



Computer & Systems Engineering Department

Project - Phase 2

Roots of Equations

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1. Introduction

The aim of this project is to compare and analyze the behavior of the different numerical methods used for calculating the roots of equations:

1. Bisection
2. False-Position
3. Fixed point
4. Original Newton-Raphson
5. Modified Newton-Raphson
6. Secant Method.

2. Pseudo-codes

✓ Bisection Method:

```
Class BisectionMethod:
    Method __init__(equation, x_min, x_max, eps=1e-5,
max_iter=50, show_steps=False, precision=6):
        Initialize symbols, functions, and parameters

    Method format_significant_figures(num):
        Return formatted number with specified significant figures

    Method plot_function():
        Plot the function within the given range

    Method find_root(a, b):
        If f(a) * f(b) > 0:
            Print "Bisection method fails"
            Return None

        Set X_l to a, X_u to b, X_r_old to None

        For n from 1 to max_iter:
            Compute X_r as midpoint of X_l and X_u
            Compute f_m_n as f(X_r)

            If show_steps:
                Print iteration details

            If f_m_n == 0:
                Print "Root found"
                Return X_r

            If f(X_l) * f_m_n > 0:
                Set X_l to X_r
            Else:
                Set X_u to X_r

        If X_r_old is not None:
            Compute relative_error
```

```
If show_steps:
    Print relative error
    If relative_error < eps:
        Break

    Set X_r_old to X_r

    Return X_r

Method solve():
    Set a to x_min, b to x_max
    Record start time
    Call find_root(a, b) and store result in root

    If root is not None:
        Print root, number of iterations, relative error, and
        execution time

Main:
    Define equation
    Get user inputs for x_min, x_max, eps, max_iter, precision,
    show_steps
    Create BisectionMethod instance with user inputs
    Call solve() method on the instance
```

✓ False position method:

Class FalsePosition:

Method `__init__`(equation, x_min, x_max, eps=1e-5, max_iter=50, show_steps=False, precision=6):

Initialize symbols, functions, and parameters

Method `format_significant_figures`(num):

Return formatted number with specified significant figures

Method `plot_function`():

Plot the function within the given range

Method `find_root`(a, b):

If $f(a) * f(b) > 0$:

Print "False Position method fails"

Return None

Set X_l to a, X_u to b, X_{r_old} to None

For n from 1 to max_iter:

Compute X_r using False Position formula

Compute f_{m_n} as $f(X_r)$

If show_steps:

Print iteration details

If $f_{m_n} == 0$:

Print "Root found"

Return X_r

If $f(X_l) * f_{m_n} > 0$:

Set X_l to X_r

Else:

Set X_u to X_r

If X_{r_old} is not None:

Compute relative_error

If show_steps:

Print relative error

If relative_error < eps:

Break

Set X_{r_old} to X_r

Return X_r

Method `solve`():

Set a to x_min, b to x_max

Record start time

Call `find_root(a, b)` and store result in root

If root is not None:

Print root, number of iterations, relative error, and execution time

Main:

Define equation

Get user inputs for x_min, x_max, eps, max_iter, precision, show_steps

Create FalsePosition instance with user inputs

Call `solve()` method on the instance

✓ Fixed Point method:

Class FixedPointMethod:

Method `__init__(equation, x_min, x_max, eps=1e-5, max_iter=50, show_steps=False, precision=6)`:

Initialize symbols, functions, and parameters

Method `format_significant_figures(num)`:

Return formatted number with specified significant figures

Method `plot_function()`:

Plot the function $g(x)$ and $y = x$ within the given range

Method `find_root(x0)`:

Try:

Set x_{old} to $x0$

For n from 1 to max_iter :

Compute x_{new} as $g(x_{old})$

If $g(x_{old}) == x_{old}$:

Print "Root found"

Append "Root found" to answer string

Break

If `show_steps`:

Print iteration details

If $abs(x_{new}) < eps$:

Print "Root close to zero"

Append "Root close to zero" to answer

string

Break

Compute `relative_error`

If `show_steps`:

Print relative error

If `relative_error < eps`:

Break

Set x_{old} to x_{new}

Return x_{new}

Except Exception as `e`:

Print error message

Append error message to answer string

Return None

Method `solve()`:

Set $x0$ to x_{min}

Record start time

Call `find_root(x0)` and store result in `root`

If `root` is not None:

Print `root`, number of iterations, relative error, and execution time

Main:

Define equation

Get user inputs for x_{min} , x_{max} , `eps`, `max_iter`, `precision`, `show_steps`

Create FixedPointMethod instance with user inputs

Call `solve()` method on the instance

✓ Original Newton Raphson method :

Class NewtonRaphsonMethod:

Method `__init__(equation, x_min, x_max, eps=1e-5, max_iter=50, show_steps=False, precision=6):`

Initialize symbols, functions, and parameters

Method `format_significant_figures(num):`

Return formatted number with specified significant figures

Method `plot_function():`

Plot the function $f(x)$ within the given range

Method `find_root(x0):`

Try:

Set x_{old} to x_0

For n from 1 to max_iter :

Compute f_value , f_prime_value ,

$f_double_prime_value$

If $abs(f_value) == 0$:

Print "Root found"

Append "Root found" to answer string

Break

If $f_prime_value == 0$:

Print "Derivative is zero. No roots found."

Append "Derivative is zero. No roots found." to

answer string

Return None

If $f_double_prime_value == 0$:

Print "Second derivative is zero. Inflection point."

Append "Second derivative is zero. Inflection point." to answer string

Return None

Compute x_{new} using Newton-Raphson formula

If `show_steps`:

Print iteration details

If $abs(x_{new}) < eps$:

Print "Root close to zero"

Append "Root close to zero" to answer string

Break

If $abs(x_{new}) > 1000$:

Print "Method will diverge"

Append "Method will diverge" to answer string

Return None

Compute `relative_error`

If `show_steps`:

Print relative error

If `relative_error < eps`:

Break

Set x_{old} to x_{new}

Return x_{new}

Except Exception as `e`:

Print error message

Append error message to answer string

Return None

Method `solve():`

Set x_0 to x_{min}

Record start time

Call `find_root(x0)` and store result in `root`

If `root` is not None:

Print `root`, number of iterations, relative error, and execution time

Main:

Define equation

Get user inputs for x_{min} , x_{max} , `eps`, `max_iter`, `precision`, `show_steps`

Create `NewtonRaphsonMethod` instance with user inputs

Call `solve()` method on the instance

✓ Modified Newton Raphson method :

```
Class ModNewtonRaphsonMethod:
    Method __init__(equation, x_min, x_max, eps=1e-5,
max_iter=50, show_steps=False, precision=6):
        Initialize symbols, functions, and parameters

    Method format_significant_figures(num):
        Return formatted number with specified significant
figures

    Method plot_function():
        Plot the function f(x) within the given range

    Method find_root(x0):
        Try:
            Set x_old to x0
            For n from 1 to max_iter:
                Compute f_value, f_prime_value,
f_double_prime_value

                If abs(f_value) == 0:
                    Print "Root found"
                    Append "Root found" to answer string
                    Break

                If f_prime_value^2 - (f_value *
f_double_prime_value) == 0:
                    Print "Division by zero. No roots found."
                    Append "Division by zero. No roots found." to
answer string
                    Return None

            Compute x_new using Modified Newton-Raphson
formula

            If show_steps:
                Print iteration details

            If abs(x_new) < eps:
                Print "Root close to zero"
                Append "Root close to zero" to answer string
                Break

            If abs(x_new) > 1000:
                Print "Method will diverge"
                Append "Method will diverge" to answer string
                Return None

        Compute relative_error
        If show_steps:
            Print relative error

        If relative_error < eps:
            Break
```

```
Set x_old to x_new

    Return x_new
Except Exception as e:
    Print error message
    Append error message to answer string
    Return None

Method solve():
    Set x0 to x_min
    Record start time
    Call find_root(x0) and store result in root

    If root is not None:
        Print root, number of iterations, relative error, and
execution time

Main:
    Define equation
    Get user inputs for x_min, x_max, eps, max_iter,
precision, show_steps
    Create ModNewtonRaphsonMethod instance with user
inputs
    Call solve() method on the instance
```

