# Central Limit Theorem and Bootstrap in High Dimensions

Zihang Liang

University of Science and Technology of China

October 2, 2024

## Outline

- Introduction
- Central Limit Theorem for hyperrectangles
- Generalization
- Application for Bootstrap

## Outline

- Introduction
- 2 Central Limit Theorem for hyperrectangles
- Generalization
- Application for Bootstrap

#### Introduction

- Let  $X_1, X_2, ..., X_n$  be a sequence of random vectors in  $\mathbb{R}^p$
- Define the normalized sum of X:

$$S_{n,X} = \frac{1}{\sqrt{n}} \sum_{i=1}^{n} X_i$$

- Let covariance matrix  $\Xi = \text{cov}(S_{n,X})$ , and a Guassian random vector  $G \sim N(0,\Xi)$
- Define

$$\rho_n(\mathcal{A}) = \sup_{A \in \mathcal{A}} |\mathbb{P}(S_n^X \in A) - \mathbb{P}(G \in A)| \tag{1}$$

where  $\mathcal{A}$  is a class of Borel set of  $\mathbb{R}^p$ 

#### Introduction

- Question: how fast the  $p = p_n$  is allowed to grow as  $n \to \infty$  while guaranteeing  $\rho_n \to 0$ ?
- We hope to construct a convergence rate which allows *p* to grow sub-exponentially fast in the sample size n.
- The main result<sup>12</sup> suggests that under some conditions, we have

$$\rho_n \to 0$$
 if  $p_n = O(e^{Cn^c})$ 

<sup>&</sup>lt;sup>1</sup>Victor Chernozukov, Denis Chetverikov, and Kengo Kato. "Central Limit Theorems and Bootstrap in High Dimensions". In: *The Annals of Probability* 45 (Dec. 2014). DOI: 10.1214/16-A0P1113.

<sup>&</sup>lt;sup>2</sup>Jinyuan Chang, Xiaohui Chen, and Mingcong Wu. "Central limit theorems for high dimensional dependent data". In: Bernoulli 30.1 (Feb. 2024). ISSN: 1350-7265. DOI: 10.3150/23-bej1614. URL: http://dx.doi.org/10.3150/23-BEJ1614.

#### Outline

- Introduction
- Central Limit Theorem for hyperrectangles
- Generalization
- Application for Bootstrap

## Notation

- For  $x, y \in \mathbb{R}^p$ ,  $x \le y \iff x_i \le y_i$ ,  $\forall i \in [p]$
- For  $x \in \mathbb{R}^p$ ,  $|x|_p$  means p-norm, and  $|x|_0 = \#\{i : x_i \neq 0\}$
- $a_n \ll b_n \iff a_n = o(b_n) \iff \lim_{n \to \infty} \frac{a_n}{b_n} = 0$
- $a_n \lesssim b_n \iff a_n = O(b_n) \iff \limsup_{n \to \infty} \frac{a_n}{b_n} < \infty$
- $\psi_{\alpha}: [0,\infty) \to [0,\infty), \psi_{\alpha}(x) = \exp(x^{\alpha}) 1$ , where  $\alpha \geq 1$

Oclicz norm:  $||X||_{\psi_{\alpha}} = \inf\{\lambda : E[\psi_{\alpha}(|X|/\lambda)] \le 1\}$ 

#### Outline

- Introduction
- Central Limit Theorem for hyperrectangles
  - Independent data
  - Dependent data
- Generalization
- Application for Bootstrap

• In this subsection, we assume that  $\{X_i\}$  is an independent sequence.

- In this subsection, we assume that  $\{X_i\}$  is an independent sequence.
- Assume  $\{X_i\}$  satisfy the following conditions:
  - CI1: (Non-degeneracy of convariance matrix)  $Var(S_{n,X,j}) \ge b$  for all  $j \in [p]$
  - C12: (Bound for moment)  $n^{-1} \sum_{i=1}^{n} \mathbb{E}[|X_{i,j}|^{2+k}] \leq B_n^k$  for any  $j \in [p], k = 1, 2$

- In this subsection, we assume that  $\{X_i\}$  is an independent sequence.
- Assume  $\{X_i\}$  satisfy the following conditions:
  - CI1: (Non-degeneracy of convariance matrix)  $Var(S_{n,X,j}) \geq b$  for all  $j \in [p]$
  - C12: (Bound for moment)  $n^{-1} \sum_{i=1}^n \mathbb{E}[|X_{i,j}|^{2+k}] \leq B_n^k$  for any  $j \in [p], k = 1, 2$
- smoothing: Let  $\varrho_n = \sup_{y \in \mathbb{R}^p, v \in [0,1]} |\mathbb{P}(\sqrt{v}S_{n,X} + \sqrt{1-v}G \leq y) \mathbb{P}(G \leq y)|$
- Obviously, to bound  $\rho_n(\mathcal{A}^{re})$ , we just need to bound  $\varrho_n$

• By independency of  $\{X_i\}$ , let  $Y_1, ..., Y_n$  be a sequence of Guassian random vectors in  $\mathbb{R}^p$ , and  $Y_i \sim N(0, E[X_i X_i^T])$ , and  $\{W_i\}$  is a copy of  $\{Y_i\}$ , then  $S_{n,Y} \stackrel{d}{=} S_{n,W} \stackrel{d}{=} G$ , so

$$\varrho_n = \sup_{y \in \mathbb{R}^p, v \in [0,1]} |\mathbb{P}(\sqrt{v}S_{n,X} + \sqrt{1-v}S_{n,Y} \le y) - \mathbb{P}(S_{n,W} \le y)|$$

• This method is called Slepian-Stein interpolation<sup>3</sup>

<sup>&</sup>lt;sup>3</sup>It's actually Stein method and Slepian interpolation, but in fact they are the same method, see (Victor Chernozhukov, Denis Chetverikov, and Kengo Kato. "Gaussian approximations and multiplier bootstrap for maxima of sums of high-dimensional random vectors". In: *The Annals of Statistics* 41.6 [Dec. 2013]. ISSN: 0090-5364. DOI: 10.1214/13-aos1161. URL: http://dx.doi.org/10.1214/13-A0S1161) in Appendix H

