

# A reconciliation between finite-sample and asymptopia-based methods in conditional independence testing

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- This a joint work with



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- ArXiv link: <https://arxiv.org/pdf/2211.14698.pdf>

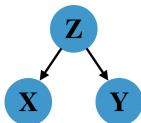
# Outline

- ① Hardness of CI Testing and regularity conditions  $\mathcal{R}_n$
- ② Two choices of  $\mathcal{R}_n$  : dCRT statistic and GCM statistic
- ③  $\widehat{\text{dCRT}}$  Test and its equivalence to GCM Test
- ④ Numerical simulation

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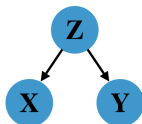
# Hardness of conditional independence testing



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$$H_0^{CI} = \mathbf{X} \perp\!\!\!\perp \mathbf{Y} | \mathbf{Z}.$$

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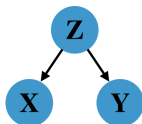


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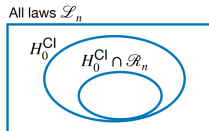
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- **Hardness of CI test:** According to Shah and Peters [2020],
  - If  $\mathbf{Z}$  is continuous, any test with Type-I error control over the entire CI null  $H_0^{CI} : \mathbf{X} \perp\!\!\!\perp \mathbf{Y} | \mathbf{Z}$  **cannot have nontrivial power against any alternative.**  
 $\Rightarrow$  a test with type-I error control must protect against too many sneaky ways  $\mathbf{Z}$  can affect both  $\mathbf{X}$  and  $\mathbf{Y}$ .

# CI testing requires assumptions

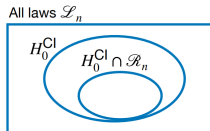
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What kind of regularity conditions  $\mathcal{R}_n$  should we impose?

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# dCRT statistic

## dCRT statistic

- **Model-X (MX) assumption Candes et al. [2018]:** Assume we know the conditional distribution  $\mathcal{L}_n(\mathbf{X}|\mathbf{Z})$  exactly, i.e.

$$\mathcal{R}_n = \{\mathcal{L}_n : \mathcal{L}_n(\mathbf{X}|\mathbf{Z}) = \mathcal{L}_n^*(\mathbf{X}|\mathbf{Z})\}.$$

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- This is an asymptopia-based method as opposed to resampling nature of dCRT. It enjoys the **double robustness**.

## Theorem 1 (Shah and Peters [2020]; informal)

For  $\mathcal{L}_n \in H_0 = H_0^{CI} \cap \mathcal{R}_n$ , where  $\mathcal{R}_n$  is defined as a set of laws satisfying

$$\left\{ \text{RMSE}(\hat{\mu}_{n,x}) = o_P(1), \text{RMSE}(\hat{\mu}_{n,y}) = o_P(1), \text{RMSE}(\hat{\mu}_{n,x}) \cdot \text{RMSE}(\hat{\mu}_{n,y}) = o_P(n^{-1/2}) \right\},$$

then we have

$$\limsup_{n \rightarrow \infty} \sup_{\mathcal{L}_n \in H_0} \mathbb{P}_{\mathcal{L}_n}[\text{GCM rejects null}] \leq \alpha.$$

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- **Our focus:** Robustness and power of MX (dCRT) methods when  $\mathcal{L}_n^*(\mathbf{X}|\mathbf{Z})$  learned in sample. In other words, replace  $\mu_{n,x}(\cdot)$  with the estimate  $\hat{\mu}_{n,x}(\cdot)$  and draw resamples from the learned distribution  $\mathcal{L}_n^*(X_i | \mathbf{Z} = Z_i)$ .



Procedure:

- Fit an approximation  $\hat{\mu}_{n,y}(\mathbf{Z})$  of  $\mu_{n,y}(\mathbf{Z}) = \mathbb{E}_{\mathcal{L}_n}[\mathbf{Y}|\mathbf{Z}]$  via machine learning;
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- Compute  $T_n(X, Y, Z) = \frac{1}{\sqrt{n}} \sum_{i=1}^n (X_i - \mu_{n,x}(Z_i))(Y_i - \hat{\mu}_{n,y}(Z_i))$ ;
- For  $b = 1, \dots, B$ 
  - Draw  $\tilde{X}_i^{(b)} \sim \mathcal{L}_n^*(\mathbf{X}_i | \mathbf{Z} = Z_i)$ ;
  - Compute test statistic

$$T_n(\tilde{X}^{(b)}, X, Y, Z) = \frac{1}{\sqrt{n}} \sum_{i=1}^n (\tilde{X}_i^{(b)} - \hat{\mu}_{n,x}(Z_i))(Y_i - \hat{\mu}_{n,y}(Z_i));$$

