# Assignment 1

# Part 1: Continuous Bandit Algorithm

# Part 2: Theory

a) Proof.

$$\begin{split} P(\text{greedy action}) &= 1 - P(\text{not greedy action}) \\ &= 1 - P(\text{not greedy selection } AND \text{ not greedy action}) \\ &= 1 - P(\text{not greedy selection}) \cdot P(\text{not greedy action} \mid \text{not greedy selection}) \\ &= 1 - \epsilon \cdot \left(\frac{k-1}{k}\right) \qquad \quad ^* \textit{Since there is only one greedy action} \\ &= 1 - \epsilon \cdot \left(1 - \frac{1}{k}\right) \\ &= 1 - \epsilon + \frac{\epsilon}{k} \end{split}$$

b) i) *Proof.* 

To determine the probability that the greedy action was chosen for the first time at time T, we need to consider that it was not chosen at any time before T, and that it was chosen at time T.

Thus, the following equation should be quantified:

$$P(\text{greedy at }T) = P(\text{not greedy before }T) \cdot P(\text{greedy at }T)$$

Therefore, the probability that the greedy action was chosen for the first time at time T is:

$$\begin{split} P(\text{greedy at } T) &= P(\text{not greedy before } T) \cdot P(\text{greedy at } T) \\ &= \left(1 - 1 + \epsilon - \frac{\epsilon}{k}\right)^{T-1} \cdot \left(1 - \epsilon + \frac{\epsilon}{k}\right) \\ &= \left(\epsilon - \frac{\epsilon}{k}\right)^{T-1} \cdot \left(1 - \epsilon + \frac{\epsilon}{k}\right) \end{split}$$

ii) Proof.

To get the expected number of steps,  $\mathbb{E}[T]$ , until the the greedy action is chosen for the first time is a sum over all possible time steps, each weighted by its probability of being the

first time the greedy action is chosen.

Thus, the following equation should be quantified:

$$\mathbb{E}[T] = \sum_{t=1}^{\infty} t \cdot P(\text{greedy at } t)$$

Following, the equation is

$$\mathbb{E}[T] = \sum_{t=1}^{\infty} t \cdot P(\text{greedy at } t)$$
$$= \sum_{t=1}^{\infty} t \cdot \left(\epsilon - \frac{\epsilon}{k}\right)^{t-1} \cdot \left(1 - \epsilon + \frac{\epsilon}{k}\right)$$

It can be observed that the above equation is a geometric series, which can be simplified to the following:

$$\mathbb{E}[T] = \sum_{t=1}^{\infty} t \cdot \left(\epsilon - \frac{\epsilon}{k}\right)^{t-1} \cdot \left(1 - \epsilon + \frac{\epsilon}{k}\right)$$
$$= \frac{1}{\left(\epsilon - \frac{\epsilon}{k}\right)^{t-1} \cdot \left(1 - \epsilon + \frac{\epsilon}{k}\right)}$$

The above simplification is valid due to the definiton of the expected value of a geometric series.

c) i) Proof.

Firstly, denote  $\max(q(1), q(2), \dots, q(10))$  as  $q_*$ .

The algorithm will choose the greedy selection,  $q_*$  with probability  $1 - \epsilon$ , and a non-greedy selection with probability  $\epsilon$ .

Moreover, the expected value of the an action during non-greedy selection is the average of all the action values, which is  $\frac{\sum_{i=1}^{10} q(i)}{10}$ .

Therefore, the long-run reward is

$$R = (1 - \epsilon) \cdot q_* + \epsilon \cdot \frac{\sum_{i=1}^{10} q(i)}{10}$$

ii) Proof.

Since  $q(1), q(2), \ldots, q(10)$  are i.i.d. random variables, the expected value of a greedy action becomes  $\mathbb{E}[q_*] = b$ .

Moreover, since q(a) is  $\mathcal{N}(0,1)$ , the expected average of all the action values becomes  $\mathbb{E}\left[\frac{\sum_{i=1}^{10} q(i)}{10}\right] = 0$ .

