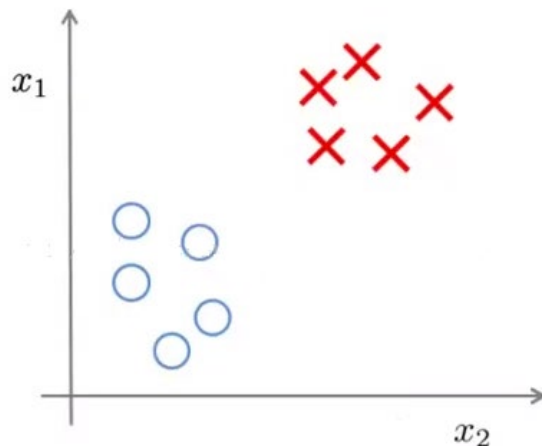


Chapter 11 Clustering

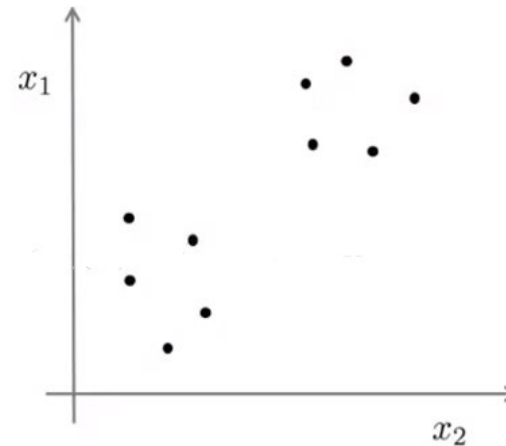
- Definition
- Distance Calculation
- Algorithms
 - K-means
 - Mixture of Gaussian
 - DBSCAN
 - AGNES
- Performance Measure

Definition

- Supervised learning VS. Unsupervised learning
- In supervised learning, we know something(label or value) about data($X=\{x_1, \dots, x_n\}$, $Y=\{y_1, \dots, y_n\}$ known), learn $y = f(x)$
- In unsupervised learning, we know nothing about the data(X known, Y unknown).



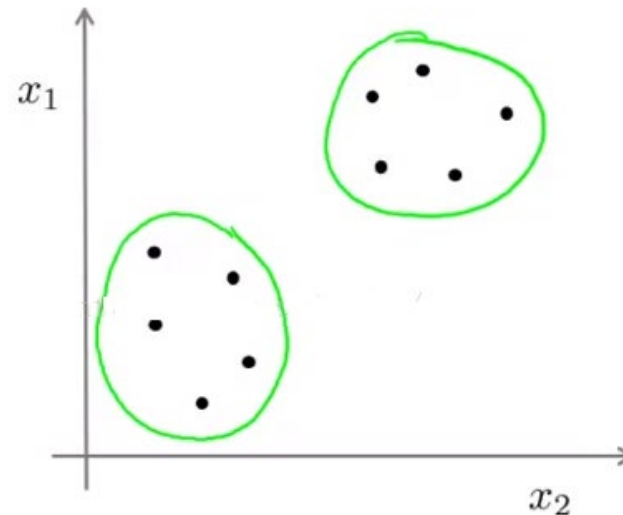
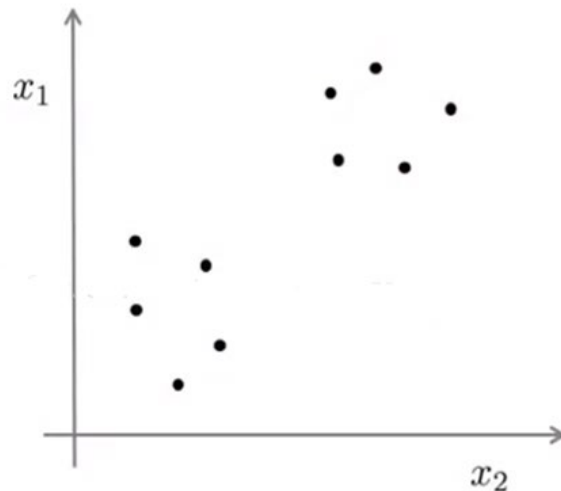
Supervised Learning



Unsupervised Learning

Definition

- Clustering is the task of grouping a set of objects in such a way that objects in the same group(**intra-group**) are **more similar** to each other than to those in other groups(**inter-group**) .



Distance Calculation

■ Minkowski distance

$$dist_{mk}(x_i, x_j) = \left(\sum_{u=1}^n |x_{iu} - x_{ju}|^p \right)^{\frac{1}{p}}$$

$$x_i = (x_{i1}; x_{i2}; \dots x_{in}), x_j = (x_{j1} \ x_{j2}; \dots x_{jn})$$

■ Euclidean distance (p=2)

■ Manhattan distance (p=1)

$x_1 = [2, 1]$	Manhattan distance	$d = (2-3 ^1 + 1-3 ^1)^1 = 3$
$x_2 = [3, 3]$	Euclidean distance	$d = (2-3 ^2 + 1-3 ^2)^{1/2} = \sqrt{5}$

Other Similarity Metrics

■ Chebyshev Distance $D = \max(|x_1 - x_2|, |y_1 - y_2|)$

■ Cosine
$$\cos(\theta) = \frac{\sum_{i=1}^n (x_i * y_i)}{\sqrt{\sum_{i=1}^n (x_i)^2} * \sqrt{\sum_{i=1}^n (y_i)^2}}$$

■ Hamming Distance $d(x, y) = \sum X[i] \oplus Y[i]$

■ Jaccard Distance
$$\frac{|A \cup B| - |A \cap B|}{|A \cup B|}$$

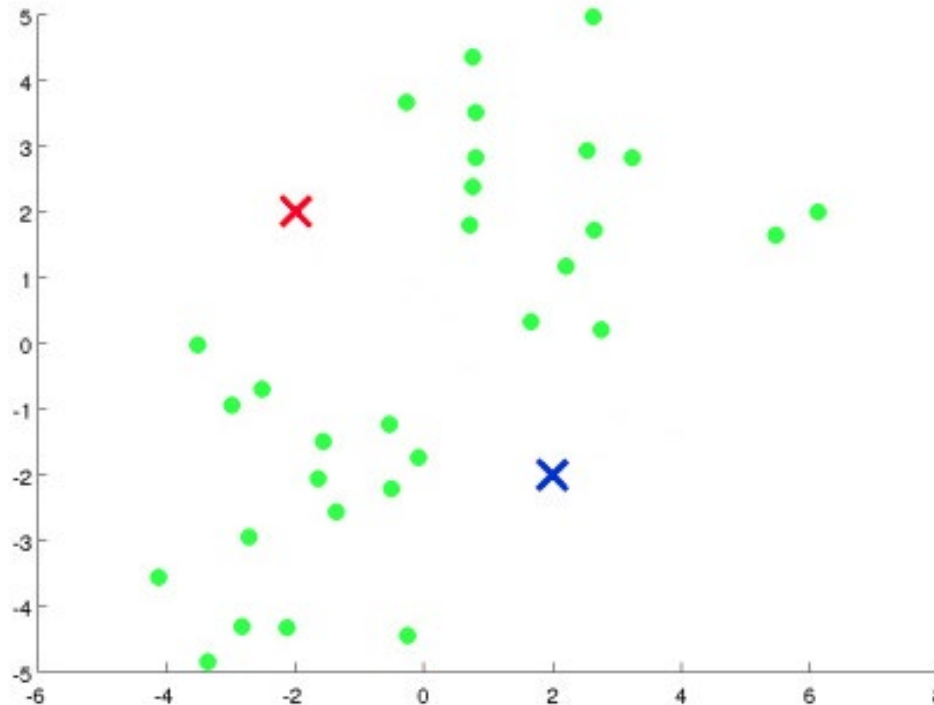
■ Correlation coefficient and Correlation distance

Algorithm--K-means

- Randomly select **K** samples as the centroids of clustering.
- Calculate the distances of each sample from the **K** centroid points.
- Select the cluster centroid c_i ($i = 1, 2 \dots K$) with the **smallest distance** to divide the cluster.
- Re-determine the centroids.
- **Iterate** until it converges.