✓ Secant method :

Class SecantMethod:

Method `__init__`(equation, x_min, x_max, eps=1e-5, max_iter=50, show_steps=False, precision=6):

Initialize symbols, functions, and parameters

Method `format_significant_figures`(num):

Return formatted number with specified significant figures

Method `plot_function`():

Plot the function $f(x)$ within the given range

Method `find_root`(x0, x1):

For n from 1 to max_iter:

Compute f_{x0} and f_{x1}

If $f_{x0} - f_{x1} == 0$:

Print "Division by zero. No roots found."

Append "Division by zero. No roots found." to

answer string

Return None

Compute x_{new} using Secant formula

If $abs(f(x_{new})) == 0$:

Print "Root found"

Append "Root found" to answer string

Break

If show_steps:

Print iteration details

If $abs(x_{new}) < eps$:

Print "Root close to zero"

Append "Root close to zero" to answer string

Break

Compute relative_error

If show_steps:

Print relative error

If relative_error < eps:

Break

If $abs(x_{new}) > 1000$:

Print "Method will diverge"

Append "Method will diverge" to answer string

Return None

If show_steps and $n \neq \text{max_iter}$:

Print separator

Append separator to answer string

Set $x0$ to $x1$ and $x1$ to x_{new}

Return x_{new}

Method `solve`():

Set $x0$ to x_{min} and $x1$ to x_{max}

Record start time

Call `find_root`($x0$, $x1$) and store result in root

If root is not None:

Print root, number of iterations, relative error, and execution time

Main:

Define equation

Get user inputs for x_{min} , x_{max} , eps, max_iter, precision, show_steps

Create SecantMethod instance with user inputs

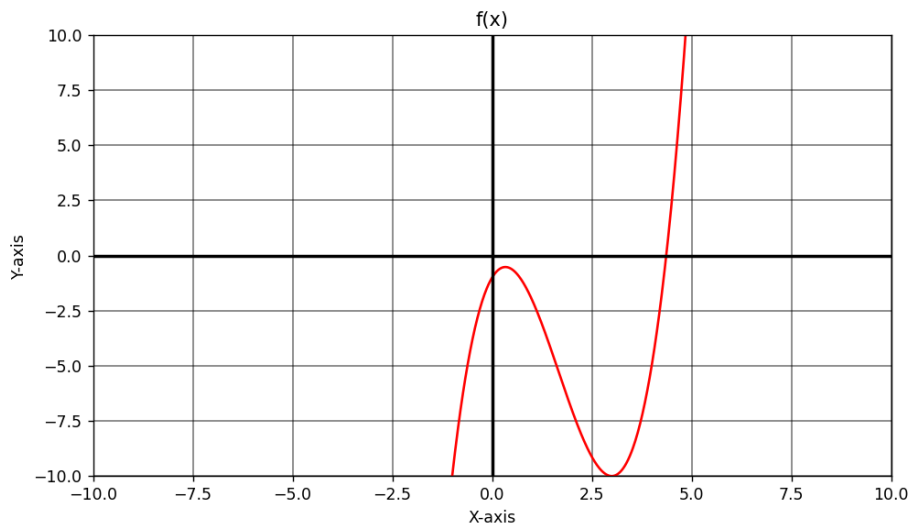
Call `solve`() method on the instance

3. Sample Runs

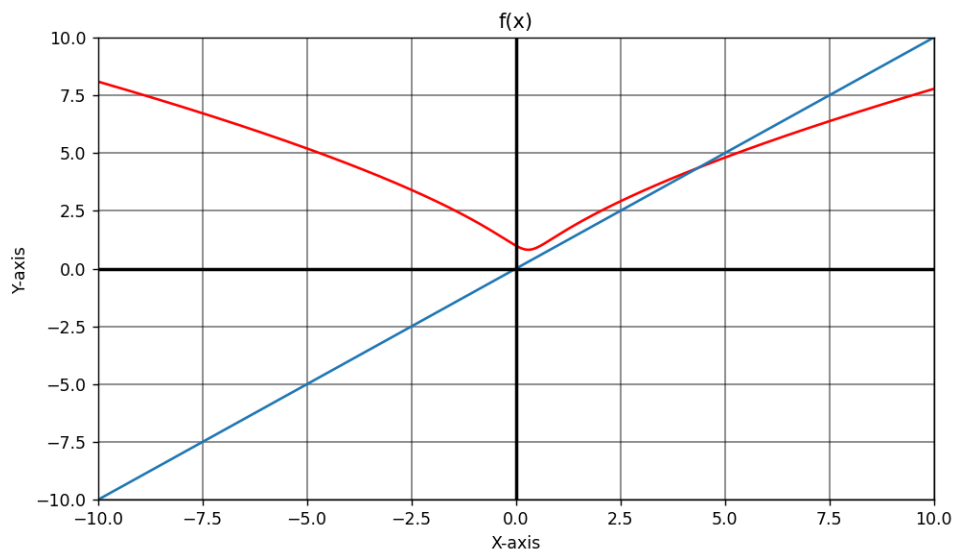
TC_1:

Plotting:

