let f(n) be the cost of dividing the original problem of input size n into subproblems and for combining subsolutions into a solution.
- The recurrence is then

$$C(n) = aC\left(\frac{n}{b}\right) + f(n),$$

with some initial conditions.

Solving the Recurrence

- This recurrence can be solved by using the Master Theorem.
- Usually the function C(n) is smooth and thus the asymptotic solution obtained when n is a power of b is also valid when n is not a power of b. (See text Appendix B for technical details.)

The Master Theorem

• THEOREM Let $C(n) = aC\left(\frac{n}{b}\right) + f(n)$. If $f(n) \in \Theta(n^d)$, $d \ge 0$, then

$$C(n) = \begin{cases} \Theta(n^d), & a < b^d; \\ \Theta(n^d \log n), & a = b^d; \\ \Theta(n^{\log_b a}), & a > b^d. \end{cases}$$

- Analogous results hold for the O and Ω notations.
- Examples:
 - Ex. 1: $C(n) = 4C(n/2) + n \Longrightarrow C(n) \in ?$
 - Ex. 2: $C(n) = 4C(n/2) + n^2 \Longrightarrow C(n) \in ?$
 - Ex. 3: $C(n) = 4C(n/2) + n^3 \Longrightarrow C(n) \in ?$

Use of the Master Theorem

• Ex. 1: C(n) = 4C(n/2) + n. $a = 4, b = 2, d = 1, a > b^d, C(n) \in \Theta(n^{\log_b a}) = \Theta(n^{\log_2 4}) = \Theta(n^2).$

- Ex. 2: $C(n) = 4C(n/2) + n^2$. $a = 4, b = 2, d = 2, a = b^d, C(n) \in \Theta(n^d \log n) = \Theta(n^2 \log n).$
- Ex. 3: $C(n) = 4C(n/2) + n^3$. $a = 4, b = 2, d = 3, a < b^d, C(n) \in \Theta(n^d) = \Theta(n^3).$

Mergesort

- Mergesort sorts the array A[0..n-1] by first sorting the two subarrays A[0..k-1] and A[k..n-1], where $k=\lfloor n/2 \rfloor$.
- Note that subarray A[0..k-1] has $\lfloor \frac{n}{2} \rfloor$ elements and subarray A[k..n-1] has $\lceil \frac{n}{2} \rceil$ elements.
- The two sorted subarrays are then merged so that A[0..n-1] is sorted.

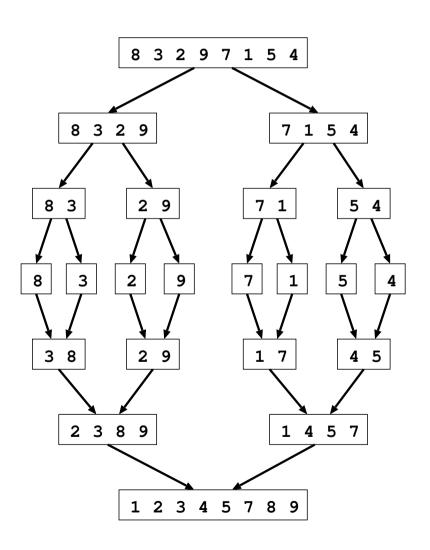
A Mergesort Algorithm

```
\begin{array}{l} \text{MERGESORT(} \ A[0..n-1] \ ) \\ \text{// Input: An array } A[0..n-1] \ \text{of orderable elements} \\ \text{// Output: Array } A[0..n-1] \ \text{sorted in nondecreasing order} \\ \text{if } n>1 \ \text{then} \\ \text{copy } A[0..\lfloor n/2\rfloor-1] \ \text{to } B[0..\lfloor n/2\rfloor-1] \\ \text{copy } A[\lfloor n/2\rfloor..n-1] \ \text{to } C[0..\lceil n/2\rceil-1] \\ \text{MERGESORT(} \ B[0..\lfloor n/2\rfloor-1] \ ) \\ \text{MERGESORT(} \ C[0..\lceil n/2\rceil-1] \ ) \\ \text{MERGE(} B, C, A \ ) \\ \text{fi} \end{array}
```

A Mergesort Algorithm: Merge

```
MERGE( B[0..p-1], C[0..q-1], A[0..p+q-1] )
   // Input: B[0..p-1], C[0..q-1] are both sorted
    i \leftarrow 0; j \leftarrow 0; k \leftarrow 0
    while i < p and j < q do
       if B[i] < C[j] then
          A[k] \leftarrow B[i]; i \leftarrow i+1
       else
          A[k] \leftarrow C[j]; j \leftarrow j+1 \text{ fi}
       k \leftarrow k + 1 od
    if i = p then
       copy C[j..q-1] to A[k..p+q-1]
    else
       copy B[i..p-1] to A[k..p+q-1] fi
```

Mergesort Example



Comparison Counts for Merging: Lemma

• LEMMA The maximum number of comparisons for merging k_1 sorted keys and k_2 sorted keys is $2k_1 - 1$ when $k_1 = k_2$, and is $2k_1$ when $k_1 < k_2$.