# Key Lemma

• The Key Lemma indicates that  $\varrho_n$  satisfies the following inequality for all  $\phi \geq 1$ :

$$\varrho_n \lesssim \frac{\phi^2 \log^2 p}{n^{1/2}} \{ \phi L_n \varrho_n + L_n \log^{1/2} p + \phi (M_{n,X}(\phi) + M_{n,Y}(\phi)) \} + \frac{\log^{1/2} p}{\phi}$$

where

$$M_{n,X}(\phi) = n^{-1} \sum_{i=1}^{n} \mathbb{E}[\max_{1 \le j \le p} |X_{i,j}|^{3} 1\{\max_{1 \le j \le p} |X_{i,j}| > \sqrt{n}/4\phi \log p\}]$$

$$M_{n,Y}(\phi) = n^{-1} \sum_{i=1}^{n} \mathbb{E}[\max_{1 \le j \le p} |Y_{i,j}|^{3} 1\{\max_{1 \le j \le p} |Y_{i,j}| > \sqrt{n}/4\phi \log p\}]$$

$$L_{n} = \max_{j \in [p]} n^{-1} \sum_{i=1}^{n} \mathbb{E}[|X_{i,j}|^{3}]$$

## High-dimensional CLT for hyperrectangles

- Select  $\phi$  properly, and bound  $M_{n,X}, M_{n,Y}, L_n$  respectively, we can get an explicit result
- (**Theorem**) Suppose that  $||X_{i,j}||_{\psi_1} \leq B_n$  for all  $i \in [n], j \in [p]$ , then

$$\rho_n(\mathcal{A}^{re}) \lesssim \frac{B_n^{1/3} \log^{7/6}(pn)}{n^{1/6}}$$

• (**Theorem**) Suppose that  $||X_{i,j}||_{\psi_{\gamma}} \leq B_n$  for all  $i \in [n], j \in [p]$ , and some  $\gamma \geq 4$ , then

$$\rho_n(\mathcal{A}^{re}) \lesssim \frac{B_n^{1/3} \log^{7/6}(pn)}{n^{1/6}} + \frac{B_n^{2/3} \log(p)}{n^{(\gamma-2)/3\gamma}}$$

The following is some preparations, we hope to smooth the  $\varrho_n$ :

• Note that 
$$x \leq y \Longleftrightarrow \max_{j \in [p]} (x_j - y_j) \leq 0 \Longleftrightarrow I_{(-\infty,0]}(\max_{j \in [p]} (x_j - y_j)) = 1$$
, so 
$$\varrho_n = \sup_{y \in \mathbb{R}^p, v \in [0,1]} |\mathbb{P}(\sqrt{v}S_{n,X} + \sqrt{1 - v}S_{n,Y} \leq y) - \mathbb{P}(S_{n,W} \leq y)|$$
$$= \sup_{y \in \mathbb{R}^p, v \in [0,1]} |\mathbb{E}[I_{(-\infty,0]}(\max_{j \in [p]} (\sqrt{v}S_{n,X,j} + \sqrt{1 - v}S_{n,Y,j} - y_j))]|$$
$$- \mathbb{E}[I_{(-\infty,0]}(\max_{j \in [p]} (S_{n,W,j} - y_j))]|$$

• Smooth the function  $I_{(-\infty,0]}$  and  $\max_{i \in [p]} (\cdot_j - y_i)$ 

- (Smooth indicate function)Let  $g \in \mathsf{C}^\infty : \mathbb{R} \to \mathbb{R}$  satisfy that g(t) = 1 for  $t \leq 0$ , and g(t) = 0 for  $t \geq \phi^{-1}$
- (Smooth maximum function)Let  $F_{\beta}(w) = \beta^{-1} \log(\sum_{j=1}^{p} \exp(\beta(w_j y_j)))$ , where  $\beta = \phi \log p$
- $F_{\beta}(w) \approx \max_{j \in [p]} (w_j y_j), g \approx I_{(-\infty,0)}.$
- Let  $m = g \circ F_{\beta}$ ,  $\mathcal{I}_n = m(\sqrt{v}S_{n,X} + \sqrt{1-v}S_{n,Y}) m(S_{n,W})$
- In fact,

$$\varrho_n \lesssim |\mathbb{E}[\mathcal{I}_n]| + \phi^{-1} \log^{1/2} p$$

double Slepian interpolant:

$$Z_i(t) = rac{1}{\sqrt{n}} \{ \sqrt{t} (\sqrt{v} X_i + \sqrt{1-v} Y_i) + \sqrt{1-t} W_i \}$$
  $Z(t) = \sum_{i=1}^{n} Z_i(t)$ 

So

$$\mathcal{I}_n = \int_0^1 \frac{dm(Z(t))}{dt} dt$$

• Note that  $\{Z_i\}$  is mutually independent

#### Left-one-out:

• By Taylor expansion: let  $Z^{(i)} = Z - Z_i \Longrightarrow Z^{(i)}$  is independent to  $Z_i$ 

$$\begin{split} \mathbb{E}[\mathcal{I}_n] &= \frac{1}{2} \sum_{j \in [p]} \sum_{i \in [n]} \int_0^1 \mathbb{E}[m_j(Z) \dot{Z}_{i,j}] dt \\ &= \frac{1}{2} \sum_{j \in [p]} \sum_{i \in [n]} \int_0^1 \mathbb{E}[m_j(Z^{(i)}) \dot{Z}_{i,j}] dt + \frac{1}{2} \sum_{j,k \in [p]} \sum_{i \in [n]} \int_0^1 \mathbb{E}[m_{jk}(Z^{(i)}) \dot{Z}_{i,j} Z_{i,k}] dt + \\ &\frac{1}{2} \sum_{j,k,l \in [p]} \sum_{i \in [n]} \int_0^1 \int_0^1 (1-\tau) \mathbb{E}[m_{jkl}(Z^{(i)} + \tau Z_i) \dot{Z}_{i,j} Z_{i,k} Z_{i,l}] d\tau dt \end{split}$$