1. $F(x) = x^3 - 5x^2 + 3x - 1$

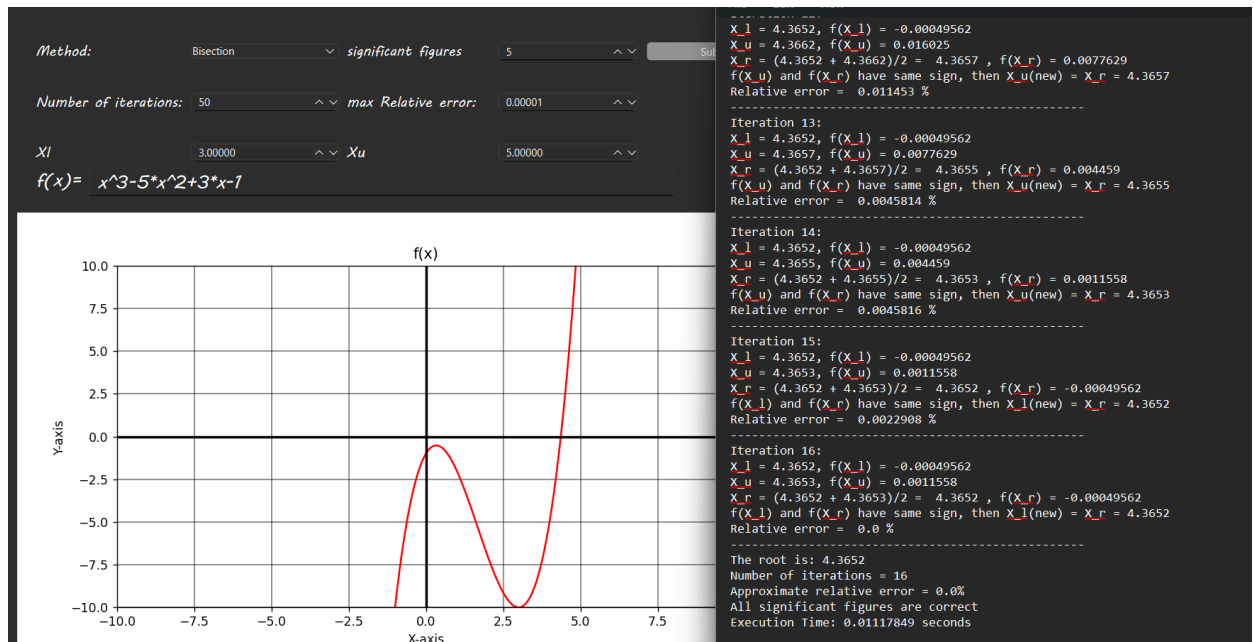


2. Will assume $g(x) = (5x^2 - 3x + 1)^{1/3}$:

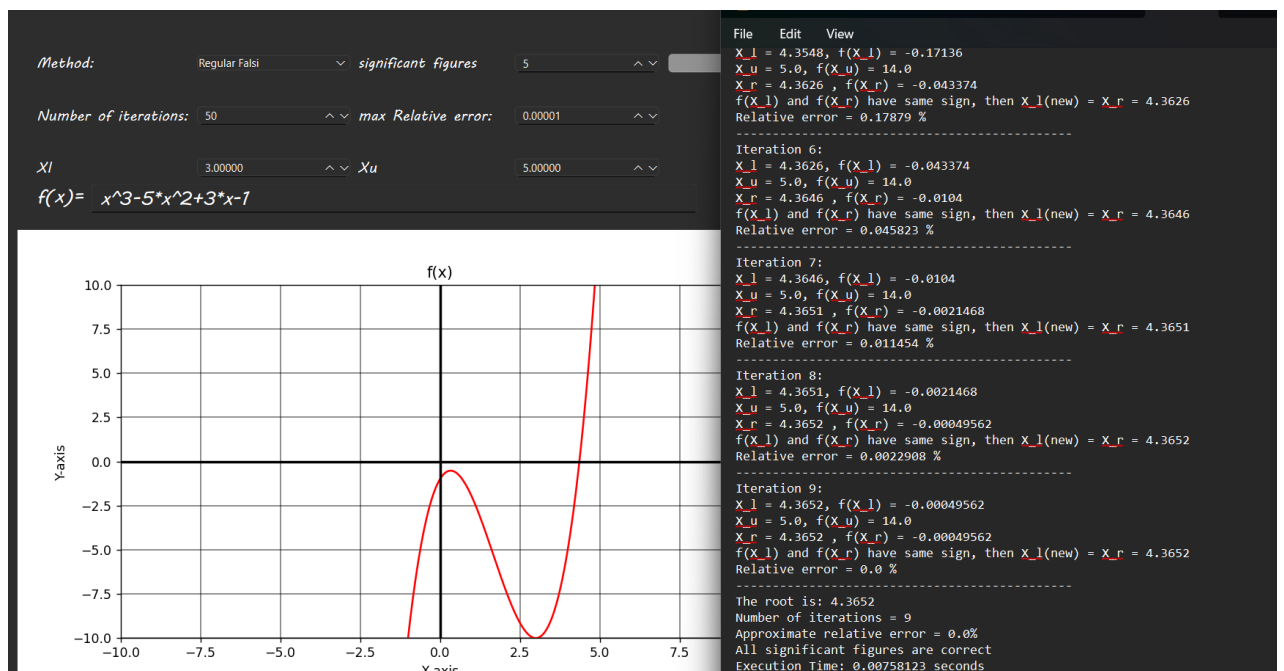


Methods:

