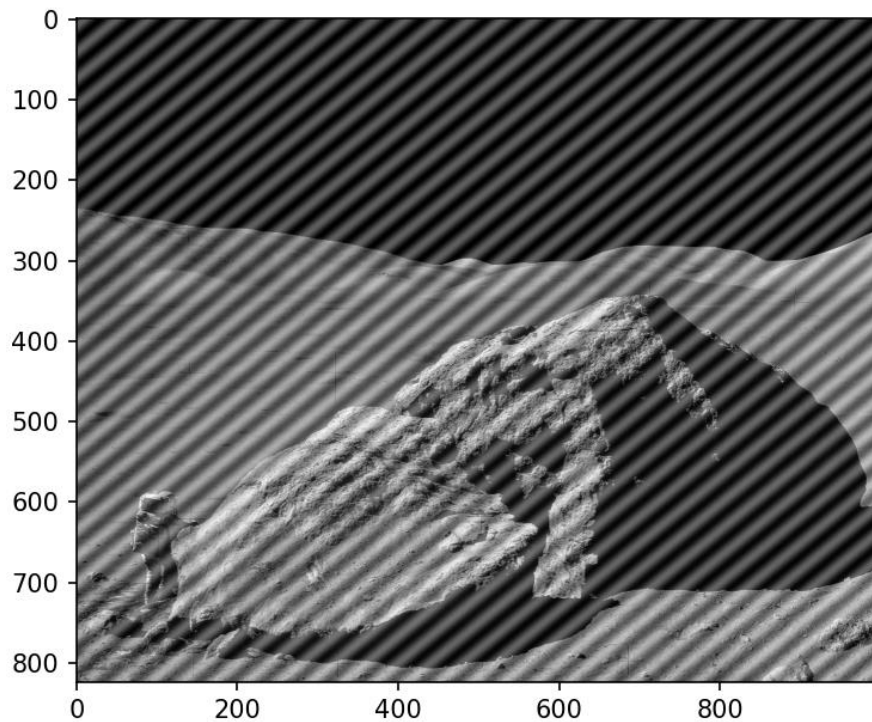


## 數位影像處理 DIP Homework Chapter 4\_2

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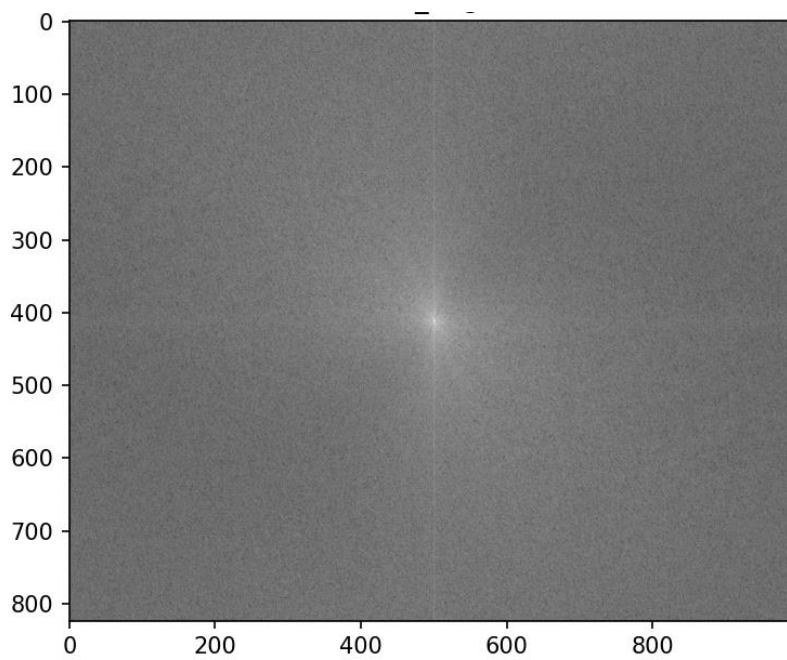
1. Please use FFT and design a **frequency filter** to cancel the sinusoidal noise of the assigned image, 'astronaut-interference.tif', and print out the source code and the processed image? (40)

原圖



```
# matplotlib read image
img = mpimg.imread("astronaut-interference.tif")
print(img.shape)
# Output Images
plt.imshow(img, cmap=cm.gray)
plt.show()
```