- The independency of  $\{X_i\}$   $\Longrightarrow$  The first and second term equal to 0, so we just need to bound the last term. Write the last term as III
- Divide III into small part and large part:

$$III_1 = \sum_{j,k,l} \sum_i \int_0^1 \int_0^1 (1-\tau) E[\chi_i m_{jkl} (Z^{(i)} + \tau Z_i) \dot{Z}_{ij} Z_{ik} Z_{il}] d\tau dt$$
 $III_2 = \sum_{i,k,l} \sum_i \int_0^1 \int_0^1 (1-\tau) E[(1-\chi_i) m_{jkl} (Z^{(i)} + \tau Z_i) \dot{Z}_{ij} Z_{ik} Z_{il}] d\tau dt$ 

where 
$$\chi_i = 1\{\max_{i \in [n], i \in [n]} \{|X_{i,j}|, |Y_{i,j}|, |W_{i,j}|\} \le \sqrt{n}/4\beta\}$$

- Estimate  $III_1$ ,  $III_2$  respectively
- We have

$$\mathbb{E}[\mathcal{I}_n] \lesssim \frac{\phi^2 \log^2 p}{n^{1/2}} \{ \phi L_n \varrho_n + L_n \log^{1/2} p + \phi (M_{n,X}(\phi) + M_{n,Y}(\phi)) \}$$

## Outline

- Introduction
- 2 Central Limit Theorem for hyperrectangles
  - Independent data
  - Dependent data
- Generalization
- Application for Bootstrap

Now, we hope to omit the independency of  $\{X_i\}$ .

• Difficulty 1: without independency, Slepian interpolation is invalid. For example: Independent sequence  $\{Y_i\}$  such that  $Y_i \sim N(0, \Sigma_i)$ , where  $\Sigma_i = \text{cov}(X_i)$ , however:

$$\mathsf{cov}(G) = \mathsf{cov}(S_{n,X}) = n^{-1} \sum_{t,s \in [n]} \mathbb{E}[X_t X_s^T] \neq n^{-1} \sum_{t \in [n]} \mathbb{E}[X_t X_t^T] = \mathsf{cov}(S_{n,Y})$$

In other word, interpolating for each  $X_i$  cannot approximate G.

Difficulty 2: without independency, left-one-out method is invalid.
 For example:

$$\mathbb{E}[m_j(Z^{(i)})\dot{Z}_{i,j}] = \mathbb{E}[m_j(Z^{(i)})\mathbb{E}[\dot{Z}_{i,j}|\mathcal{F}]] \neq 0$$

In other words, we have to bound the conditional expectation respectively!

- **Solution 1**: "Package" data so that we can approximate *G* applying interpolation:
  - Large-and-small-blocks

- Solution 1: "Package" data so that we can approximate G applying interpolation:
  - Large-and-small-blocks
- **Solution 2**: Introduce some measures to measure the dependency (Do not be too corelated), which can help us to bound conditional expectation:
  - $\alpha$ -mixing sequence
  - Dependency graph
  - Sequence with physical dependence

Later, we always assume  $p \ge n^{\kappa}$  since we only care about the case that  $p \gg n$ .

## CLT for dependent data: $\alpha$ -mixing sequence

Concepts of  $\alpha$ -mixing:

- $\mathcal{A}, \mathcal{B}$  are  $\sigma$ -field, let  $\alpha(\mathcal{A}, \mathcal{B}) = \sup_{A \in \mathcal{A}, B \in \mathcal{B}} |\mathbb{P}(A)\mathbb{P}(B) \mathbb{P}(AB)|$
- Let  $\mathcal{F}_{-\infty}^t = \sigma(X_i, i \leq t)$ ,  $\mathcal{F}_t^{\infty} = \sigma(X_i, i \geq t)$
- $\alpha$ -coefficient of  $\{X_i\}$ :  $\alpha(n) = \sup_{t>1} \alpha(\mathcal{F}_{-\infty}^t, \mathcal{F}_{t+n}^{+\infty})$
- $\{X_i\}$  is a  $\alpha$ -mixing (or strong mixing) sequence, if  $\lim_{n\to\infty} \alpha(n)=0$

## CLT for dependent data: $\alpha$ -mixing sequence

There are some conditions which we will assume later.

- Condition 1 (Sub-exponential moment). There exist constants  $\gamma_1 \geq 1$ ,  $B_n \geq 1$ , such that  $||X_{i,j}||_{\psi_{\gamma_1}} \leq B_n$  ( $\Rightarrow$  distribution function  $\mathbb{P}(|X| > u)$  has an exponential decay)
- Condition 2 (Decay of  $\alpha$ -mixing coefficient). There exist some universal constants  $K_1 > 1$ ,  $K_2 > 0$  and  $\gamma_2 > 0$ , such that  $\alpha_n(k) \leq K_1 \exp(-K_2 k^{\gamma_2})$  for any  $k \geq 1$
- Condition 3 (Non-degeneracy of covariance matrix). There exist a universal constant  $K_3 > 0$  such that  $\min_{j \in [p]} \text{Var}(S_{n,X,j}) \geq K_3$

## CLT for dependent data: $\alpha$ -mixing sequence

- Recall that  $\varrho_n = \sup_{y \in \mathbb{R}^p, v \in [0,1]} |\mathbb{P}(\sqrt{v} S_{n,X} + \sqrt{1-v} G \leq y) \mathbb{P}(G \leq y)|$
- (Theorem) Assume  $\{X_i\}$  is an  $\alpha$ -mixing sequence. Under Conditions 1-3:

$$\varrho_n \lesssim \frac{B_n^{2/3} (\log p)^{(1+2\gamma_2)/3\gamma_2}}{n^{1/9}} + \frac{B_n (\log p)^{7/6}}{n^{1/9}}$$

provided that  $(\log p)^{3-\gamma_2} = o(n^{\gamma_2/3})$ 

• Let Q = o(n), and Q = b + h, where  $h \ll b$ 

- Let Q = o(n), and Q = b + h, where  $h \ll b$
- ullet Divide the sequence into L blocks:  $L=\lfloor rac{n}{Q} 
  floor$

