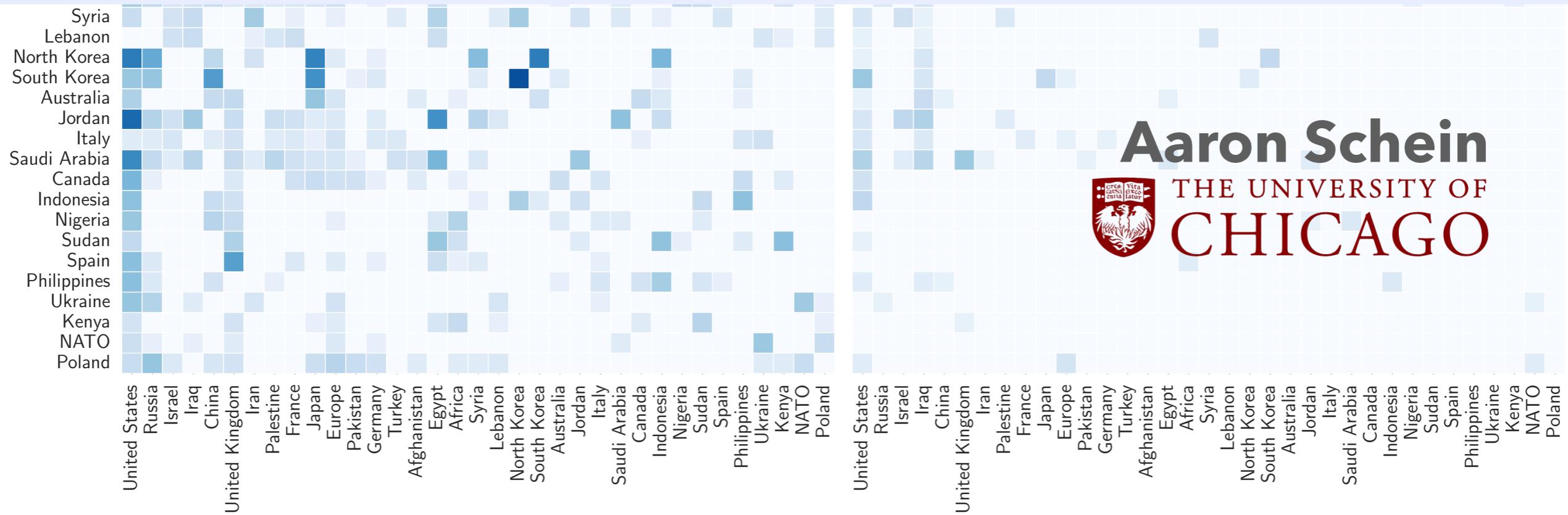


Tensor Decomposition Models for Measuring Complex Dependence Structure in Sparse Dyadic Event Data



Aaron Schein

THE UNIVERSITY OF
CHICAGO

DYADIC EVENT DATA

Example from [Schrodt et al. \[1995\]](#):

Table 2
WEIS Coding of 1990 Iraq-Kuwait Crisis

<u>Date</u>	<u>Source</u>	<u>Target</u>	<u>Type of Action</u>
900717	IRQ	KUW	CHARGE
900725	IRQ	EGY	ASSURE
900727	IRQ	KUW	WARN
900731	IRQ	KUW	MOBILIZATION
900801	KUW	IRQ	REFUSE
900802	IRQ	KUW	MILITARY FORCE

DYADIC EVENT DATA

Example from [Schrodt et al. \[1995\]](#):

Table 2
WEIS Coding of 1990 Iraq-Kuwait Crisis

Date	Source	Target	Type of Action
900717	IRQ	KUW	CHARGE
900725	IRQ	EGY	ASSURE
900727	IRQ	KUW	WARN
900731	IRQ	KUW	MOBILIZATION
900801	KUW	IRQ	REFUSE
900802	IRQ	KUW	MILITARY FORCE

DYADIC EVENT DATA

Example from [Schrodt et al. \[1995\]](#):

Table 2
WEIS Coding of 1990 Iraq-Kuwait Crisis

Date	Source	Target	Type of Action
900717	IRQ	KUW	CHARGE
900725	IRQ	EGY	ASSURE
900727	IRQ	KUW	WARN
900731	IRQ	KUW	MOBILIZATION
900801	KUW	IRQ	REFUSE
900802	IRQ	KUW	MILITARY FORCE

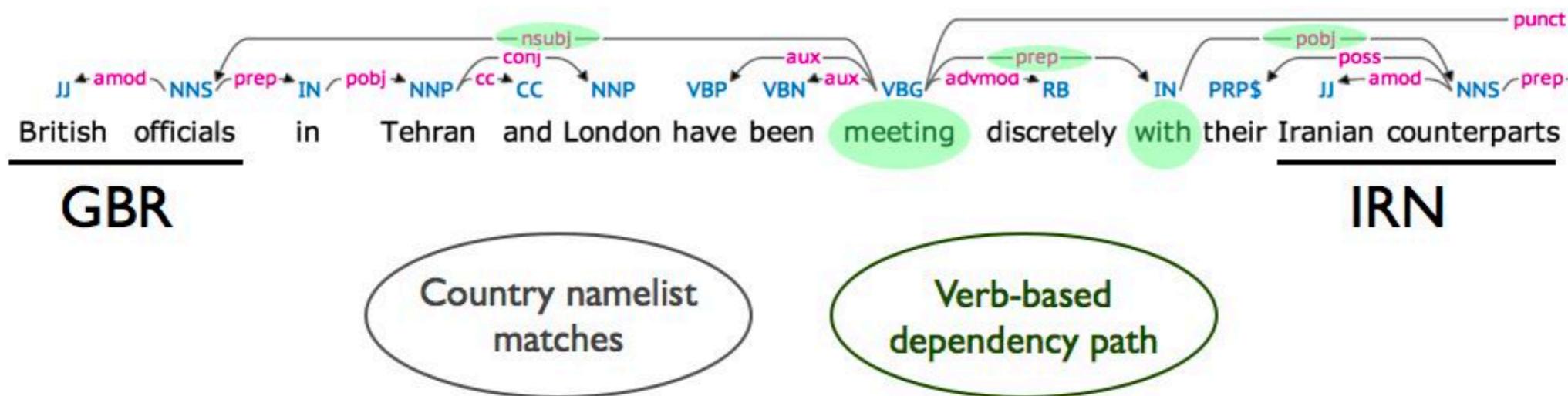
July 31, 1990: IRAQ INCREASES TROOP LEVELS ON KUWAIT BORDER

Iraq has concentrated nearly 100,000 troops close to the Kuwaiti border, more than triple the number reported a week ago, the Washington Post said in its Tuesday editions.

MACHINE-CODED EVENT DATA

Figure from O'Connor [2013]:

Event Extraction: Who did what to whom?



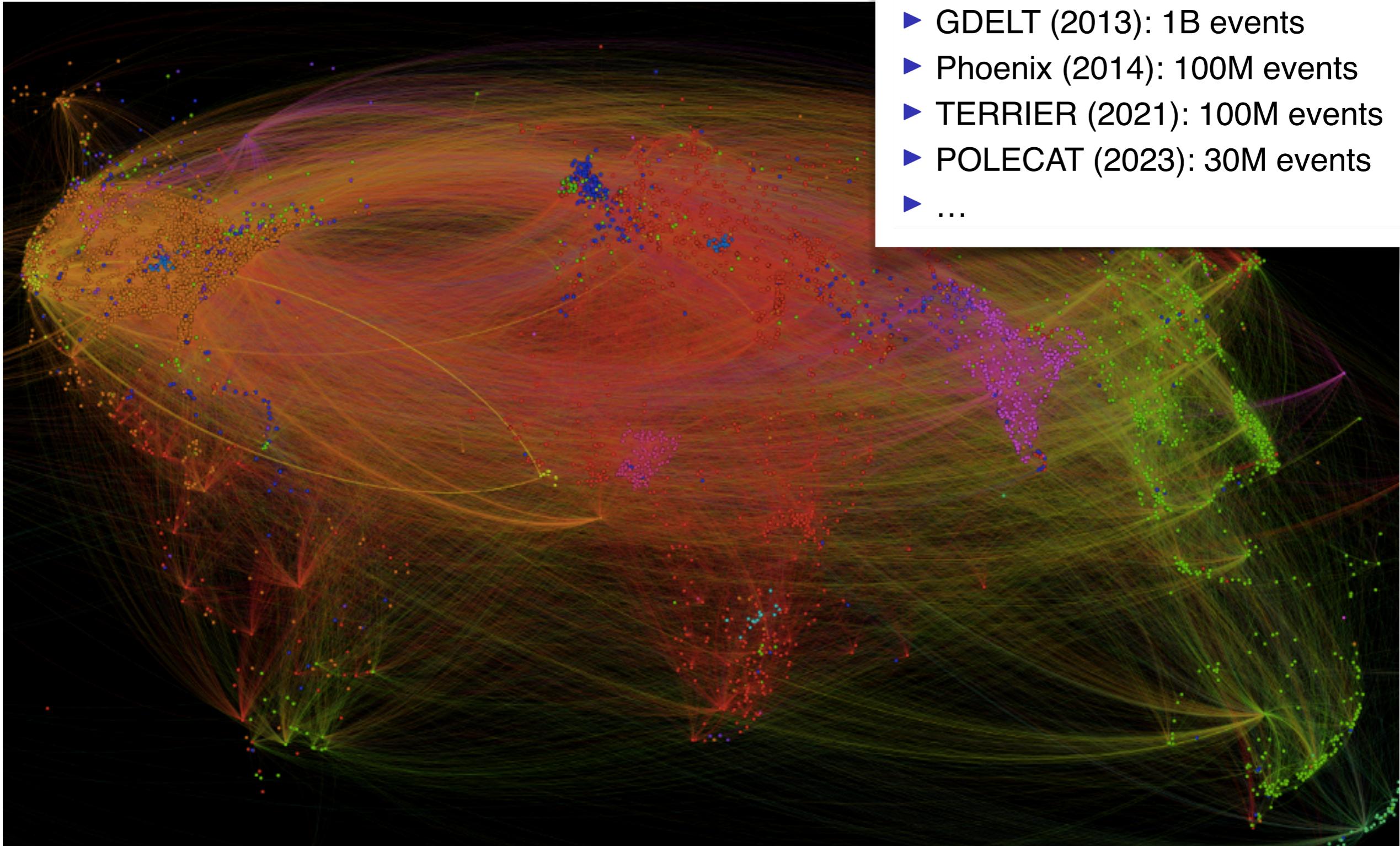
Source (*s*): **GBR**
Recipient (*r*): **IRN**
Predicate (*w*): <–*nsubj*– **meet** –*prep*–> **with** –*pobj*–>

“X meets with Y”

Proto-role terminology
(Dowty 1991): Agent, Patient

MODERN DYADIC EVENT DATA SETS

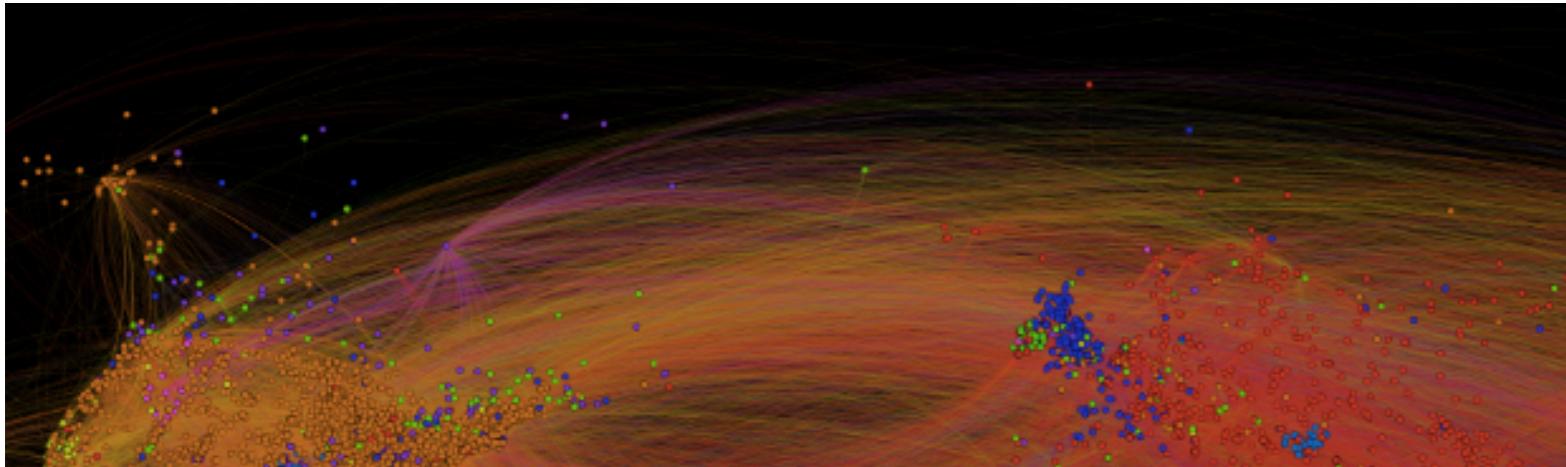
Lots of progress on event **extraction**...



- ▶ ICEWS (2011): 10M events
- ▶ GDELT (2013): 1B events
- ▶ Phoenix (2014): 100M events
- ▶ TERRIER (2021): 100M events
- ▶ POLECAT (2023): 30M events
- ▶ ...

MODERN DYADIC EVENT DATA SETS

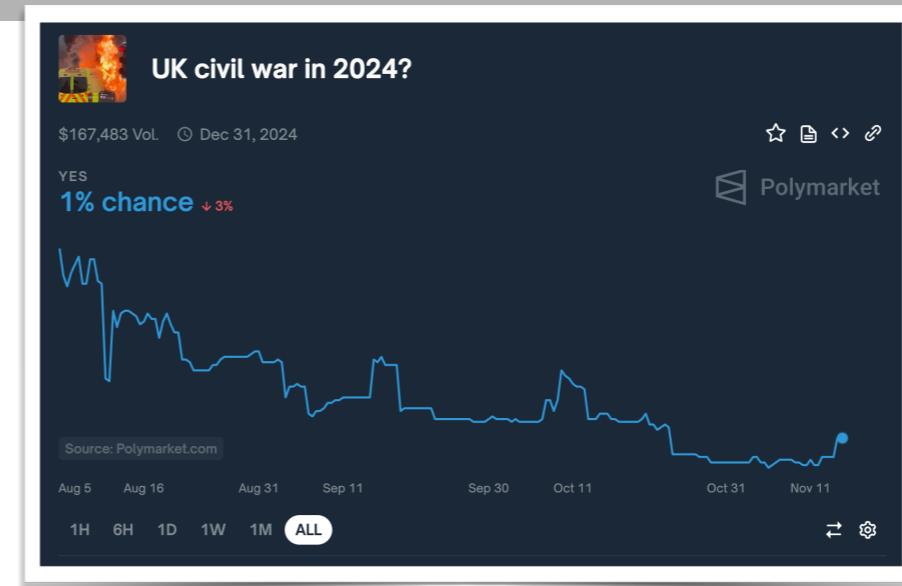
Lots of progress on event extraction...



- ▶ ICEWS (2011): 10M events
- ▶ GDELT (2013): 1B events
- ▶ Phoenix (2014): 100M events
- ▶ TERRIER (2021): 100M events
- ▶ POLECAT (2023): 30M events
- ▶ ...

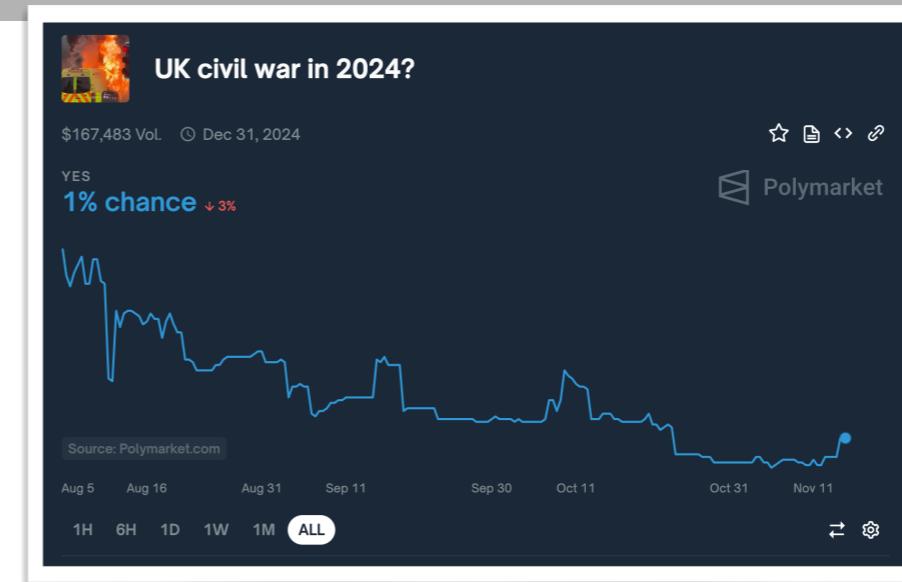
Event_Date	Source_Name	Source_Sectors	Source_Country	Event_Text	CAMEO	Target_Name	Target_Sectors	Target_Country
2022-06-14	Foreign Affairs (Japan)	Executive,Forei...	Japan	Consult	40	Abul Kalam Abdul ...	Executive,Forei...	Bangladesh
2002-04-10	Business (Iraq)	Social,Business	Iraq	Sign formal agre...	57	Industry (Bahrain)	Social,Business	Bahrain
2005-01-13	Israeli Defense Forces	Military,Govern...	Israel	fight with small ...	193	Citizen (Palestinia...	General Popul...	Occupied Pal...
2001-03-01	Royal Administration (...)	Government	Nepal	Engage in negot...	46	Jiang Zemin	Executive Offic...	China
2005-06-27	Foreign Affairs (Irelan...	Executive,Forei...	Ireland	Consult	40	Secretary of State ...	Government,E...	United Kingd...
2006-03-13	Civil Service (Kazakhs...	Government	Kazakhstan	Consult	40	Foreign Affairs (C...	Foreign Minist...	China
1999-08-30	Ilya Iosifovich Klebanov	Executive Offic...	Russian Fed...	Host a visit	43	Jiang Zemin	Executive,Gov...	China
2022-04-20	Nikol Pashinyan	Elite,Executive,...	Armenia	Express intent t...	36	Federal Assembly	Government,L...	Switzerland
2012-09-03	Legislature (Syria)	Government,Le...	Syria	Consult	40	Foreign Affairs (R...	Executive,Gov...	Russian Fed...
2005-07-27	Head of Government (...)	Executive,Gove...	Guyana	Engage in negot...	46	Tang Jiaxuan	Elite,Governme...	China
2009-10-02	Defense / Security Mi...	Government,De...	Belarus	Consult	40	Defense / Security...	Defense / Sec...	Russian Fed...
2004-12-17	Jean-Claude Juncker	Elite,Executive ...	Luxembourg	Criticize or deno...	111	Citizen (Belgium)	Social,General ...	Belgium
2004-04-23	Vladimir Putin	Executive,Exec...	Russian Fed...	Consult	40	Leonid Kuchma	Elite,Executive,...	Ukraine
2018-07-26	Qasem Soleimani	Government,Mi...	Iran	Threaten	130	Donald Trump	Government,E...	United States

(POTENTIAL) APPLICATIONS OF EVENT DATA



(POTENTIAL) APPLICATIONS OF EVENT DATA

- ▶ **Predictive:**
 - ▶ e.g., forecasting civil war



(POTENTIAL) APPLICATIONS OF EVENT DATA

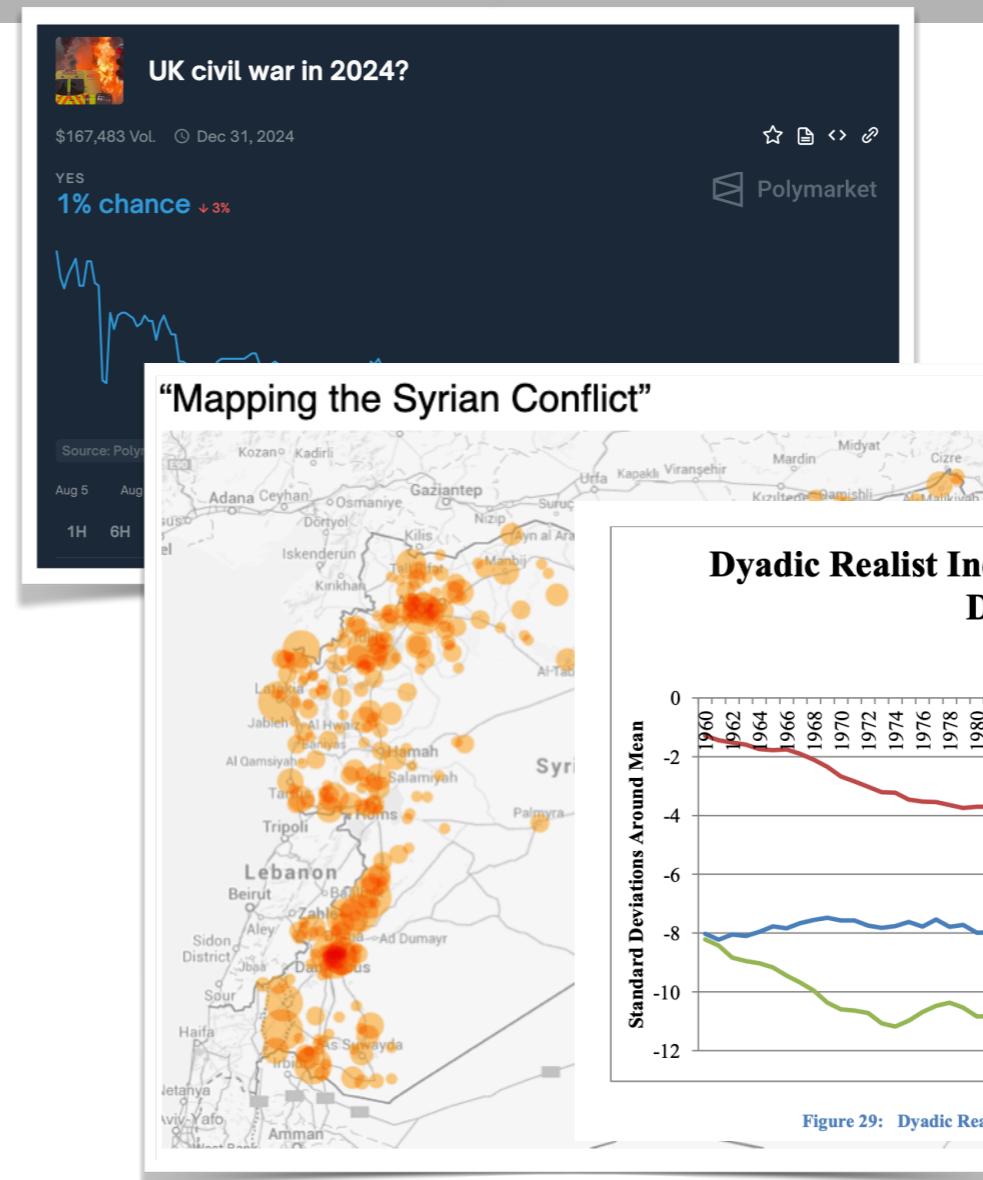


Figure 29: Dyadic Realist Index Select Passive Dyads

(POTENTIAL) APPLICATIONS OF EVENT DATA

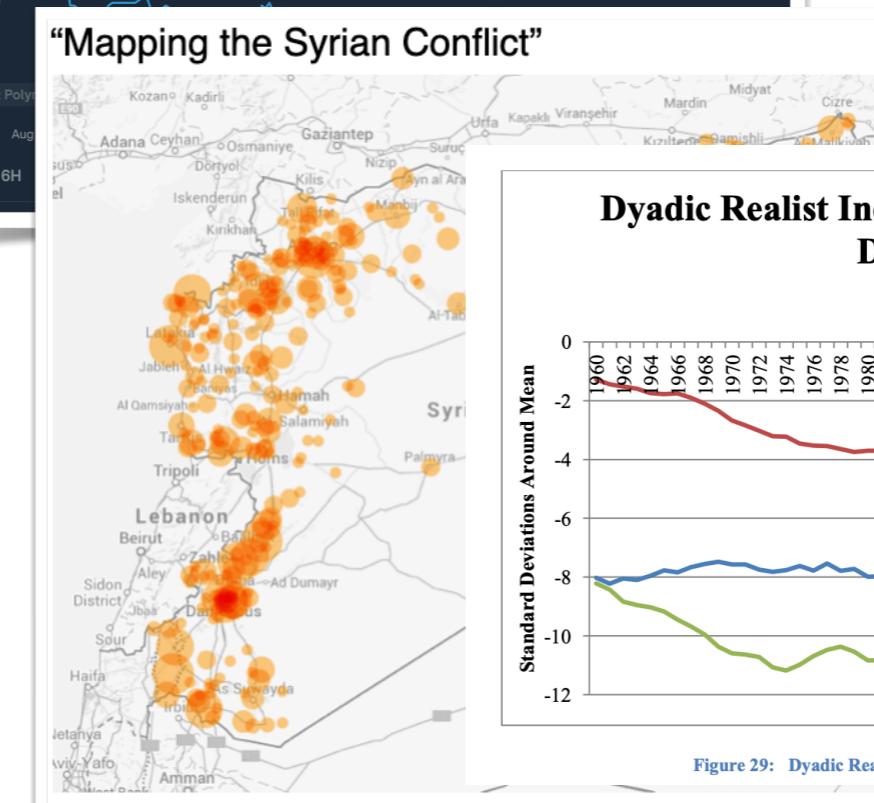
► Predictive:

- e.g., forecasting civil war



► Descriptive:

- e.g., “power imbalance” index
- e.g., conflict mapping



► Exploratory:

- hypothesis generation

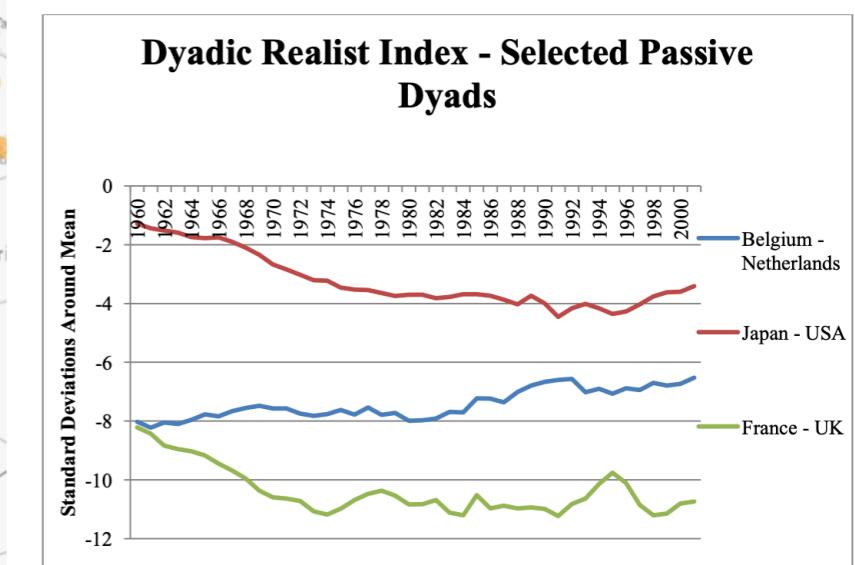
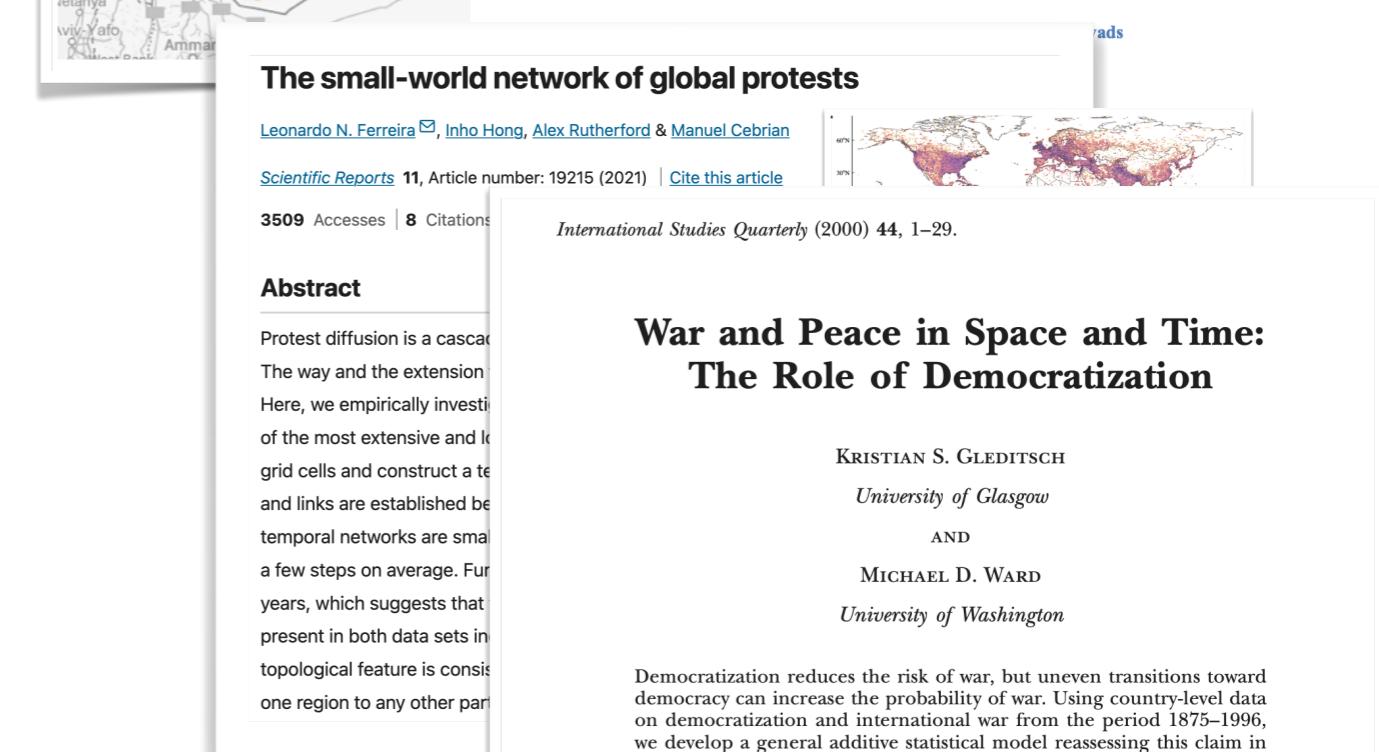
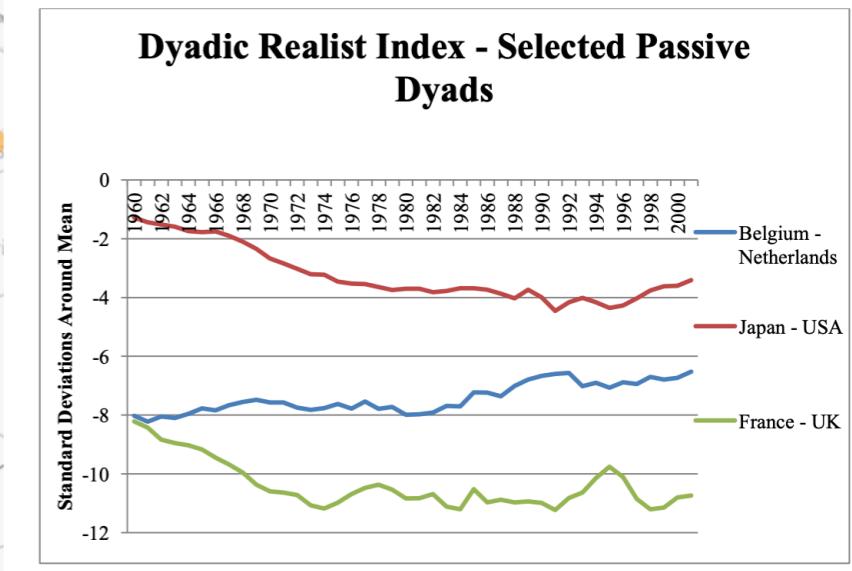
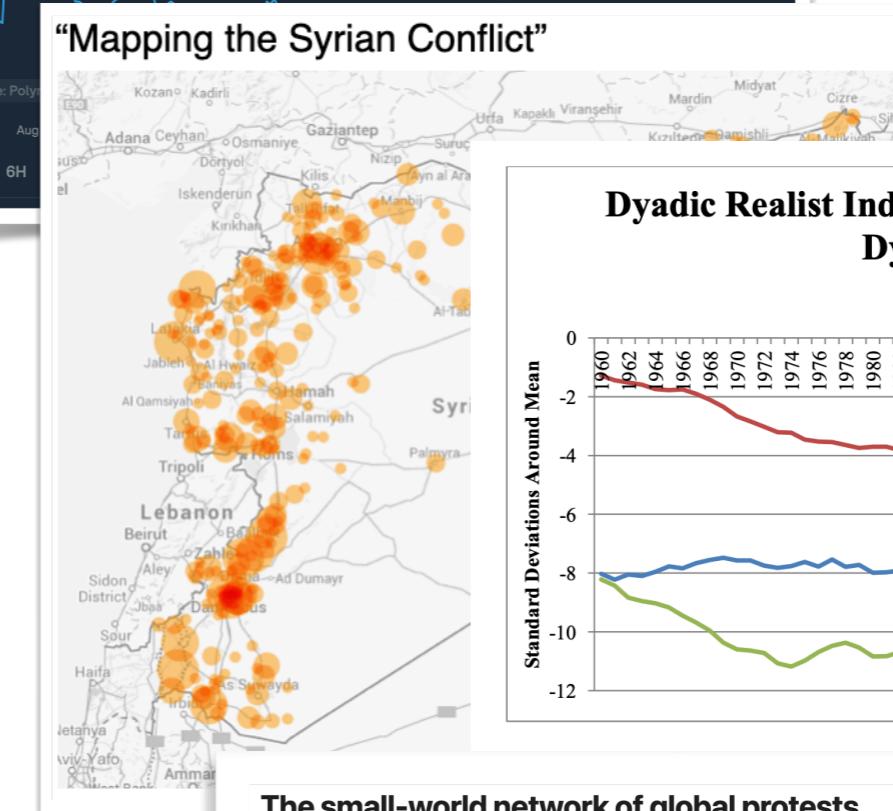
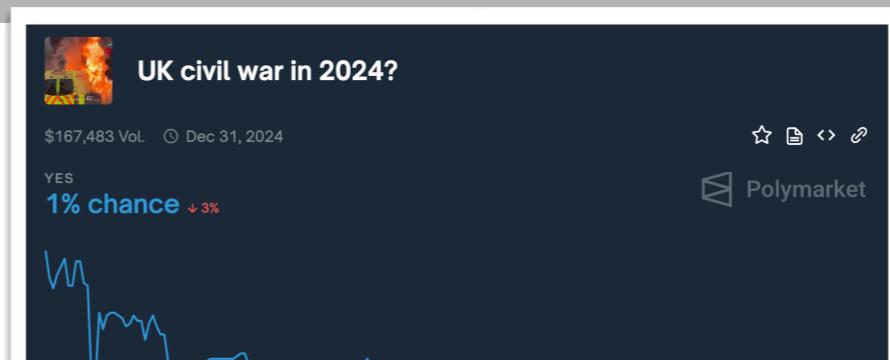


Figure 29: Dyadic Realist Index Select Passive Dyads

(POTENTIAL) APPLICATIONS OF EVENT DATA



(POTENTIAL) APPLICATIONS OF EVENT DATA

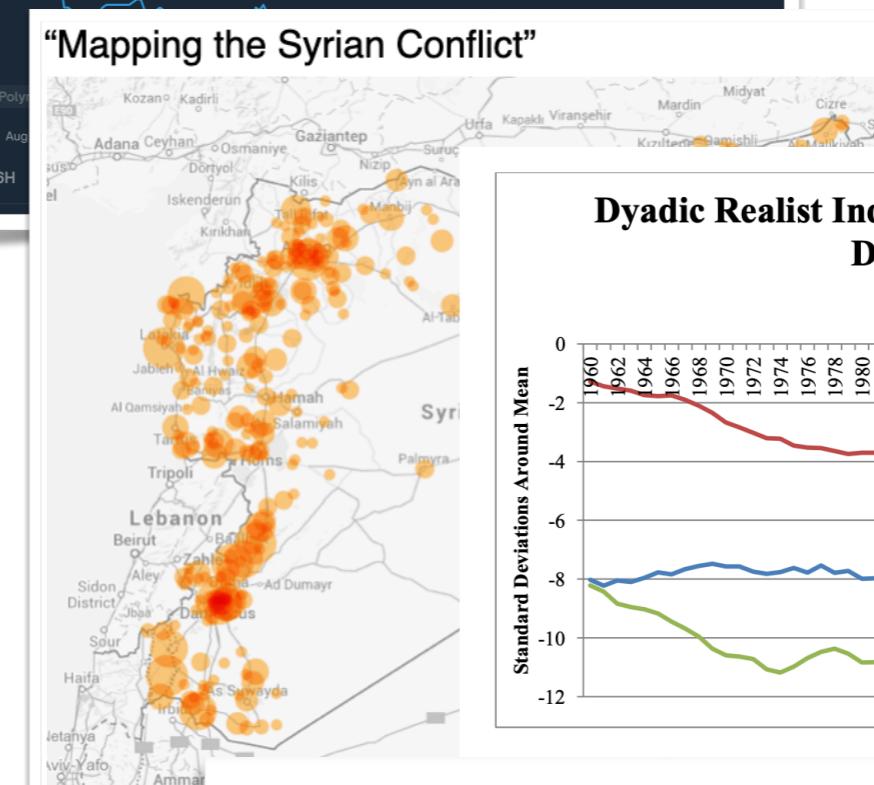
► Predictive:

- e.g., forecasting civil war



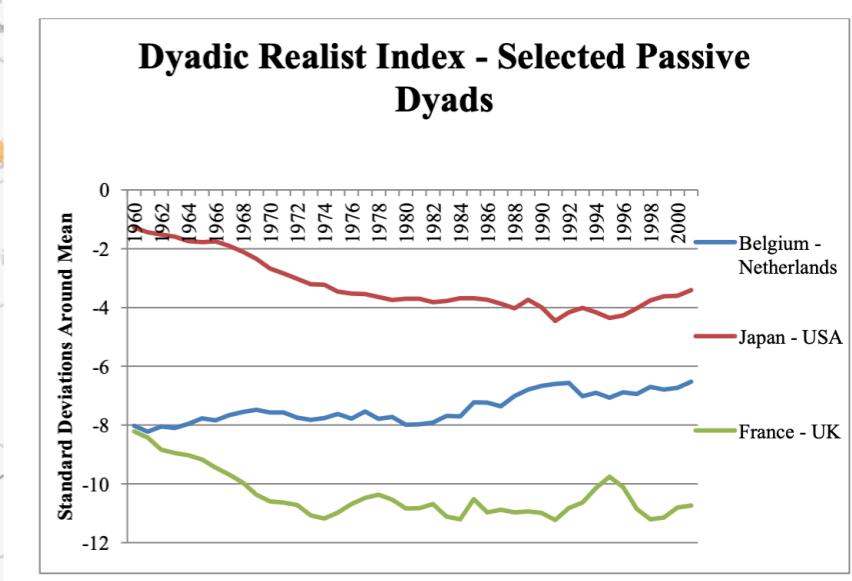
► Descriptive:

- e.g., “power imbalance” index
- e.g., conflict mapping



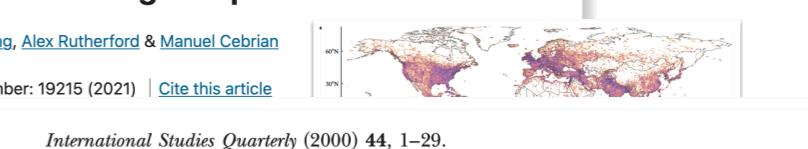
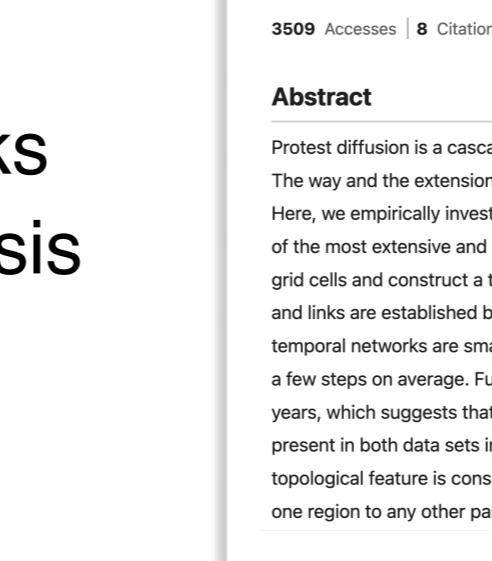
► Exploratory:

- hypothesis generation



► Explanatory:

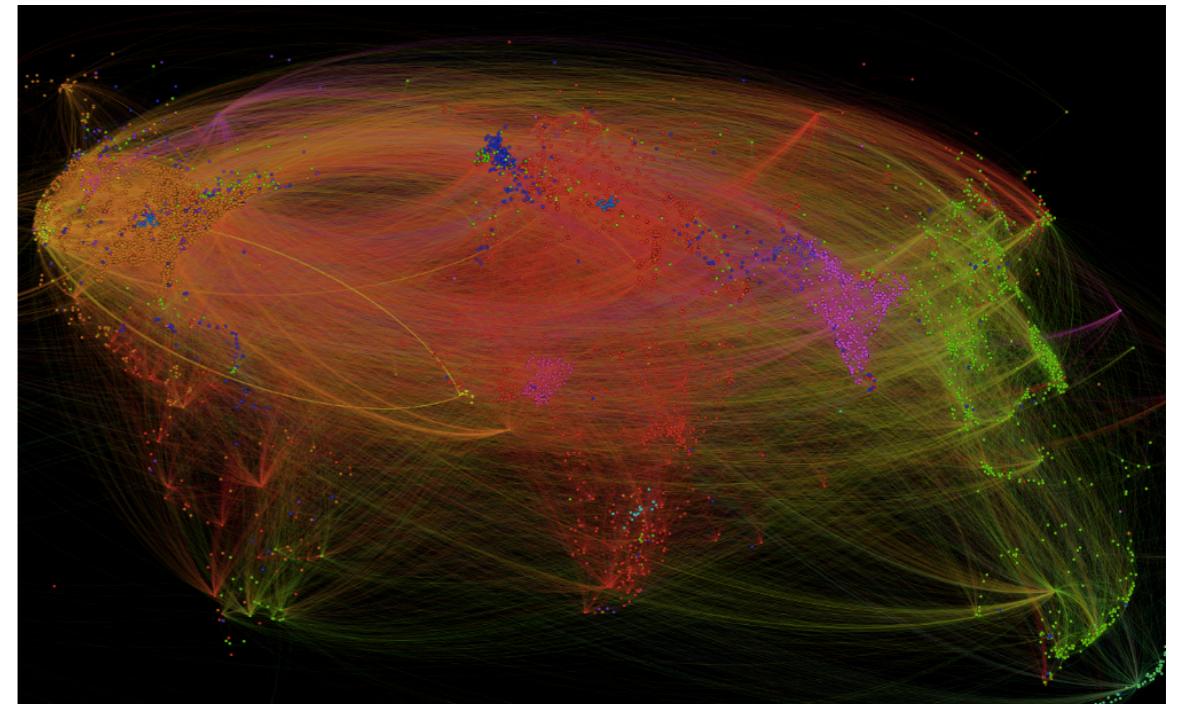
- test theories / hypotheses
- e.g., small-world protest networks
- e.g., Democratic peace hypothesis



Democratization reduces the risk of war, but uneven transitions toward democracy can increase the probability of war. Using country-level data on democratization and international war from the period 1875–1996, we develop a general additive statistical model reassessing this claim in light of temporal and spatial dependence. We also develop a new geopolitical database of contiguities and demonstrate new statistical techniques for probing the extent of spatial clustering and its impact on the

CHALLENGES

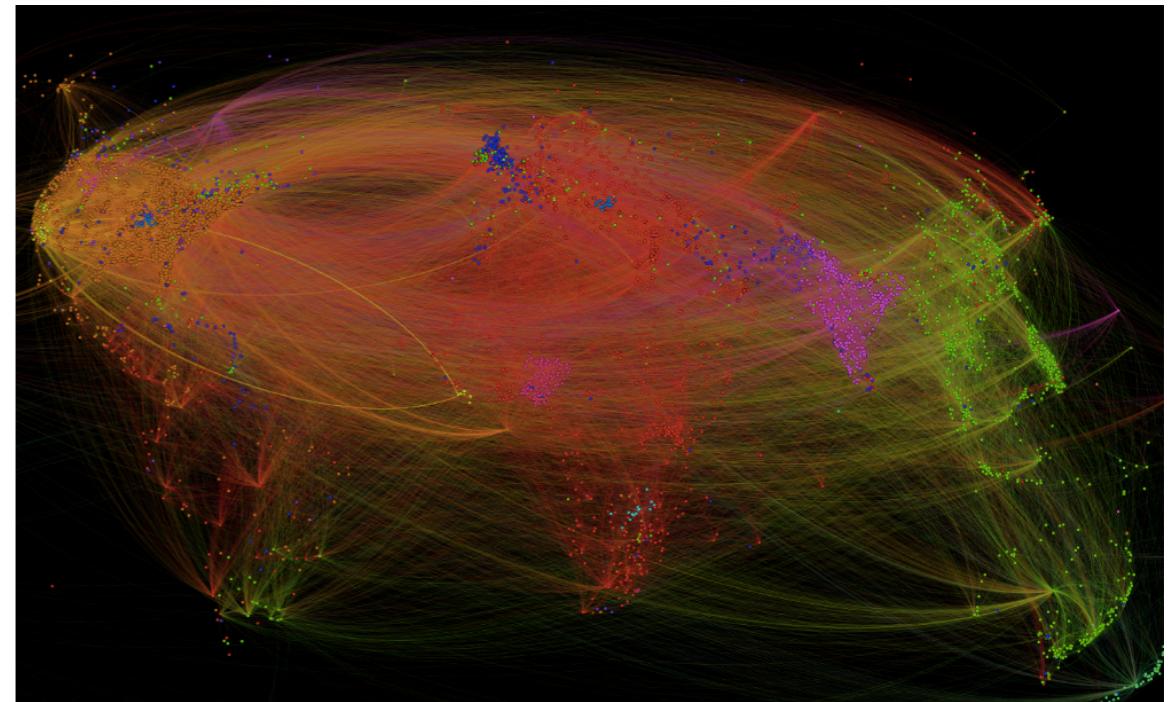
- ▶ **Noisy, error-prone, biased:**
 - ▶ Extraction / coding errors
 - ▶ Reporting / sourcing biases



CHALLENGES

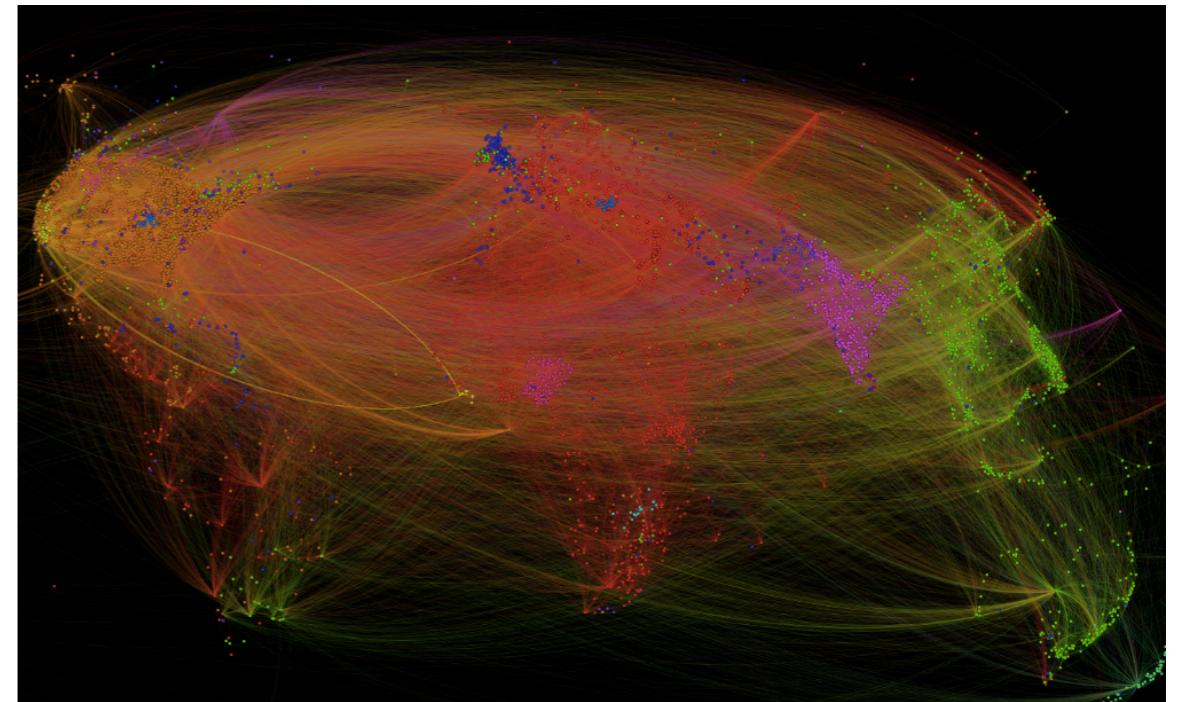
- ▶ **Noisy, error-prone, biased:**
 - ▶ Extraction / coding errors
 - ▶ Reporting / sourcing biases

- ▶ **High-dimensional, big, structured:**
 - ▶ e.g., 100M events
 - ▶ e.g., 300K unique “source sectors”
 - ▶ e.g., hierarchical coding schemes



CHALLENGES

- ▶ **Noisy, error-prone, biased:**
 - ▶ Extraction / coding errors
 - ▶ Reporting / sourcing biases
- ▶ **High-dimensional, big, structured:**
 - ▶ e.g., 100M events
 - ▶ e.g., 300K unique “source sectors”
 - ▶ e.g., hierarchical coding schemes
- ▶ **Complex dependencies**
 - ▶ network dependence
 - ▶ temporal dependence
 - ▶ ...