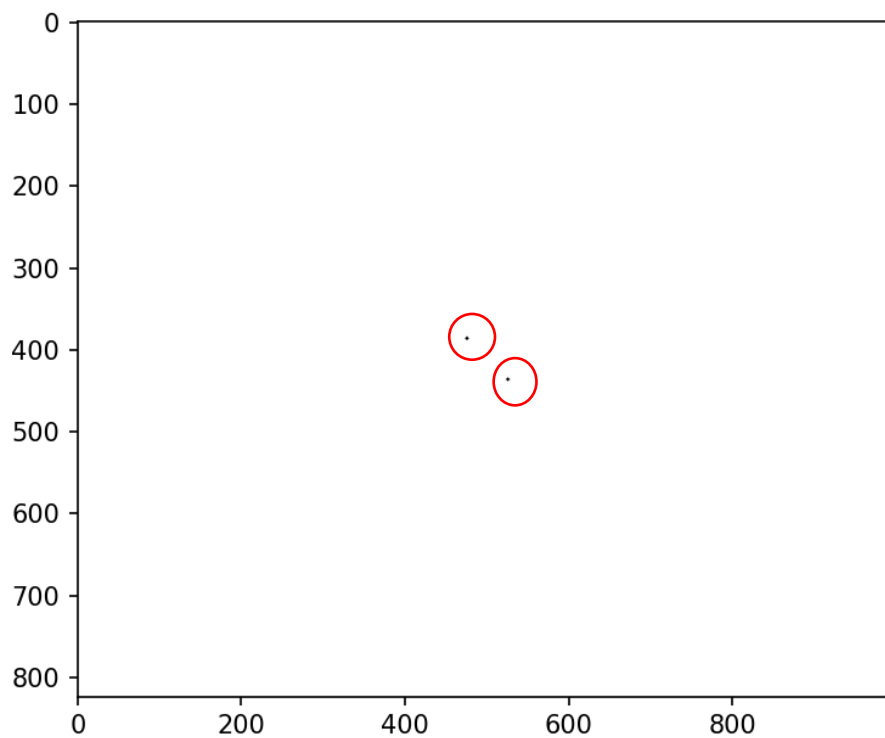
### 原圖經 Discrete Fourier Transform (FFT\_image)



```
# Fourier Transform
fft_img = np.fft.fftshift(np.fft.fft2(img))
plt.imshow(np.log(abs(fft_img) + 1), cmap='gray'), plt.title("fft_img")
plt.show()
```

### designed mask

(這邊以紅圓圈標記改動位置，紅圈標記的那兩點像素設為 0)



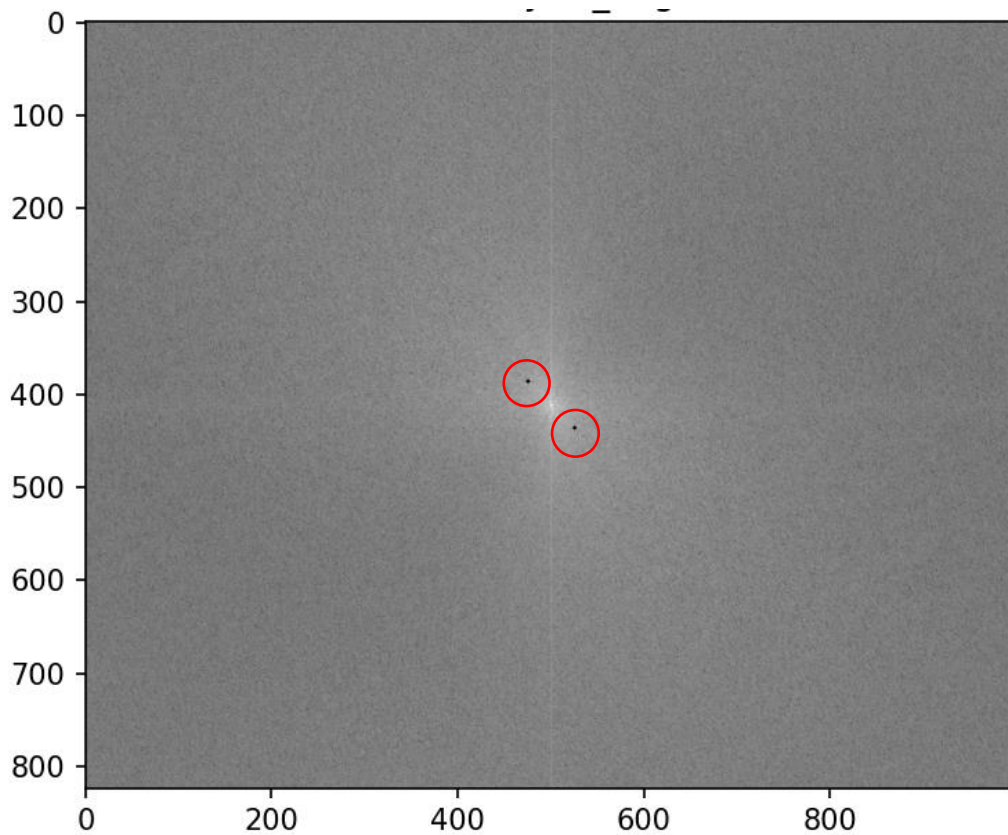
```

## modify on FFT image
mask = np.zeros_like(img)
mask = cv2.circle(mask, (475,386), 2, (255,255,255), -1) # 左上角 burst
mask = cv2.circle(mask, (525,436), 2, (255,255,255), -1) # 右下角 burst
mask = 255 - mask
mask = mask/mask.max()
plt.imshow(mask, cmap='gray'), plt.title("mask")
plt.show()

