view_frames Result Recorded at time: 123.706 map Broadcaster: /turtlebot3_slam_gmapping Average rate: 20.433 Hz Most recent transform: 123.750 (-0.044 sec old) Buffer length: 2.447 sec odom Broadcaster: /gazebo Average rate: 100.407 Hz Most recent transform: 123.701 (0.005 sec old) Buffer length: 2.460 sec base_footprint Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (123.706 sec old) Buffer length: 0.000 sec base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (123.706 sec old) Most recent transform: 0.000 (123.706 sec old) Most recent transform: 0.000 (123.706 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec

base_scan

imu_link

Broadcaster: /robot_state_publisher

Average rate: 10000.000 Hz

Most recent transform: 0.000 (123.706 sec old)

Buffer length: 0.000 sec

base_camera

caster_back_link