

Inference and Representation, Fall 2017

Problem Set 5: Hamiltonian Monte-Carlo

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Disclaimer: I adhered to NYU honor code in this assignment.

1. To show $\mathcal{L}(\mathbf{v}, \mathbf{x})$ is convex given \mathbf{v} , we show the second derivative of \mathcal{L} with respect to \mathbf{v} is larger than zero for all \mathbf{v} . In fact:

$$\frac{\partial^2 \mathcal{L}}{\partial \mathbf{v}^2} = M. \tag{1}$$

By definition M is a positive matrix. Therefore \mathcal{L} is convex with respect to \mathbf{v} .

2. We use the fact that the pointwise supremum of a set of convex functions is also convex. Consider any $y \in \Omega$, we must have $\langle y, p \rangle + f(y)$ is convex with respect to p , therefore the convex conjugate:

$$f^*(p) = \sup_y (\langle y, p \rangle + f(y)) \quad (2)$$

is convex.

3. By the definition of \mathcal{L} and \mathbf{p} we have:

$$\mathbf{p} = \frac{\partial \mathcal{L}}{\partial \mathbf{v}} = M\mathbf{v}. \quad (3)$$

The convex conjugate of $\mathcal{L}(\mathbf{v})$ is:

$$\begin{aligned} \mathcal{L}^*(v) &= \sup_v [\langle v, p \rangle - \mathcal{L}(\mathbf{v})] \\ &= \sup_v [\langle v, Mv \rangle - \frac{1}{2} \langle v, mv \rangle + U(\mathbf{x})] \\ &= \sup_v [\frac{1}{2} \langle v, mv \rangle + U(\mathbf{x})] \end{aligned}$$

There fore the Hamilton \mathcal{H} must have the form:

$$\mathcal{H}(\mathbf{p}, \mathbf{x}) = \frac{1}{2} \langle \mathbf{p}, M^{-1}\mathbf{p} \rangle + U(\mathbf{x}) \quad (4)$$

4. By the definition of \mathcal{H} (equation 4), we have:

$$\frac{\partial \mathcal{H}}{\partial \mathbf{p}} = M^{-1} \mathbf{p} = \mathbf{v}. \quad (5)$$

By the definition of \mathcal{H} and \mathcal{L} we also have:

$$\frac{\partial \mathcal{L}}{\partial \mathbf{x}} = -\frac{\partial U}{\partial \mathbf{x}} = -\frac{\partial \mathcal{H}}{\partial \mathbf{x}} \quad (6)$$

By Euler-Lagrange equation and the definition of \mathbf{p}

$$\frac{\partial \mathcal{H}}{\partial \mathbf{x}} = -\frac{\partial \mathcal{L}}{\partial \mathbf{x}} = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \mathbf{v}} = \frac{d\mathbf{p}}{dt}. \quad (7)$$

Equation 5 and 7 are *Hamiltonian Equations*.

5. Without loss of generality, let the temperature $T = 1$. The canonical distribution of hamiltonian $\mathcal{H}(\mathbf{x}, \mathbf{p})$ is:

$$p(\mathbf{x}, \mathbf{p}) = \frac{1}{Z} \exp[-\mathcal{H}(\mathbf{x}, \mathbf{p})] \quad (8)$$

$$\begin{aligned} &= \frac{1}{Z} \exp[-\mathbf{p}^T M^{-1} \mathbf{p} - U(\mathbf{x})] \\ &= \frac{1}{Z} \exp[-\mathbf{p}^T M^{-1} \mathbf{p}] \exp[-U(\mathbf{x})], \end{aligned} \quad (9)$$

where Z is the partition function. Observed that $p(\mathbf{x}, \mathbf{p})$ is seperable function, therefore one can factor $p(\mathbf{x}, \mathbf{p}) = p(\mathbf{x})p(\mathbf{p})$.

6. From equation 9, we can derive that the expression of marginal distribution:

$$p(\mathbf{p}) = \int p(\mathbf{x}, \mathbf{p}) d\mathbf{x} \propto \exp[-\mathbf{p}^T M^{-1} \mathbf{p}]. \quad (10)$$

From equation 10, we know that $p(\mathbf{p})$ is a Gaussian distribution with mean $\mathbf{0}$ and Varaince M .

7. The update of \mathbf{x} and \mathbf{p} is based on *Hamiltonian equation*, which is depended only on the hamiltonian $\mathcal{H}(\mathbf{x}, \mathbf{p})$ but not the partition function Z . Therefore the leapfrog algorithm does not require the knowledge of the partition function.