```
MODULE FanMod
   CONST robtarget Target_10:=[[441.25,39,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E →
+09,9E+09,9E+09]];
    CONST robtarget Target_20:=[[407.75,39,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E →
+09,9E+09,9E+09]];
    CONST robtarget Target_30:=[[407.75,33.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_40:=[[441.25,33.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_50:=[[441.25,28,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E →
+09,9E+09,9E+09]];
    CONST robtarget Target_60:=[[407.75,28,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E →
+09,9E+09,9E+09]];
    CONST robtarget Target_70:=[[407.75,22.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                P
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_80:=[[441.25,22.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_90:=[[441.25,17,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E →
+09,9E+09,9E+09]];
    CONST robtarget Target_100:=[[407.75,17,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E →
+09,9E+09,9E+09]];
    CONST robtarget Target_110:=[[407.75,11.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_120:=[[441.25,11.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_130:=[[441.25,6,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E →
+09,9E+09,9E+09]];
    CONST robtarget Target_140:=[[407.75,6,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E →
+09,9E+09,9E+09]];
    CONST robtarget Target_150:=[[407.75,0.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                P
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_160:=[[441.25,0.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_170:=[[441.25,-5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E →
+09,9E+09,9E+09]];
    CONST robtarget Target_180:=[[407.75,-5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E →
+09,9E+09,9E+09]];
    CONST robtarget Target_200:=[[441.25,-10.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                7
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_190:=[[407.75,-10.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                7
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_210:=[[441.25,-16,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                7
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_220:=[[407.75,-16,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                7
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_230:=[[407.75,-21.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                7
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_240:=[[441.25,-21.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                7
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_250:=[[441.25,-27,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                \overline{a}
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_260:=[[407.75,-27,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                \overline{a}
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_270:=[[407.75,-32.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                7
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_280:=[[441.25,-32.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                7
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_290:=[[441.25,-38,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                7
```

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+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_300:=[[407.75,-38,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                   P
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_310:=[[407.75,-44.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                   P
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_320:=[[447.25,-44.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                   P
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_330:=[[447.25,44.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                   P
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_340:=[[402.75,44.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                   P
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_350:=[[402.75,-50,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                   P
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_360:=[[447.25,-50,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                   P
+09,9E+09,9E+09,9E+09]];
    PERS tooldata tExtruder:=[TRUE,[[-92.3257,2.14224,443.917],[1,0,0,0]],[0.5,[0,80,5],
                                                                                                   ₽
[1,0,0,0],0,0,0]];
    PROC Fan_Extruder() !Change this to suit.
        MoveJ [[350,0,-300],[0,0,-1,0],[-1,-1,-1,0],[9E+09,9E+09,9E+09,9E+09,9E+09,9E+09]],
v200, z50, tExtruder;
        MoveL Target_10, v50, fine, tExtruder\WObj:=wobj0;
        Stop:
            MoveL Target_20, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_30, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_40, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_50, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_60, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_70, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_80, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_90, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_100, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_110, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_120, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_130, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_140, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_150, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_160, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_170, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_180, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_190, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_200, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target 210, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_220, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_230, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_240, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target 250, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_260, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_270, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_280, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_290, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_300,v40,fine,tExtruder\WObj:=wobj0;
            MoveL Target_310, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_320, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_330, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_340, v40, fine, tExtruder\WObj:=wobj0;
```

ENDMODULE