K-means

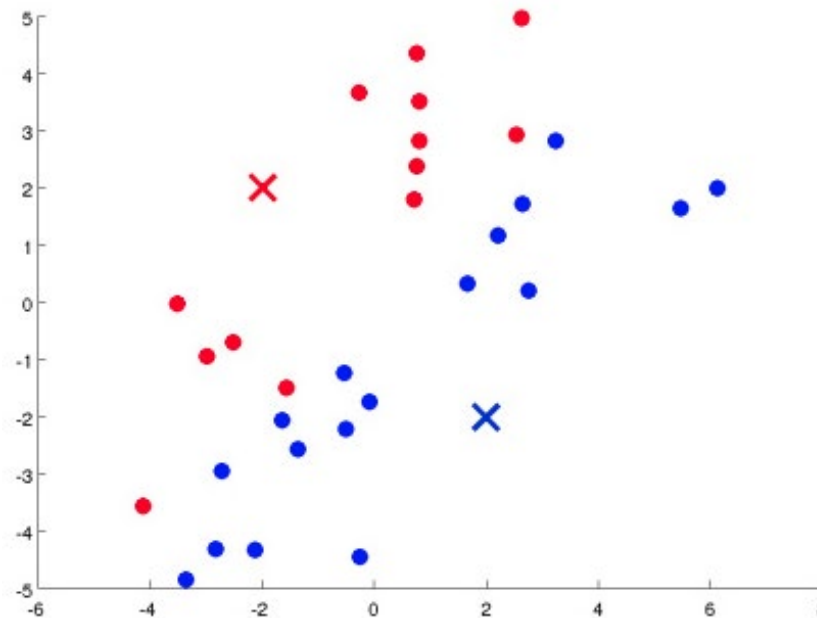
- By experience, set $k=2$.
- Randomly select two points as cluster centroids.



K-means

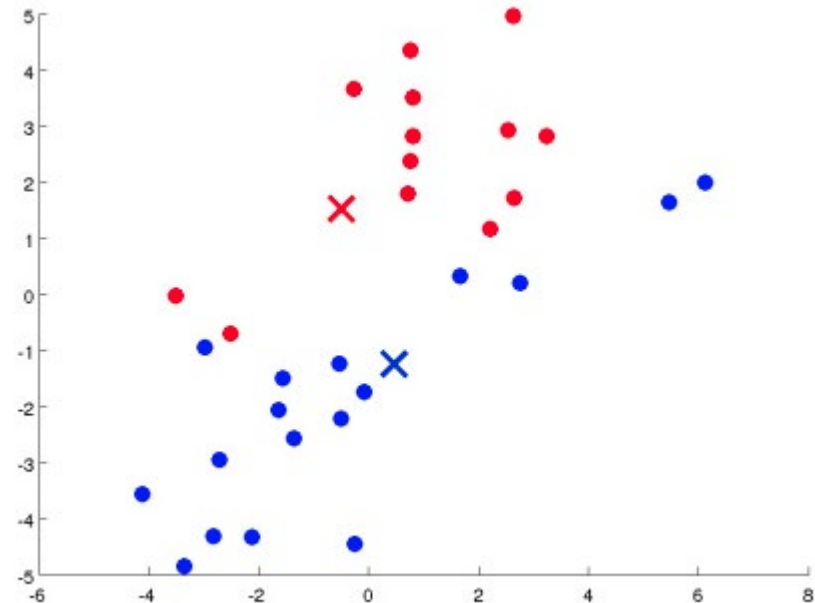
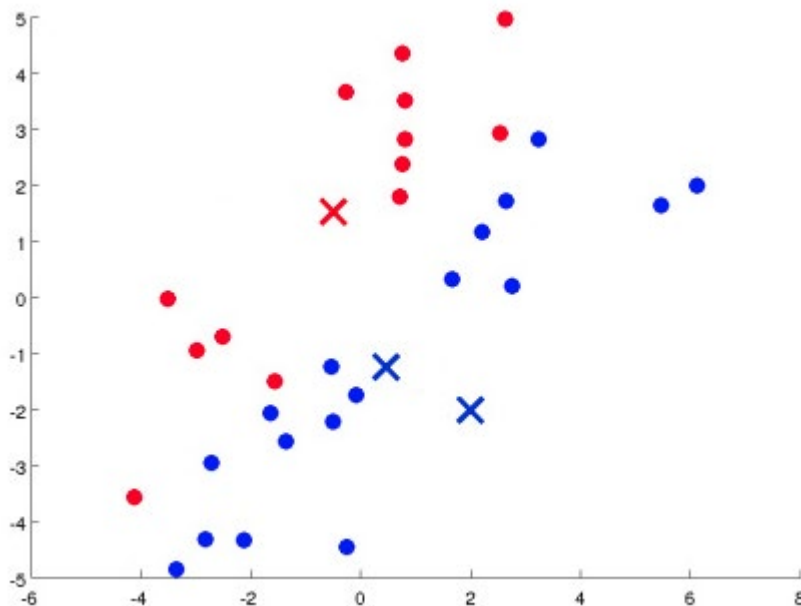
- For all green samples, compute distances from the blue point and red point.
- Choose the smallest distance and assign it to one cluster.

簇划分



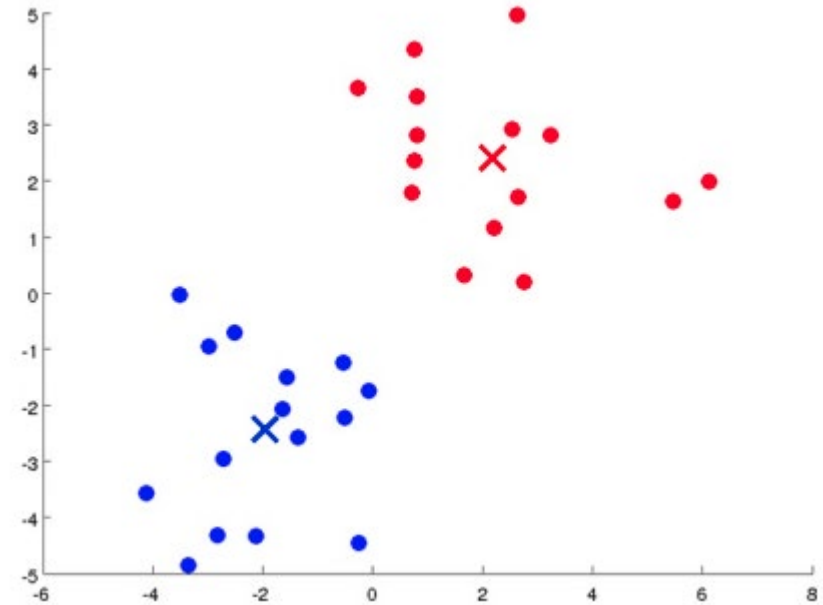
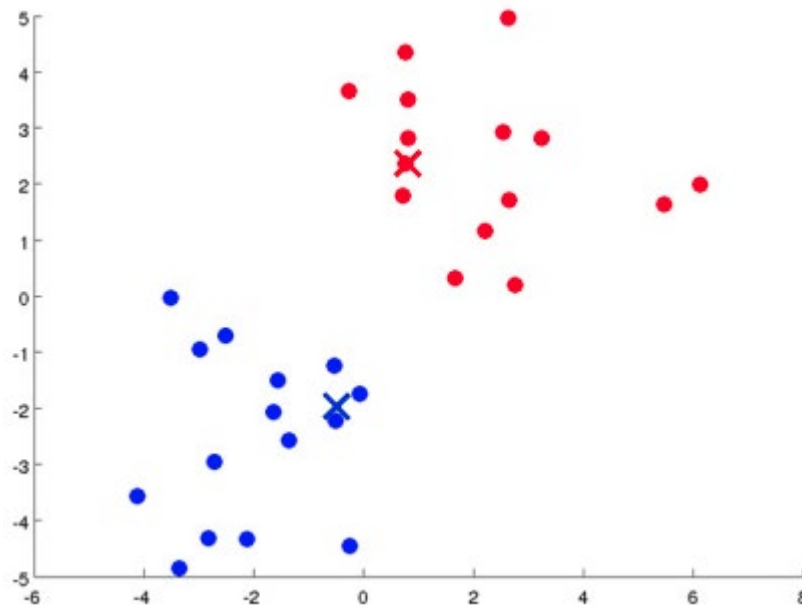
K-means

- Compute the average for two clusters.
- Re-determine cluster centroids.