```

### FFT\_image \* designed mask

(這邊以紅圓圈標記改動位置)

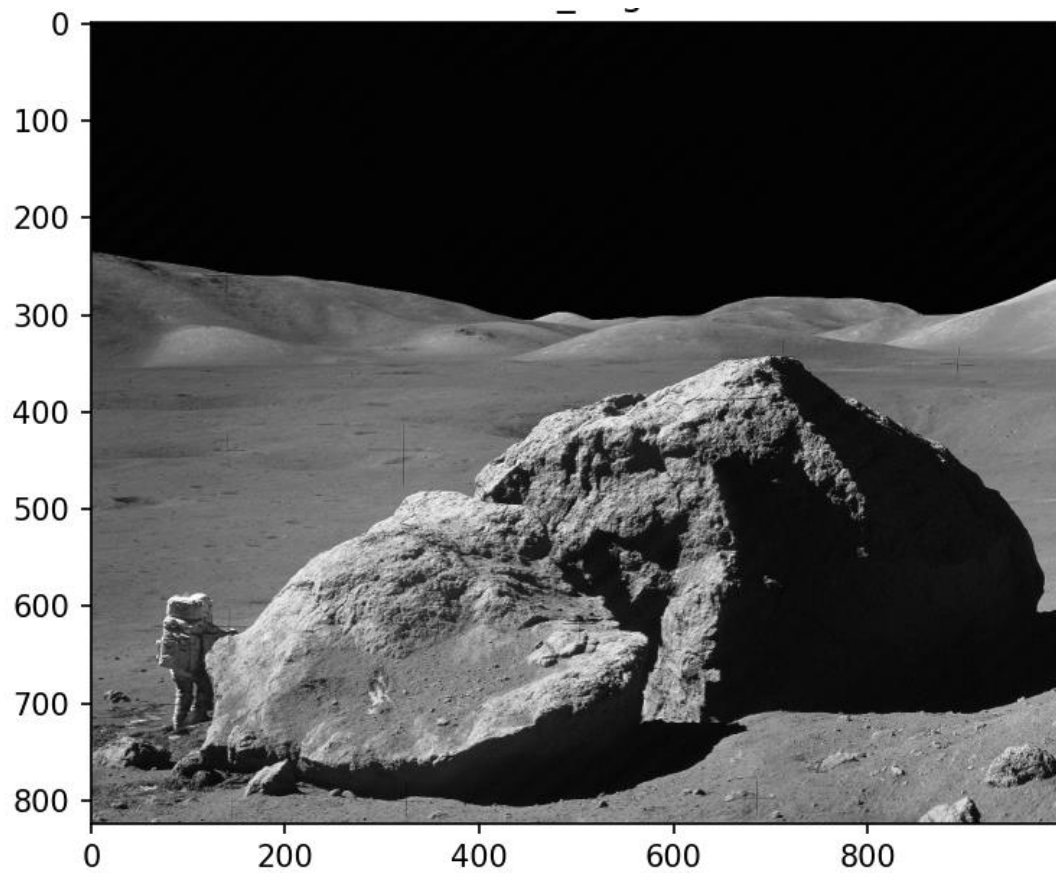


```

modify_fft_img = fft_img*mask
plt.imshow(np.log(abs(modify_fft_img) + 1), cmap='gray'), plt.title("modify fft_img")
plt.show()