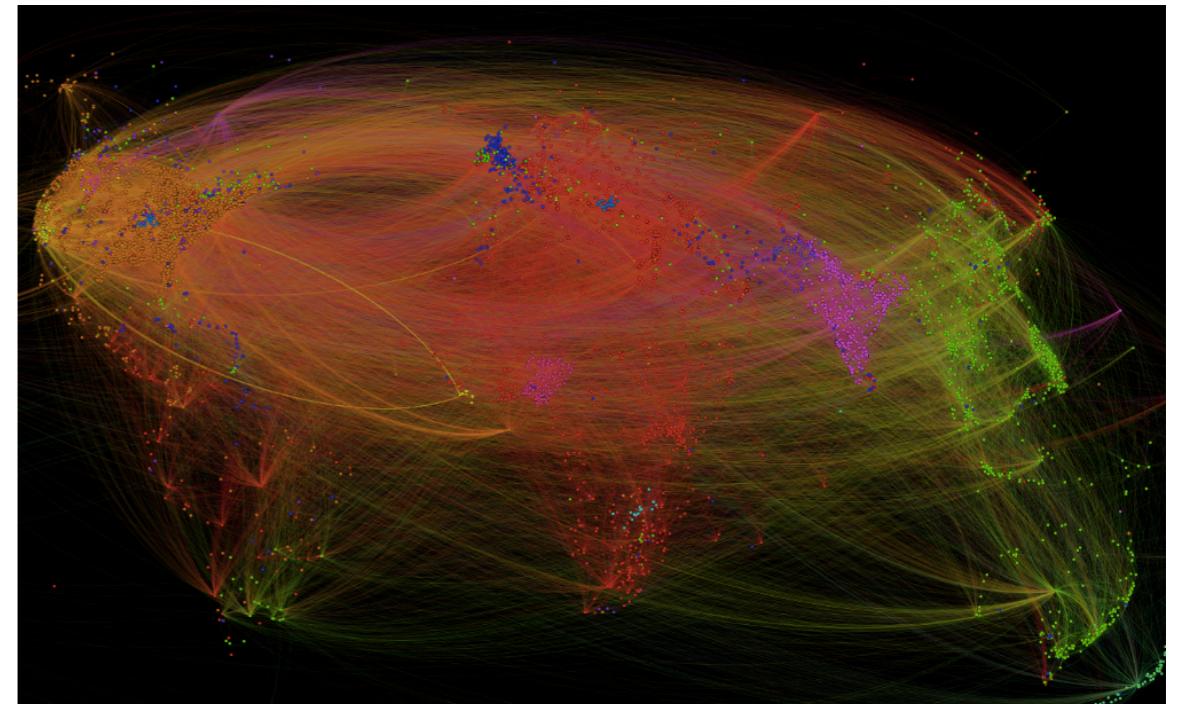


King [2001]:

[...] *dyadic observations in international conflict data have complex dependence structures [...]*

CHALLENGES

- ▶ **Noisy, error-prone, biased:**
 - ▶ Extraction / coding errors
 - ▶ Reporting / sourcing biases
- ▶ **High-dimensional, big, structured:**
 - ▶ e.g., 100M events
 - ▶ e.g., 300K unique “source sectors”
 - ▶ e.g., hierarchical coding schemes
- ▶ **Complex dependencies**
 - ▶ network dependence
 - ▶ temporal dependence
 - ▶ ...
- ▶ **Dyadic only**
 - ▶ e.g., summits not recorded
 - ▶ e.g., alliances not recorded



King [2001]:

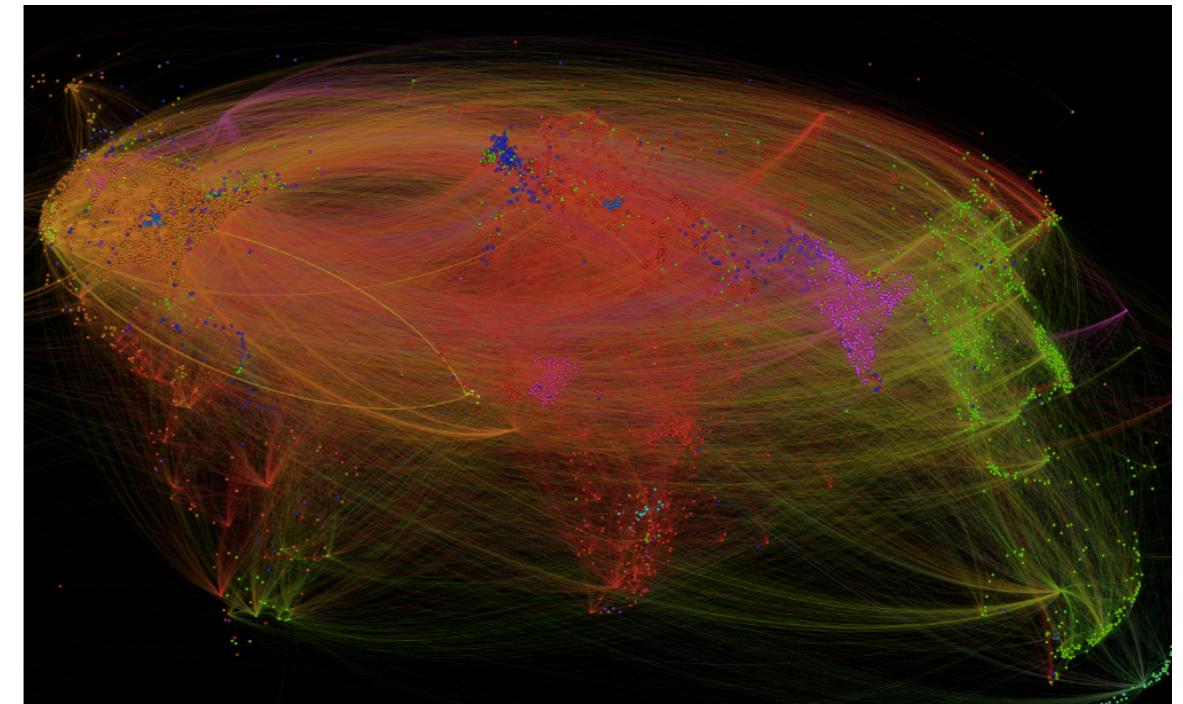
[...] *dyadic observations in international conflict data have complex dependence structures [...]*

Poast [2010]:

Dyadic (state-pair) data is completely inappropriate for analyzing multilateral events (such as large alliances and major wars).

CHALLENGES

- ▶ **Noisy, error-prone, biased:**
 - ▶ Extraction / coding errors
 - ▶ Reporting / sourcing biases
- ▶ **High-dimensional, big, structured:**
 - ▶ e.g., 100M events
 - ▶ e.g., 300K unique “source sectors”
 - ▶ e.g., hierarchical coding schemes
- ▶ **Complex dependencies**
 - ▶ network dependence
 - ▶ temporal dependence
 - ▶ ...
- ▶ **Dyadic only**
 - ▶ e.g., summits not recorded
 - ▶ e.g., alliances not recorded



King [2001]:

*[...] dyadic observations in international conflict data have **complex dependence structures** [...]*

Poast [2010]:

*Dyadic (state-pair) data is **completely inappropriate** for analyzing multilateral events (such as large alliances and major wars).*



Need: models to extract meaningful signal

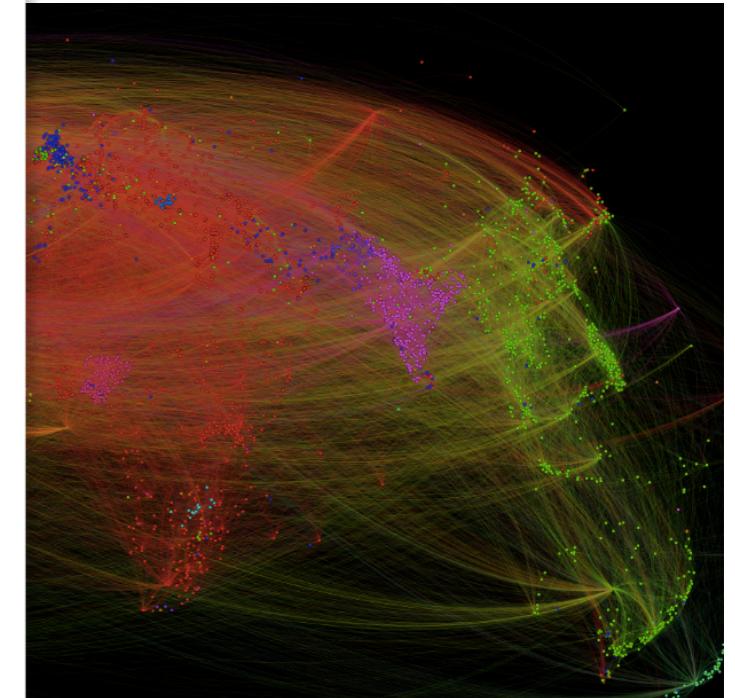
CHALLENGES

Relax, Tensors Are Here Dependencies in International Processes[☆]

Shahryar Minhas^a, Peter D. Hoff^b, Michael D. Ward^{a,*}

^a*Department of Political Science, Duke University, Durham, NC 27701, USA*

^b*Departments of Biostatistics & Statistics, University of Washington, Seattle, WA, USA*



Abstract

Previous models of international conflict have suffered two shortfalls. They tended not to embody dynamic changes, focusing rather on static slices of behavior over time. These models have also been empirically evaluated in ways that assumed the independence of each country, when in reality they are searching for the interdependence among all countries. We illustrate a solution to these two hurdles and evaluate this new, dynamic, network based approach to the dependencies among the ebb and flow of daily international interactions using a newly developed, and openly available, database of events among nations.

Keywords: Dynamic networks, time series, international crises, event data, tensor products

ns in interna-
complex de-
]

• Dyadic [2010].

► Dyadic only

- e.g., summits not recorded
- e.g., alliances not recorded



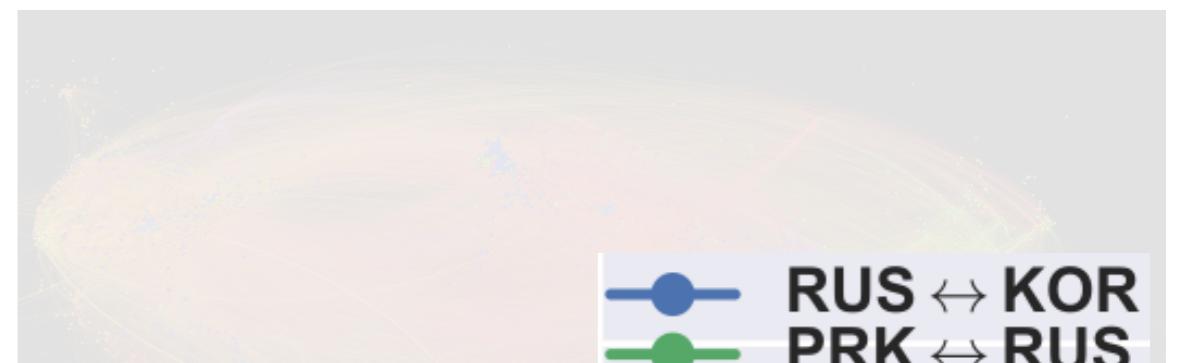
Dyadic (state-pair) data is completely inappropriate for analyzing multilateral events (such as large alliances and major wars).



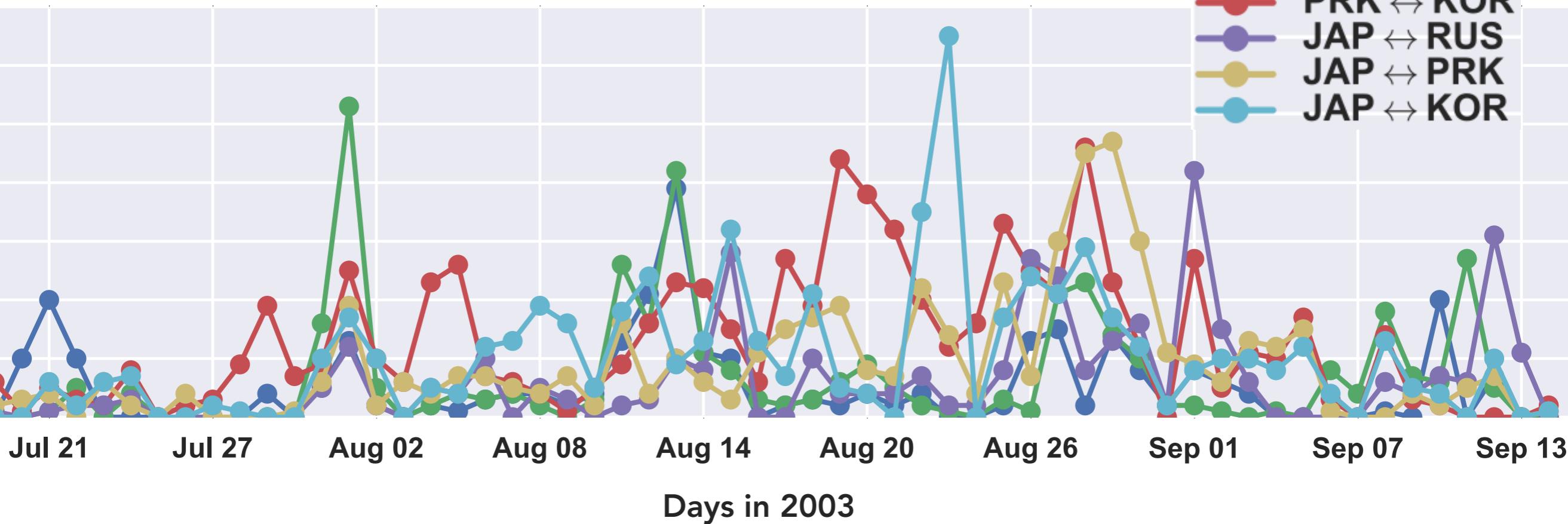
Need: models to extract meaningful signal

CHALLENGES

- ▶ Noisy, error-prone, biased:
 - ▶ Extraction / coding errors
 - ▶ Reporting / sourcing biases



—●—	RUS ↔ KOR
—●—	PRK ↔ RUS
—●—	PRK ↔ KOR
—●—	JAP ↔ RUS
—●—	JAP ↔ PRK
—●—	JAP ↔ KOR



- ▶ Dyadic only
 - ▶ e.g., summits not recorded
 - ▶ e.g., alliances not recorded

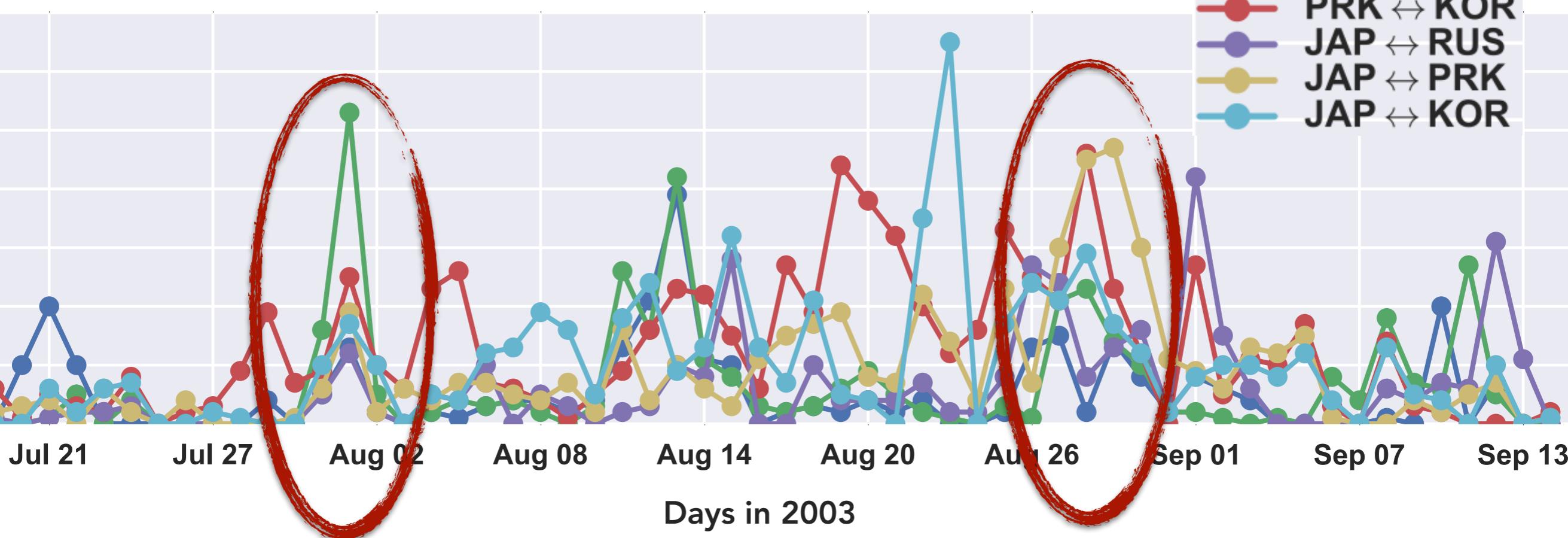
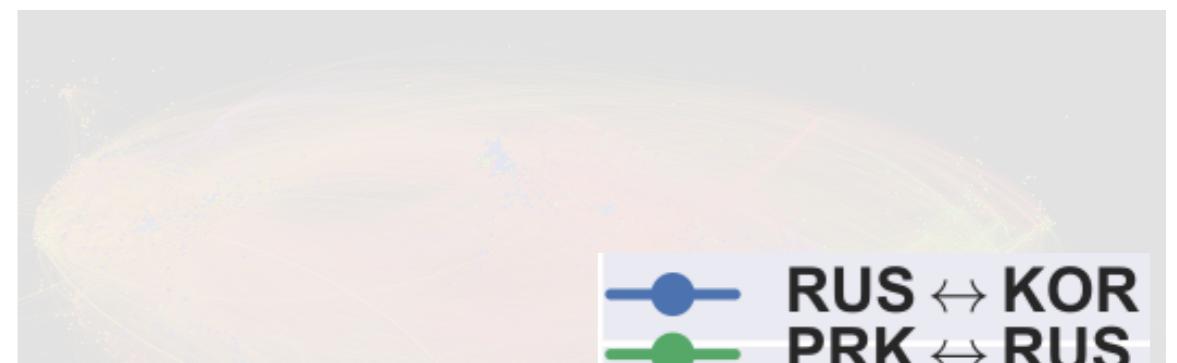
Dyadic (state-pair) data is completely inappropriate for analyzing multilateral events (such as large alliances and major wars).



➡ Need: models to extract meaningful signal

CHALLENGES

- ▶ Noisy, error-prone, biased:
 - ▶ Extraction / coding errors
 - ▶ Reporting / sourcing biases



- ▶ Dyadic only
 - ▶ e.g., summits not recorded
 - ▶ e.g., alliances not recorded



Dyadic (state-pair) data is completely inappropriate for analyzing multilateral events (such as large alliances and major wars).



Need: models to extract meaningful signal

CHALLENGES

- ▶ Noisy, error-prone, b
- ▶ Extraction / coding
- ▶ Reporting / sourcir

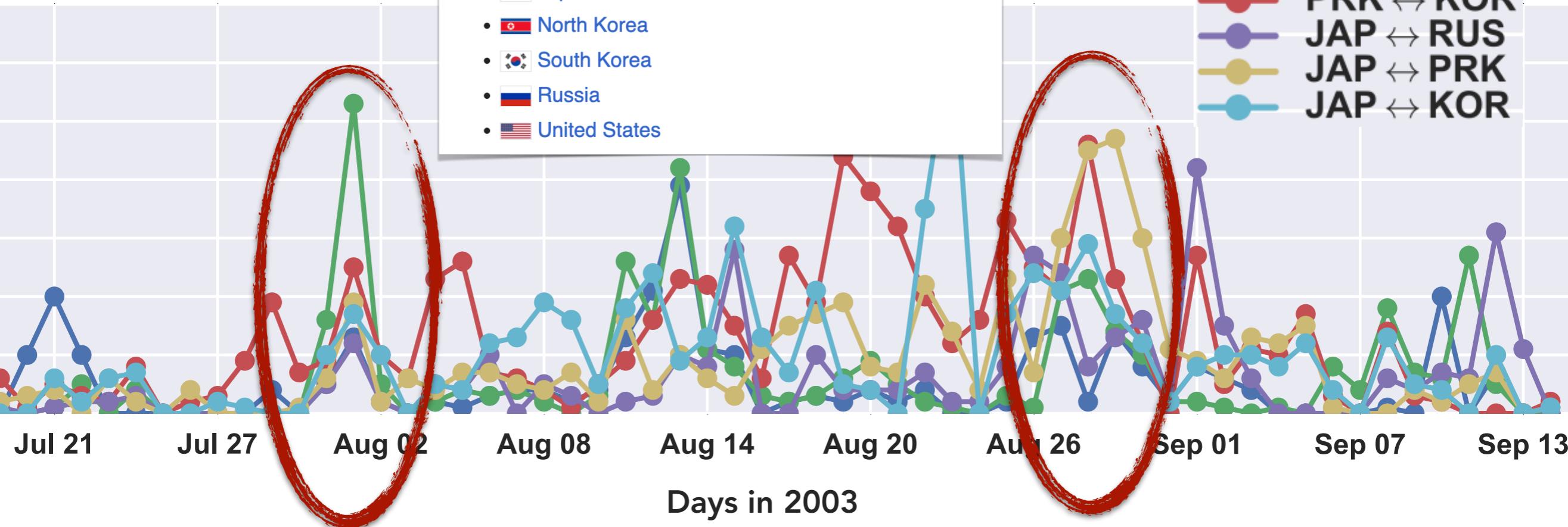
≡ Six-party talks

Article [Talk](#)

From Wikipedia, the free encyclopedia

The **six-party talks** aimed to find a peaceful resolution to the security concerns as a result of the [North Korean nuclear weapons program](#). There was a series of meetings with six participating states in [Beijing](#):^[1]

- China
- Japan
- North Korea
- South Korea
- Russia
- United States



- ▶ Dyadic only
 - ▶ e.g., summits not recorded
 - ▶ e.g., alliances not recorded

Dyadic (state-pair) data is completely inappropriate for analyzing multilateral events (such as large alliances and major wars).



Need: models to extract meaningful signal

(there *is* signal)

OUTLINE

- ▶ **Motivation:** Dyadic event data (and its challenges)
- ▶ **Non-negative (Poisson) tensor decompositions**
 - ▶ **CP** extracts “multilateral” structure [[Schein et al., 2015](#)]
 - ▶ **Tucker** extracts “communities” [[Schein et al., 2016](#)]
 - ▶ Why (allocative) Poisson factorization
 - ▶ **AL ℓ_0 CORE** avoids the “exponential blowup” [[Hood & Schein, 2024](#)]

Appendix (*time permitting*)

- ▶ **State-space** modeling
 - ▶ **Gamma state-space** models [[Schein et al., 2016b](#); [Schein et al., 2019](#)]
 - ▶ **Modeling “escalation”** with a new matrix prior [[Stoehr et al., 2023](#)]

OUTLINE

- ▶ Motivation: Dyadic event data (and its challenges)
- ▶ Non-negative (Poisson) tensor decompositions
 - ▶ CP extracts “multilateral” structure [Schein et al., 2015]
 - ▶ Tucker extracts “communities” [Schein et al., 2016]
 - ▶ Why (allocative) Poisson factorization
 - ▶ AL ℓ_0 CORE avoids the “exponential blowup” [Hood & Schein, 2024]

Appendix (*time permitting*)

- ▶ State-space modeling
 - ▶ Gamma state-space models [Schein et al., 2016b; Schein et al., 2019]
 - ▶ Modeling “escalation” with a new matrix prior [Stoehr et al., 2023]

Event tokens

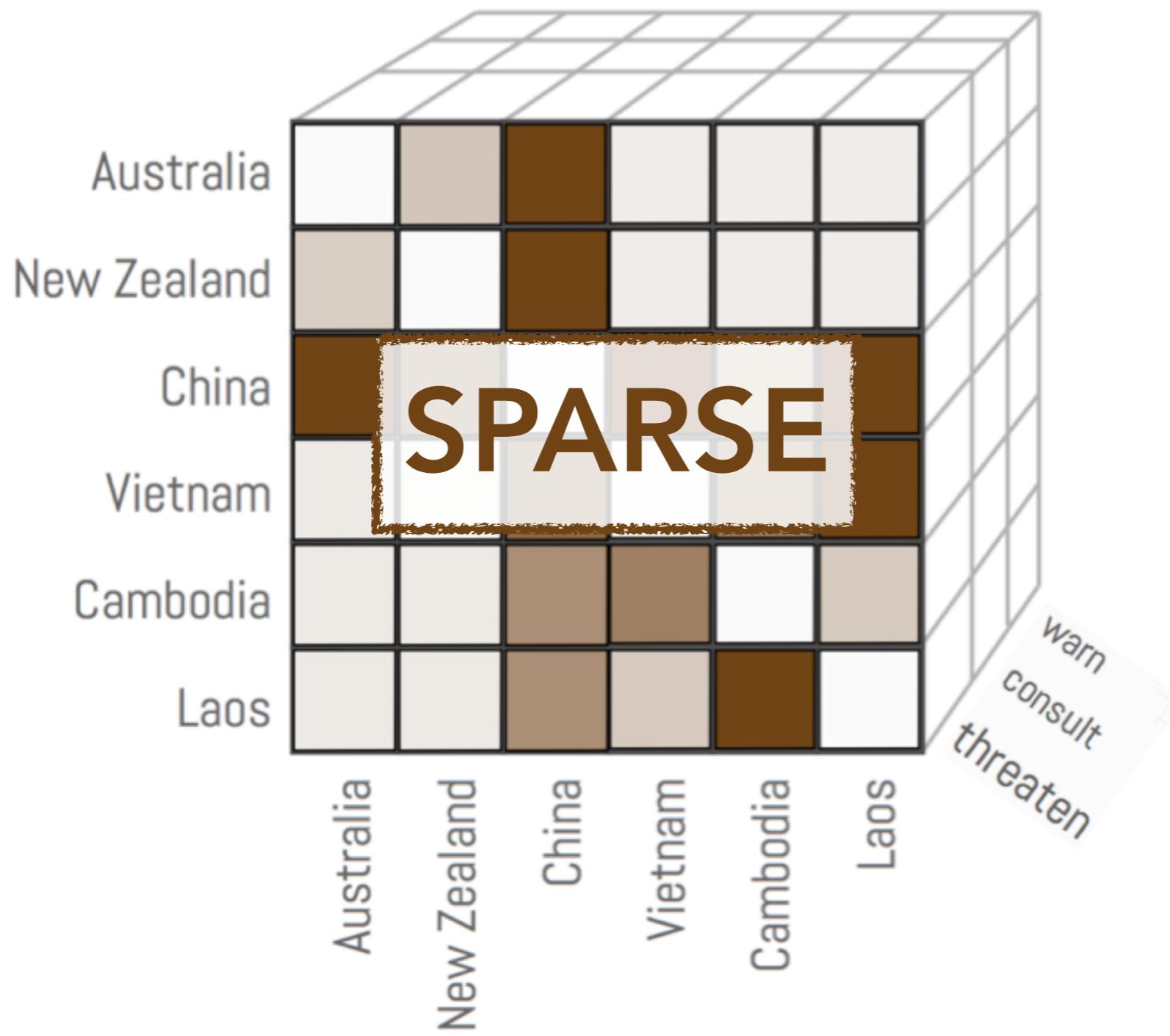
Table 2
WEIS Coding of 1990 Iraq-Kuwait Crisis [Schrodt, '93]

Date	Source	Target	Type of Action
900717	IRQ	KUW	CHARGE
900725	IRQ	EGY	ASSURE
900727	IRQ	KUW	WARN
900731	IRQ	KUW	MOBILIZATION
900801	KUW	IRQ	REFUSE
900802	IRQ	KUW	MILITARY FORCE

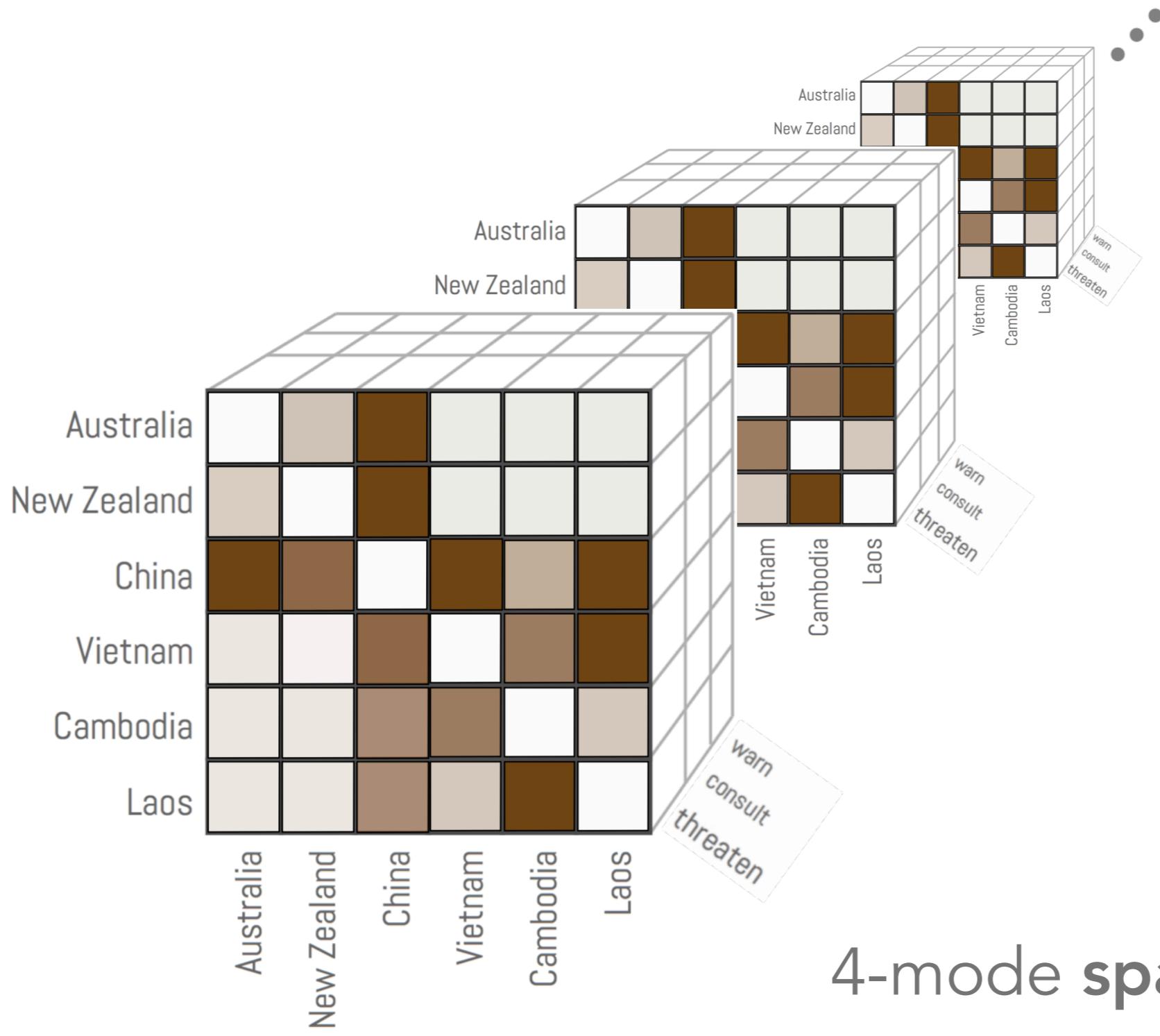
Event type counts

$y_{i \xrightarrow{a} j}^{(t)} =$ “the number of tokens of type
country i took **action a** to
country j during **time t** ”

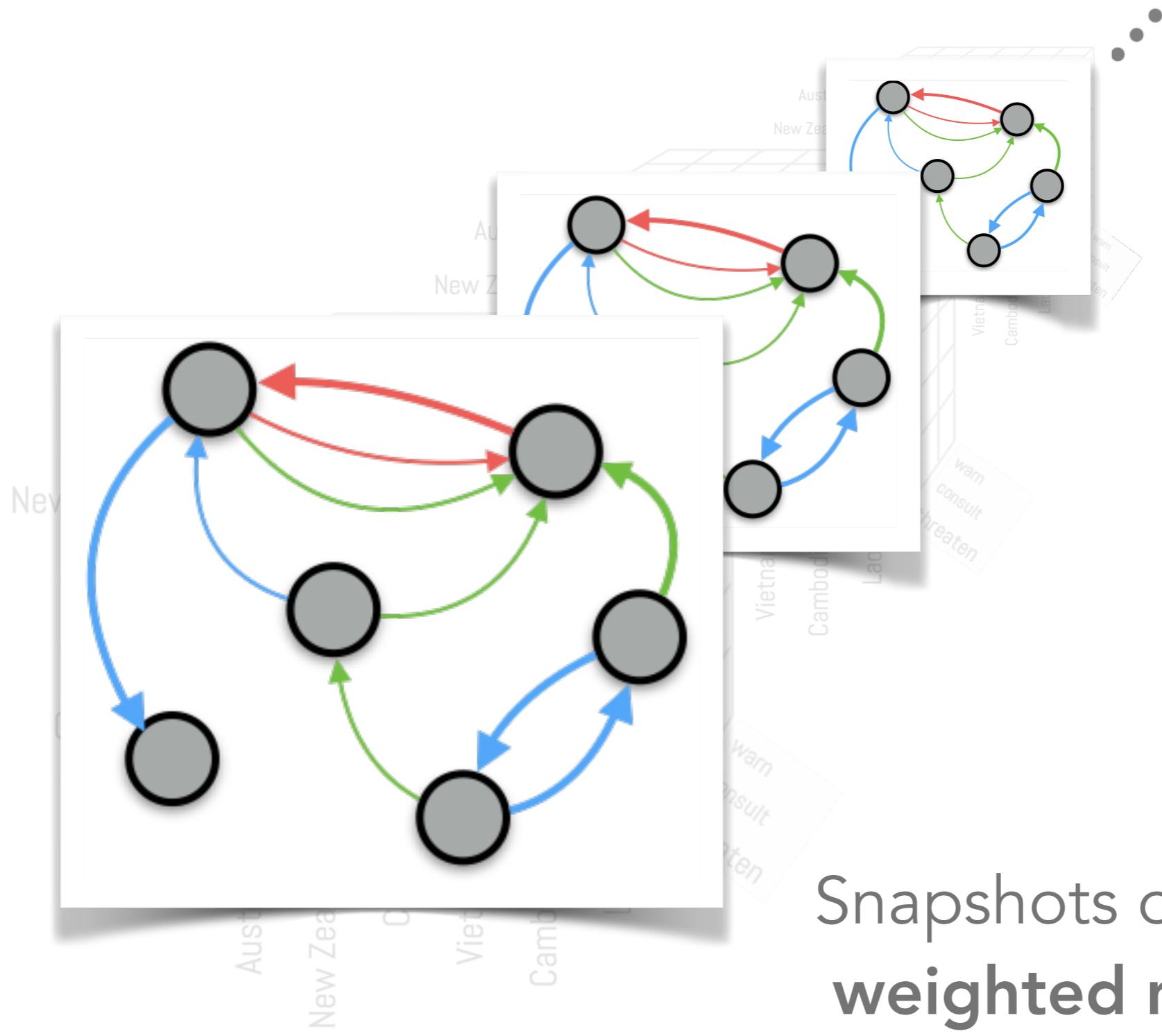
Event type counts



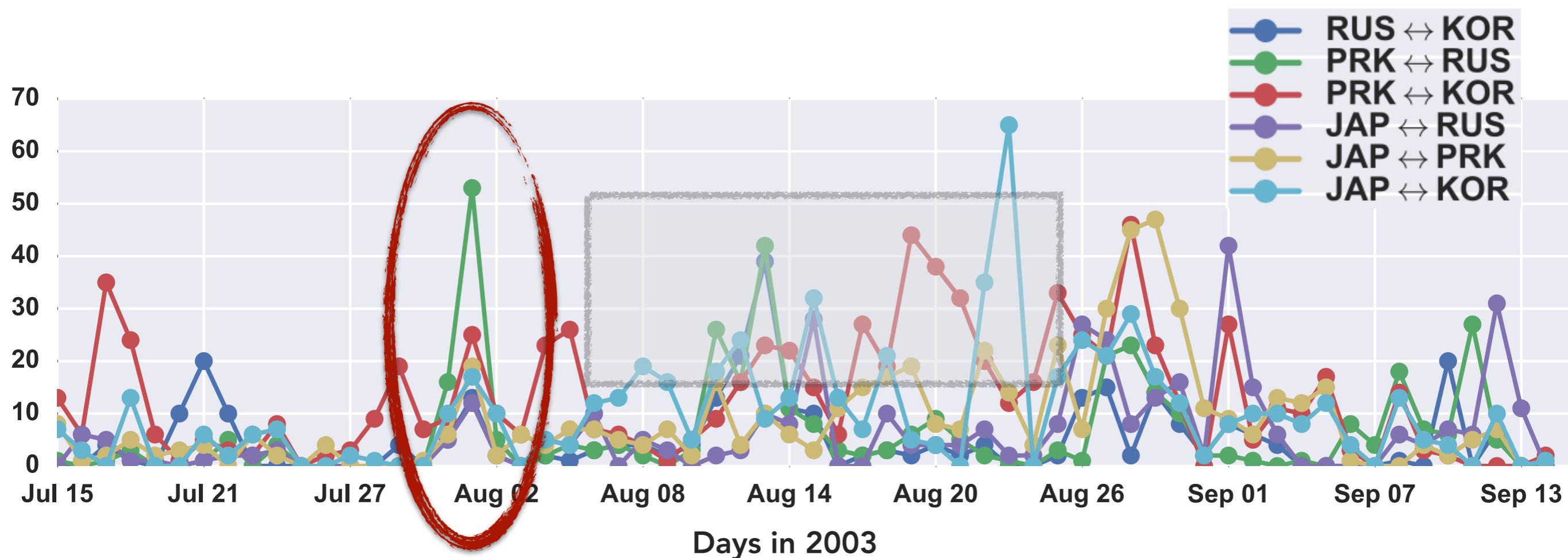
Event type counts



Event type counts



Event type counts

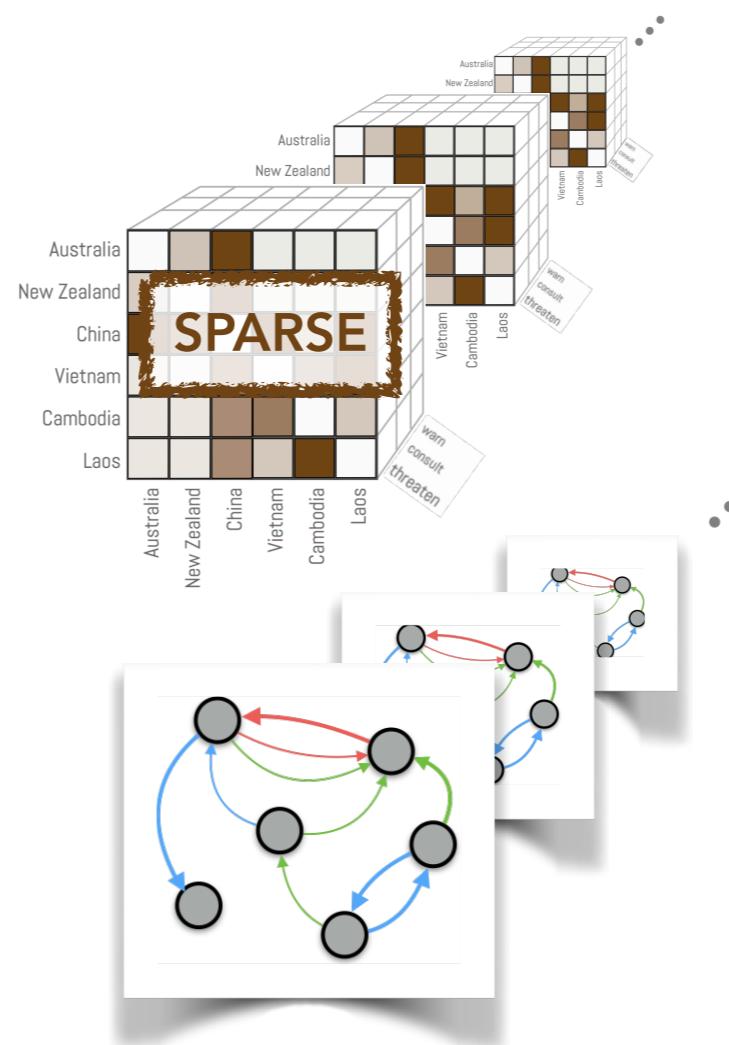


REPRESENTATIONS OF DYADIC DATA

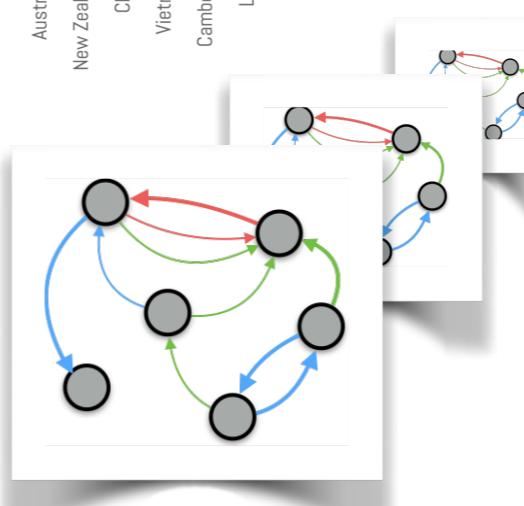
tokens

Date	Source	Target	Type of Action
900717	IRQ	KUW	CHARGE
900725	IRQ	EGY	ASSURE
900727	IRQ	KUW	WARN
900731	IRQ	KUW	MOBILIZATION
900801	KUW	IRQ	REFUSE
900802	IRQ	KUW	MILITARY FORCE

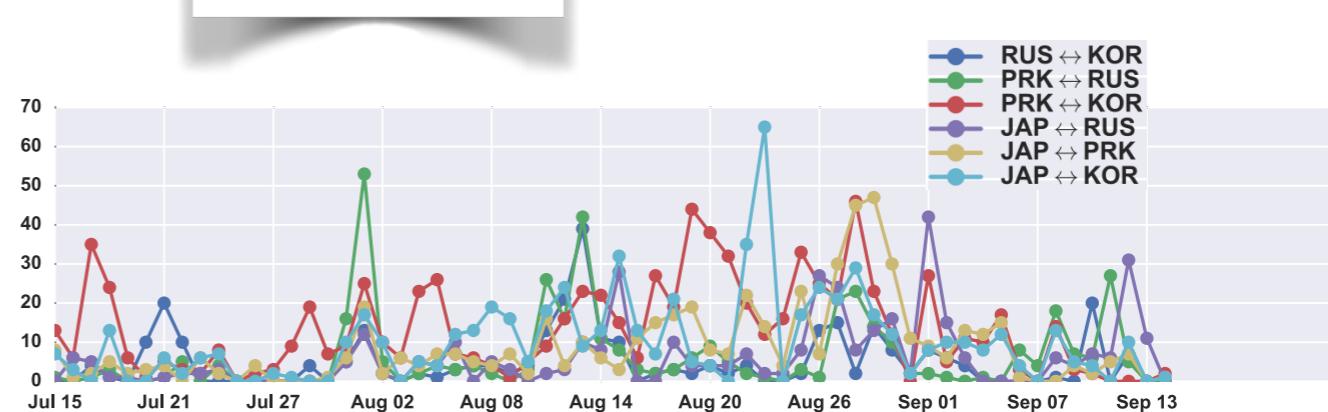
count tensor



networks



time series



OUTLINE

- ▶ Motivation: Dyadic event data (and its challenges)
- ▶ Non-negative (Poisson) tensor decompositions
 - ▶ CP extracts “multilateral” structure [Schein et al., 2015]
 - ▶ Tucker extracts “communities” [Schein et al., 2016]
 - ▶ Why (allocative) Poisson factorization
 - ▶ AL ℓ_0 CORE avoids the “exponential blowup” [Hood & Schein, 2024]

Appendix (*time permitting*)

- ▶ State-space modeling
 - ▶ Gamma state-space models [Schein et al., 2016b; Schein et al., 2019]
 - ▶ Modeling “escalation” with a new matrix prior [Stoehr et al., 2023]

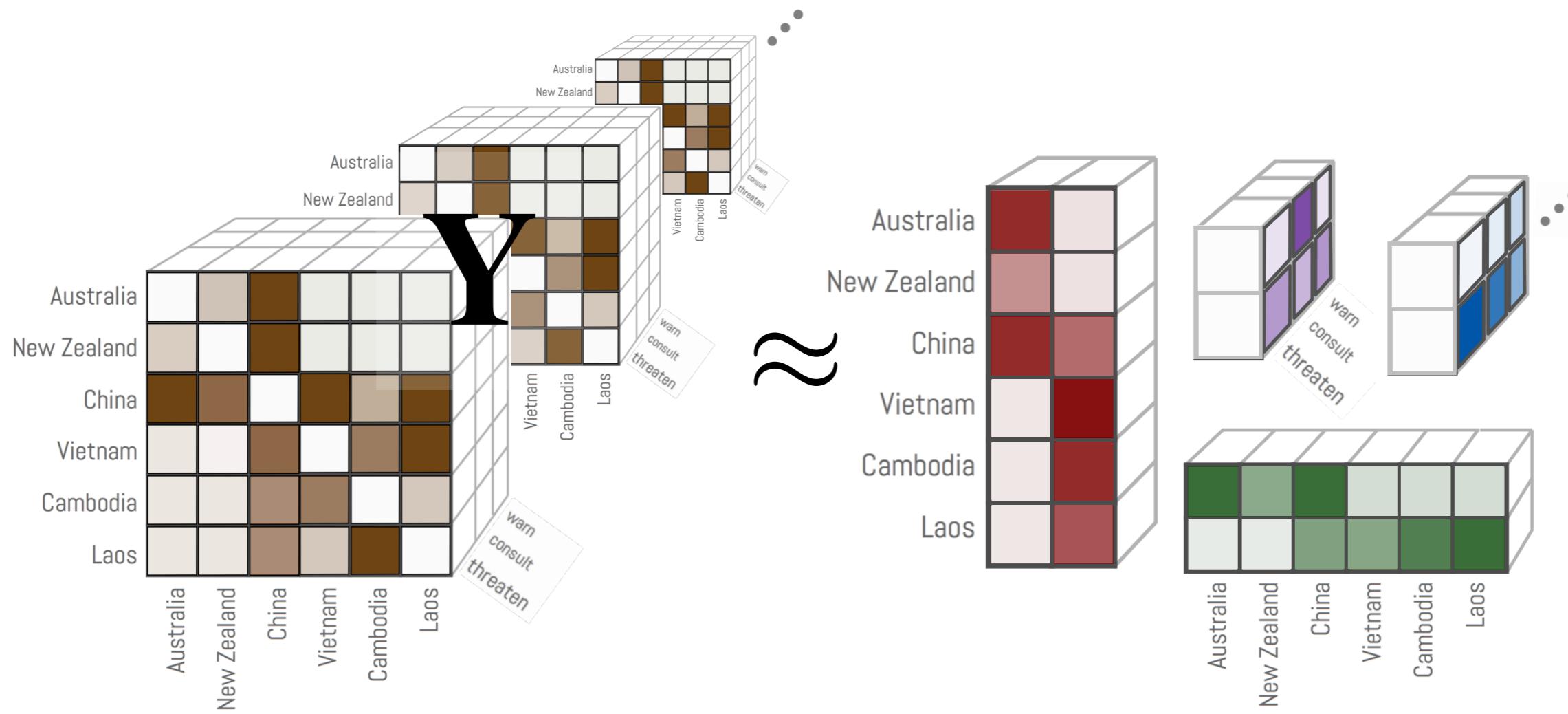
OUTLINE

- ▶ Motivation: Dyadic event data (and its challenges)
- ▶ Non-negative (Poisson) tensor decompositions
 - ▶ CP extracts “multilateral” structure [[Schein et al., 2015](#)]
 - ▶ Tucker extracts “communities” [[Schein et al., 2016](#)]
 - ▶ Why (allocative) Poisson factorization
 - ▶ AL ℓ_0 CORE avoids the “exponential blowup” [[Hood & Schein, 2024](#)]

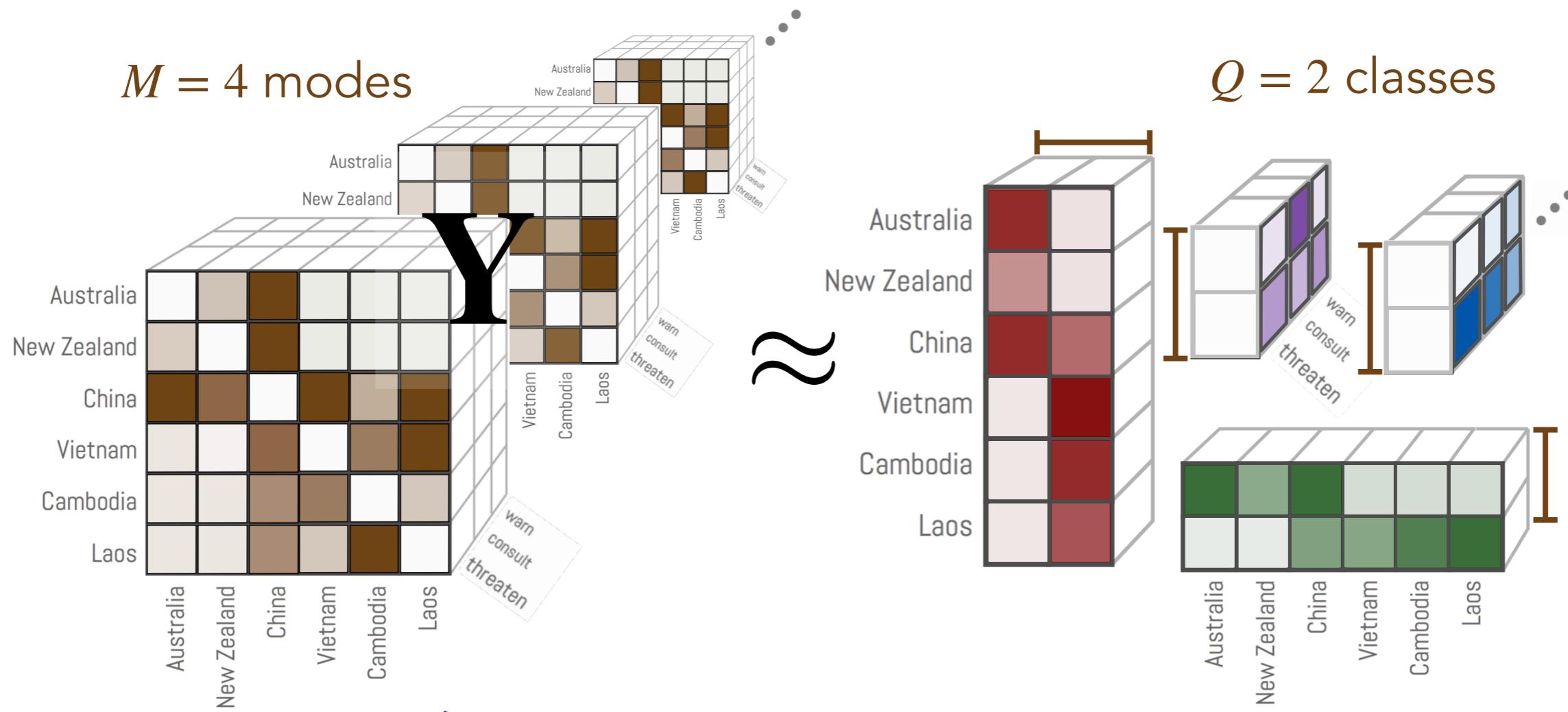
Appendix (*time permitting*)