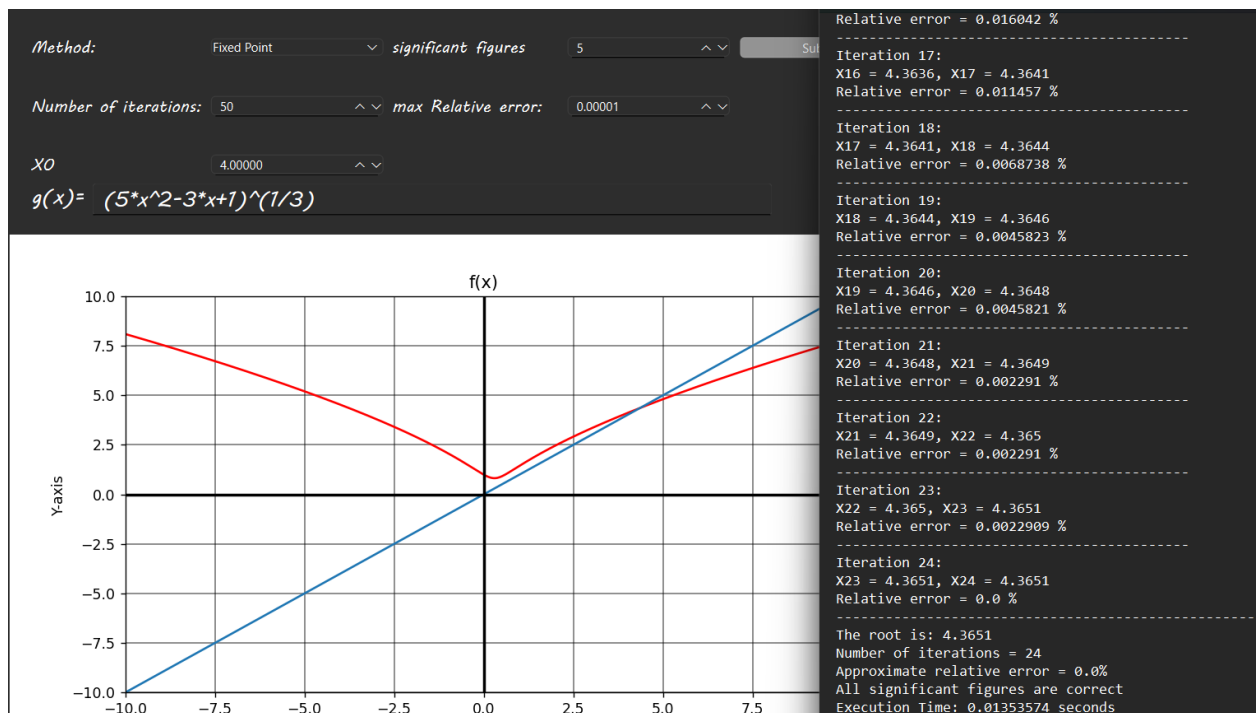
- Bisection



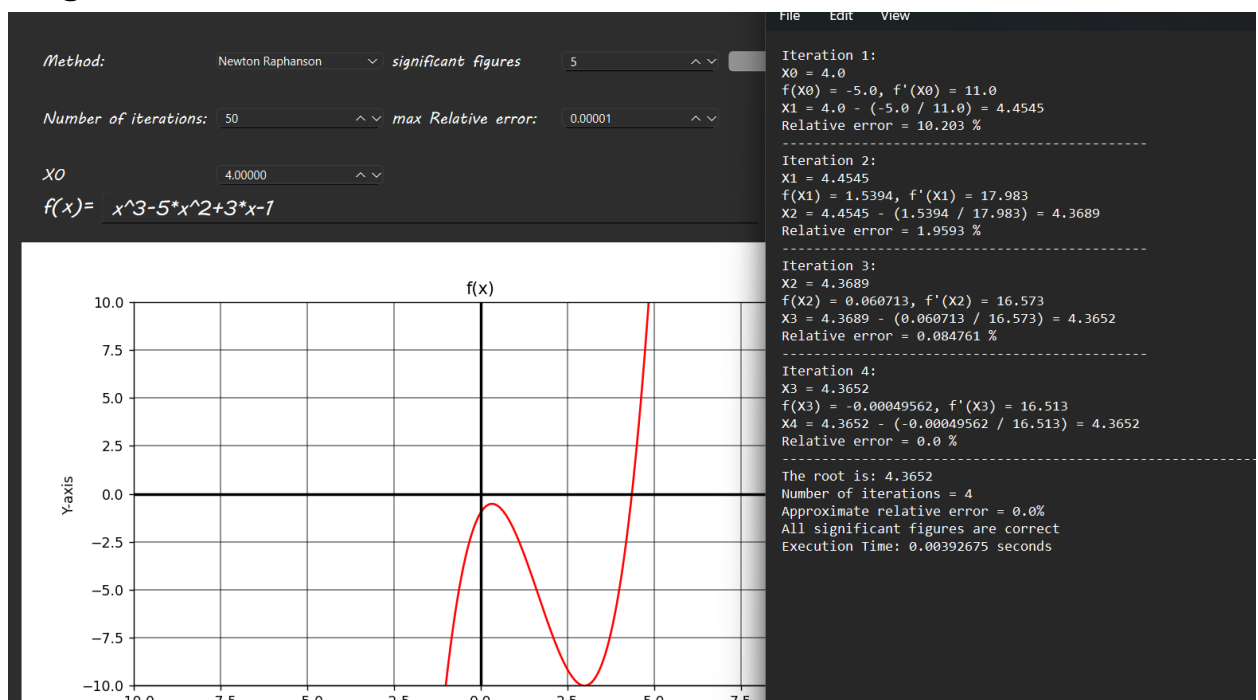
- False Position



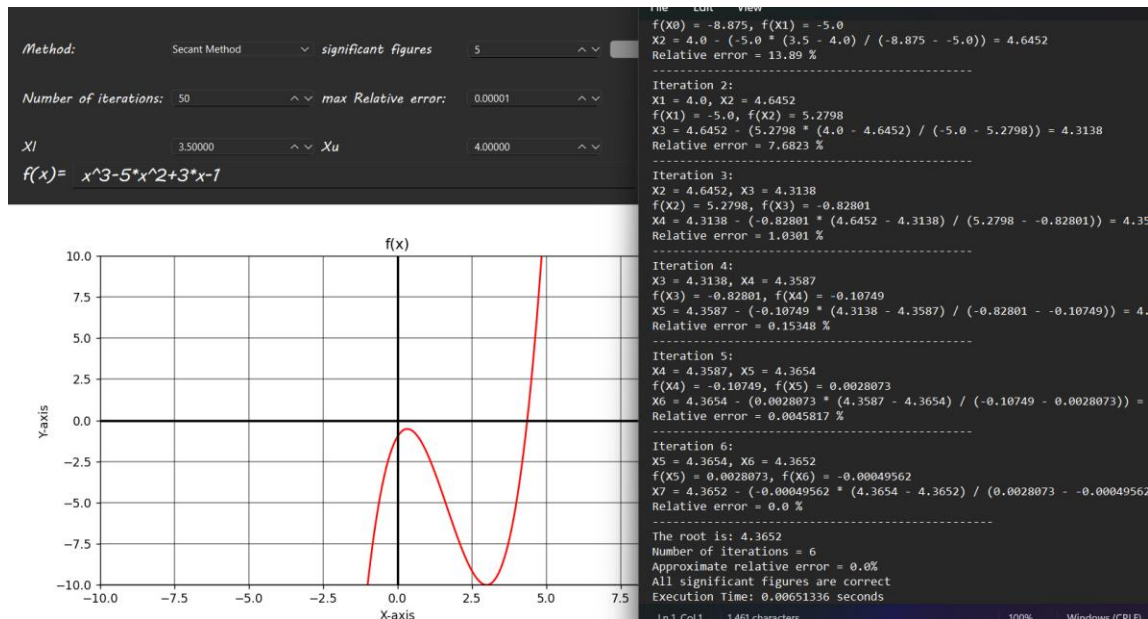
- Fixed Point



- Original Newton



- Secant



Comparable Table:

Method	Number of iterations	Run time	App. Root	initial guess	Relative Error
Bisection	16	0.01117849 sec	4.3652	$X_l = 3$ $X_u = 5$	0 %
False Position	9	0.00758123 sec	4.3652	$X_l = 3$ $X_u = 5$	0 %
Fixed Point	24	0.01353574 sec	4.3651	$X_o = 4$	0 %
Original Newton	4	0.00392675 sec	4.3652	$X_o = 4$	0 %
Secant	6	0.00651336 sec	4.3652	$X_o = 3.5$ $X_1 = 4$	0 %

Comments:

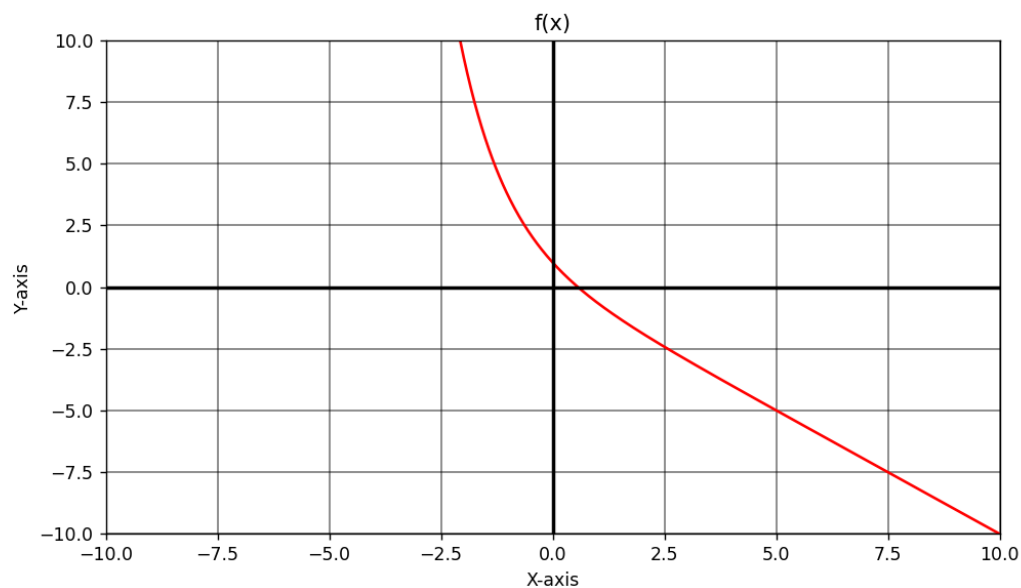
- **Efficiency:** The Original Newton method was the most efficient, followed by the Secant and False Position methods.
- **Accuracy:** All methods achieved high accuracy with zero relative error.
- **Iterations:** The Fixed Point method required the most iterations, indicating lower efficiency for this specific problem.

Overall, the Original Newton method stands out as the best performer in terms of both speed and accuracy, while the Fixed Point method, despite being accurate, was less efficient.

