

Novel Optimization-based Multilevel CVT Construction Algorithm

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Outline

- *Introduction*
 - Centroidal Voronoi tessellation (CVT) formulation
- *Multigrid-based Optimization for CVT construction*
 - Multigrid Optimization (MG/OPT) algorithm: background
 - Applying MG/OPT to the CVT Formulation
- Numerical Experiments
 - 1-dimensional examples
 - 2-dimensional examples
- Comments and Conclusions

Centroidal Voronoi tessellation (CVT)

- Given

- a set of points $\{\mathbf{z}_i\}_{i=1}^k$ (generators)
- a set of regions $\{V_i\}_{i=1}^k$ (Voronoi tessellation)

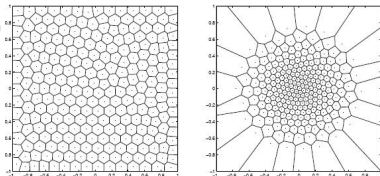
- Define *the centroids*:
$$\mathbf{z}_i^* = \frac{\int_{V_i} \rho(\mathbf{y}) \mathbf{y} d\mathbf{y}}{\int_{V_i} \rho(\mathbf{y}) d\mathbf{y}}$$

- Define *energy functional*:

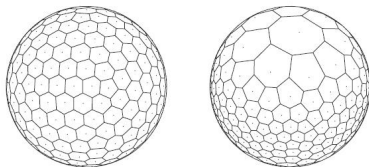
$$\mathcal{G}(\{\mathbf{z}_i\}_{i=1}^k) = \sum_{i=1}^k \int_{V_i} \rho(\mathbf{y}) |\mathbf{y} - \mathbf{z}_i|^2 d\mathbf{y}.$$

- The minimizer of \mathcal{G} forms a CVT with $\mathbf{z}_i = \mathbf{z}_i^*$.
This illustrates the optimization property of the CVT

tessellations of a square



tessellations on a sphere



Some Methods to construct CVTs

- Fixed-point iteration methods:
 - Lloyd method (Lloyd 1960s)
- Probabilistic methods:
 - random k-means methods (Macqueen 1966)
 - random 2-clustering method (Imai et.al 1994)
- Newton-based methods:
 - Newton-Lloyd method (Du/Emelianenko 2008)
 - quasi-Newton L-BFGS method (Liu et.al 2009)
- Multigrid/multilevel methods:
 - Lloyd-Multilevel (Du/Emelianenko 2008)
 - Multilevel Lloyd-Max (Koren/Yavneh 2003,2006)

Introduction of MG/OPT

- MG/OPT is a **general** framework to accelerate a traditional optimization algorithm labeled "OPT", first introduced in [S.G. Nash 2000].
- Recursively use coarse problems to generate search directions for fine problems
- Inspired by multigrid for elliptic PDEs
 - highly efficient algorithm

Notations of MG/OPT components

- **OPT**: a convergent optimization algorithm:

$$\mathbf{z}^+ \leftarrow \text{Opt}(\mathcal{G}(\cdot), \mathbf{v}, \bar{\mathbf{z}}, k)$$

- h : fine grid; H : coarse grid
- a high-fidelity model \mathcal{G}_h
- a low-fidelity model \mathcal{G}_H
- a downdate operator I_h^H
- an update operator I_H^h

Multigrid Optimization Algorithm (MG/OPT)

- Given:
 - an initial estimate \mathbf{v}_h^0 of the solution \mathbf{z}_h on the fine level
 - Integers k_1 and k_2 satisfying $k_1 + k_2 > 0$

- One iteration of MG/OPT:

- Pre-smoothing*: $\bar{\mathbf{z}}_h \leftarrow \text{Opt}(\mathcal{G}_h(\cdot), \mathbf{v}_h, \mathbf{z}_h^j, k_1)$
- Recursion*:
 - Compute

$$\begin{aligned}\bar{\mathbf{z}}_H &= I_h^H \bar{\mathbf{z}}_h \\ \bar{\mathbf{v}} &= \hat{I}_h^H \mathbf{v}_h + \nabla \mathcal{G}_H(\bar{\mathbf{z}}_H) - \hat{I}_h^H \nabla \mathcal{G}_h(\bar{\mathbf{z}}_h)\end{aligned}$$

- Apply MG/Opt recursively to the surrogate model:

$$\mathbf{z}_H^+ \leftarrow \text{MG/Opt}(\mathcal{G}_H(\cdot), \bar{\mathbf{v}}, \bar{\mathbf{z}}_H)$$

