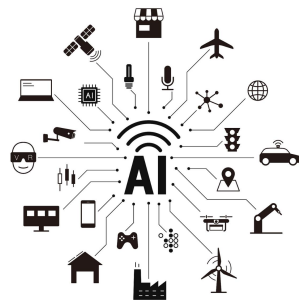
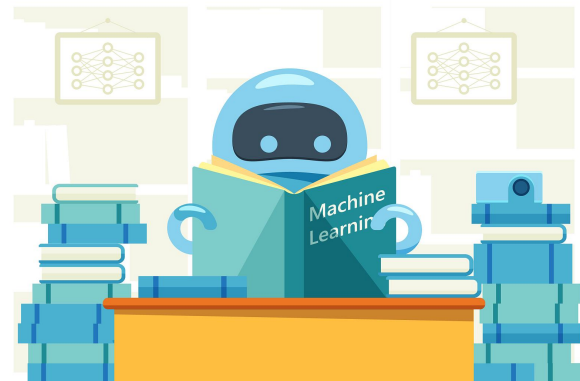
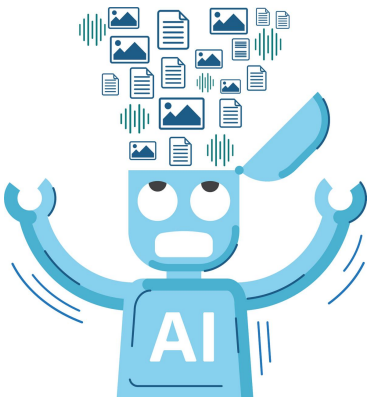


机器学习 Machine Learning

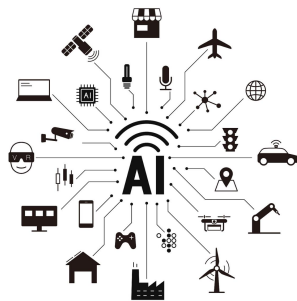


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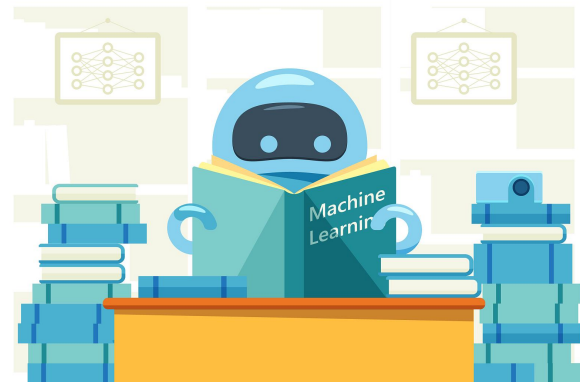




Chapter 3 Parameter Estimation



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Contents

- Introduction
- Maximum-Likelihood Estimation
- Bayesian Estimation

Preliminaries and Notations

$\omega_i \in \{\omega_1, \omega_2, \dots, \omega_c\}$: a state of nature

$P(\omega_i)$: prior probability 先验概率

\mathbf{x} : feature vector

$p(\mathbf{x})$: evidence probability

$p(\mathbf{x} \mid \omega_i)$: class-conditional density / likelihood 类条件概率密度/似然

$P(\omega_i \mid \mathbf{x})$: posterior probability 后验概率

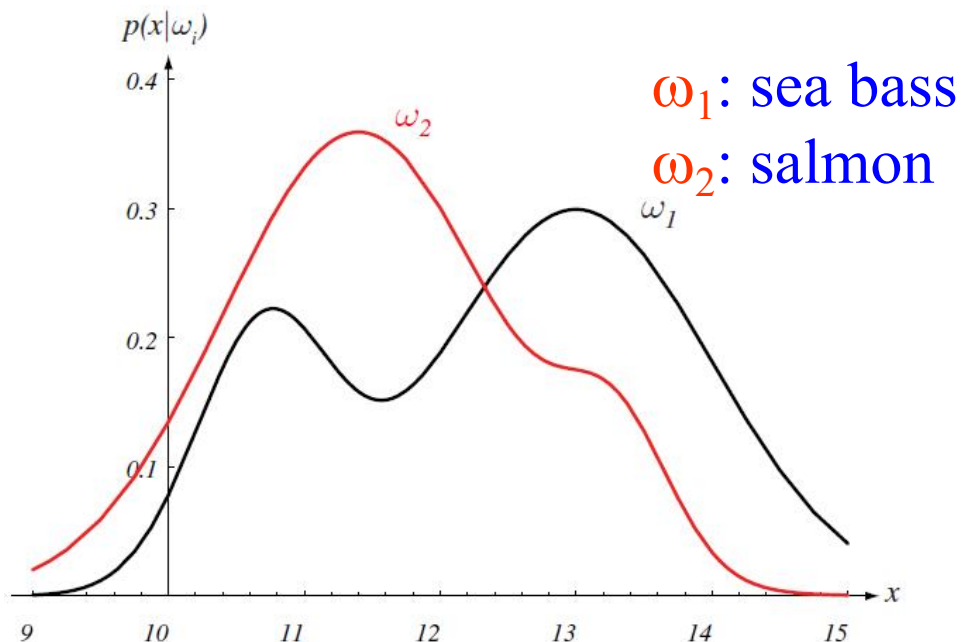
sea bass	salmon
鲈鱼	鲑鱼

ω_1 : sea bass

ω_2 : salmon



An example



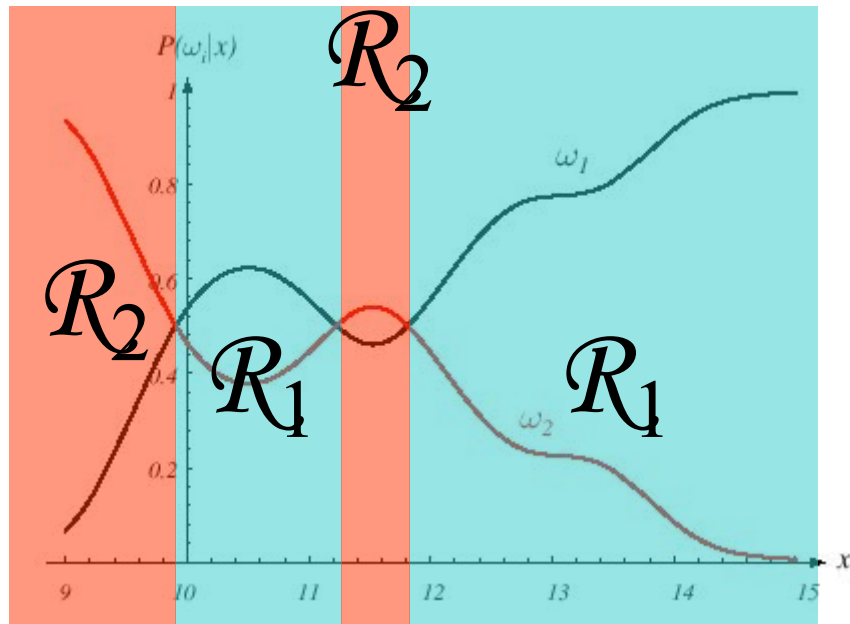
$$P(\omega_1)=2/3$$

$$P(\omega_2)=1/3$$

What will the posterior probability for either type of fish look like?

class-conditional pdf for *lightness*

An example



h-axis: lightness of fish scales

v-axis: posterior probability for each type of fish

Black curve: sea bass

Red curve: salmon

- For each value of x , the higher curve yields the output of Bayesian decision
- For each value of x , the posteriors of either curve sum to 1.0

posterior probability for either type of fish

Bayes Theorem

$$P(\omega_i | \mathbf{x}) = \frac{p(\mathbf{x} | \omega_i)P(\omega_i)}{p(\mathbf{x})}$$

$$p(\mathbf{x}) = \sum_{i=1}^c p(\mathbf{x} | \omega_i)P(\omega_i)$$



Thomas Bayes
(1702-1761)

$$\underline{P(\omega_i | \mathbf{x})} = \frac{p(\mathbf{x} | \omega_i)P(\omega_i)}{p(\mathbf{x})}$$

$$p(\mathbf{x}) = \sum_{j=1}^c p(\mathbf{x} | \omega_j)P(\omega_j)$$

- To compute posterior probability $P(\omega_i | \mathbf{x})$, we need to know:

$$p(\mathbf{x} | \omega_i) \quad P(\omega_i)$$

How can we get these values?