Therefore, the long-run reward is

$$R = (1 - \epsilon) \cdot \mathbb{E}[q_*] + \epsilon \cdot \mathbb{E}\left[\frac{\sum_{i=1}^{10} q(i)}{10}\right]$$
$$= (1 - \epsilon) \cdot b + \epsilon \cdot 0$$
$$= (1 - \epsilon) \cdot b$$

d) • Restatement In any stochastic bandit problem, denoted as  $\nu$ , where you have a set of actions A that is either finite or can be counted (like a list), and a fixed number of rounds or steps  $n \in \mathbb{N}$ , the regret  $R_n$  of following a certain strategy or policy  $\pi$  in this environment can be calculated as follows:

The total regret  $R_n$  is the sum of the regrets for each individual action in A. The regret for each action a is the product of two things: the suboptimality gap  $\Delta_a$  of action a (which is how much less reward you expect from action a compared to the best possible action), and the expected number of times  $E[T_a(n)]$  that action a is chosen within the first n rounds.

Mathematically, this is represented as:

$$R_n = \sum_{a \in A} \Delta_a E[T_a(n)]$$

This means you add up the products of the suboptimality gap and the expected number of selections for each action to find the total regret.

#### Proof

Proof.

Before the proof, we need to redefine the above terms to be consistent with S&B's notation.

Firstly, the set of actions, A, is the set of arms, k.

Secondly, the suboptimality gap,  $\Delta_a$ , is the difference between the expected reward of the optimal action,  $\max_{1 \le a \le k} q_*(a)$ , and the expected reward of action  $q_*(a)$ :

$$\Delta_a = \max_{1 \le a \le k} q_*(a) - q_*(a)$$

Thirdly, the expected number of times  $E[T_a(n)]$  that action a is chosen within the first n rounds is the expected number of times that action a is chosen within the first n rounds:

$$\mathbb{E}[T_a(n)] = \mathbb{E}[N_n(a)]$$

Since the regret is the difference in choosing the optimal action and the action chosen, it can be expressed as follows:

$$\operatorname{Reg}_n = n \cdot \max_{1 \le a \le k} q_*(a) - \mathbb{E}[R_n]$$

where n is the number of rounds,  $\max_{1 \le a \le k} q_*(a)$  is the expected reward of the optimal action, and

 $\mathbb{E}[R_n]$  is the expected reward of the action chosen up to round n.

To further break down the term  $\mathbb{E}[R_n]$ , we can transform it into a term that descirbes actions, rather than rewards.

Thus, consider the following representation:

$$R_n = \sum_{t=1}^{n} \sum_{a=1}^{k} R_t(a) \cdot \mathbb{1}_{A_t = a}$$

Now, the regret can be expressed as follows:

$$\operatorname{Reg}_{n} = n \cdot \max_{1 \leq a \leq k} q_{*}(a) - \mathbb{E}[R_{n}]$$
$$= n \cdot \max_{1 \leq a \leq k} q_{*}(a) - \mathbb{E}\left[\sum_{t=1}^{n} \sum_{a=1}^{k} R_{t}(a) \cdot \mathbb{1}_{A_{t}=a}\right]$$

Using properties of the expected value and that we are summing over n time steps, the above equation can be simplified to the following:

$$\operatorname{Reg}_{n} = n \cdot \max_{1 \leq a \leq k} q_{*}(a) - \mathbb{E}\left[\sum_{t=1}^{n} \sum_{a=1}^{k} R_{t}(a) \cdot \mathbb{1}_{A_{t}=a}\right]$$
$$= \sum_{a=1}^{k} \sum_{t=1}^{n} \mathbb{E}\left[\max_{1 \leq a \leq k} q_{*}(a) - R_{t}(a) \cdot \mathbb{1}_{A_{t}=a}\right]$$

The expected reward on round t is conditional on the action chosen on round t,  $A_t$ . Thus, the expected value term can be expressed as follows:

$$\mathbb{E}\left[\max_{1\leq a\leq k}q_*(a) - R_t(a)\cdot \mathbb{1}_{A_t=a}|A_t\right] = \mathbb{1}_{A_t=a}\mathbb{E}\left[\max_{1\leq a\leq k}q_*(a) - R_t(a)|A_t\right]$$
$$= \mathbb{1}_{A_t=a}\left(\max_{1\leq a\leq k}q_*(a) - q(a)\right)$$
$$= \mathbb{1}_{A_t=a}\cdot \Delta_a$$

The term  $\sum_{t=1}^{n} \mathbb{1}_{A_t=a}$  is the number of times that action a is chosen within the first n rounds,  $N_n(a)$ .

