# Machine Learning LSTM

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# Long **Short-Term** Memory (LSTM) Networks

- One special kind of RNNs introduced by Hochreiter and Schmidhuber in 1997
- Goal: to address the vanishing gradient problem in RNNs in long sequences
- LSTM key goal is to create a smarter state that allows longer flow of information in the feedforward and backpropagation
  - People interpret that as being able to remember for a longer time
  - We call it the cell state
- To do so, LSTM introduces the concept of gates that will help it control the flow of information: 3 gates
  - What to forget from the from the last cell state?
  - What new information we're going to store in the cell state?
  - What to select for the output?

## Gates Concept

- Gates are used to control the flow of information through the network.
  - Control: what to pass and what to discard
  - As a result, we also control the gradient backpropagation!

#### Implementation

- Typically implemented using sigmoid activation functions
  - These values are used to scale the amount of information passed through.
  - A value close to 0 means "let nothing through,"
  - A value close to 1 means "let everything through."
- Example: input [10, 30, 8] and sigmoids [0, 0.5, 1]  $\Rightarrow$  element wise multiplication:
  - $[10 \times 0, 30 \times 0.5, 8 \times 1] = [0, 15, 8] \Rightarrow$  cancel 10, half of 30 and keep all 8
- We learn **weights** to decide the gates values
- Popular examples:
  - LSTM (forget, input, output gates) GRUs (update, rest gates)

#### **Gates Roles**

- Memory Management:
  - We can't keep all historical information (RNN fails)
  - We can select information to remain over long sequences
- Gradient Flow:
  - As we control the feedforward flow, we control the gradients tii
  - This help mitigate the vanishing and exploding gradient problems
- Modeling Complex Patterns:
  - With the flow control, the network may learn complex dependencies and patterns
- Interpretation: Assume a sigmoid value 0.7
  - Some people interpret it as we keep (select) 70% of the value
  - Some people interpret it as we forget (throw away) 30% of the value

## Creating a Gate

- Assume you want a gate (e.g. to forget something)
- We utilize 2 1-D vectors
  - Your input vector X for this time step
  - Your hidden state (network output) of the last step
- We create a transformation that will learn the gate
  - We need 2 weight matrices to transform each vector and add bias
  - Transform and perform element wise addition
- Finally, use sigmoid to generate the learned [0-1] range

```
def transform(Wx, x_t, Wh, h_t, b):
    # Transform the 2 vectors and do element-wise addition
    return np.dot(Wx, x_t) + np.dot(Wh, h_t) + b

def gate(Wx, x_t, Wh, h_t, b):
    t = transform(Wx, x_t, Wh, h_t, b)
    return sigmoid(t) # [0-1] for scaling values
```

# **Creating Gates**

- Based on your logic, you can learn many gates
- Below, we prepare 3 gates. Each gate helps learning 2 weight matrices

```
# What to keep from the history
f_t = gate(Wf, x_t, Uf, h_t, bf)
# What to keep from the input
i_t = gate(Wi, x_t, Ui, h_t, bi)
# What to keep from the output
o_t = gate(Wo, x_t, Uo, h_t, bo)
```

#### LSTM: Accumulation Trick

- ullet Recall RNN:  $h_t = anh(x_t W_{ih}^T + b_{ih} + h_{t-1} W_{hh}^T + b_{hh})$
- In LSTM, the first key change is we don't just REPLACE the old state with the fused state, but we ACCUMULATE to it
  - This accumulation helps the gradient flow. Kind of a weak skip connection in resent
  - Observe: C\_t: series of tanh() additions

```
# Code before gates
h_t, C_t = initial_states
for x_t in inputs:
    # non-linear Transformation for input and history (like RNN)
    fused_state = tanh(transform(Wc, x_t, Uc, h_t, bc))

# ACCUMULATE to the previous history (Cell state)
C_t = C_t + fused_state
    # Output hidden state
h_t = tanh(C_t)
```