Feasibility of Bayes Formula

- To compute posterior probability, we need to know **prior probability** and **likelihood**

$$P(\omega_i | \mathbf{x}) = \frac{p(\mathbf{x} | \omega_i)P(\omega_i)}{p(\mathbf{x})} \quad \left(\text{posterior} = \frac{\text{likelihood} \times \text{prior}}{\text{evidence}} \right)$$

How do we know
these
probabilities?

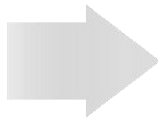
➤ A simple solution: Counting Relative frequencies

Example - Counting

- Collecting samples
 - Suppose we have randomly picked 1209 cars in the campus, got prices from their owners, and measured their heights.
- Compute $P(\omega_1)$ and $P(\omega_2)$

cars in ω_1 : 221

cars in ω_2 : 988

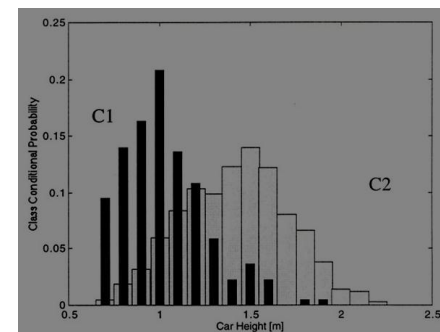


$$P(\omega_1) = \frac{221}{1209} = 0.183$$

$$P(\omega_2) = \frac{988}{1209} = 0.817$$

Example - Counting (Cont.)

- Compute $P(x|\omega_1)$ $P(x|\omega_2)$
 - Discretize the height spectrum (say [0.5m, 2.5m]) into 20 intervals each with length 0.1m, and then count the number of cars falling into each interval for either class
- Suppose $x = 1.05$, which means that x falls into interval $I_x = [1.0m, 1.1m]$



For ω_1 , # cars in I_x is 46,

For ω_2 , # cars in I_x is 59,



$$P(x = 1.05 | \omega_1) = \frac{46}{221} = 0.2081$$
$$P(x = 1.05 | \omega_2) = \frac{59}{988} = 0.0597$$

Feasibility of Bayes Formula

- To compute posterior probability, we need to know **prior probability** and **likelihood**

$$P(\omega_i | \mathbf{x}) = \frac{p(\mathbf{x} | \omega_i)P(\omega_i)}{p(\mathbf{x})} \quad \left(\text{posterior} = \frac{\text{likelihood} \times \text{prior}}{\text{evidence}} \right)$$

How do we know
these
probabilities?

➤ A simple solution: Counting Relative frequencies

➤ **An advanced solution: Conduct Density estimation**

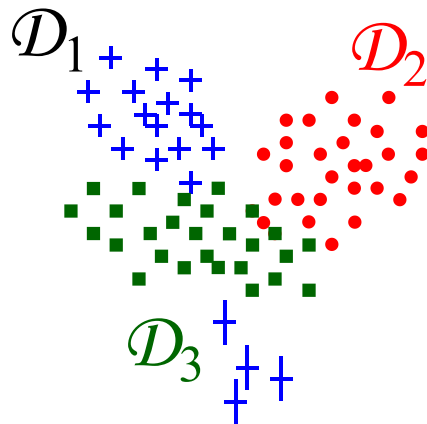
Contents

- Introduction
- **Maximum-Likelihood Estimation**
- Bayesian Estimation

$$\mathcal{D} = \{\mathcal{D}_1, \mathcal{D}_2, \dots, \mathcal{D}_c\}$$

The samples in \mathcal{D}_j are drawn independently according to the probability law $p(\mathbf{x}|\omega_j)$.

That is, examples in \mathcal{D}_j are i.i.d. random variables, i.e., **independent and identically distributed**. 独立同分布



It is easy to compute the prior probability:

$$P(\omega_i) = \frac{|D_j|}{\sum_{i=1}^c |D_i|}$$

- For class-conditional pdf:
 - Case I: $p(\mathbf{x}|\omega_j)$ has certain parametric form
 - Case II: $p(\mathbf{x}|\omega_j)$ doesn't have parametric form

- For class-conditional pdf:

- Case I: $p(\mathbf{x}|\omega_j)$ has certain parametric form

- e.g.

$$p(\mathbf{x} | \omega_j) \sim N(\boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)$$

$$\underbrace{\theta_j}_{\text{parameters}} \longrightarrow \boldsymbol{\theta}_j = (\theta_1, \theta_2, \dots, \theta_m)^T$$

- If $X \in R^d$ θ_j contains “ $d+d(d+1)/2$ ” free parameters.

- Case II: $p(\mathbf{x}|\omega_j)$ doesn't have parametric form

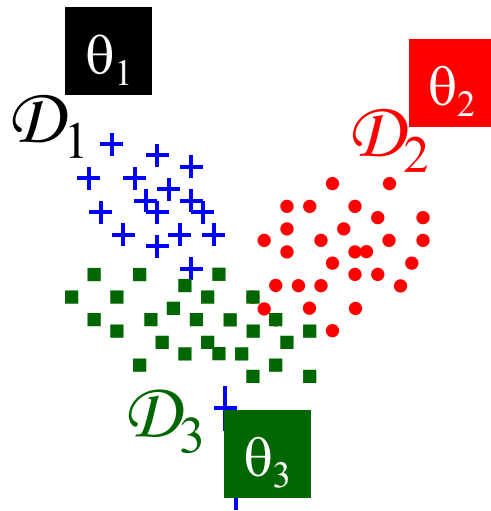
- Next chapter.

$$\mathcal{D} = \{\mathcal{D}_1, \mathcal{D}_2, \dots, \mathcal{D}_c\}$$

$$p(\mathbf{x} \mid \omega_j) \equiv p(\mathbf{x} \mid \boldsymbol{\theta}_j)$$

Use \mathcal{D}_j to estimate the unknown parameter vector $\boldsymbol{\theta}_j$

$$\boldsymbol{\theta}_j = (\theta_1, \theta_2, \dots, \theta_m)^T$$



■ Maximum-Likelihood Estimation

View parameters as quantities whose values are fixed but unknown



Estimate parameter values by maximizing the likelihood (probability) of observing the actual examples.