Therefore, we get the final result that the formula for the regret is

$$\operatorname{Reg}_n = \sum_{a=1}^k \Delta_a \cdot \mathbb{E}[N_n(a)]$$

## e) • Algorithm Restatement in S&B Terms

(a) Initialization:

- For each action a (in 1, 2, ..., k):
  - \* Initialize action-value estimate  $Q_t(a) = 0$ .
  - \* Initialize the number of times action a has been chosen,  $N_t(a) = 0$ .

(b) Loop for each step t = 1, 2, 3, ...:

- Select action  $A_t$  using the UCB criterion:

$$A_t = \operatorname*{arg\,max}_{a} \left[ Q_t(a) + c \sqrt{\frac{\ln t}{N_t(a)}} \right]$$

where c is a confidence level parameter.

- Take action  $A_t$ , observe reward  $R_t$ .
- Update the action-value estimate for  $A_t$ :

$$Q_{t+1}(A_t) = Q_t(A_t) + \frac{1}{N_t(A_t)}(R_t - Q_t(A_t))$$

- Increment  $N_t(A_t)$ .

#### • Proof Restatement

In a k-armed bandit problem using the UCB algorithm, for any time step t, the expected regret  $R_t$  is bounded by:

$$R_t \le 3\sum_{i=1}^k \Delta_i + \sum_{i:\Delta_i > 0} \frac{16\log(t)}{\Delta_i}$$

where  $\Delta_i = q_*(a^*) - q_*(a_i)$  is the regret associated with choosing action  $a_i$  instead of the optimal action  $a^*$ .

## (a) Optimal Action Assumption:

Assume that the first arm  $a_1$  is optimal, so  $q_*(a_1) = q_*(a^*)$ , where  $q_*(a)$  represents the true value of action a.

### (b) Regret Decomposition:

The total regret after t steps is:

$$R_t = \sum_{i=1}^k \Delta_i E[N_t(a_i)]$$

where  $E[N_t(a_i)]$  is the expected number of selections of action  $a_i$  up to time t.

# (c) Defining "Good" Event $G_i$ :

Define the good event  $G_i$  for a suboptimal arm  $a_i$  as:

$$G_i = \left\{ q_*(a_1) < \min_{\tau \le t} UCB(a_1, \tau) \right\} \cap \left\{ \hat{q}_\tau(a_i) + \sqrt{\frac{2\log(1/\delta)}{N_\tau(a_i)}} < q_*(a_1) \,\forall \, \tau \le t \right\}$$

where  $\hat{q}_{\tau}(a_i)$  is the estimated value of action  $a_i$  at time  $\tau$ ,  $N_{\tau}(a_i)$  is the number of times action  $a_i$  has been selected up to time  $\tau$ , and  $\delta$  is a confidence level parameter.

# (d) Bounding $E[N_t(a_i)]$ under $G_i$ :

Show that under  $G_i$ ,  $a_i$  is selected at most  $u_i$  times, where  $u_i$  is a function of  $\Delta_i$  and  $\delta$ . This leads to:

$$E[N_t(a_i)|G_i] < u_i$$

### (e) Bounding Probability of $G_i^c$ :

The probability of the complement event  $G_i^c$  (where the good event does not occur) is small. It is bounded using concentration inequalities.