#### LSTM: Gates Trick

- We can identify ~3 components in the last code
- We can learn a gate for everyone and let the network control their flows
- The way the author interpreted them:
  - Forget Gate: Decides what information should be thrown away from the cell state.
    - Prevent accumulation of irrelevant information to avoid gradients issues (e.g. vanish)
  - o **Input Gate**: Decides which values should be updated in the cell state.
    - They call the fused state; the state candidate!
  - Output Gate: Determines what part of the cell state should be output at the current timestep.
- Remember; we learn the weights that help the control

#### LSTM: Gates Trick

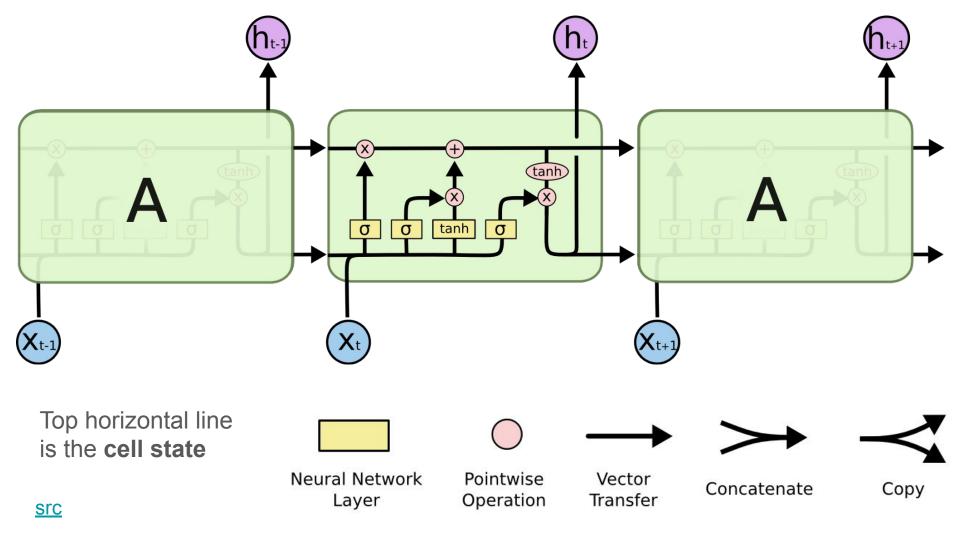
```
h t, C t = initial states
for x t in inputs:
   # What to keep from the history
    f t = qate(Wf, x t, Uf, h t, bf)
   # What to keep from the input / fused state
   i t = gate(Wi, x t, Ui, h t, bi)
   # What to keep from the output
   o t = qate(Wo, x t, Uo, h t, bo)
    fused state = tanh(transform(Wc, x t, Uc, h t, bc))
   # Select from old state + select from fused state
   C t = f t * C t + i t * fused state
   # Select what to output
   h t = o t * tanh(C t)
```

#### Imagine:

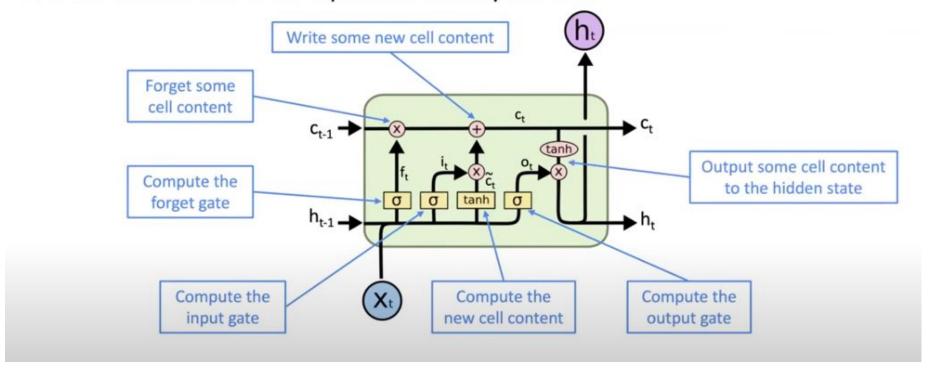
- f\_t = 1
- -it = 0
- This means the network decided to preserve the state and ignore new element (e.g. duplicate frame)

