Prof. Luis Gustavo Nonato

SME/ICMC - USP

August 29, 2017

From previous classes we learned that the eigenvectors of a graph Laplacian behave similarly to a Fourier basis, motivating the development of graph-based Fourier analysis theory.

From previous classes we learned that the eigenvectors of a graph Laplacian behave similarly to a Fourier basis, motivating the development of graph-based Fourier analysis theory.

A major obstacle to the development of a graph signal processing theory is the irregular and coordinate-free nature of a graph domain.

From previous classes we learned that the eigenvectors of a graph Laplacian behave similarly to a Fourier basis, motivating the development of graph-based Fourier analysis theory.

A major obstacle to the development of a graph signal processing theory is the irregular and coordinate-free nature of a graph domain.

For instance, signal translation is basic operation for signal processing. However, that operation is not naturally implemented in graph domains.

Let G = (V, E) be a weighted graph, **L** be its corresponding graph Laplacian, and  $f : V \to \mathbb{R}$  a function defined on the vertices of G.

Let G = (V, E) be a weighted graph, **L** be its corresponding graph Laplacian, and  $f : V \to \mathbb{R}$  a function defined on the vertices of G.

#### **Graph Fourier Transform**

The Graph Fourier Transform of f is defined as

$$\mathcal{GF}[f](\lambda_l) = \hat{f}(\lambda_l) = \langle f, u_l \rangle = \sum_{i=1}^n f(i)u_l(i)$$

Let G = (V, E) be a weighted graph, **L** be its corresponding graph Laplacian, and  $f : V \to \mathbb{R}$  a function defined on the vertices of G.

#### **Graph Fourier Transform**

The Graph Fourier Transform of f is defined as

$$\mathcal{GF}[f](\lambda_l) = \hat{f}(\lambda_l) = \langle f, u_l \rangle = \sum_{i=1}^n f(i)u_l(i)$$

#### **Inverse Graph Fourier Transform**

The Inverse Graph Fourier Transform is given by

$$\mathcal{IGF}[\hat{f}](i) = f(i) = \sum_{l=0}^{n-1} \hat{f}(\lambda_l) u_l(i)$$

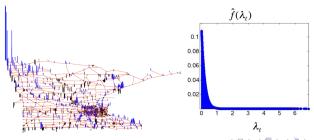
$$\hat{f}(\lambda_l) = \sum_{i=1}^n f(i)u_l(i)$$

The eigenvalues of L play the role of frequencies and the eigenvectors the Fourier basis.

$$\hat{f}(\lambda_l) = \sum_{i=1}^n f(i)u_l(i)$$

The eigenvalues of L play the role of frequencies and the eigenvectors the Fourier basis.

The graph Fourier transform (and its inverse) gives a way to represent a signal in two different domains: the vertex domain and the graph spectral domain.



# Graph Fourier Transform: Synthesizing Signals

$$f(i) = \sum_{l=0}^{n-1} \hat{f}(\lambda_l) u_l(i)$$

# Graph Fourier Transform: Synthesizing Signals

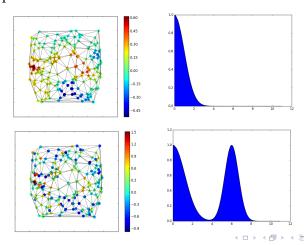
$$f(i) = \sum_{l=0}^{n-1} \left[ \hat{f}(\lambda_l) \right] u_l(i) \Rightarrow f(i) = \sum_{l=0}^{n-1} \hat{g}(\lambda_l) u_l(i)$$

We can generate signals in the graph domain by using a kernel in the spectral domain.

# Graph Fourier Transform: Synthesizing Signals

$$f(i) = \sum_{l=0}^{n-1} \left[ \hat{f}(\lambda_l) \right] u_l(i) \Rightarrow f(i) = \sum_{l=0}^{n-1} \hat{g}(\lambda_l) u_l(i)$$

We can generate signals in the graph domain by using a kernel in the spectral domain.