K-means

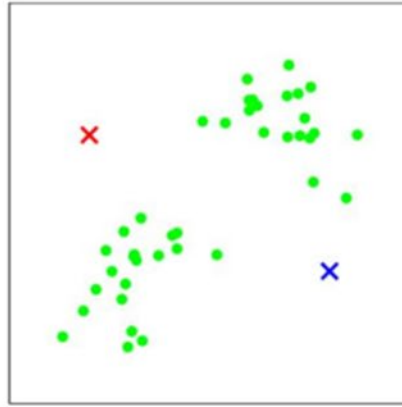
- Iterate until convergence (the cluster centroids will not change).



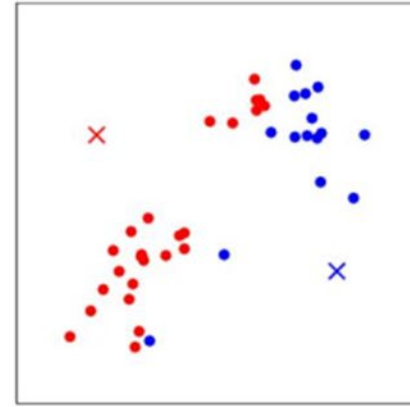
K-means



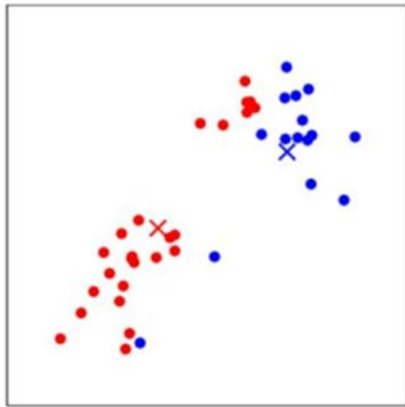
(a)



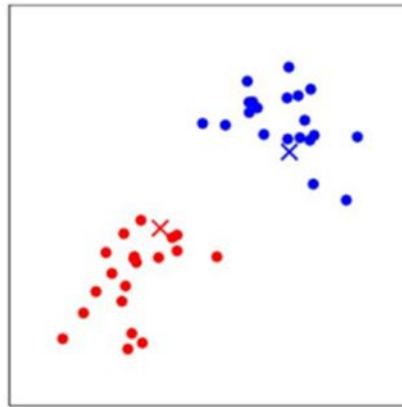
(b)



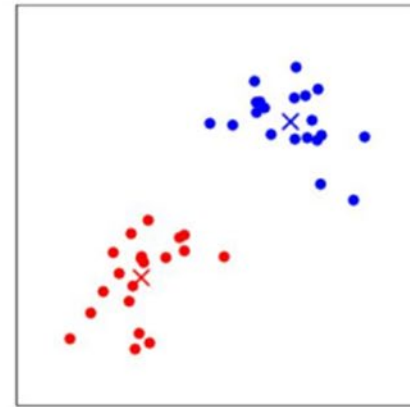
(c)



(d)



(e)



(f)

K-means

输入: 样本集 $D = \{x_1, x_2, \dots, x_m\}$;
聚类簇数 k .

过程:

```
1: 从  $D$  中随机选择  $k$  个样本作为初始均值向量  $\{\mu_1, \mu_2, \dots, \mu_k\}$ 
2: repeat
3:   令  $C_i = \emptyset$  ( $1 \leq i \leq k$ )
4:   for  $j = 1, \dots, m$  do
5:     计算样本  $x_j$  与各均值向量  $\mu_i$  ( $1 \leq i \leq k$ ) 的距离
6:     根据距离最近的均值向量确定  $x_j$  的簇标记:
7:     将样本  $x_j$  划入相应的簇:  $C_{\lambda_j} = C_{\lambda_j} \cup \{x_j\}$ ;
8:   end for
9:   for  $i = 1, \dots, k$  do
10:    计算新均值向量:  $\mu'_i = \frac{1}{|C_i|} \sum_{x \in C_i} x$ ;
11:    if  $\mu'_i \neq \mu_i$  then
12:      将当前均值向量  $\mu_i$  更新为  $\mu'_i$ 
13:    else
14:      保持当前均值向量不变
15:    end if
16:  end for
17: until 当前均值向量均未更新
18: return 簇划分结果
```

输出: 簇划分 $\mathcal{C} = \{C_1, C_2, \dots, C_k\}$

簇划分

移动
聚类中心

- Are the results with different random initialization same?
- How to choose K ?

- We need all possible initializations and get the best result.
- The measure to find the best result is **minimizing square error E(SSE, sum of the Squared Error)**.

$$E = \sum_{i=1}^k \sum_{x \in C_i} \|x - u_i\|_2^2$$

$$E = \sum_{i=1}^m \|x_i - u_{\lambda_i}\|_2^2$$

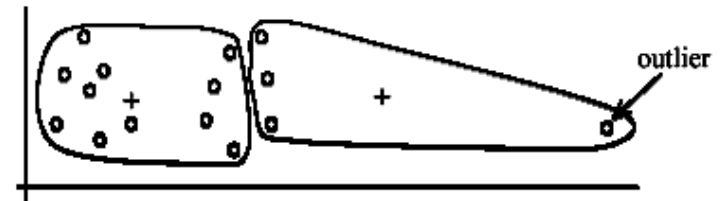
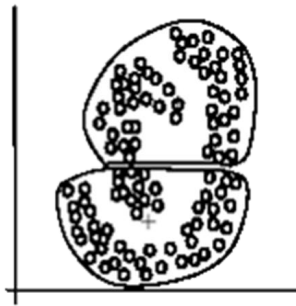
$$u_i = \frac{1}{|C_i|} \sum_{x \in C_i} x$$

□ How to initialize

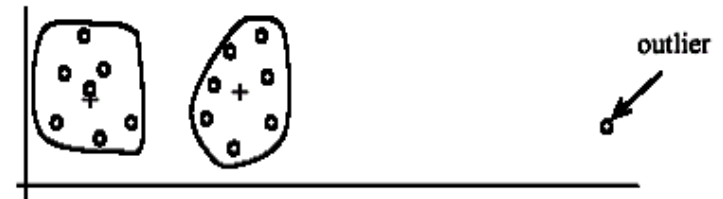
- It is **NP-Hard** to minimizing E.
- K-means uses an **iterative optimal** algorithm. Each step of every iteration is the process of optimizing E.
- We can choose multiple initializations to get the best result(**Attention: Whether this measure is effective depends on k**).

K-means

- K-means is not always suitable.



(A): Undesirable clusters



(B): Ideal clusters

- Gaussian mixture distribution

$$\begin{aligned} p(\mathbf{x}) &= \sum_{k=1}^K p(k)p(\mathbf{x}|k) \\ &= \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}|\mu_k, \Sigma_k) \end{aligned}$$

- μ_i, Σ_i : mean vector and covariance matrix of i_{th} mixed component
- π_k : corresponding mixture coefficient

- Objective function:

$$\sum_{i=1}^N \log \left\{ \sum_{k=1}^K \pi_k \mathcal{N}(x_i | \mu_k, \Sigma_k) \right\}$$

- Then, we use MLE(Maximum likelihood estimate) to optimize function.