■ Bayesian Estimation

View parameters as random variables having some known prior distribution



Observation of the actual training examples transforms parameters' prior into posterior distribution. (via Bayes rule)



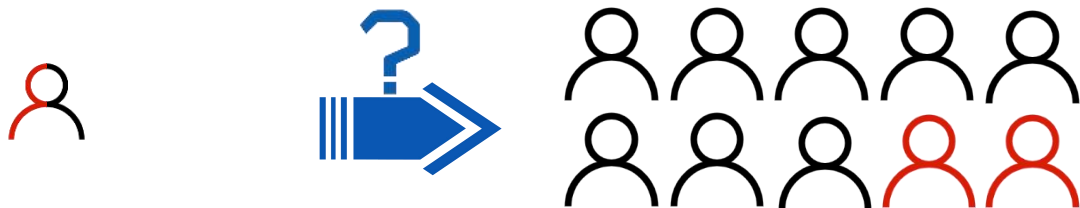
概 率

描述了参数已知时的随机变量的输出结果



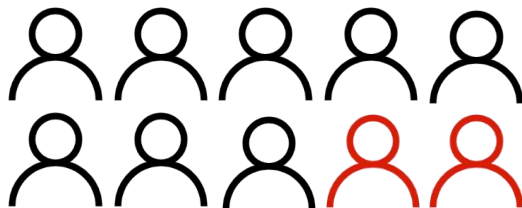
似 然

用来描述已知随机变量输出结果时，**未知参数的可能取值**



已知参数感染率 θ

推测密切接触者感染的各种情况的可能性

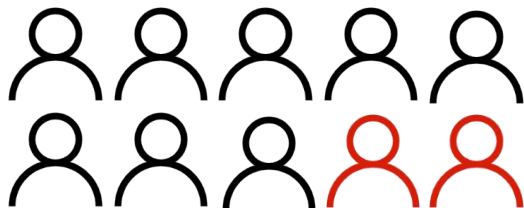


参数感染率 θ 为0.1



密切接触者感染的可能性为0.1

可以推测，在10个密切接触者中，出现2例确诊病例的概率为：



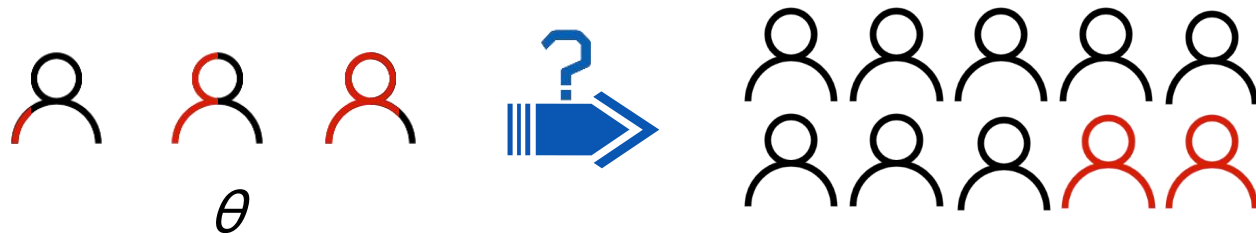
参数感染率 θ 为0.1



密切接触者感染的可能性为0.1

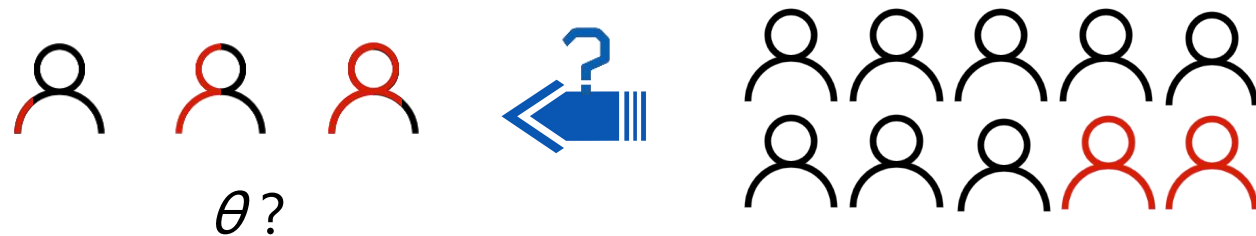
可以推测，在10个密切接触者中，出现2例确诊病例的概率为：

$$\binom{10}{2} 0.1^2 (1 - 0.1)^8 \approx 0.19$$

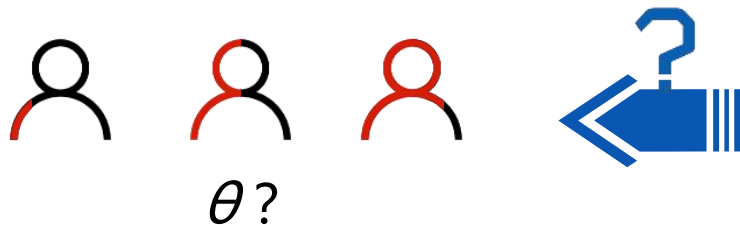


概 率

当我们对参数并不清楚，要通过采样的情况去推测参数



似 然



证据

似然：通过证据，对参数 θ 进行推断。

最大似然估计：得到最可能的参数的过程。

极大似然估计

- 某地一天内增长无症状感染者2例，密切接触者10人并采取了相应的隔离举措，发现6人为阳性。



极大似然估计

- 某地一天内增长无症状感染者2例，密切接触者10人并采取了相应的隔离举措，发现6人为阳性。



如果密切接触者感染的感染率为0.5，出现这个结果的可能性是：

$$\binom{10}{6} 0.5^6 (1 - 0.5)^4 \approx 0.21$$

极大似然估计

- 某地一天内增长无症状感染者2例，密切接触者10人并采取了相应的隔离举措，发现6人为阳性。



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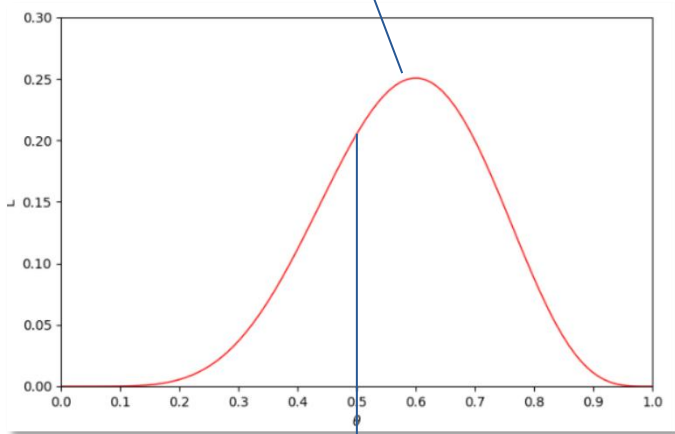
如果密切接触者感染的感染率为0.6，出现这个结果的可能性是：