- Let Q = o(n), and Q = b + h, where  $h \ll b$
- Divide the sequence into L blocks:  $L = \lfloor \frac{n}{Q} \rfloor$
- Divide each blocks into large parts and small parts: For  $\ell \in [L]$ , Let  $\mathcal{G}_\ell = \{\ell Q + 1, \ell Q + 2, ..., \ell Q + b, ...(\ell+1)Q\}$ , and  $\mathcal{I}_\ell = \{\ell Q + 1, \ell Q + 2, ..., \ell Q + b\}$ ,  $\mathcal{J}_\ell = \{\ell Q + b + 1, ..., (\ell+1)Q\}$ . and  $\mathcal{J}_{\ell+1} = \{\text{The remaining } X_t\}$

- Let Q = o(n), and Q = b + h, where  $h \ll b$
- Divide the sequence into L blocks:  $L = \lfloor \frac{n}{Q} \rfloor$
- Divide each blocks into large parts and small parts: For  $\ell \in [L]$ , Let  $\mathcal{G}_\ell = \{\ell Q + 1, \ell Q + 2, ..., \ell Q + b, ...(\ell+1)Q\}$  , and  $\mathcal{I}_\ell = \{\ell Q + 1, \ell Q + 2, ..., \ell Q + b\}$  ,  $\mathcal{J}_\ell = \{\ell Q + b + 1, ..., (\ell+1)Q\}$  , and  $\mathcal{J}_{L+1} = \{\text{The remaining } X_t\}$
- ullet packaging: Let  $ilde{X}_\ell = b^{-1/2} \sum_{t \in \mathcal{I}_\ell} X_t$

- A series of normal random vectors: Let independent sequence  $\{Y_t\}_1^n$  such that  $Y_t \sim \mathsf{N}(0,\mathbb{E}[\tilde{X}_\ell \tilde{X}_\ell^\top])$  for  $t \in \mathcal{I}_\ell$
- ullet blocks of  $\{Y_t\}$ : Define  $ilde{Y}_\ell=b^{-1/2}\sum_{t\in\mathcal{I}_\ell}Y_t$ . Corresponding:  $ilde{Y}_\ell\longleftrightarrow ilde{X}_\ell$
- normalized sum:  $S_{n,X} = \frac{1}{\sqrt{n}} \sum_{t=1}^{n} X_t$ ,  $S_{n,X}^{(1)} = \frac{1}{\sqrt{L}} \sum_{\ell=1}^{L} \tilde{X}_{\ell}$ ,  $S_{n,Y}^{(1)} = \frac{1}{\sqrt{L}} \sum_{\ell=1}^{L} \tilde{Y}_{\ell}$

# Large-and-Small-Blocks Technique: Advantage

Advantages:

## Large-and-Small-Blocks Technique: Advantage

#### Advantages:

• By dividing the sequence  $\{X_i\}$  into a series of "large blocks" and "small blocks", we can construct a series of normal distribution  $\{Y_\ell\}$ , such that  $G \approx n^{-1/2} \sum_\ell Y_\ell$ , so we can apply Slepian interpolation for these "blocks".

## Large-and-Small-Blocks Technique: Advantage

#### Advantages:

- By dividing the sequence  $\{X_i\}$  into a series of "large blocks" and "small blocks", we can construct a series of normal distribution  $\{Y_\ell\}$ , such that  $G \approx n^{-1/2} \sum_\ell Y_\ell$ , so we can apply Slepian interpolation for these "blocks".
- By throwing out "small blocks", we can construct "time gap" between 2 "large blocks". As a result, we can bound the conditional expectation by  $\alpha(n)$

# Sketch of proof

By triangle inequality:

$$\varrho_{n} \leq \sup_{\substack{y \in \mathbb{R}^{p}, v \in [0,1]}} |\mathbb{P}(\sqrt{v}S_{n,X} + \sqrt{1-v}G \leq y) - \mathbb{P}(\sqrt{v}S_{n,X} + \sqrt{1-v}S_{n,Y}^{(1)} \leq y)| \\
+ \sup_{\substack{y \in \mathbb{R}^{p}, v \in [0,1]}} |\mathbb{P}(\sqrt{v}S_{n,X} + \sqrt{1-v}S_{n,Y}^{(1)} \leq y) - \mathbb{P}(S_{n,Y}^{(1)} \leq y)| \\
+ \sup_{\substack{y \in \mathbb{R}^{p}}} |\mathbb{P}(S_{n,Y}^{(1)} \leq y) - \mathbb{P}(G \leq y)|$$

# Sketch of proof

Bound  $I_1$ ,  $I_3$ :

- (Gaussian comparison)  $|\mathbb{P}(S_{n,Y}^{(1)} \leq y) \mathbb{P}(G \leq y)| \lesssim |\mathsf{cov}(S_{n,Y}^{(1)}) \mathsf{cov}(G)|_{\infty} (\log p)^{2/3}$
- (Difference of covariance matrix)  $|\text{cov}(S_{n,Y}^{(1)}) \text{cov}(G)|_{\infty} \lesssim B_n^2(hb^{-1} + bn^{-1})$
- $I_1 \leq I_3$

# Sketch of proof

- $\bullet \ \ \textit{I}_2 \approx \sup_{y \in \mathbb{R}^p, v \in [0,1]} |\mathbb{P}(\sqrt{v} S_{n,X}^{(1)} + \sqrt{1-v} S_{n,Y}^{(1)} \leq y) \mathbb{P}(S_{n,Y}^{(1)} \leq y)| \xrightarrow{\mathsf{Slepian-Stein} \ \mathsf{Method}} \mathsf{Bound}$
- The right-hand side just replaces  $S_{n,X}$  in  $I_2$  by  $S_{n,X}^{(1)}$ . What we do is throwing out the "small blocks" so that we can apply Slepian-Stein method.
- $\tilde{X}_{\ell}$  and  $\tilde{X}_{\ell+1}$  have a time gap h(the size of small blocks).
- Bound conditional expectation by  $\alpha(n)$ :  $\mathbb{E}\{|\mathbb{P}(\tilde{X}_{\ell,j} > u|\mathcal{F}_{-\ell}) \mathbb{P}(\tilde{X}_{\ell,j} > u)|\} \lesssim \alpha(h)$ , where  $\mathcal{F}_{-\ell} = \sigma(\{\tilde{X}_s\}_{s \neq \ell})$ .