```

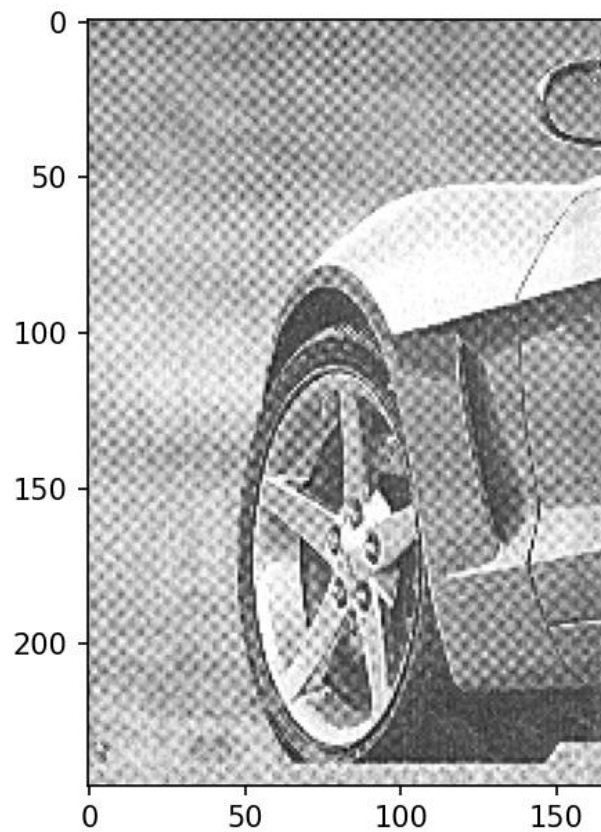
## FFT\_image 經 Inverse Discrete Fourier Transform (IFFT\_image)



```
## inverse Fourier Transform
ifft_img = np.fft.ifft2(np.fft.ifftshift(modify_fft_img))
print(f"ifft_img.max(), ifft_img.min() = {ifft_img.max(), ifft_img.min()}")
plt.imshow(np.abs(ifft_img), cmap='gray'), plt.title("ifft_img")
plt.show()
```

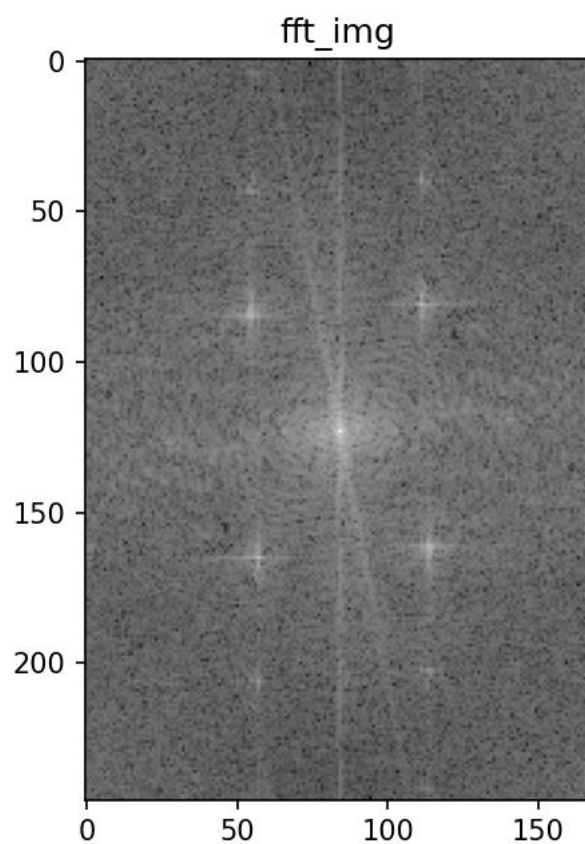
2. Please use FFT and design a **frequency filter** to cancel the moire-pattern noise of the assigned image, 'car-moire-pattern.tif', and print out the source code and the processed image? (40)

原圖



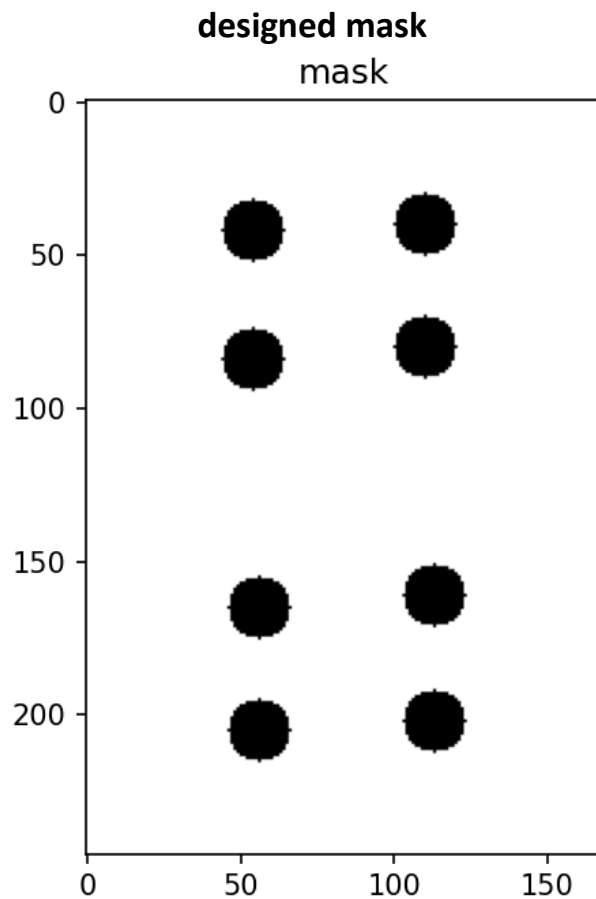
```
# matplotlib read image
img = mpimg.imread("car-moire-pattern.tif")
print(img.shape)
# Output Images
plt.imshow(img, cmap=cm.gray)
plt.show()
```