$$\binom{10}{6} 0.6^6 (1 - 0.6)^4 \approx 0.25$$

$\theta=0.6$ 作为参数的可能性是 $\theta=0.5$ 作为参数的可能性的1.19倍

极大似然估计

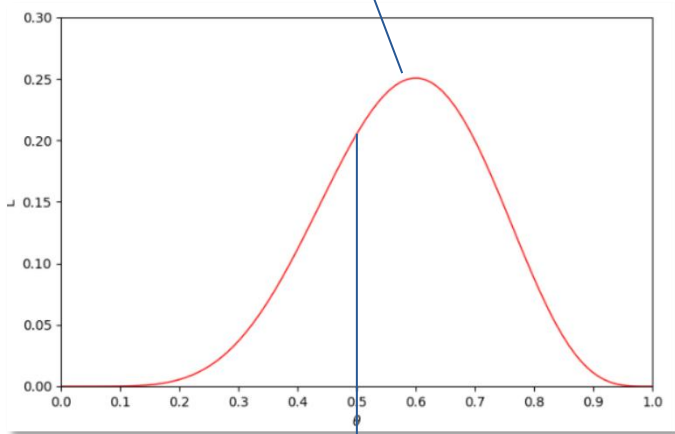
参数 θ 为0.6时，概率较大



$\theta=0.5$ 也是有可能的，
虽然可能性小一点

极大似然估计

参数 θ 为0.6时，概率较大

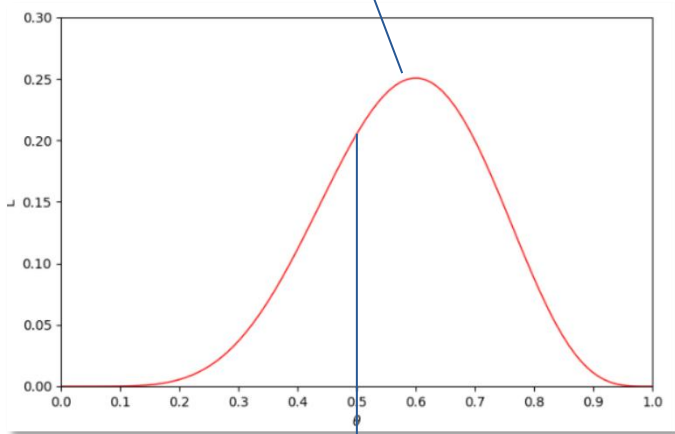


$\theta=0.5$ 也是有可能的，
虽然可能性小一点

$$L(\theta) = \binom{10}{6} \theta^6 (1 - \theta)^4$$

极大似然估计

参数 θ 为0.6时，概率较大

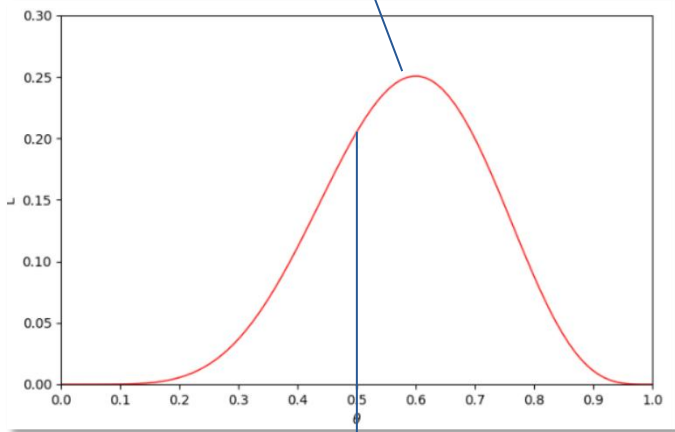


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极大似然估计

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虽然可能性小一点

$$L(\theta) = \binom{10}{6} \theta^6 (1 - \theta)^4$$

似然函数是推测参数的分布。

而求最大似然估计的问题，就变成了求似然函数的极值。

求似然函数
的极值



对似然函数
求导

- 从特殊到一般
- 最大似然估计针对多次实验。用 x_1, x_2, \dots, x_N 表示每次实验结果，因为每次实验都是独立的，所以似然函数可以写作：

$$L(\theta) = p(x_1|\theta)p(x_2|\theta)\dots p(x_N|\theta) = \prod_{n=1}^N p(x_n|\theta)$$

- 从特殊到一般
- 最大似然估计针对**多次实验**。用 x_1, x_2, \dots, x_N 表示每次实验结果，因为每次实验都是独立的，所以似然函数可以写作：

$$L(\theta) = p(x_1|\theta)p(x_2|\theta)\dots p(x_N|\theta) = \prod_{n=1}^N p(x_n|\theta) \quad \text{似然函数}$$

- 则此时可写为：

$$\hat{\theta} = \arg \max_{\theta} L(\theta) \qquad \hat{\theta} = \arg \max_{\theta} \prod_{n=1}^N p(x_n|\theta)$$

$$\hat{\theta} = \arg \max_{\theta} L(\theta)$$

$$\hat{\theta} = \arg \max_{\theta} \prod_{n=1}^N p(\mathbf{x}_n | \theta)$$



通常，使用对数似然

$$\hat{\theta} = \arg \max_{\theta} LL(\theta)$$

$$LL(\theta) = \log L(\theta)$$

$$\hat{\theta} = \arg \max_{\theta} \sum_{n=1}^N \log p(\mathbf{x}_n | \theta)$$

Maximum-Likelihood Estimation

MIMA

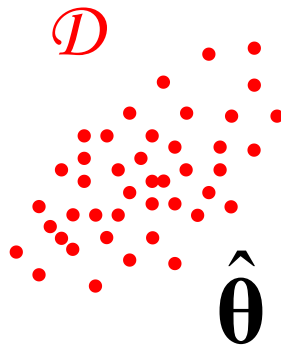
- Because each class is considered individually, the subscript used before will be dropped.

Maximum-Likelihood Estimation

- Because each class is considered individually, the subscript used before will be dropped.

- Now the problem becomes:

Given a sample set \mathcal{D} , whose elements are drawn independently from a population possessing a known parameter form, say $p(x|\theta)$, we want to choose a $\hat{\theta}$ that will make \mathcal{D} to occur most likely.



Maximum-Likelihood Estimation (Cont.)

- Criterion of ML

$$\mathcal{D} = \{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$$

- By the independence assumption, we have:

$$p(\mathcal{D} | \boldsymbol{\theta}) = p(\mathbf{x}_1 | \boldsymbol{\theta}) p(\mathbf{x}_2 | \boldsymbol{\theta}) \cdots p(\mathbf{x}_n | \boldsymbol{\theta})$$

- The Likelihood function:

$$L(\boldsymbol{\theta} | \mathcal{D}) = p(\mathcal{D} | \boldsymbol{\theta}) = \prod_{k=1}^n p(\mathbf{x}_k | \boldsymbol{\theta})$$

- The maximum-likelihood estimation:

$$\hat{\boldsymbol{\theta}} = \arg \max_{\boldsymbol{\theta}} L(\boldsymbol{\theta} | \mathcal{D})$$

Maximum-Likelihood Estimation (Cont.)

- Often, we resort to maximize the **log-likelihood function**

$$l(\boldsymbol{\theta} \mid \mathcal{D}) = \ln L(\boldsymbol{\theta} \mid \mathcal{D}) = \sum_{k=1}^n \ln p(\mathbf{x}_k \mid \boldsymbol{\theta})$$

$$\hat{\boldsymbol{\theta}} = \arg \max_{\boldsymbol{\theta}} l(\boldsymbol{\theta} \mid \mathcal{D})$$




$$\hat{\boldsymbol{\theta}} = \arg \max_{\boldsymbol{\theta}} L(\boldsymbol{\theta} \mid \mathcal{D})$$

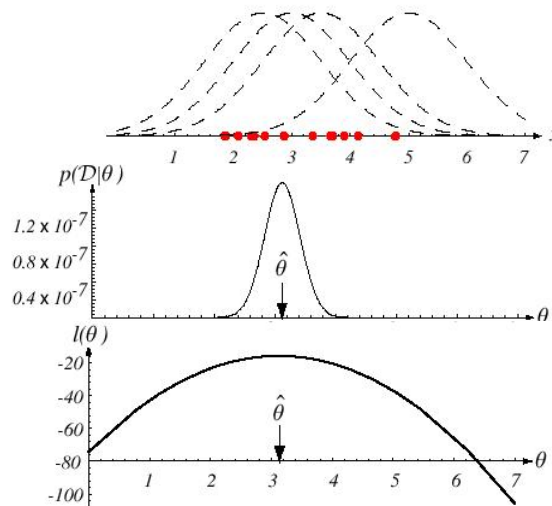
why?