• Let undirected graph  $G_n = (V_n, E_n)$ , where  $V_n = [n]$  with  $t \stackrel{denote}{\Longleftrightarrow} X_t$ ,  $(t, s) \in E_n \Longleftrightarrow X_t$  and  $X_s$  are dependent. In particular,  $(t, t) \in E_n$  for all t.

- Let undirected graph  $G_n = (V_n, E_n)$ , where  $V_n = [n]$  with  $t \stackrel{denote}{\Longleftrightarrow} X_t$ ,  $(t, s) \in E_n \Longleftrightarrow X_t$  and  $X_s$  are dependent. In particular,  $(t, t) \in E_n$  for all t.
- (Packaging) Let  $\mathcal{N}_t := \{s : (t,s) \in E_n\}$  be the set of neighbor of  $X_t$ , and  $\mathcal{N}_t^* := \cup_{s \in \mathcal{N}_t} \mathcal{N}_s$  be the set of second-degree neighbor of  $X_t$ .
- $\bullet \ D_n := \max_{t \in [n]} |\mathcal{N}_t|, \ D_n^* := \max_{t \in [n]} |\mathcal{N}_t^*|$
- ullet Let  $Z_{\mathcal{N}_t}:=\sum_{t\in\mathcal{N}_t}Z_t$  be the sum of the random vector dependent to  $Z_t.$

The proof coincides with the proof in the case of independent data. What difference is when left-one-out by Taylor expansion:

- Independent :  $m(Z) = m(Z^{(-t)}) + \sum m_j(Z^{(-t)})Z_{t,j} + ...$
- Dependent :  $m(Z) = m(Z^{(-\mathcal{N}_t)}) + \sum m_j(Z^{(-\mathcal{N}_t)})Z_{\mathcal{N}_t,j} + ...$

• (Theorem) Suppose Condition 1 and 3, it holds that

$$\varrho_n \lesssim \frac{B_n (D_n D_n^*)^{1/3} (\log p)^{7/6}}{n^{1/6}}$$

# CLT for dependent data: physical dependence

In this section, we consider time series model.

- Time series model:  $X_t = f_t(\epsilon_t, \epsilon_{t-1}, ...)$ , where t > 1
- (Coupling) $\epsilon'_t$  independent copy of  $\epsilon_t$ , let  $X'_{t,\{m\}} := f_t(\epsilon_t, \epsilon_{t-1}, ..., \epsilon'_{t-m}, \epsilon_{t-m-1}, ...)$
- ullet  $heta_{m,q,j}=\sup_{t>1}||X_{t,j}-X'_{t,j,\{m\}}||_q$ ,  $\Theta_{m,q,j}=\sum_{i=m}^\infty heta_{i,q,j}$ , where q>0
- $\bullet \ ||X_{\cdot,j}||_{q,\alpha} = \sup_{m \geq 0} (m+1)^{\alpha} \Theta_{m,q,j}, \ \text{and} \ ||X_{\cdot,j}||_{\psi_{\nu},\alpha} = \sup_{q \geq 2} q^{-\nu} ||X_{\cdot,j}||_{q,\alpha}$
- $\bullet \ \Psi_{q,\alpha} = \max_{j \in [p]} ||X_{\cdot,j}||_{q,\alpha}, \ \Phi_{\psi_{\nu},\alpha} = \max_{j \in [p]} ||X_{\cdot,j}||_{\psi_{\nu},\alpha}$

## CLT for dependent data: physical dependence

- (Theorem)  $\Phi_{\psi_{\nu},\alpha} < \infty$  for some  $\alpha, \nu$ , then:
  - (i) Under Condition 3,

$$arrho_n \lesssim rac{\Phi_{\psi_
u,0}(\log p)^{7/6}}{n^{lpha/(3+9lpha)}} + rac{\Psi_{2,lpha}^{1/3}\Psi_{2,0}^{1/3}(\log p)^{2/3}}{n^{lpha/(3+9lpha)}} + rac{\Phi_{\psi_
u,lpha}(\log p)^{1+
u}}{n^{lpha/(1+3lpha)}}$$

provided that  $(\log p)^{\max\{6\nu-1,(5+6\nu)/4\}} = o\{n^{\alpha/(1+3\alpha)}\}$  (ii) Under Condition 1 and 3.

$$\varrho_n \lesssim \frac{B_n(\log p)^{7/6}}{n^{\alpha/(12+6\alpha)}} + \frac{\Psi_{2,\alpha}^{1/3}\Psi_{2,0}^{1/3}(\log p)^{2/3}}{n^{\alpha/(12+6\alpha)}} + \frac{\Phi_{\psi_{\nu},\alpha}(\log p)^{1+\nu}}{n^{\alpha/(4+2\alpha)}}$$

## CLT for dependent data: physical dependence

- Idea: Large-and-small-blocks method to create "time gap". Conditional expectation and "time gap" to create independency.
- Apply Large-and-small-blocks with large size b, and small size m.
- ullet Conditional expectation with time lag m: For each random vector  $X_t$ , define  $X_t^{(m)}:=\mathbb{E}[X_t|\epsilon_t,...,\epsilon_{t-m}]$
- $X_t^{(m)}$  is m-dependent sequence:  $X_t^{(m)}$  is independent to  $X_{t+m+1}^{(m)}$

# CLT for dependent data: physical dependence. Part(ii)

- If  $\{X_t\}$  satisfy **Condition 1 and 3**, since  $\{X_t^{(m)}\}$  is m-dependent sequence with  $m \ll b \ll n$ , the result for dependent graph derives **part (ii)** of the theorem.
- If  $\{X_t\}$  just satisfy **Condition 3**, without sub-exponential moment bounds, the conditions of the dependent graph theorem don't hold.