In classical signal processing, frequency filtering is given by amplifying or attenuating the contributions of some Fourier Basis.

$$\mathcal{L}[f] = f * h \rightarrow \mathcal{F}[f * h] = \hat{f}\hat{h}$$

In classical signal processing, frequency filtering is given by amplifying or attenuating the contributions of some Fourier Basis.

$$\mathcal{L}[f] = f * h \to \mathcal{F}[f * h] = \hat{f}\hat{h}$$

Taking the IGFT

$$\mathcal{L}[f](i) = \sum_{l=0}^{n-1} \hat{f}(\lambda_l) \hat{h}(\lambda_l) u_l(i)$$
 (1)

Suppose  $\hat{h}(\lambda_l) = \sum_{k=0}^{K} a_k \lambda_l^k$  (polynomial on the spectral domain)

In classical signal processing, frequency filtering is given by amplifying or attenuating the contributions of some Fourier Basis.

$$\mathcal{L}[f] = f * h \to \mathcal{F}[f * h] = \hat{f}\hat{h}$$

Taking the IGFT

$$\mathcal{L}[f](i) = \sum_{l=0}^{n-1} \hat{f}(\lambda_l) \hat{h}(\lambda_l) u_l(i)$$
 (1)

Suppose  $\hat{h}(\lambda_l) = \sum_{k=0}^{K} a_k \lambda_l^k$  (polynomial on the spectral domain)

Replacing  $\hat{h}(\lambda_l)$  and the definition of  $\hat{f}(\lambda_l)$  in Eq. (1) we get

$$\mathcal{L}[f](i) = \sum_{j=1}^{n} f(j) \sum_{k=0}^{K} a_k \sum_{l=1}^{n} \lambda_l^k u_l(j) u_l(i)$$

$$\mathcal{L}[f](i) = \sum_{i=1}^{n} f(j) \sum_{k=0}^{K} a_k \sum_{l=1}^{n} \lambda_l^k u_l(j) u_l(i)$$

$$\mathcal{L}[f](i) = \sum_{j=1}^{n} f(j) \sum_{k=0}^{K} a_k \sum_{l=1}^{n} \lambda_l^k u_l(j) u_l(i)$$
$$(\mathbf{L}^k)_{ij} = \sum_{l=1}^{n} \lambda_l^k u_l(j) u_l(i)$$

$$\mathcal{L}[f](i) = \sum_{j=1}^{n} f(j) \sum_{k=0}^{K} a_k \sum_{l=1}^{n} \lambda_l^k u_l(j) u_l(i)$$
$$(\mathbf{L}^k)_{ij} = \sum_{l=1}^{n} \lambda_l^k u_l(j) u_l(i)$$

It can be shown that  $(\mathbf{L}^k)_{ij} = 0$  when the shortest distance between nodes i and j is greater than k.

$$\mathcal{L}[f](i) = \sum_{j=1}^{n} f(j) \sum_{k=0}^{K} a_k \sum_{l=1}^{n} \lambda_l^k u_l(j) u_l(i)$$
$$(\mathbf{L}^k)_{ij} = \sum_{l=1}^{n} \lambda_l^k u_l(j) u_l(i)$$

It can be shown that  $(\mathbf{L}^k)_{ij} = 0$  when the shortest distance between nodes i and j is greater than k. Defining

$$b_{ij} = \sum_{k=0}^{K} a_k \, \mathbf{L}_{ij}^k$$

$$\mathcal{L}[f](i) = \sum_{j=1}^{n} f(j) \sum_{k=0}^{K} a_k \sum_{l=1}^{n} \lambda_l^k u_l(j) u_l(i)$$
$$(\mathbf{L}^k)_{ij} = \sum_{l=1}^{n} \lambda_l^k u_l(j) u_l(i)$$

It can be shown that  $(\mathbf{L}^k)_{ij} = 0$  when the shortest distance between nodes i and j is greater than k. Defining

$$b_{ij} = \sum_{k=0}^{K} a_k \mathbf{L}_{ij}^k$$
$$\mathcal{L}[f](i) = \sum_{j \in N_k(i)}^{n} b_{ij} f(j)$$

$$\mathcal{L}[f](i) = \sum_{j=1}^{n} f(j) \sum_{k=0}^{K} a_k \sum_{l=1}^{n} \lambda_l^k u_l(j) u_l(i)$$
$$(\mathbf{L}^k)_{ij} = \sum_{l=1}^{n} \lambda_l^k u_l(j) u_l(i)$$