- 估计数据由每个 Component 生成的概率（并不是每个 Component 被选中的概率）：对于每个数据 x_i 来说，它由第 k 个 Component 生成的概率为

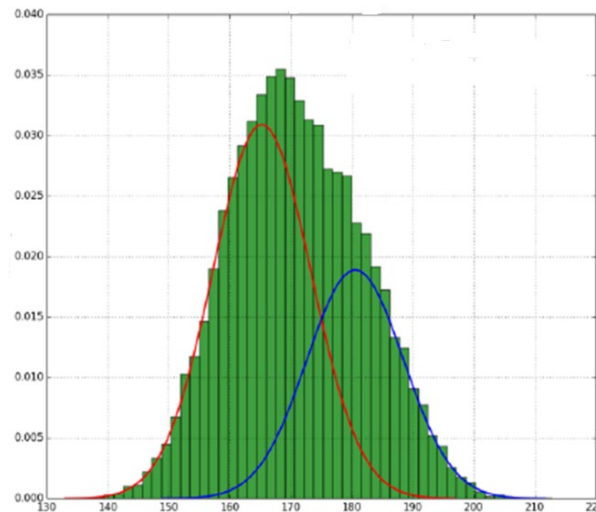
$$\gamma(i, k) = \frac{\pi_k \mathcal{N}(x_i | \mu_k, \Sigma_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(x_i | \mu_j, \Sigma_j)}$$

- 估计每个 Component 的参数

$$\mu_k = \frac{1}{N_k} \sum_{i=1}^N \gamma(i, k) x_i$$
$$\Sigma_k = \frac{1}{N_k} \sum_{i=1}^N \gamma(i, k) (x_i - \mu_k)(x_i - \mu_k)^T$$

Mixture of Gaussian

- Suppose we have 100 students and the only data we can get is their height. Try to model the distribution of male and female.
- The height obeys Gaussian distribution.



Mixture of Gaussian

先假定男生服从参数为 $\sim N(180, 10)$ 的高斯分布，女生服从参数为 $\sim N(160, 8)$ 的高斯分布(Assume a determined Gaussian model for boys and girls)

- 对每个样本计算出分别属于男生和女生的概率(Compute the probability that clustering each sample to boys and girls)
- 认定：每个样本分属于男生和女生的部分（即概率，用 $\gamma(i, k)$ 表示，即第 i 个样本属于第 k 个类别的概率）同样服从高斯分布，且具有更好的拟合属性。(如一个样本身高175，我们可以通过设定的参数计算出他有80%的概率为男生，20%的概率为女生，那可以把这个样本看作由80%的男生和20%的女生组成，并将这个样本看作是一个80%的男生样本和一个20%的女生样本。)(Divide each sample into two components according to the probability in step 2)
- 根据每个样本的男生组分和女生组分拟合出新的高斯模型。(Update the parameters according to the components in step 3)
- 迭代直到收敛。(Iterating these steps until convergence)

Mixture of Gaussian

输入: 样本集 $D = \{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_m\}$;
高斯混合成分个数 k .

过程:

1: 初始化高斯混合分布的模型参数 $\{(\alpha_i, \boldsymbol{\mu}_i, \boldsymbol{\Sigma}_i) \mid 1 \leq i \leq k\}$

2: **repeat**

3: **for** $j = 1, \dots, m$ **do**

4: 根据(9.30)计算 \mathbf{x}_j 由各混合成分生成的后验概率, 即
 $\gamma_{ji} = p_{\mathcal{M}}(z_j = i \mid \mathbf{x}_j) \ (1 \leq i \leq k)$

5: **end for**

6: **for** $i = 1, \dots, k$ **do**

7: 计算新均值向量: $\boldsymbol{\mu}'_i = \frac{\sum_{j=1}^m \gamma_{ji} \mathbf{x}_j}{\sum_{j=1}^m \gamma_{ji}};$

8: 计算新协方差矩阵: $\boldsymbol{\Sigma}'_i = \frac{\sum_{j=1}^m \gamma_{ji} (\mathbf{x}_j - \boldsymbol{\mu}'_i)(\mathbf{x}_j - \boldsymbol{\mu}'_i)^\top}{\sum_{j=1}^m \gamma_{ji}};$

9: 计算新混合系数: $\alpha'_i = \frac{\sum_{j=1}^m \gamma_{ji}}{m};$

10: **end for**

11: 将模型参数 $\{(\alpha_i, \boldsymbol{\mu}_i, \boldsymbol{\Sigma}_i) \mid 1 \leq i \leq k\}$ 更新为 $\{(\alpha'_i, \boldsymbol{\mu}'_i, \boldsymbol{\Sigma}'_i) \mid 1 \leq i \leq k\}$

12: **until** 满足停止条件

13: $C_i = \emptyset \ (1 \leq i \leq k)$

14: **for** $j = 1, \dots, m$ **do**

15: 根据(9.31)确定 \mathbf{x}_j 的簇标记 λ_j ;

16: 将 \mathbf{x}_j 划入相应的簇: $C_{\lambda_j} = C_{\lambda_j} \cup \{\mathbf{x}_j\}$

17: **end for**

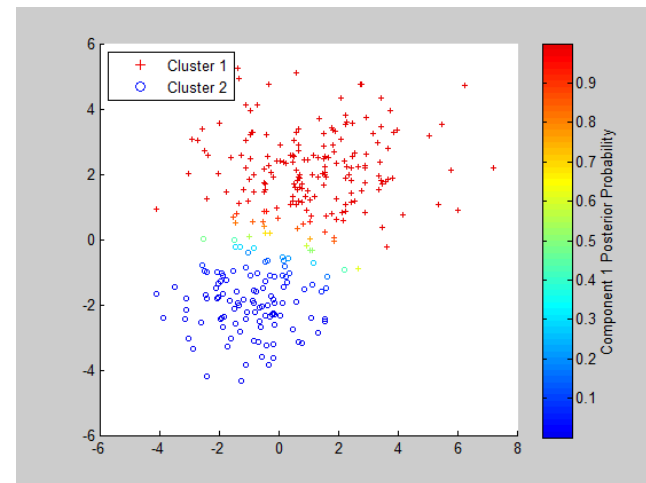
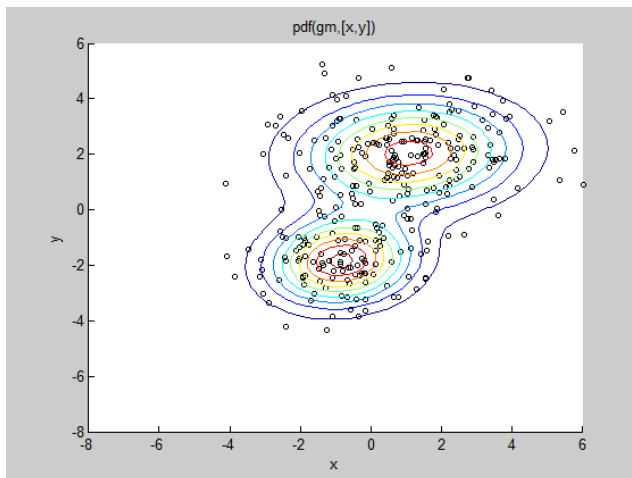
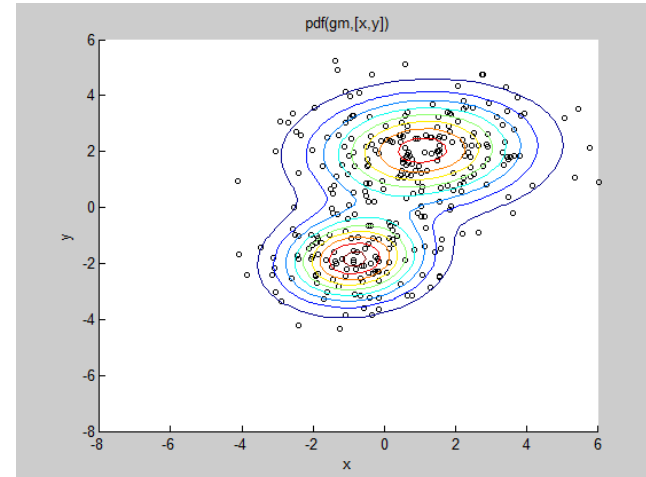
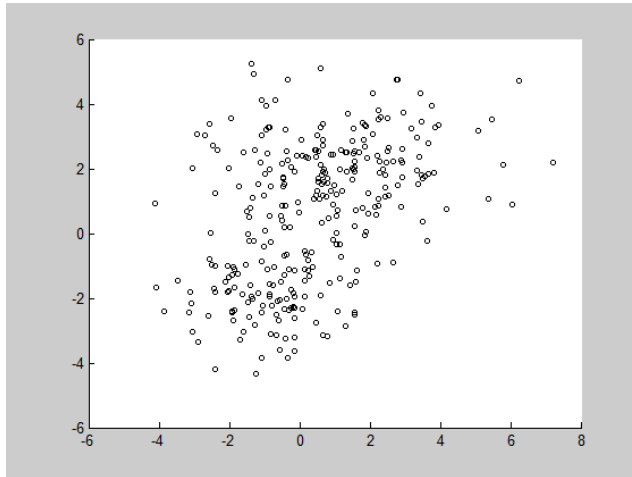
18: **return** 簇划分结果