# CLT for dependent data: physical dependence. Part(i)

Now we don't have exponential moment bound

- Let  $\mathcal{F}_t = \sigma\{\epsilon_t, \epsilon_{t-1}, ...\}$
- Define a projection operator  $\mathcal{P}_t(\cdot) := \mathbb{E}[\cdot|\mathcal{F}_t] \mathbb{E}[\cdot|\mathcal{F}_{t-1}]$ .  $\{\mathcal{P}_t\}$  is a family of mutually orthogonal operator:  $\mathbb{E}[\mathcal{P}_s(X)\mathcal{P}_t(X)] = 0$  if  $s \neq t$
- Then  $X_t = \sum_{s=0}^{\infty} \mathcal{P}_{t-s}(X_t)$ , and  $||\mathcal{P}_{t-s}(X_{t,j})||_q \leq ||X_{t,j} X'_{t,i,\{s\}}||_q \leq \theta_{s,q,j}$

# CLT for dependent data: physical dependence. Part(i)

 As a result, though we don't have bounds for exponential moment, we can prove that the probability of "large part" decay in exponentially fast:

$$\mathbb{P}(| ilde{X}_{\ell}| > u) \lesssim \exp(-C(u\Phi_{\psi_{u,\alpha}}^{-1})^{\gamma})$$

• Large-and-small-blocks technique derives Part(i) of the theorem

#### Outline

- Introduction
- Central Limit Theorem for hyperrectangles
- Generalization
- Application for Bootstrap

#### Some concepts of simple convex set:

- For closed convex set A, support function:  $S_A(x) = \sup_{y \in A} x^T y$ . Representation:  $A = \bigcap_{v \in \mathbb{S}^{p-1}} \{x : x^T v < S_A(v)\}$
- Polyhedron:  $A = \bigcap_{v \in \mathcal{V}(A)} \{x : x^T v \leq S_A(v)\}$ , where  $\mathcal{V}(A)$  is a finite subset of  $\mathbb{S}^{p-1}$ .
- $x \in A \iff v^T x < S_A(v)$  for all  $v \in \mathcal{V}(A)$
- For each A, corresponding: Random vector  $X \in \mathbb{R}^p \mapsto \tilde{X} := (v^T X)_{v \in \mathcal{V}(A)} \in \mathbb{R}^{|\mathcal{V}(A)|}$
- $\mathbb{P}(X \in A) = \mathbb{P}(\tilde{X} \leq (S_A(v))_v)$

- fattening or shrinking a convex set:  $A^{\epsilon} := \bigcap_{v \in \mathbb{S}^{p-1}} \{x : x^T v \leq S_A(v) + \epsilon\}$
- $A^K \subset A \subset A^{K,\epsilon}$ : A can be approximated by a polyhedron  $A^K$  with  $|\mathcal{V}(A)| = K$  with precision  $\epsilon$ .
- A family of subset  $\mathcal{A}^{si}(a,d):=\{A \text{ convex}: A \text{ can be approximated by } A^K \text{ satisfying } K \leq (pn)^d \text{ with precision } \epsilon=a/n\}$

Let 
$$A \in \mathcal{A}^{si}(a,d)$$
,  $ho^K := |\mathbb{P}(S_{n,X} \in A^K) - \mathbb{P}(G \in A^K)|$  ,  $ho^{K,\epsilon} := |\mathbb{P}(S_{n,X} \in A^{K,\epsilon}) - \mathbb{P}(G \in A^{K,\epsilon})|$ , then  $|\mathbb{P}(S_{n,X} \in A) - \mathbb{P}(G \in A)| \le \epsilon (\log K)^{1/2} + \rho^K + \rho^{K,\epsilon}$ 

 $\mathcal{A} \subset \mathcal{A}^{si}(a,d)$  such that  $\tilde{X}_i$  satisfies condition CI1,2 uniformly for all  $A \in \mathcal{A}$ 

• (Independent) (i) Suppose that  $||v^T X_i||_{\psi_1} \leq B_n$  for all  $i \in [n], v \in \mathcal{V}(A)$ , then

$$\rho_n(\mathcal{A}) \lesssim \frac{B_n^{1/3} \log^{7/6}(pn)}{n^{1/6}}$$

(ii) Suppose that  $||v^T X_i||_{\psi_{\gamma}} \leq B_n$  for all  $i \in [n], v \in \mathcal{V}(A)$ , and some  $\gamma \geq 4$ , then

$$ho_n(\mathcal{A}^{re}) \lesssim rac{B_n^{1/3} \log^{7/6}(pn)}{n^{1/6}} + rac{B_n^{2/3} \log(p)}{n^{(\gamma-2)/3\gamma}}$$

 $\mathcal{A} \subset \mathcal{A}^{si}(a,d)$  such that  $\tilde{X}_i$  satisfies **Condition 1,3** uniformly for all  $A \in \mathcal{A}$ 

• (Dependent,  $\alpha$ -mixing) If  $X_i$  also s.t. Condition  $2(\Rightarrow \tilde{X}_i \text{ s.t.})$ 

$$\rho_n(\mathcal{A}) \lesssim \frac{a(d\log p)^{1/2}}{n} + \frac{B_n^{2/3}(d\log p)^{(1+2\gamma_2)/(3\gamma_2)}}{n^{1/9}} + \frac{B_n(d\log p)^{7/6}}{n^{1/9}}$$

provided that  $(d \log p)^{3-\gamma_2} = o(n^{\gamma_2/3})$ 

• (Dependent, Dependent graph)

$$\rho_n(\mathcal{A}) \lesssim \frac{a(d\log p)^{1/2}}{n} + \frac{B_n \left(D_n D_n^*\right)^{1/3} (d\log p)^{7/6}}{n^{1/6}}$$