## 原圖經 Discrete Fourier Transform (FFT\_image)



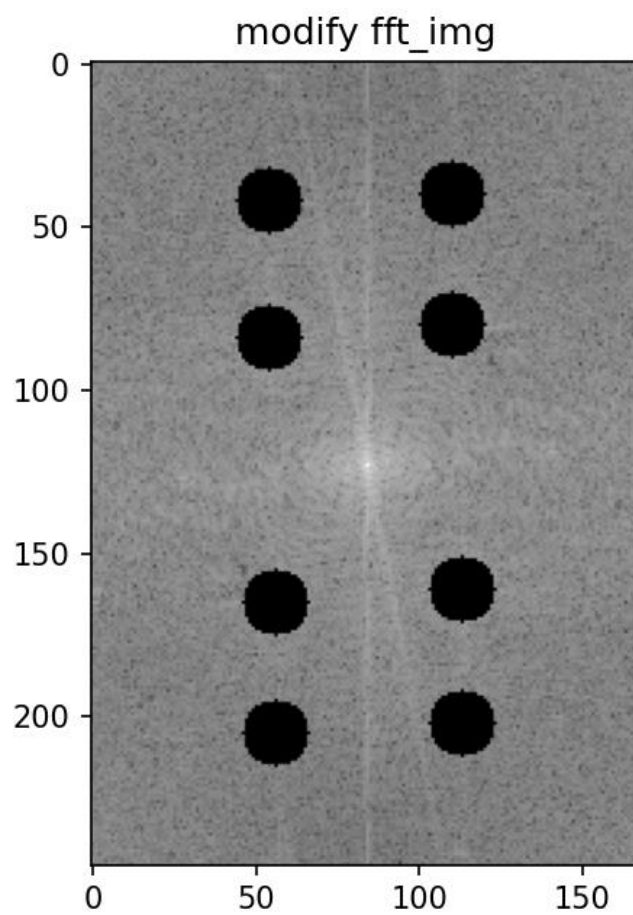
```
# Fourier Transform
fft_img = np.fft.fftshift(np.fft.fft2(img))
plt.imshow(np.log(abs(fft_img) + 1), cmap='gray'), plt.title("fft_img")
plt.show()
```





```
## modify on FFT image
mask = np.zeros_like(img)
# 左邊那排
mask = cv2.circle(mask, (54,42), 10, (255,255,255), -1)
mask = cv2.circle(mask, (54,84), 10, (255,255,255), -1)
mask = cv2.circle(mask, (56,165), 10, (255,255,255), -1)
mask = cv2.circle(mask, (56,205), 10, (255,255,255), -1)
# 右邊那排
mask = cv2.circle(mask, (110,40), 10, (255,255,255), -1)
mask = cv2.circle(mask, (110,80), 10, (255,255,255), -1)
mask = cv2.circle(mask, (113,161), 10, (255,255,255), -1)
mask = cv2.circle(mask, (113,202), 10, (255,255,255), -1)
mask = 255 - mask
mask = mask/mask.max()
plt.imshow(mask, cmap='gray'), plt.title("mask")
plt.show()
```

