

Zhongyang Ren

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EDUCATION

Northwestern Polytechnical University
Ph.D, Neuromorphic Vision

Supervisor: Prof. Yuchao Dai
Sep. 2025 – Present

Hunan University
Master, Neuromorphic Vision

Supervisor: Prof. Yi Zhou
Sep. 2022 – Jun. 2025

Shandong Normal University
Bachelor, Computer Science and Technology

Sep. 2018 – Jun. 2022

Research interests: 3D Vision, Event Camera, Robotics.

PUBLICATIONS

* denotes equal contribution, # denotes corresponding author

Zhongyang Ren*, Bangyan Liao*, Delei Kong, Jinghang Li, Peidong Liu, Laurent Kneip, Guillermo Gallego, Yi Zhou#. **Motion and Structure from Event-based Normal Flow**. In Proceedings of the European Conference on Computer Vision (ECCV 2024).

Sheng Zhong*, **Zhongyang Ren***, Xiya Zhu, Dehao Yuan, Fermüller Cornelia, Yi Zhou#. **Real-Time Motion Segmentation with Event-based Normal Flow**. IEEE International Conference on Robotics and Automation (ICRA 2026)

Yuting He*, Bin Fan*, **Zhongyang Ren**, Qi Liu, Yuchao Dai#. **Learning Spatio-Temporal Dynamic Event Voxels for Robust Event-based Object Tracking**. (Under Review)

EXPERIENCE

Research on Event-based Motion Segmentation
Project Leader

Nov. 2024 – Aug. 2025
Advised by Prof. Yi Zhou and Cornelia Fermüller

Teaching Assistant
RO10005: Advanced Practice in Robotics Engineering

Sep. 2024 – Dec. 2024
Assist Prof. Yi Zhou

Research on Geometric Model Fitting on Event Data
Project Leader

Mar. 2023 – Jul. 2024
Advised by Prof. Yi Zhou and Guillermo Gallego

Research on Hyperspectral Image Super-Resolution
Undergraduate Thesis

Dec. 2021 – May 2022

AWARDS

- Excellent Student Scholarship(First Class), Hunan University
- National Second Prize in National Undergraduate Mathematical Contest in Modeling
- Provincial First Prize in Lanqiao Cup Programming Contest
- Excellent Student, Shandong Normal University

SERVICES

Reviewer of ECCV, CVPR and IEEE RA-L

Volunteer of IROS 2025 at Hangzhou

TECHNICAL SKILLS

Programming Languages: MATLAB, C++, Python, Java

Libraries & Tools: PyTorch, NumPy, OpenCV, Git, Docker, ROS, L^AT_EX