

# AGDwoD for Quadratic function

## Derivation

Let  $f$  be a quadratic function  $f(x) = \frac{1}{2}\langle x, Ax \rangle$ ,  $A \succeq 0$ .



### ▼ Analysis of GD for quadratic functions

The general form of a quadratic function is  $g(x) = \frac{1}{2}\langle x, Ax \rangle + \langle b, x \rangle + c$ ,  $A \succeq 0$ . However, we can simplify it for analysis by variable substitution:

Let  $x^*$  be any minimizer of function. It exists given that  $b \in R(A)$ . We know that

$$\nabla g(x^*) = 0 \Rightarrow Ax^* = -b \quad (1)$$

Set  $x = y + x^*$ . Then, our function becomes

$$g(x) = \frac{1}{2}(\langle y, Ay \rangle + \langle x^*, Ay \rangle + \langle y, Ax^* \rangle + \langle x^*, Ax^* \rangle) + \langle b, x^* \rangle + \langle b, y \rangle + c$$

Using (1), as well as symmetry of  $A$ , the above simplifies to:

$$g(x) = \frac{\langle y, Ay \rangle + \langle x^*, Ax^* \rangle}{2} + \langle b, x^* \rangle + c = \frac{\langle y, Ay \rangle}{2} + c_0$$

Finally, we can redefine the function as  $f(y) = g(x) - c_0$  to get a much more convenient representation for analysis.

Note that

$$y_* = 0 \text{ is a minimizer of } f \quad (2)$$

$$f(y_*) = f_* = 0 \quad (3)$$



### ▼ Algorithm

#### Algorithm 1: Adaptive gradient descent

- 1: **Input:**  $x^0 \in \mathbb{R}^d$ ,  $\lambda_0 > 0$ ,  $\theta_0 = +\infty$
- 2:  $x^1 = x^0 - \lambda_0 \nabla f(x^0)$
- 3: **for**  $k = 1, 2, \dots$  **do**
- 4:    $\lambda_k = \min \left\{ \sqrt{1 + \theta_{k-1}} \lambda_{k-1}, \frac{3\|x^k - x^{k-1}\|}{4\|\nabla f(x^k) - \nabla f(x^{k-1})\|} \right\}$
- 5:    $x^{k+1} = x^k - \lambda_k \nabla f(x^k)$
- 6:    $\theta_k = \frac{\lambda_k}{\lambda_{k-1}}$
- 7: **end for**

We assumed that for quadratic problem a bigger stepsize can be taken. That is why set  $\lambda_k$  such satisfies two inequalities

$$\begin{cases} \lambda_k^2 \leq (1 + \theta_{k-1})\lambda_{k-1}^2, \\ \lambda_k \leq \frac{\beta\|x^k - x^{k-1}\|}{\|\nabla f(x^k) - \nabla f(x^{k-1})\|}, \end{cases}$$

And we want to find maximum possible  $\beta$  for which algorithm will converge and check whether  $\max(\beta) > \frac{1}{2}$ .

### Lemma 1

Let  $f : \mathbb{R}^d \rightarrow \mathbb{R}$  be convex and differentiable and let  $x^* = \min_{x \in \mathbb{R}^d} f(x) = 0$ . Then for  $x^k$  generated by the Algorithm it holds

$$\frac{1}{2} \|x^{k+1}\|^2 + \left( \frac{3}{2} - \beta \right) \|x^{k+1} - x^k\|^2 + 2\lambda_k(1 + \theta_k)f(x^k) \leq \frac{1}{2} \|x^k\|^2 + \beta \|x^k - x^{k-1}\|^2 + 2\lambda_k\theta_k f(x^{k-1}). \quad (4)$$

*Proof.*

Let  $k \geq 1$ .

$$\begin{aligned} \|x^{k+1} - x^*\|^2 &= \|x^k - x^*\|^2 + 2\langle x^{k+1} - x^k, x^k - x^* \rangle + \|x^{k+1} - x^k\|^2 \\ &= \|x^k\|^2 + 2\lambda_k \langle \nabla f(x^k), x^* - x^k \rangle + \|x^{k+1} - x^k\|^2. \end{aligned}$$

Using second-order Taylor expansion for our quadratic  $f$ , we have:

$$2\lambda_k \langle \nabla f(x^k), x^* - x^k \rangle = 2\lambda_k(f_* - f(x^k) - \frac{1}{2} \langle x^* - x^k, A(x^* - x^k) \rangle) \quad (5)$$

Which, since  $Ax_* = 0$ , simplifies to (using the definition of the GD step):

$$2\lambda_k \langle \nabla f(x^k), x^* - x^k \rangle = \langle x^{k+1} - x^k, x^k \rangle - 2\lambda_k f(x^k) \quad (6)$$

Thus, we can rewrite the initial equation as

$$\|x^{k+1}\|^2 = \|x^k\|^2 + \langle x^{k+1} - x^k, x^k \rangle - 2\lambda_k f(x^k) + \|x^{k+1} - x^k\|^2. \quad (7)$$

