## Generating self-supervised training data **Template-Aware Dynamic Convolution Module (TDCM)** convNext-V2 Stage-1 **Dynamic** $F_i: \mathbb{C} \times \frac{H}{A} \times \frac{W}{A}$ **Depthwise** Convolution CAHAW convNext-V2 Stage-1 as dynamic conv kernels $C \times \frac{H}{4} \times \frac{W}{4}$ $h \times w H_t \times W_t$ $F_t: \mathbb{C} \times \frac{H_t}{A} \times \frac{W_t}{A}$ classification\_ $\mathcal{L}_{\underline{center}}$ Pixel Shuffling Conv1Conv2 Shuffling $\mathbf{C} \times \frac{H}{4} \times \frac{W}{4}$ $\mathbf{C} \times \frac{H}{4} \times \frac{W}{4}$ $\frac{C}{4} \times \frac{H}{2} \times \frac{W}{2}$ $\frac{C}{2} \times \frac{H}{2} \times \frac{W}{2}$ $\frac{C}{8} \times H \times W$ $\frac{C}{4} \times H \times W$ regression Conv1 BN1 Conv2 ReLU Ф\*--Ф← Refine $\mathcal{L}_{\mathrm{sign}(\boldsymbol{\theta})}^{\boldsymbol{CE}}$ $\frac{C}{16} \times H \times W$ $\frac{C}{4} \times H \times W$ $\frac{C}{\Omega} \times H \times W$ $\mathcal{L}_{geom}$ BN2 Sigmoid Conv3 ReLU regression $1 \times H \times W$ $1 \times H \times W$ $\Phi^*: (x_c^*, y_c^*, s_x^*, s_y^*, \theta^*)$ sx sy cos $\theta$ sign $(\theta)$ $\Phi$ : $(x_c, y_c, s_x, s_y, \theta)$ Center localization & geometry regression