- ▶ State-space modeling
 - ▶ Gamma state-space models [[Schein et al., 2016b; Schein et al., 2019](#)]
 - ▶ Modeling “escalation” with a new matrix prior [[Stoehr et al., 2023](#)]

CANONICAL POLYADIC (CP) DECOMPOSITION

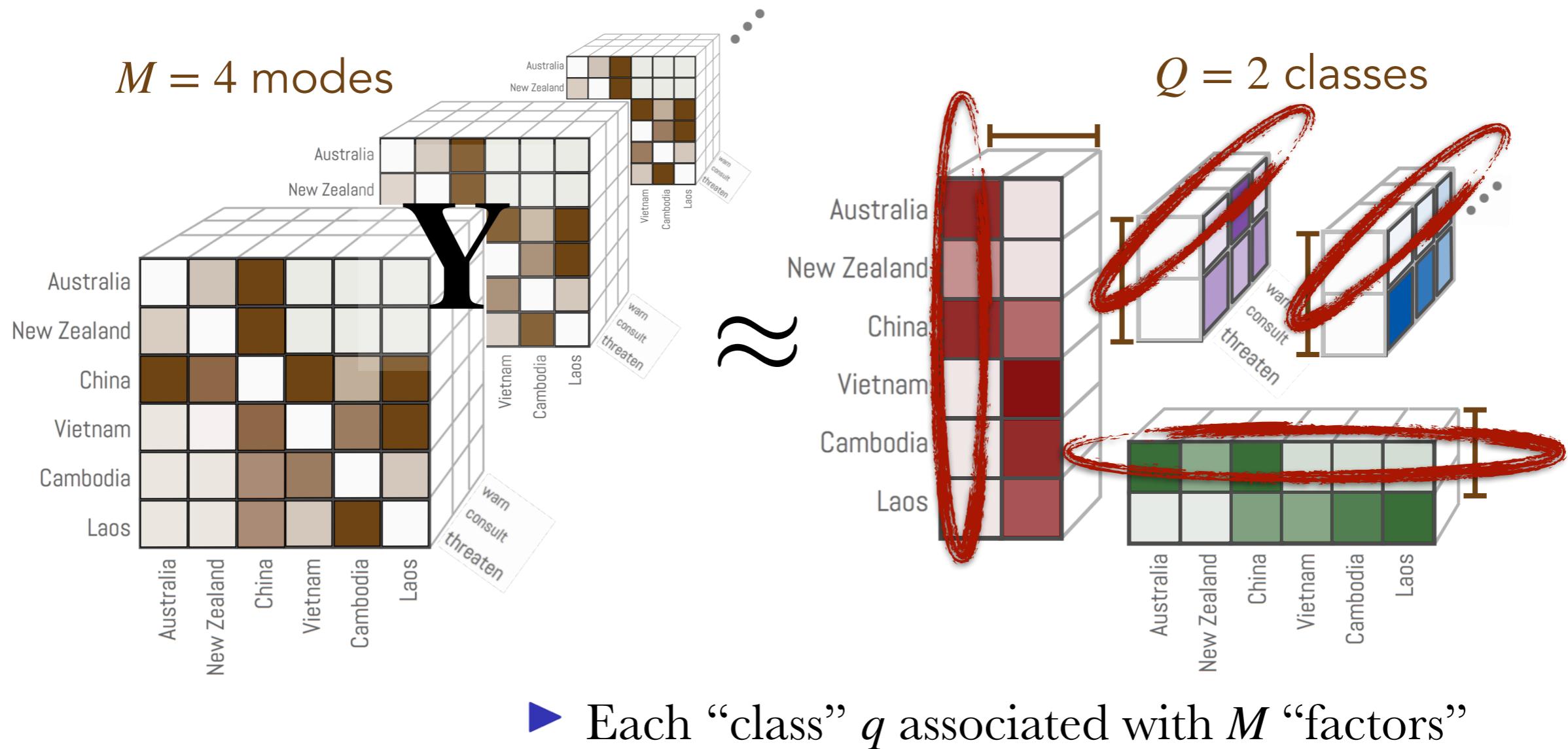


CANONICAL POLYADIC (CP) DECOMPOSITION



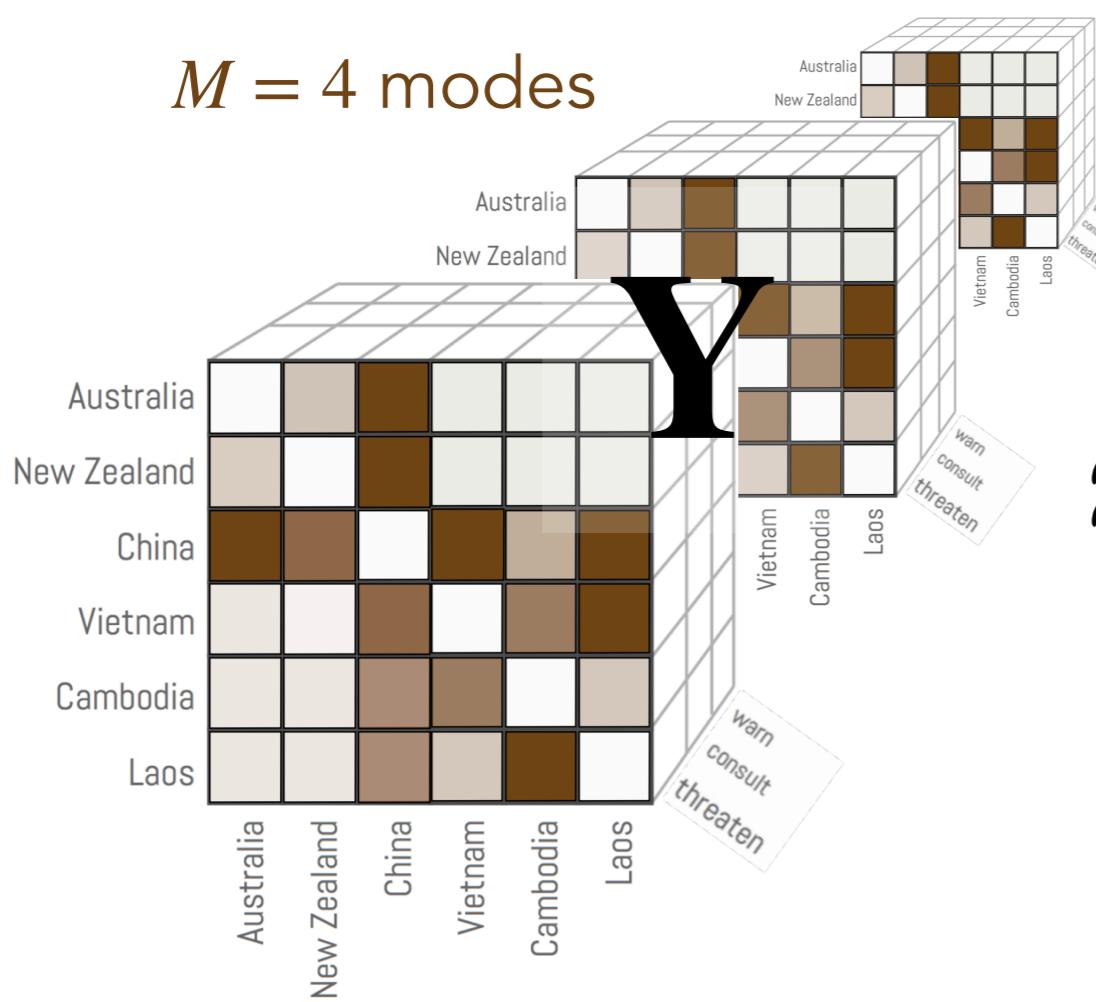
- ▶ M -mode tensor $\rightarrow M$ factor matrices
- ▶ Q latent “classes” (or “components”)

CANONICAL POLYADIC (CP) DECOMPOSITION

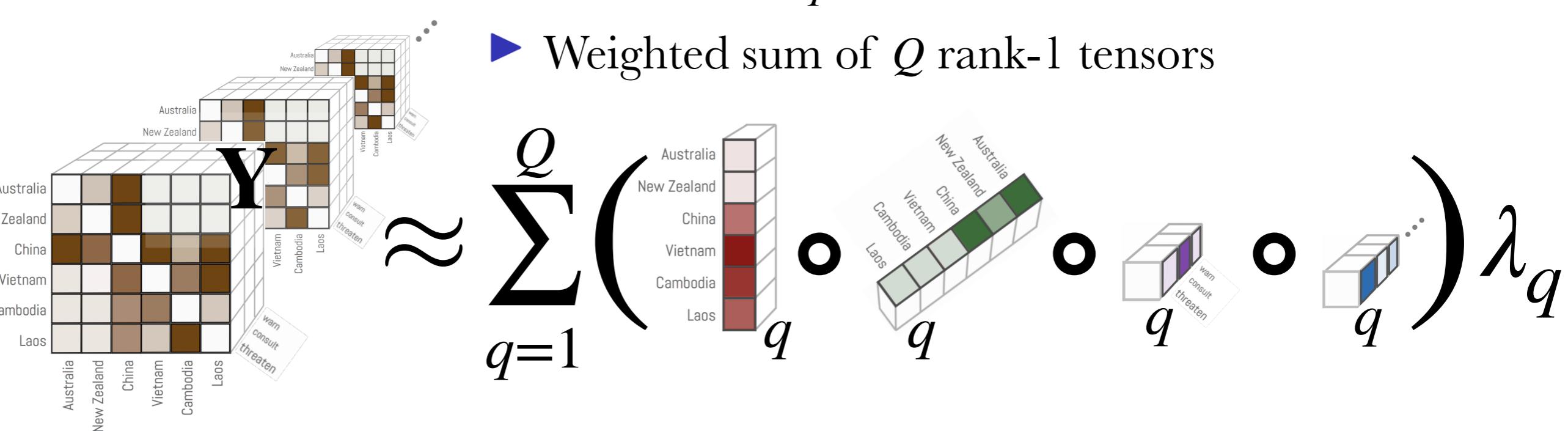


CANONICAL POLYADIC (CP) DECOMPOSITION

$M = 4$ modes

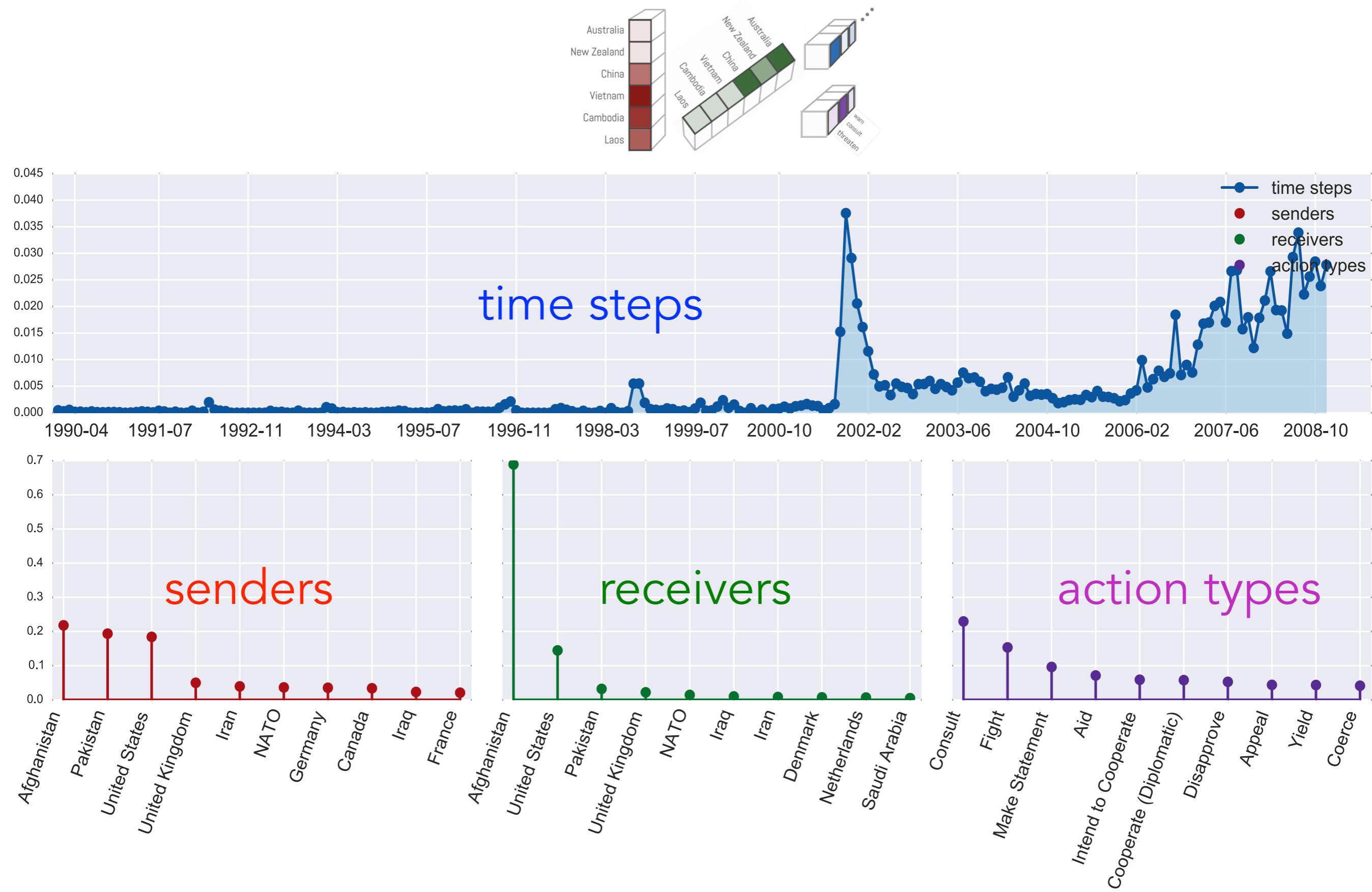


$Q = 2$ classes

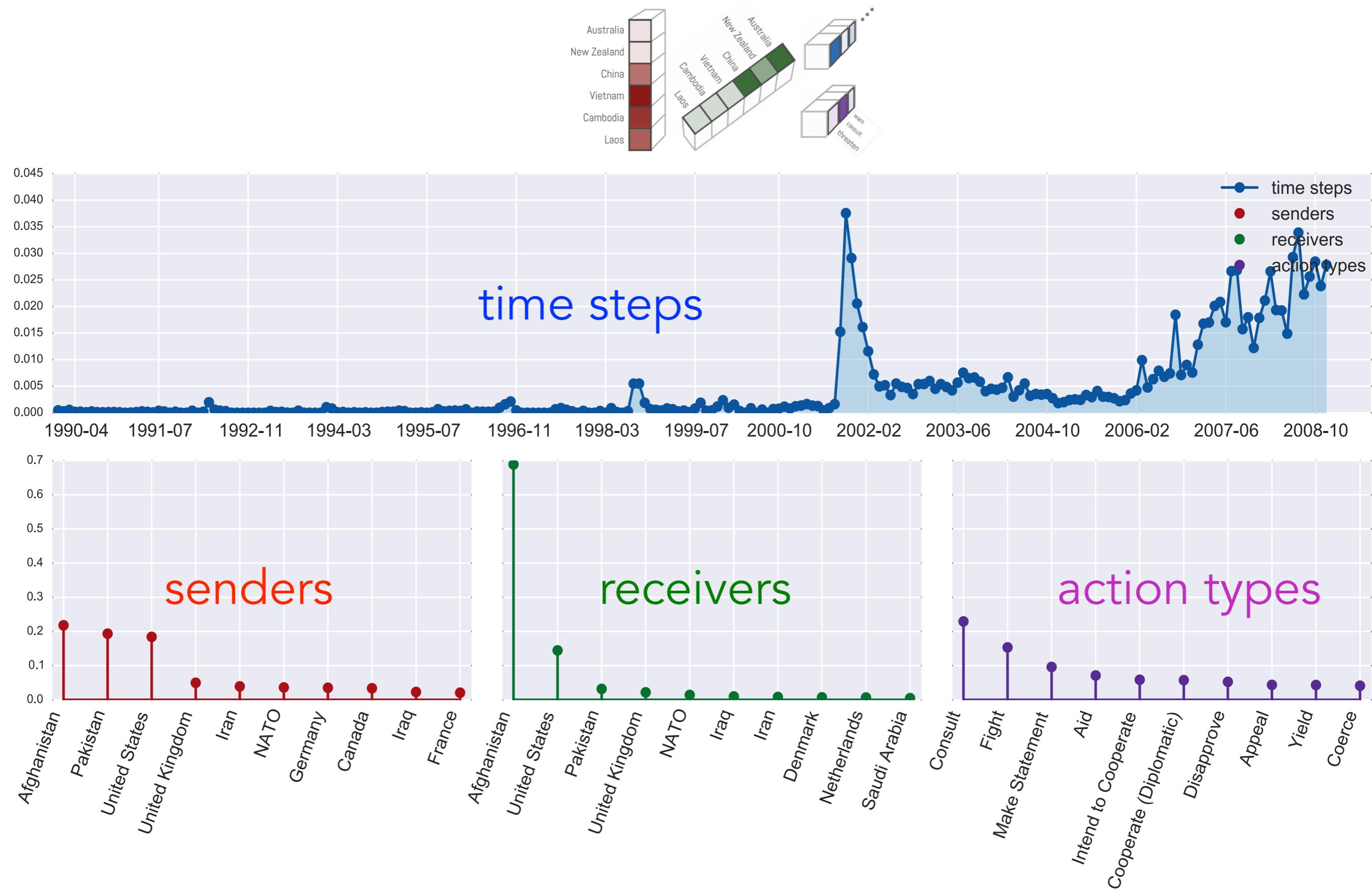


- ▶ Each “class” q associated with M “factors”
- ▶ Weighted sum of Q rank-1 tensors

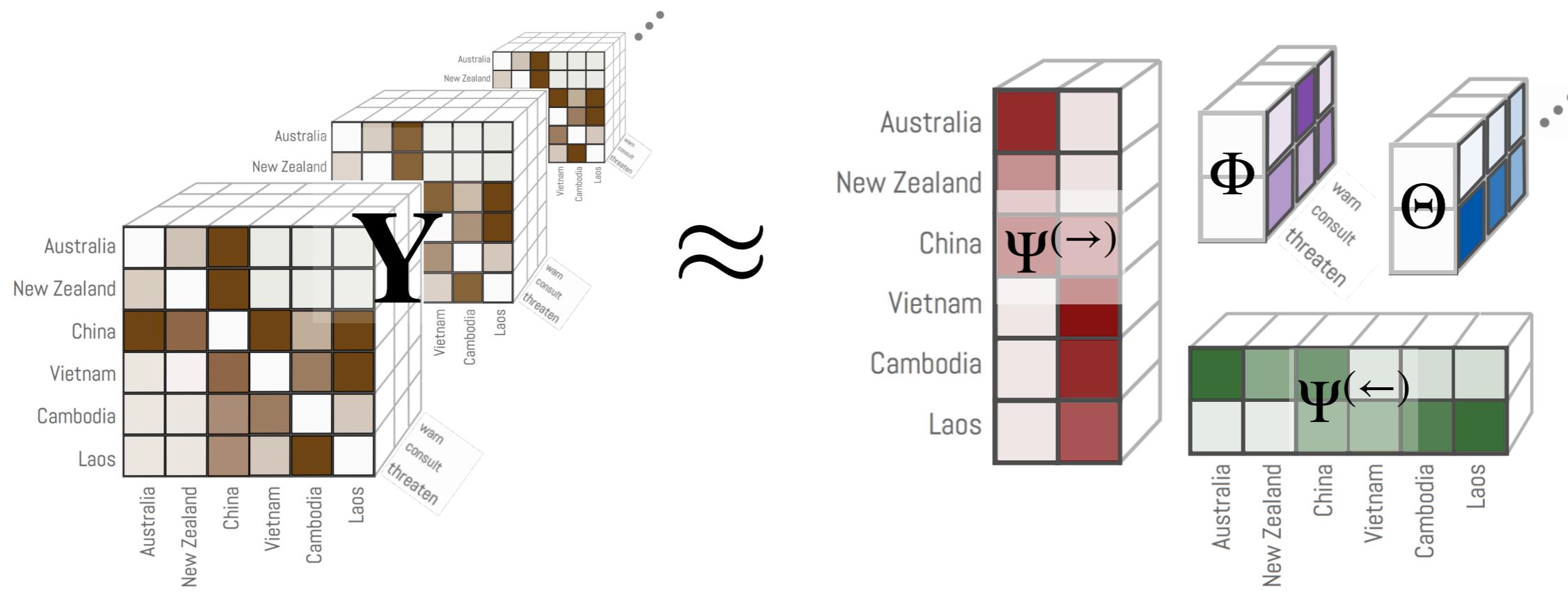
EXAMPLE CLASS



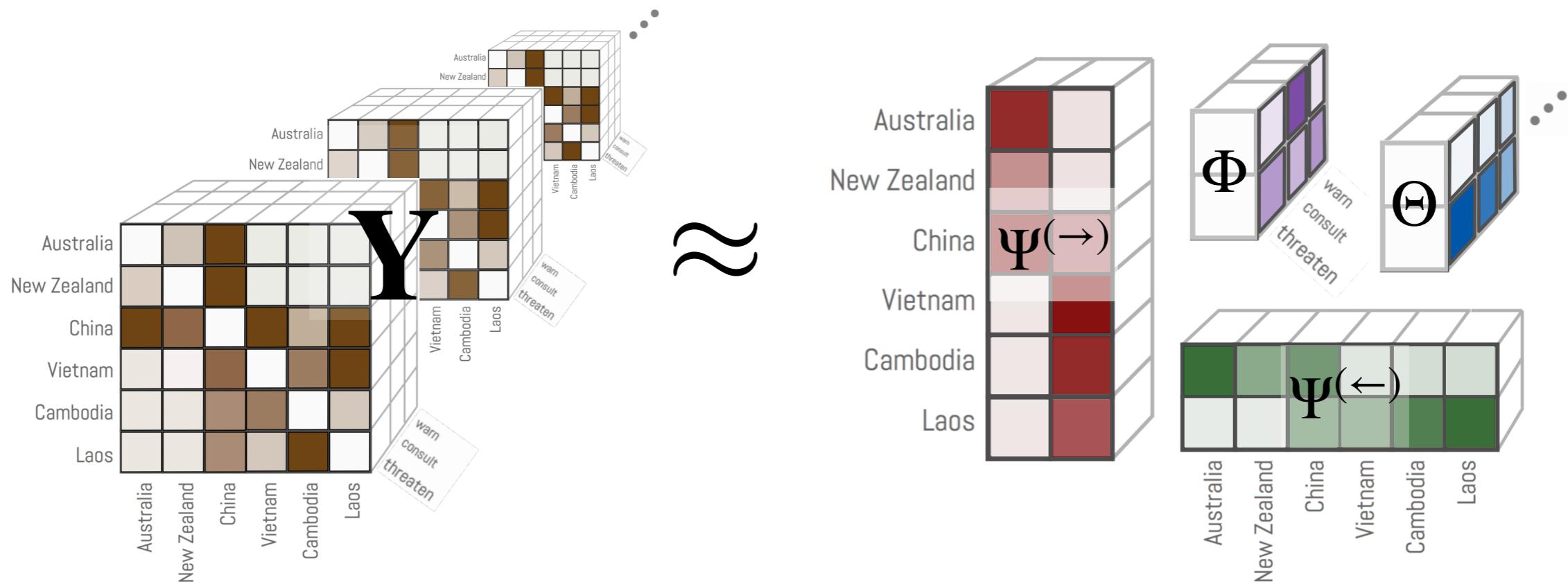
EXAMPLE CLASS: War in Afghanistan



CANONICAL POLYADIC (CP) DECOMPOSITION

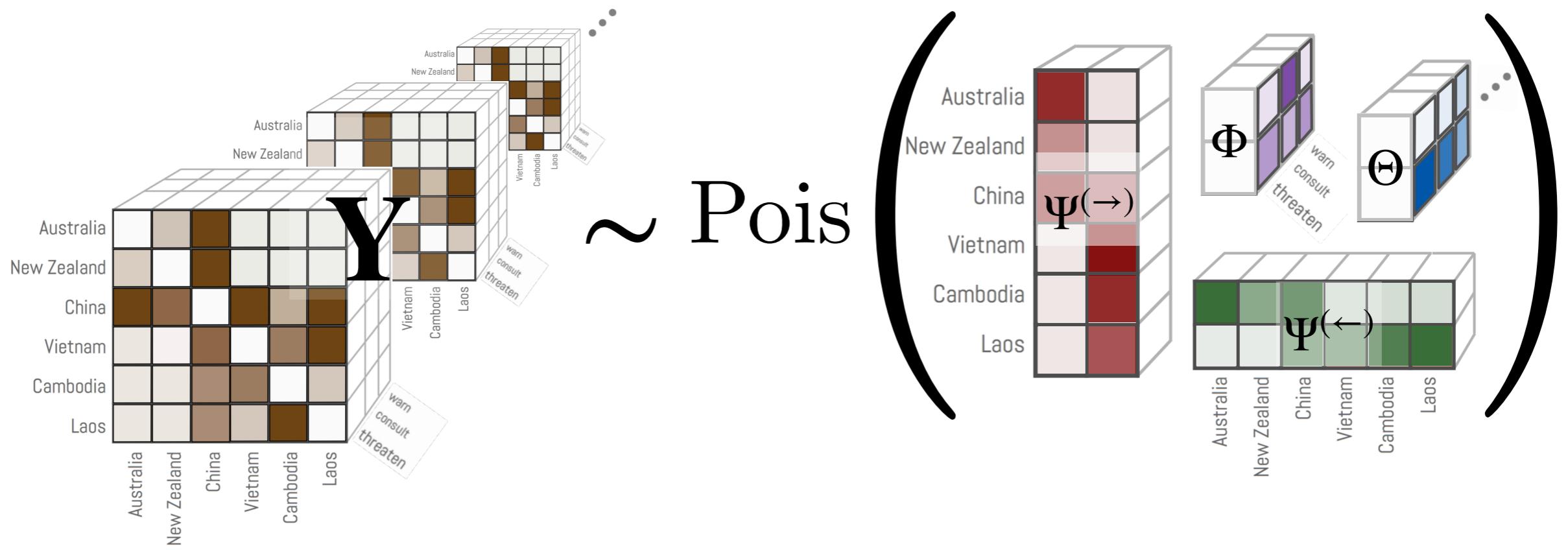


CANONICAL POLYADIC (CP) DECOMPOSITION



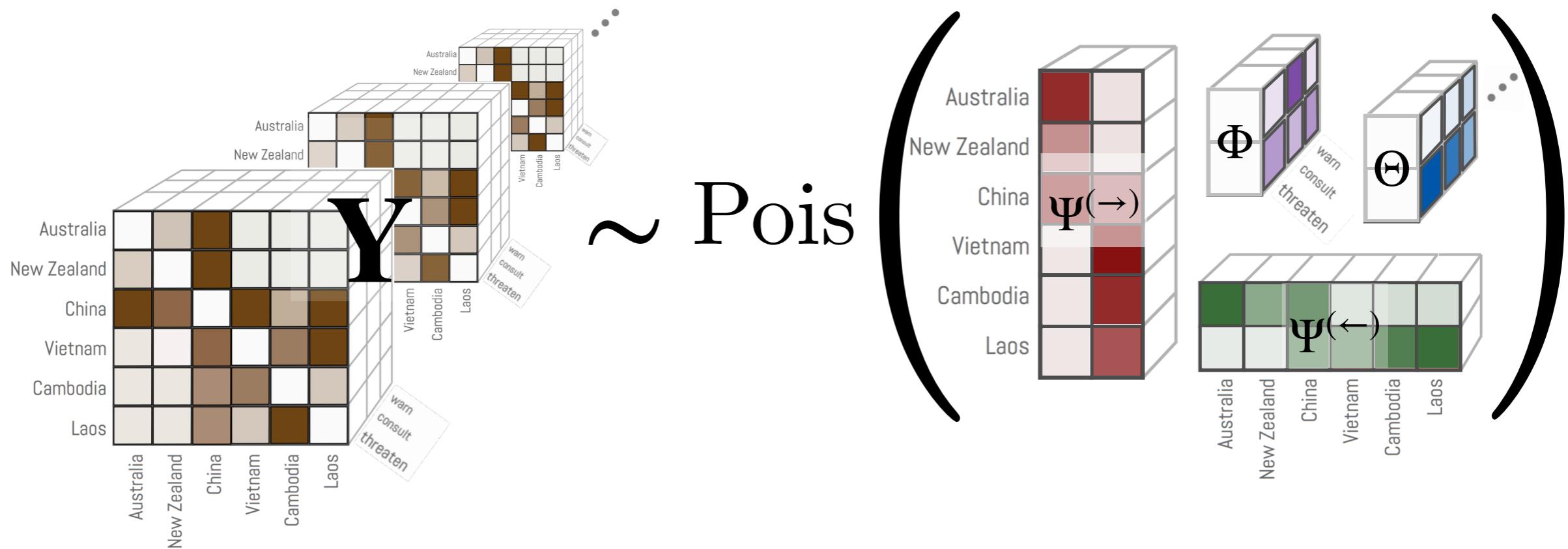
$$y_{i \rightarrow j}^{(t)} \underset{a}{\sim} \sum_{q=1}^Q \psi_{iq}^{(\rightarrow)} \psi_{jq}^{(\leftarrow)} \phi_{aq} \theta_q^{(t)} \lambda_q$$

POISSON CP DECOMPOSITION



$$y_{i \rightarrow j}^{(t)} \sim \text{Pois} \left(\sum_{q=1}^Q \psi_{iq}^{(\rightarrow)} \psi_{jq}^{(\leftarrow)} \phi_{aq} \theta_q^{(t)} \lambda_q \right)$$

POISSON CP DECOMPOSITION

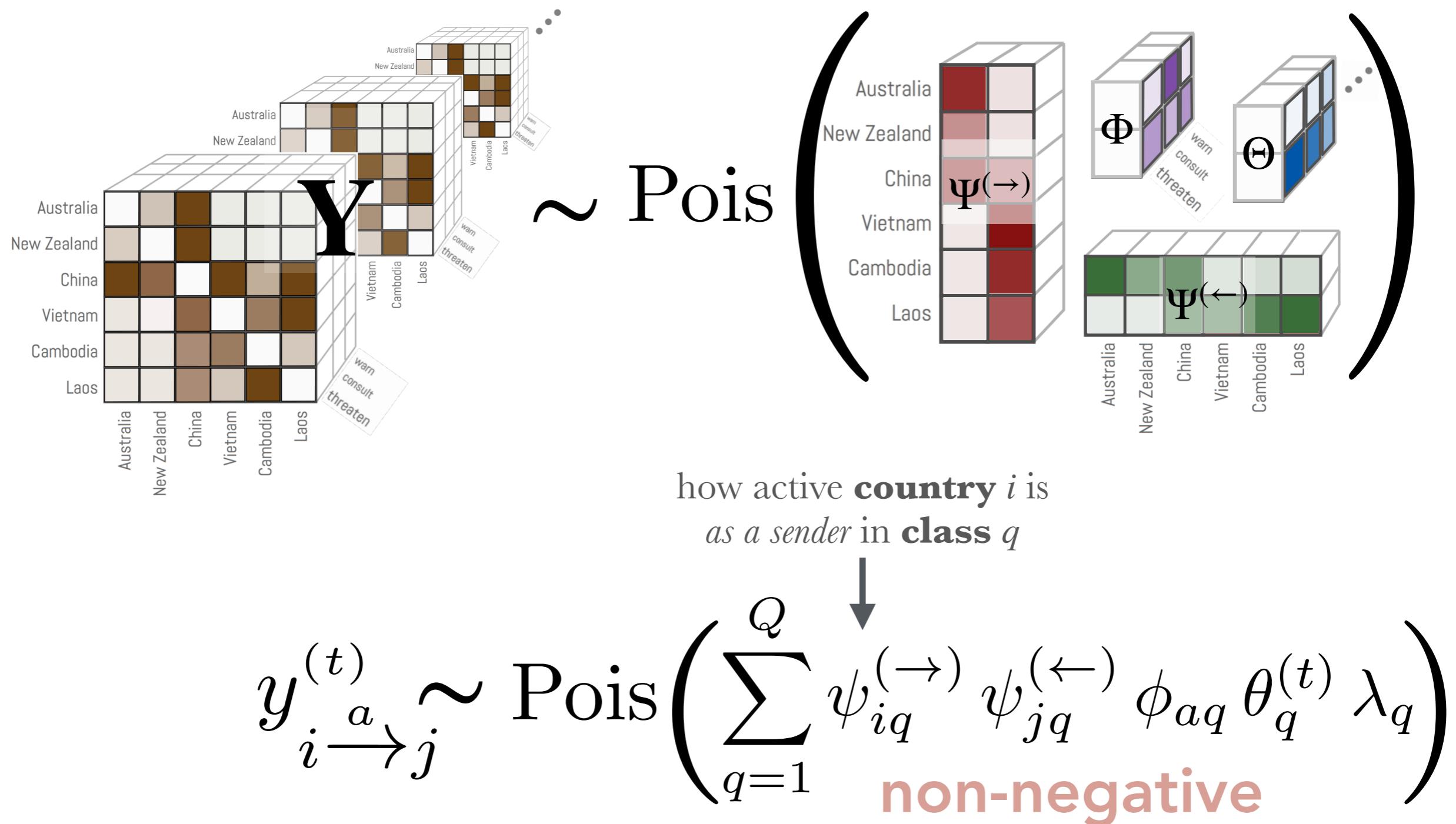


$$y_{i \rightarrow j}^{(t)} \sim \text{Pois} \left(\sum_{q=1}^Q \psi_{iq}^{(\rightarrow)} \psi_{jq}^{(\leftarrow)} \phi_{aq} \theta_q^{(t)} \lambda_q \right)$$

non-negative

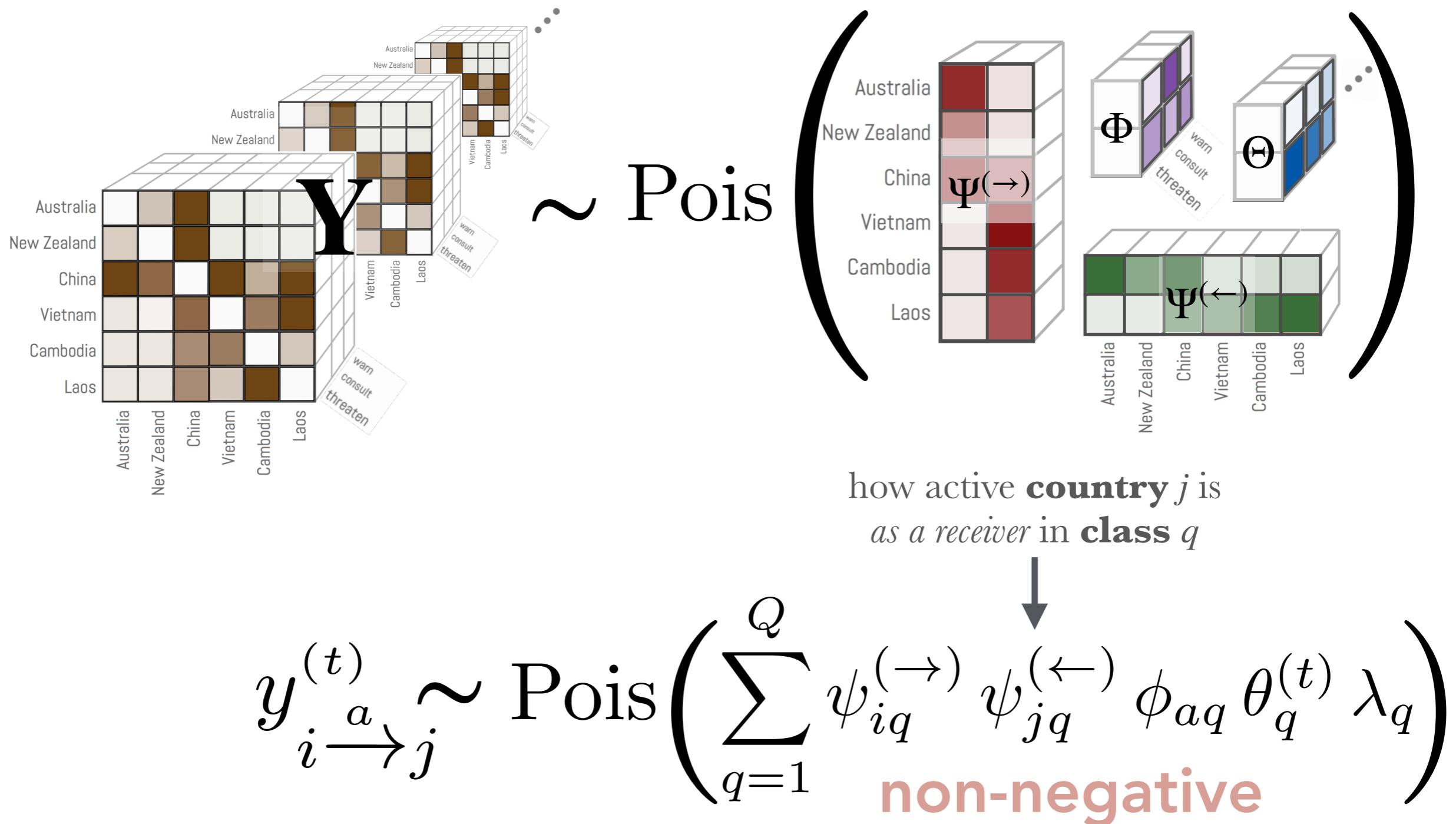
“parts-based” representation [Lee and Seung, 1999]

POISSON CP DECOMPOSITION



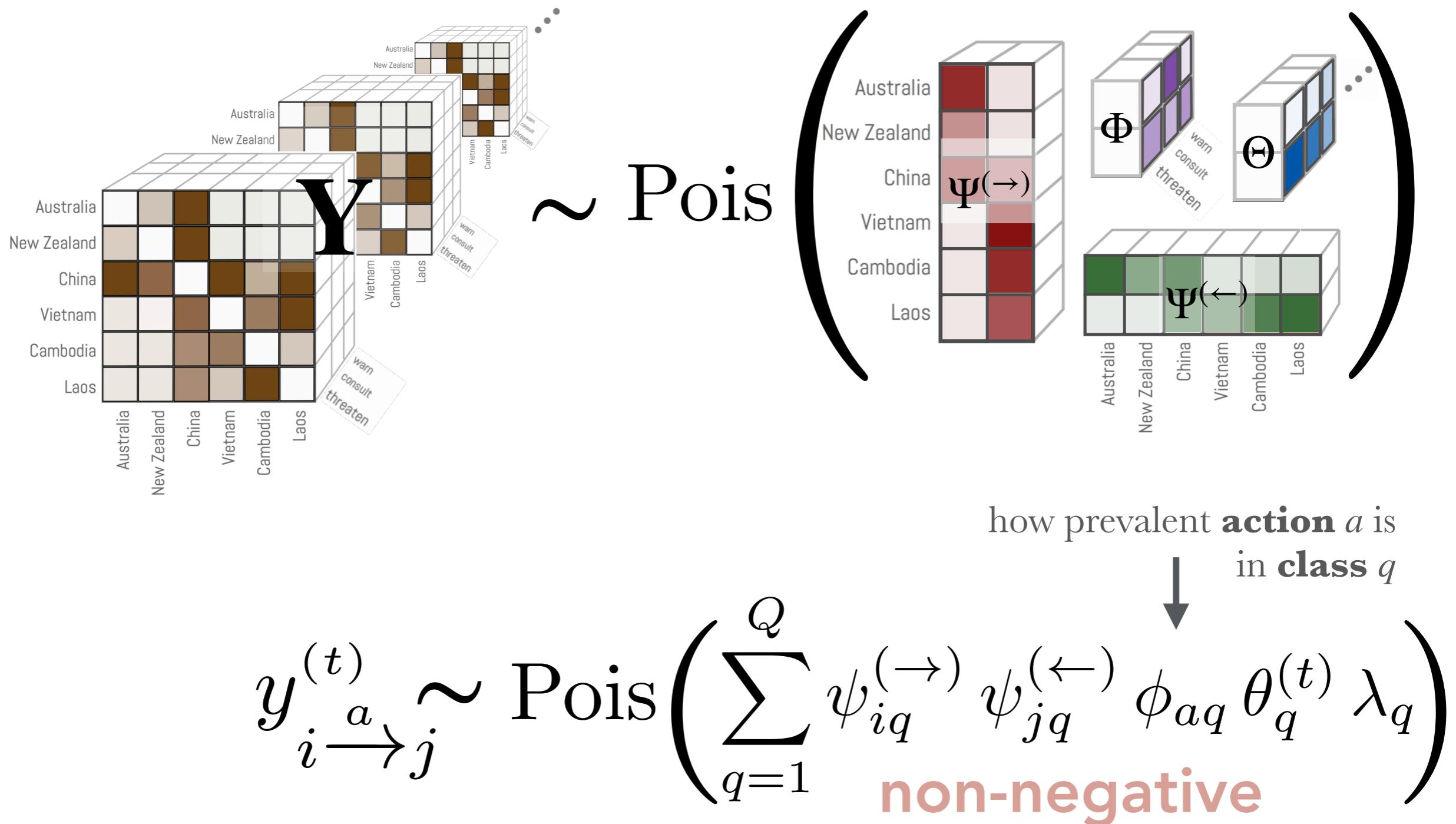
“parts-based” representation [Lee and Seung, 1999]

POISSON CP DECOMPOSITION



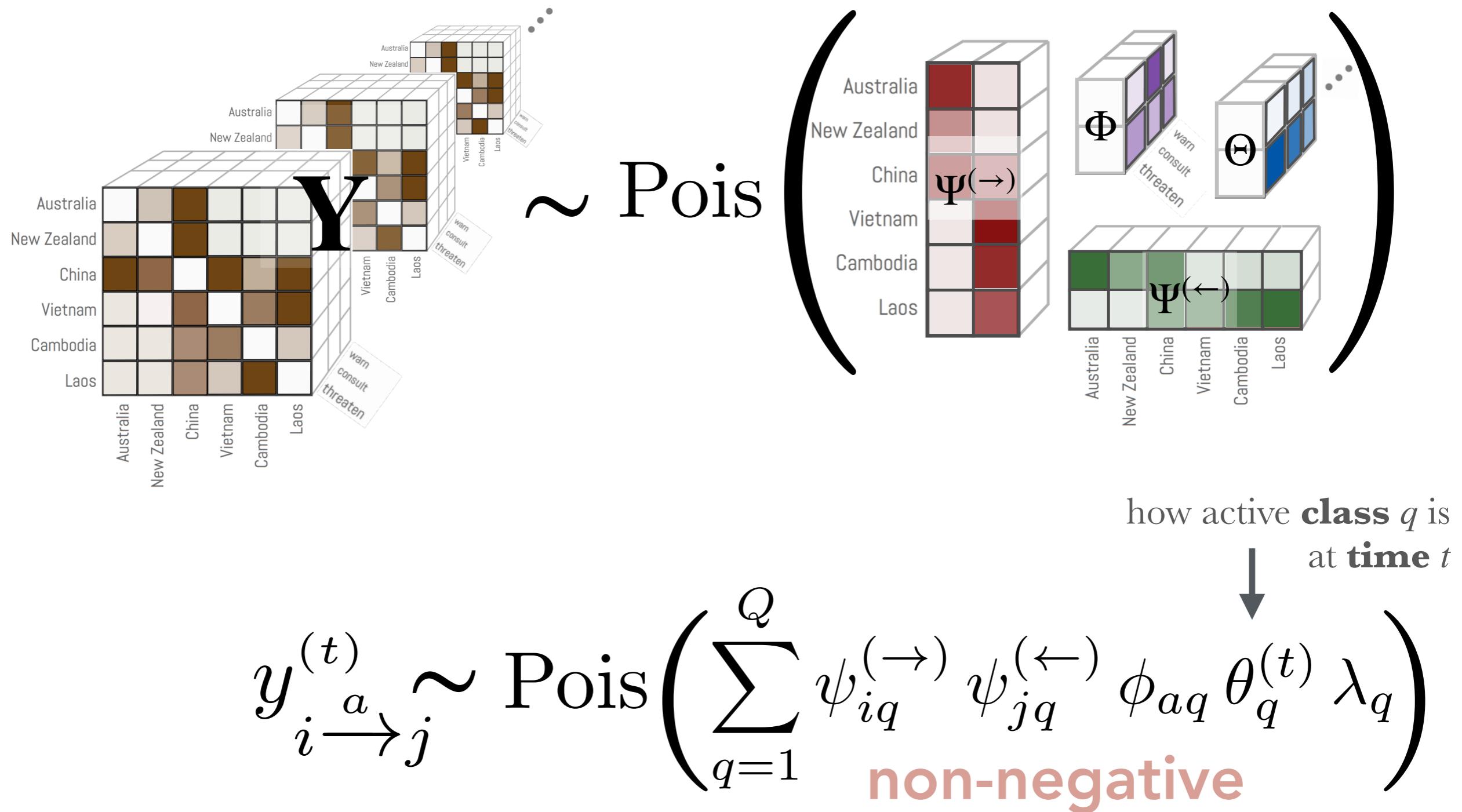
“parts-based” representation [Lee and Seung, 1999]

POISSON CP DECOMPOSITION



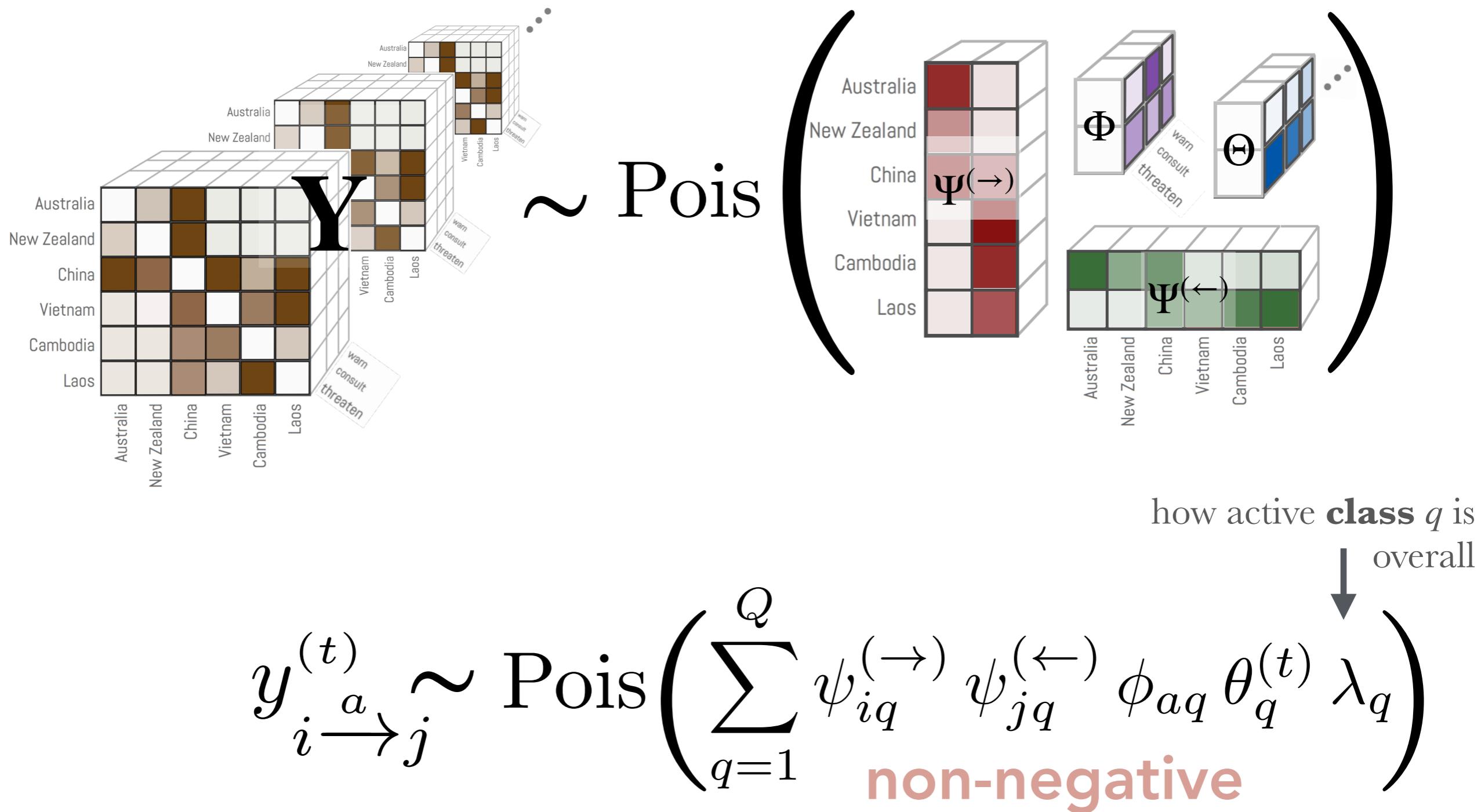
“parts-based” representation [Lee and Seung, 1999]