Comparison Counts for Merging: Proof

• PROOF When $k_1 = k_2$ and merging $a_1 \le \cdots \le a_{k_1}$ and $b_1 \le \cdots \le b_{k_1}$, the maximum comparison count occurs when

$$b_1 \le a_1 \le b_2 \le a_2 \le \dots \le b_{k_1} \le a_{k_1}.$$

• When $k_1 < k_2$ and merging $a_1 \le \cdots \le a_{k_1}$ and $b_1 \le \cdots \le b_{k_2}$, the maximum comparison count occurs when

$$b_1 \le a_1 \le b_2 \le a_2 \le \dots \le b_{k_1} \le a_{k_1} \le b_{k_1+1} \le \dots \le b_{k_2}$$
.

Analysis of Mergesort Algorithm

- We may assume that n is a power of 2. $n = k_1 + k_2$; $k_1 = k_2$.
- Let C(n) be the worst case count of key comparisons.
- The recurrence is

$$C(n) = 2C(n/2) + n - 1, \quad n > 1, \quad C(1) = 0$$

By the Master Theorem, we have

$$C(n) = \Theta(n \log n)$$

$$a = 2, b = 2, d = 1, a = b^d, C(n) \in \Theta(n^d \log n)$$

Mergesort: Summary

- Runtime, average case: $(n \log n)$
- Runtime, worst case: $(n \log n)$
- Space efficiency: O(n)
- Stability: yes

Quicksort

- Quicksort divides and conquers, but unlike mergesort that divides by array position, quicksort divides by array value.
- Quicksort partitions an array A[0..n-1] into three parts:

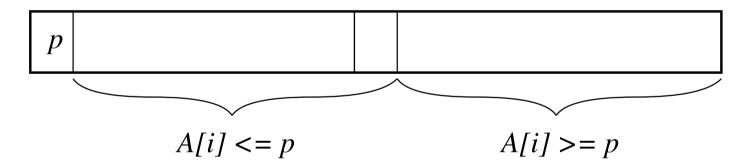
$$A[0..s - 1] \le A[s] \le A[s + 1..n - 1].$$

$$A[i..j] \leq X$$
 means $A[i], \dots, A[j] \leq X; X \leq A[i..j]$ means $X \leq A[i], \dots, A[j]$.

• That is, the partition puts the element A[s] in its rightful position, elements A[0..s-1] in their rightful positions relative to A[s], and elements A[s+1..n-1] in their rightful positions relative to A[s].

A Quicksort Algorithm

- Select a pivot (partitioning element) e.g., the first element.
- Rearrange the list so that all the elements in the first s positions are smaller than or equal to the pivot and all the elements in the remaining n-s-1 positions are larger than or equal to the pivot.



- Exchange the pivot with the last element in the first (i.e., \leq) subarray the pivot is now in its final position.
- Sort the two subarrays recursively.

A Quicksort Algorithm

```
Quicksort (A[l..r]) // Input: A subarray A[l..r] of A[0..n-1], defined by its left // and right indices l and r. // Output: Subarray A[l..r] sorted in nondecreasing order. if l < r then s \leftarrow \mathsf{Partition}(A[l..r]) // s is split position Quicksort (A[0..s-1]) Quicksort (A[s+1..r]) fi
```

A Partition Algorithm

```
Partition( A[l \dots r] )
   //A[l] is pivot
   p \leftarrow A[l]; i \leftarrow l; j \leftarrow r+1
    repeat
       repeat i \leftarrow i + 1 until A[i] \geq p
       repeat j \leftarrow j-1 until A[j] \leq p
       swap(A[i], A[j])
    until i \geq j
    swap(A[i], A[j])
                                             // undo last swap when i \geq j
    swap(A[l], A[j])
    return j
```

Quicksort Analysis: Example

For a Quicksort animation see:

http://pages.stern.nyu.edu/%7epanos/java/Quicksort/

Quicksort Analysis: Best Case

- The best case occurs when all the partitions divide their subarrays about evenly.
- Thus, the best case number of key comparisons is given by the recurrence

$$C(n) = 2C(n/2) + \Theta(n)$$

and we have $C(n) \in \Theta(n \log n)$ by the Master Theorem.

