Homework 3: Planning Report

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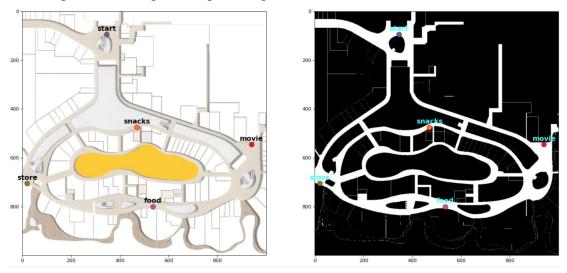
Task 1: Task 1: Global Planning

Task 1.1:

The aim of this task is to write an SVD-based ICP algorithm to calculate

For both Task 1&2 of your planning homework, you will be using a map of the VivoCity level 2, as shown. The left picture is the original floor plan, while the right one is a grayscale version to be used by your planning algorithms. The whole map has a size of 1000 x 1000 pixels (grid cells), with each cell representing a 0.2m x 0.2m square area. Each grid cell belongs to one of two possible states: Free (value `255`) or Occupied (value `0`). You yourself, as a human, are expected to have a circular footprint of no less than0.3m radius. There are five given key locations on the map you wish to visit: `start`, `snacks`, `store`, `movie`, and `food`. Your mission is to plan a path/trajectory between each pair of a start and end points, display your plan on the map and count the total travel distance of your plan in meters. Finally, use the distances you calculated, find the most efficient route for yourself, that is currently standing at the level 2 escalator (the start), to visit all the four locations and return to the start.

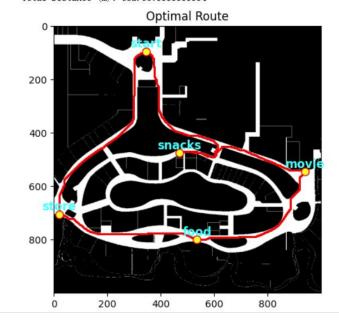




Step 2:A* algorithm

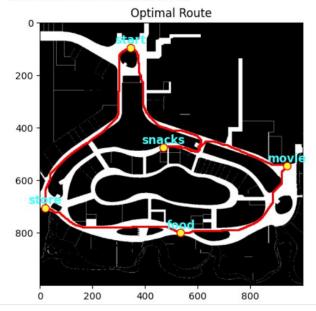
Result:

```
Total runtime (s): 3.6700079441070557
Distance Table:
from/to start snacks store
                                 movie
                                          food
start 0
                143. 75 155. 61 179. 15 225. 40
snacks 143.75 0
                         115. 44 108. 35 135. 02
store 155.61 115.44 0
                                 210.14
                                         111.12
movie
        179. 15 108. 35 210. 14 0
                                          113.83
        225. 40 135. 02 111. 12 113. 83 0
food
Optimal Route: start \rightarrow store \rightarrow food \rightarrow movie \rightarrow snacks \rightarrow start
Total Distance (m): 632.657999999994
```



Step 3:Degenerate the A* algorithm to Dijkstra's Algorithm Result:

```
Total runtime (s): 3.6700079441070557
Distance Table:
from/to start snacks store
                              movie
                                      food
start 0
               143. 75 155. 61 179. 15
                                     225.40
snacks 143.75 0
                      115. 44 108. 35
                                     135.02
store 155.61 115.44 0
                              210. 14 111. 12
movie
       179. 15 108. 35 210. 14 0
                                      113.83
       225.40 135.02 111.12 113.83 0
food
Optimal Route: start -> store -> food -> movie -> snacks -> start
Total Distance (m): 632.6579999999994
```



Step 4: Comparison

From the results we can see, A*algorithm is way faster than Dijkstra algorithm. Summarize the shortest distances between each pair of locations in a table:

Distance Table produced by A*

From\to	start	snacks	store	movie	food
1 TOTTI (to	Start	Silacks	Store	movie	1000
start	0	144.23	155.97	179.38	226.11
snacks	144.23	0	115.68	105.58	135.73
store	155.97	115.68	0	210.26	111.12
	1=0.00	400.50	210.26		112.05
movie	179.38	108.58	210.26	0	113.95
C 1	226 11	125.72	111 12	112.05	
food	226.11	135.73	111.12	113.95	0

Task 2:The "Travelling Shopper" Problem

You are now at the VivoCity level 2 escalator (the start), and you wish to visit all the four locations andthen return to the escalator. Based on the distance table you obtained in Task 1, find the optimal route for you to visit all stores and come back to the start location.

For Greedy method:

Runtime (s): 6.527727127075195e-05

Optimal Route: start \rightarrow store \rightarrow food \rightarrow movie \rightarrow snacks \rightarrow start

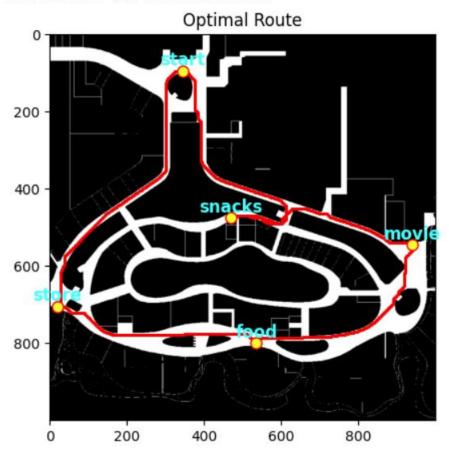
Total Distance (m): 632.66

For Traversal method:

Runtime (s): 4.416203498840332e-06

Optimal Route: start -> snacks -> movie -> food -> store -> start

Total Distance (m): 632.6600000000001



The final shortest route and the total distance are shown on the map.

Appendices:

The code and file can be found here: https://github.com/Zhou-Tianli/ME5413_Homework3_planning