POISSON CP DECOMPOSITION



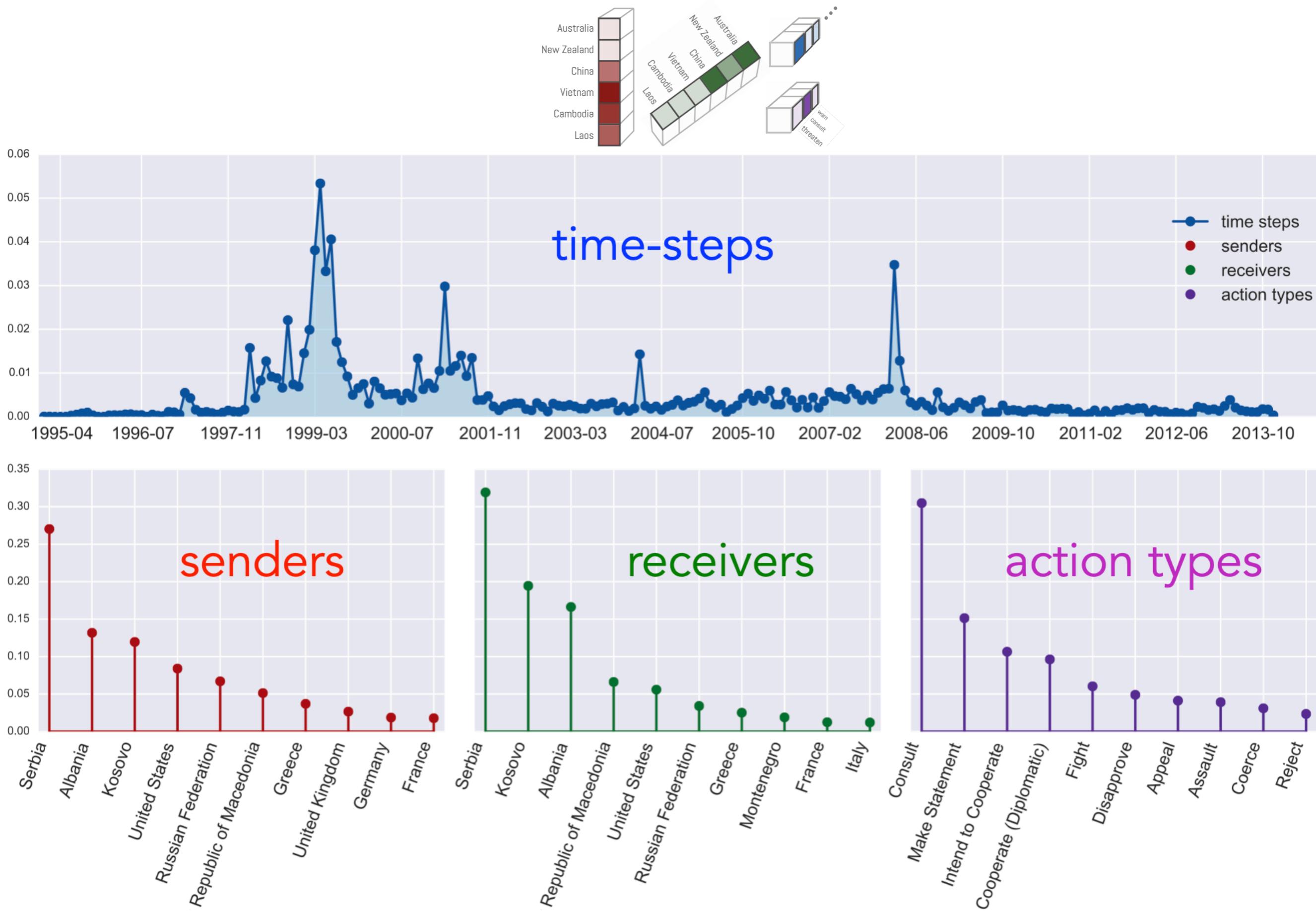
“parts-based” representation [Lee and Seung, 1999]

POISSON CP DECOMPOSITION

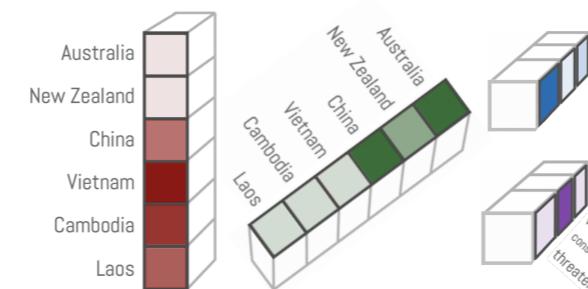


“parts-based” representation [Lee and Seung, 1999]

EXAMPLE CLASS:



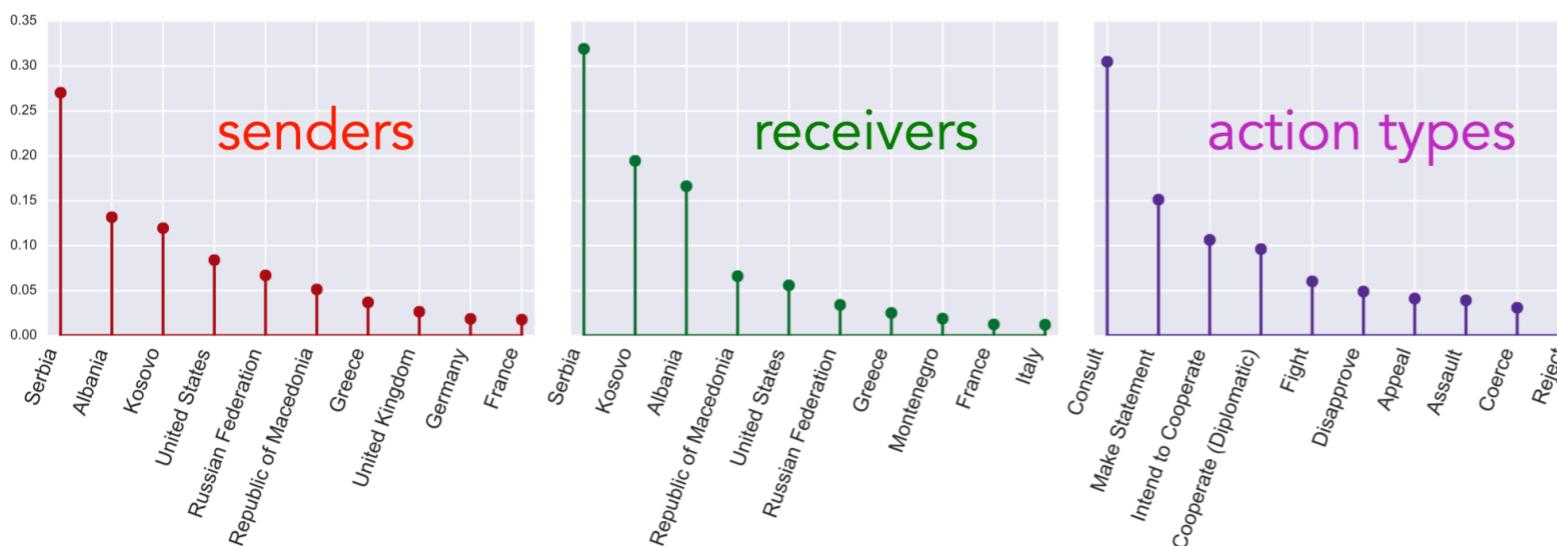
EXAMPLE CLASS: Yugoslav Wars



Yugoslav Wars

From Wikipedia, the free encyclopedia

The **Yugoslav Wars** were ethnic conflicts fought from 1991 to 2001 inside the territory of the former Yugoslavia. These wars accompanied and/or facilitated the breakup of the country, when its constituent republics declared independence, but the issues of ethnic minorities in the new countries (chiefly Serbs in central parts and Albanians in the southeast) were still unresolved at the time the republics were recognized internationally. The wars are generally considered to be a series of separate but related military conflicts which, occurred in, and affected most of the former Yugoslav republics:^{[2][3][4]}



Classes almost always describe easily recognizable **multilateral** relations / events

- War in Slovenia (1991)
- Croatian War of Independence (1991–1995)
- Bosnian War (1992–1995)
- Kosovo War (1998–1999), including the NATO bombing of Yugoslavia
- Insurgency in the Preševo Valley (1999–2001)
- Insurgency in the Republic of Macedonia (2001)

OUTLINE

- ▶ Motivation: Dyadic event data (and its challenges)
- ▶ Non-negative (Poisson) tensor decompositions
 - ▶ CP extracts “multilateral” structure [[Schein et al., 2015](#)]
 - ▶ Tucker extracts “communities” [[Schein et al., 2016](#)]
 - ▶ Why (allocative) Poisson factorization
 - ▶ AL ℓ_0 CORE avoids the “exponential blowup” [[Hood & Schein, 2024](#)]

Appendix (*time permitting*)

- ▶ State-space modeling
 - ▶ Gamma state-space models [[Schein et al., 2016b; Schein et al., 2019](#)]
 - ▶ Modeling “escalation” with a new matrix prior [[Stoehr et al., 2023](#)]

OUTLINE

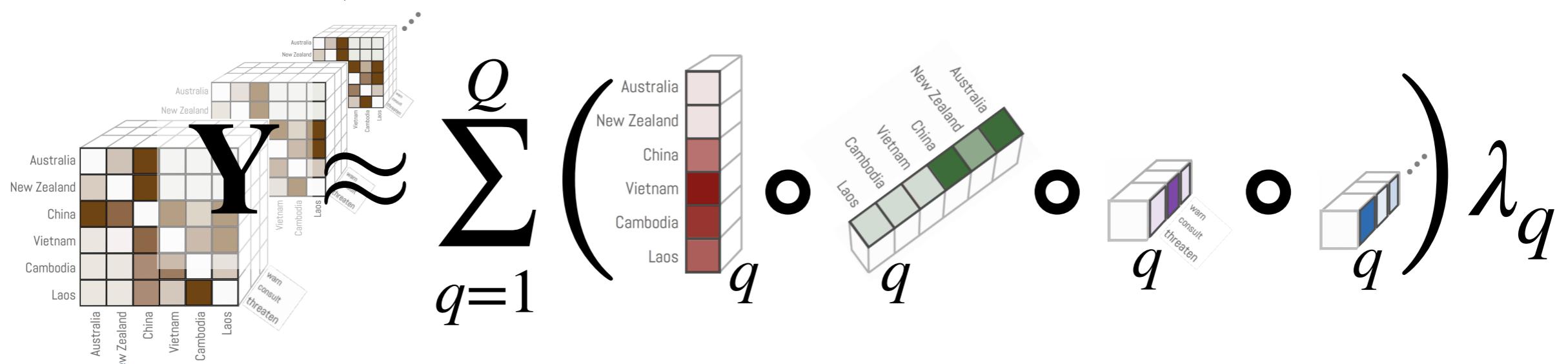
- ▶ Motivation: Dyadic event data (and its challenges)
- ▶ Non-negative (Poisson) tensor decompositions
 - ▶ CP extracts “multilateral” structure [Schein et al., 2015]
 - ▶ Tucker extracts “communities” [Schein et al., 2016]
 - ▶ Why (allocative) Poisson factorization
 - ▶ AL ℓ_0 CORE avoids the “exponential blowup” [Hood & Schein, 2024]

Appendix (*time permitting*)

- ▶ State-space modeling
 - ▶ Gamma state-space models [Schein et al., 2016b; Schein et al., 2019]
 - ▶ Modeling “escalation” with a new matrix prior [Stoehr et al., 2023]

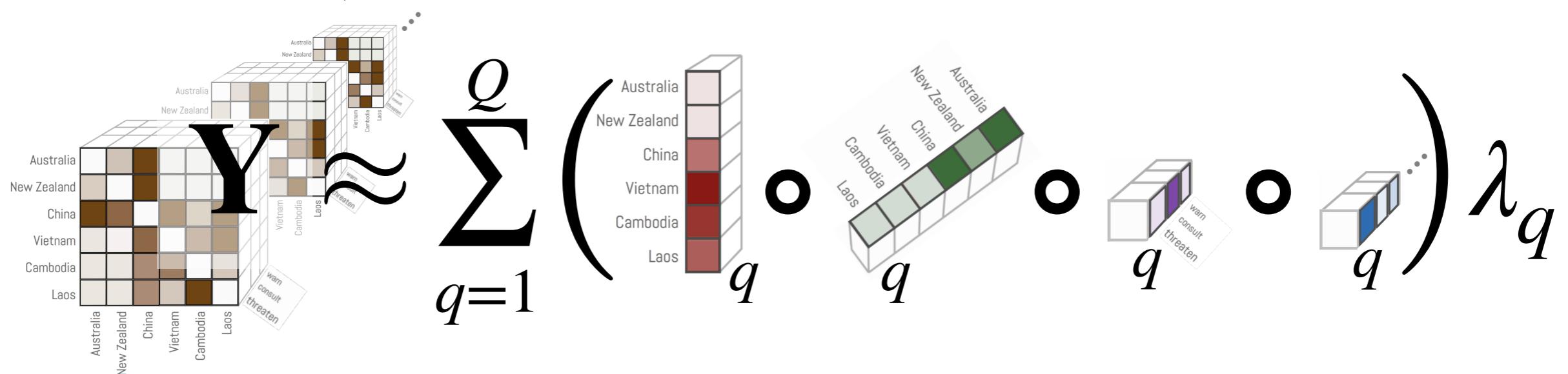
TUCKER DECOMPOSITION

- ▶ CP is unappealing if mode dimensions are very different
- ▶ e.g., (country x country x action x month) for 1995-2013 ICEWS data
 $= (250 \times 250 \times 20 \times 216)$
- ▶ $Q = 100$ classes; each must learn a different 20-dimensional action factor

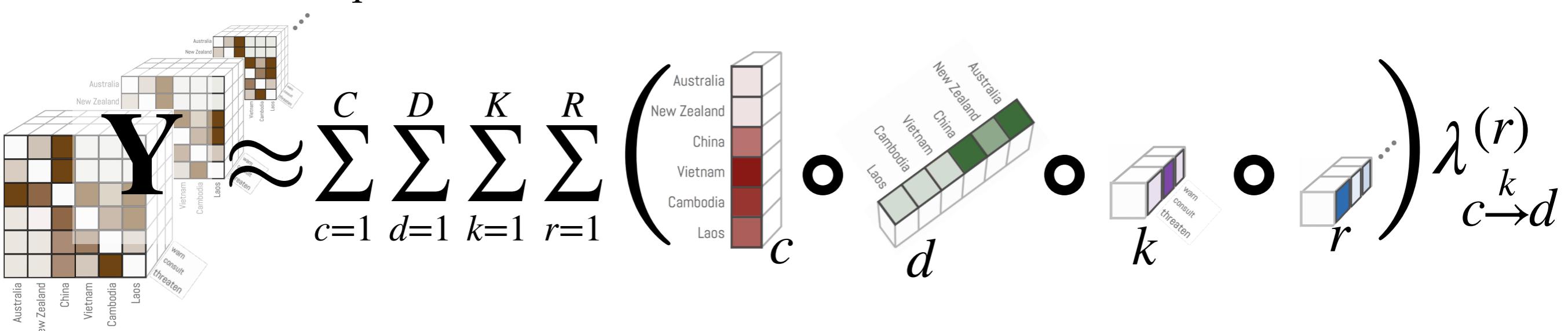


TUCKER DECOMPOSITION

- ▶ CP is unappealing if mode dimensions are very different
- ▶ e.g., (country x country x action x month) for 1995-2013 ICEWS data
 $= (250 \times 250 \times 20 \times 216)$
- ▶ $Q = 100$ classes; each must learn a different 20-dimensional action factor



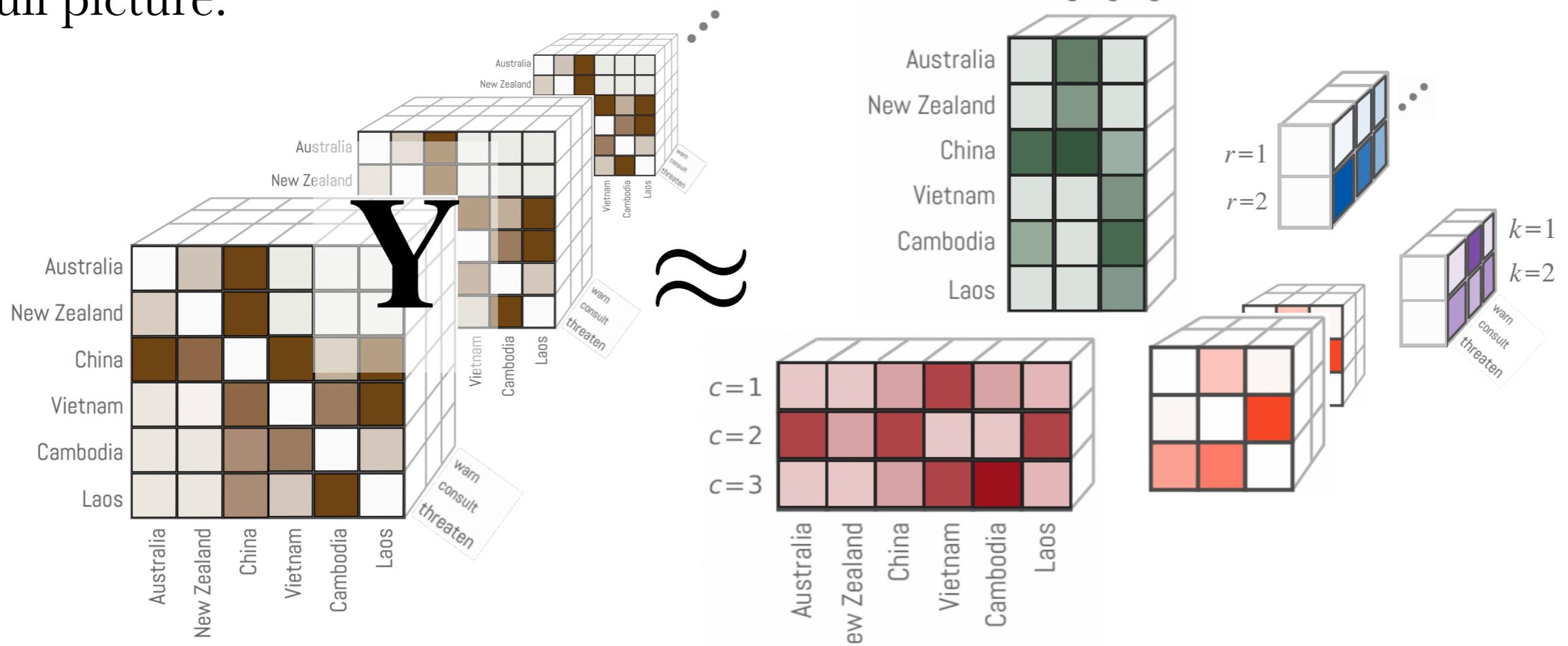
- ▶ Tucker decomposition fixes this...



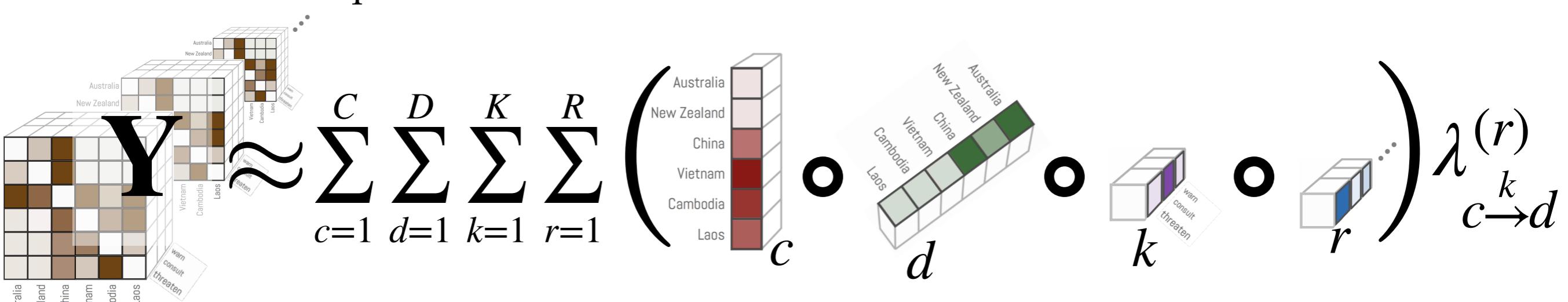
- ▶ Every class is now a unique combination (c, d, k, r) of **shared factors**

TUCKER DECOMPOSITION

► Full picture:



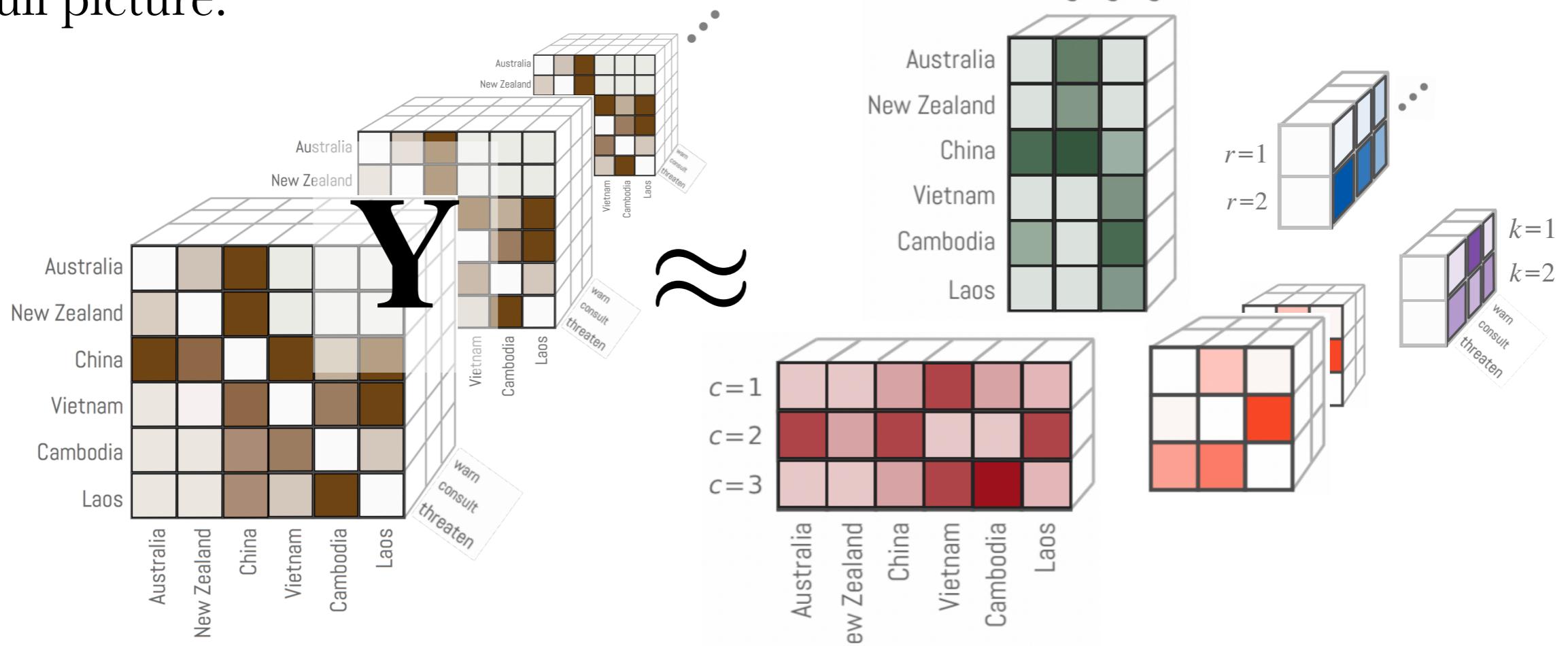
► Tucker decomposition fixes this...



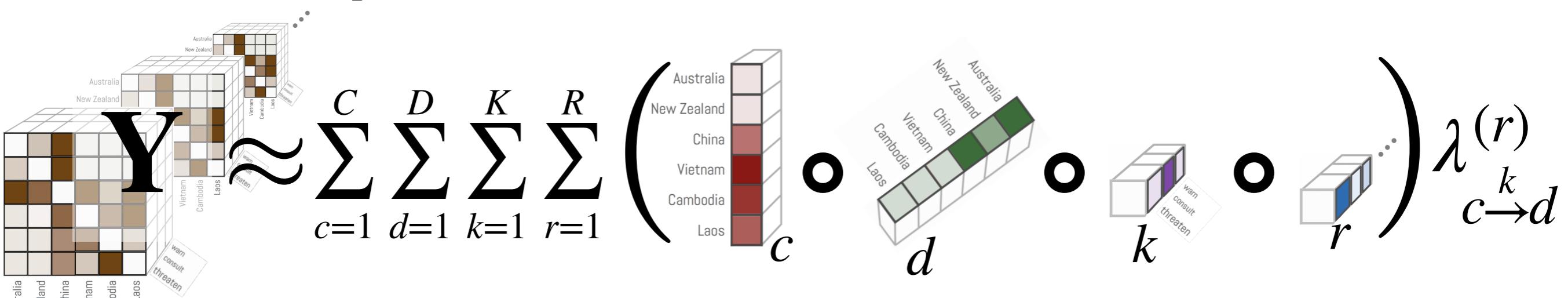
► Every class is now a unique combination (c, d, k, r) of **shared factors**

TUCKER DECOMPOSITION

► Full picture:



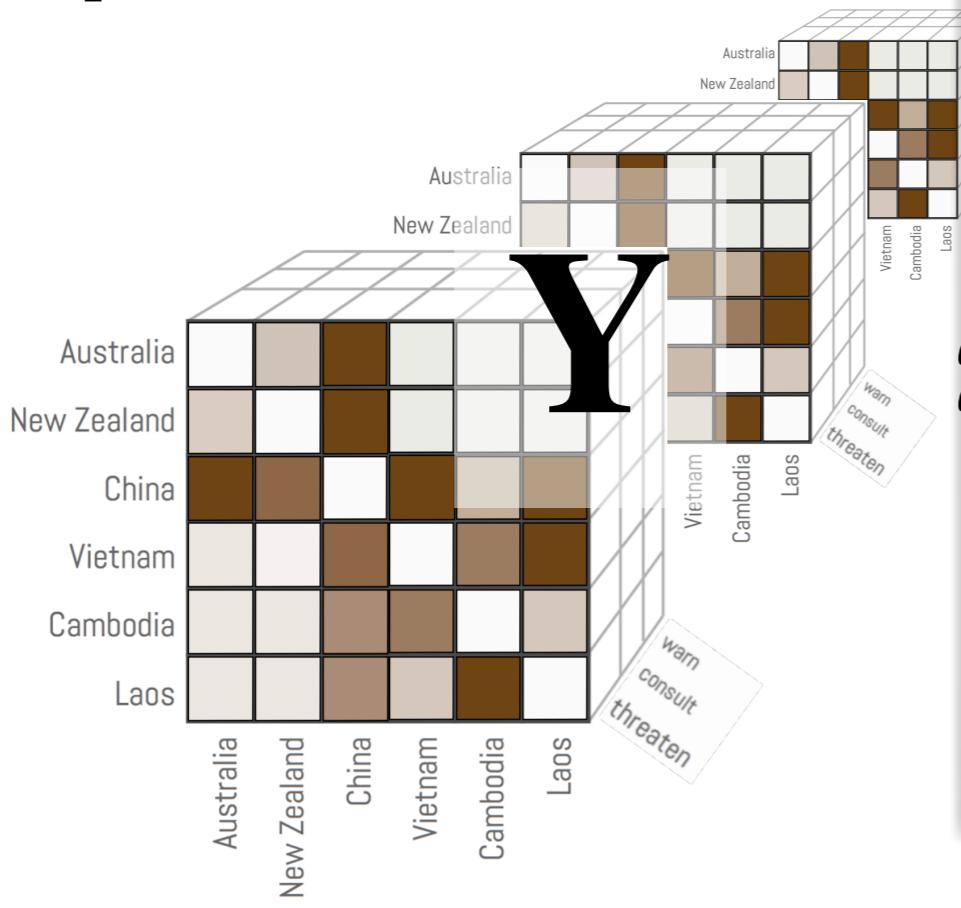
► Tucker decomposition fixes this... different number of factors in each mode



► Every class is now a unique combination (c, d, k, r) of **shared factors**

TUCKER DECOMPOSITION

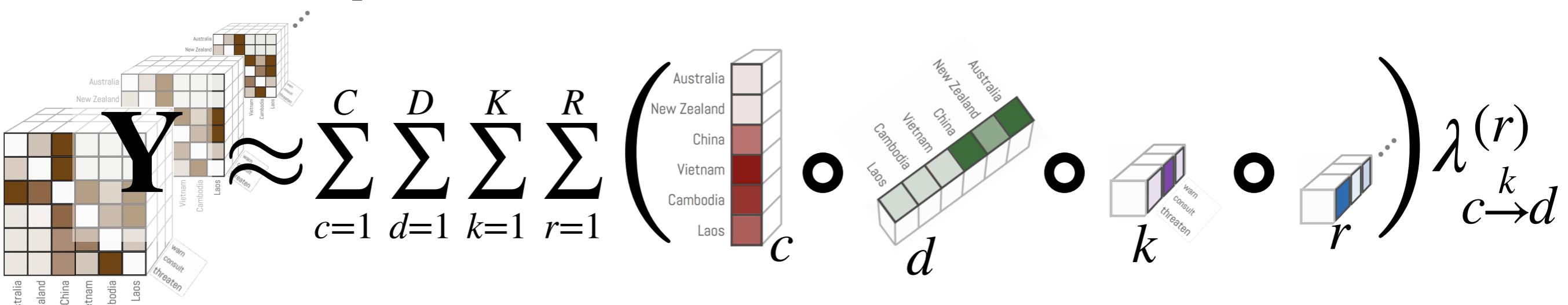
- Full picture:



Convergent lines of research on Tucker for multilayer networks / dyadic event data:

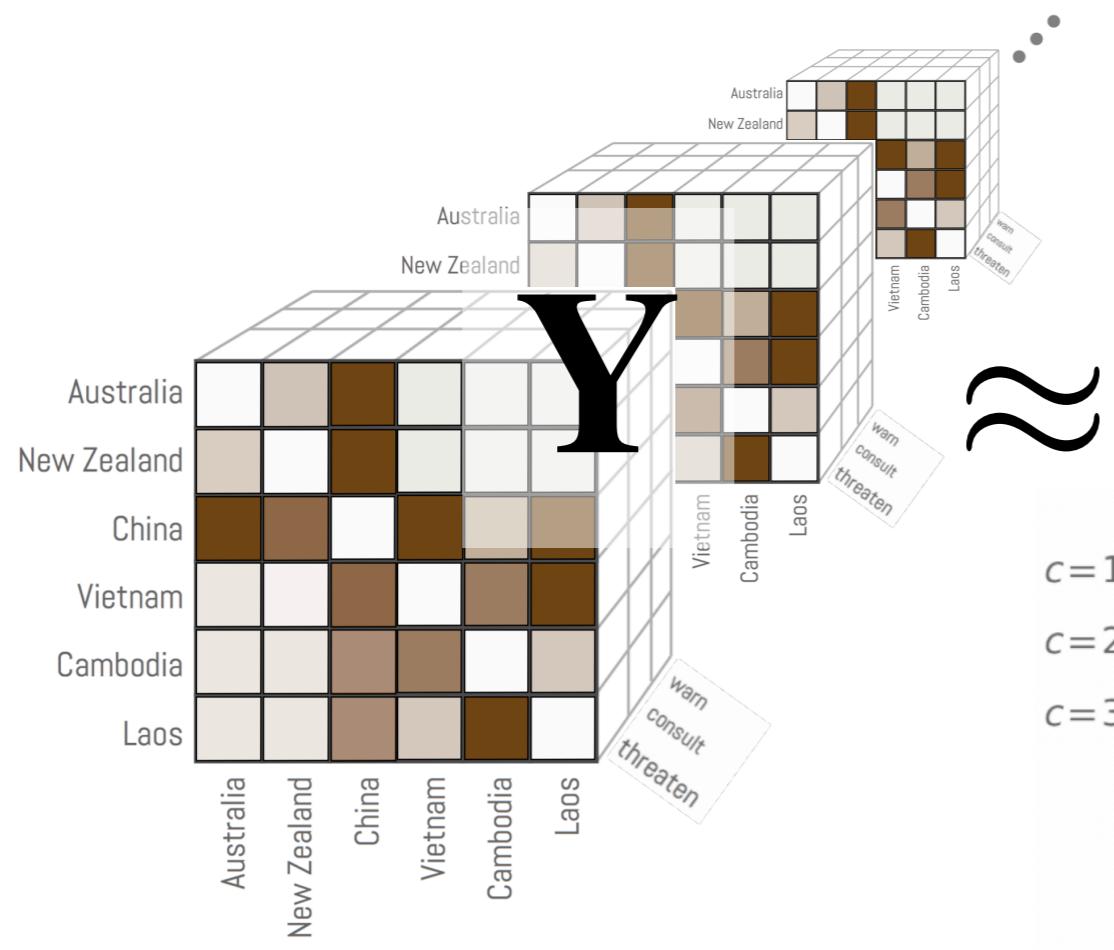
- Tucker (regression) for dyadic event data: [...]
[Minhas, Hoff, & Ward \(2015\)](#), [Hoff \(2015\)](#), [Hoff \(2016\)](#), [...]
- Non-negative Tucker for dyadic events:
[Schein et al. \(2016\)](#)
- Non-negative Tucker for multilayer networks:
[De Bacco et al. \(2017\)](#), [Aguiar et al. \(2023\)](#)

- Tucker decomposition fixes this... different number of factors in each mode

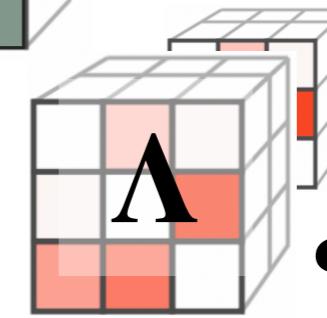
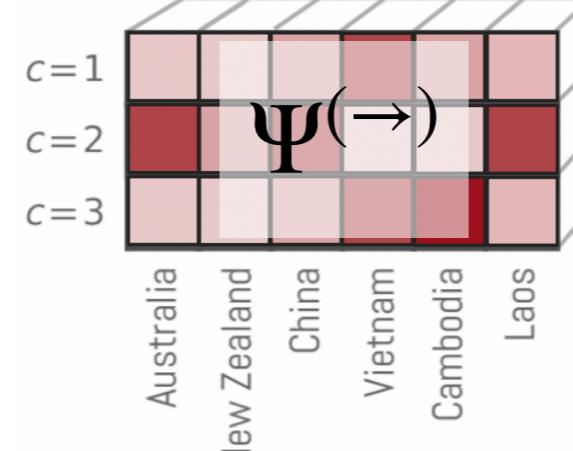
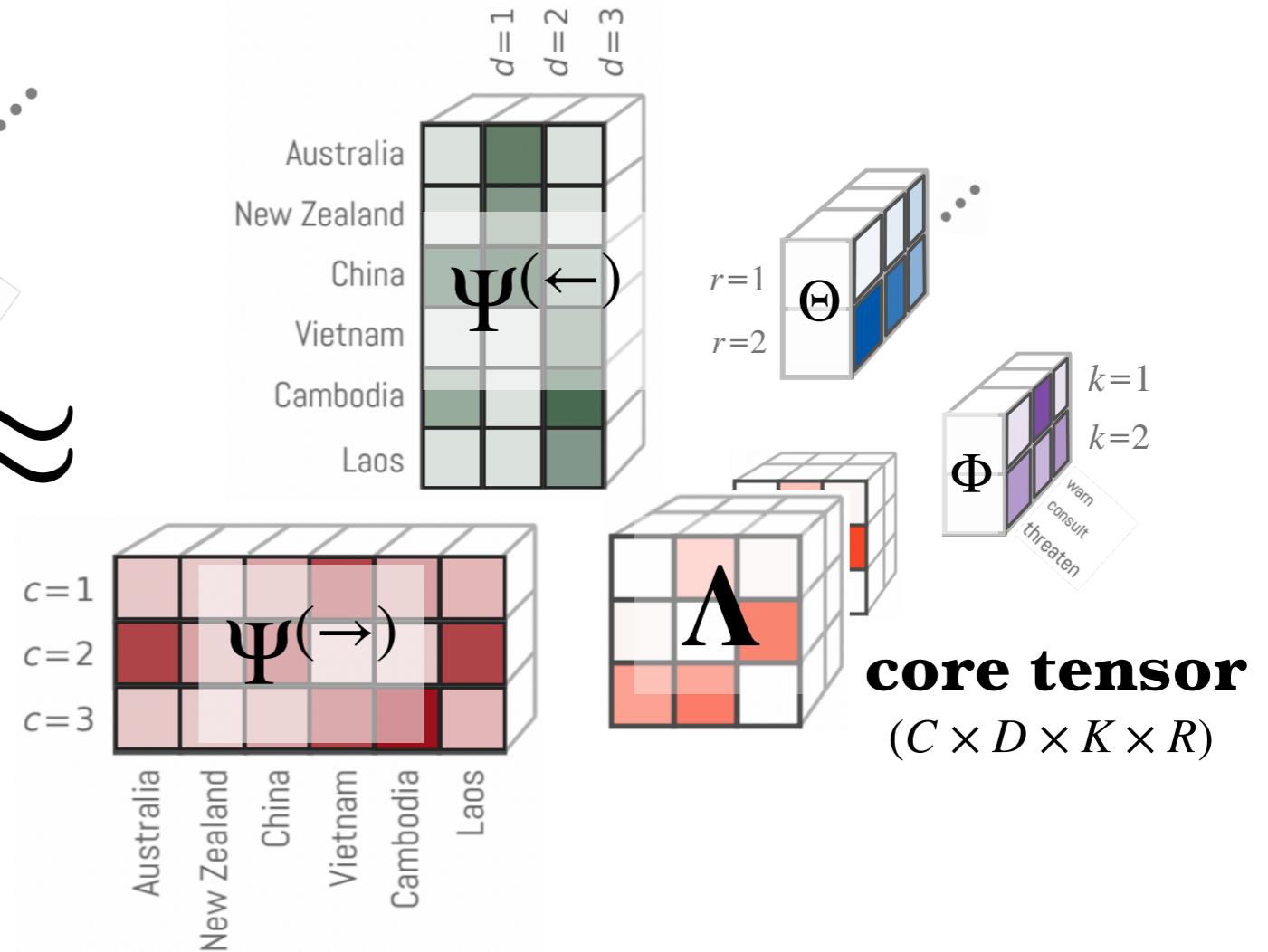


- Every class is now a unique combination (c, d, k, r) of **shared factors**

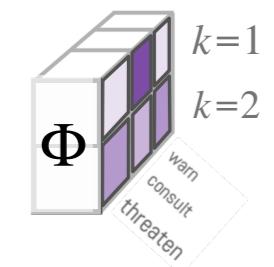
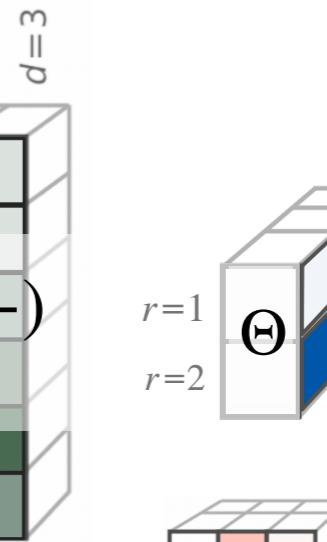
POISSON TUCKER DECOMPOSITION



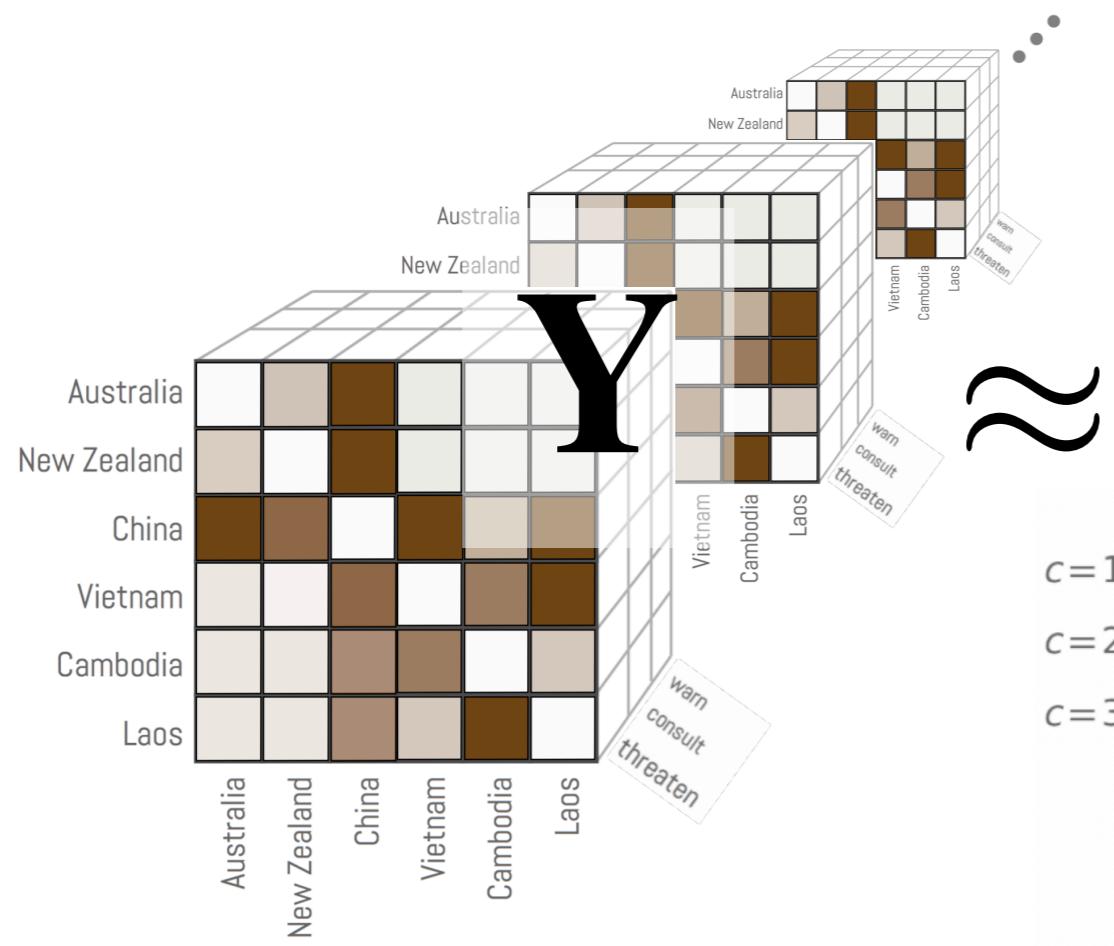
\approx



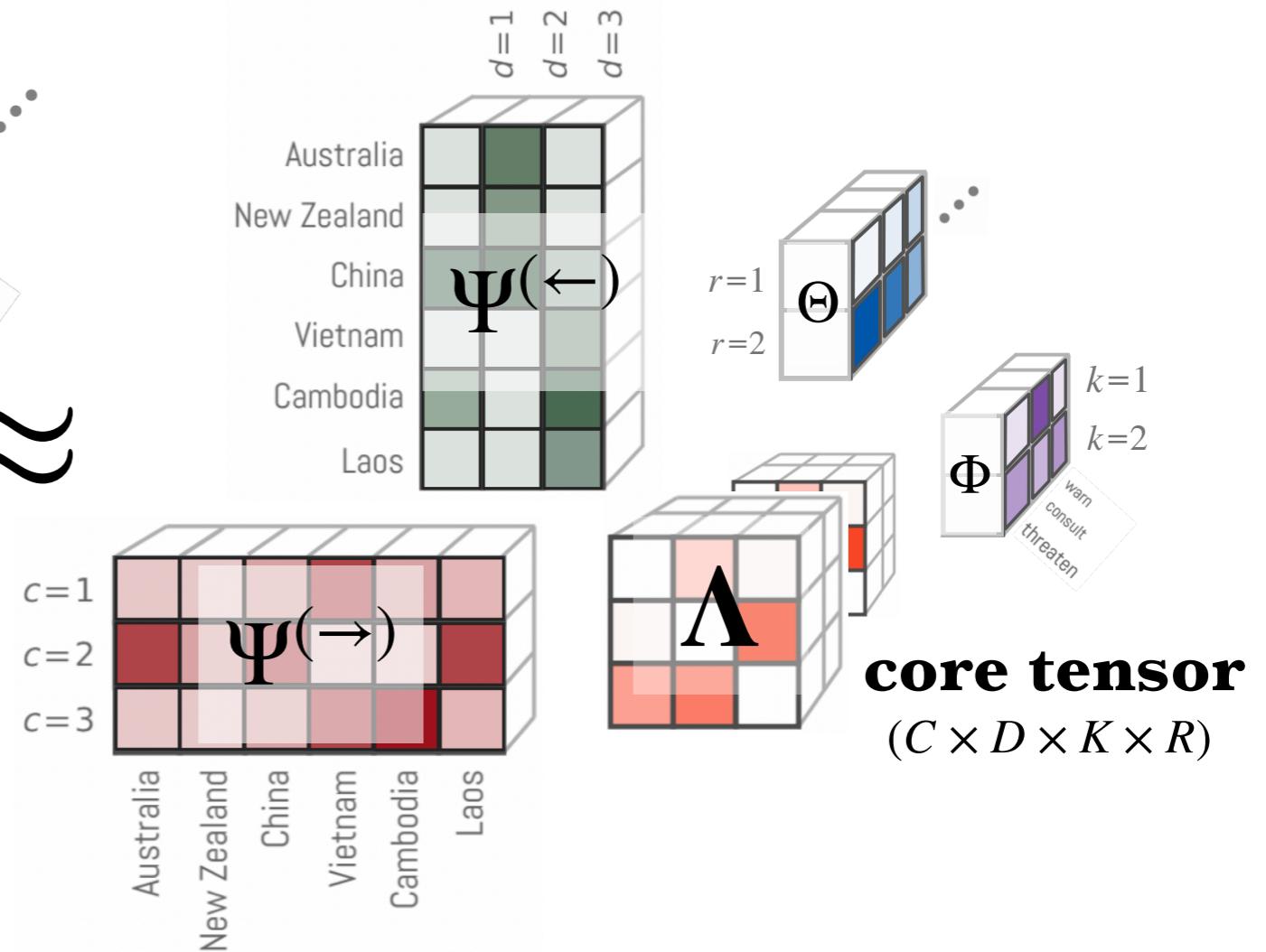
core tensor
 $(C \times D \times K \times R)$



POISSON TUCKER DECOMPOSITION

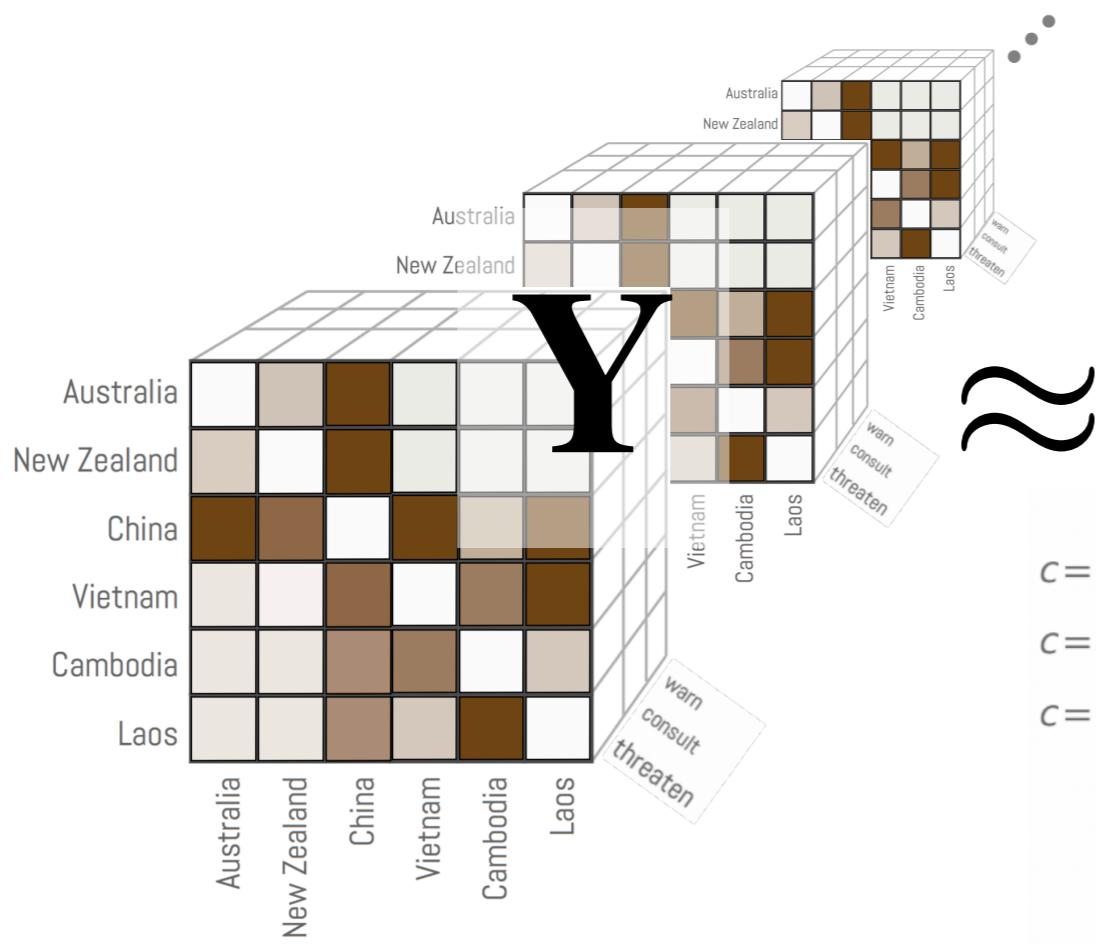


\approx

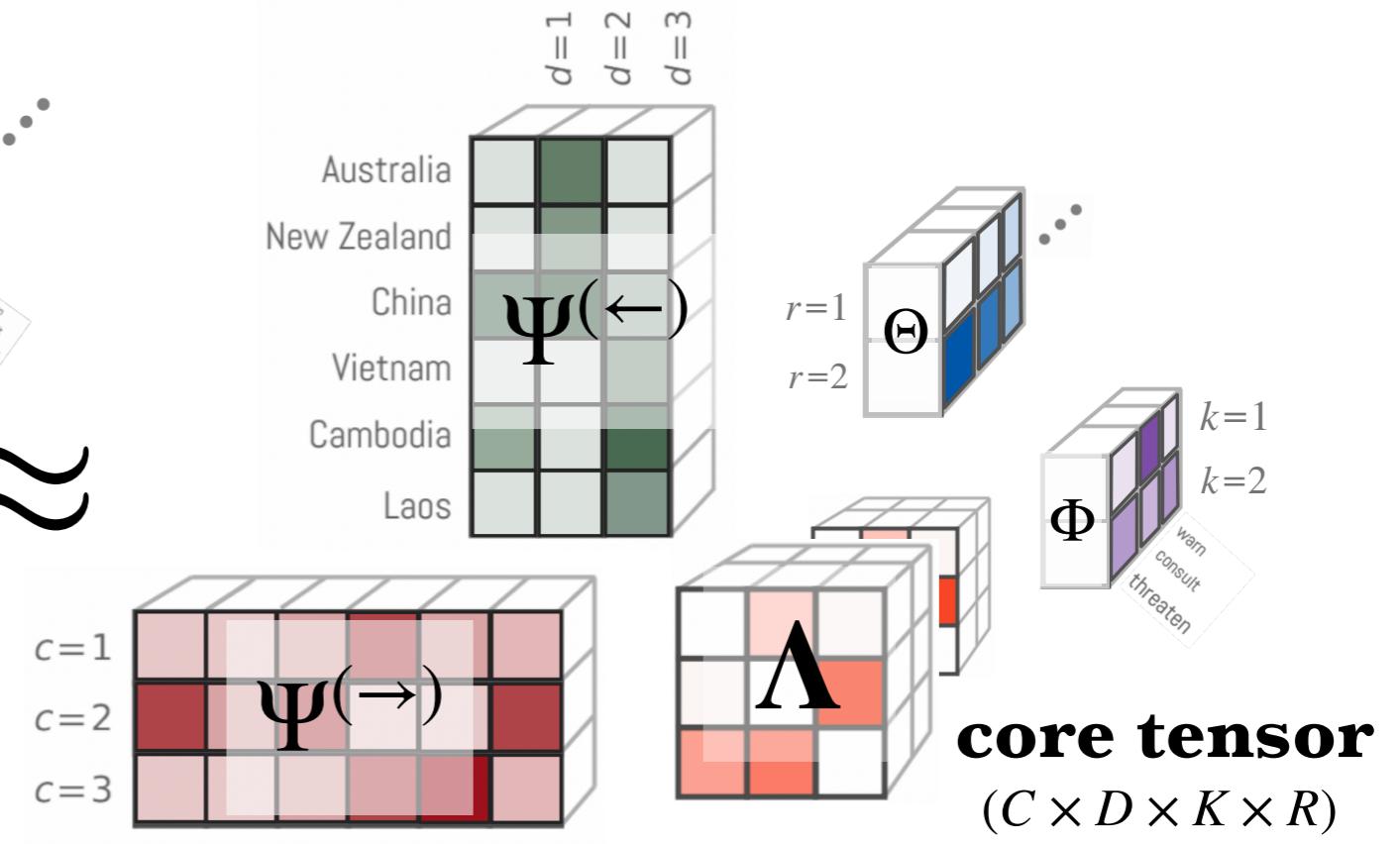


► **Optional:** $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$

POISSON TUCKER DECOMPOSITION



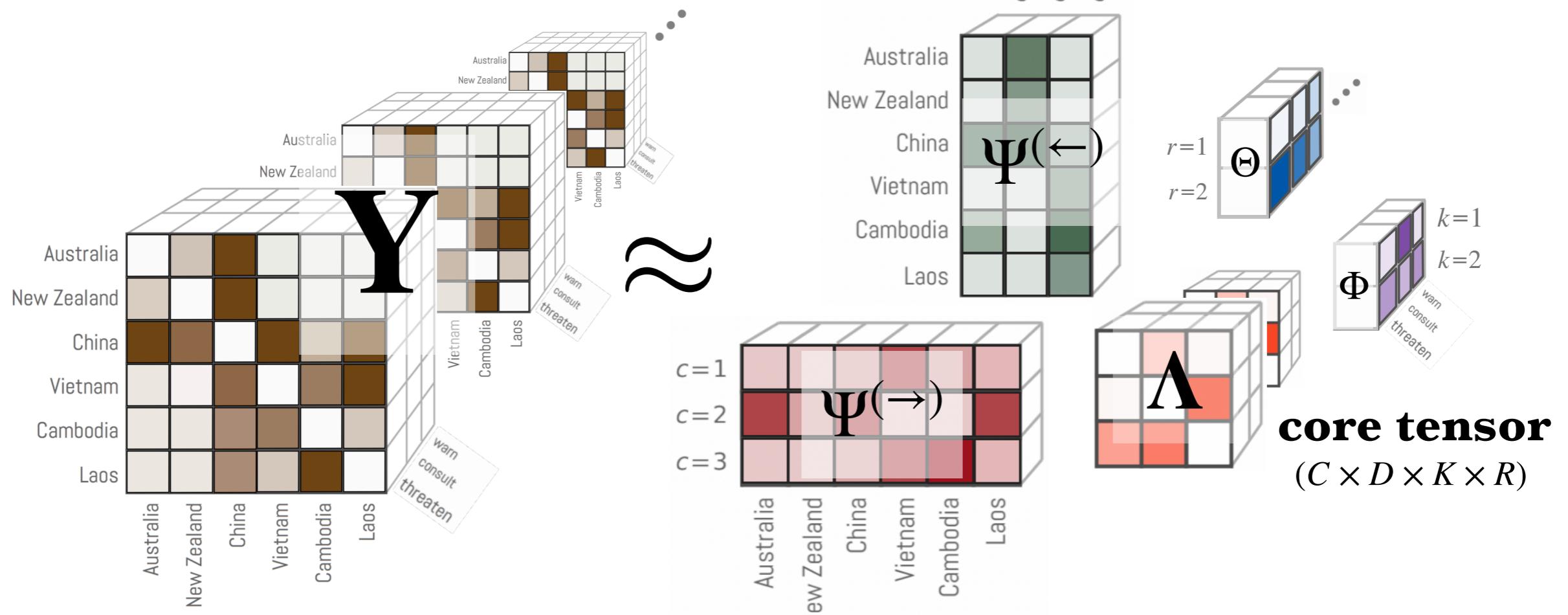
?



