```
CONST robtarget Target_10:=[[402.75,-50,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E →
+09,9E+09,9E+09]];
    CONST robtarget Target_20:=[[402.75,44.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_30:=[[447.25,44.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_40:=[[447.25,-50,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E →
+09,9E+09,9E+09]];
    CONST robtarget Target_50:=[[408.25,-50,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E →
+09,9E+09,9E+09]];
    CONST robtarget Target_60:=[[408.25,39,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E →
+09,9E+09,9E+09]];
    CONST robtarget Target_70:=[[413.75,39,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E →
+09,9E+09,9E+09]];
    CONST robtarget Target_80:=[[413.75,-44.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
                                                                                                P
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_90:=[[419.25,-44.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_100:=[[419.25,39,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E →
+09,9E+09,9E+09]];
    CONST robtarget Target_110:=[[424.75,39,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E →
+09,9E+09,9E+09]];
    CONST robtarget Target_120:=[[424.75,-44.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_130:=[[430.25,-44.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_140:=[[430.25,39,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E →
+09,9E+09,9E+09]];
    CONST robtarget Target_150:=[[435.75,39,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E →
+09,9E+09,9E+09]];
    CONST robtarget Target_160:=[[435.75,-44.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_170:=[[441.25,-44.5,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E
+09,9E+09,9E+09,9E+09]];
    CONST robtarget Target_180:=[[441.25,39,-387],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E
+09,9E+09,9E+09]];
    PERS tooldata tExtruder:=[TRUE,[[-92.3257,2.14224,443.917],[1,0,0,0]],[0.5,[0,80,5],
                                                                                                P
[1,0,0,0],0,0,0]];
    PROC Fan_Extruder() !Change this to suit.
        MoveJ [[350,0,-300],[0,0,-1,0],[-1,-1,-1,0],[9E+09,9E+09,9E+09,9E+09,9E+09]],
v200, z50, tExtruder;
        MoveL Target_10, v50, fine, tExtruder\WObj:=wobj0;
            MoveL Target_20, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_30, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target 40, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target 50, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target 60, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_70, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_80, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_90, v40, fine, tExtruder\WObj:=wobj0;
            MoveL Target_100, v40, fine, tExtruder\WObj:=wobj0;
```

```
MoveL Target_110,v40,fine,tExtruder\WObj:=wobj0;
    MoveL Target_120,v40,fine,tExtruder\WObj:=wobj0;
    MoveL Target_130,v40,fine,tExtruder\WObj:=wobj0;
    MoveL Target_140,v40,fine,tExtruder\WObj:=wobj0;
    MoveL Target_150,v40,fine,tExtruder\WObj:=wobj0;
    MoveL Target_160,v40,fine,tExtruder\WObj:=wobj0;
    MoveL Target_170,v40,fine,tExtruder\WObj:=wobj0;
    MoveL Target_170,v40,fine,tExtruder\WObj:=wobj0;
    Stop;
    MoveL [[450,110,-300],[0,0,-1,0],[-1,0,-1,0],[9E+09,9E+09,9E+09,9E+09,9E+09]],
v100, fine, tExtruder;
    MoveJ [[450,0,-100],[0,0,-1,0],[-1,-1,-1,0],[9E+09,9E+09,9E+09,9E+09,9E+09,9E+09]],
v200, z50, tExtruder;
    ENDPROC
```

ENDMODULE