For each polyhedron A, define  $\Psi_{q,\alpha}(A)$ ,  $\Phi_{\psi_{\nu},\alpha}(A)$  with respect to  $\{\tilde{X}_t\}$ . Let  $\Psi_{q,\alpha,\mathcal{A}}:=\sup_{A\in\mathcal{A}}\Psi_{q,\alpha}(A^K)$ ,  $\Phi_{\psi_{\nu},\alpha,\mathcal{A}}:=\sup_{A\in\mathcal{A}}\Phi_{\psi_{\nu},\alpha}(A^K)$ 

• (Dependent, Physical dependence)(i) If A satisfies Condition 3, and  $\Phi_{\psi_{\nu},\alpha,A} < \infty$ ,

$$\rho_n(\mathcal{A}) \lesssim \frac{a(d\log p)^{1/2}}{n} + \frac{\Phi_{\psi_{\nu},0,\mathcal{A}}(d\log p)^{7/6}}{n^{\alpha/(3+9\alpha)}} + \frac{\Psi_{2,\alpha,\mathcal{A}}^{1/3}\Psi_{2,0,\mathcal{A}}^{1/3}(d\log p)^{2/3}}{n^{\alpha/(3+9\alpha)}} + \frac{\Phi_{\psi_{\nu},\alpha,\mathcal{A}}(d\log p)^{1+\nu}}{n^{\alpha/(1+3\alpha)}}$$
provided that  $(d\log p)^{\max\{6\nu-1,(5+6\nu)/4\}} = o\{n^{\alpha/(1+3\alpha)}\}$ 

(ii) If A satisfies Condition 1,3, and  $\Phi_{\psi_{\nu},\alpha,A} < \infty$ ,

$$\rho_n(\mathcal{A}) \lesssim \frac{a(d\log p)^{1/2}}{n} + \frac{B_n(d\log p)^{7/6}}{n^{\alpha/(12+6\alpha)}} + \frac{\Psi_{2,\alpha,\mathcal{A}}^{1/3}\Psi_{2,0,\mathcal{A}}^{1/3}(d\log p)^{2/3}}{n^{\alpha/(12+6\alpha)}} + \frac{\Phi_{\psi_{\nu},\alpha,\mathcal{A}}(d\log p)^{1+\nu}}{n^{\alpha/(4+2\alpha)}}$$

- A is a s-sparsely convex set:
  - (i): Sparse representation  $A = \bigcap_{q=1}^{K*} A_q$  for convex sets  $A_1, ..., A_{K*}$ .
  - (ii): Indicator function  $I_{\{w \in A_q\}}$  of each  $A_q$  depends on at most s components of w.

- A is a s-sparsely convex set:
  - (i): Sparse representation  $A = \bigcap_{q=1}^{K*} A_q$  for convex sets  $A_1, ..., A_{K*}$ .
  - (ii): Indicator function  $I_{\{w \in A_a\}}$  of each  $A_q$  depends on at most s components of w.
- (Condition 6) There exist a universal constant  $K_5 > 0$  such that  $Var(v^T S_{n,X}) \ge K_5$  for each  $v \in \mathbb{S}^{p-1}$  with  $|v|_0 < s$
- $A^{sp}(s) := \{A : A \text{ is s-sparsely convex set } \}$

- Let A is a s-sparsely convex set,  $B := \{w : ||w||_{\infty} \le pn^{5/2}\}, A^* = A \cap B$ .
- "small" far away from origin:

$$\mathbb{P}(S_{n,X} \in B^c) \lesssim B_n n^{-1}, \mathbb{P}(G \in B^c) \lesssim B_n n^{-1}$$

- $|\mathbb{P}(S_{n,X} \in A) \mathbb{P}(G \in A)| \lesssim |\mathbb{P}(S_{n,X} \in A^*) \mathbb{P}(G \in A^*)| + B_n n^{-1}$
- $A^* = A \cap B$  is also a s-sparsely convex set with  $A^* = \bigcap_{a=1}^{K_*} A_a^*$

$$\mathcal{A}_1^{sp}(s) := \{ A \in \mathcal{A}^{sp}(s) : A \subset B, A \text{ contains a ball with radius } n^{-1} \},$$

- Lemma D.1<sup>4</sup>:  $\mathcal{A}_1^{sp}(s) \subset \mathcal{A}^{si}(1, Cs^2)$ . Besides, the approximating polyhedron  $A^K$  can be chosen to satisfy  $|v|_0 \leq s$  for all  $v \in \mathcal{V}(A^K)$ .
- Case 1: If  $A^* \in \mathcal{A}_1^{sp}(s)$ , by Lemma D.1, we can apply the result for simple convex sets.

<sup>&</sup>lt;sup>4</sup>Victor Chernozukov, Denis Chetverikov, and Kengo Kato. "Central Limit Theorems and Bootstrap in High Dimensions". In: *The Annals of Probability* 45 (Dec. 2014). DOI: 10.1214/16-A0P1113.

- Case 3:  $A^* \notin A_1^{sp}(s)$ , and each  $A_q^*$  contains a ball with radius  $n^{-1}$ , but they are not all the same.
- Note that  $A_q^*$  itself is also s-sparsely. We can apply **Lemma D.1** for each  $A_q^*$  such that:  $A_q^{K_q} \subset A_q^* \subset A_q^{K_q, \frac{1}{n}}$ ,  $\forall q \in [K_*]$
- ullet Let  $Q:=\cap_{q=1}^{K_*}A_q^{K_q}$ , then  $Q^{rac{1}{n}}:=\cap_{q=1}^{K_*}A_q^{K_q,rac{1}{n}}$ , and

$$\varnothing = Q^{-\frac{1}{n}} \subset Q \subset A^* \subset Q^{\frac{1}{n}}$$

.