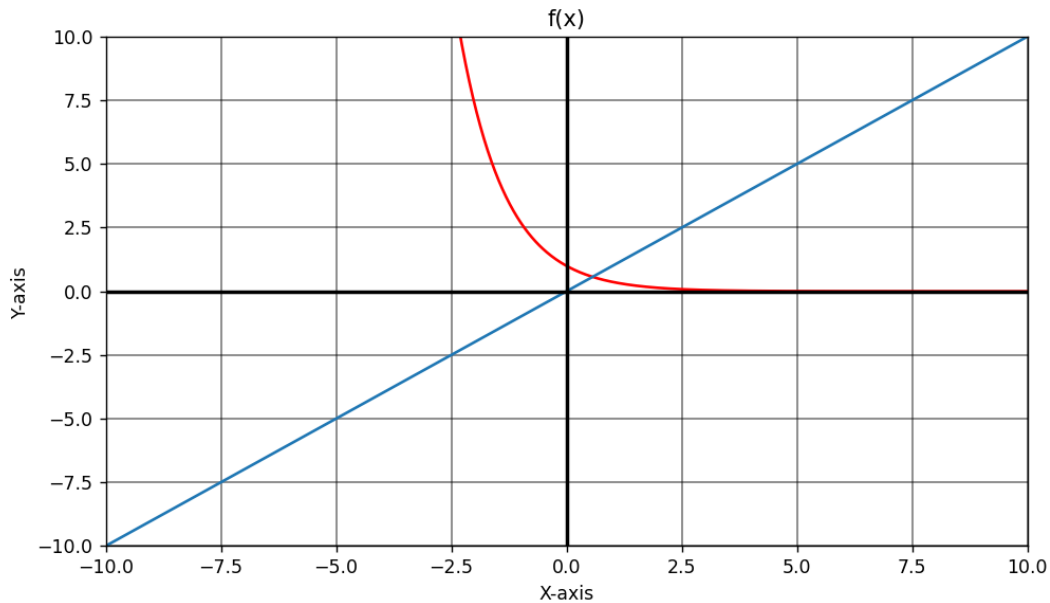
TC_2:

Plotting:

1. $F(x) = e^{-x} - x$

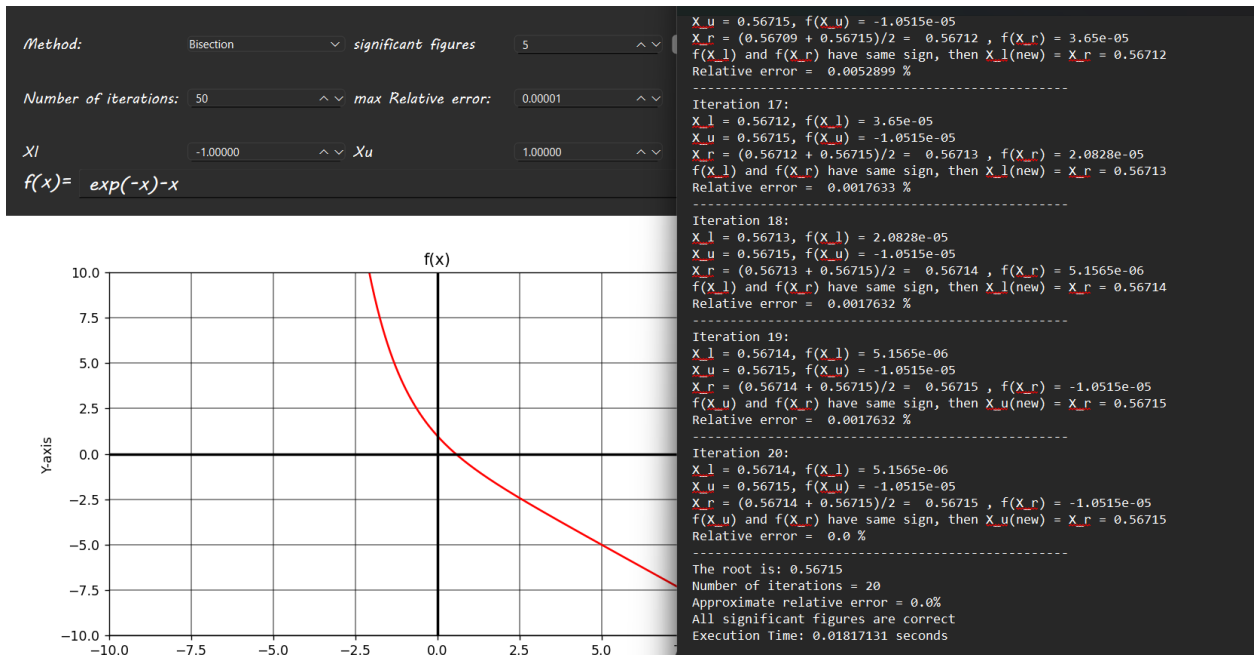


2. Will assume that $g(x) = e^{-x}$:

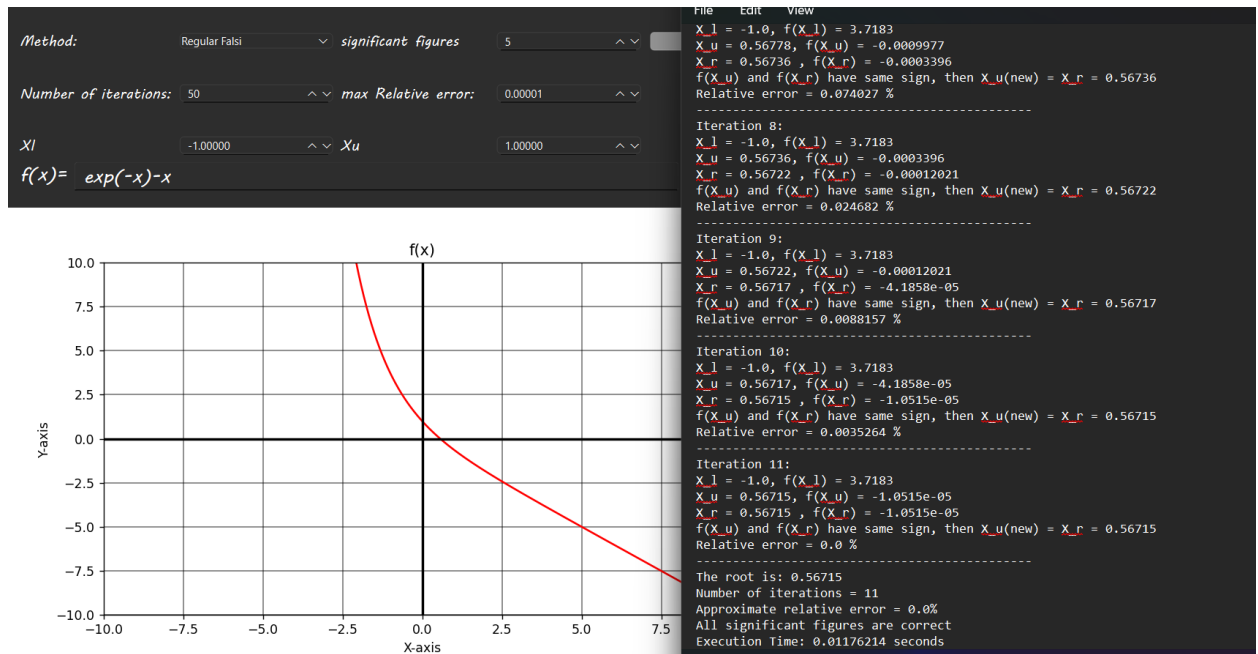


Methods:

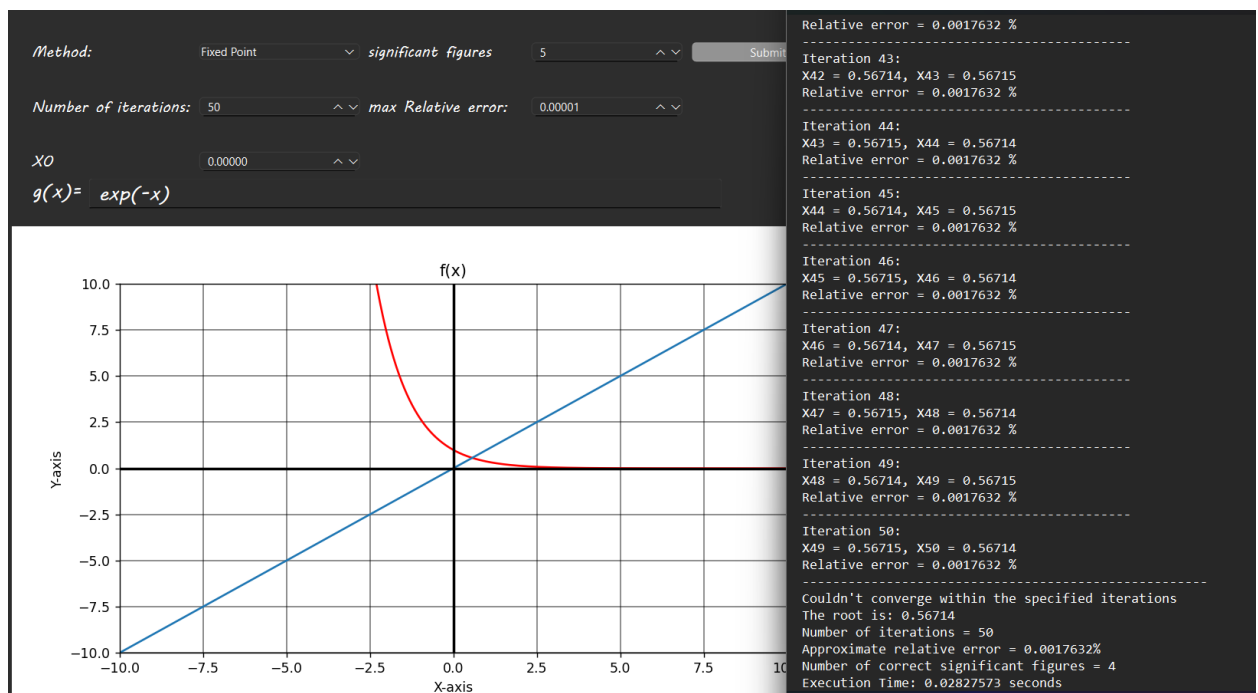
• Bisection



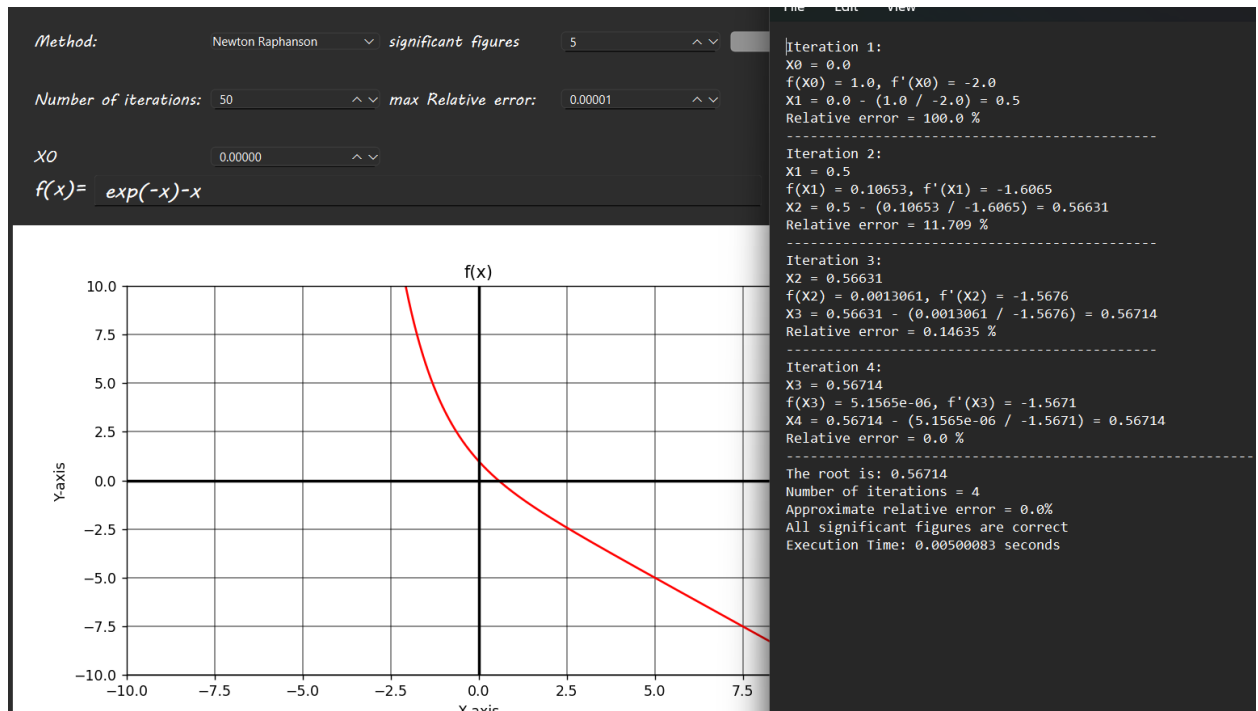
- False Position



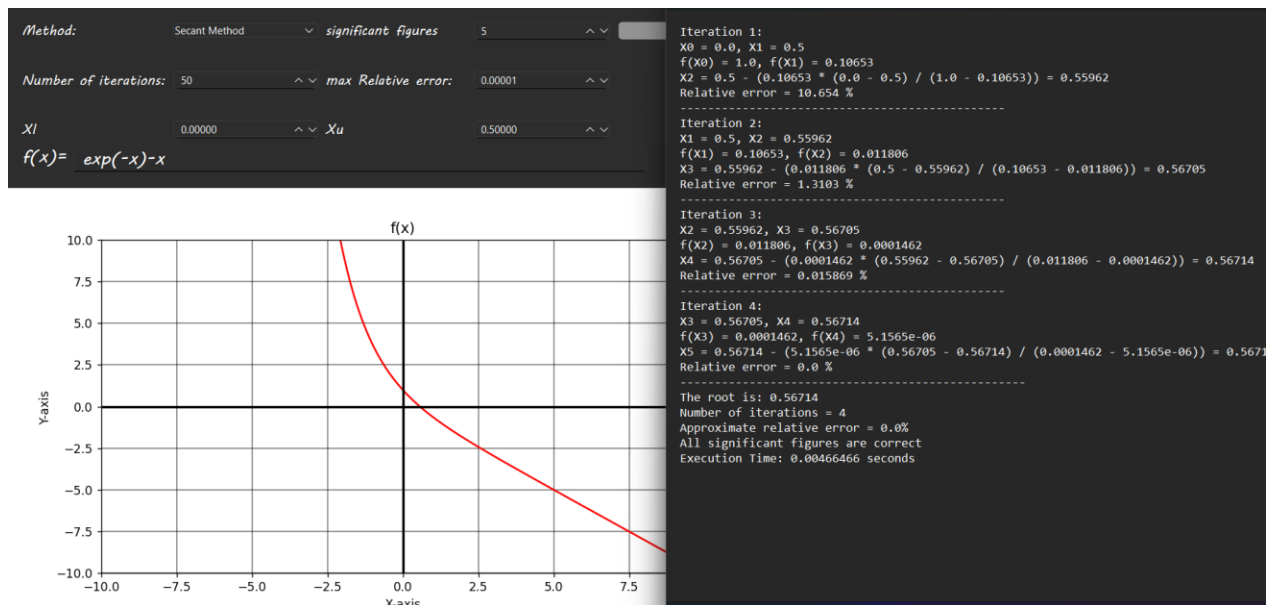
- Fixed Point



- Org Newton Raphson



- Secant



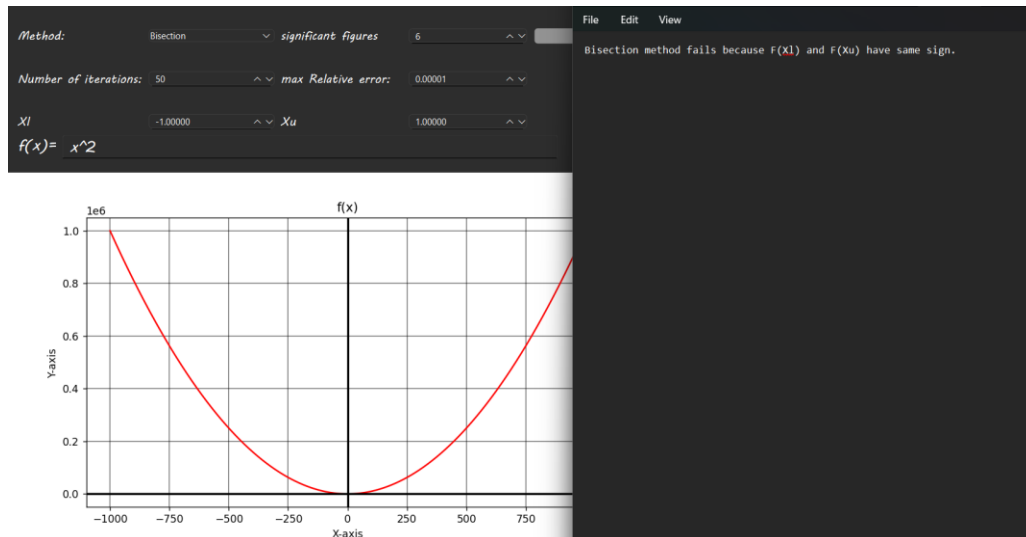
Comparable Table:

Method	Number of iterations	Run time	App. Root	initial guess	Relative Error
Bisection	20	0.01817131 sec	0.56715	$X_l = -1$ $X_u = 1$	0 %
False Position	11	0.01176214 sec	0.56715	$X_l = -1$ $X_u = 1$	0 %
Fixed Point	50	0.02827573 sec	0.56714	$X_o = 0$	0.0017632 %
Original Newton	4	0.005 sec	0.56714	$X_o = 0$	0 %
Secant	4	0.00466466 sec	0.56714	$X_o = 0$ $X_1 = 0.5$	0 %

Comments:

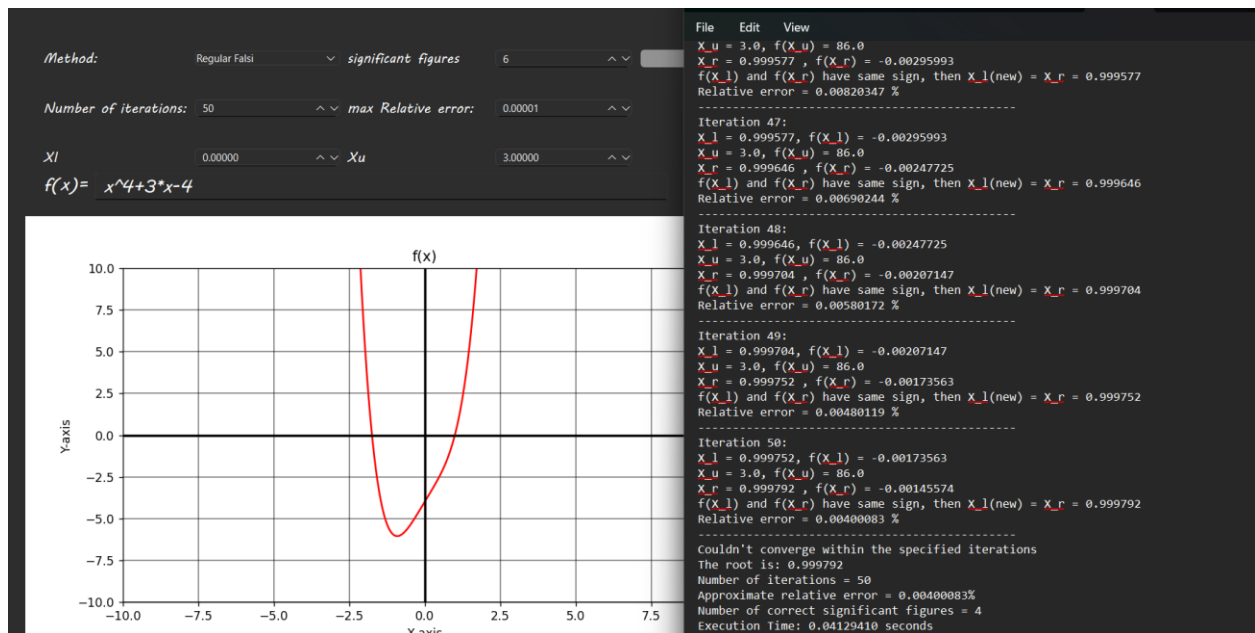