- Compute

$$C_{n,\alpha}(X, Y, Z) = \mathbb{Q}_{1-\alpha}[\{T_n(X, Y, Z), T_n(\tilde{X}^{(1)}, X, Y, Z), \dots, T_n(\tilde{X}^B, X, Y, Z)\}].$$

- Reject if  $T_n(X, Y, Z) > C_{n,\alpha}(X, Y, Z)$ .

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- Recall the test statistic and resampling test statistic

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$$\frac{T_n(X, Y, Z)}{S_n^{\widehat{\text{dCRT}}}(X, Y, Z)} > \mathbb{Q}_{1-\alpha} \left[ \frac{T_n(\tilde{X}, X, Y, Z)}{S_n^{\widehat{\text{dCRT}}}(X, Y, Z)} | X, Y, Z \right],$$

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- The normalized  $\widehat{\text{dCRT}}$  resampling distribution convergence to  $N(0, 1)$ .

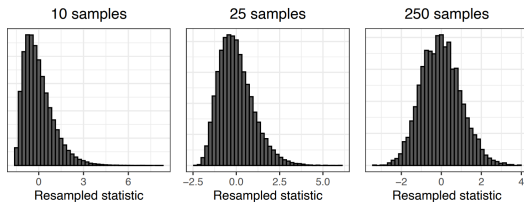
# Convergence of $\widehat{\text{dCRT}}$ resampling distribution to $N(0, 1)$

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# $\widehat{\text{dCRT}}$ -GCM equivalence and $\widehat{\text{dCRT}}$ robustness

Equivalence result:

**Theorem (Niu et al '22; informal).** Assume

1.  $\text{RMSE}(\hat{\mu}_{n,x}) = o_P(1)$ ,  $\text{RMSE}(\hat{\mu}_{n,y}) = o_P(1)$ ,  $\text{RMSE}(\hat{\mu}_{n,x}) \cdot \text{RMSE}(\hat{\mu}_{n,y}) = o_P(n^{-1/2})$ .
2. The estimated variances are consistent in the following sense:

$$\frac{1}{n} \sum_{i=1}^n (\text{Var}_{\widehat{\mathcal{L}}_n}[X_i | Z_i] - \text{Var}_{\mathcal{L}_n}[X_i | Z_i]) \text{Var}_{\mathcal{L}_n}[Y_i | Z_i] \xrightarrow{P} 0.$$

Then, for any  $\mathcal{L}_n \in H_0$ , the  $\widehat{\text{dCRT}}$  is asymptotically equivalent to the GCM test, i.e.

$$\lim_{n \rightarrow \infty} \inf_{\mathcal{L}_n \in H_0} \mathbb{P}_{\mathcal{L}_n}[\text{GCM test and } \widehat{\text{dCRT}} \text{ coincide}] = 1.$$

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Double robustness result:

**Corollary (Niu et al '22; informal).** Given conditions 1 & 2,  $\widehat{\text{dCRT}}$  is doubly robust:

$$\limsup_{n \rightarrow \infty} \sup_{\mathcal{L}_n \in H_0} \mathbb{P}_{\mathcal{L}_n}[\widehat{\text{dCRT}} \text{ rejects null}] \leq \alpha.$$

# Outline

- ① Hardness of CI Testing and regularity conditions  $\mathcal{R}_n$
- ② Two choices of  $\mathcal{R}_n$  : dCRT statistic and GCM statistic
- ③  $\widehat{\text{dCRT}}$  Test and its equivalence to GCM Test
- ④ Numerical simulation

# Numerical simulation: Design

- Consider

$$Z \sim N(0, \Sigma(p)), \mathcal{L}(X|Z) = N(Z^\top \beta, 1), \mathcal{L}(Y|X, Z) = N(X\theta + Z^\top \beta, 1)$$

where

$$\Sigma_{ij}(p) = \rho^{|i-j|}, \beta_j = \begin{cases} \nu & \text{if } j \leq s, \\ 0 & \text{if } j > s. \end{cases}$$

Parameters  $\nu$  and  $\theta$  control degree of confounding and signal strength.