Maximum-Likelihood Estimation (Cont.)

- Often, we resort to maximize the **log-likelihood function**

$$l(\boldsymbol{\theta} \mid \mathcal{D}) = \ln L(\boldsymbol{\theta} \mid \mathcal{D}) = \sum_{k=1}^n \ln p(\mathbf{x}_k \mid \boldsymbol{\theta})$$

$$\hat{\boldsymbol{\theta}} = \arg \max_{\boldsymbol{\theta}} l(\boldsymbol{\theta} \mid \mathcal{D})$$

$$\hat{\boldsymbol{\theta}} = \arg \max_{\boldsymbol{\theta}} L(\boldsymbol{\theta} \mid \mathcal{D})$$



Maximum-Likelihood Estimation (Cont.)

- Find the extreme values using the method in differential calculus.
- Gradient Operator
 - Let $f(\theta)$ be a continuous function, where $\theta = (\theta_1, \theta_2, \dots, \theta_n)^T$.

Gradient Operator

$$\nabla_{\theta} = \left(\frac{\partial}{\partial \theta_1}, \frac{\partial}{\partial \theta_2}, \dots, \frac{\partial}{\partial \theta_n} \right)^T$$

- Find the extreme values by solving

$$\nabla_{\theta} f = 0$$

■ 情况一：

均值未知 方差已知

$$p(\mathbf{x} | \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{d/2} |\boldsymbol{\Sigma}|^{1/2}} \exp\left[-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu})\right]$$

获得均值

■ 情况二：

均值未知 方差未知

$$p(x | \mu, \sigma^2) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left[-\frac{(x - \mu)^2}{2\sigma^2}\right]$$

获得均值、方差

高斯分布的极大似然估计

MIMA

均值未知
方差已知

$$p(\mathbf{x} | \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{d/2} |\boldsymbol{\Sigma}|^{1/2}} \exp\left[-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu})\right]$$

➡ $L(\boldsymbol{\mu} | \mathcal{D}) = p(\mathcal{D} | \boldsymbol{\mu}) = \prod_{k=1}^n p(\mathbf{x}_k | \boldsymbol{\theta})$ (似然函数)

➡ $= \frac{1}{(2\pi)^{nd/2} |\boldsymbol{\Sigma}|^{n/2}} \prod_{k=1}^n \exp\left[-\frac{1}{2}(\mathbf{x}_k - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x}_k - \boldsymbol{\mu})\right]$

高斯分布的极大似然估计

MIMA

均值未知
方差已知

$$L(\boldsymbol{\mu} | \mathcal{D}) = \frac{1}{(2\pi)^{nd/2} |\boldsymbol{\Sigma}|^{n/2}} \prod_{k=1}^n \exp\left[-\frac{1}{2}(\mathbf{x}_k - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x}_k - \boldsymbol{\mu})\right]$$

➡ $l(\boldsymbol{\mu} | \mathcal{D}) = \ln L(\boldsymbol{\mu} | \mathcal{D})$ (对数似然函数)

➡
$$= -\ln(2\pi)^{nd/2} |\boldsymbol{\Sigma}|^{n/2} - \frac{1}{2} \sum_{k=1}^n (\mathbf{x}_k - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x}_k - \boldsymbol{\mu})$$

➡
$$\nabla_{\boldsymbol{\mu}} l(\boldsymbol{\mu} | \mathcal{D}) = \sum_{k=1}^n \boldsymbol{\Sigma}^{-1}(\mathbf{x}_k - \boldsymbol{\mu}) = 0$$

➡
$$\hat{\boldsymbol{\mu}} = \frac{1}{n} \sum_{k=1}^n \mathbf{x}_k$$



高斯分布均值的最大似然估计等于样本的均值

高斯分布的极大似然估计

均值未知
方差未知

$$\boldsymbol{\theta} = (\theta_1, \theta_2)^T = (\mu, \sigma^2)^T$$

➔
$$p(x | \mu, \sigma^2) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left[-\frac{(x - \mu)^2}{2\sigma^2}\right]$$

➔
$$L(\boldsymbol{\theta} | \mathcal{D}) = p(\mathcal{D} | \boldsymbol{\theta}) \quad (\text{似然函数})$$

$$= \prod_{k=1}^n p(x_k | \boldsymbol{\theta}) = \frac{1}{(2\pi)^{n/2} \sigma^n} \prod_{k=1}^n \exp\left[-\frac{(x_k - \mu)^2}{2\sigma^2}\right]$$

高斯分布的极大似然估计

均值未知
方差未知

$$\boldsymbol{\theta} = (\theta_1, \theta_2)^T = (\mu, \sigma^2)^T$$

$$L(\boldsymbol{\theta} | \mathcal{D}) = \frac{1}{(2\pi)^{n/2} \sigma^n} \prod_{k=1}^n \exp \left[-\frac{(x_k - \mu)^2}{2\sigma^2} \right]$$


➡ $l(\boldsymbol{\theta} | \mathcal{D}) = \ln L(\boldsymbol{\theta} | \mathcal{D})$ (对数似然函数)

$$= -\ln(2\pi)^{n/2} \theta_2^{n/2} - \frac{1}{2\theta_2} \sum_{k=1}^n (x_k - \theta_1)^2$$

➡ $\nabla_{\boldsymbol{\theta}} l(\boldsymbol{\theta} | \mathcal{D}) = \begin{bmatrix} \frac{1}{\theta_2} \sum_{k=1}^n (x_k - \theta_1) \\ -\frac{n}{2\theta_2} + \sum_{k=1}^n \frac{(x_k - \theta_1)^2}{2\theta_2^2} \end{bmatrix} = \mathbf{0}$

➡ $\hat{\mu} = \hat{\theta}_1 = \frac{1}{n} \sum_{k=1}^n x_k$

$\hat{\sigma}^2 = \hat{\theta}_2 = \frac{1}{n} \sum_{k=1}^n (x_k - \hat{\mu})^2$



The Gaussian Case I

- Case I: unknown μ , and Σ is known

$$p(\mathbf{x} | \mu, \Sigma) = \frac{1}{(2\pi)^{d/2} |\Sigma|^{1/2}} \exp\left[-\frac{1}{2}(\mathbf{x} - \mu)^T \Sigma^{-1}(\mathbf{x} - \mu)\right] \quad 1$$

$$L(\mu | \mathcal{D}) = p(\mathcal{D} | \mu) = \prod_{k=1}^n p(\mathbf{x}_k | \mu) \quad (\text{Likelihood function}) \quad 2$$

$$= \frac{1}{(2\pi)^{nd/2} |\Sigma|^{n/2}} \prod_{k=1}^n \exp\left[-\frac{1}{2}(\mathbf{x}_k - \mu)^T \Sigma^{-1}(\mathbf{x}_k - \mu)\right] \quad 3$$


$$l(\mu | \mathcal{D}) = \ln L(\mu | \mathcal{D}) \quad 4$$

$$= -\ln(2\pi)^{nd/2} |\Sigma|^{n/2} - \frac{1}{2} \sum_{k=1}^n (\mathbf{x}_k - \mu)^T \Sigma^{-1}(\mathbf{x}_k - \mu) \quad 5$$