- **Efficiency:** The Original Newton method and Secant were the most efficient.
- **Accuracy:** All methods achieved high accuracy **except** the Fixed Point method having a very small relative error and doesn't reach the needed epsilon so the iterations stopped due to reaching max number iterations = 50
- **Iterations:** The Fixed Point method required the most iterations, indicating lower efficiency for this specific problem.

TC_3:



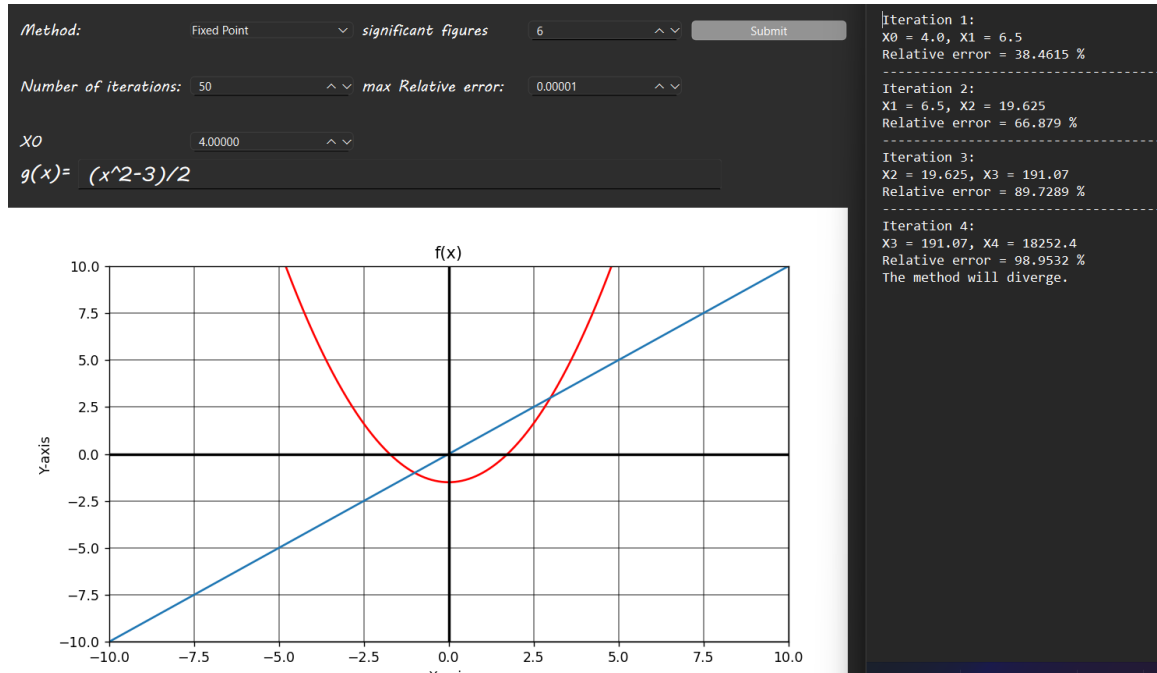
- As shown, in the graph $F(-1)$ and $F(1)$ are both positive and the only condition to apply Bisection method is that $F(-1) * F(1) < 0$, so **Bisection Method FAILS.**