输出: 簇划分 $\mathcal{C} = \{C_1, C_2, \dots, C_k\}$

固定模型参数
更新后验概率

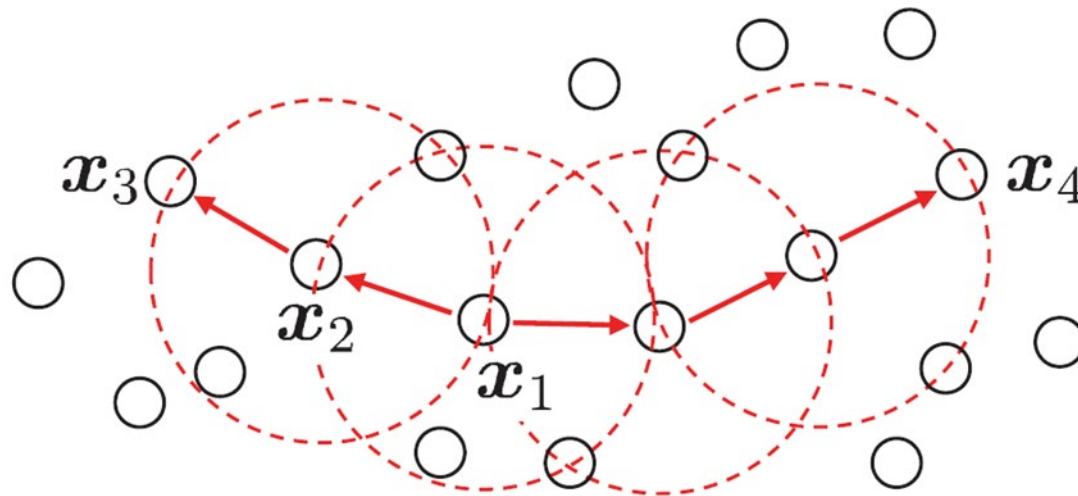
固定后验概率
更新模型参数

Mixture of Gaussian

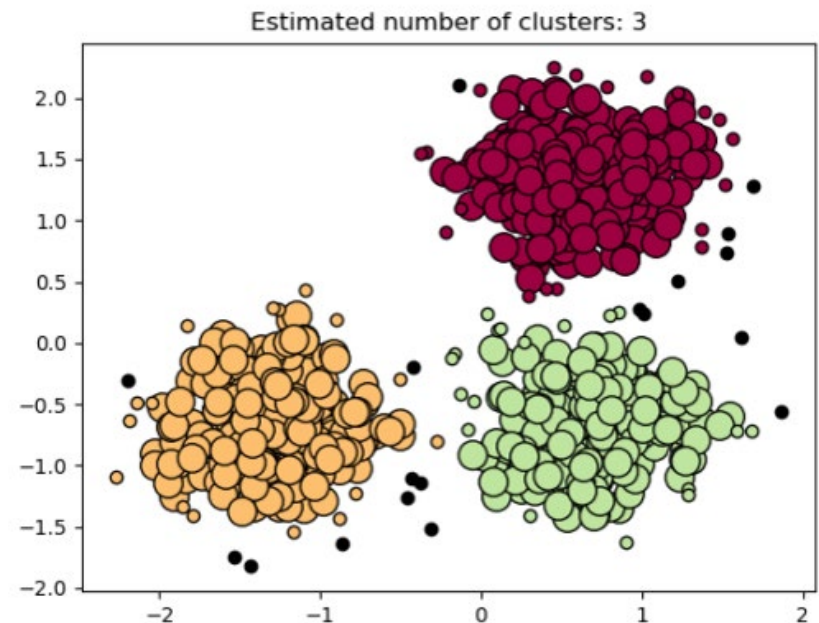
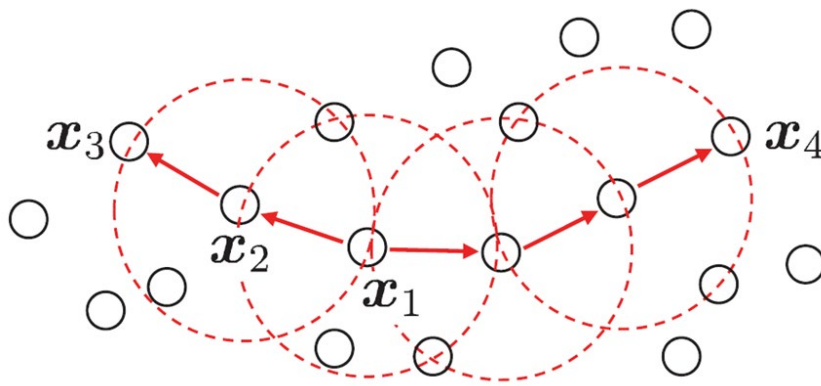


- It is a famous **density-based-clustering**.
- ϵ -neighborhood: $N_\epsilon(x_j) = \{x_i \in D \mid \text{dist}(x_i, x_j) \leq \epsilon\}$ of the point x_j
- core object : a point with a $|N_\epsilon(x_j)| \geq \text{MinPts}$
- Directly density-reached: x_j is directly density-reachable from a core object x_i if x_j is in $N_\epsilon(x_i)$
- Density-reached: x_j is density-reachable from a core object x_i if a sequence of core objects p_1, p_2, \dots, p_n between x_i and x_j exists and p_{i+1} is directly density-reached from p_i .
- Density-connected: x_i and x_j are density-connected if they are density-reachable from a common core object x_k .

- Directly density-reached: x_2 from x_1
- Density-reached: x_3 from x_1
- Density-connected: x_4 from x_3



- DBSCAN defines cluster as such sample set which is **most density-connected**.