It can be shown that  $(\mathbf{L}^k)_{ij} = 0$  when the shortest distance between nodes i and j is greater than k. Defining

$$b_{ij} = \sum_{k=0}^{K} a_k \, \mathbf{L}_{ij}^k$$

$$\mathcal{L}[f](i) = \sum_{j \in N_k(i)}^n b_{ij} f(j)$$

Therefore, when the filter is a polynomial in the spectral domain, the filtered signal in each node i is a linear combination of the original signal in the neighborhood of i.



The definition of convolution between two functions *f* and *g* is

$$(f * g)(x) = \int_{-\infty}^{\infty} f(x - t)g(t)dt$$

The definition of convolution between two functions *f* and *g* is

$$(f * g)(x) = \int_{-\infty}^{\infty} f(x - t)g(t)dt$$

Such definition can not be directly applied because the shift f(x-t) (or singal translation) is not defined in the context of graphs.

The definition of convolution between two functions *f* and *g* is

$$(f * g)(x) = \int_{-\infty}^{\infty} f(x - t)g(t)dt$$

Such definition can not be directly applied because the shift f(x-t) (or singal translation) is not defined in the context of graphs.

However, convolution can be defined as:

$$(f * g) = \mathcal{IGF}[\mathcal{GF}[(f * g)]]$$

The definition of convolution between two functions *f* and *g* is

$$(f * g)(x) = \int_{-\infty}^{\infty} f(x - t)g(t)dt$$

Such definition can not be directly applied because the shift f(x-t) (or singal translation) is not defined in the context of graphs.

However, convolution can be defined as:

$$(f * g) = \mathcal{IGF}[\mathcal{GF}[(f * g)]]$$

$$(f * g)(i) = \sum_{l=1}^{n} \hat{f}(\lambda_l) \hat{g}(\lambda_l) u_l(i)$$

$$f * g = g * f$$

$$f * g = g * f$$

$$f * (g + h) = f * g + f * h$$

$$f * g = g * f$$

$$f * (g + h) = f * g + f * h$$

## Graph Fourier Transform: Translation

# Graph Fourier Transform: Translation The classical translation

$$(T_t f)(x) = f(x - t)$$

can not be directly generalized to the graph setting.

# Graph Fourier Transform: Translation The classical translation

$$(T_t f)(x) = f(x - t)$$

can not be directly generalized to the graph setting.

However, translation can be seen as a convolution with the delta function

$$(T_t f)(x) = (f * \delta_t)(x)$$

# Graph Fourier Transform: Translation

The classical translation

$$(T_t f)(x) = f(x - t)$$

can not be directly generalized to the graph setting.

However, translation can be seen as a convolution with the delta function

$$(T_t f)(x) = (f * \delta_t)(x)$$

Recalling that  $\mathcal{F}[\delta(t-a)](\lambda) = e^{-\mathrm{i}2\pi\lambda a}$ , we define translation to a vertex j as

$$(T_j f)(i) = \sqrt{n} (f * \delta_j)(i) = \sqrt{n} \sum_{l=0}^{n-1} \hat{f}(\lambda_l) u_l(j) u_l(i)$$

# Graph Fourier Transform: Translation

The classical translation

$$(T_t f)(x) = f(x - t)$$

can not be directly generalized to the graph setting.

However, translation can be seen as a convolution with the delta function

$$(T_t f)(x) = (f * \delta_t)(x)$$

Recalling that  $\mathcal{F}[\delta(t-a)](\lambda) = e^{-\mathrm{i}2\pi\lambda a}$ , we define translation to a vertex j as

$$(T_j f)(i) = \sqrt{n} (f * \delta_j)(i) = \sqrt{n} \sum_{l=0}^{n-1} \hat{f}(\lambda_l) u_l(j) u_l(i)$$