TC_4:



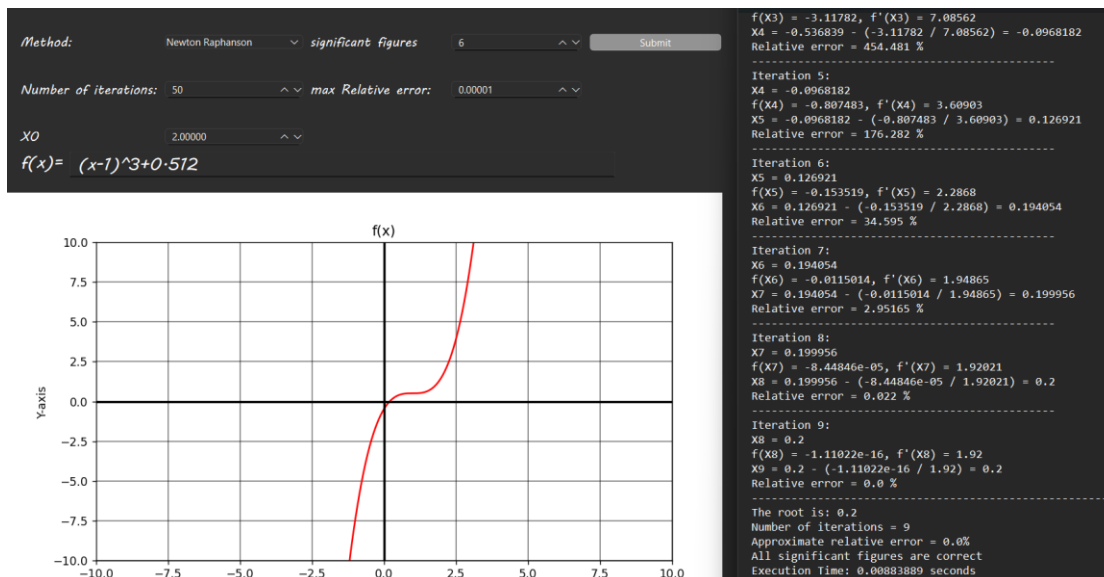
- As shown, it **couldn't converge** within the max number of iterations
With error = 0.004% > epsilon (0.00001)

TC_5:



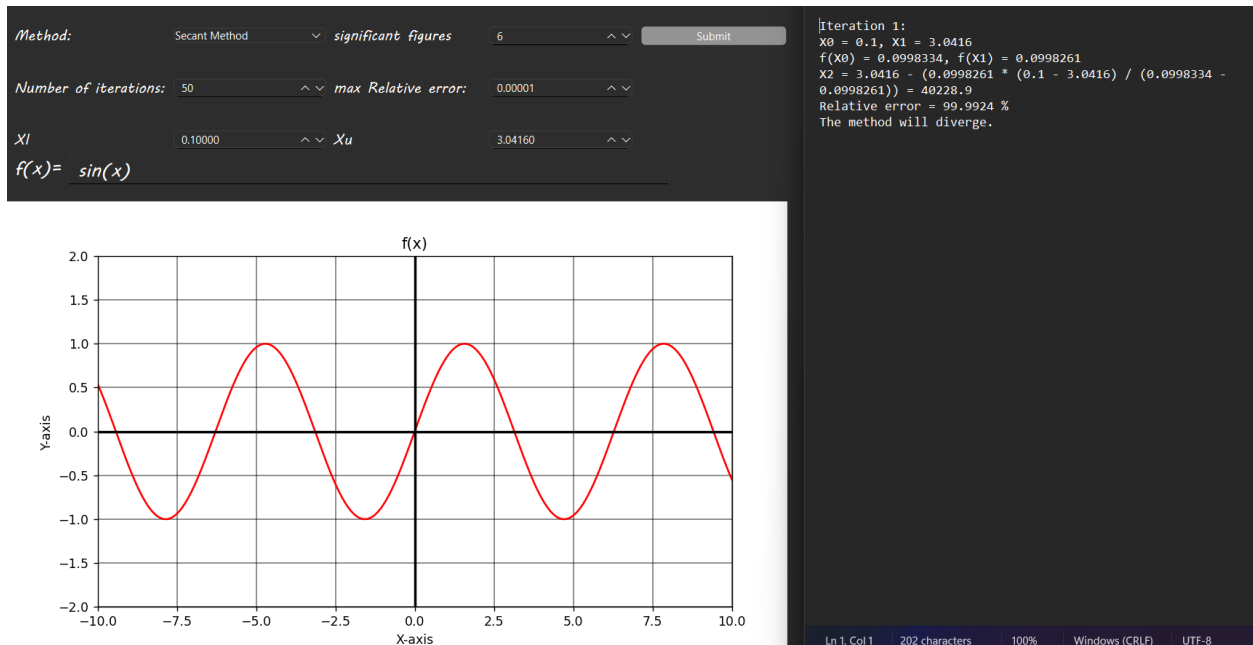
- As shown, in fourth iteration X increased enormously in one jump so **It will Diverge**.

TC_6:



- Will **converge** to exact root which is 0.2 after 9 iterations with error = 0%

TC_7:



- As shown, **it will diverge** as x increased enormously and according to my assumption that if x increased enormously in one jump so it will diverge.

4. Comparison between methods

Method	Time	Convergence	Error
Bisection	Very Slow	Always Converge Converge Linearly	The error decreases linearly with each iteration.
False Position	Faster than Bisection but still slow	Always converge Converge Linearly	the error may decrease faster than Bisection.
Fixed Point	The slower method in the open methods	May converge and may diverge according to initial guess and $g(x)$ Converge quadratically	The error decreases according to the convergence rate
Original Newton	Fast (if near the root)	May converge and may diverge according to initial guess Converge quadratically	The error typically decreases quadratically after each iteration.
Modified Newton	The fastest Method (if near the root)	May converge and may diverge according to initial guess Converge quadratically	The error typically decreases quadratically after each iteration, which makes this method very fast when it works well.
Secant	Fast (Slower than Newton)	May converge and may diverge according to initial guesses Converge quadratically	The error in each iteration can decrease roughly

5. Data Structures used

- **Arrays:** primarily used for numerical computations and evaluation Like **NumPy arrays**.
- **Lists:** Collects and formats output messages for display or logging.

Advantages:

- Arrays provide direct indexing for rapid access.
- Lists offer dynamic sizing for iterative methods.