找出所有核心对象

随机选一个核心对象生长出一个簇，并在核心对象集合里删去该核心对象

```

输入: 样本集  $D = \{x_1, x_2, \dots, x_m\}$ ;
      邻域参数  $(\epsilon, MinPts)$ .

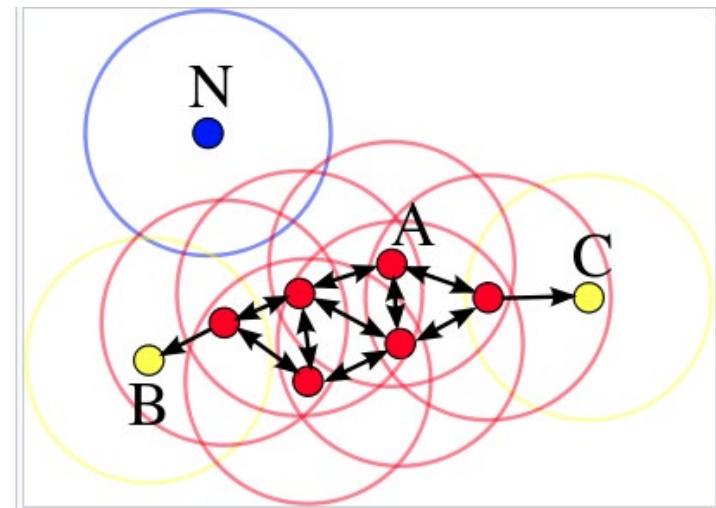
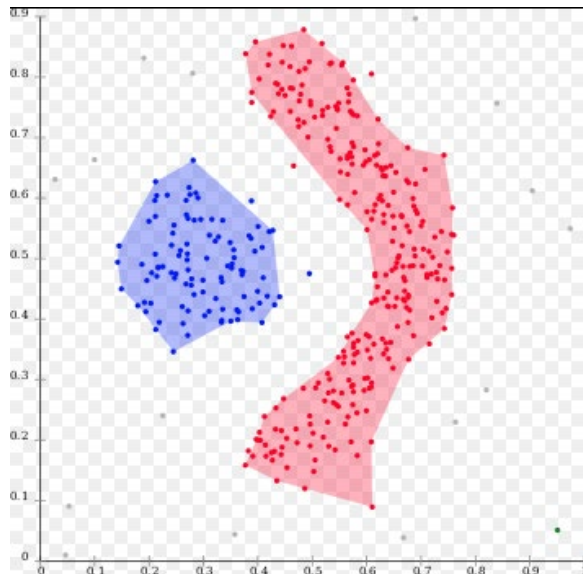
过程:
1: 初始化核心对象集合:  $\Omega = \emptyset$ 
2: for  $j = 1, \dots, m$  do
3:   确定样本  $x_j$  的  $\epsilon$ -邻域  $N_\epsilon(x_j)$ ;
4:   if  $|N_\epsilon(x_j)| \geq MinPts$  then
5:     将样本  $x_j$  加入核心对象集合:  $\Omega = \Omega \cup \{x_j\}$ 
6:   end if
7: end for
8: 初始化聚类簇数:  $k = 0$ 
9: 初始化未访问样本集合:  $\Gamma = D$ 
10: while  $\Omega \neq \emptyset$  do
11:   记录当前未访问样本集合:  $\Gamma_{old} = \Gamma$ ;
12:   随机选取一个核心对象  $o \in \Omega$ , 初始化队列  $Q = \langle o \rangle$ ;
13:    $\Gamma = \Gamma \setminus \{o\}$ ;
14:   while  $Q \neq \emptyset$  do
15:     取出队列  $Q$  中的首个样本  $q$ ;
16:     if  $|N_\epsilon(q)| \geq MinPts$  then
17:       令  $\Delta = N_\epsilon(q) \cap \Gamma$ ;
18:       将  $\Delta$  中的样本加入队列  $Q$ ;
19:        $\Gamma = \Gamma \setminus \Delta$ ;
20:     end if
21:   end while
22:    $k = k + 1$ , 生成聚类簇  $C_k = \Gamma_{old} \setminus \Gamma$ ;
23:    $\Omega = \Omega \setminus C_k$ 
24: end while
25: return 簇划分结果

输出: 簇划分  $\mathcal{C} = \{C_1, C_2, \dots, C_k\}$ 

```

■ Strengths

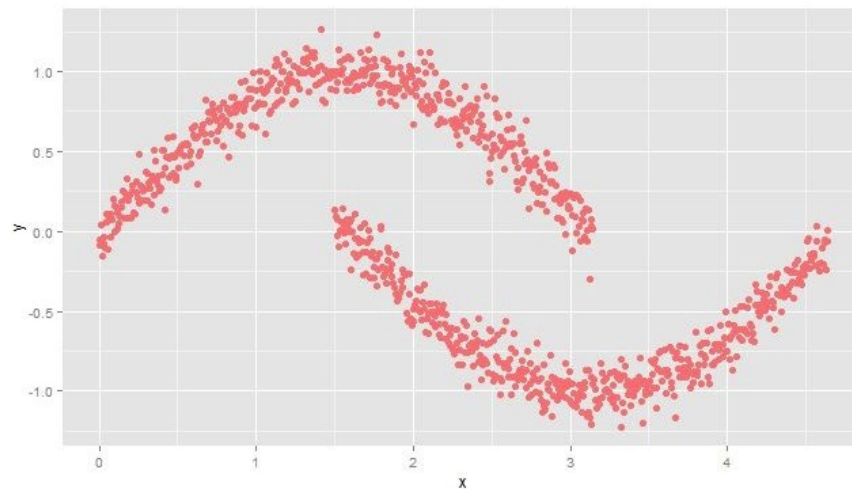
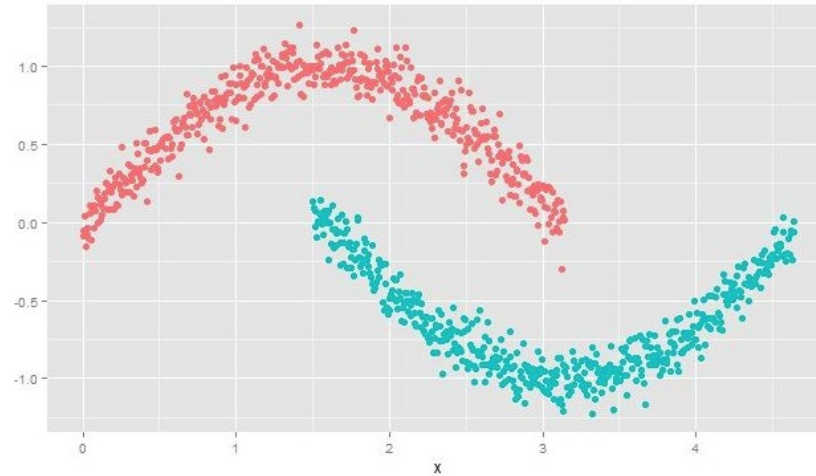
- There is no K.
- It can discover **any shape** of spatial clustering.
- It can discard the remote point.



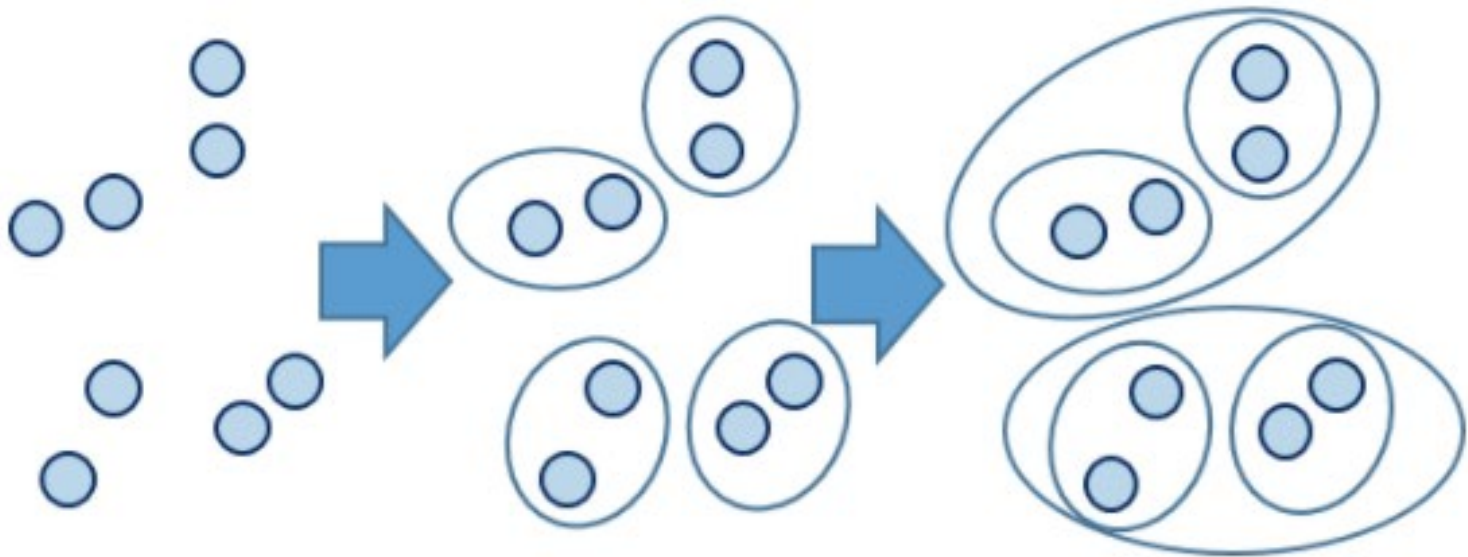
■ Weaknesses

- It is not suitable when the cluster spacing difference is very different.
- Parameters adjustment are more complicated.