Next, let us examine  $\|x^{k+1} - x^k\|^2$ :

$$\begin{aligned} \|x^{k+1} - x^k\|^2 &= 2\|x^{k+1} - x^k\|^2 - \|x^{k+1} - x^k\|^2 \text{ add and subtract} \\ &= -2\lambda_k \langle \nabla f(x^k), x^{k+1} - x^k \rangle - \|x^{k+1} - x^k\|^2 \text{ apply G.D step def.} \\ &= 2\lambda_k \langle \nabla f(x^k) - \nabla f(x^{k-1}), x^k - x^{k+1} \rangle \\ &\quad + 2\lambda_k \langle \nabla f(x^{k-1}), x^k - x^{k+1} \rangle - \|x^{k+1} - x^k\|^2. \end{aligned}$$

Where in the last row, we added and subtracted  $2\lambda_k \langle \nabla f(x^{k-1}), x^k - x^{k+1} \rangle$ .

We can analyze parts of the above equation separately:

$$\begin{aligned} 2\lambda_k \langle \nabla f(x^k) - \nabla f(x^{k-1}), x^k - x^{k+1} \rangle &\leq 2\lambda_k \|\nabla f(x^k) - \nabla f(x^{k-1})\| \|x^k - x^{k+1}\| \\ &\leq 2\beta \|x^k - x^{k-1}\| \|x^k - x^{k+1}\| \text{ as } \lambda_k \leq \frac{\beta \|x^k - x^{k-1}\|}{\|\nabla f(x^k) - \nabla f(x^{k-1})\|} \\ &\leq \beta (\|x^k - x^{k-1}\|^2 + \|x^{k+1} - x^k\|^2) \end{aligned}$$

Where in the last inequality we used that  $a^2 + b^2 \geq 2ab$ .

$$\begin{aligned} \lambda_k \langle \nabla f(x^{k-1}), x^k - x^{k+1} \rangle &\stackrel{\text{G.D. step}}{=} \frac{2\lambda_k}{\lambda_{k-1}} \langle x^{k-1} - x^k, x^k - x^{k+1} \rangle \\ &\stackrel{\text{G.D. step}}{=} 2\lambda_k \theta_k \langle x^{k-1} - x^k, \nabla f(x^k) \rangle \\ &\stackrel{\text{convexity}}{\leq} 2\lambda_k \theta_k (f(x^{k-1}) - f(x^k)). \end{aligned}$$

Combining these bounds we get

$$\|x^{k+1} - x^k\|^2 \leq \beta \|x^k - x^{k-1}\|^2 + 2\lambda_k \theta_k (f(x^{k-1}) - f(x^k)) + (\beta - 1) \|x^{k+1} - x^k\|^2$$

Putting it into (7) we get

$$\|x^{k+1}\|^2 \leq \|x^k\|^2 + \langle x^{k+1} - x^k, x^k \rangle - 2\lambda_k f(x^k) + \beta \|x^k - x^{k-1}\|^2 + 2\lambda_k \theta_k (f(x^{k-1}) - f(x^k)) + (\beta - 1) \|x^{k+1} - x^k\|^2$$

Note also, by cosine theorem:

$$\langle x^{k+1} - x^k, x^k \rangle = \frac{1}{2} (\|x^{k+1}\|^2 - \|x^k\|^2 - \|x^{k+1} - x^k\|^2)$$

Therefore, (8) can be reordered to:

$$\frac{1}{2} \|x^{k+1}\|^2 + \left( \frac{3}{2} - \beta \right) \|x^{k+1} - x^k\|^2 + 2\lambda_k (1 + \theta_k) f(x^k) \leq \frac{1}{2} \|x^k\|^2 + \beta \|x^k - x^{k-1}\|^2 + 2\lambda_k \theta_k f(x^{k-1}). \quad (9)$$

Which is the desired inequality ■.

To ensure that inequality from Lemma 1 represents a proper Lyapunov energy dissipation, we require:

$$\frac{3}{2} - \beta \geq \beta \Rightarrow \beta \leq \frac{3}{4}$$

So,  $\max(\beta)$  is indeed larger than  $\frac{1}{2}$ .

Let us now continue our analysis for  $\beta = \frac{3}{4}$ :

### Theorem 1

For  $f(x) = \frac{\langle x, Ax \rangle}{2}$ ,  $(x^k)$  generated by Algorithm 1 converges to a solution of (1) and we have that

$$f(\hat{x}^k) \leq \frac{D}{2S_k} = \mathcal{O}\left(\frac{1}{k}\right)$$

where

$$\begin{aligned} \hat{x}^k &= \frac{\lambda_k(1 + \theta_k)x^k + \sum_{i=1}^{k-1} w_i x^i}{S_k}, \\ w_i &= \lambda_i(1 + \theta_i) - \lambda_{i+1}\theta_{i+1}, \\ S_k &= \lambda_k(1 + \theta_k) + \sum_{i=1}^{k-1} w_i = \sum_{i=1}^k \lambda_i + \lambda_1\theta_1 \end{aligned}$$

and  $D$  is a constant that explicitly depends on the initial data and the solution set.