Quicksort Analysis: Worst Case

- The worst case occurs when all the partitions divide their subarrays into an empty array and an array with one fewer element than the given subarray.
- This happens when the array is already sorted.
- The worst case key comparison count is

$$C(n) = (n+1) + n + \dots + 3 = \frac{(n+1)(n+2)}{2} - 3 \in \Theta(n^2).$$

Quicksort Analysis: Average Case

- To find the average case key comparison count C(n), we assume the pivot position s is equally likely to be any among 0..n-1.
- The average case recurrence is

$$C(n) = \frac{1}{n} \sum_{s=0}^{n-1} [(n+1) + C(s) + C(n-1-s)], \quad n > 1,$$

$$C(0) = 0, C(1) = 0.$$

The Solution: $C(n) \approx 2n \ln n \approx 1.38n \log_2 n$.

Thus, only 38% more comparisons than in the best case.

Quicksort

- Improvements:
 - Better pivot selection: median of three partitioning.
 - Switch to insertion sort on small subfiles.
 - Elimination of recursion.
- These combine to 20%-25% improvement.
- Quicksort has good average case performance, but worst case is $\Theta(n^2)$. How can we avoid the worst case (i.e., an already sorted array)?

Quicksort: Summary

- Runtime, average case: $(n \log n)$
- Runtime, worst case: (n^2)
- Space efficiency: naive O(n); $O(\log n)$
- Stability: no

Binary Search

- Binary search is very efficient for searching a given key among an array of sorted keys.
- It divides and conquers but is degenerate because it needs to solve only one subproblem and thus need not combine subsolutions.
- It can be implemented iteratively instead of recursively.

A Binary Search Algorithm

```
BINARYSEARCH
   // Input: a sorted array A[0 \dots n-1], a key K
   l \leftarrow 0; r \leftarrow n-1
   while l < r do
       m \leftarrow \lfloor (l+r)/2 \rfloor
       if K = A[m] then return m
       elsif K < A[m] then r \leftarrow m-1
       else l \leftarrow m+1
   od
   return -1
```

Binary Search Example

Index	0	1	2	3	4	5	6	7	8	9	10	11	12
Value	3	14	27	31	39	42	55	70	74	81	85	93	98
Iteration 1	l						m						r
Iteration 2								l		m			r
Iteration 3								l,m	r				

An Analysis of the Binary Search Algorithm

• The size of the larger of the subarrays A[0..m-1] and A[m+1..n-1], $m=\lfloor (n-1)/2 \rfloor$, is

$$\left\lfloor \frac{n}{2} \right\rfloor$$
.

- To simplify we assume three-way comparisons; that is, with only one comparison we know if it is A[m] < K, A[m] = K or A[m] > K.
- The recurrence for the worst case 3-way key count is

$$C(n) = C(\lfloor n/2 \rfloor) + 1, \quad n > 1; \quad C(1) = 1.$$

The Solution

The solution of the preceding recurrence is

$$C(n) = \lfloor \log_2 n \rfloor + 1, \quad n \ge 1.$$

- This is very fast, e.g., $C(10^6) = 20$.
- Note: Initially assume $n=2^k$, but then generalize.
- The claim can be proved by strong mathematical induction and the fact that for any positive integer n there is an integer l such that

$$2^{l} \le n \le 2^{l+1} - 1.$$

Binary Tree Traversals and Related Properties

- Recall that a binary tree is a rooted tree such that every vertex has either no children or a left child or a right child or both.
- A binary tree can also be defined recursively as being either an empty tree having a left binary subtree and a right binary subtree.
- Thus a binary tree has three parts: root, left binary subtree, right binary subtree.
- This natural partition of a binary tree makes it inherently amenable to divide and conquer algorithms.

Full Binary Trees

- A binary tree is full if every vertex has either no children or two children.
- Let i and l be the numbers of internal vertices and leaves, respectively.
- In a full binary tree, every vertex except the root shares a parent with another vertex, thus

$$\frac{i+l-1}{2} = i.$$

That is,

$$l = i + 1$$
.

This is a very useful property of full binary trees.