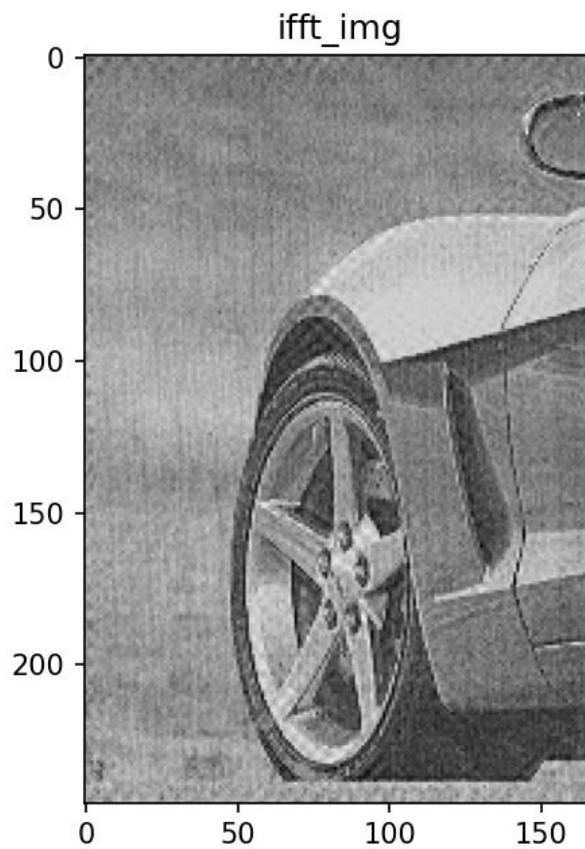
FFT\_image \* designed mask



```
modify_fft_img = fft_img*mask  
plt.imshow(np.log(abs(modify_fft_img) + 1), cmap='gray', plt.title("modify fft_img")  
plt.show()
```

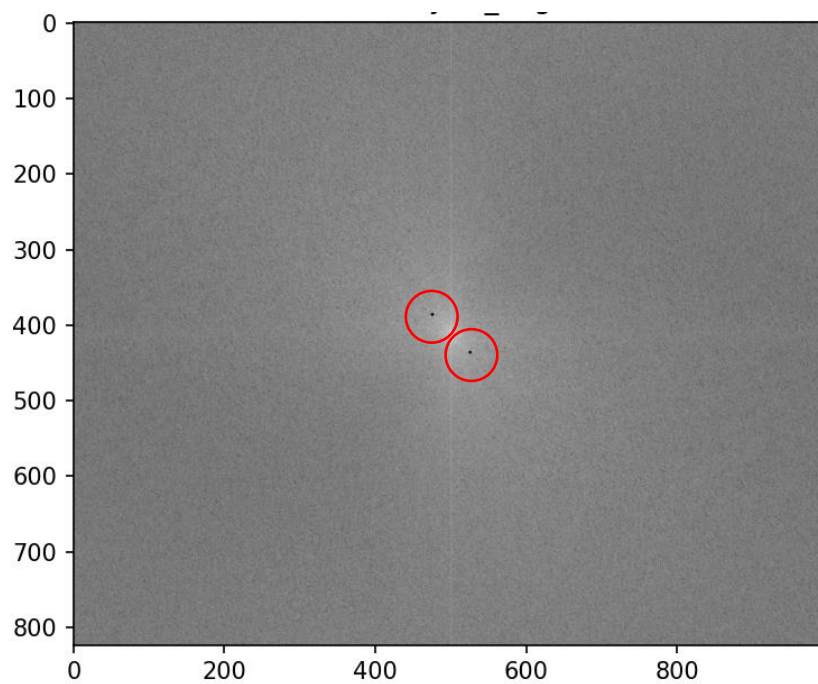
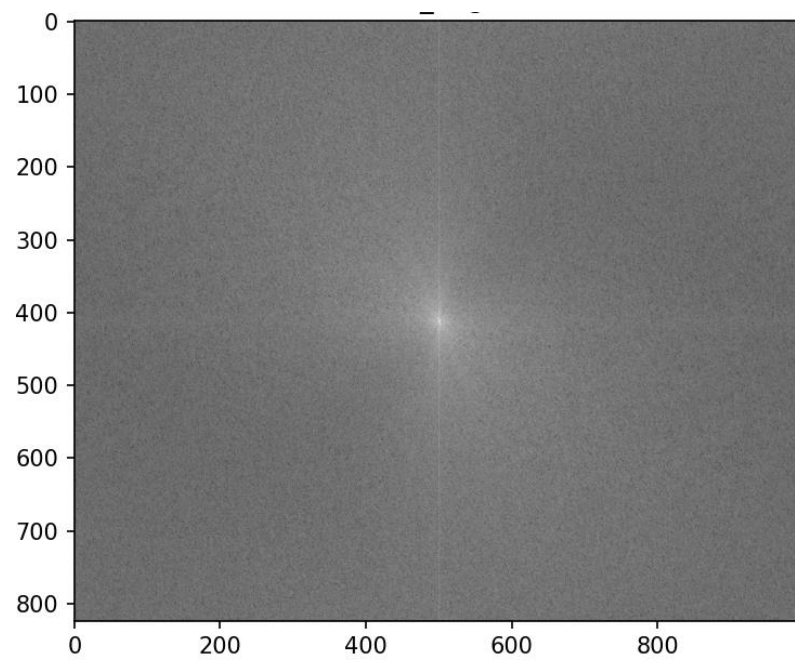


