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CONST robtarget Target_10:=[ [402.75,-50,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E
+09,9E+09,9E+09]];
CONST robtarget Target_20:=[ [402.75,44.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
CONST robtarget Target_30:=[ [447.25,44.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
CONST robtarget Target_40:=[ [447.25,-50,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E
+09,9E+09,9E+09]];
CONST robtarget Target_50:=[ [408.25,-50,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E
+09,9E+09,9E+09]];
CONST robtarget Target_60:=[ [402.75,-50,-382],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E
+09,9E+09,9E+09]];
CONST robtarget Target_70:=[ [402.75,44.5,-382],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
CONST robtarget Target_80:=[ [447.25,44.5,-382],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
CONST robtarget Target_90:=[ [447.25,-50,-382],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E
+09,9E+09,9E+09]];
CONST robtarget Target_100:=[ [408.25,-50,-382],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
CONST robtarget Target_110:=[ [402.75,-50,-377],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
CONST robtarget Target_120:=[ [402.75,44.5,-377],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
CONST robtarget Target_130:=[ [447.25,44.5,-377],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
CONST robtarget Target_140:=[ [447.25,-50,-377],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
CONST robtarget Target_150:=[ [408.25,-50,-377],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
CONST robtarget Target_160:=[ [402.75,-50,-372],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
CONST robtarget Target_170:=[ [402.75,44.5,-372],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
CONST robtarget Target_180:=[ [447.25,44.5,-372],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
CONST robtarget Target_190:=[ [447.25,-50,-372],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
CONST robtarget Target_200:=[ [408.25,-50,-372],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];

PERS tooldata tExtruder:=[TRUE,[[-92.3257,2.14224,443.917],[1,0,0,0]],[0.5,[0,80,5],
[1,0,0,0],0,0,0]];

PROC Fan_Extruder() !Change this to suit.

MoveJ [[350,0,-300],[0,0,-1,0],[-1,-1,-1,0],[9E+09,9E+09,9E+09,9E+09,9E+09,9E+09]],
v200, z50, tExtruder;
MoveL Target_10,v50,fine,tExtruder\WObj:=wobj0;
Stop;

MoveL Target_20,v40,fine,tExtruder\WObj:=wobj0;
MoveL Target_30,v40,fine,tExtruder\WObj:=wobj0;
MoveL Target_40,v40,fine,tExtruder\WObj:=wobj0;

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MoveL Target_50,v40,fine,tExtruder\WObj:=wobj0;
MoveL Target_60,v40,fine,tExtruder\WObj:=wobj0;
MoveL Target_70,v40,fine,tExtruder\WObj:=wobj0;
MoveL Target_80,v40,fine,tExtruder\WObj:=wobj0;
MoveL Target_90,v40,fine,tExtruder\WObj:=wobj0;
MoveL Target_100,v40,fine,tExtruder\WObj:=wobj0;
MoveL Target_110,v40,fine,tExtruder\WObj:=wobj0;
MoveL Target_120,v40,fine,tExtruder\WObj:=wobj0;
MoveL Target_130,v40,fine,tExtruder\WObj:=wobj0;
MoveL Target_140,v40,fine,tExtruder\WObj:=wobj0;
MoveL Target_150,v40,fine,tExtruder\WObj:=wobj0;
MoveL Target_160,v40,fine,tExtruder\WObj:=wobj0;
MoveL Target_170,v40,fine,tExtruder\WObj:=wobj0;
MoveL Target_180,v40,fine,tExtruder\WObj:=wobj0;
MoveL Target_190,v40,fine,tExtruder\WObj:=wobj0;
MoveL Target_200,v40,fine,tExtruder\WObj:=wobj0;
Stop;
MoveJ [[450,0,-100],[0,0,-1,0],[-1,-1,-1,0],[9E+09,9E+09,9E+09,9E+09,9E+09,9E+09]],
v200, z50, tExtruder;
ENDPROC

ENDMODULE

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