#### (f) Expected Selection Bound:

Combine these results to express  $E[N_t(a_i)]$ :

$$E[N_t(a_i)] = E[N_t(a_i)|G_i|P(G_i) + E[N_t(a_i)|G_i^c]P(G_i^c) \le u_i + tP(G_i^c)$$

### (g) Choosing $u_i$ and c:

The choice of  $u_i$  is made to ensure that the upper confidence bound for suboptimal arm  $a_i$  is properly controlled. A natural choice for  $u_i$ , considering the balance between exploration and exploitation, is given by:

$$u_i = \left\lceil \frac{2\log(1/\delta)}{(1-c)^2 \Delta_i^2} \right\rceil$$

where  $\delta$  is the confidence level parameter, and c is a constant.

In the proof, c is chosen to be 1/2 somewhat arbitrarily but in a way that balances the two terms in the regret bound. This choice leads to a simplification of the regret bound while maintaining a balance between exploration and exploitation.

#### (h) Finalizing the Bound on $R_t$ :

With  $u_i$  and c chosen, the final bound on  $R_t$  is derived by substituting these values into the regret decomposition:

$$R_t \le \sum_{i:\Delta_i > 0} \Delta_i \left( \left\lceil \frac{2\log(1/\delta)}{(1-c)^2 \Delta_i^2} \right\rceil + tP(G_i^c) \right)$$

Applying the choice of c = 1/2, the final bound simplifies to:

$$R_t \le 3\sum_{i=1}^k \Delta_i + \sum_{i: \Delta_i > 0} \frac{16\log(t)}{\Delta_i}$$

f) We consider a stochastic k-armed bandit problem where the goal is to maximize cumulative rewards over time.

We use the Upper Confidence Bound (UCB) algorithm for arm selection. Let  $Q_n$  be the average reward at time n for a chosen arm, and let  $a^*$  be the optimal arm. We aim to prove that:

$$\lim_{n \to \infty} \mathbb{E}[Q_n] = q_*(a^*)$$

where  $q_*(a^*)$  is the expected reward of the optimal arm.

Proof.

### • Theorem 7.1 Recap

Theorem 7.1 provides an upper bound on the regret  $R_n$  for the UCB algorithm:

$$R_n \le 3\sum_{i=1}^k \Delta_i + \sum_{i:\Delta_i > 0} \frac{16\log(n)}{\Delta_i}$$

where  $\Delta_i$  is the difference between the expected reward of the optimal arm and arm i.

• Definition of  $Q_n$ 

 $Q_n$  is defined as the average of rewards received from taking action a up to time t:

$$Q_n = \frac{\sum_{i=1}^t R_i \cdot \mathbb{1}_{A_i = a}}{\sum_{i=1}^t \mathbb{1}_{A_i = a}}$$

where  $R_i$  is the reward received at time i,  $A_i$  is the action taken at time i, and  $\mathbb{1}_{A_i=a}$  is the indicator function.

By the law of large numbers, for each arm a, the average reward converges to the expected reward  $q_*(a)$  as n increases.

Therefore,

$$\frac{\sum_{i=1}^{n} R_i \cdot \mathbb{1}_{A_i = a}}{\sum_{i=1}^{n} \mathbb{1}_{A_i = a}} \to q_*(a)$$

as  $n \to \infty$ .

The UCB algorithm selects arms based on the estimated reward and the uncertainty in that estimate. Over time, it favors arms with higher estimated rewards.

For the optimal arm  $a^*$ , as  $n \to \infty$ , the UCB algorithm will increasingly favor this arm, assuming it correctly identifies it. Therefore, the frequency of selecting arm  $a^*$ , denoted by  $N_{a^*}(n)$ , will dominate over other arms, leading to:

$$\frac{N_{a^*}(n)}{n} \to 1$$

and for each suboptimal arm a,

$$\frac{N_a(n)}{n} \to 0$$

Given the dominance of the optimal arm in selections, the limit of the expected average reward  $\mathbb{E}[Q_n]$  converges to the expected reward of the optimal arm:

$$\lim_{n \to \infty} \mathbb{E}[Q_n] = q_*(a^*)$$

Under the UCB algorithm, the expected average reward for the arm selected by the algorithm converges to the expected reward of the optimal arm as the number of trials n goes to infinity.