Finding the Height of a Binary Tree by Div-and-Conq

```
HEIGHT( T )

// Input: A binary tree T

if

T=\varnothing then return -1

else

return(max( HEIGHT(T_L), HEIGHT(T_R) ) +1)

fi
```

Number of Empty Tree Checkings

- Let C(n) be the number of times for checking if a binary tree is empty.
- We may represent an empty binary tree as a NULL vertex.
- By attaching these NULL vertices, a binary tree becomes a full binary tree whose leaves are NULL vertices.
- Since the algorithm visits every subtree root regardless if the subtree is empty, we have

$$C(n) = n + x = n + (n + 1) = 2n + 1$$

where x is the number of NULL vertices attached.

Number of Additions

- Let N(T) be the number of vertices of a binary tree T.
- The recurrence for the addition count A(n) of the algorithm is

$$A(N(T)) = A(N(T_L)) + A(N(T_R)) + 1;$$
 $A(0) = 0.$

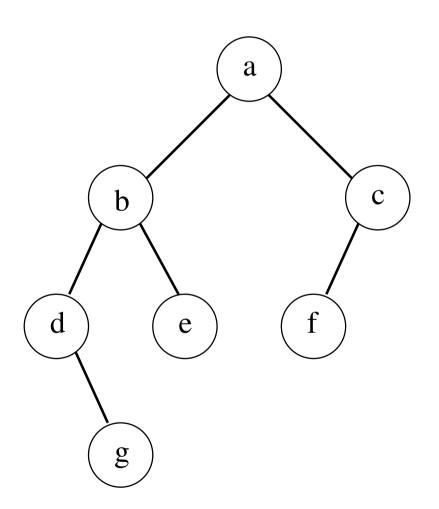
 By observation that there is one addition for each vertex in the binary tree, we immediately have

$$A(n) = n$$
.

Preorder, Inorder, Postorder Traversal

```
Preorder (T)
   if T \neq \emptyset then
      print T; PREORDER(T_L); PREORDER(T_R) fi
end
INORDER(T)
   if T \neq \emptyset then
      INORDER(T_L); print T; INORDER(T_R) fi
end
Postorder (T)
   if T \neq \emptyset then
      POSTORDER(T_L); POSTORDER(T_R); print T fi
end
```

Traversal Example



Preorder: a, b, d, g, e, c, f

Inorder: d, g, b, e, a, f, c

Postorder: g, d, e, b, f, c, a

Multiplication of Large Integers

- To multiply two n-digit numbers, n^2 digit multiplications are needed.
- Using divide and conquer, the number of digit multiplications can be reduced to $n^{1.585}$.
- For simplicity we assume n is a power of 2.
- Example:
 - Multiply 2 two-digit numbers, 23 and 14.
 - Representation: $23 = 2 \cdot 10^1 + 3 \cdot 10^0$ and $14 = 1 \cdot 10^1 + 4 \cdot 10^0$.
 - Multiplication: $23 \times 14 = (2 \cdot 10^1 + 3 \cdot 10^0) \times (1 \cdot 10^1 + 4 \cdot 10^0)$ = $(2 \times 1)10^2 + (2 \times 4 + 3 \times 1)10^1 + (3 \times 4)10^0$.
 - Note: $2 \times 4 + 3 \times 1 = (2+3) \times (1+4) 2 \times 1 3 \times 4$.

An Algorithm for the Multiplication of Large Integers

• An n-digit number x can be written as two $\frac{n}{2}$ numbers x_1 and x_0 as follows:

$$x = x_1 \times 10^{\frac{n}{2}} + x_0.$$

To find the product c of two n-digit numbers a and b we compute

$$c = a \times b = (a_1 \times 10^{\frac{n}{2}} + a_0) \times (b_1 \times 10^{\frac{n}{2}} + b_0) = c_2 \times 10^n + c_1 \times 10^{\frac{n}{2}} + c_0$$

where
$$c_2 = a_1b_1$$
, $c_0 = a_0b_0$, and $c_1 = (a_1 + a_0)(b_1 + b_0) - c_2 - c_0$.

• Note: For n=2 we reduced the number of multiplications from 4 to 3. However, we increased the number of additions!