- Compute the search directions $\mathbf{e}_H = \mathbf{z}_H^+ - \bar{\mathbf{z}}_H$ and $\mathbf{e}_h = I_H^h \mathbf{e}_H$.
- Use a line search to determine $\mathbf{z}_h^+ = \bar{\mathbf{z}}_h + \alpha \mathbf{e}_h$ satisfying $\mathcal{G}_h(\mathbf{z}_h^+) \leq \mathcal{G}_h(\bar{\mathbf{z}}_h)$.
- Post-smoothing*: $\mathbf{z}_h^{j+1} \leftarrow \text{Opt}(\mathcal{G}_h(\cdot), \mathbf{v}_h, \mathbf{z}_h^+, k_2)$

Properties of MG/OPT

- Not dependent on a specific (single-grid) optimization algorithm
- Isolates optimization algorithm, differential equation solver, grid generation
- Convergence & descent can be guaranteed
- Excellent performance at initial iteration

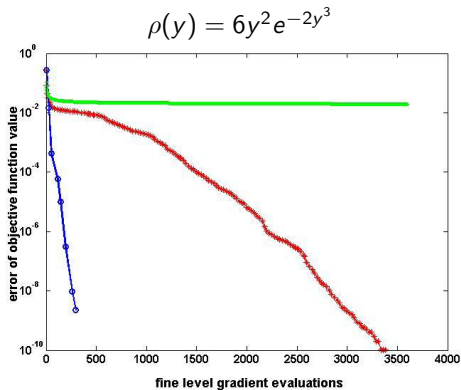
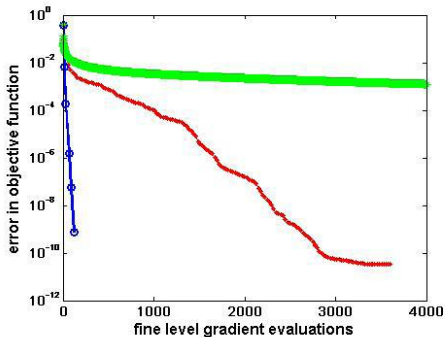
MG/OPT setup

- We have chosen OPT to be **the truncated-Newton algorithm** in our experiments
- 1-D case:
 - Downdate from finer to coarser grid:
 - **Solution restriction (injecton)**: $[I_h^H v_h]^i = v_h^{2i}, \quad i = 1, 2, \dots, k/2$
 - **Gradient restriction (scaled full weighting)**:

$$[\hat{I}_h^H v_h]^i = \frac{1}{2} v_h^{2i-1} + v_h^{2i} + \frac{1}{2} v_h^{2i+1}, \quad i = 1, 2, \dots, k/2$$
 - Update from coarser to finer grid: $I_H^h = (\hat{I}_h^H)^T$
- 2-D case:
 - Downdate from finer to coarser grid:
 - Solution restriction is performed by **injection**
 - **Gradient restriction**: $[\hat{I}_h^H v_h]^i = \sum_j \alpha_j^i v_h^j$, where $\alpha_i^i = 1$ and $\alpha_j^i = \frac{1}{2}$ for any j s.t. z_j is a fine node sharing an edge with z_i in the fine level triangulation
 - Update from coarser to finer grid: $I_H^h = 4(\hat{I}_h^H)^T$

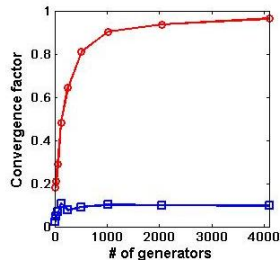
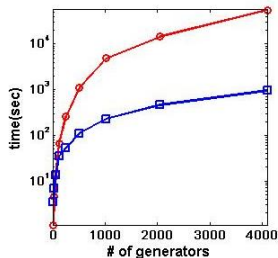
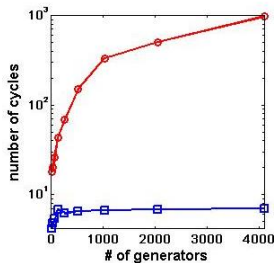
Convergence Result on 1-D CVT

Blue: MG/Opt; Red: OPT; Green: Lloyd
 $\rho(y) = 1$



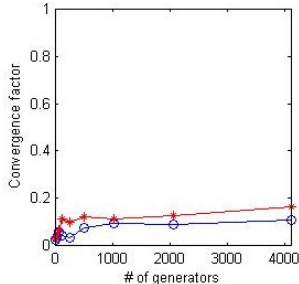
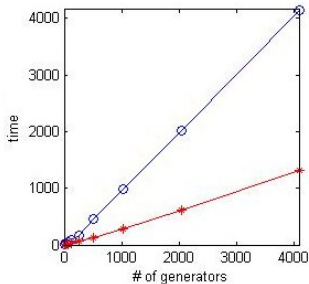
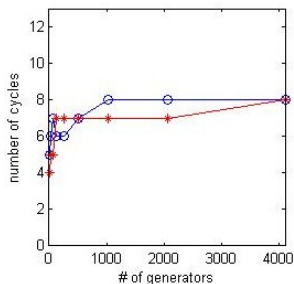
Convergence Result on 1-D CVT (cont'd)