► **Optional:** $\Psi^{(\rightarrow)} = \Psi^{(<-)} = \Psi$

$$y_{i \rightarrow j}^{(t)} \sim \text{Pois}\left(\sum_{c=1}^C \sum_{d=1}^D \sum_{k=1}^K \sum_{r=1}^R \psi_{ic}^{(\rightarrow)} \psi_{jd}^{(<-)} \phi_{ak} \theta_r^{(t)} \lambda_{c \rightarrow d}^{(r)}\right)$$

POISSON TUCKER DECOMPOSITION

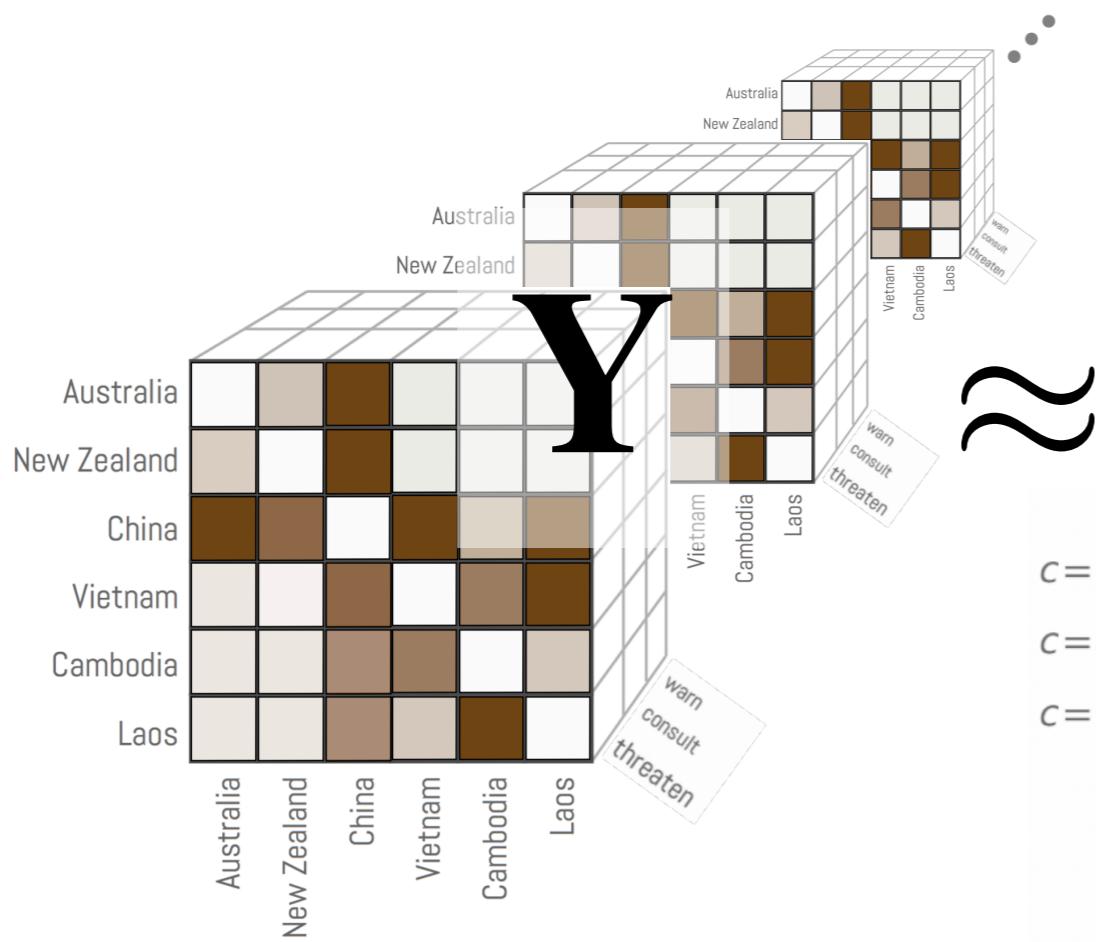


► **Optional:** $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$

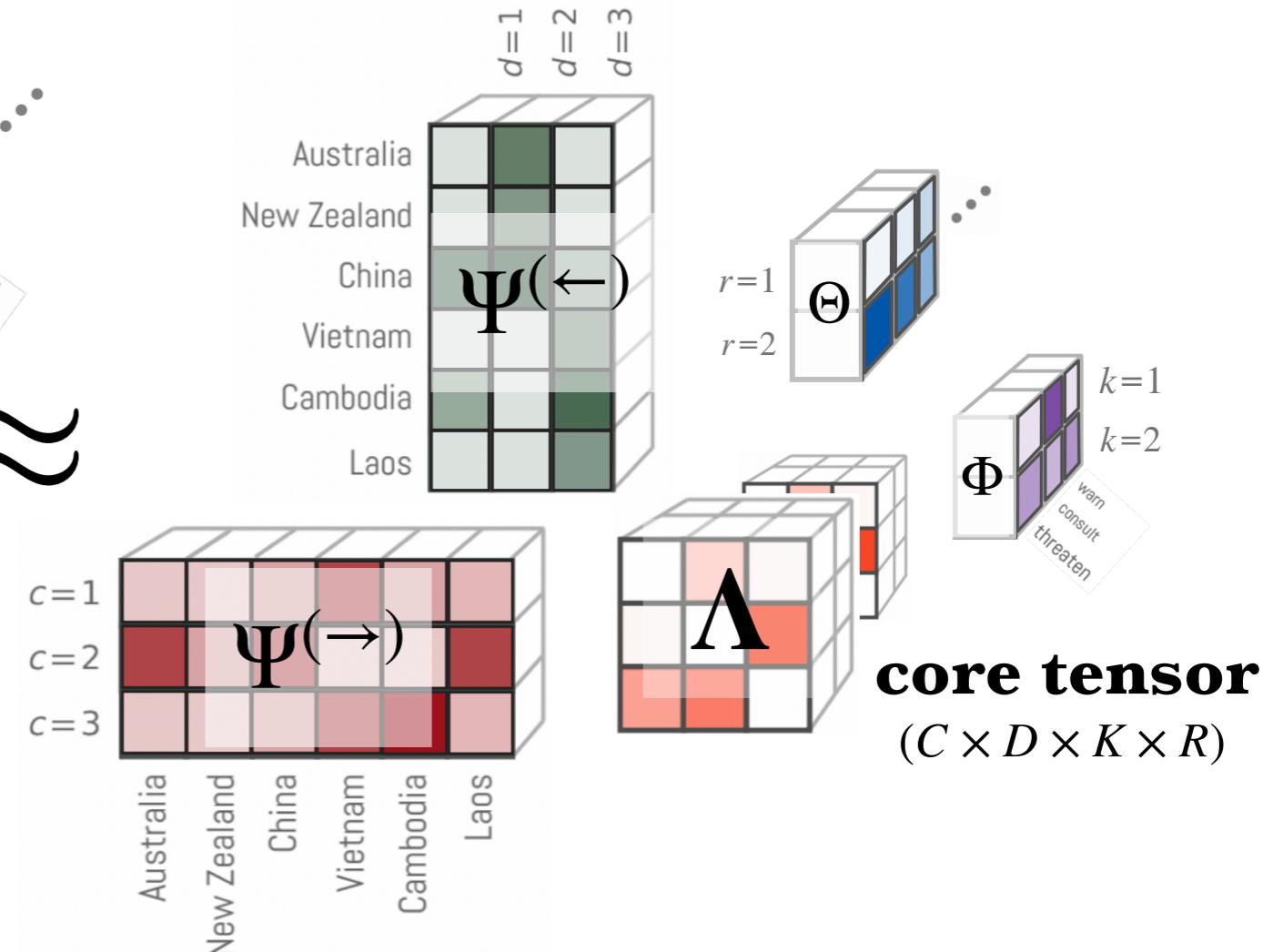
$$y_{i \rightarrow j}^{(t)} \sim \text{Pois} \left(\sum_{c=1}^C \sum_{d=1}^D \sum_{k=1}^K \sum_{r=1}^R \psi_{ic}^{(\rightarrow)} \psi_{jd}^{(\leftarrow)} \phi_{ak} \theta_r^{(t)} \lambda_{c \rightarrow d}^{(r)} \right)$$

non-negative

POISSON TUCKER DECOMPOSITION



?

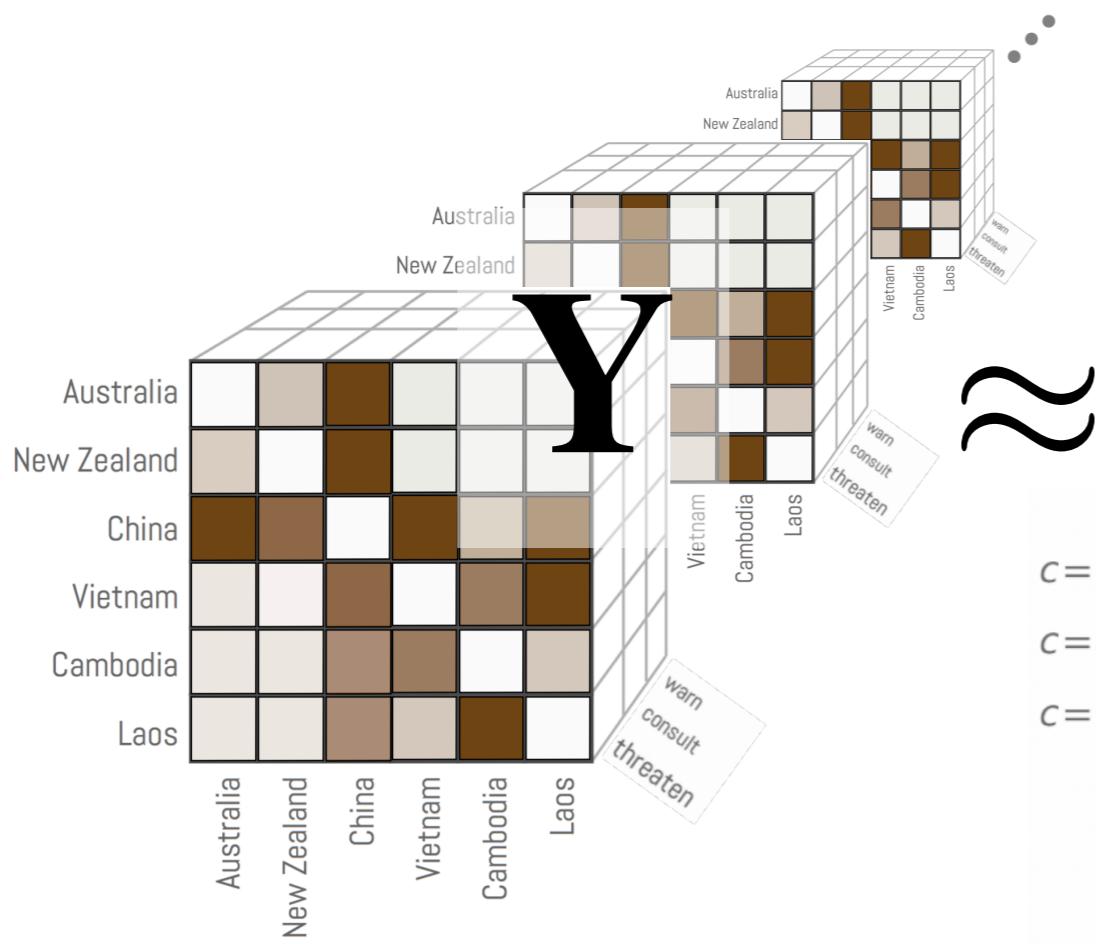


► **Optional:** $\Psi^{(\rightarrow)} = \Psi^{(<)} = \Psi$

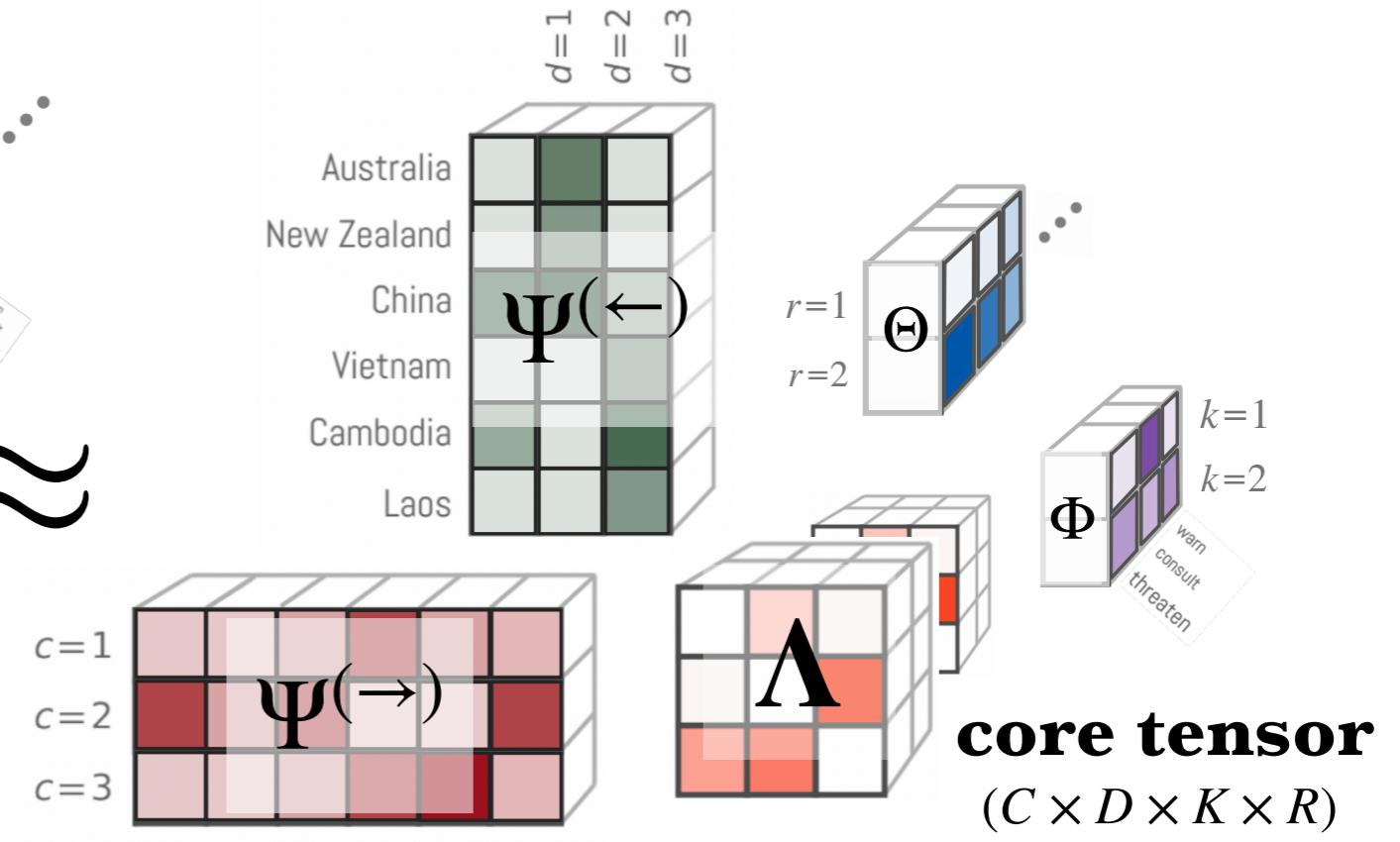
how active **country** i is
in (sender) **community** c

$$y_{i \rightarrow j}^{(t)} \sim \text{Pois}\left(\sum_{c=1}^C \sum_{d=1}^D \sum_{k=1}^K \sum_{r=1}^R \psi_{ic}^{(\rightarrow)} \psi_{jd}^{(<)} \phi_{ak} \theta_r^{(t)} \lambda_{c \rightarrow d}^{(r)}\right)$$

POISSON TUCKER DECOMPOSITION



\approx



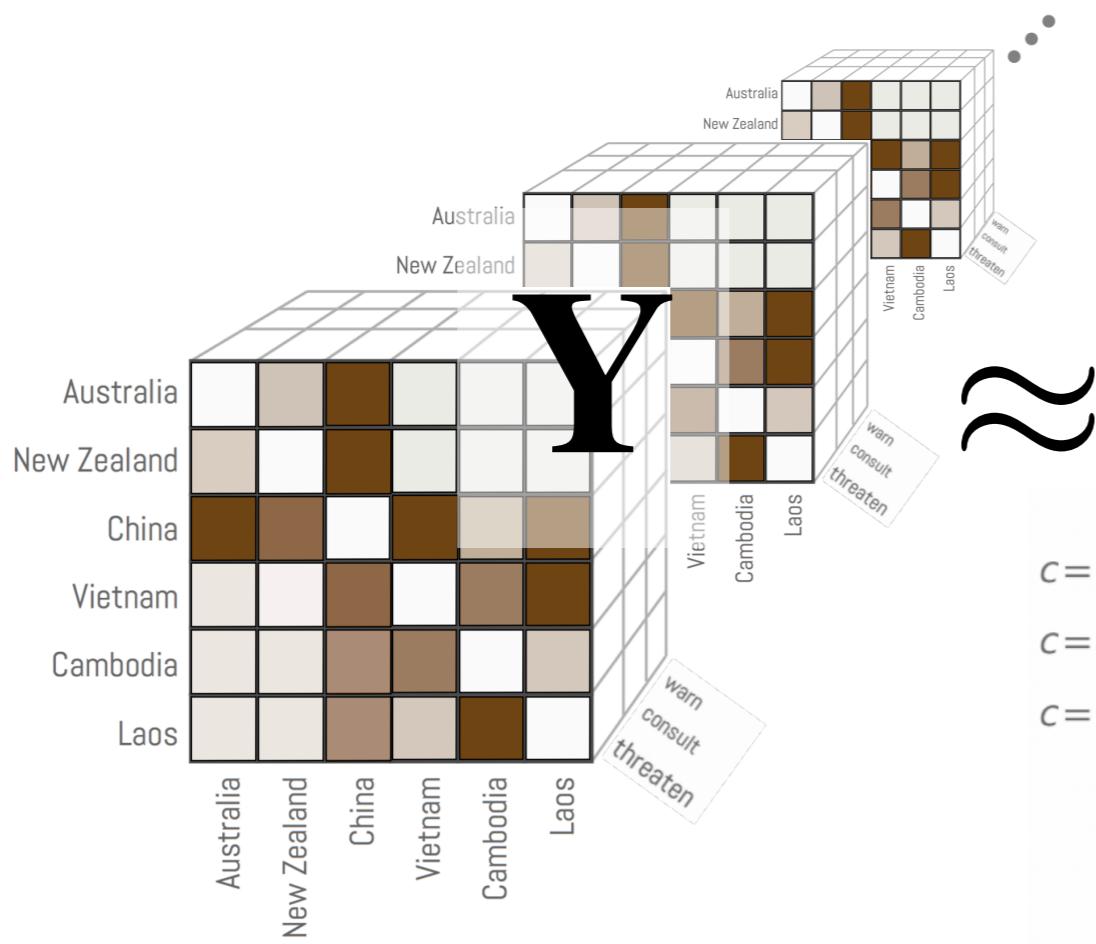
core tensor
 $(C \times D \times K \times R)$

► **Optional:** $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$

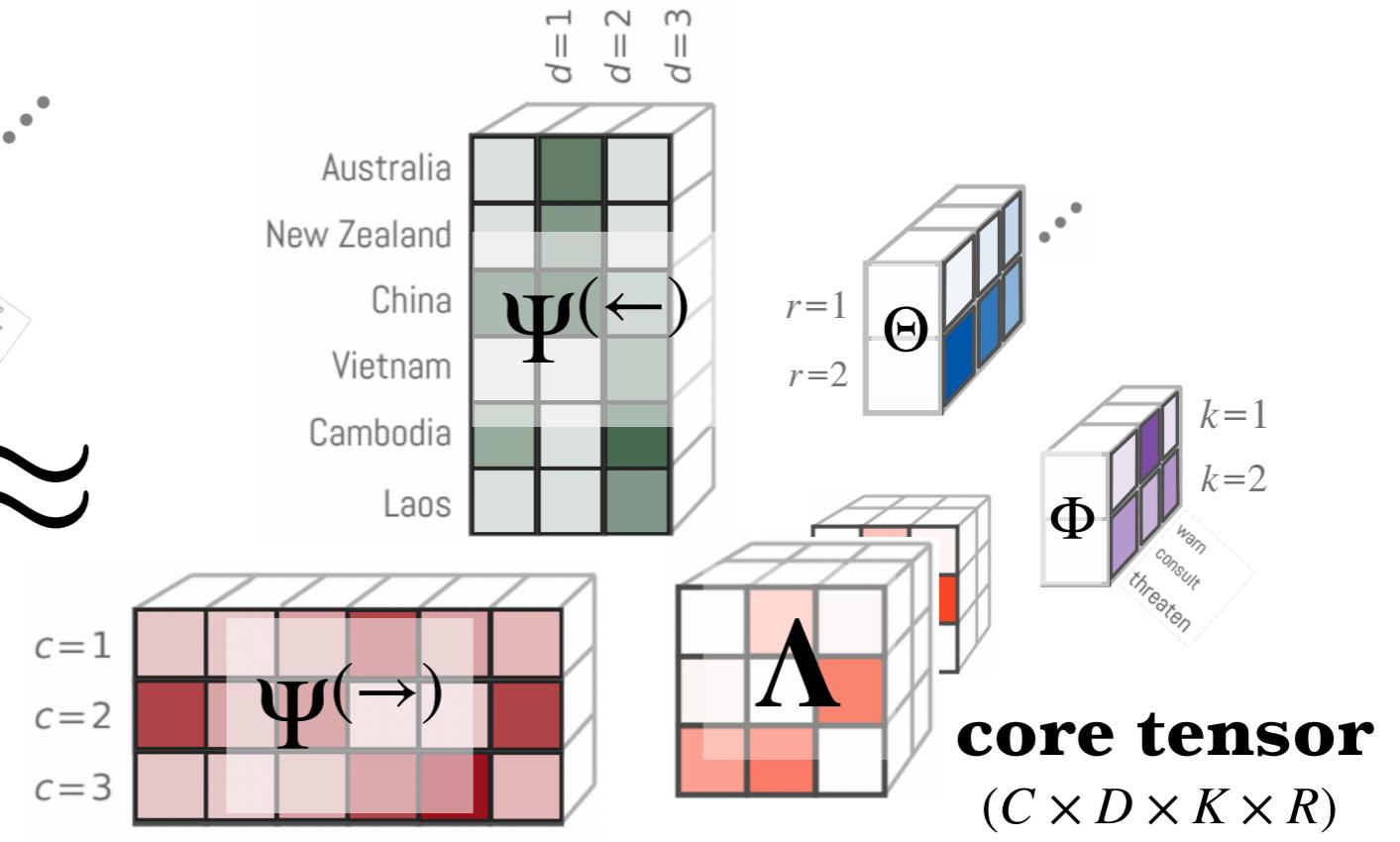
how active **country** j is
in (receiver) **community** d

$$y_{i \rightarrow j}^{(t)} \sim \text{Pois}\left(\sum_{c=1}^C \sum_{d=1}^D \sum_{k=1}^K \sum_{r=1}^R \psi_{ic}^{(\rightarrow)} \psi_{jd}^{(\leftarrow)} \phi_{ak} \theta_r^{(t)} \lambda_{c \rightarrow d}^{(r)}\right)$$

POISSON TUCKER DECOMPOSITION



?



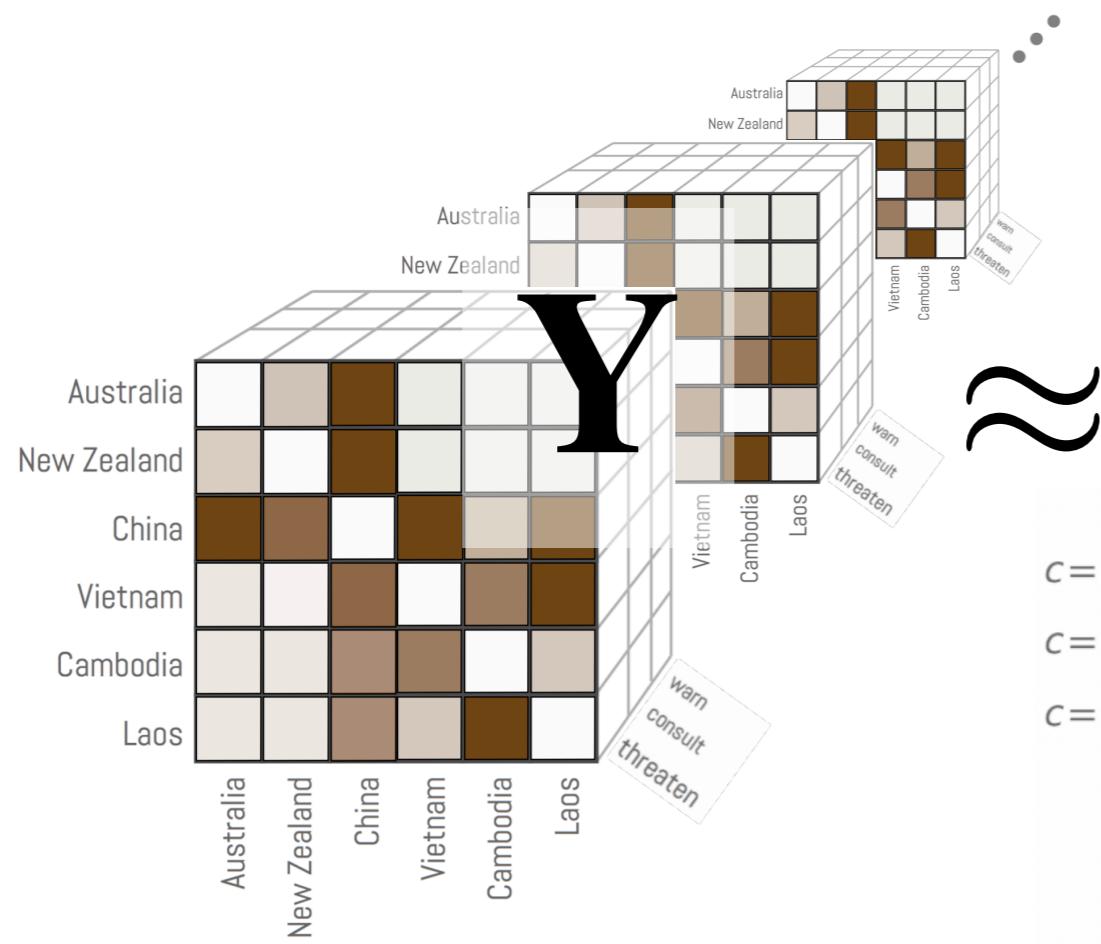
core tensor
 $(C \times D \times K \times R)$

► **Optional:** $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$

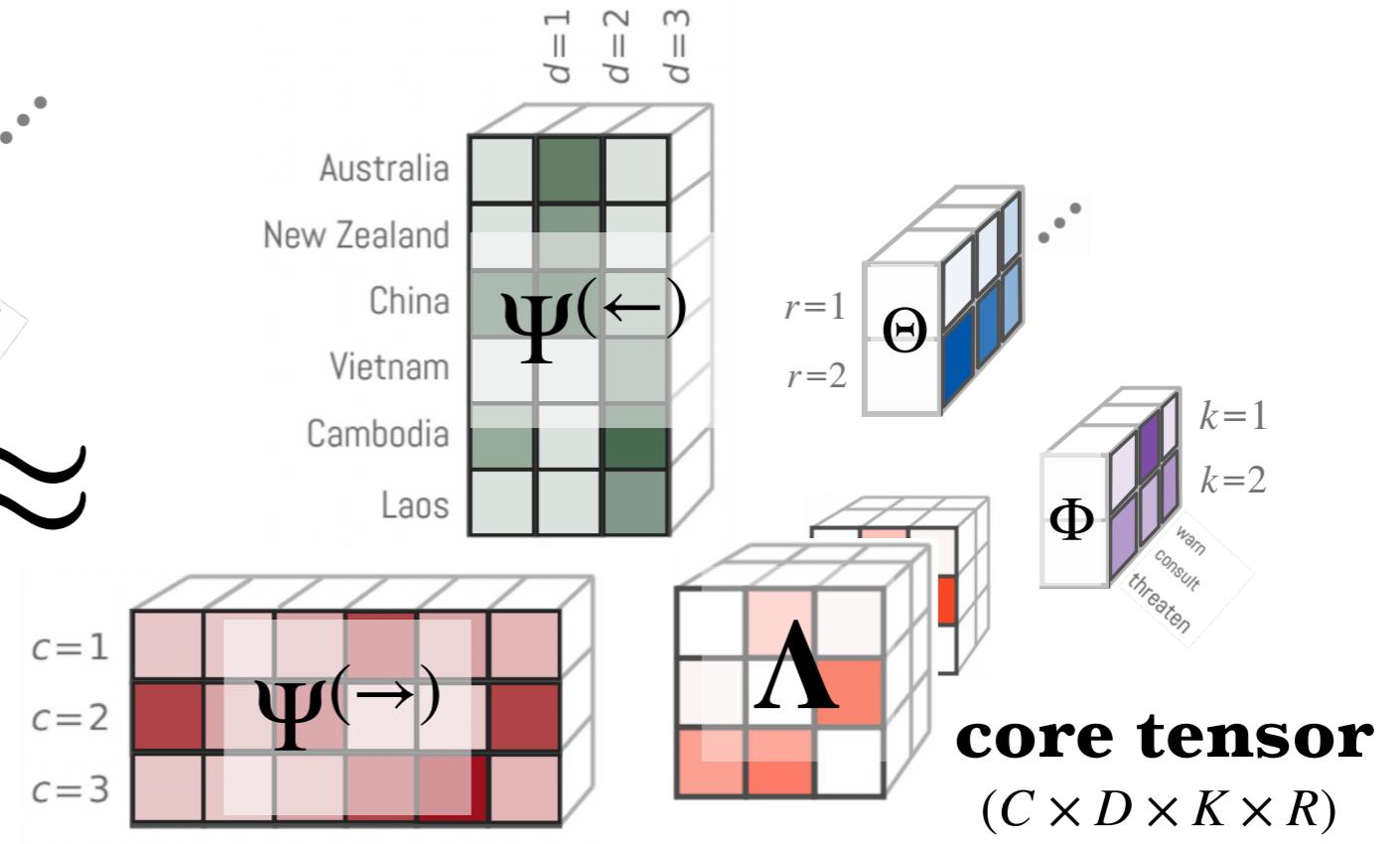
how prevalent **action** a is
in **topic** k

$$y_{i \rightarrow j}^{(t)} \sim \text{Pois} \left(\sum_{c=1}^C \sum_{d=1}^D \sum_{k=1}^K \sum_{r=1}^R \psi_{ic}^{(\rightarrow)} \psi_{jd}^{(\leftarrow)} \phi_{ak} \theta_r^{(t)} \lambda_{c \rightarrow d}^{(r)} \right)$$

POISSON TUCKER DECOMPOSITION



?



core tensor

$(C \times D \times K \times R)$

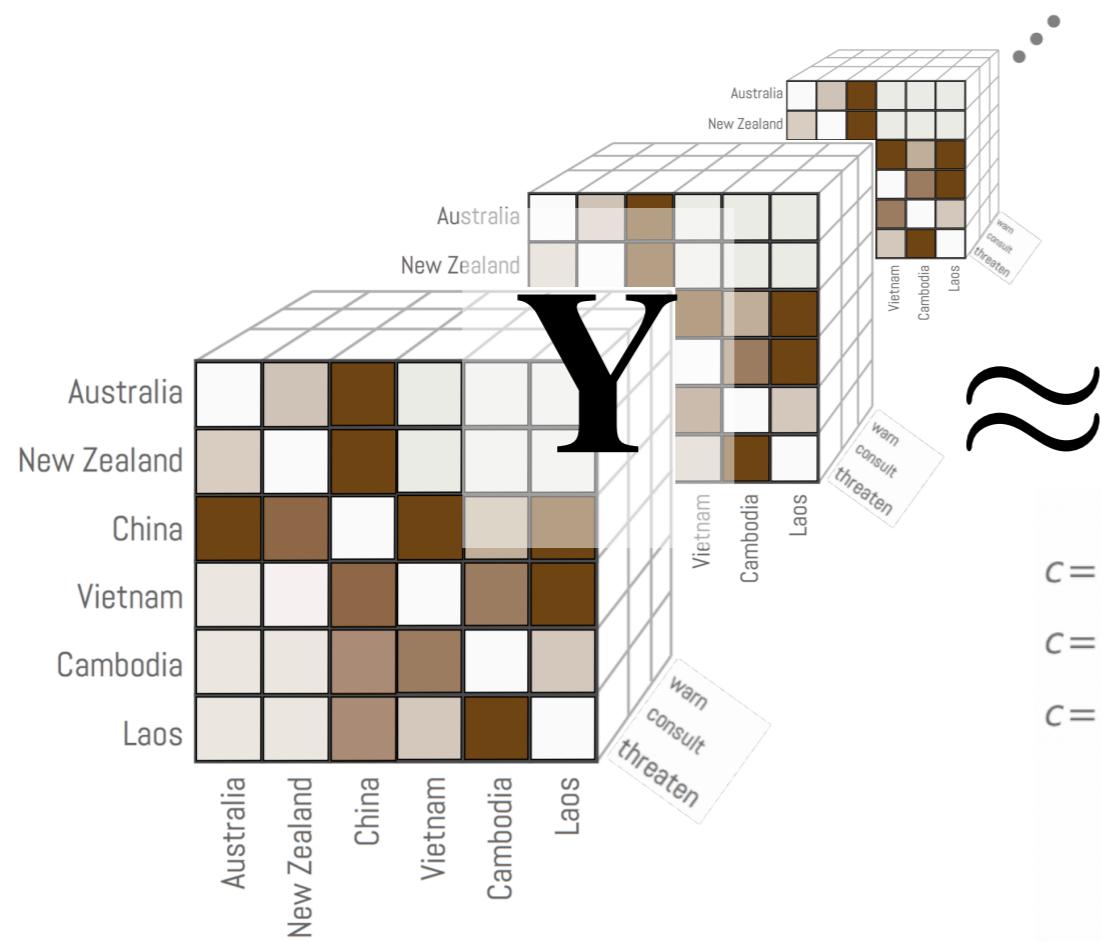
► **Optional:** $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$

how active **regime** r is

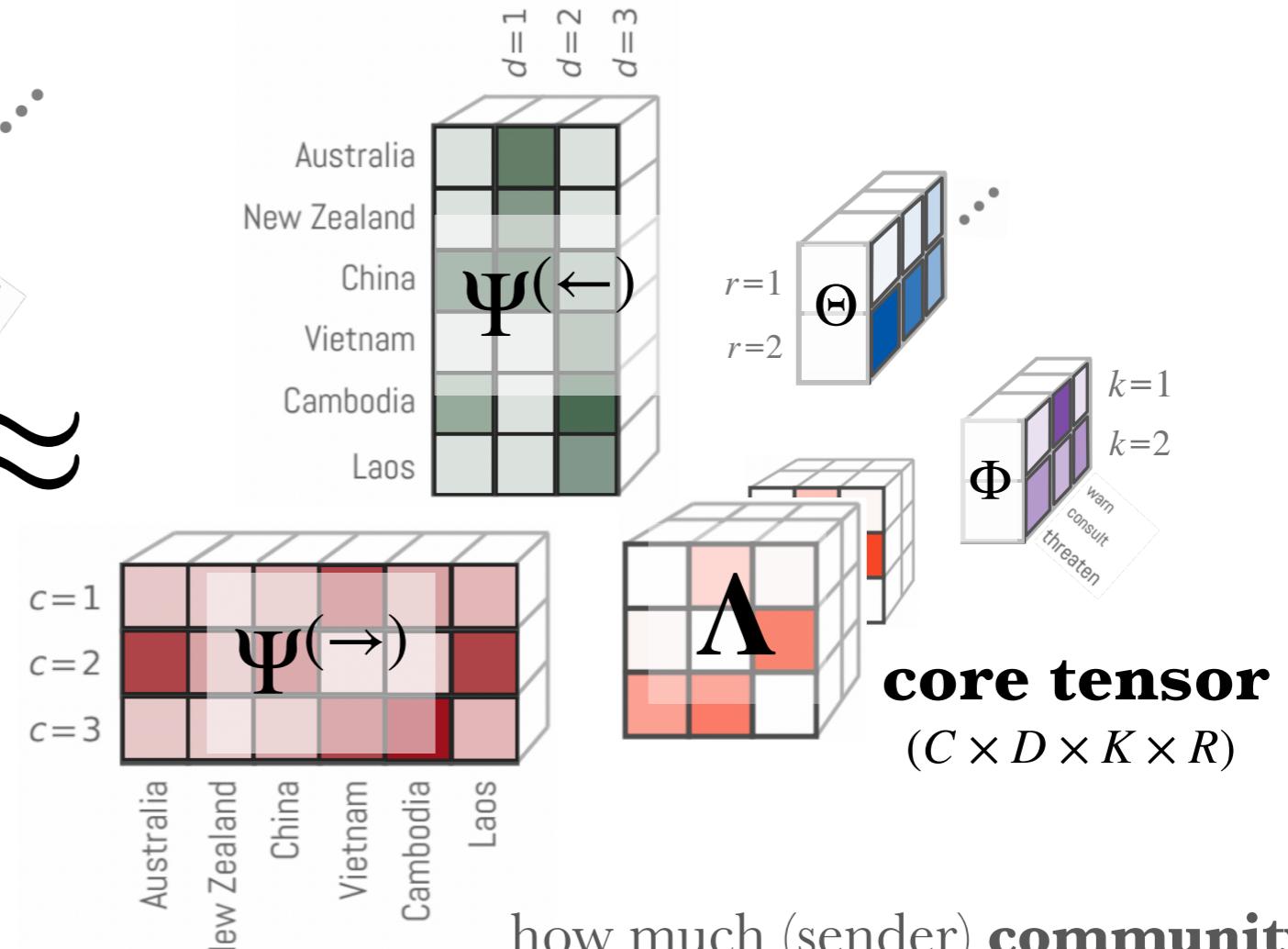
at **time** t

$$y_{i \rightarrow j}^{(t)} \sim \text{Pois} \left(\sum_{c=1}^C \sum_{d=1}^D \sum_{k=1}^K \sum_{r=1}^R \psi_{ic}^{(\rightarrow)} \psi_{jd}^{(\leftarrow)} \phi_{ak} \theta_r^{(t)} \lambda_{c \rightarrow d}^{(r)} \right)$$

POISSON TUCKER DECOMPOSITION



?



core tensor
 $(C \times D \times K \times R)$

how much (sender) **community** c
takes **topic** k
toward (receiver) **community** d
under **regime** r

► **Optional:** $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$

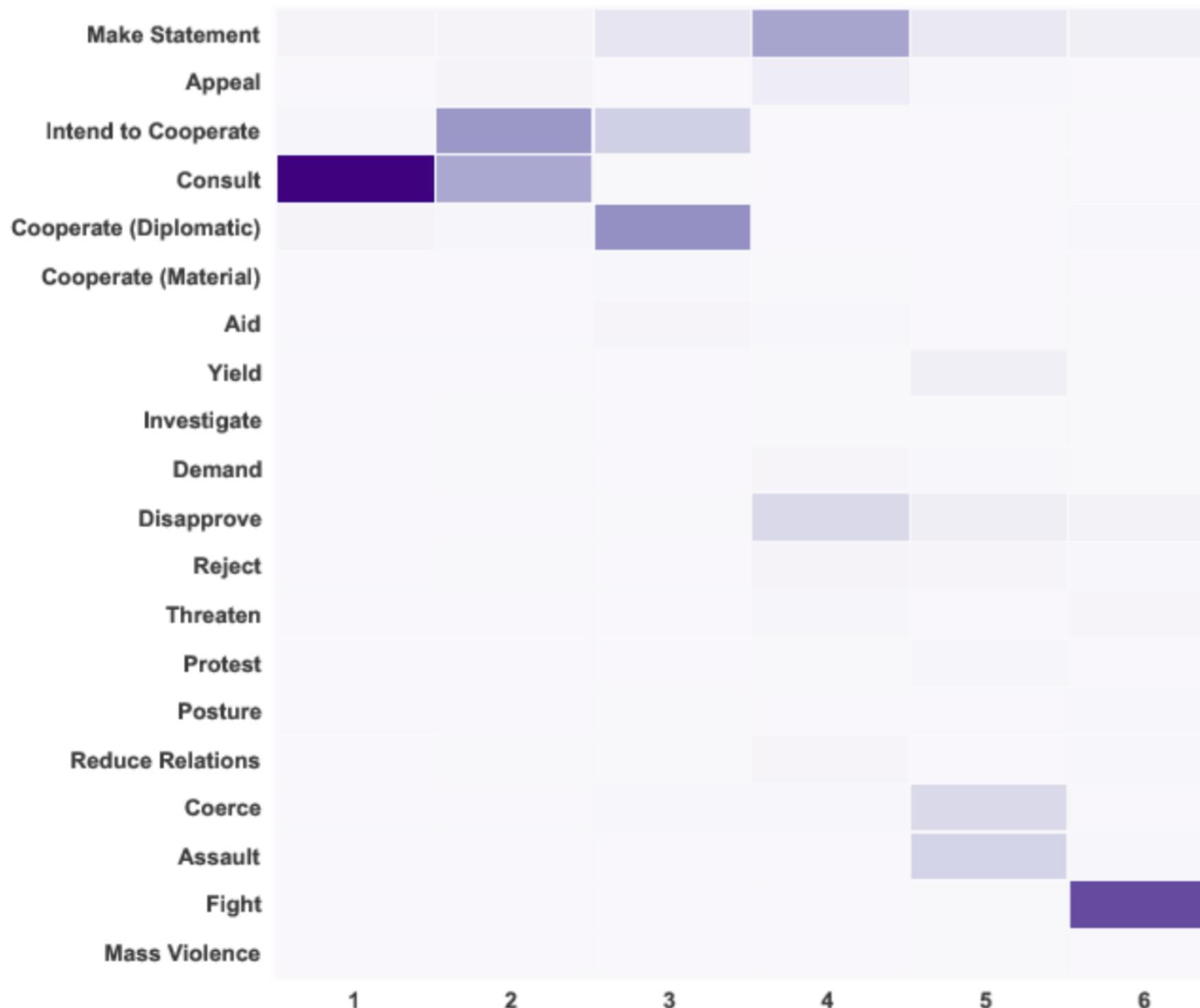
$$y_{i \rightarrow j}^{(t)} \sim \text{Pois} \left(\sum_{c=1}^C \sum_{d=1}^D \sum_{k=1}^K \sum_{r=1}^R \psi_{ic}^{(\rightarrow)} \psi_{jd}^{(\leftarrow)} \phi_{ak} \theta_r^{(t)} \lambda_{c \rightarrow d}^{(r)} \right)$$

EXAMPLE RESULTS

- ▶ GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- ▶ Core size: (12 x 12 x 6 x 1)
- ▶ $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$

EXAMPLE RESULTS

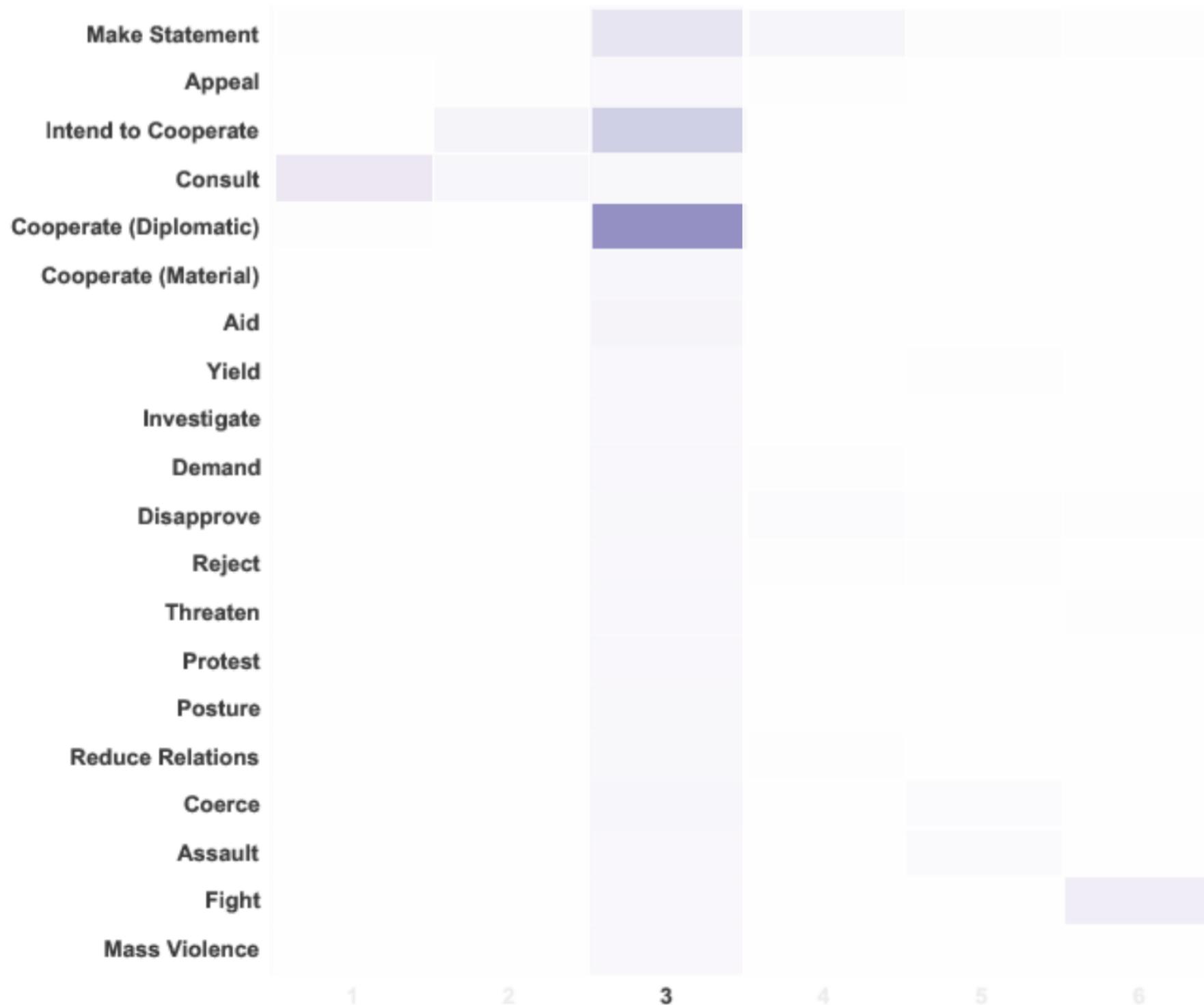
- ▶ GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- ▶ Core size: (12 x 12 x 6 x 1)
- ▶ $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$