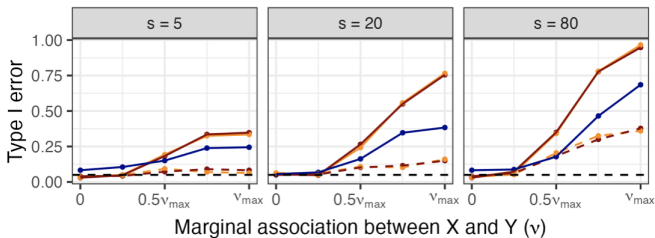
- Methods compared:
  - $\widehat{\text{dCRT}}^1$  and GCM (with lasso and post-lasso);
  - Maxway CRT (a competitive method).

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<sup>1</sup>We will use dCRT instead in the following.

# Numerical simulations: Type-I error control

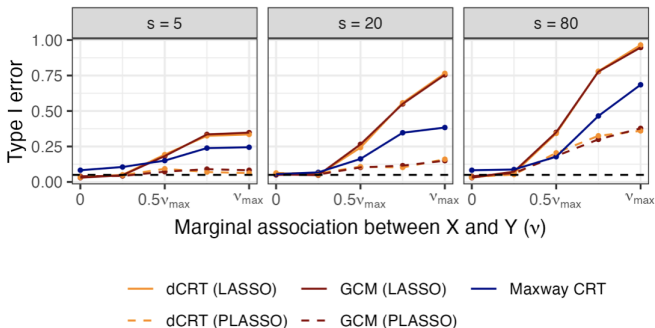
$n = 200$ ;  $p = 400$ ;  $\rho = 0.4$



— dCRT (LASSO)    — GCM (LASSO)    — Maxway CRT  
- - dCRT (PLASSO)    - - GCM (PLASSO)

# Numerical simulations: Type-I error control

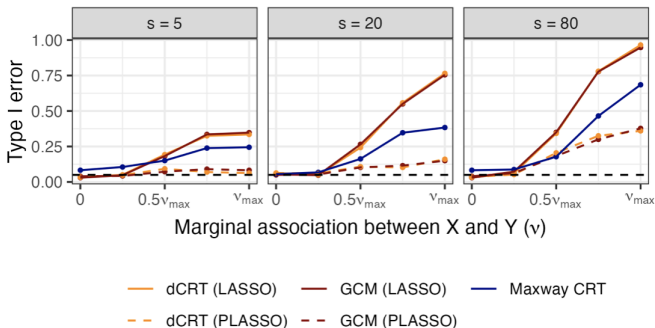
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- Some takeaways:

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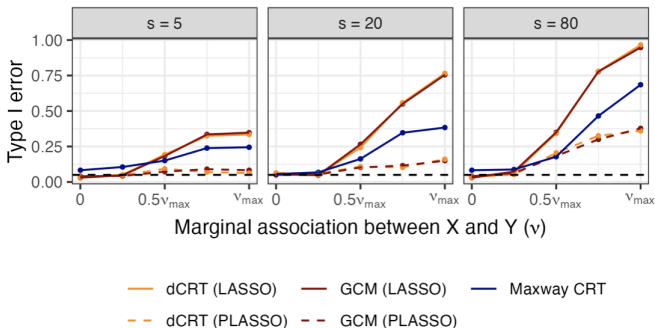


- Some takeaways:
  - GCM and dCRT perform similarly, consistent with asymptotic theory.



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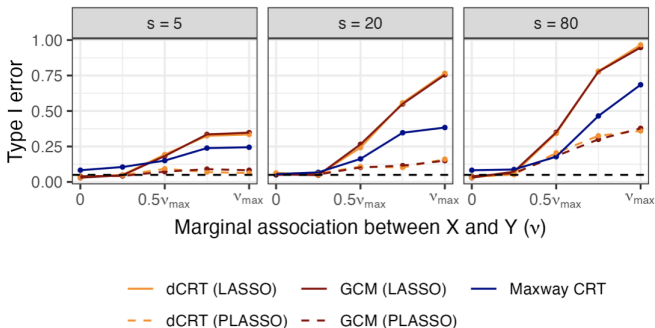
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# Numerical simulations: Type-I error control