*Proof.* Fix any  $x^* = \min_{x \in \mathbb{R}^d} f(x) = 0$ . Telescoping inequality from Lemma 1 we get

$$\sum_{i=1}^k \frac{1}{2} \|x^{i+1}\|^2 + \sum_{i=1}^k \frac{3}{4} \|x^{i+1} - x^i\|^2 + \sum_{i=1}^k 2\lambda_i(1 + \theta_i) f(x^i) \quad (10)$$

$$\leq \sum_{i=1}^k \frac{1}{2} \|x^i\|^2 + \sum_{i=1}^k \frac{3}{4} \|x^i - x^{i-1}\|^2 + \sum_{i=1}^k 2\lambda_i \theta_i f(x^{i-1}) \quad (11)$$

$$\frac{1}{2} \|x^{k+1}\|^2 + \frac{3}{4} \|x^{k+1} - x^k\|^2 + 2\lambda_k(1 + \theta_k)f(x^k) \quad (12)$$

$$+ 2 \sum_{i=1}^{k-1} [\lambda_i(1 + \theta_i) - \lambda_{i+1}\theta_{i+1}] f(x^i) \quad (13)$$

$$\leq \frac{3}{4} \|x^1 - x^0\|^2 + \frac{1}{2} \|x^1\|^2 + 2\lambda_1\theta_1 f(x^0) = D \quad (14)$$

Notice that  $2 \sum_{i=1}^{k-1} [\lambda_i(1 + \theta_i) - \lambda_{i+1}\theta_{i+1}] (f(x^i) - f_*)$  is non-negative, as,  $f(x^i) \geq 0$ , and  $\lambda_i(1 + \theta_i) - \lambda_{i+1}\theta_{i+1} \geq 0 \iff \lambda_{i+1}^2 \leq \lambda_i^2(1 + \theta_i)$ , which is condition required by algorithm. Thus, sequence of  $x^k$  is bounded ( $\|x^{k+1}\|^2 + \text{positive term} \leq D$ ). For a quadratic  $f$ , we know that is is L-Lipschitz, where L is the max eigenvalue of  $A$ :

$$\|\nabla f(x) - \nabla f(y)\| \leq L\|x - y\| \quad \forall x, y \in \mathbb{R}$$

Clearly,  $\lambda_1 = \frac{3\|x^1 - x^0\|}{4\|\nabla f(x^1) - \nabla f(x^0)\|} \geq \frac{3}{4L}$  thus, by induction one can prove that  $\lambda_k \geq \frac{3}{4L}$  in other words, the sequence  $(\lambda_k)$  is separated from zero.

Notice, that the total sum of coefficients at these terms is

$$\lambda_k(1 + \theta_k) + \sum_{i=1}^{k-1} [\lambda_i(1 + \theta_i) - \lambda_{i+1}\theta_{i+1}] = \sum_{i=1}^k \lambda_i + \lambda_1\theta_1 = S_k$$

Then apply Jensen inequality

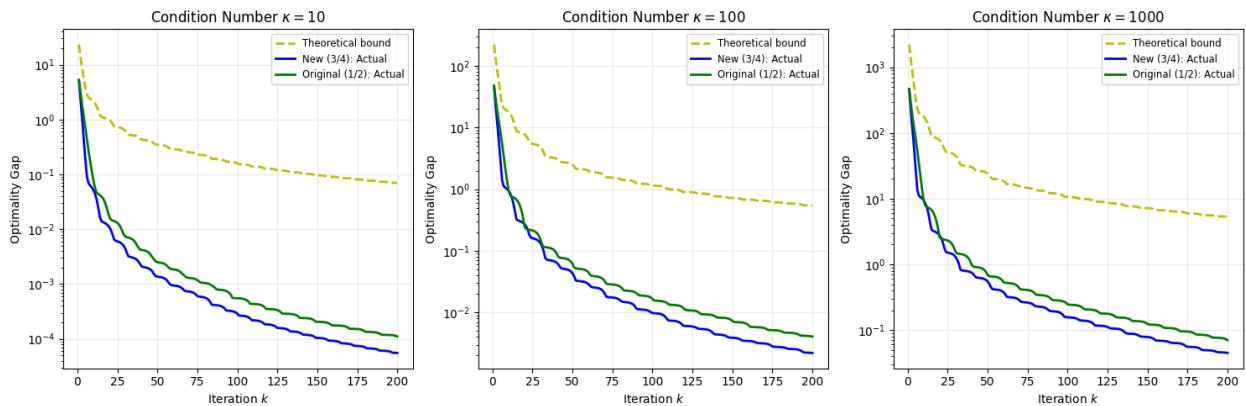
$$\lambda_k(1 + \theta_k)f(x^k) + \sum_{i=1}^{k-1} [\lambda_i(1 + \theta_i) - \lambda_{i+1}\theta_{i+1}] f(x^i) \geq S_k f(\hat{x}^k)$$

Consequently

$$\frac{D}{2} \geq S_k f(\hat{x}^k)$$

It proves convergence rate for the algorithm and boundeness of iterations.

## Experiments



Here you can see comparison of original algorithm from paper, updated version for quadratic function and overimposed theoretical bound for updated algorithm