A Remark

- The sum of two $\frac{n}{2}$ -digit numbers $x_0 + x_1$ either remains a $\frac{n}{2}$ -digit number or becomes a $\left(\frac{n}{2} + 1\right)$ -digit number with a leading digit 1.
- Thus we may write $x_1 + x_0 \times 10^{n/2} + x_2$ where x_3 is either 0 or 1 and x_2 is a $\frac{n}{2}$ -digit number.
- The product $(x_3 \times 10^{n/2} + x_2)(y_3 \times 10^{n/2} + y_2) = x_3y_3 \times 10^n + (x_2y_3 + x_3y_2) \times 10^{n/2} + x_2y_2$.
- The product x_3y_3 and the sum $x_2y_3 + x_3y_2$ are trivial to compute because x_3, y_3 are either 0 or 1.

A Remark

• Consequently, the cost of multiplying two potentially $\left(\frac{n}{2}+1\right)$ -digit numbers with 1 as the leading digit is the same as that of multiplying two $\frac{n}{2}$ -digit numbers.

Analysis of the Integer Multiplication Algorithm

- Let M(n) be the number of digit multiplications to multiply two n-digit numbers by the algorithm.
- Clearly the recurrence is

$$M(n) = 3M(n/2), \quad n > 1; \quad M(1) = 1.$$

Backward substitution yields

$$M(2^k) = 3M(2^{k-1}) = 3[3M(2^{k-2})] =$$

 $3^2M(2^{k-2}) = \dots = 3^iM(2^{k-i}) = \dots = 3^kM(2^{k-k}) = 3^k.$

• If $n=2^k$, then

$$M(n) = 3^k = 3^{\log_2 n} = n^{\log_2 3} \approx n^{1.585}.$$

Strassen's Matrix Multiplication

• The product C = AB of two order n square matrices A and B can be found with n^3 scalar multiplications:

for
$$i\leftarrow 1$$
 to n do for $j\leftarrow 1$ to n do $C[i,j]=0$ for $k\leftarrow 1$ to n do
$$C[i,j]+=A[i,k]\times B[k,j]$$
 od od od

· Clearly,

$$\sum_{i=1}^{n} \sum_{j=1}^{n} \sum_{k=1}^{n} 1 = n^{3}.$$

• Using divide and conquer, Strassen's algorithm improves the scalar multiplication cost to be in $\Theta(n^{\log_2 7}) = \Theta(n^{2.807})$.

Partition a Matrix into Submatrices

• An order n = 2m matrix X can be partitioned into four order m submatrices X_{00}, X_{01}, X_{10} , and X_{11} :

$$X = \left[\begin{array}{cc} X_{00} & X_{01} \\ X_{10} & X_{11} \end{array} \right].$$

Partition a Matrix into Submatrices

- The product C = AB of two order n = 2m matrices A, B can be found with seven order m submatrix multiplications.
- Let

$$M_{1} = (A_{00} + A_{11}) \times (B_{00} + B_{11}),$$

$$M_{2} = (A_{10} + A_{11}) \times B_{00},$$

$$M_{3} = A_{00} \times (B_{01} - B_{11}),$$

$$M_{4} = A_{11} \times (B_{10} - B_{00}),$$

$$M_{5} = (A_{00} + A_{01}) \times B_{11},$$

$$M_{6} = (A_{10} - A_{00}) \times (B_{00} + B_{01}),$$

$$M_{7} = (A_{01} - A_{11}) \times (B_{10} + B_{11}).$$

Partition a Matrix into Submatrices

It can be verified that:

$$C = \begin{bmatrix} M_1 + M_4 - M_5 + M_7 & M_3 + M_5 \\ M_2 + M_4 & M_1 + M_3 - M_2 + M_6 \end{bmatrix}.$$

Strassen's Matrix Multiplication Algorithm

• Strassen's algorithm simply employs the above method recursively whenever a matrix multiplication is needed.

Number of Scalar Multiplications of Strassen's Alg.

• The recurrence for M(n), the number of scalar multiplications to multiply two order n matrices, is

$$M(n) = 7M\left(\frac{n}{2}\right), \quad M(1) = 1.$$

• If $n = 2^k$ (i.e., $k = \log_2 n$), then

$$M(n) = M(2^k) = 7M(2^{k-1}) = \dots = 7^k = 7^{\log_2 n} = n^{\log_2 7} = n^{2.807}.$$

Number of Scalar Additions of Strassen's Alg.

• The recurrence for A(n), the number of scalar additions/subtractions to multiply two order n matrices, is

$$A(n) = 7A\left(\frac{n}{2}\right) + 18\left(\frac{n}{2}\right)^2, \quad A(1) = 0.$$

By the Master Theorem,

$$A(n) \in \Theta(n^{\log_2 7}).$$

• Thus the counts M(n) and A(n) have the same order of growth, and both are better than the brute force algorithm.