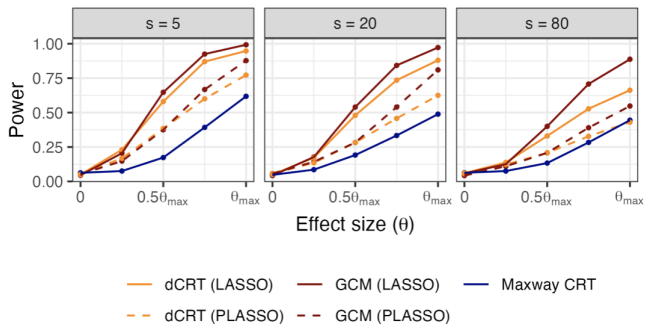
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- Some takeaways:
  - GCM and dCRT perform similarly, consistent with asymptotic theory.
  - Lasso-based methods can have very inflated Type-I error in difficult settings.
  - Post-lasso-based dCRT and GCM typically outperform Maxway CRT.

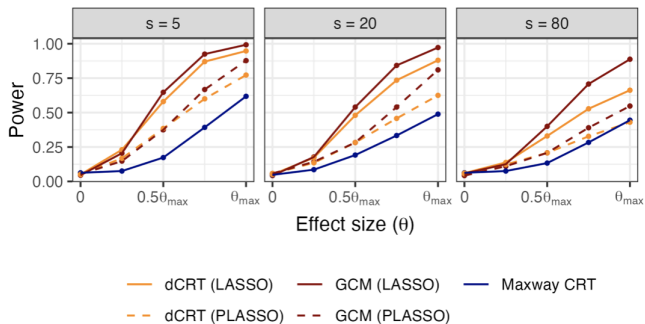
# Numerical simulations: Power

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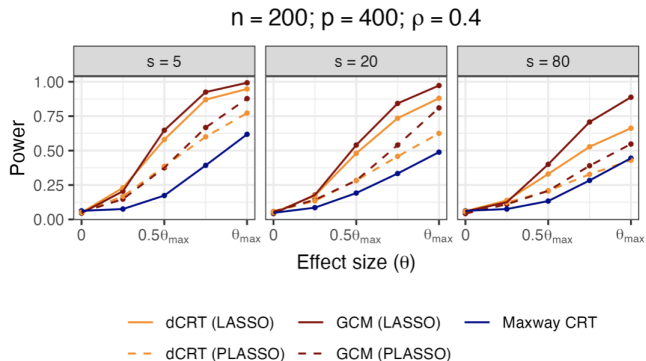
# Numerical simulations: Power

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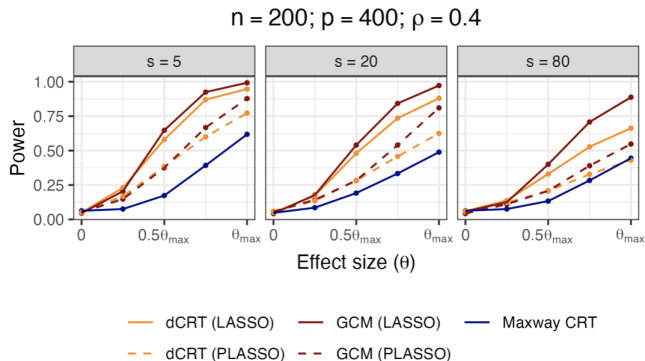
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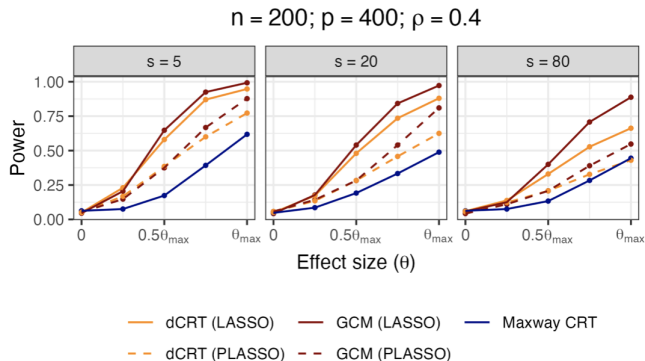
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- Some takeaways:
  - GCM tends to outperform dCRT.
  - Lasso outperforms post-lasso, suggesting bias-variance trade-off.
  - Maxway CRT has lowest power, due to data splitting.

# References

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