• Nazarov's inequality gives the bound that

$$\mathbb{P}(G \in A^*) \leq \mathbb{P}(G \in Q^{\frac{1}{n}} \backslash Q^{-\frac{1}{n}}) \lesssim n^{-1} (s^2 \log p)^{1/2}$$

- By the result for simple convex set, we can get the estimation of  $\mathbb{P}(S_{n,X} \in A^*)$ .
- $|\mathbb{P}(S_{n,X} \in A^*) \mathbb{P}(G \in A^*)| \leq \mathbb{P}(S_{n,X} \in A^*) + \mathbb{P}(G \in A^*)$

Case 2(Difficult):  $A^* \notin A_1^{sp}(s)$ , and at least  $1 A_q$  don't contain a ball with radius  $n^{-1}$ .

• We need to derive the Berry-Esseen type estimate for convex sets:

$$\sup_{h\in\mathcal{H}}|\mathbb{E}[h(S_{n,X})]-\mathbb{E}[h(G)]|=\sup_{h\in\mathcal{H}}|\int h(x)d(F_n(x)-\Phi(x))|$$

where  $\mathcal{H}$  is the family of indicator function of convex sets.

• Detailed derivation can see<sup>5</sup>, section 9. Motivation can see<sup>6</sup>, chapter 7.

<sup>&</sup>lt;sup>5</sup> Jinyuan Chang, Xiaohui Chen, and Mingcong Wu. "Central limit theorems for high dimensional dependent data". In: Bernoulli 30.1 (Feb. 2024). ISSN: 1350-7265. DOI: 10.3150/23-bej1614. URL: http://dx.doi.org/10.3150/23-BEJ1614.

<sup>&</sup>lt;sup>6</sup>Rabi N. Bhattacharya and R. Ranga Rao. *Normal Approximation and Asymptotic Expansions*. Society for Industrial and Applied Mathematics, 2010. DOI: 10.1137/1.9780898719895. URL: https://epubs.siam.org/doi/abs/10.1137/1.9780898719895.

#### Outline

- Introduction
- Central Limit Theorem for hyperrectangles
- Generalization
- Application for Bootstrap

In theory,  $G \sim N(0, \Xi)$  depends on covariance matrix  $\Xi$ . However, covariance matrix  $\Xi$  is unknown in practice. As a result, we need to construct a series of matrix  $\{\hat{\Xi}_n\}$  to approximate  $\Xi$ 

- Let  $\mathcal{X}_n = \{X_1, X_2, ..., X_n\}$  a data set, data-dependent Gaussian random vector  $\hat{G}|\mathcal{X}_n \sim \mathcal{N}(0, \hat{\Xi}_n)$ .
- To establish theoretical validity, we have to bound

$$\hat{
ho}_n(\mathcal{A}) := \sup_{A \in \mathcal{A}} |\mathbb{P}(S_{n,X} \in A) - \mathbb{P}(\hat{G} \in A|\mathcal{X}_n)|$$

- $\bullet \ \hat{\rho}_n(\mathcal{A}) \leq \rho_n(\mathcal{A}) + \sup_{A \in \mathcal{A}} |\mathbb{P}(\hat{G} \in A | \mathcal{X}_n) \mathbb{P}(G \in A)|$
- The problem is boiled down to estimate the difference between covariance matrix.
- $\Delta_{n,r} := |\hat{\Xi}_n \Xi|_{\infty}$
- By Gaussian comparison, we have

$$\hat{\rho}_n(\mathcal{A}^{\mathrm{re}}) \lesssim \rho_n(\mathcal{A}^{\mathrm{re}}) + \Delta_{n,r}^{1/3} (\log p)^{2/3}.$$

• Hope: Select proper approximation matrices  $\hat{\Xi}_n$  such that  $\Delta_{n,r} = o_p\{(\log p)^{-2}\}$ 

• we suggest to adopt the kernel-type estimator for its long-run covariance matrix, that is

$$\hat{\Xi}_n = \sum_{j=-n+1}^{n-1} \mathcal{K}\left(\frac{j}{b_n}\right) \hat{H}_j$$

where 
$$\hat{H}_j = n^{-1} \sum_{t=j+1}^n (X_t - \bar{X})(X_{t-j} - \bar{X})^{\top}$$
 if  $j \geq 0$  and  $\hat{H}_j = n^{-1} \sum_{t=-j+1}^n (X_{t+j} - \bar{X})(X_t - \bar{X})^{\top}$  if  $j < 0$  with optimal kernel

$$\mathcal{K}_{\mathrm{QS}}(x) = rac{25}{12\pi^2 x^2} \left\{ rac{\sin(6\pi x/5)}{6\pi x/5} - \cos(6\pi x/5) 
ight\}$$

• With assumption above, we have

$$\Delta_{n,r} = O_{\mathrm{p}}\{B_n^2 n^{-c_1} (\log p)^{c_2}\} + O(B_n^2 n^{-\rho})$$

 we see that our proposed parametric bootstrap procedure is asymptotically valid even if the dimension p grows sub-exponentially fast in the sample size n

#### Reference

- [1] Rabi N. Bhattacharya and R. Ranga Rao. *Normal Approximation and Asymptotic Expansions*. Society for Industrial and Applied Mathematics, 2010. DOI: 10.1137/1.9780898719895. URL: https://epubs.siam.org/doi/abs/10.1137/1.9780898719895.
- [2] Jinyuan Chang, Xiaohui Chen, and Mingcong Wu. "Central limit theorems for high dimensional dependent data". In: *Bernoulli* 30.1 (Feb. 2024). ISSN: 1350-7265. DOI: 10.3150/23-bej1614. URL: http://dx.doi.org/10.3150/23-BEJ1614.
- [3] Victor Chernozhukov, Denis Chetverikov, and Kengo Kato. "Gaussian approximations and multiplier bootstrap for maxima of sums of high-dimensional random vectors". In: *The Annals of Statistics* 41.6 (Dec. 2013). ISSN: 0090-5364. DOI: 10.1214/13-aos1161. URL: http://dx.doi.org/10.1214/13-AOS1161.
- [4] Victor Chernozukov, Denis Chetverikov, and Kengo Kato. "Central Limit Theorems and Bootstrap in High Dimensions". In: *The Annals of Probability* 45 (Dec. 2014). DOI: 10.1214/16-A0P1113.