The Closest Pair Problem

• Recall that given n points $P_1 = (x_1, y_1), \dots, P_n = (x_n, y_n)$, a closest pair can be identified by finding the minimum of $\binom{n}{2}$ square distances:

$$\min_{1 \le i < j \le n} (x_i - x_j)^2 + (y_i - y_j)^2.$$

- This brute force approach is a $\Theta(n^2)$ algorithm.
- With divide and conquer, we can formulate a $\Theta(n \log n)$ algorithm.

A Divide and Conquer Closest Pair Algorithm: Idea

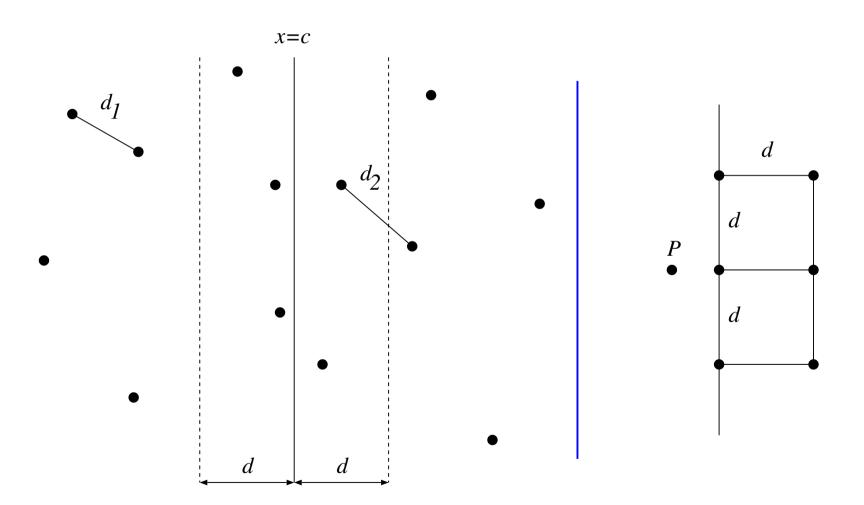
- For simplicity we may assume the number of points n is a power of 2.
- Sort the n points by their x coordinates.
- Divide the n points into two $m = \frac{n}{2}$ element sets

$$C_1 = \{P_i : 1 \le i \le m\}$$
 and $C_2 = \{P_i : m+1 \le i \le n\}.$

The two groups are separated by the vertical line

$$x = \frac{x_m + x_{m+1}}{2} = V.$$

Closest Pair Explanation



A Divide and Conquer Closest Pair Algorithm: Idea

- Find the distance d_i of a closest pair in C_i for i = 1, 2.
- We may assume the algorithm that finds a closest pair in C_i has sorted the points in C_i by their y coordinates.
- Let $d = \min(d_1, d_2)$.
- Merge the points in C_1 and C_2 by their y coordinates so that the points are now sorted by y coordinates.
- Let

$$S = \{ P_i : V - d \le x_i \le V + d \}.$$

• Clearly, only two points in $S \cap (C_1 \cup C_2)$ can possibly be closer than d.

A Divide and Conquer Closest Pair Algorithm: Idea

• For each $P_i \in S$, the set

$$V_i = \{P_j : y_i \le y_j, d(P_i, P_j) \le d, P_i \ne P_j\}$$

contains at most six points.

- By scanning the list S, sorted by the y coordinate, from bottom to top, each time we need to check the next five points to see if there is a pair closer than d.
- Pick any of those pairs that have the smallest distance in the preceding step.

Analysis of the Divide and Conquer Closest Pair Alg.

- The main work of the algorithm is really the combination of subsolutions into a solution.
- Let this work be M(n) which is in O(n).
- The recurrence is thus

$$C(n) = 2C(n/2) + M(n).$$

Analysis of the Divide and Conquer Closest Pair Alg.

By the Master Theorem we have

$$C(n) = O(n \log n).$$

• Since the sorting by x coordinates takes $\Theta(n \log n)$, so the time efficiency of the divide and conquer algorithm is $\Theta(n \log n)$.

Take Away Message on Divide-and-Conquer

- The divide-and-conquer strategy is very general and solves a problem by dividing a problem's instance into several smaller, non-overlapping instances, solving each of them recursively, and then combining their solutions to get a solution to the original instance of the problem.
- The runtime T(n) of many divide-and-conquer algorithms satisfies the recurrence T(n) = aT(n/b) + f(n). The Master Theorem establishes the order of growth of its solutions.