

Ychen Zhu

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Master Student - ShanghaiTech University

RESEARCH INTEREST

My current research interests include 1. Spatial Intelligence, 2. Multimodal Large Language Models (LLM/MLLM), 3. Open-world Visual Understanding. Currently, I am focusing on equipping multimodal large language models with spatial reasoning abilities, particularly in 3D scene understanding, embodied navigation, and object grounding.

PUBLICATIONS

• Rethinking Query-based Transformer for Continual Image Segmentation

Yuchen Zhu*, Cheng Shi*, Dingyou Wang, Jiajin Tang, Zhengxuan Wei, Yu Wu, Guanbin Li, Sibe Yang[†]

◦ Accepted by IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR) 2025

◦ We revisit query-based transformers from a continual learning perspective and propose a novel framework for continual image segmentation, enhancing model plasticity and mitigating catastrophic forgetting.

◦ Code and models released for reproducibility: [SimCIS](#)

• Plain-Det: A Plain Multi-Dataset Object Detector

Cheng Shi*, Yuchen Zhu*, Sibe Yang[†]

◦ Accepted by European Conference on Computer Vision (ECCV) 2024

◦ We propose Plain-Det, a simplified end-to-end object detector designed to scale with both dataset size and diversity. Plain-Det leverages CLIP priors to resolve label conflicts and employs dynamic sampling strategies to handle joint training over datasets with varying sizes. Furthermore, it performs de-biasing on text embeddings to enhance classification accuracy. As the dataset scales up, Plain-Det effectively scales up in capability.

◦ Code and models released for reproducibility: [Plain-Det](#)

• Sim-DETR: Unlock DETR for Temporal Sentence Grounding

Jiajin Tang*, Zhengxuan Wei*, Yuchen Zhu, Cheng Shi, Guanbin Li, Liang Lin, Sibe Yang[†]

◦ Accepted by International Conference on Computer Vision (ICCV) 2025

◦ We propose Sim-DETR, which resolves DETR's query conflicts in temporal sentence grounding via self-attention adjustments and query-frame alignment, unlocking superior performance and faster convergence.

• Unified Mitigation of LVLM Hallucinations across Alignment Formats

Jiaye Qian*, Ge Zheng*, Yuchen Zhu, Sibe Yang[†]

◦ In Submission

EDUCATION

• ShanghaiTech University

Master of Computer Science

◦ GPA: 3.33/4.00 (Major GPA: 3.45/4.00)

Sep. 2023 - Now

Shanghai, China

• Nanjing Institute of Technology

B.Eng. in Automation

◦ Major Courses: Automatic Control, Microprocessors, Digital Electronic Technology, Mechanics ...

◦ Grade: 3.1/4.0

Sep. 2018 - June 2022

Nanjing, China

PROJECTS

• Undergraduate Thesis: Design of a Two-Wheeled Self-Balancing Vehicle Based on STM32

2022

C++, Stm32, PID Control, Keil, MPU6050, PWM, Embedded Systems

◦ Hardware: A two-wheeled self-balancing vehicle built around STM32F103C8T6, MPU6050, TB6612 and ultrasonic sensors, with complete circuit and mechanical design.

◦ Software & Control: Cascade PID enables dynamic balance, velocity tracking, straight-line driving and autonomous obstacle avoidance.

• Undergraduate Course Project: keyword recommendation multi-task IO server

2021

C++, Linux, TCP/IP

◦ Designed and implemented a multi-task I/O keyword recommendation server using the Reactor framework and thread pool. The server processes client queries by retrieving and ranking similar words from a combined Chinese-English dictionary using edit distance, cppjieba segmentation, and LRU-based caching for optimized performance.

HONORS AND AWARDS

• ShanghaiTech Outstanding Student

Dec. 2024

• CET-6 certificate

Dec. 2019

• Scholarship awarded by the School of Automation

Dec. 2018, 2019