The Gaussian Case I

$$l(\boldsymbol{\mu} \mid \mathcal{D}) = \ln L(\boldsymbol{\mu} \mid \mathcal{D})$$


1

$$= -\ln(2\pi)^{nd/2} |\boldsymbol{\Sigma}|^{n/2} - \frac{1}{2} \sum_{k=1}^n (\mathbf{x}_k - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x}_k - \boldsymbol{\mu})$$

2

$$\nabla_{\boldsymbol{\mu}} l(\boldsymbol{\mu} \mid \mathcal{D}) = \sum_{k=1}^n \boldsymbol{\Sigma}^{-1} (\mathbf{x}_k - \boldsymbol{\mu}) = 0$$

3


$$\hat{\boldsymbol{\mu}} = \frac{1}{n} \sum_{k=1}^n \mathbf{x}_k \quad \longrightarrow \quad \text{Sample Mean!}$$

4

Intuitive Result: Maximum estimate for the unknown $\boldsymbol{\mu}$ is just the arithmetic average of training samples---sample mean.

The Gaussian Case II

- Case II: both μ and Σ are unknown
- Consider univariate case

$$\boldsymbol{\theta} = (\theta_1, \theta_2)^T = (\mu, \sigma^2)^T$$

0

$$p(x | \mu, \sigma^2) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left[-\frac{(x - \mu)^2}{2\sigma^2}\right]$$

1

Likelihood
function

$$L(\boldsymbol{\theta} | \mathcal{D}) = p(\mathcal{D} | \boldsymbol{\theta}) = \prod_{k=1}^n p(x_k | \boldsymbol{\theta}) = \frac{1}{(2\pi)^{n/2} \sigma^n} \prod_{k=1}^n \exp\left[-\frac{(x_k - \mu)^2}{2\sigma^2}\right]$$

2

$$l(\boldsymbol{\theta} | \mathcal{D}) = \ln L(\boldsymbol{\theta} | \mathcal{D}) = -\ln(2\pi)^{n/2} \sigma^n - \frac{1}{2\sigma^2} \sum_{k=1}^n (x_k - \mu)^2$$

3


$$= -\ln(2\pi)^{n/2} \theta_2^{n/2} - \frac{1}{2\theta_2} \sum_{k=1}^n (x_k - \theta_1)^2$$

4

The Gaussian Case II

$$l(\boldsymbol{\theta} | \mathcal{D}) = -\ln(2\pi)^{n/2} \theta_2^{n/2} - \frac{1}{2\theta_2} \sum_{k=1}^n (x_k - \theta_1)^2 \quad 1$$

$$\nabla_{\boldsymbol{\theta}} l(\boldsymbol{\theta} | \mathcal{D}) = \begin{bmatrix} \frac{1}{\theta_2} \sum_{k=1}^n (x_k - \theta_1) \\ -\frac{n}{2\theta_2} + \sum_{k=1}^n \frac{(x_k - \theta_1)^2}{2\theta_2^2} \end{bmatrix} = \mathbf{0} \quad 2$$


$$\left\{ \begin{aligned} \hat{\mu} &= \hat{\theta}_1 = \frac{1}{n} \sum_{k=1}^n x_k \\ \hat{\sigma}^2 &= \hat{\theta}_2 = \frac{1}{n} \sum_{k=1}^n (x_k - \hat{\mu})^2 \end{aligned} \right. \quad \begin{matrix} 3 \\ 4 \end{matrix}$$

Unbiased Estimator:

$$E[\hat{\boldsymbol{\theta}}] = \boldsymbol{\theta}$$

Consistent Estimator:

$$\lim_{n \rightarrow \infty} E[\hat{\boldsymbol{\theta}}] = \boldsymbol{\theta}$$

Arithmetic average of n vectors

Arithmetic average of n matrices

$$(\mathbf{x}_k - \hat{\boldsymbol{\mu}})(\mathbf{x}_k - \hat{\boldsymbol{\mu}})^T$$

MLE for Normal Population

$$\hat{\boldsymbol{\mu}} = \frac{1}{n} \sum_{k=1}^n \mathbf{x}_k$$

Sample Mean

$$E[\hat{\boldsymbol{\mu}}] = \boldsymbol{\mu}$$

$$\hat{\boldsymbol{\Sigma}} = \frac{1}{n} \sum_{k=1}^n (\mathbf{x}_k - \hat{\boldsymbol{\mu}})(\mathbf{x}_k - \hat{\boldsymbol{\mu}})^T$$

$$E[\hat{\boldsymbol{\Sigma}}] = \frac{n-1}{n} \boldsymbol{\Sigma} \neq \boldsymbol{\Sigma}$$

$$\mathbf{C} = \frac{1}{n-1} \sum_{k=1}^n (\mathbf{x}_k - \hat{\boldsymbol{\mu}})(\mathbf{x}_k - \hat{\boldsymbol{\mu}})^T$$

Sample Covariance Matrix

$$E[\mathbf{C}] = \boldsymbol{\Sigma}$$

Contents

- Introduction
- Maximum-Likelihood Estimation
- **Bayesian Estimation**

■ Settings

- The **parametric form** of the likelihood function for each category is known.
- However, θ_j is considered to be **random variables** instead of being fixed (but unknown) values.

In this case, we can no longer make a single ML estimate $\hat{\theta}$ and then infer $P(\omega_i | \mathbf{x})$ based on $P(\omega_i)$ and $p(\mathbf{x} | \omega_i)$



How can we proceed?



Fully exploit training examples!

Posterior Probabilities from sample

$$\mathcal{D} = \{\mathcal{D}_1, \mathcal{D}_2, \dots, \mathcal{D}_c\}$$

0

$$P(\omega_i | \mathbf{x}) = P(\omega_i | \mathbf{x}, \mathcal{D})$$

1

$$P(\omega_i | \mathbf{x}) = \frac{p(\mathbf{x} | \omega_i)P(\omega_i)}{p(\mathbf{x})} = \frac{p(\mathbf{x} | \omega_i, \mathcal{D})P(\omega_i | \mathcal{D})}{\sum_{j=1}^c p(\mathbf{x} | \omega_j, \mathcal{D})P(\omega_j | \mathcal{D})} = P(\omega_i | \mathbf{x}, \mathcal{D})$$

2

Assumptions:

$$P(\omega_i | \mathcal{D}) = P(\omega_i)$$

$$P(\mathbf{x} | \omega_i, \mathcal{D}) = P(\mathbf{x} | \omega_i, \mathcal{D}_i)$$

3

$$P(\omega_i | \mathbf{x}, \mathcal{D}) = \frac{P(\mathbf{x} | \omega_i, \mathcal{D}_i)P(\omega_i)}{\sum_{j=1}^c P(\mathbf{x} | \omega_j, \mathcal{D}_j)P(\omega_j)}$$

Each class can be considered independently

4

$$P(\omega_i | \mathbf{x}, \mathcal{D}) = \frac{P(\mathbf{x} | \omega_i, \mathcal{D}_i)P(\omega_i)}{\sum_{j=1}^c P(\mathbf{x} | \omega_j, \mathcal{D}_j)P(\omega_j)}$$

1

The key problem is to determine, $P(\mathbf{x} | \omega_i, \mathcal{D}_i)$, treat each class independently, the problem becomes $P(\mathbf{x} | \mathcal{D})$

*This is always the central problem of **Bayesian Learning**.*

Class-Conditional Density Estimation

Assume $p(\mathbf{x})$ is unknown but knowing it has a fixed form with parameter vector θ .