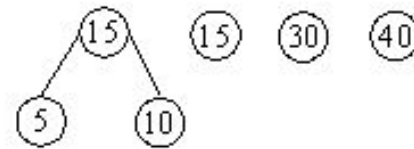


- AGNES is a kind of Hierarchical clustering

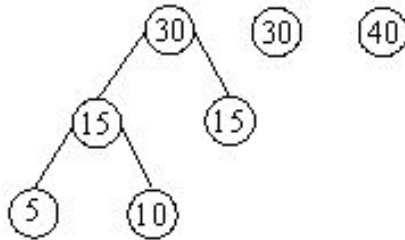




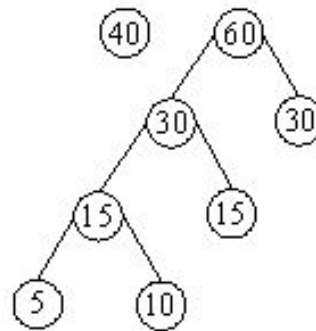
(a) 第一步



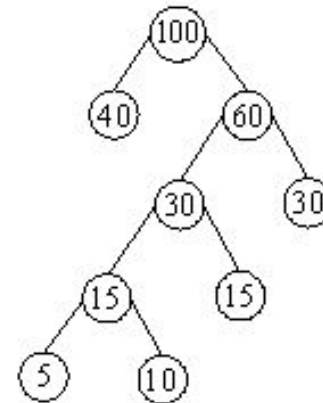
(b) 第二步



(c) 第三步



(d) 第四步



(e) 第五步

- Given cluster C_i, C_j , Usually the **distance** between two clusters is one of the following
 - Maximum distance(also called **complete-linkage** clustering)
$$dist_{max}(C_i, C_j) = \max_{x \in C_i, z \in C_j} dist(x, z)$$
 - Minimum distance(also called **single-linkage** clustering)
$$dist_{min}(C_i, C_j) = \min_{x \in C_i, z \in C_j} dist(x, z)$$
 - Average distance (also called **average-linkage** clustering)

$$dist_{avg}(C_i, C_j) = \frac{1}{|C_i||C_j|} \sum_{x \in C_i} \sum_{z \in C_j} dist(x, z)$$

输入: 样本集 $D = \{x_1, x_2, \dots, x_m\}$;
 聚类簇距离度量函数 $d \in \{d_{\min}, d_{\max}, d_{\text{avg}}\}$;
 聚类簇数 k .

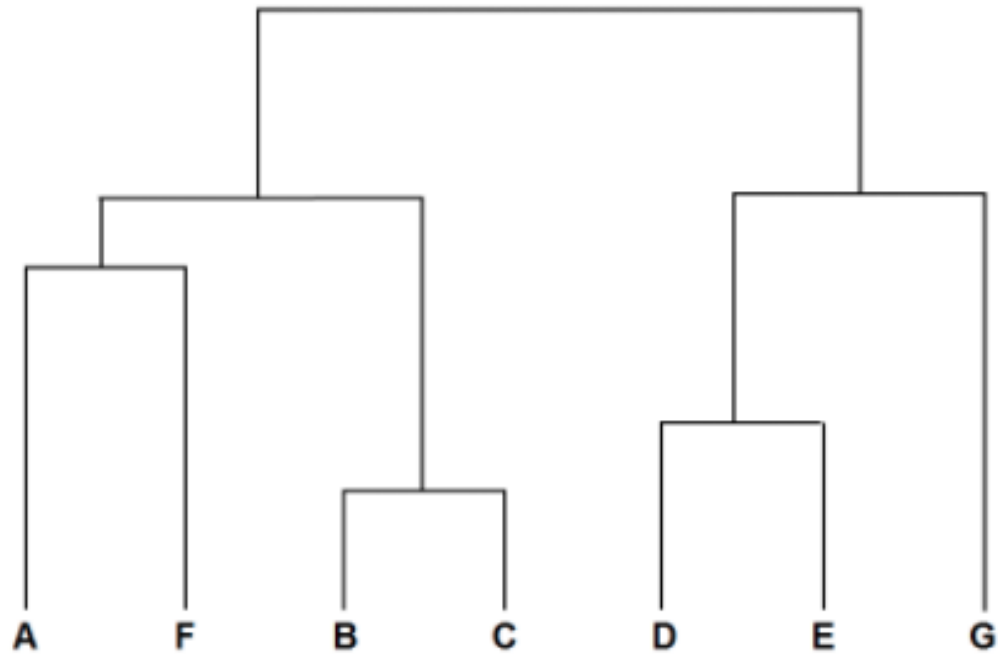
过程:

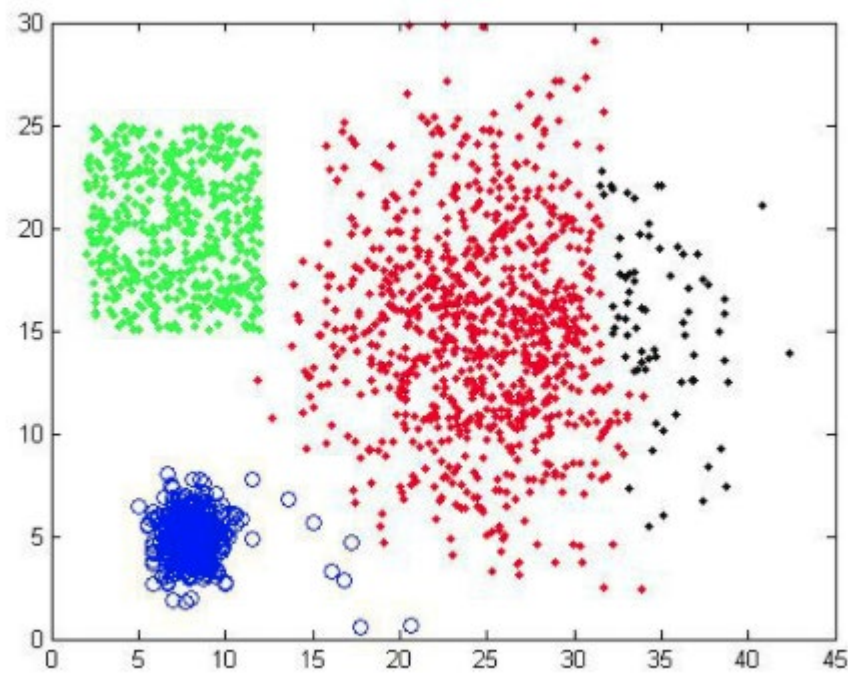
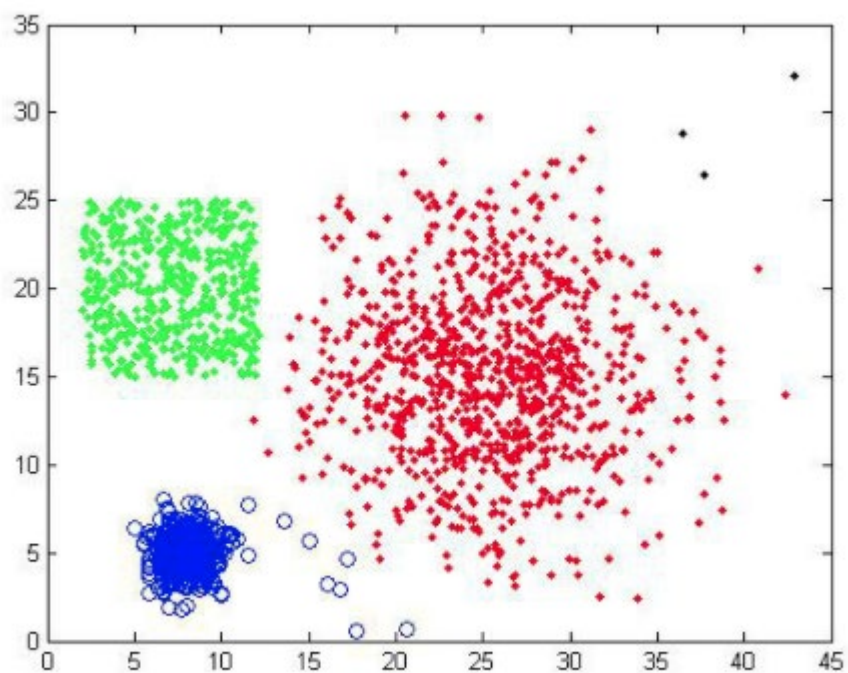
```

1: for  $j = 1, \dots, m$  do
2:    $C_j = \{x_j\}$ 
3: end for
4: for  $i = 1, \dots, m$  do
5:   for  $j = i, \dots, m$  do
6:      $M(i, j) = d(C_i, C_j)$ ;
7:      $M(j, i) = M(i, j)$ 
8:   end for
9: end for
10: 设置当前聚类簇个数:  $q = m$ 
11: while  $q > k$  do
12:   找出距离最近的两个聚类簇  $(C_{i^*}, C_{j^*})$ ;
13:   合并  $(C_{i^*}, C_{j^*})$ :  $C_{i^*} = C_{i^*} \cup C_{j^*}$ ;
14:   for  $j = j^* + 1, \dots, q$  do
15:     将聚类簇  $C_j$  重编号为  $C_{j-1}$ 
16:   end for
17:   删除距离矩阵  $M$  的第  $j^*$  行与第  $j^*$  列;
18:   for  $j = 1, \dots, q - 1$  do
19:      $M(i^*, j) = d(C_{i^*}, C_j)$ ;
20:      $M(j, i^*) = M(i^*, j)$ 
21:   end for
22:    $q = q - 1$ 
23: end while
24: return 簇划分结果
输出: 簇划分  $C = \{C_1, C_2, \dots, C_k\}$ 
    
```

计算距离矩阵

每次循环合并
两个簇并更新
距离矩阵





- Partitioning Methods
 - k-means, k-medoids, CLARANS, FCM
- Hierarchical Methods
 - AGNES, Birch, Cure, Rock, CHEMALOEN
- Density-based Methods
 - DBSCAN, OPTICS
- Grid-based Methods
- Model-Based Methods
 - Transitive closure, Boolean matrix, direct clustering, correlation analysis clustering, clustering method based on statistics.....

- Good clustering should be:

Intra-cluster similarity \Rightarrow maximized

Inter-cluster similarity \Rightarrow minimized

Intra distance & Inter distance

Intra distance {
$$agv(C) = \frac{2}{|C|(|C| - 1)} \sum_{1 \leq i \leq j \leq |C|} dist(x_i, x_j)$$

$$diam(C) = \max_{1 \leq i \leq j \leq |C|} dist(x_i, x_j)$$

Inter distance {
$$d_{min}(C_i, C_j) = \min_{x_i \in C_i, x_j \in C_j} dist(x_i, x_j)$$

$$d_{cen}(C_i, C_j) = dis(\mu_i, \mu_j)$$

- Internal Index
 - Evaluate clustering results directly **without using reference model.**

- External Index
 - Compare clustering results **with reference model**, for example, partitioning results given by domain expert.

■ Davies-Boukdin Index:

The smaller the better

$$DBI = \frac{1}{k} \sum_{i=1}^k \max_{j \neq i} \left(\frac{avg(C_i) + avg(C_j)}{d_{cen}(C_i, C_j)} \right)$$

■ Dunn Index:

The bigger the better

$$DI = \min_{1 \leq i \leq k} \left\{ \min_{j \neq i} \frac{d_{min}(C_i, C_j)}{\max_{1 \leq l \leq k} diam(C_l)} \right\}$$

- Assume our cluster partition is

- $C = \{C_1, C_2, \dots, C_k\}$

- The partition given by reference model is

- $C^* = \{C_1^*, C_2^*, \dots, C_s^*\}$

- let λ and λ^* be clustering label vectors corresponding to

- C and C^* . Consider C_m^2 sample pairs



$$a = |SS|, SS = \{(x_i, x_j) | \lambda_i = \lambda_j, \lambda_i^* = \lambda_j^*, i < j\}$$

$$b = |SD|, SS = \{(x_i, x_j) | \lambda_i = \lambda_j, \lambda_i^* \neq \lambda_j^*, i < j\}$$

$$c = |DS|, SS = \{(x_i, x_j) | \lambda_i \neq \lambda_j, \lambda_i^* = \lambda_j^*, i < j\}$$

$$d = |DD|, SS = \{(x_i, x_j) | \lambda_i \neq \lambda_j, \lambda_i^* \neq \lambda_j^*, i < j\}$$

$$a + b + c + d = C_m^2 = m(m-1)/2$$

- JC: Jaccard Coefficient

$$JC = \frac{a}{a + b + c}$$

- FMI: Fowlkes and Mallows Index

$$FMI = \sqrt{\frac{a}{a + b} \cdot \frac{a}{a + c}}$$

- RI: Rand Index

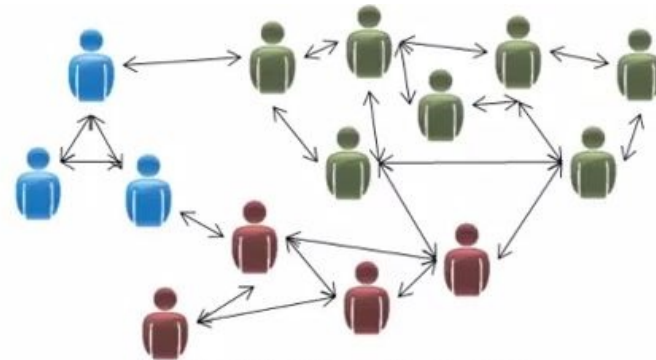
$$RI = \frac{2(a + d)}{m(m - 1)}$$

[0,1] interval
the bigger
the better

Applications



Organize computing clusters



Social network analysis



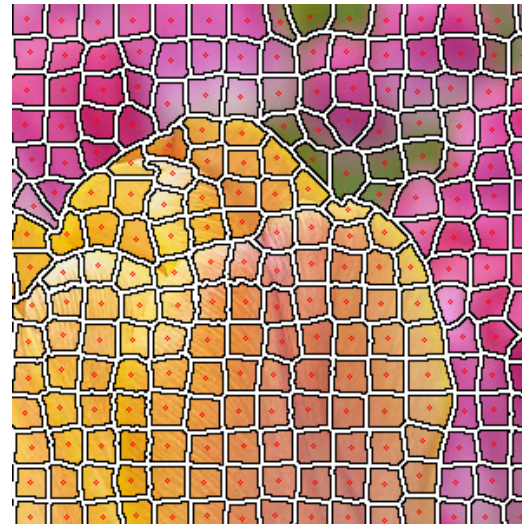
Market segmentation



Astronomical data analysis

An Example

- **Supapixel segmentation** uses the similarity of features between pixels to group pixels, and replaces a large number of pixels with a small number of superpixels to express image features.



[Thank You !]

Any Question?