#### **LSTM Overall**

- These 2 tricks allows the gradients to flow through the network without undergoing the transformations that typically lead to vanishing or exploding gradients for long sequences.
  - People consider the cell state the long memory and hidden state the short memory!
  - But hidden output state is just tanh(cell state)!
- Common practice: Any input feed to some transformation should have some kind of normalization / activation to have stable network
  - Empirically tanh validated across a wide range of sequence modeling tasks
    - Try input scales: [-1, 1] and [0, 1]
- In practice, LSTM may work well in range like 100-500 steps
  - o Beyond that, gradient will vanish. Depends on the data complexity.
- Note: Gated Recurrent Units (GRUs)
  - GRUs simplify the LSTM model with 2 gates only and achieves close performance



#### You can think of the LSTM equations visually like this:

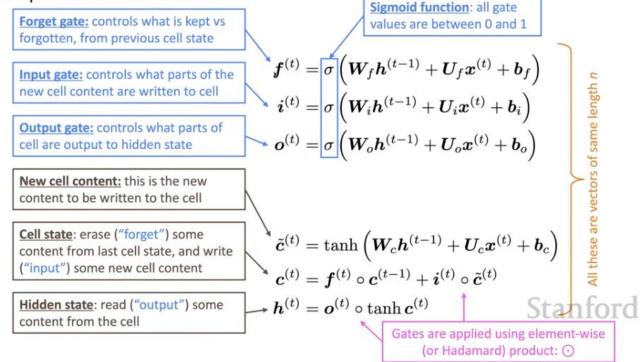




#### Long Short-Term Memory (LSTM)



We have a sequence of inputs  $x^{(t)}$ , and we will compute a sequence of hidden states  $h^{(t)}$  and cell states  $c^{(t)}$ . On timestep t:

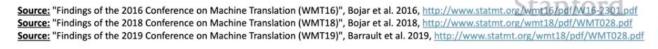




#### LSTMs: real-world success

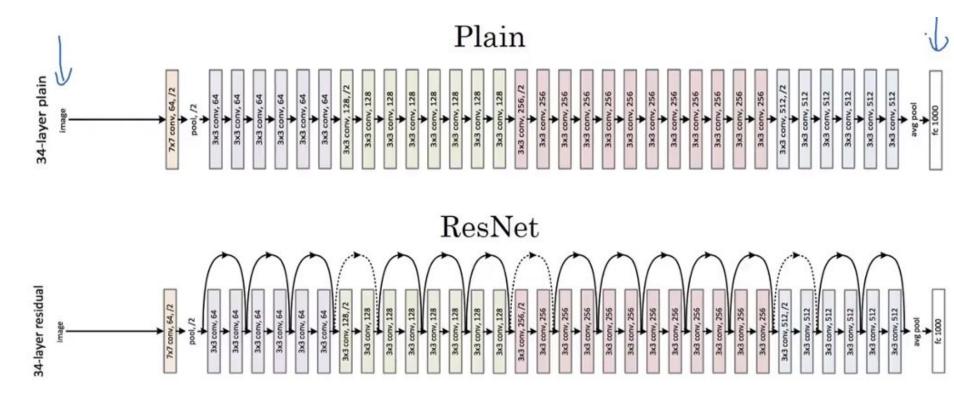


- In 2013–2015, LSTMs started achieving state-of-the-art results
  - Successful tasks include handwriting recognition, speech recognition, machine translation, parsing, and image captioning, as well as language models
  - LSTMs became the dominant approach for most NLP tasks
- Now (2021), other approaches (e.g., Transformers) have become dominant for many tasks
  - For example, in WMT (a Machine Translation conference + competition):
    - In WMT 2014, there were 0 neural machine translation systems (!)
    - In WMT 2016, the summary report contains "RNN" 44 times (and these systems won)
    - In WMT 2019: "RNN" 7 times, "Transformer" 105 times





### Little about Resnet





#### Relevant Materials

- Understanding LSTM Networks: <u>Article</u>
  - One of the oldest articles in 2015 that helped many people understand LSTM
  - Most of articles just follow it
- StateQuest
- Lecture from <u>Stanford</u>
- There are LSTM variants, e.g. B-LSTM (B for Bidirectional)

"Acquire knowledge and impart it to the people."

"Seek knowledge from the Cradle to the Grave."