θ : Random variable w.r.t. parametric form
 \mathbf{x} is independent of D given θ

$$p(\mathbf{x} | \mathcal{D}) = \int p(\mathbf{x}, \theta | D) d\theta \quad 1$$

$$= \int p(\mathbf{x} | \theta, D) p(\theta | \mathcal{D}) d\theta \quad 2$$

$$= \int p(\mathbf{x} | \theta) p(\theta | \mathcal{D}) d\theta \quad 3$$

Class-Conditional Density Estimation

Assume $p(\mathbf{x})$ is unknown but knowing it has a fixed form with parameter vector θ .

θ : Random variable w.r.t. parametric form
 \mathbf{x} is independent of D given θ

$$p(\mathbf{x} | \mathcal{D}) = \int p(\mathbf{x}, \theta | D) d\theta$$

1

$$= \int p(\mathbf{x} | \theta, D) p(\theta | \mathcal{D}) d\theta$$

2

$$\stackrel{\text{yellow dot}}{=} \int \overset{\text{yellow dot}}{p}(\overset{\text{yellow dot}}{\mathbf{x}} | \overset{\text{yellow dot}}{\theta}) p(\overset{\text{green dot}}{\theta} | \overset{\text{green dot}}{D}) d\overset{\text{green dot}}{\theta}$$

3

$$= p(\mathbf{x} | \omega_i, \mathcal{D})$$

4

$$p(\mathbf{x} | \mathcal{D}) \approx p(\mathbf{x} | \hat{\theta})$$

5

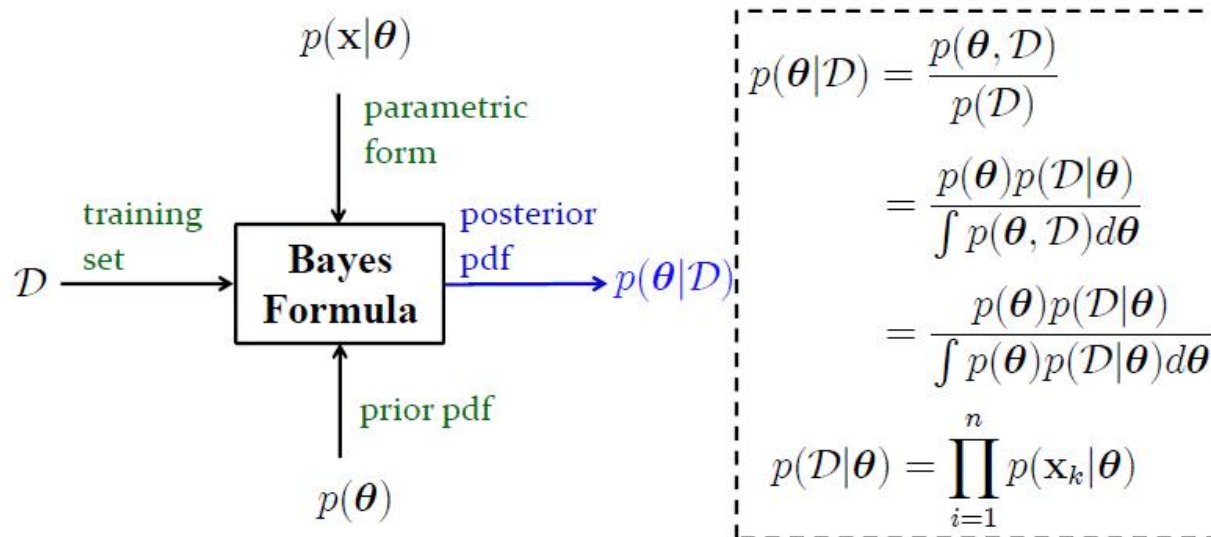
The form of distribution is assumed known

The posterior density we want to estimate

Bayesian Estimation: General Procedure

Phase I:

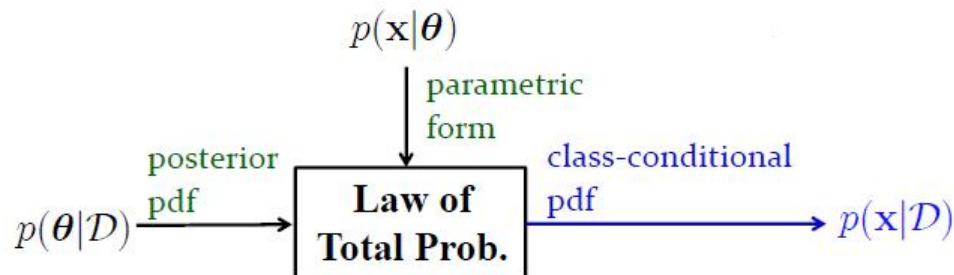
$$p(\boldsymbol{\theta} \mid \mathcal{D}) = ?$$



Phase II:

$$p(\mathbf{x} | \mathcal{D}) = \int p(\mathbf{x} | \boldsymbol{\theta}) p(\boldsymbol{\theta} | \mathcal{D}) d\boldsymbol{\theta}$$

1



Phase III:

$$P(\omega_i | \mathbf{x}, \mathcal{D}) = \frac{P(\mathbf{x} | \omega_i, \mathcal{D}_i) P(\omega_i)}{\sum_{j=1}^c P(\mathbf{x} | \omega_j, \mathcal{D}_j) P(\omega_j)}$$

2

The Gaussian Case

- The univariate Gaussian: unknown μ

Phase I:

$$\underline{\underline{p(\mu)}}, \underline{\underline{p(x | \mu)}}, D \implies p(\mu | D)$$

1

$$p(x | \mu) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left[-\frac{1}{2}\left(\frac{x - \mu}{\sigma}\right)^2\right]$$

2

$$p(\mu) = \frac{1}{\sqrt{2\pi}\sigma_0} \exp\left[-\frac{1}{2}\left(\frac{\mu - \mu_0}{\sigma_0}\right)^2\right]$$

3

Other form of prior pdf could be assumed as well.