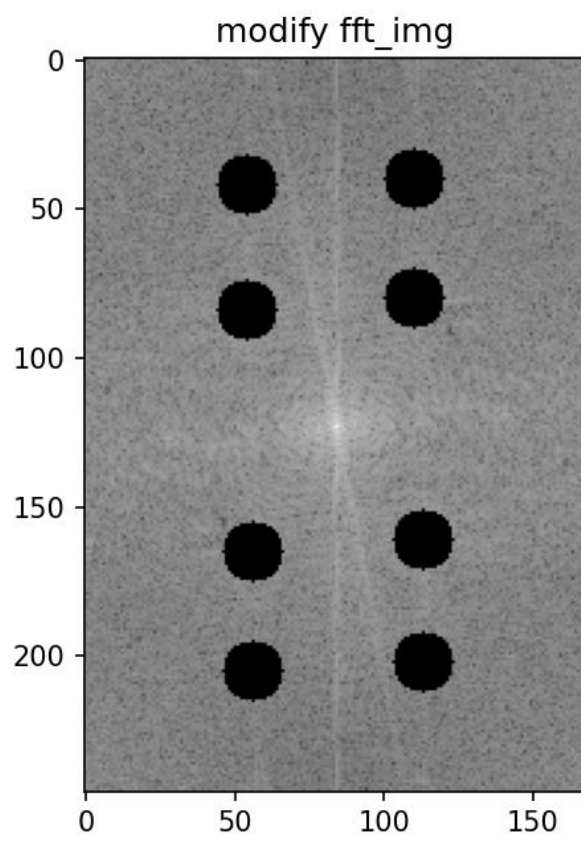
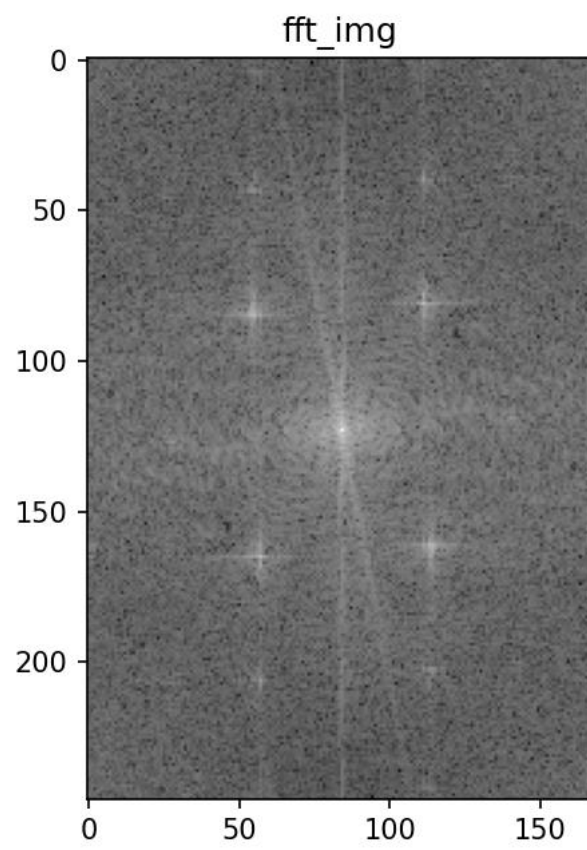
## FFT\_image 經 Inverse Discrete Fourier Transform (IFFT\_image)



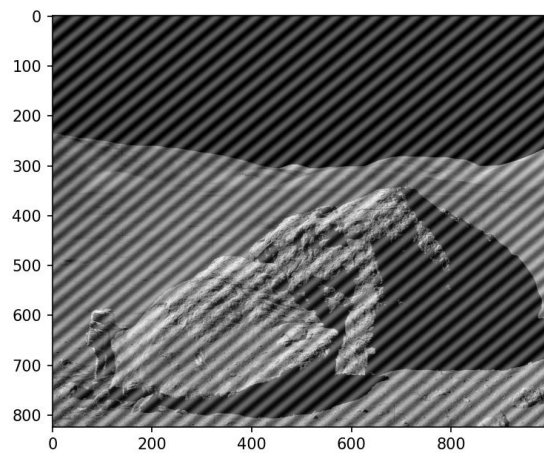
```
## inverse Fourier Transform
ifft_img = np.fft.ifft2(np.fft.ifftshift(modify_fft_img))
print(f"ifft_img.max(), ifft_img.min() = {ifft_img.max(), ifft_img.min()}")
plt.imshow(np.abs(ifft_img), cmap='gray'), plt.title("ifft_img")
plt.show()
```