The normalizing constant  $\sqrt{n}$  ensures that the translation operator preserves the mean of a signal, i.e.,

$$\sum_{i=1}^n (T_j f)(i) = \sum_{i=1}^n f(i)$$

$$T_j(f*g) = (T_jf)*g = f*(T_jg)$$

- $T_j(f * g) = (T_j f) * g = f * (T_j g)$
- $T_j T_k f = T_k T_j f$

$$T_i(f * g) = (T_i f) * g = f * (T_i g)$$

$$T_i T_k f = T_k T_i f$$

$$\sum_{i=1}^{n} (T_{j}f)(i) = \sqrt{n}\hat{f}(0) = \sum_{i=1}^{n} f(i)$$

- $T_i(f * g) = (T_i f) * g = f * (T_i g)$
- $T_j T_k f = T_k T_j f$
- $||T_i f|| \neq ||f||$  (the energy of the signal is not preserved)

$$(D_s f)(x) = \frac{1}{s} f(\frac{1}{s}) \Longrightarrow (\widehat{D_s f})(\lambda) = \hat{f}(s\lambda)$$

$$(D_s f)(x) = \frac{1}{s} f(\frac{1}{s}) \Longrightarrow (\widehat{D_s f})(\lambda) = \hat{f}(s\lambda)$$

in the graph setting,  $\frac{t}{s}$  is not well defined, impairing the direct generalization of dilation in the graph domain.

$$(D_s f)(x) = \frac{1}{s} f(\frac{1}{s}) \Longrightarrow (\widehat{D_s f})(\lambda) = \hat{f}(s\lambda)$$

in the graph setting,  $\frac{t}{s}$  is not well defined, impairing the direct generalization of dilation in the graph domain.

An alternative is to define dilation via GFT:

$$(D_s f)(i) = \sum_{l=0}^{n-1} \hat{f}(s \cdot \lambda_l) u_l(i)$$

$$(D_s f)(x) = \frac{1}{s} f(\frac{1}{s}) \Longrightarrow (\widehat{D_s f})(\lambda) = \hat{f}(s\lambda)$$

in the graph setting,  $\frac{t}{s}$  is not well defined, impairing the direct generalization of dilation in the graph domain.

An alternative is to define dilation via GFT:

$$(D_s f)(i) = \sum_{l=0}^{n-1} \hat{f}(s \cdot \lambda_l) u_l(i)$$

Notice that  $\hat{f}(s \cdot \lambda_l)$  might not be in the interval  $[0, \lambda_n]$ .

$$(D_s f)(x) = \frac{1}{s} f(\frac{1}{s}) \Longrightarrow (\widehat{D_s f})(\lambda) = \hat{f}(s\lambda)$$

in the graph setting,  $\frac{t}{s}$  is not well defined, impairing the direct generalization of dilation in the graph domain.

An alternative is to define dilation via GFT:

$$(D_s f)(i) = \sum_{l=0}^{n-1} \hat{f}(s \cdot \lambda_l) u_l(i)$$

Notice that  $\hat{f}(s \cdot \lambda_l)$  might not be in the interval  $[0, \lambda_n]$ . Therefore, dilation can only be used when f is generated from a kernel defined in the whole spectral domain.

Continous case:

$$M_{\lambda}f(t) = e^{-(2\pi \mathrm{i}\lambda t)}f(t)$$

Continous case:

$$M_{\lambda}f(t) = e^{-(2\pi i \lambda t)}f(t)$$

In the graph setting we can define

$$M_{\lambda_l}f(i) = \sqrt{n} u_l(i)f(i)$$

Continous case:

$$M_{\lambda}f(t) = e^{-(2\pi i \lambda t)}f(t)$$

In the graph setting we can define

$$M_{\lambda_l}f(i) = \sqrt{n} u_l(i)f(i)$$

In contrast to the continous case, modulation in the graph setting does not correspond to a translation in the spectral domain.

Continous case:

$$M_{\lambda}f(t) = e^{-(2\pi i \lambda t)}f(t)$$

In the graph setting we can define

$$M_{\lambda_l}f(i) = \sqrt{n} u_l(i)f(i)$$

In contrast to the continous case, modulation in the graph setting does not correspond to a translation in the spectral domain.

However, if f is generated from a kernel localized in 0, than  $\widehat{M_{\lambda_l}f}(i)$  is concentrated in  $\lambda_l$ .