Solving problems of increasing size, MG/Opt versus OPT ($\rho(y) = 1$). Blue: MG/Opt, Red: OPT;



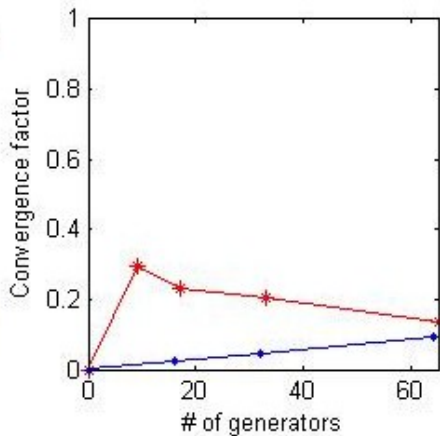
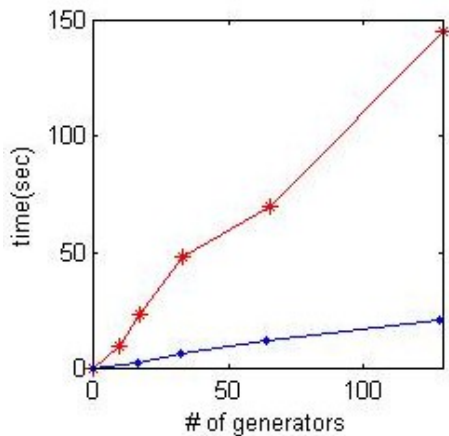
Convergence Result on 1-D CVT (cont'd)

Performance of MG/Opt with different density functions. Blue: $\rho(y) = 1 + 0.1y$.
Red: $\rho(y) = 6y^2e^{-2y^3}$



Comparison with Multilevel-Lloyd

Convergence factors for MG/Opt vs. Multilevel-Lloyd $\rho(y) = 1$; Blue: MG/Opt;
Red: Multilevel-Lloyd



Comparison with Multilevel Lloyd-Max

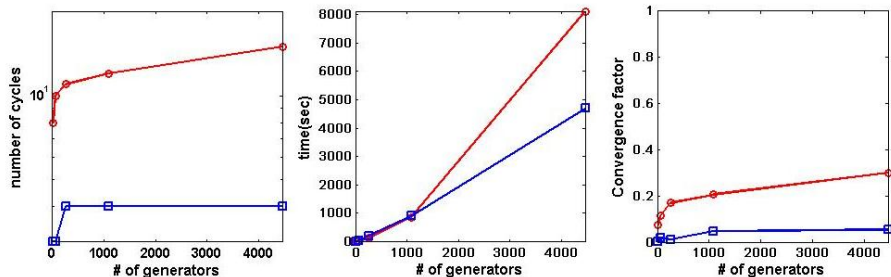
| | convergence factor | | | |
|-----|---------------------|---------------------|--------|--------|
| k | MG/Opt ² | MG/Opt ¹ | MLM | OPT |
| 16 | 0.0350 | 0.0023 | 0.1725 | 0.8060 |
| 32 | 0.0314 | 0.0177 | 0.1782 | 0.9024 |
| 64 | 0.0673 | 0.0551 | 0.1847 | 0.9381 |
| 128 | 0.1120 | 0.0673 | 0.1962 | 0.9736 |

Table: MG/OPT v.s. Multilevel Lloyd-Max v.s. OPT; density: $y = 6x^2e^{-2x^3}$

$$C^1 = \frac{|\mathcal{G}(\mathbf{z}^{k+1}) - \mathcal{G}(\mathbf{z}^*)|}{|\mathcal{G}(\mathbf{z}^k) - \mathcal{G}(\mathbf{z}^*)|}; \quad C^2 = \left(\frac{|\mathcal{G}(\mathbf{z}^{k+1}) - \mathcal{G}(\mathbf{z}^*)|}{|\mathcal{G}(\mathbf{z}^1) - \mathcal{G}(\mathbf{z}^*)|} \right)^{\frac{1}{k+1}}$$

Convergence Result on 2-D CVT based on triangular domain

Red: Opt; Blue: MG/OPT; $\rho(x) = 1$



Di/Emelianenko/Nash, to appear in NMTMA, 2011

Results and challenges

- CVT is in the heart of many applications and the number is growing: computer science, physics, social sciences, biology, engineering ...
- The main advantage of MG/OPT is its superior convergence speed, and the fact that it preserves low convergence factor regardless of the problem size.
- The simplicity of its design and the results of preliminary tests suggest that the method is generalizable to higher dimensions, which is the subject of further investigations
- Future work also includes application of this technique to various scientific and engineering applications, including image analysis and grid generation.

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THANKS!