Private location verification with incentivization

in-progress

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Abstract

We design an interactive proof system for "location is close enough" statement, in the form of specification for further implementation.

1 Definitions

Node proves the statement "distance is within a threshold" (less or equal) for node coordinates (x_n, y_n, z_n) , given location (x_l, y_l, z_l) , and some threshold d (all integers):

$$d^{2} - ((x_{n} - x_{l})^{2} + (y_{n} - y_{l})^{2} + (z_{n} - z_{l})^{2}) = a_{1}^{2} + a_{2}^{2} + a_{3}^{2} + a_{4}^{2}$$
 (1)

We rely on 4-squares Lagrange theorem to prove equality statement (Lipmaa). Proofs for integer relations are possible in hidden group order setup (Camenisch-Stadler).

2 Proof setup

Let g be a generator of a proper group of a hidden order, and h be a group element (Pedersen commitment scheme). We use multiplicative group of invertible residue classes modulo a composite n such that n = pq, p = 2p' + 1, q = 2q' + 1 and p, q, p', q' primes (Idemix).

3 Signals harvesting

Node picks random (r_x, r_y, r_z) , creates commitment (s_x, s_y, s_z) to it's coordinates

$$s_x = g^{x_n} h^{r_x}, \qquad s_y = g^{y_n} h^{r_y}, \qquad s_z = g^{z_n} h^{r_z}$$
 (2)

and keeps coordinates-randoms pairs $(x_n, y_n, z_n), (r_x, r_y, r_z)$ private.

4 Proof

Sigma-protocol with 3 messages. Public information is node location commitment, given location, threshold, proof parameters. Private information is node location and randomness to commitment.

1. Prover (node) picks random $\alpha_j, \beta_x, \beta_y, \beta_z, \rho_0, \rho_1, \eta_x, \eta_y, \eta_z$ and computes initial commitments b_0, b_1, t_x, t_y, t_z (f_0 and f_1 explained at Background section)

$$b_0 = g^{f_0} h^{\rho_0}, \qquad b_1 = g^{f_1} h^{\rho_1}$$
 (3)

$$t_x = g^{\beta_x} h^{\eta_x}, \qquad t_y = g^{\beta_y} h^{\eta_y}, \qquad t_z = g^{\beta_z} h^{\eta_z}$$
 (4)

- 2. Challenge c
- 3. Prover computes responses

$$X_n = cx_n + \beta_x, \quad Y_n = cy_n + \beta_y, \quad Z_n = cz_n + \beta_z$$
 (5)

$$R_x = cr_x + \eta_x, \quad R_y = cr_y + \eta_y, \quad R_z = cr_z + \eta_z$$
 (6)

$$A_j = ca_j + \alpha_j, \ j = 1..4 \tag{7}$$

$$R_a = c\rho_1 + \rho_0 \tag{8}$$

4. Proof verification

$$g^{c^2d - ((X_n - cx_l)^2 + (Y_n - cy_l)^2 + (Z_n - cz_l)^2) - (A_1^2 + A_2^2 + A_3^2 + A_4^2)}h^{R_a} = b_1^c b_0$$
(9)

$$g^{X_n}h^{R_x}s_x^{-c}=t_x, \quad g^{Y_n}h^{R_y}s_y^{-c}=t_y, \quad g^{Z_n}h^{R_z}s_z^{-c}=t_z \quad \ (10)$$

5 Background

Consider quadratic (degree 2 in v) polynomial

$$f_V(v) = f_2 v^2 + f_1 v + f_0 =$$

$$v^2 d - (((vx_n + \beta_x) - vx_l)^2 + ((vy_n + \beta_y) - vy_l)^2 + ((vz_n + \beta_z) - vz_l)^2)$$

$$- ((va_1 + \alpha_1)^2 + (va_2 + \alpha_2)^2 + (va_3 + \alpha_3)^2 + (va_4 + \alpha_4)^2)$$
(11)

This polynomial is actually linear ($f_2 = 0$, degree-one in v) if, and only if statement about distance (1) holds for node coordinates that are hidden from verifier. We evaluate this polynomial at a random point chosen as the challenge of verifier. It follows, distance verification equation (9) only needs constant b_0 and degree-one b_1^c components.

$$f_0 = -\beta_x^2 - \beta_y^2 - \beta_z^2 - \alpha_1^2 - \alpha_2^2 - \alpha_3^2 - \alpha_4^2$$
 (12)

$$f_1 = -2(x_n - x_l)\beta_x - 2(y_n - y_l)\beta_y - 2(z_n - z_l)\beta_z - 2a_1\alpha_1 - 2a_2\alpha_2 - 2a_3\alpha_3 - 2a_4\alpha_4$$
(13)

Prover calculates b_0, b_1 from f_0, f_1 .

6 Todo

Add awarding (payment) part to the proof system. Specify ranges for random numbers. Introduce accumulator for a set of time-locations. Design enforcement for "just one single location at a time". Add references (bibliography).