The Gaussian Case

Phase I:
$$p(\mu) = \frac{1}{\sqrt{2\pi}\sigma_0} \exp\left[-\frac{1}{2}\left(\frac{\mu - \mu_0}{\sigma_0}\right)^2\right] \quad p(x|\mu) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left[-\frac{1}{2}\left(\frac{x - \mu}{\sigma}\right)^2\right] \quad 1$$

$$p(\boldsymbol{\theta} | \mathcal{D}) = \alpha \prod_{k=1}^n p(\mathbf{x}_k | \boldsymbol{\theta}) p(\boldsymbol{\theta}) \quad 2$$

$$p(\mu | \mathcal{D}) = \alpha \prod_{k=1}^n \frac{1}{\sqrt{2\pi}\sigma} \exp\left[-\frac{1}{2}\left(\frac{x_k - \mu}{\sigma}\right)^2\right] \cdot \frac{1}{\sqrt{2\pi}\sigma_0} \exp\left[-\frac{1}{2}\left(\frac{\mu - \mu_0}{\sigma_0}\right)^2\right] \quad 3$$

$$= \alpha' \exp\left[-\frac{1}{2}\left(\sum_{k=1}^n \left(\frac{x_k - \mu}{\sigma}\right)^2 + \left(\frac{\mu - \mu_0}{\sigma_0}\right)^2\right)\right] \quad 4$$

$$= \alpha'' \exp\left[-\frac{1}{2}\left[\left(\frac{n}{\sigma^2} + \frac{1}{\sigma_0^2}\right)\mu^2 - 2\left(\frac{1}{\sigma^2} \sum_{k=1}^n x_k + \frac{\mu_0}{\sigma_0^2}\right)\mu\right]\right] \quad 5$$

The Gaussian Case

Phase I:

*$p(\mu | \mathcal{D})$ is an exponential function of a quadratic function of μ ;
thus $p(\mu | \mathcal{D})$ is also a normal.*

$$p(\mu | \mathcal{D}) \sim N(\mu_n, \sigma_n^2)$$

$$\rightarrow p(\mu | \mathcal{D}) = \frac{1}{\sqrt{2\pi}\sigma_n} \exp\left[-\frac{1}{2}\left(\frac{\mu - \mu_n}{\sigma_n}\right)^2\right]$$

$$= \frac{1}{\sqrt{2\pi}\sigma_n} \exp\left[-\frac{1}{2\sigma_n^2}(\mu^2 - 2\mu_n\mu + \mu_n^2)\right]$$

$$p(\mu | \mathcal{D}) = \alpha'' \exp\left[-\frac{1}{2}\left[\left(\frac{n}{\sigma^2} + \frac{1}{\sigma_0^2}\right)\mu^2 - 2\left(\frac{1}{\sigma^2} \sum_{k=1}^n x_k + \frac{\mu_0}{\sigma_0^2}\right)\mu\right]\right]$$

Comparison


- Equating the coefficients in both form, then, we have:


$$\mu_n = \left(\frac{n\sigma_0^2}{n\sigma_0^2 + \sigma^2} \right) \hat{\mu}_n + \frac{\sigma^2}{n\sigma_0^2 + \sigma^2} \mu_0 \quad \hat{\mu}_n = \frac{1}{n} \sum_{k=1}^n x_k$$

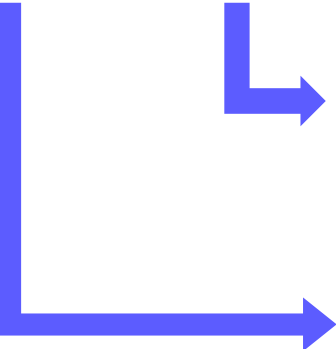
$$\sigma_n^2 = \frac{\sigma_0^2 \sigma^2}{n\sigma_0^2 + \sigma^2}$$

The Gaussian Case

Phase II: $p(\mathbf{x} | \mathcal{D}) = \int p(\mathbf{x} | \boldsymbol{\theta}) p(\boldsymbol{\theta} | \mathcal{D}) d\boldsymbol{\theta}$


$p(\mu | D)$, $p(x | \mu)$  $p(x | D)$

 $p(x | \mu) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left[-\frac{1}{2}\left(\frac{x - \mu}{\sigma}\right)^2\right]$

 $p(\mu | \mathcal{D}) \sim N(\mu_n, \sigma_n^2)$

How would $p(x | \mathcal{D})$ look like in this case?

The Gaussian Case

$$p(\mathbf{x} | \mathcal{D}) = \int p(\mathbf{x} | u) p(u | \mathcal{D}) d\theta$$

$$\left\{ \begin{array}{l} p(x | \mu) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left[-\frac{1}{2}\left(\frac{x - \mu}{\sigma}\right)^2\right] \\ p(\mu | \mathcal{D}) \sim N(\mu_n, \sigma_n^2) \end{array} \right.$$

$$\begin{aligned} p(x | \mathcal{D}) &= \frac{1}{2\pi\sigma\sigma_n} \int \exp\left[-\frac{1}{2}\left(\frac{x - \mu}{\sigma}\right)^2\right] \exp\left[-\frac{1}{2}\left(\frac{\mu - \mu_n}{\sigma_n}\right)^2\right] d\mu \\ &= \frac{1}{2\pi\sigma\sigma_n} \exp\left[-\frac{1}{2} \frac{(x - \mu_n)^2}{\sigma^2 + \sigma_n^2}\right] \underbrace{\int \exp\left[-\frac{1}{2} \frac{\sigma^2 + \sigma_n^2}{\sigma^2 \sigma_n^2} \left(\mu - \frac{\sigma_n^2 x + \sigma^2 \mu_n}{\sigma^2 + \sigma_n^2}\right)^2\right] d\mu}_{= ?} \end{aligned}$$

$p(x | \mathcal{D})$ is an exponential function of a quadratic function of x ; thus, it is also a normal pdf.

$= ?$

The Gaussian Case

$$p(\mathbf{x} | \mathcal{D}) = \int p(\mathbf{x} | u) p(u | \mathcal{D}) d\boldsymbol{\theta} \quad \left\{ \begin{array}{l} p(x | \mu) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left[-\frac{1}{2}\left(\frac{x - \mu}{\sigma}\right)^2\right] \\ p(\mu | \mathcal{D}) \sim N(\mu_n, \sigma_n^2) \end{array} \right.$$


$$p(x | \mathcal{D}) \sim N(\mu_n, \sigma^2 + \sigma_n^2)$$

$$= \frac{1}{2\pi\sigma\sigma_n} \exp\left[-\frac{1}{2} \frac{(x - \mu_n)^2}{\sigma^2 + \sigma_n^2}\right] \underbrace{\int \exp\left[-\frac{1}{2} \frac{\sigma^2 + \sigma_n^2}{\sigma^2 \sigma_n^2} \left(\mu - \frac{\sigma_n^2 x + \sigma^2 \mu_n}{\sigma^2 + \sigma_n^2}\right)^2\right] d\mu}$$

$p(x | \mathcal{D})$ is an exponential function of a quadratic function of x ; thus, it is also a normal pdf.

$=?$

Phase III:

$$P(\omega_i \mid \mathbf{x}, \mathcal{D}) = \frac{P(\mathbf{x} \mid \omega_i, \mathcal{D}_i)P(\omega_i)}{\sum_{j=1}^c P(\mathbf{x} \mid \omega_j, \mathcal{D}_j)P(\omega_j)}$$

■ Key issue

- Estimate prior and class-conditional pdf from training set
- Basic assumption on training examples: i.i.d.

■ Two strategies to key issue

- Parametric form for class-conditional pdf
 - Maximum likelihood estimation
 - Bayesian estimation
- No parametric form for class-conditional pdf

- Maximum likelihood estimation
 - Settings: parameters as fixed but unknown values
 - The objective function: log-likelihood function
 - The gradient for the objective function should be zero
 - Gaussian

- Bayesian estimation
 - Settings: parameters as random variables
 - General procedure: I, II, III
 - Gaussian case