3. Please comment and compare your two design freq. filters? (20)

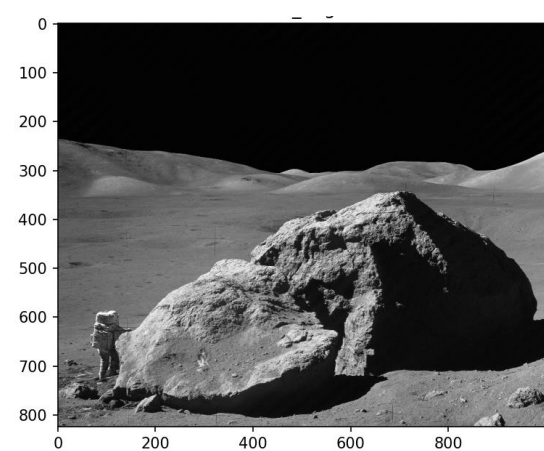
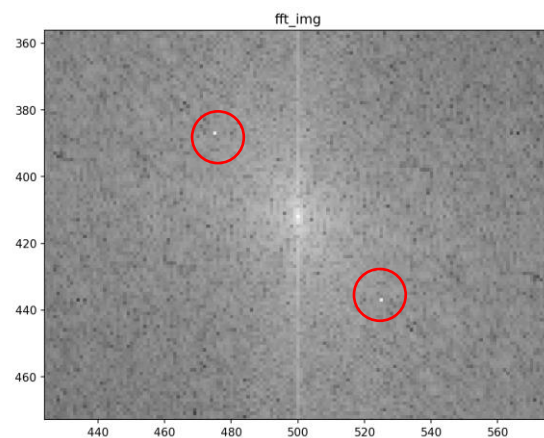




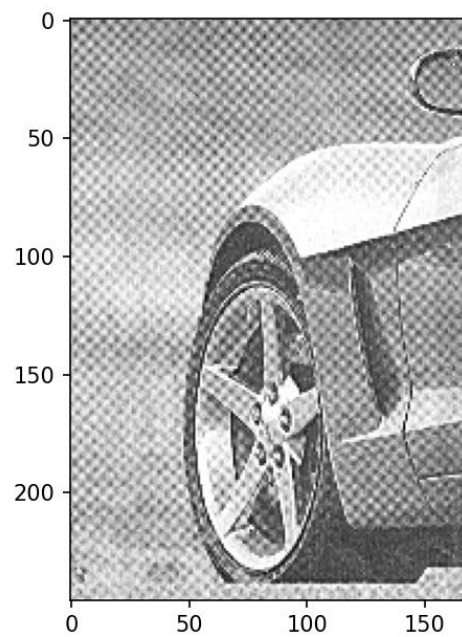
上下兩張圖分別為修改前與修改後的 frequency filter, 針對第一題的原圖



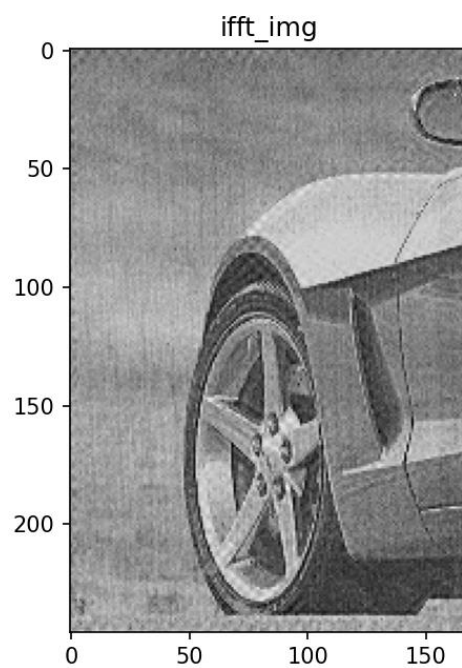
由於圖像中有特定的低頻雜訊，因此在設計 frequency filter 時，將在特定頻率上的兩個亮點像素值設為 0 (需放大較能清楚看見亮點)，以除掉該特定頻率的訊號，再 inverse fourier transform 回去得結果圖，由結果圖可見，雜訊確實由此兩再頻域的亮點產生。



而第二題的原圖



雖然 moire pattern 的雜訊非高頻也非低頻(藉在中間)，但仍可找尋造成圖片中雜訊的頻率點，並如同處理圖一的方式，使用 mask 將其像素遮掉，或在該點套上 low pass filter，而本次我是使用 ideal low pass filter, 最終得到如下的解果圖：



另附上以 butterworth 及 gaussian filter 實作的結果，但個人覺得沒有差很多。