ϕ_{ak}
topics of actions

EXAMPLE RESULTS

- ▶ GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- ▶ Core size: (12 x 12 x 6 x 1)
- ▶ $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$



ϕ_{ak}
topics of actions

EXAMPLE RESULTS

- GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- Core size: (12 x 12 x 6 x 1)
- $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$



ϕ_{ak}
topics of actions

EXAMPLE RESULTS

- ▶ GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- ▶ Core size: (12 x 12 x 6 x 1)
- ▶ $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$

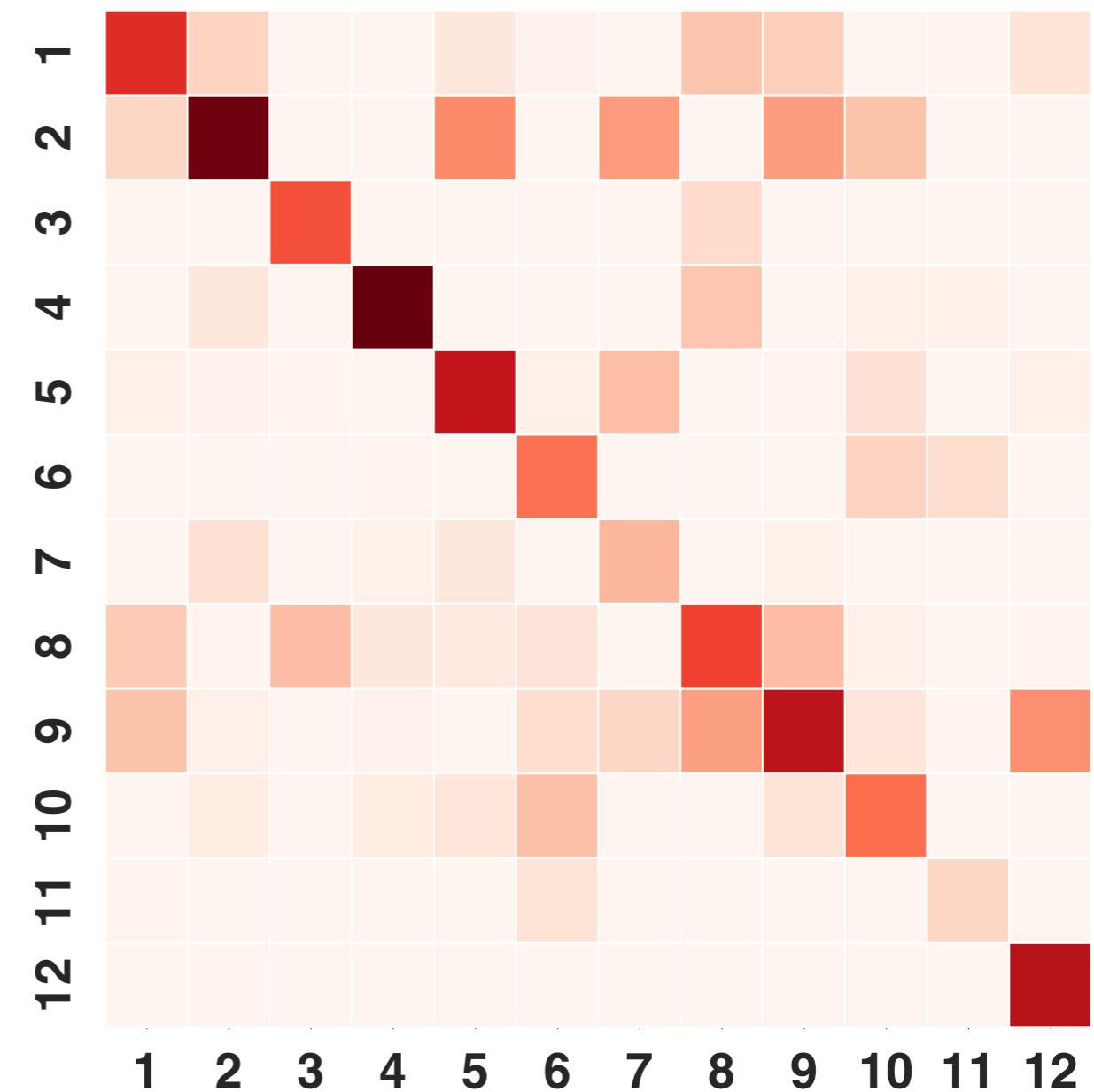


ϕ_{ak}
topics of actions

EXAMPLE RESULTS

- ▶ GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
 - ▶ Core size: (12 x 12 x 6 x 1)
 - ▶ $\Psi^{(\rightarrow)} \equiv \Psi^{(\leftarrow)} \equiv \Psi$

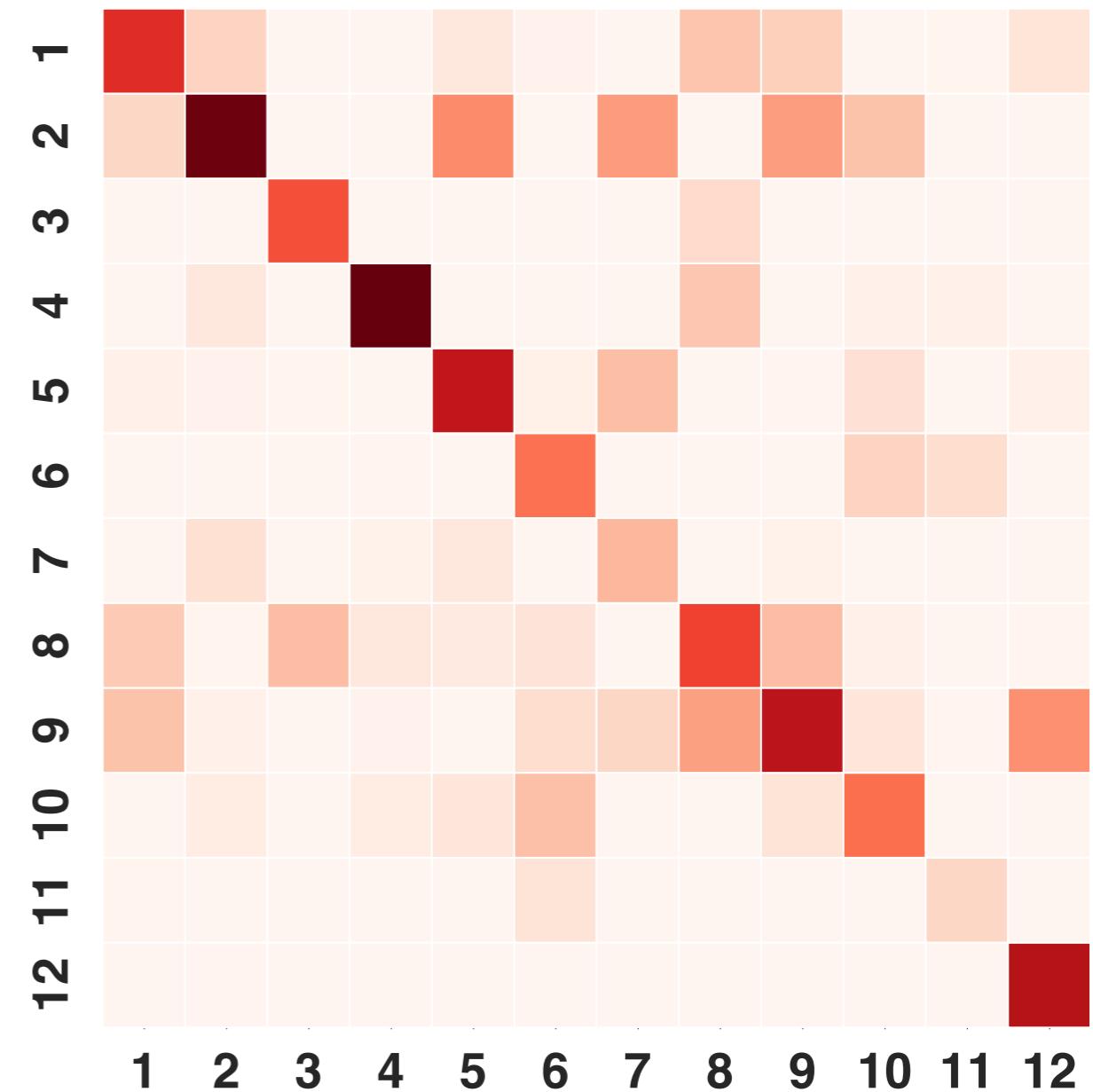
$$\lambda_{c \rightarrow d}^k \longrightarrow$$



EXAMPLE RESULTS

- ▶ GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- ▶ Core size: (12 x 12 x 6 x 1)
- ▶ $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$

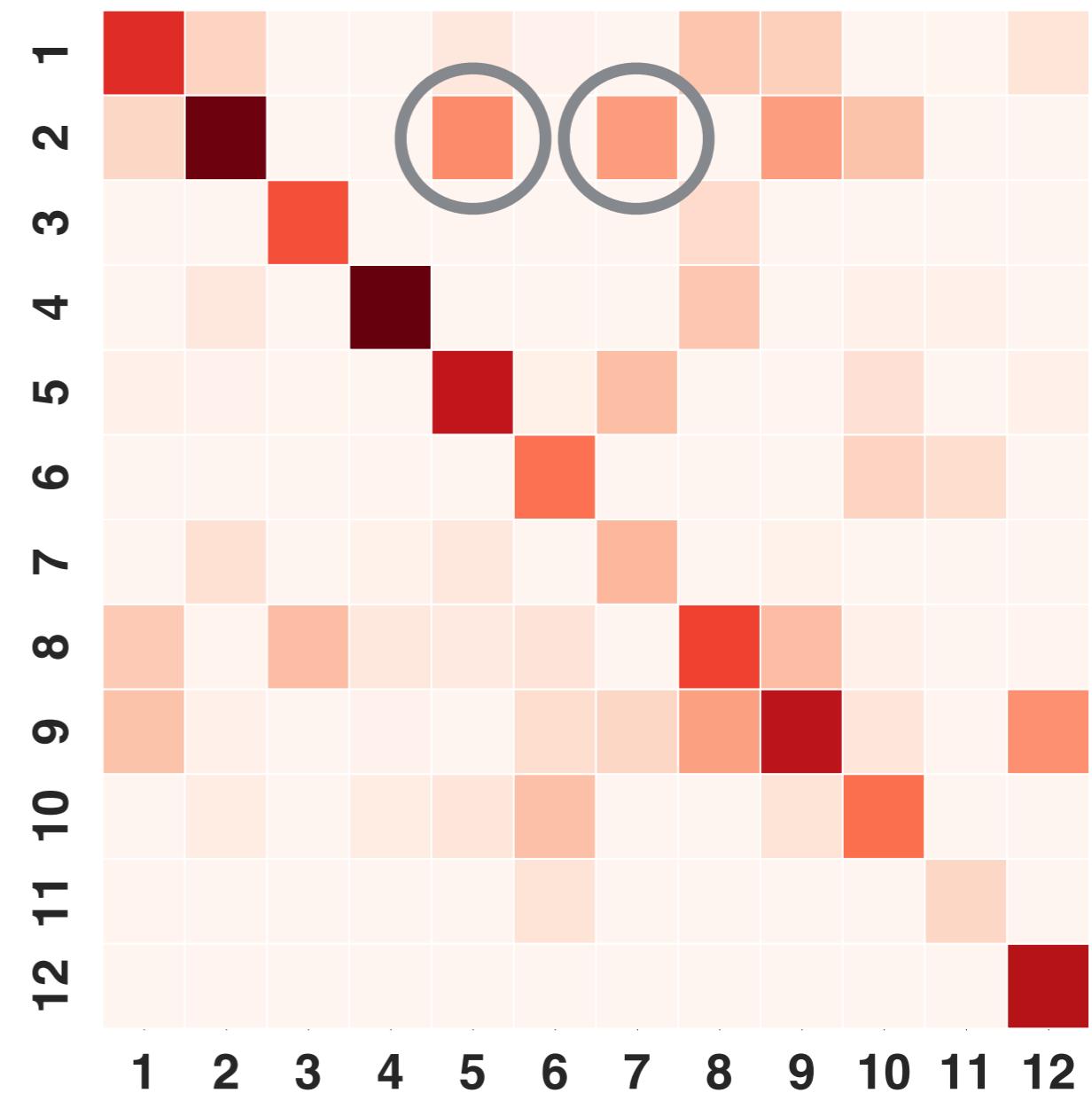
$\lambda_{c \rightarrow d}^k \longrightarrow$
Slice of core tensor for
“Lip service” topic k



EXAMPLE RESULTS

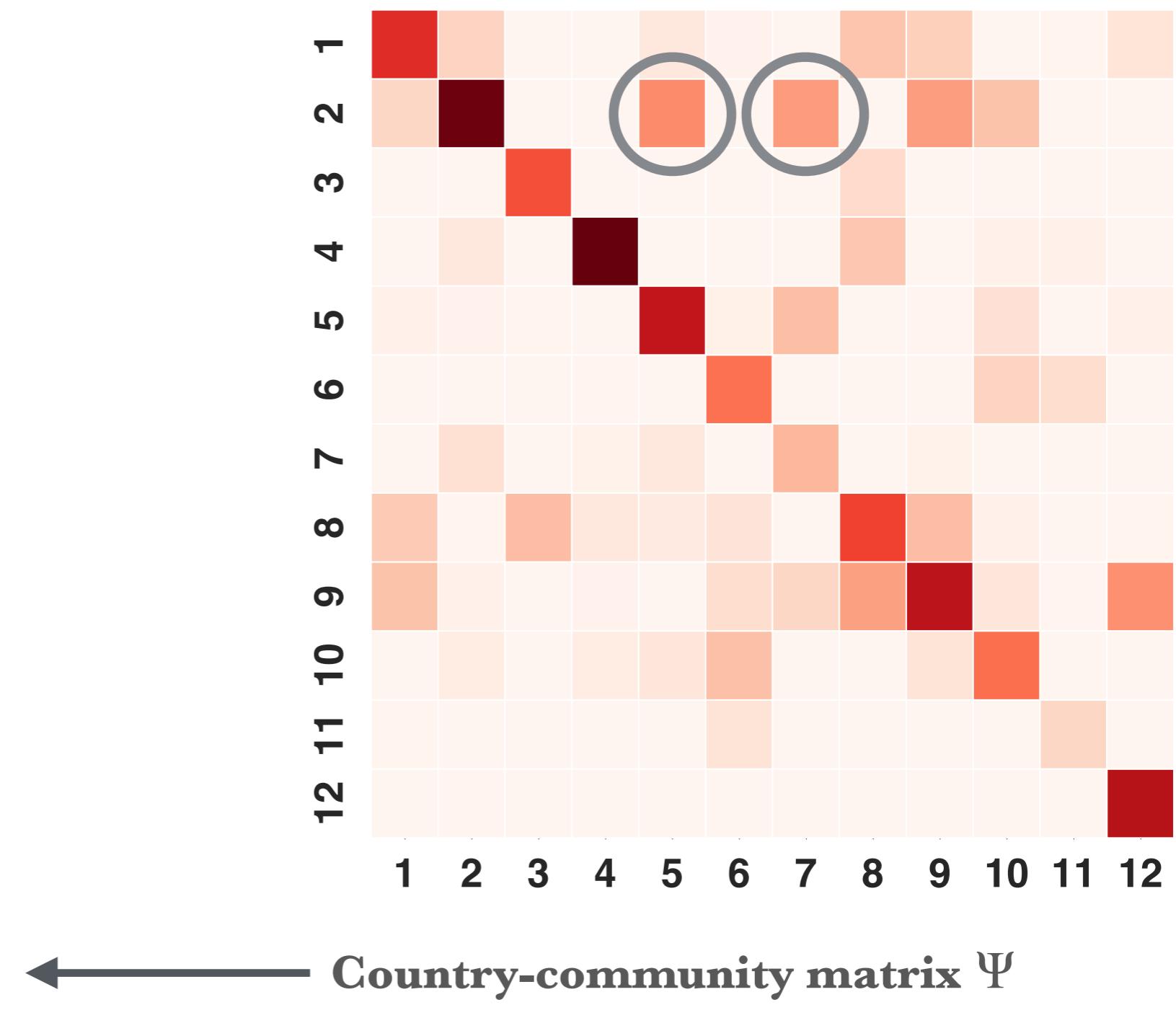
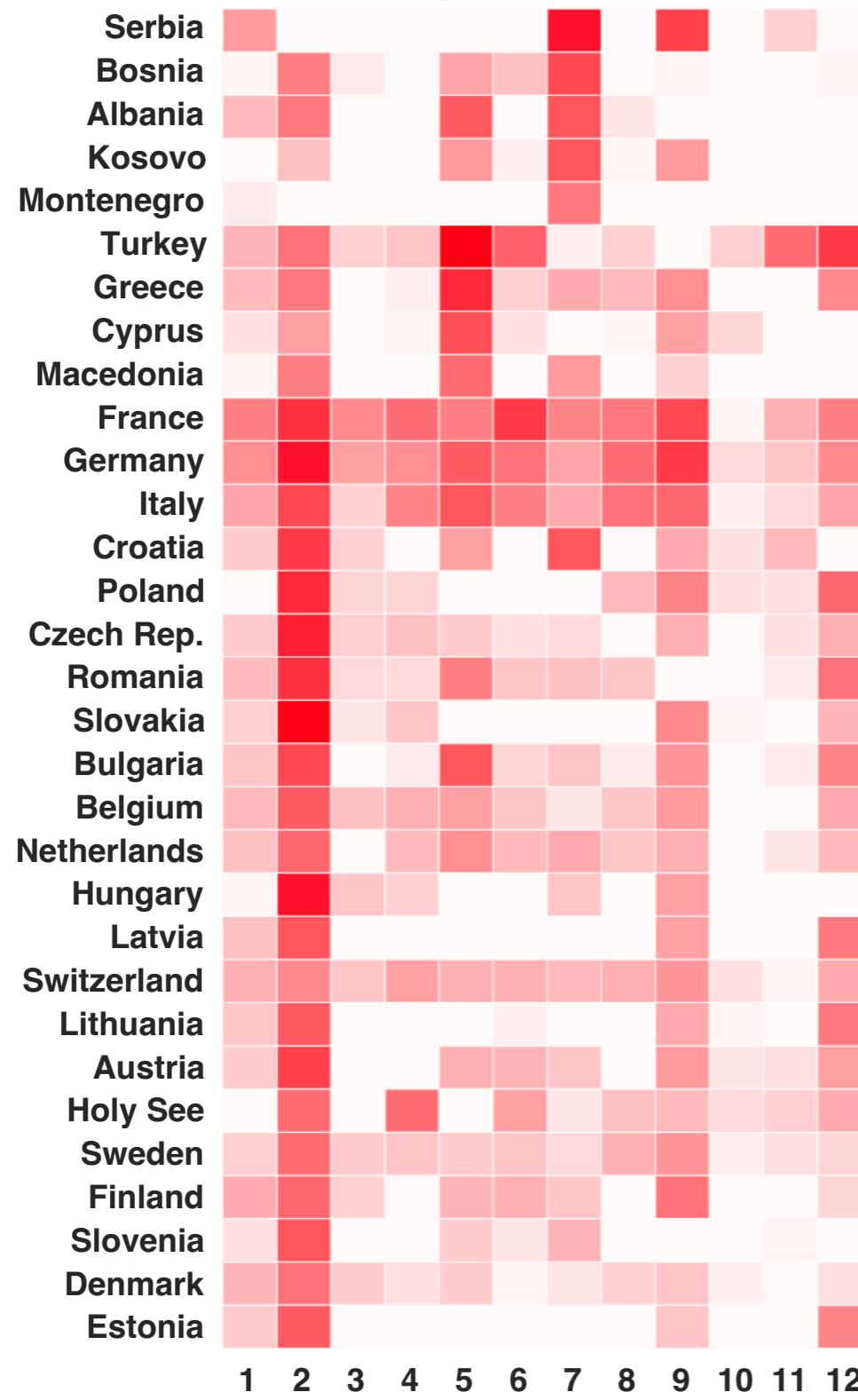
- ▶ GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- ▶ Core size: (12 x 12 x 6 x 1)
- ▶ $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$

$\lambda_{c \rightarrow d}^k$ →
Slice of core tensor for
“Lip service” topic k



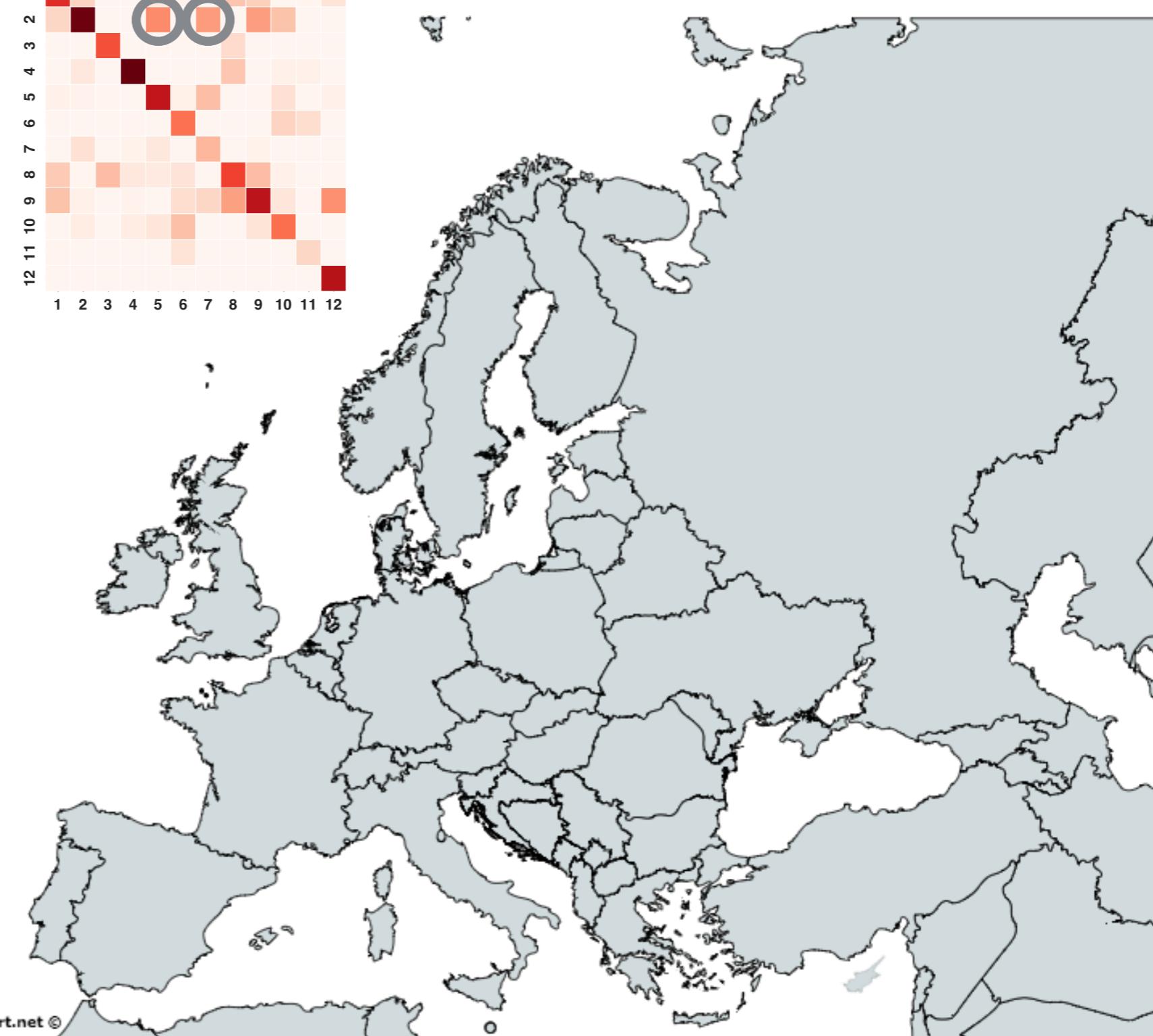
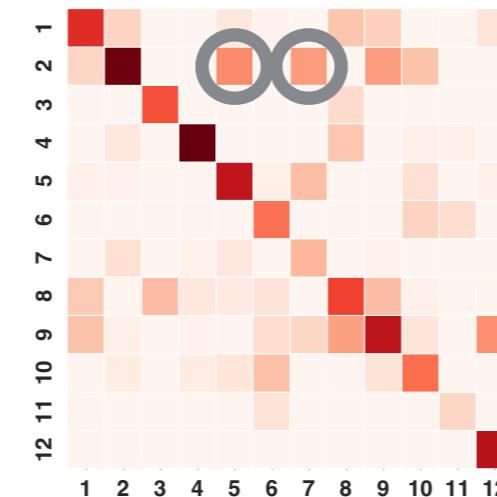
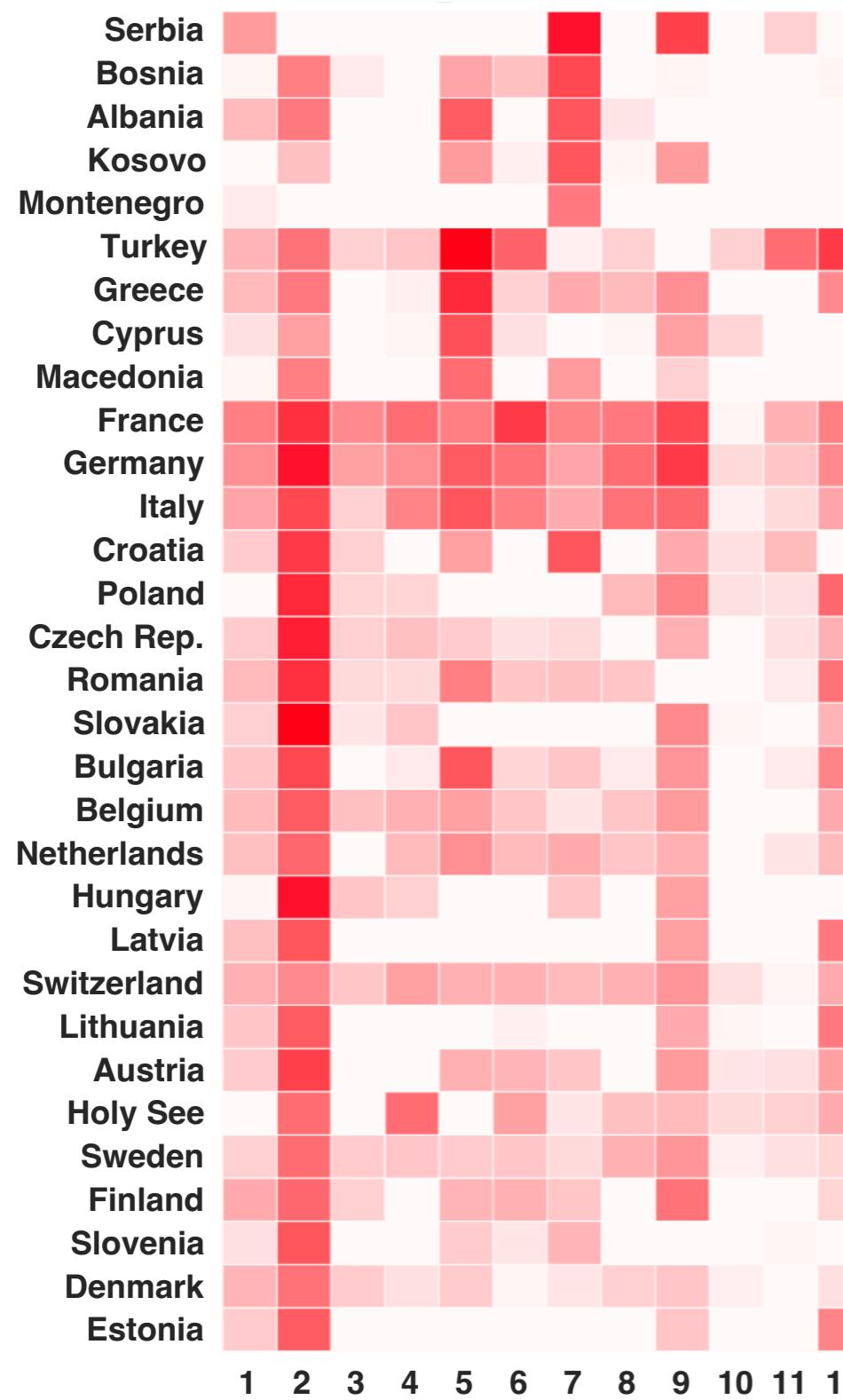
EXAMPLE RESULTS

- ▶ GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- ▶ Core size: (12 x 12 x 6 x 1)
- ▶ $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$



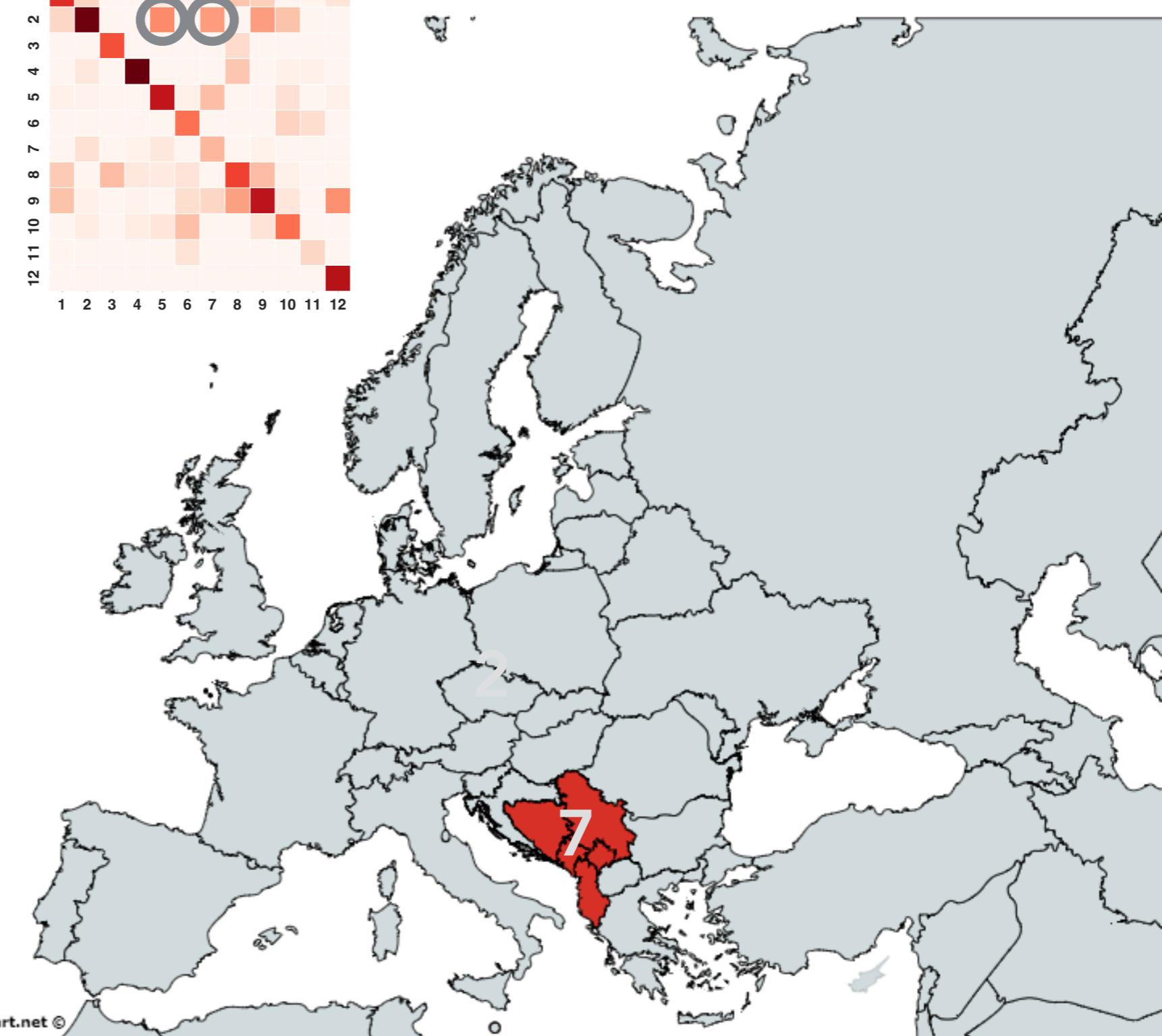
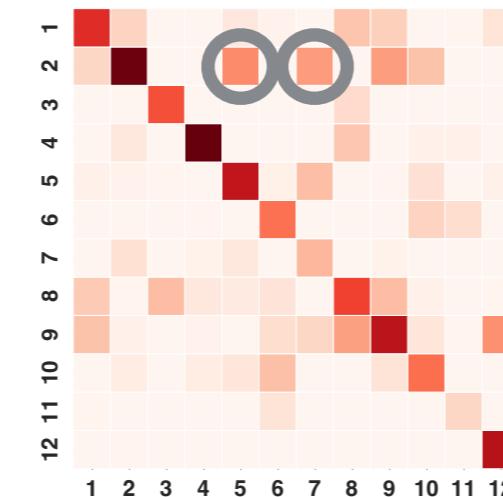
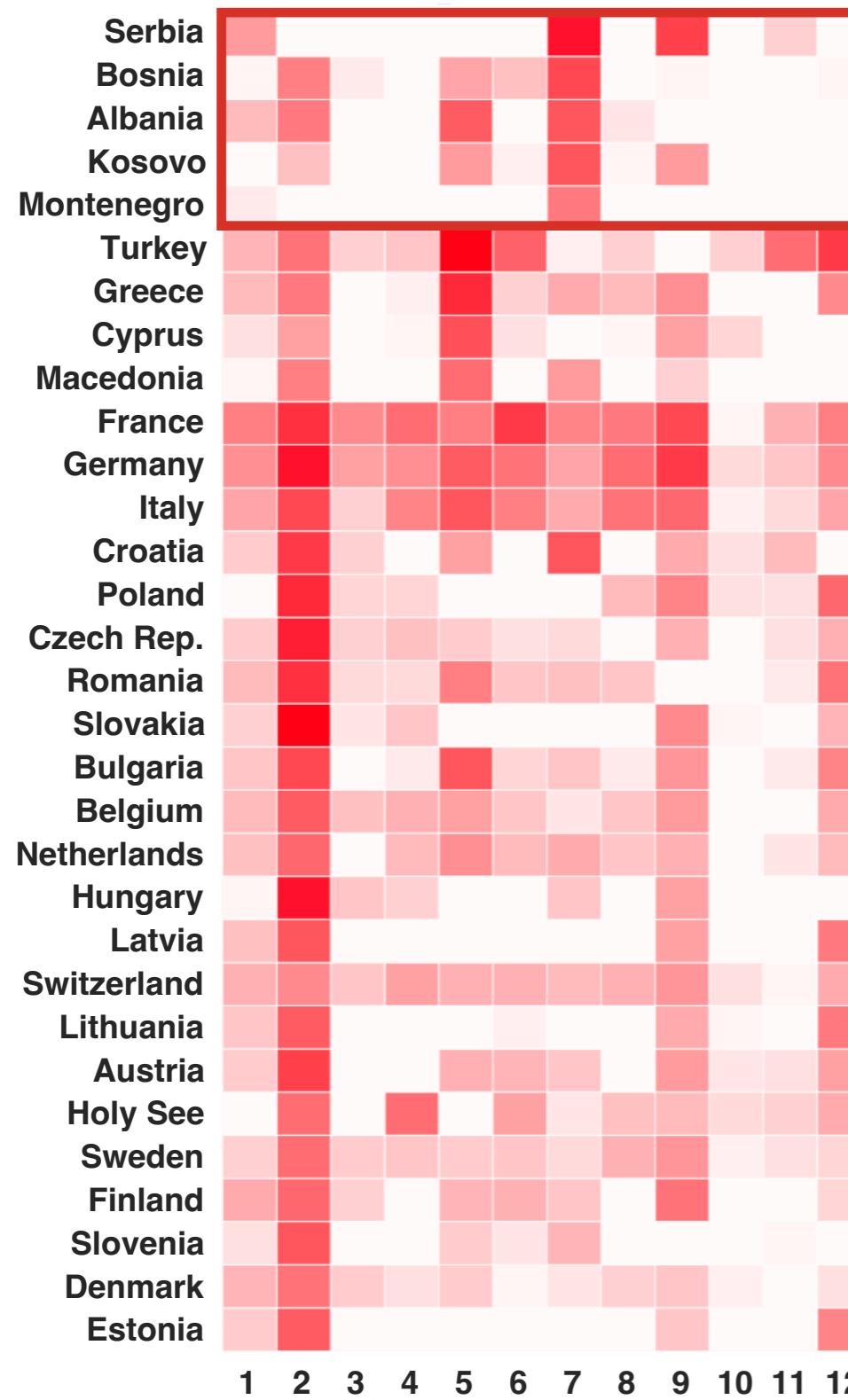
EXAMPLE RESULTS

- ▶ GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- ▶ Core size: (12 x 12 x 6 x 1)
- ▶ $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$



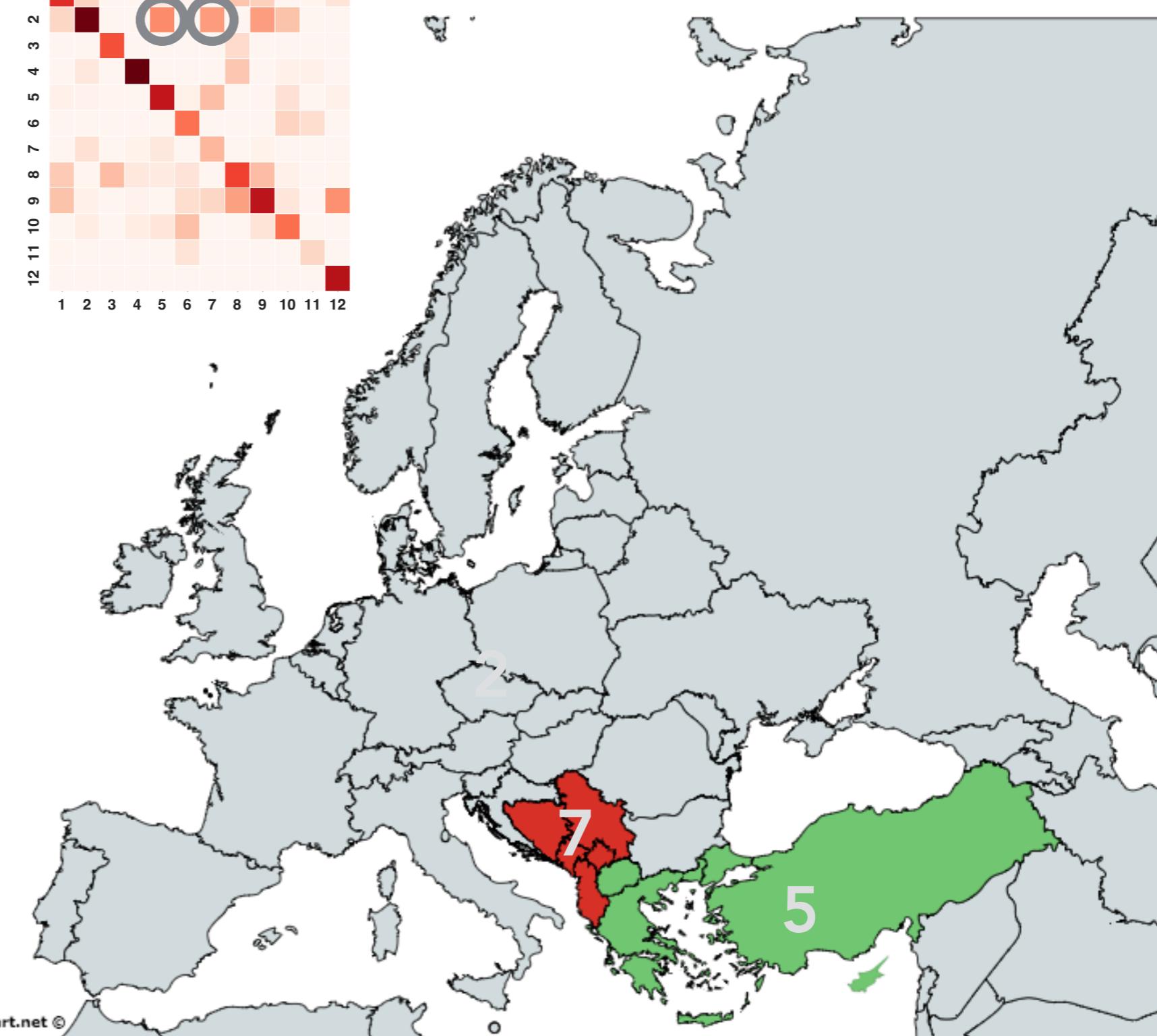
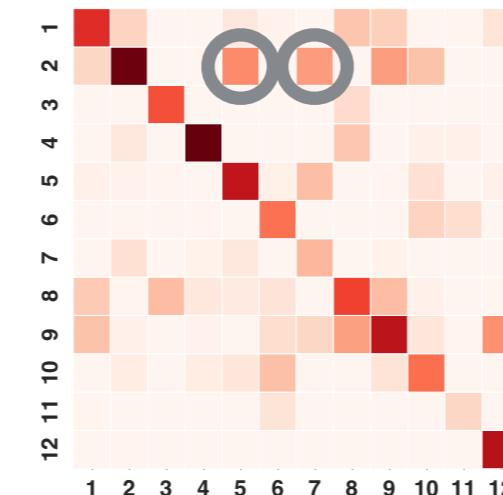
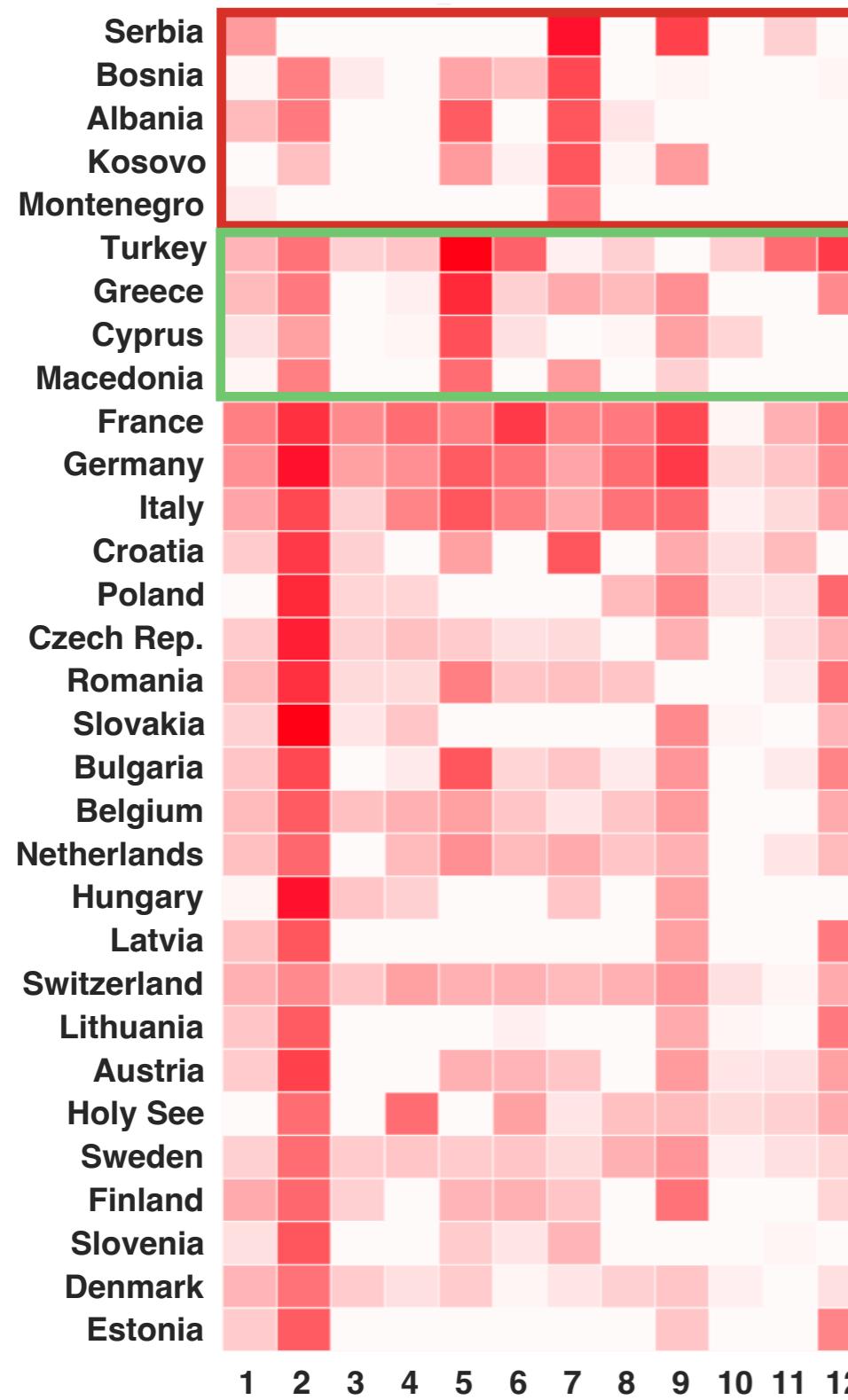
EXAMPLE RESULTS

- ▶ GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- ▶ Core size: (12 x 12 x 6 x 1)
- ▶ $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$



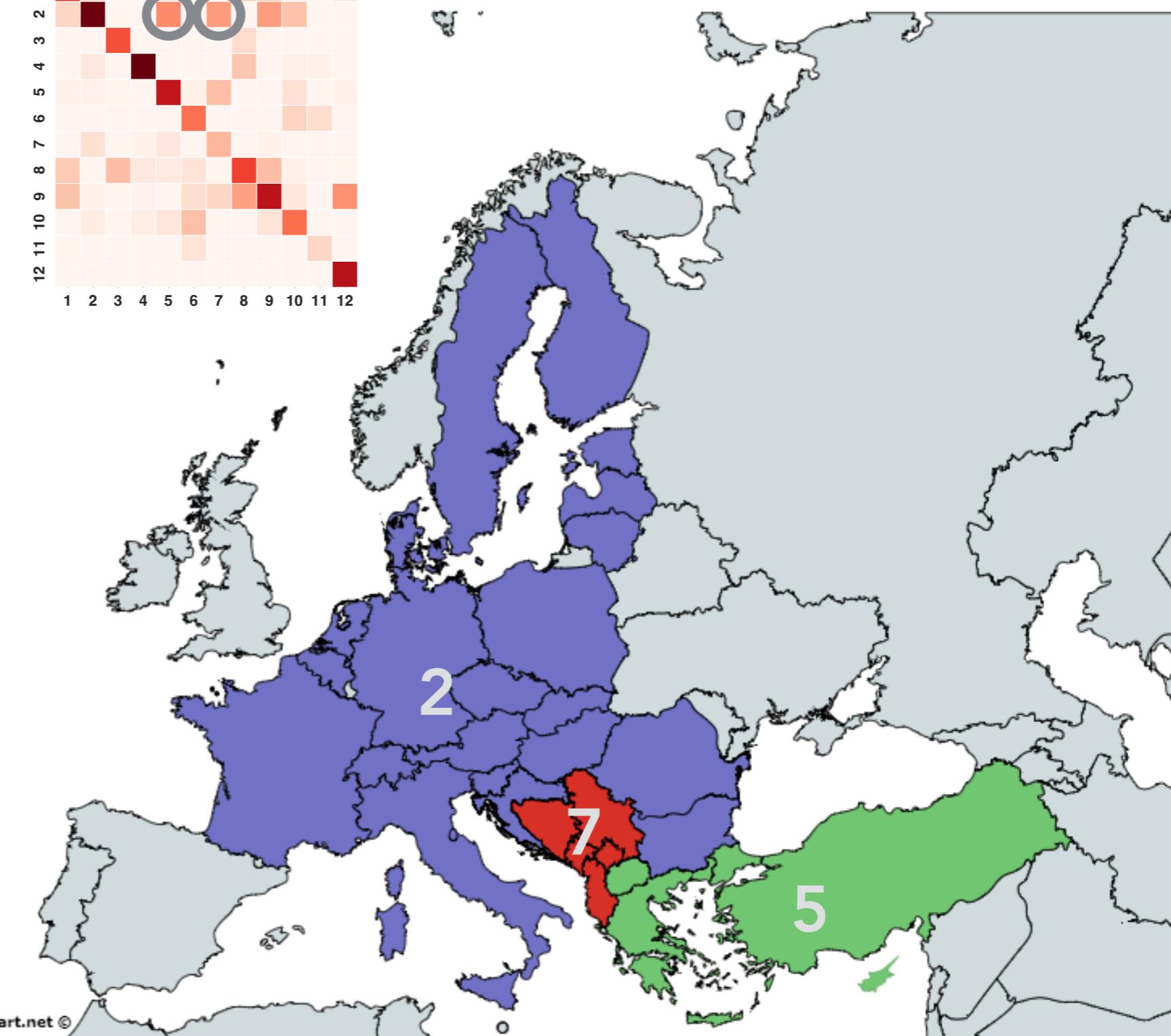
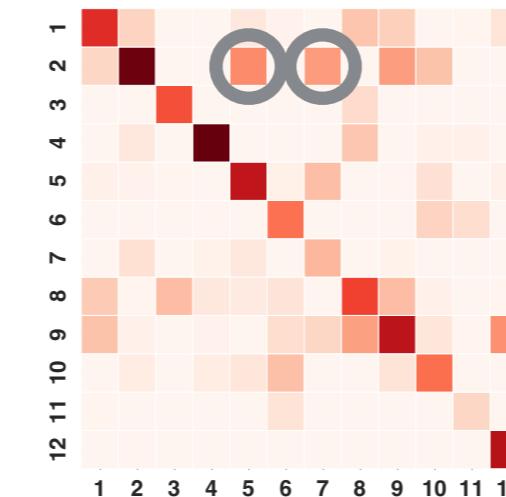
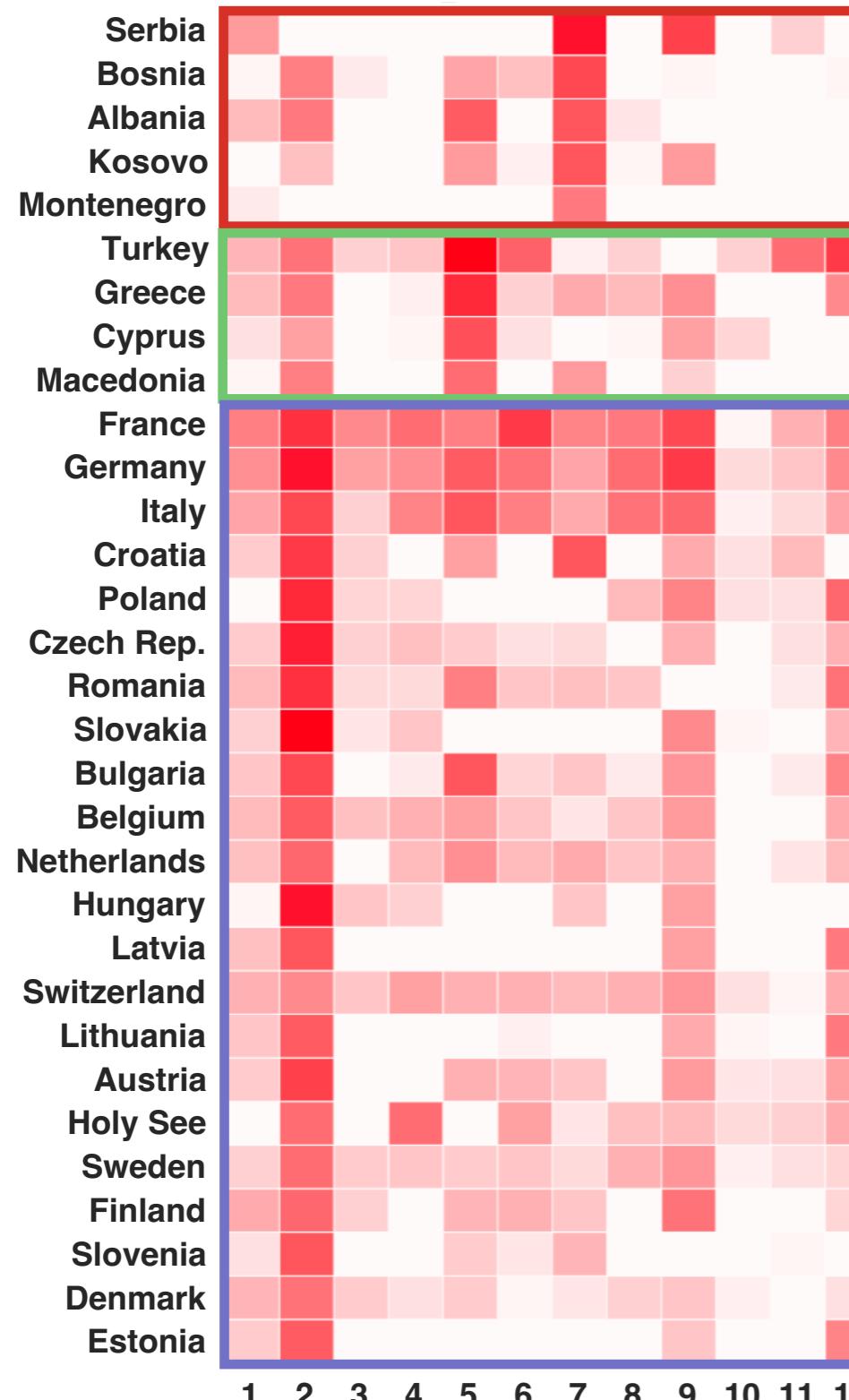
EXAMPLE RESULTS

- GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- Core size: (12 x 12 x 6 x 1)
- $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$



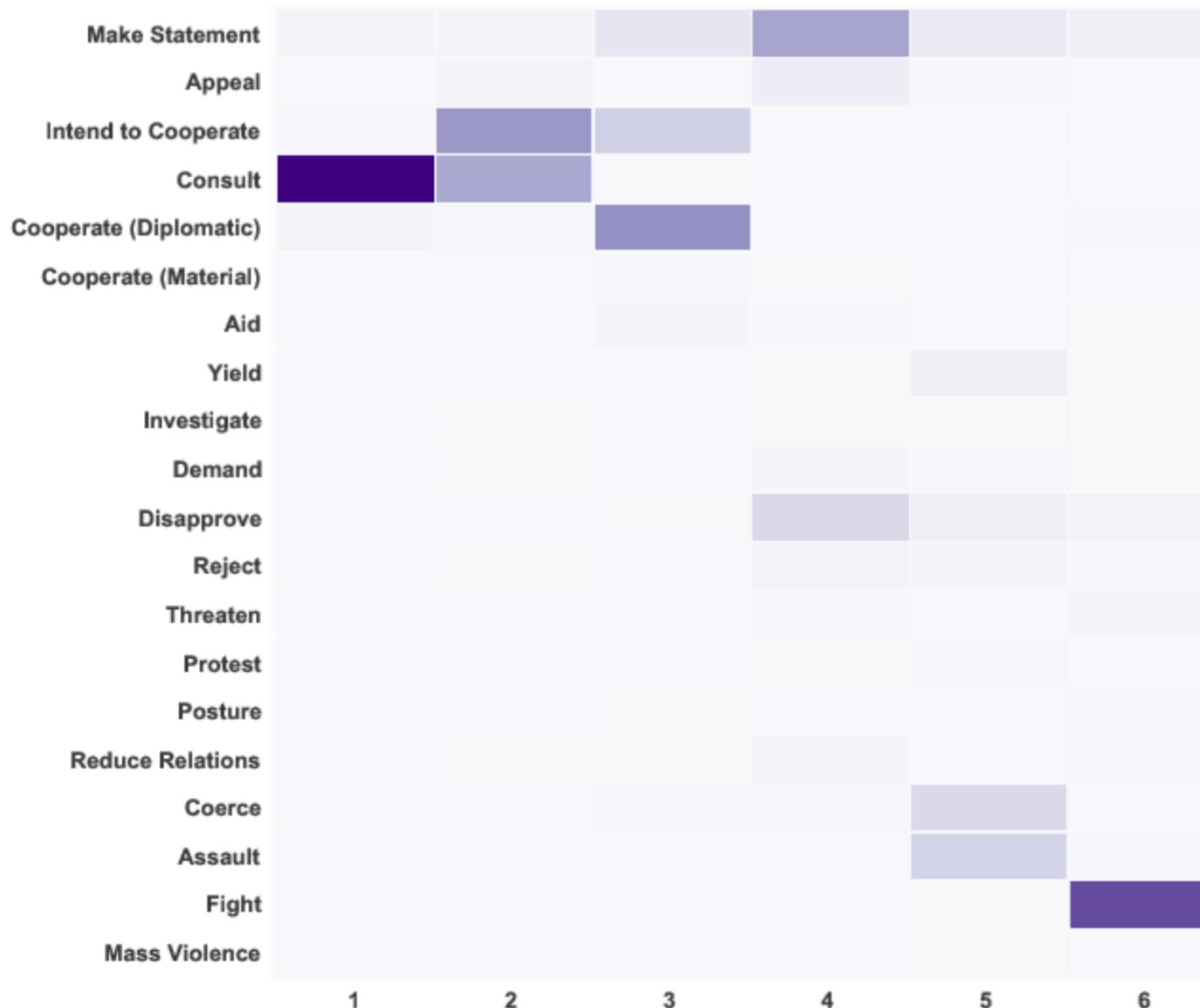
EXAMPLE RESULTS

- GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- Core size: (12 x 12 x 6 x 1)
- $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$



EXAMPLE RESULTS

- ▶ GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- ▶ Core size: (12 x 12 x 6 x 1)
- ▶ $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$



ϕ_{ak}

topics of actions

EXAMPLE RESULTS

- ▶ GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- ▶ Core size: (12 x 12 x 6 x 1)
- ▶ $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$



ϕ_{ak}

topics of actions

EXAMPLE RESULTS

- ▶ GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- ▶ Core size: (12 x 12 x 6 x 1)
- ▶ $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$

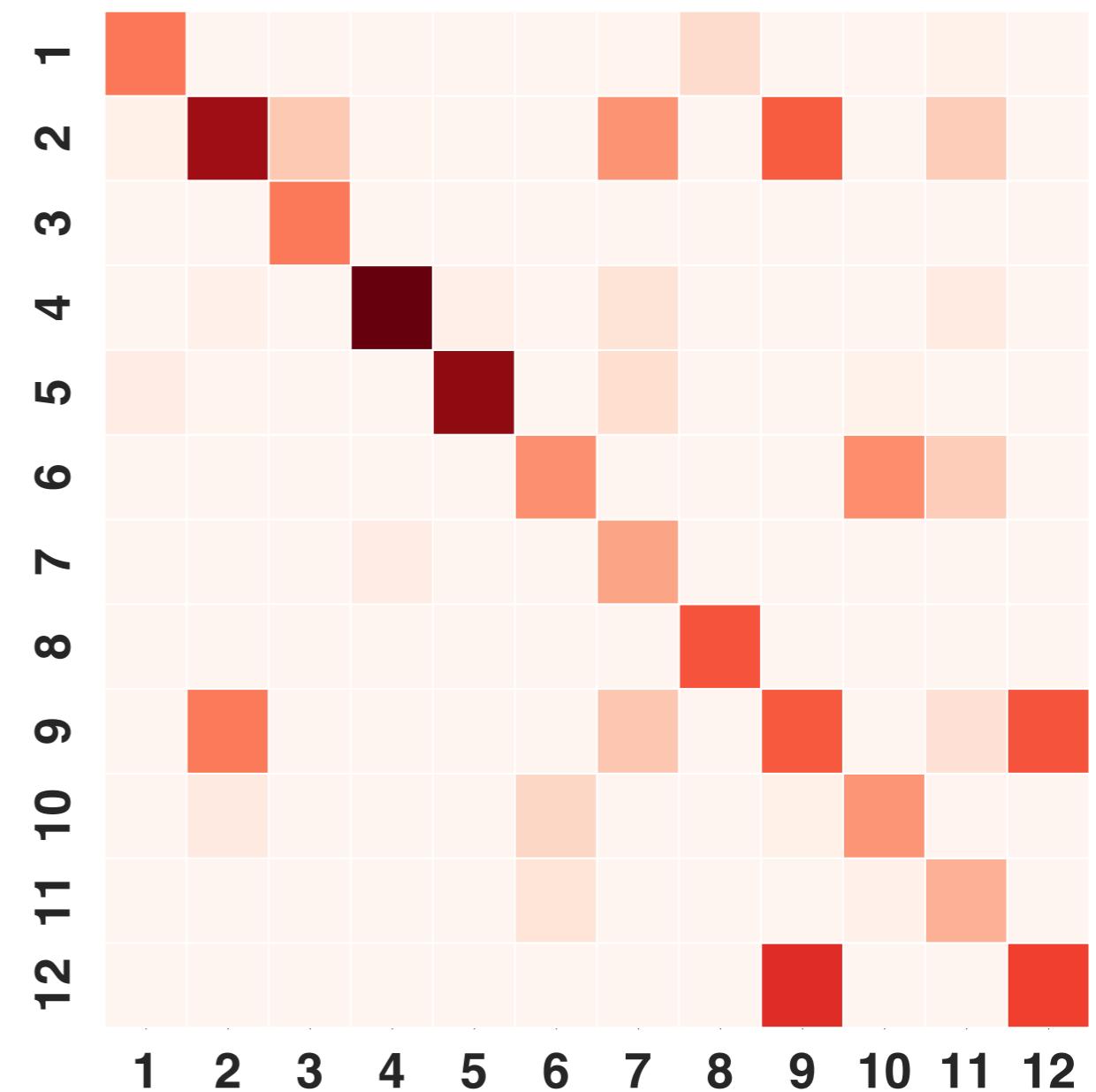


ϕ_{ak}
topics of actions

EXAMPLE RESULTS

- ▶ GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
 - ▶ Core size: (12 x 12 x 6 x 1)
 - ▶ $\Psi^{(\rightarrow)} \equiv \Psi^{(\leftarrow)} \equiv \Psi$

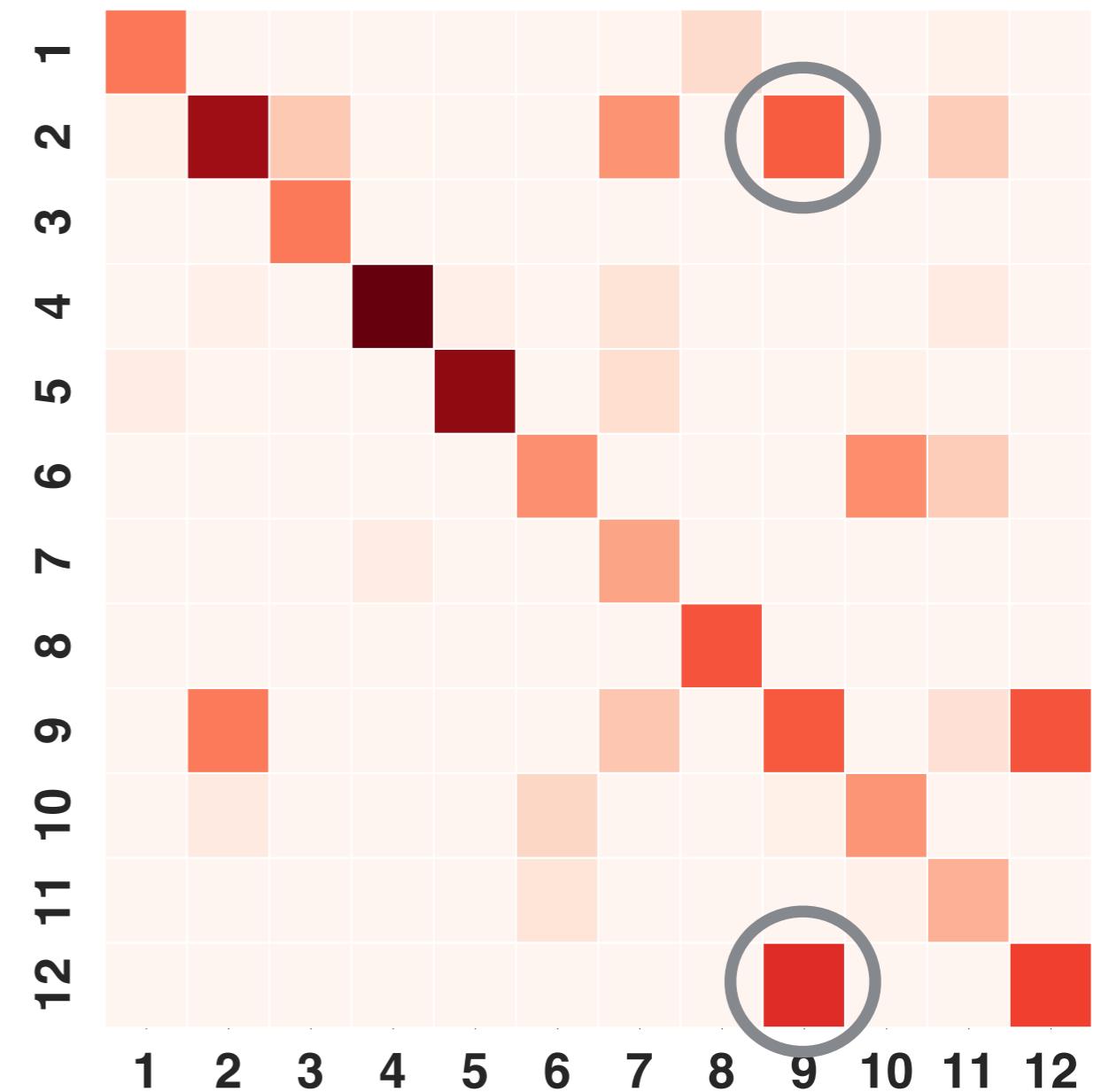
$$\lambda_{c \rightarrow d}^k \longrightarrow$$



EXAMPLE RESULTS

- ▶ GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
 - ▶ Core size: (12 x 12 x 6 x 1)
 - ▶ $\Psi^{(\rightarrow)} \equiv \Psi^{(\leftarrow)} \equiv \Psi$

$$\lambda_{c \rightarrow d}^k \longrightarrow$$

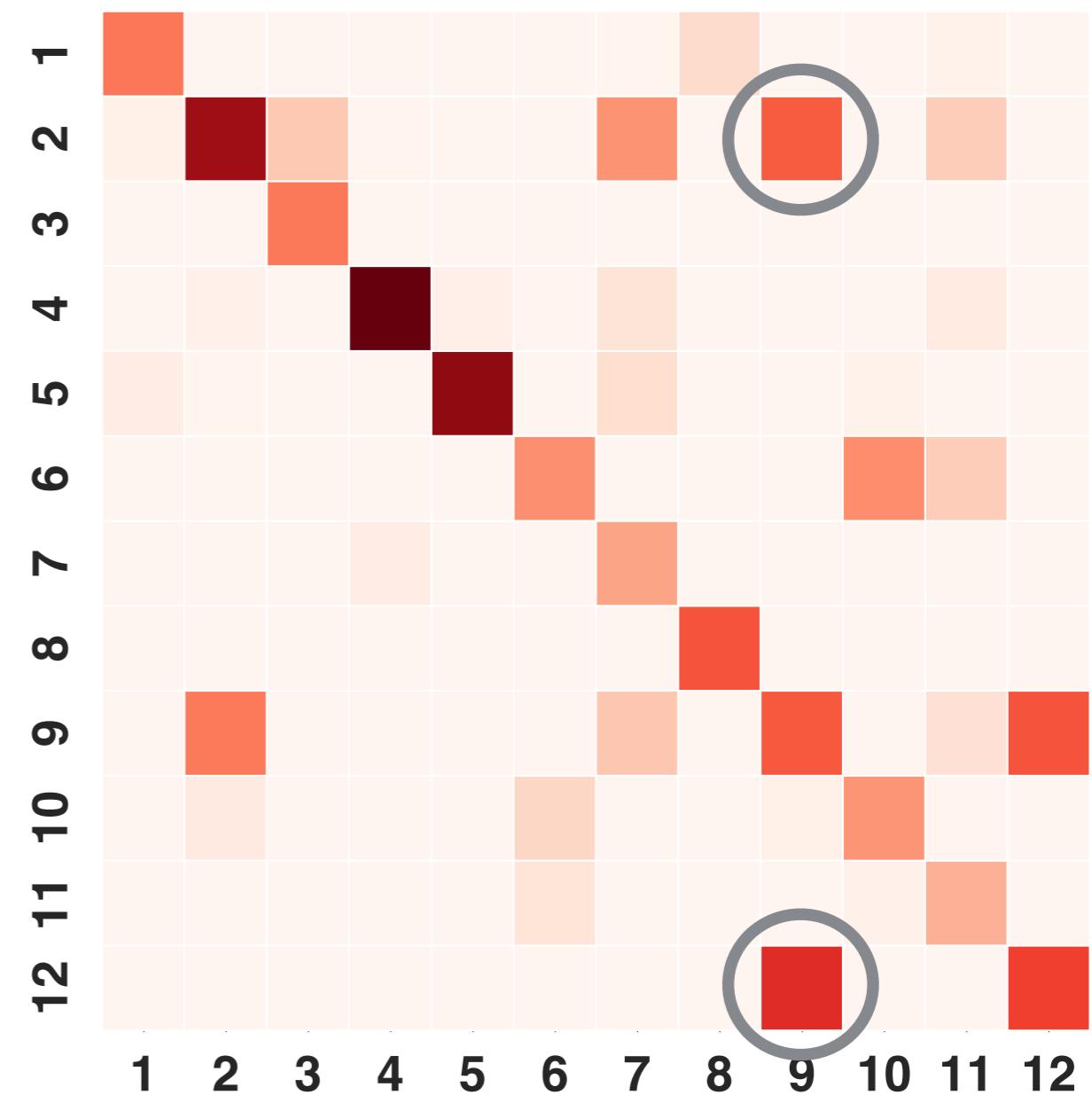


EXAMPLE RESULTS

- ▶ GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
 - ▶ Core size: (12 x 12 x 6 x 1)
 - ▶ $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$

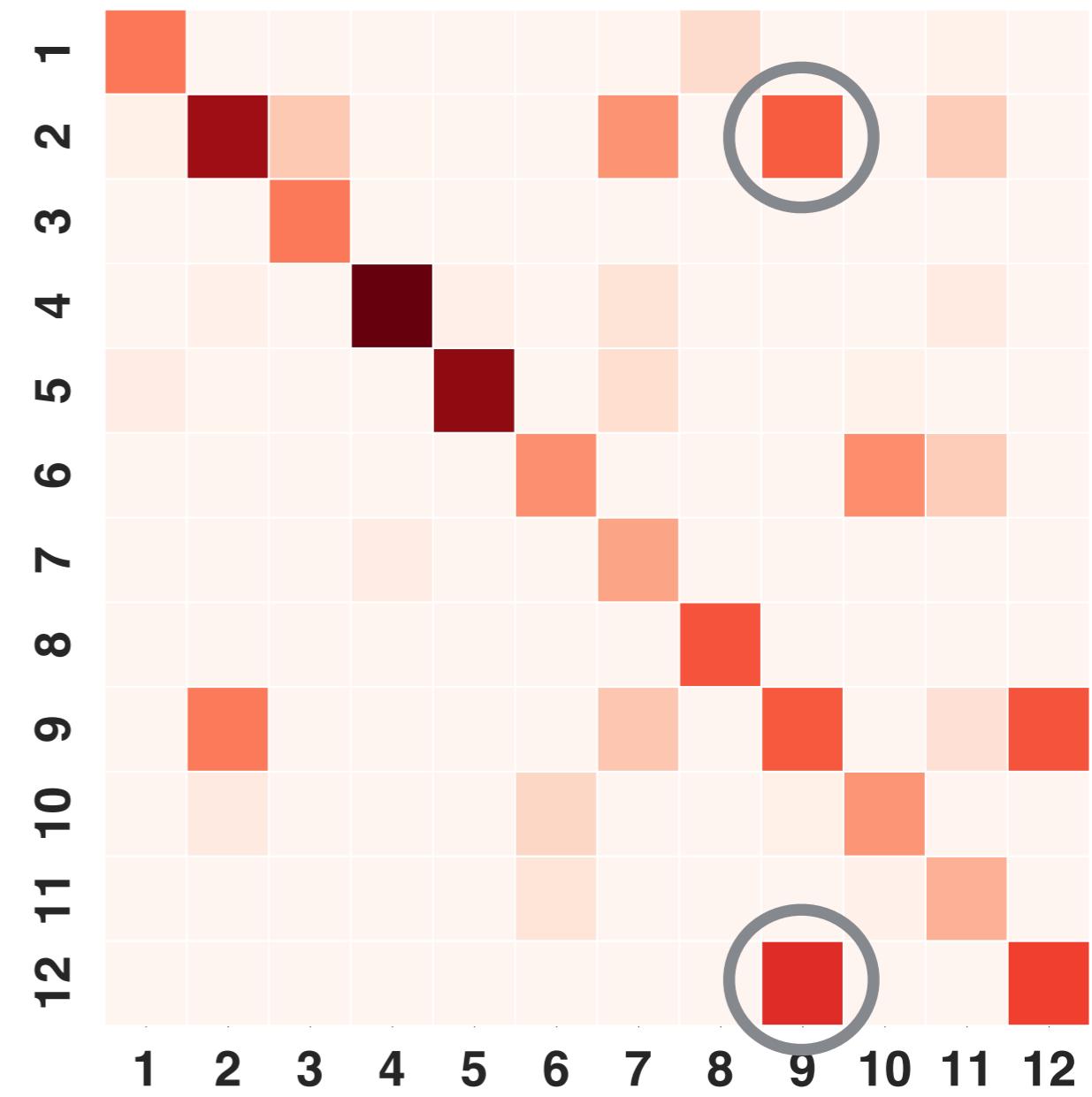
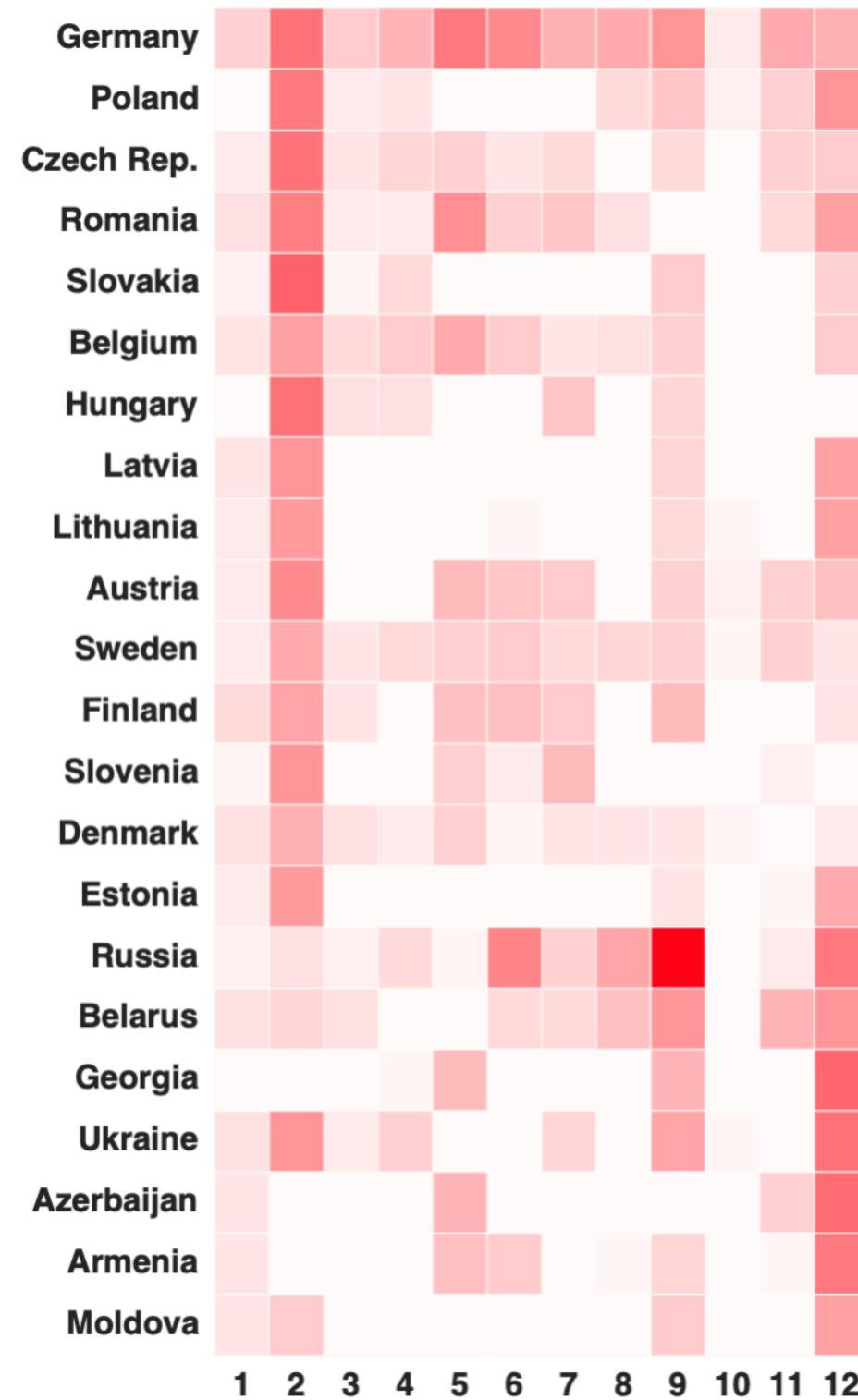
$$\lambda_{c \rightarrow d}^k \longrightarrow$$

Slice of core tensor for “Protest” topic k



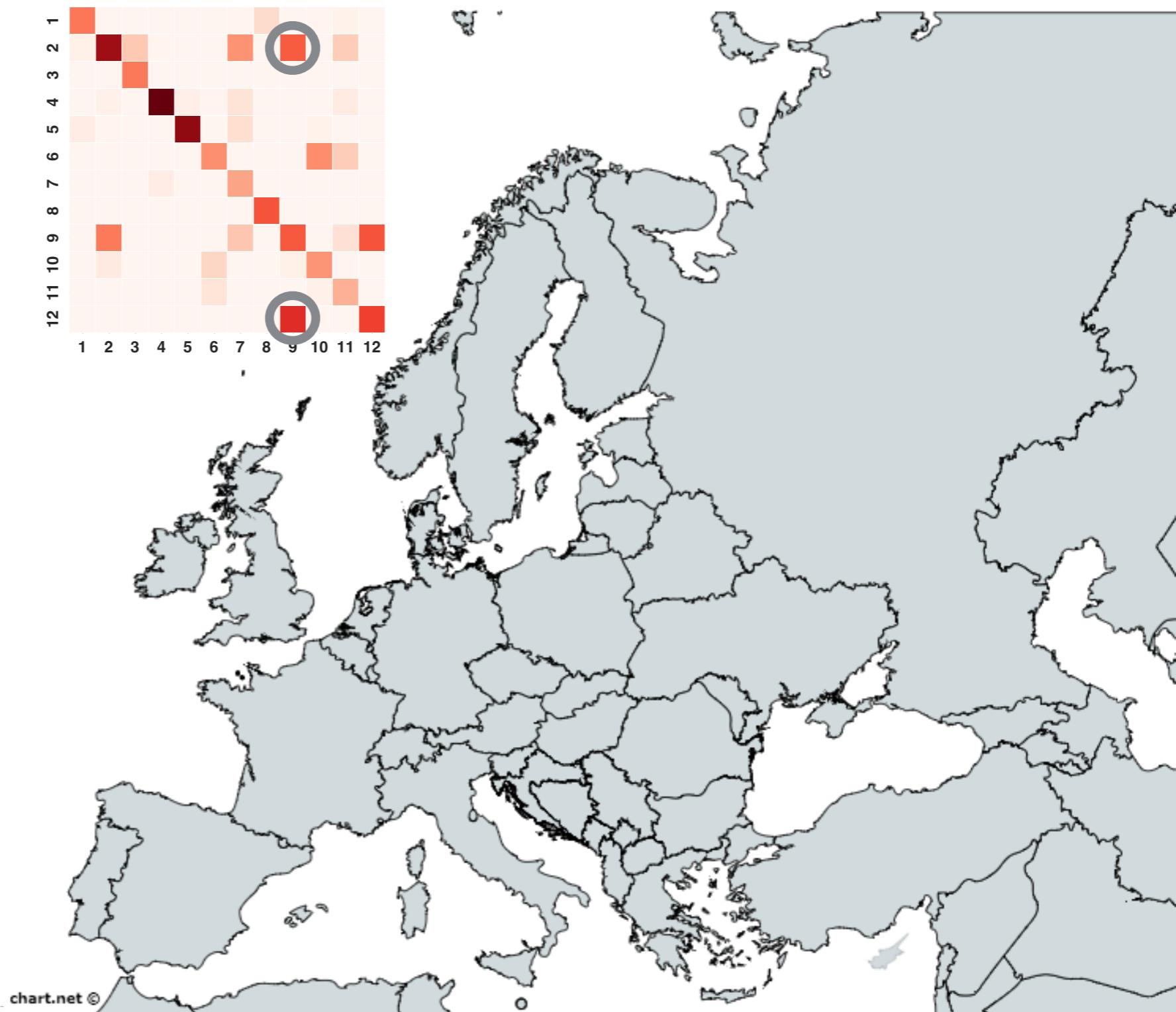
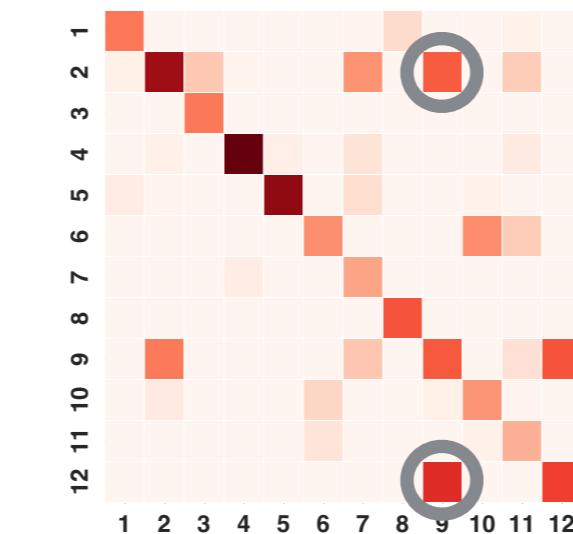
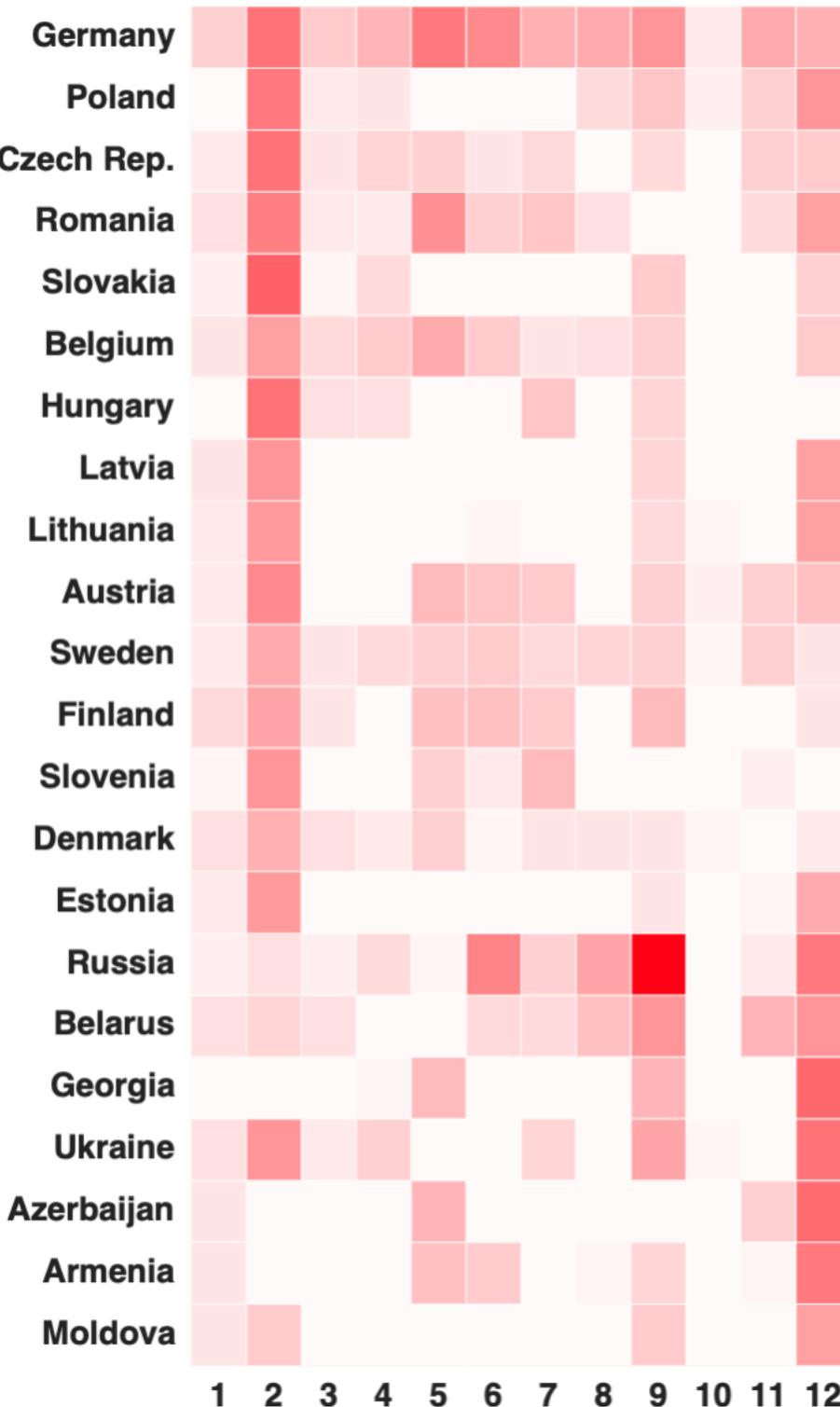
EXAMPLE RESULTS

- GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- Core size: (12 x 12 x 6 x 1)
- $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$



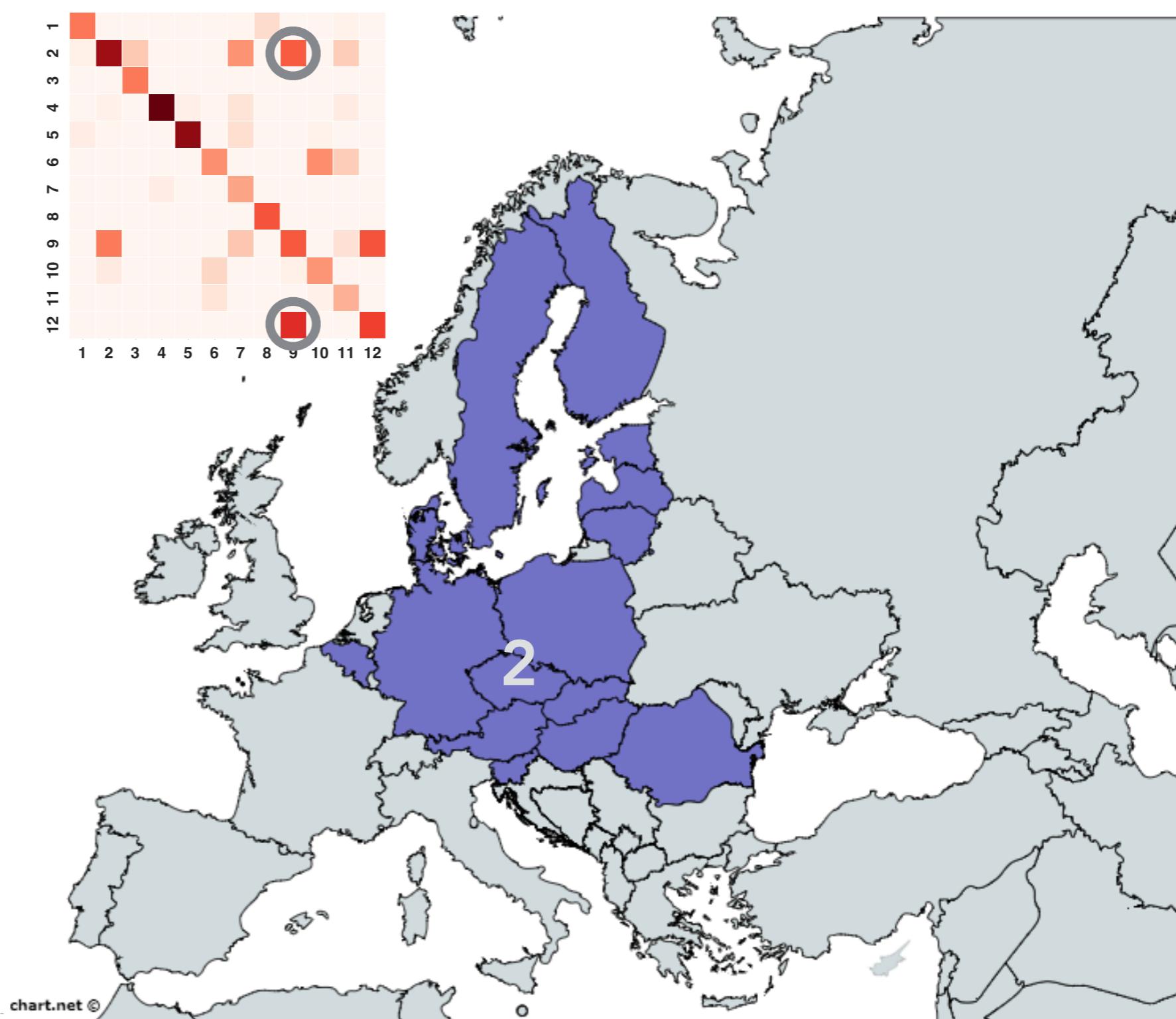
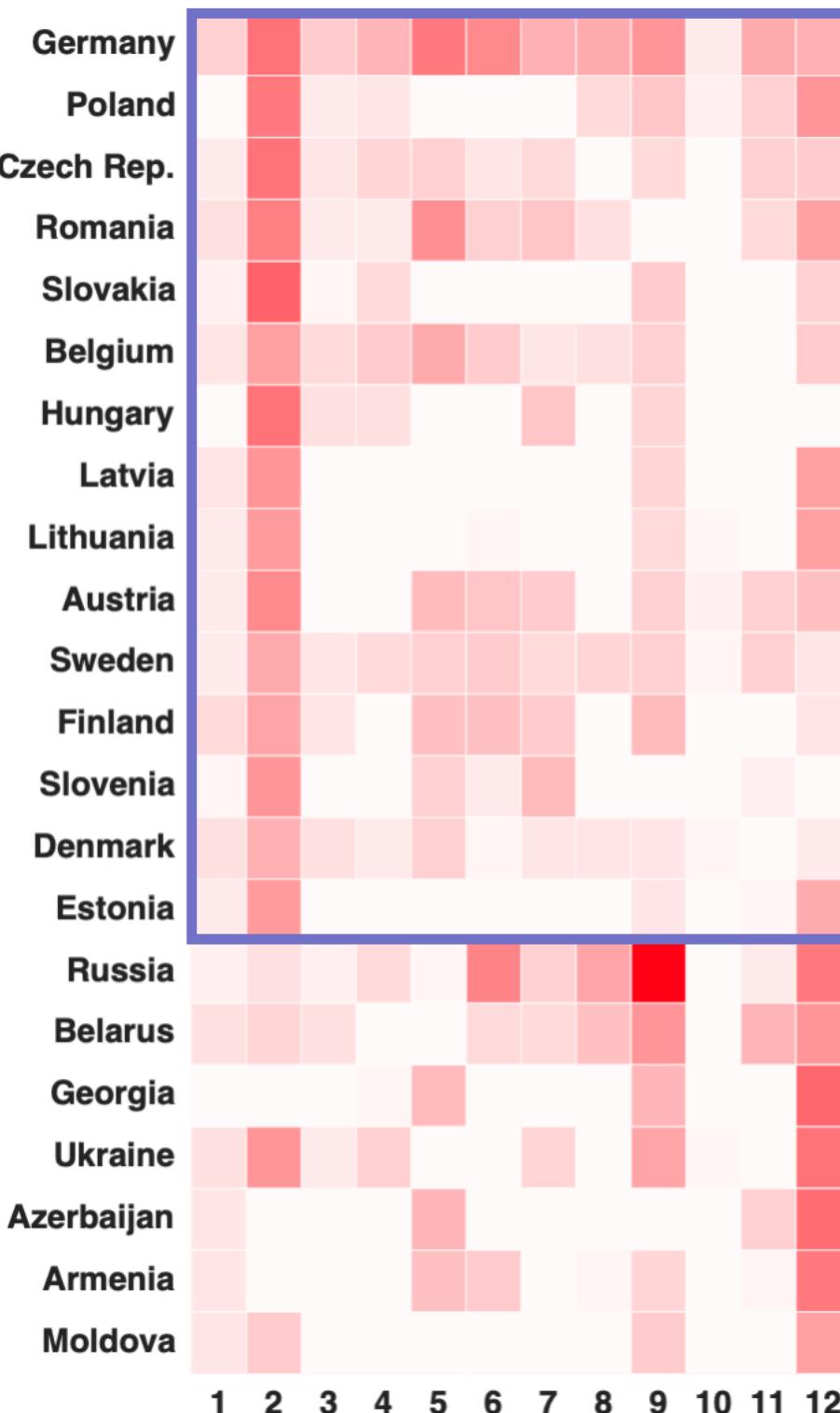
EXAMPLE RESULTS

- ▶ GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- ▶ Core size: (12 x 12 x 6 x 1)
- ▶ $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$



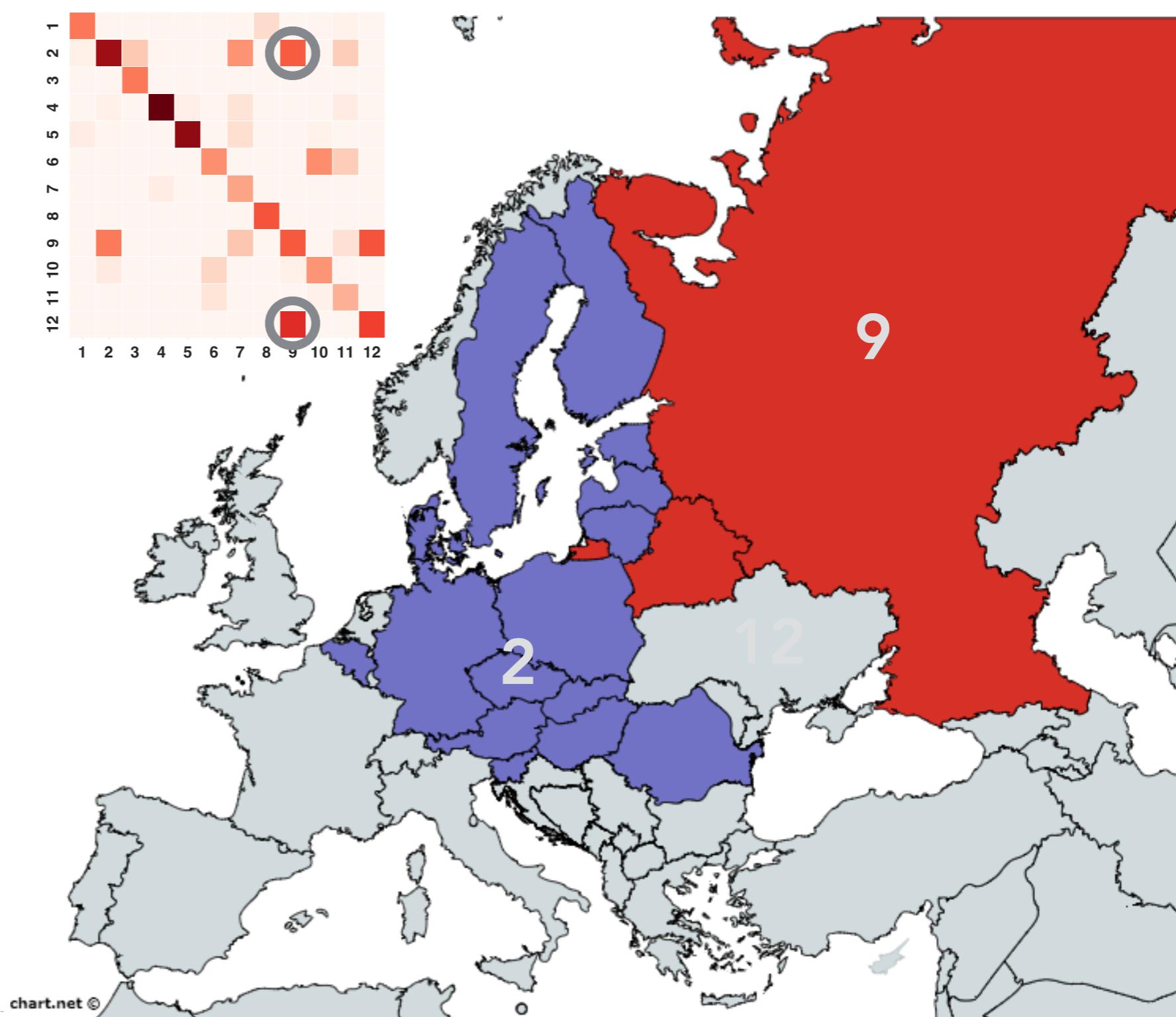
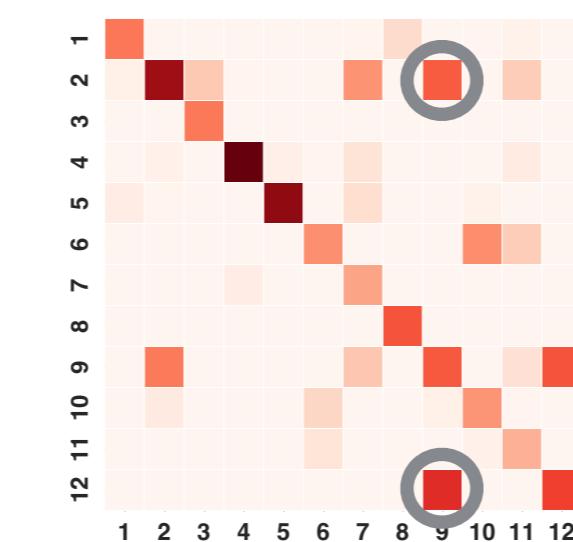
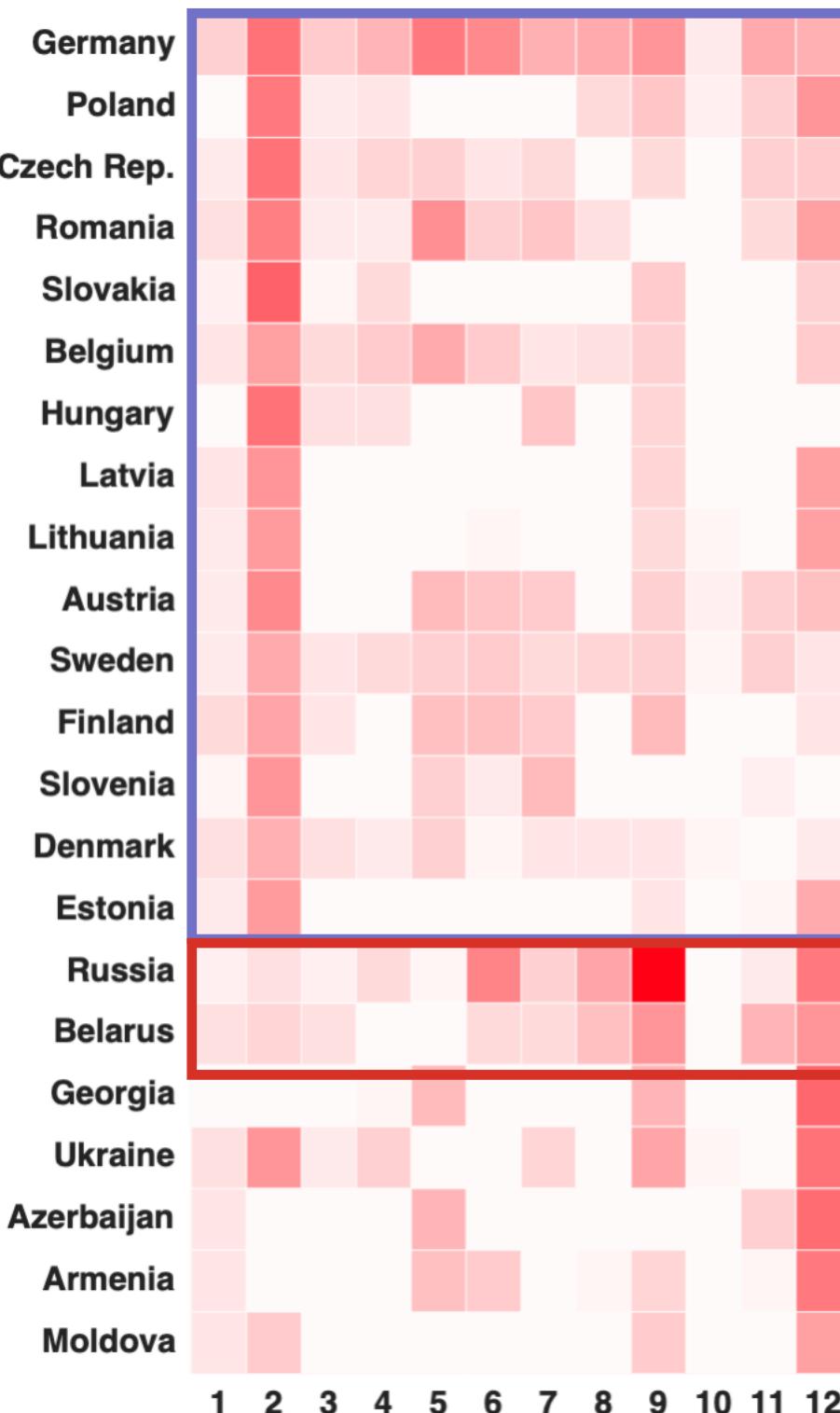
EXAMPLE RESULTS

- GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- Core size: (12 x 12 x 6 x 1)
- $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$



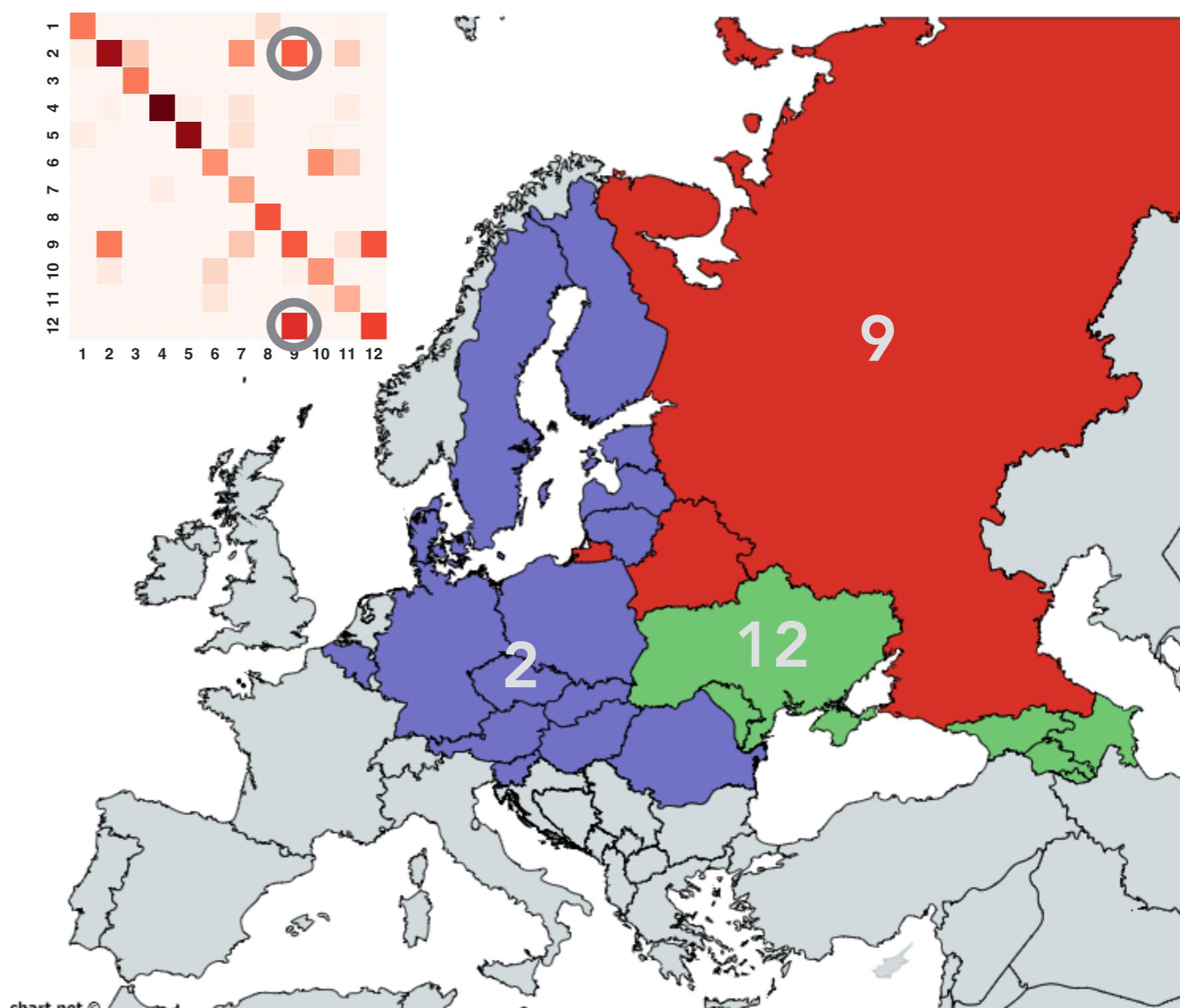
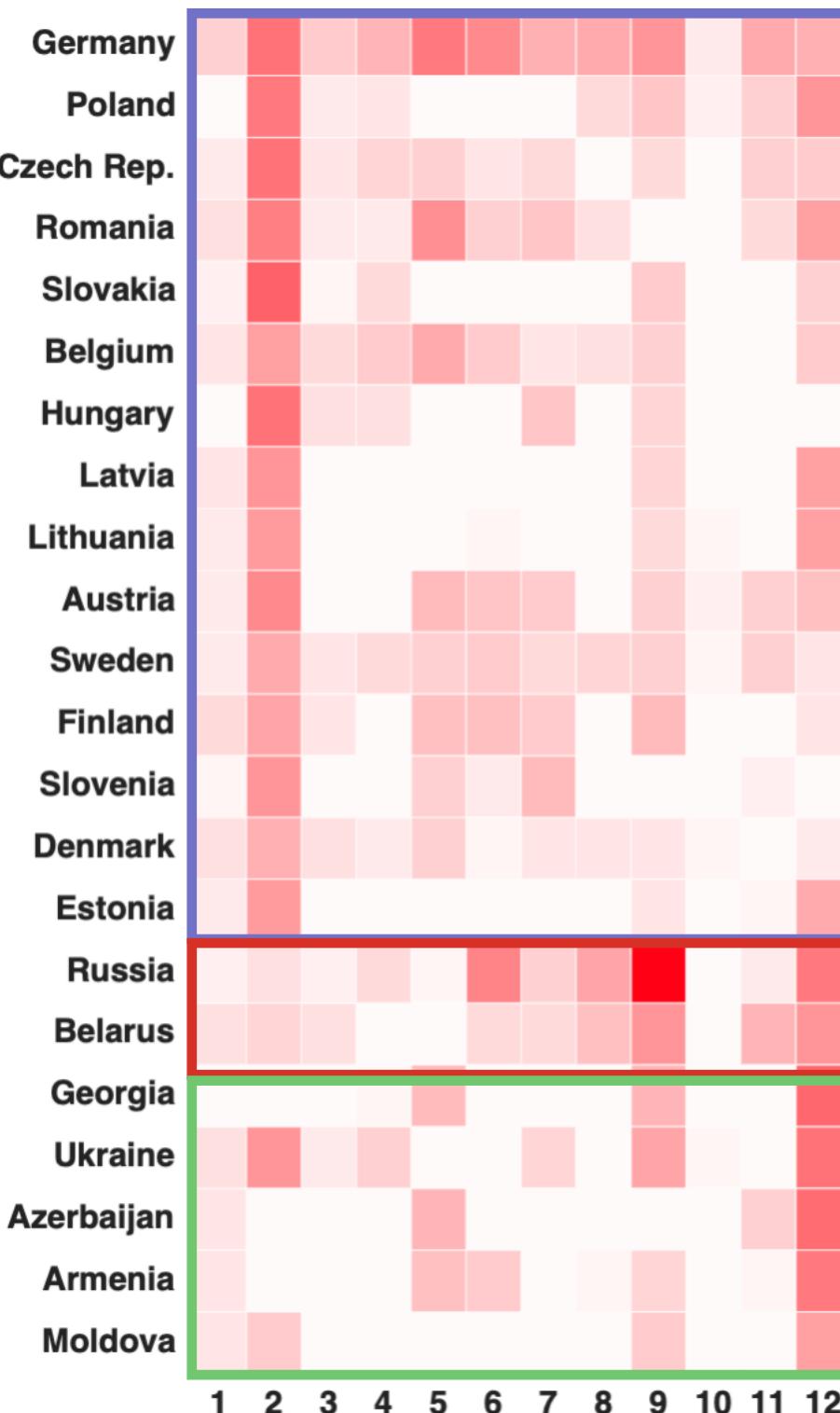
EXAMPLE RESULTS

- GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- Core size: (12 x 12 x 6 x 1)
- $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$



EXAMPLE RESULTS

- ▶ GDELT tensor (1995-2000), monthly: (150 x 150 x 20 x 60)
- ▶ Core size: (12 x 12 x 6 x 1)
- ▶ $\Psi^{(\rightarrow)} = \Psi^{(\leftarrow)} = \Psi$



OUTLINE

- ▶ Motivation: Dyadic event data (and its challenges)
- ▶ Non-negative (Poisson) tensor decompositions
 - ▶ CP extracts “multilateral” structure [Schein et al., 2015]
 - ▶ Tucker extracts “communities” [Schein et al., 2016]
 - ▶ Why (allocative) Poisson factorization
 - ▶ AL ℓ_0 CORE avoids the “exponential blowup” [Hood & Schein, 2024]

Appendix (*time permitting*)

- ▶ State-space modeling
 - ▶ Gamma state-space models [Schein et al., 2016b; Schein et al., 2019]
 - ▶ Modeling “escalation” with a new matrix prior [Stoehr et al., 2023]

OUTLINE

- ▶ Motivation: Dyadic event data (and its challenges)
- ▶ Non-negative (Poisson) tensor decompositions
 - ▶ CP extracts “multilateral” structure [Schein et al., 2015]
 - ▶ Tucker extracts “communities” [Schein et al., 2016]
 - ▶ Why (allocative) Poisson factorization
 - ▶ AL ℓ_0 CORE avoids the “exponential blowup” [Hood & Schein, 2024]

Appendix (*time permitting*)

- ▶ State-space modeling
 - ▶ Gamma state-space models [Schein et al., 2016b; Schein et al., 2019]
 - ▶ Modeling “escalation” with a new matrix prior [Stoehr et al., 2023]

ALLOCATIVE POISSON FACTORIZATION

All previous models were an instance of:

$$y_{\mathbf{i}} \sim \text{Pois}(\mu_{\mathbf{i}})$$

Poisson counts

$$\mathbf{i} \equiv (\mathbf{i}_1, \dots, \mathbf{i}_M)$$

multi-index

$$\mu_{\mathbf{i}} = \sum_{\kappa} \mu_{\mathbf{i}, \kappa}$$

linear function of parameters

ALLOCATIVE POISSON FACTORIZATION

All previous models were an instance of:

$$y_{\mathbf{i}} \sim \text{Pois}(\mu_{\mathbf{i}})$$

Poisson counts

$$\mathbf{i} \equiv (\mathbf{i}_1, \dots, \mathbf{i}_M)$$

multi-index

$$\mu_{\mathbf{i}} = \sum_{\kappa} \mu_{\mathbf{i}, \kappa}$$

linear function of parameters

e.g., Poisson CP decomposition for 4-mode dyadic event data

$$y_{i \rightarrow j}^{(t)} \sim \text{Pois}\left(\mu_{i \rightarrow j}^{(t)}\right) \quad \mathbf{i} \equiv (i, j, a, t) \quad \mu_{i \rightarrow j}^{(t)} = \sum_{q=1}^Q \psi_{iq}^{(\rightarrow)} \psi_{jq}^{(\leftarrow)} \phi_{aq} \theta_q^{(t)} \lambda_q$$

ALLOCATIVE POISSON FACTORIZATION

All previous models were an instance of:

$$y_{\mathbf{i}} \sim \text{Pois}(\mu_{\mathbf{i}})$$

Poisson counts

$$\mathbf{i} \equiv (\mathbf{i}_1, \dots, \mathbf{i}_M)$$

multi-index

$$\mu_{\mathbf{i}} = \sum_{\kappa} \mu_{\mathbf{i}, \kappa}$$

linear function of parameters

e.g., Poisson CP decomposition for 4-mode dyadic event data

$$y_{i \rightarrow j}^{(t)} \sim \text{Pois}\left(\mu_{i \rightarrow j}^{(t)}\right) \quad \mathbf{i} \equiv (i, j, a, t) \quad \mu_{i \rightarrow j}^{(t)} = \sum_{q=1}^Q \psi_{iq}^{(\rightarrow)} \psi_{jq}^{(\leftarrow)} \phi_{aq} \theta_q^{(t)} \lambda_q$$

e.g., Poisson Tucker decomposition for 4-mode dyadic event data

$$y_{i \rightarrow j}^{(t)} \sim \text{Pois}\left(\mu_{i \rightarrow j}^{(t)}\right) \quad \mathbf{i} \equiv (i, j, a, t) \quad \mu_{i \rightarrow j}^{(t)} = \sum_{c,d,k,r} \psi_{ic}^{(\rightarrow)} \psi_{jd}^{(\leftarrow)} \phi_{ak} \theta_r^{(t)} \lambda_{c \rightarrow d}^{(r)}$$

ALLOCATIVE POISSON FACTORIZATION

“Latent source” representation [Dunson & Herring, (2005); Cemgil (2009)]:

ALLOCATIVE POISSON FACTORIZATION

“**Latent source**” representation [Dunson & Herring, (2005); Cemgil (2009)]:

$$y_{\mathbf{i}} \sim \text{Pois}\left(\sum_{\kappa} \mu_{\mathbf{i}, \kappa}\right) \quad \leftrightarrow \quad y_{\mathbf{i}} = \sum_{\kappa} y_{\mathbf{i}, \kappa} \text{ where } y_{\mathbf{i}, \kappa} \sim \text{Pois}(\mu_{\mathbf{i}, \kappa})$$

Observed counts **Latent** sub-counts (“sources”)

Inference (MCMC, VI, EM, ...) in these models takes the following form:

Step 1: Given data $y_{\mathbf{i}}$, infer sources $(y_{\mathbf{i}, \kappa})_{\kappa}$:

$$(y_{\mathbf{i}, \kappa})_{\kappa} \mid y_{\mathbf{i}} \sim \text{Multinomial}\left(y_{\mathbf{i}}, \left(\frac{\mu_{\mathbf{i}, \kappa}}{\sum_{\kappa'} \mu_{\mathbf{i}, \kappa'}}\right)_{\kappa}\right)$$

ALLOCATIVE POISSON FACTORIZATION

“**Latent source**” representation [Dunson & Herring, (2005); Cemgil (2009)]:

Inference (MCMC, VI, EM, ...) in these models takes the following form:

Step 1: Given data y_i , infer sources $(y_{i,k})_k$:

$$\left(y_{\mathbf{i}, \kappa}\right)_\kappa \mid y_{\mathbf{i}} \sim \text{Multinomial}\left(y_{\mathbf{i}}, \left(\frac{\mu_{\mathbf{i}, \kappa}}{\sum_{\kappa'} \mu_{\mathbf{i}, \kappa'}}\right)_\kappa\right)$$

Step 2: Given sources $(y_{i,k})_k$, update parameters.

ALLOCATIVE POISSON FACTORIZATION

“**Latent source**” representation [Dunson & Herring, (2005); Cemgil (2009)]:

$$y_{\mathbf{i}} \sim \text{Pois}\left(\sum_{\kappa} \mu_{\mathbf{i}, \kappa}\right) \quad \leftrightarrow \quad y_{\mathbf{i}} = \sum_{\kappa} y_{\mathbf{i}, \kappa} \text{ where } y_{\mathbf{i}, \kappa} \sim \text{Pois}(\mu_{\mathbf{i}, \kappa})$$

Observed counts **Latent** sub-counts (“sources”)

Inference (MCMC, VI, EM, ...) in these models takes the following form:

Step 1: Given data $y_{\mathbf{i}}$, infer sources $(y_{\mathbf{i}, \kappa})_{\kappa}$:

$$(y_{\mathbf{i}, \kappa})_{\kappa} \mid y_{\mathbf{i}} \sim \text{Multinomial}\left(y_{\mathbf{i}}, \left(\frac{\mu_{\mathbf{i}, \kappa}}{\sum_{\kappa'} \mu_{\mathbf{i}, \kappa'}}\right)_{\kappa}\right)$$

Step 2: Given sources $(y_{\mathbf{i}, \kappa})_{\kappa}$, update parameters.

(Repeat)

ALLOCATIVE POISSON FACTORIZATION

“**Latent source**” representation [Dunson & Herring, (2005); Cemgil (2009)]:

$$y_{\mathbf{i}} \sim \text{Pois}\left(\sum_{\kappa} \mu_{\mathbf{i}, \kappa}\right) \quad \leftrightarrow \quad y_{\mathbf{i}} = \sum_{\kappa} y_{\mathbf{i}, \kappa} \text{ where } y_{\mathbf{i}, \kappa} \sim \text{Pois}(\mu_{\mathbf{i}, \kappa})$$

Observed counts **Latent** sub-counts (“sources”)

Inference (MCMC, VI, EM, ...) in these models takes the following form:

Step 1: Given data $y_{\mathbf{i}}$, infer sources $(y_{\mathbf{i}, \kappa})_{\kappa}$:

$$(y_{\mathbf{i}, \kappa})_{\kappa} \mid y_{\mathbf{i}} \sim \text{Multinomial}\left(y_{\mathbf{i}}, \left(\frac{\mu_{\mathbf{i}, \kappa}}{\sum_{\kappa'} \mu_{\mathbf{i}, \kappa'}}\right)_{\kappa}\right)$$

Step 2: Given sources $(y_{\mathbf{i}, \kappa})_{\kappa}$, update parameters.

Tends to be simple / inexpensive / parallelizable
(e.g., with conditionally conjugate priors).

(Repeat)

ALLOCATIVE POISSON FACTORIZATION

“**Latent source**” representation [Dunson & Herring, (2005); Cemgil (2009)]:

Inference (MCMC, VI, EM, ...) in these models takes the following form:

Step 1: Given data y_i , infer sources $(y_{i,k})_k$:

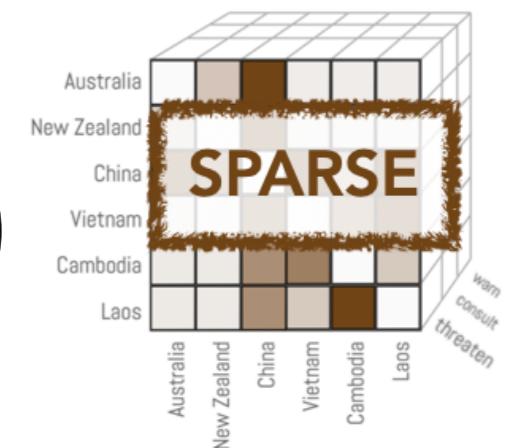
$$\left(y_{\mathbf{i}, \kappa}\right)_\kappa \mid y_{\mathbf{i}} \sim \text{Multinomial}\left(y_{\mathbf{i}}, \left(\frac{\mu_{\mathbf{i}, \kappa}}{\sum_{\kappa'} \mu_{\mathbf{i}, \kappa'}}\right)_\kappa\right)$$

Scales with **only the non-zeros**.

Step 2: Given sources $(y_{i,k})_k$, update parameters.

Tends to be simple / inexpensive / parallelizable
(e.g., with conditionally conjugate priors).

(Repeat)

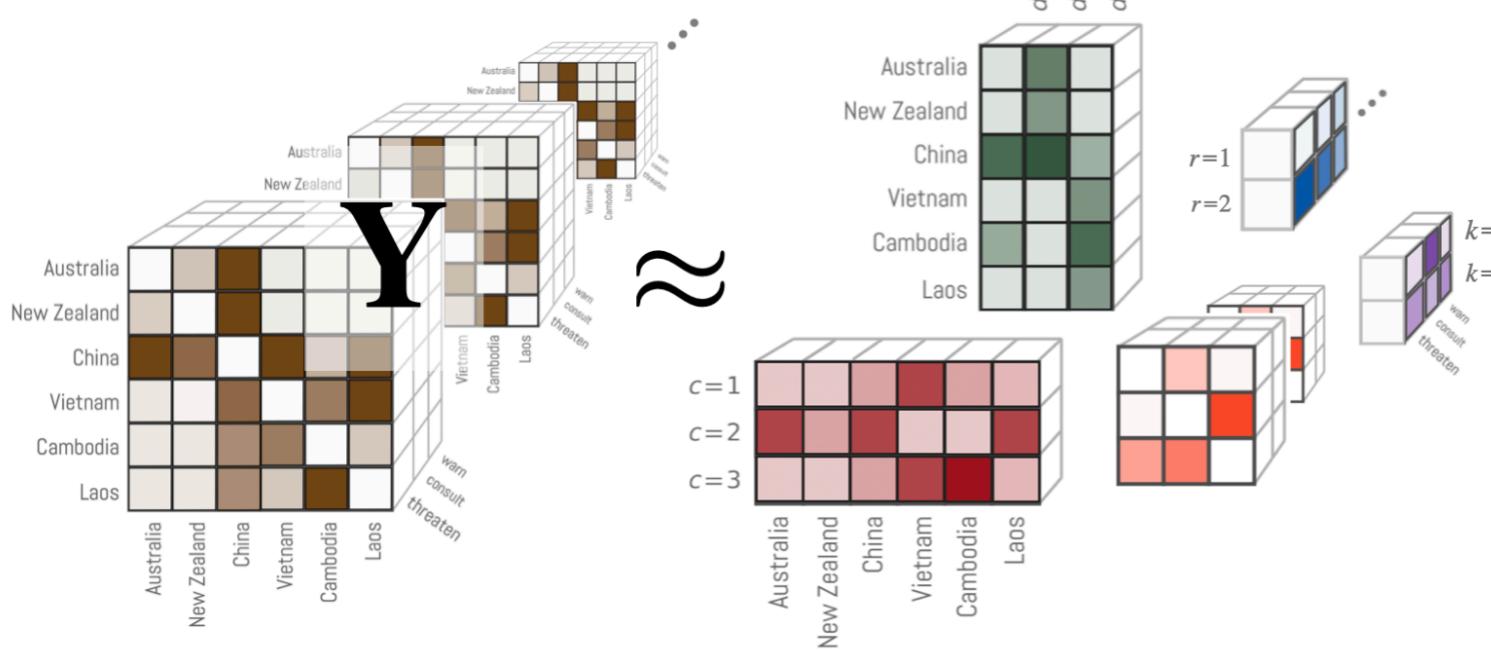


ALLOCATIVE POISSON FACTORIZATION

“**Latent source**” representation [Dunson & Herring, (2005); Cemgil (2009)]:

Decomposition of a tensor

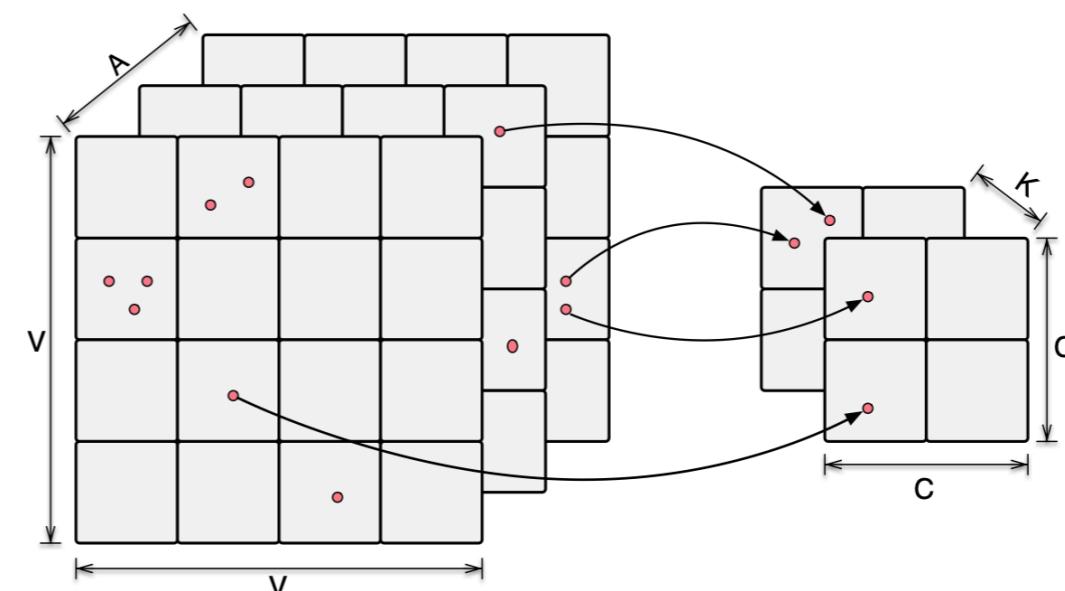
coincides with...



...latent class allocation of its tokens

Table 2
WEIS Coding of 1990 Iraq-Kuwait Crisis

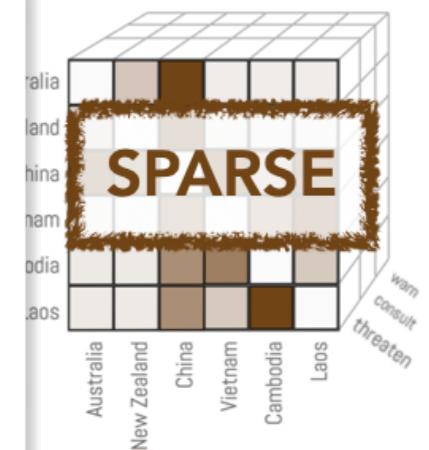
Date	Source	Target	Type of Action
900717	IRQ	KUW	CHARGE
900725	IRQ	EGY	ASSURE
900727	IRQ	KUW	WARN
900731	IRQ	KUW	MOBILIZATION
900801	KUW	IRQ	REFUSE
900802	IRQ	KUW	MILITARY FORCE



$\text{Pois}(\mu_{i,k})$

(“sources”)

ing form:



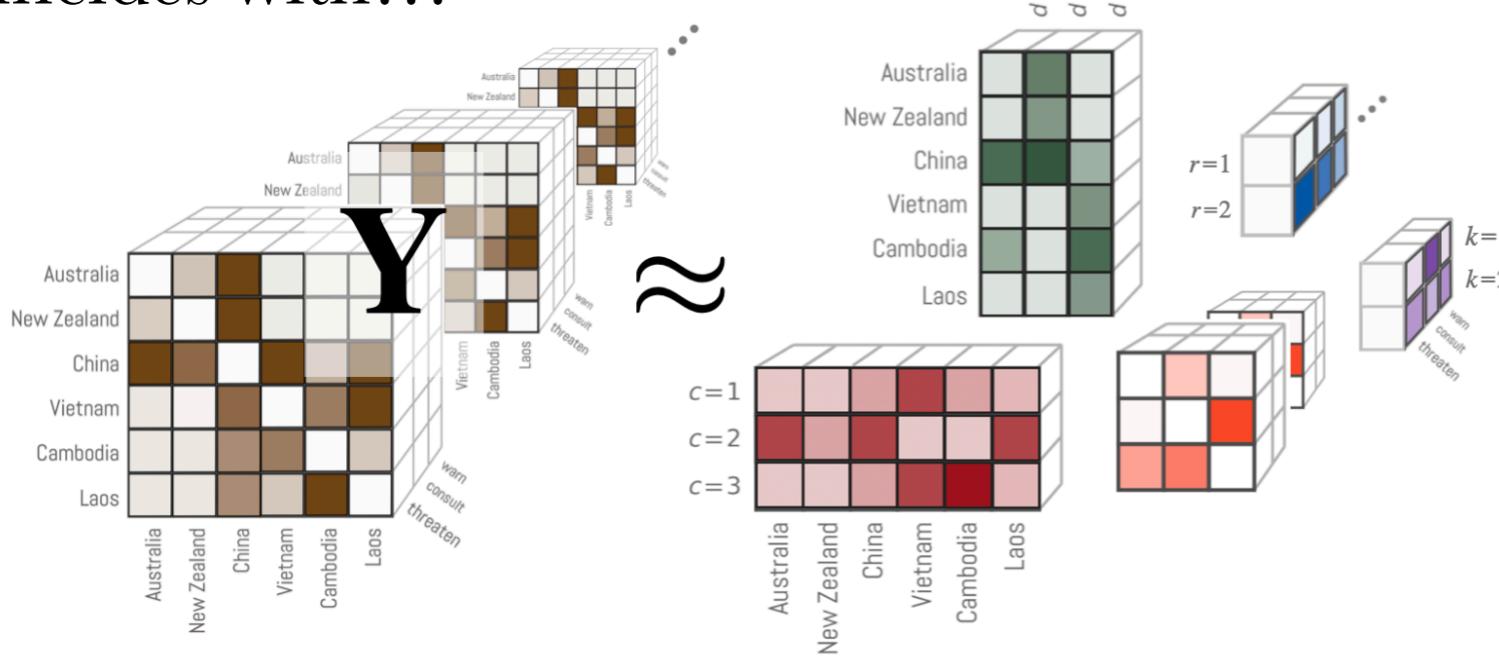
ALLOCATIVE POISSON FACTORIZATION

Folk theorem of statistical computing [Gelman, 2008]:

“Later ‘When you have computational problems, often there’s a problem with your model.’”

Decomposition of a tensor

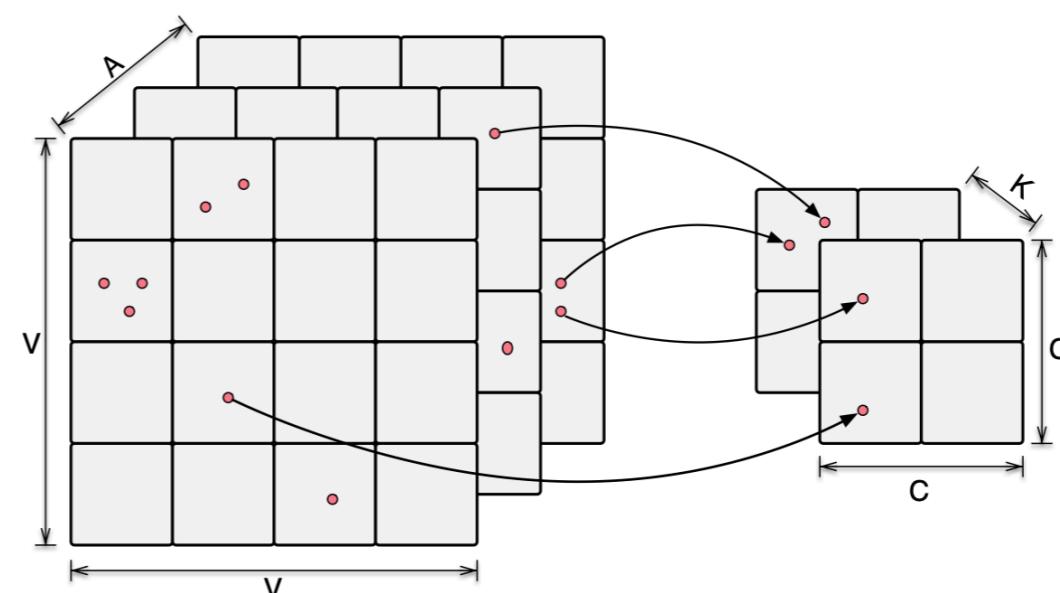
coincides with...



...latent class allocation of its tokens

Table 2
WEIS Coding of 1990 Iraq-Kuwait Crisis

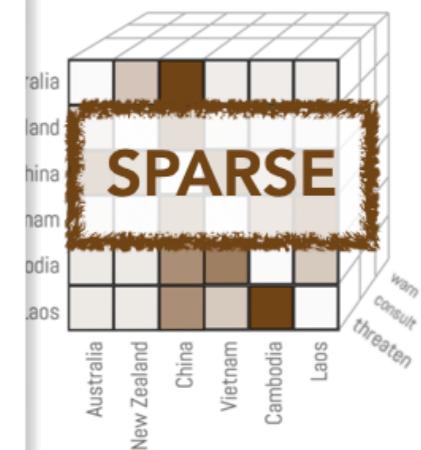
Date	Source	Target	Type of Action
900717	IRQ	KUW	CHARGE
900725	IRQ	EGY	ASSURE
900727	IRQ	KUW	WARN
900731	IRQ	KUW	MOBILIZATION
900801	KUW	IRQ	REFUSE
900802	IRQ	KUW	MILITARY FORCE



$\text{Pois}(\mu_{i,k})$

(“sources”)

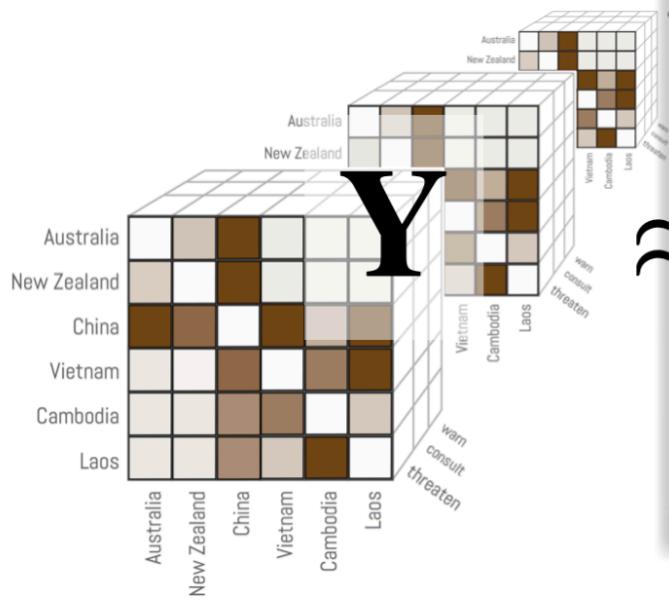
ing form:



ALLOCATIVE POISSON FACTORIZATION

“**Latent source**” representation [Dunson & Herring, (2005); Cemgil (2009)]:

Decomposition of a table
coincides with...



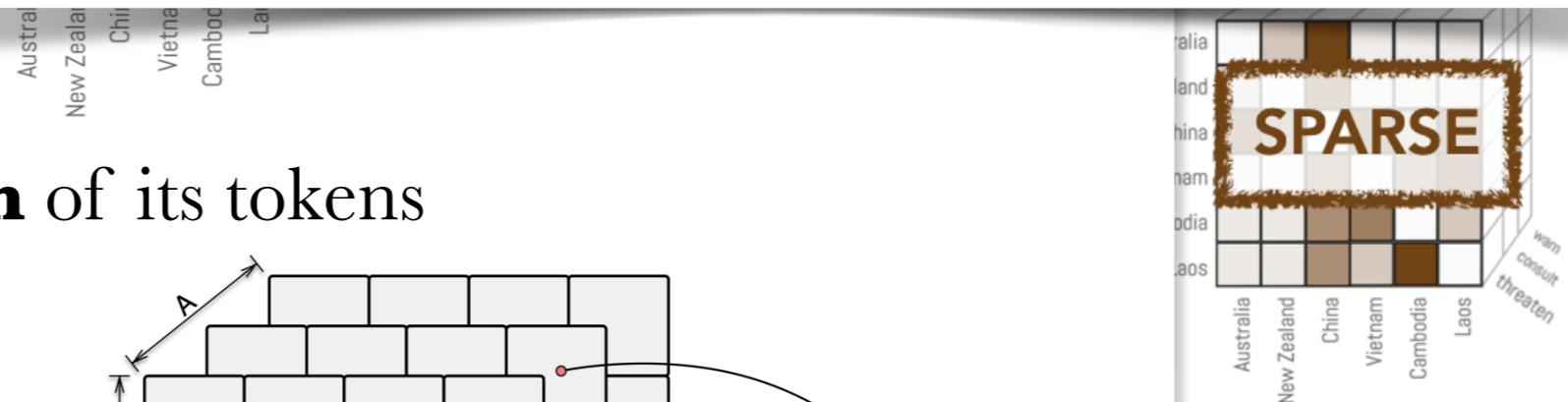
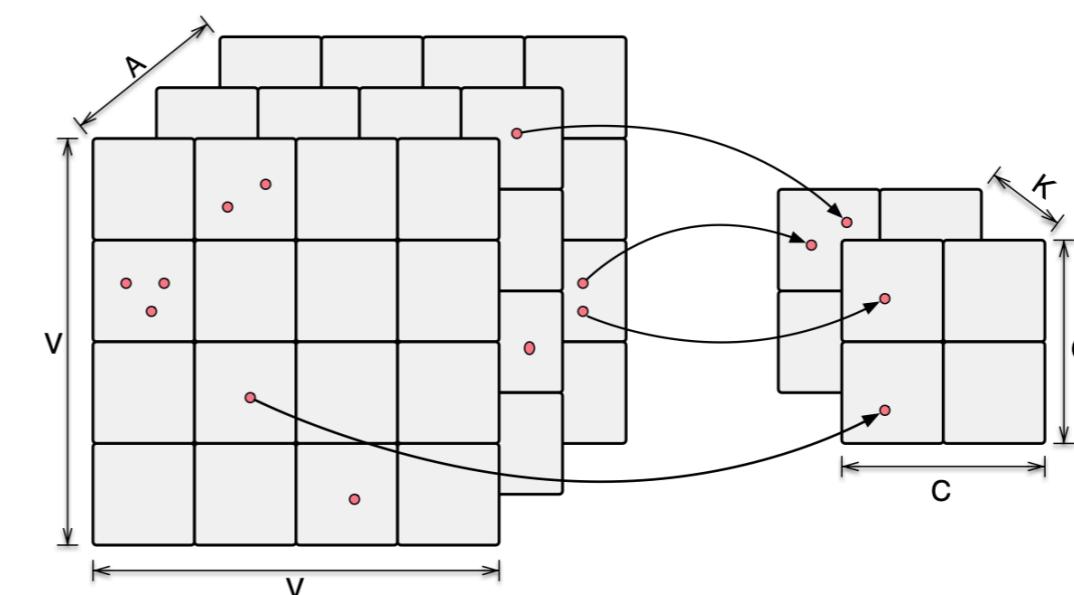
Equivalence to models specified explicitly for tokens:

- ▶ Tensor decomposition for contingency table analysis:
[...] [Dunson & Xing, 2012], [Zhou et al., 2015],
[Johndrow, Bhattacharya & Dunson, 2017] [...]
- ▶ Latent class models: [...] [Gu & Dunson, 2023] [...]
- ▶ Topic models: e.g., [Blei et al., 2003]
- ▶ Graphical models: e.g., [Lauritzen, 1996]

...latent class allocation of its tokens

Table 2
WEIS Coding of 1990 Iraq-Kuwait Crisis

Date	Source	Target	Type of Action
900717	IRQ	KUW	CHARGE
900725	IRQ	EGY	ASSURE
900727	IRQ	KUW	WARN
900731	IRQ	KUW	MOBILIZATION
900801	KUW	IRQ	REFUSE
900802	IRQ	KUW	MILITARY FORCE



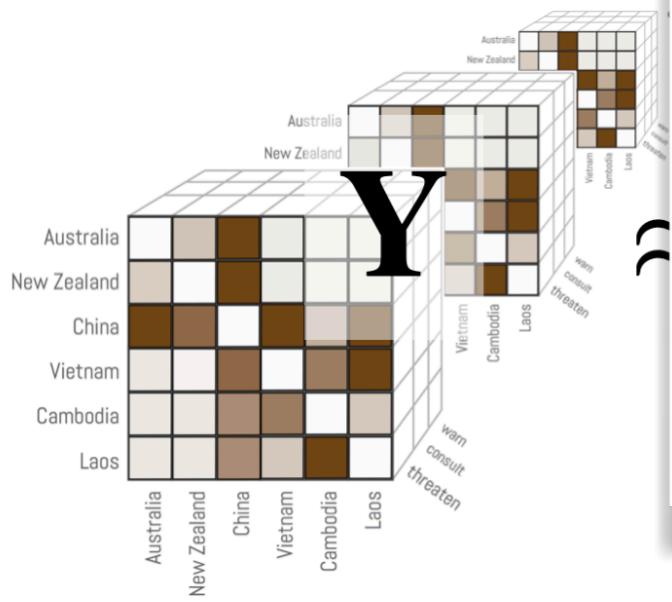
ALLOCATIVE POISSON FACTORIZATION

Folk theorem of statistical computing [Gelman, 2008]:

Late “When you have computational problems, often there’s a problem with your model.”

Decomposition of a t

coincides with...



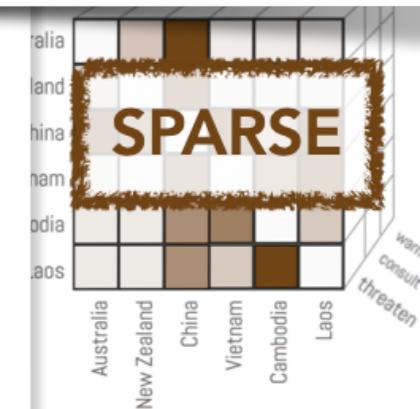
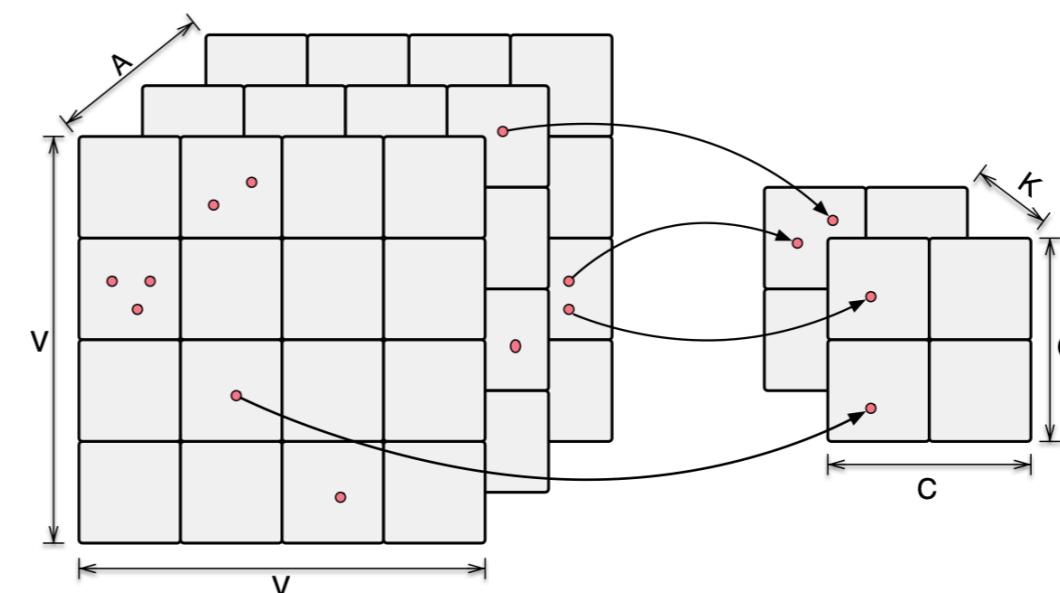
Equivalence to models specified explicitly for tokens:

- ▶ Tensor decomposition for contingency table analysis:
[...] [Dunson & Xing, 2012], [Zhou et al., 2015],
[Johndrow, Bhattacharya & Dunson, 2017] [...]
 - ▶ Latent class models: [...] [Gu & Dunson, 2023] [...]
 - ▶ Topic models: e.g., [Blei et al., 2003]
 - ▶ Graphical models: e.g., [Lauritzen, 1996]

...latent class allocation of its tokens

Table 2
WEIS Coding of 1990 Iraq-Kuwait Crisis

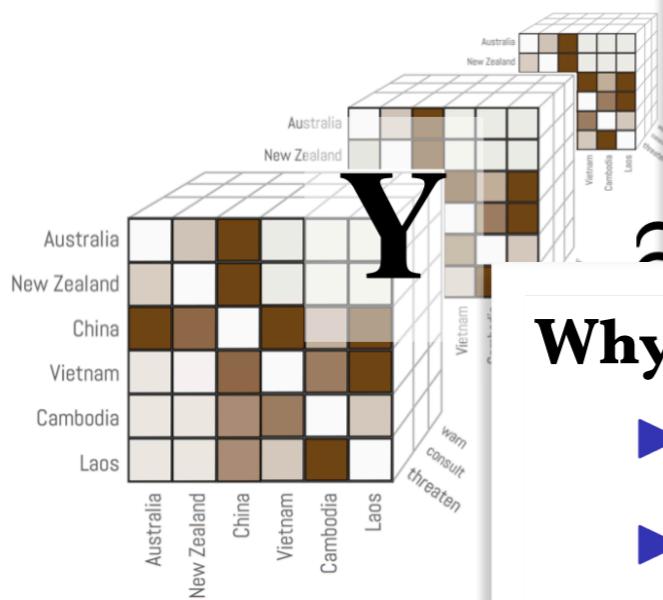
Date	Source	Target	Type of Action
900717	IRQ	KUW	CHARGE
900725	IRQ	EGY	ASSURE
900727	IRQ	KUW	WARN
900731	IRQ	KUW	MOBILIZATION
900801	KUW	IRQ	REFUSE
900802	IRQ	KUW	MILITARY FORCE



ALLOCATIVE POISSON FACTORIZATION

“**Latent source**” representation [Dunson & Herring, (2005); Cemgil (2009)]:

Decomposition of a tensor
coincides with...



...latent class all

Table 2
WEIS Coding of 1990 Iraq-Kuwait Conflict

Date	Source	Target
900717	IRQ	KUW
900725	IRQ	EGY
900727	IRQ	KUW
900731	IRQ	KUW
900801	KUW	IRQ
900802	IRQ	KUW

Equivalence to models specified explicitly for tokens:

- ▶ Tensor decomposition for contingency table analysis:
[...] [Dunson & Xing, 2012], [Zhou et al., 2015],
[Johndrow, Bhattacharya & Dunson, 2017] [...]
- ▶ Latent class models: [...] [Gu & Dunson, 2023] [...]

Why this is particularly important in this setting:

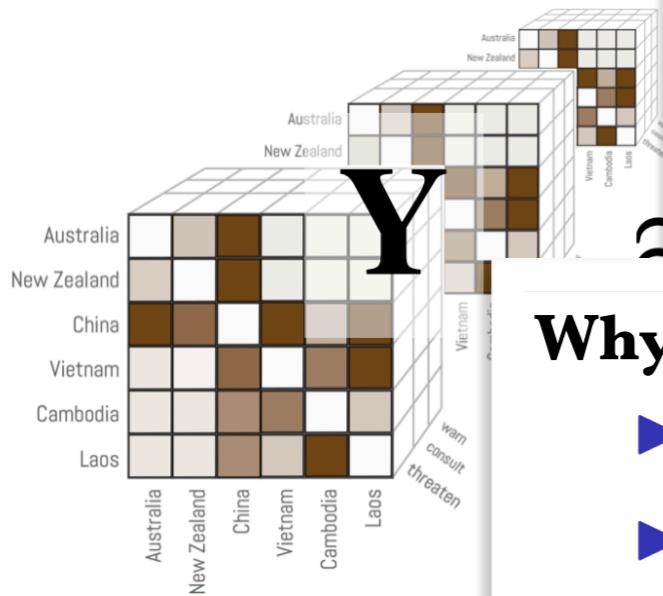
- ▶ ICEWS (1995-2023): **20M tokens**
- ▶ (country x country x action x month)
 $= (250 \times 250 \times 20 \times 336)$
 ≈ 450 million entries
- ▶ (country x country x action x day x publisher)
 $= (250 \times 250 \times 20 \times 10,220 \times 200)$
 ≈ 2.5 trillion entries
- ▶ **When we add columns, or increase granularity, we get enormous tensors, but inference is still $\mathcal{O}(\#tokens)$**

ALLOCATIVE POISSON FACTORIZATION

Folk theorem of statistical computing [Gelman, 2008]:

“Later ‘When you have computational problems, often there’s a problem with your model.’”

Decomposition of a tensor coincides with...



...latent class all

Table 2
WEIS Coding of 1990 Iraq-Kuwait Conflict

Date	Source	Target
900717	IRQ	KUW
900725	IRQ	EGY
900727	IRQ	KUW
900731	IRQ	KUW
900801	KUW	IRQ
900802	IRQ	KUW

Equivalence to models specified explicitly for tokens:

- ▶ Tensor decomposition for contingency table analysis:
[...] [Dunson & Xing, 2012], [Zhou et al., 2015],
[Johndrow, Bhattacharya & Dunson, 2017] [...]
- ▶ Latent class models: [...] [Gu & Dunson, 2023] [...]

Why this is particularly important in this setting:

- ▶ ICEWS (1995-2023): **20M tokens**
- ▶ (country x country x action x month)
 $= (250 \times 250 \times 20 \times 336)$
≈ 450 million entries
- ▶ (country x country x action x day x publisher)
 $= (250 \times 250 \times 20 \times 10,220 \times 200)$
≈ 2.5 trillion entries
- ▶ **When we add columns, or increase granularity, we get enormous tensors, but inference is still $\mathcal{O}(\#tokens)$**

NO FREE LUNCH

Allocative Poisson factorization...

$$y_i \sim \text{Pois}(\sum_{\text{non-negative}} \dots)$$

...means non-negative priors.

Fine for simple i.id priors (e.g., Gamma, Dirichlet).

NO FREE LUNCH

Allocative Poisson factorization...

$$y_{\mathbf{i}} \sim \text{Pois}\left(\sum_{\text{non-negative}} \dots\right)$$

...means non-negative priors.

Fine for simple i.id priors (e.g., Gamma, Dirichlet).

More challenging for building complex priors, e.g.,

$$\boldsymbol{\theta}^{(t)} \sim P(\boldsymbol{\theta}^{(t)} | \boldsymbol{\theta}^{(t-1)})$$

Often requires new tools (e.g., augmentation schemes).

OUTLINE

- ▶ Motivation: Dyadic event data (and its challenges)
- ▶ Non-negative (Poisson) tensor decompositions
 - ▶ CP extracts “multilateral” structure [Schein et al., 2015]
 - ▶ Tucker extracts “communities” [Schein et al., 2016]
 - ▶ Why (allocative) Poisson factorization
 - ▶ AL ℓ_0 CORE avoids the “exponential blowup” [Hood & Schein, 2024]

Appendix (*time permitting*)

- ▶ State-space modeling
 - ▶ Gamma state-space models [Schein et al., 2016b; Schein et al., 2019]
 - ▶ Modeling “escalation” with a new matrix prior [Stoehr et al., 2023]

OUTLINE

- ▶ Motivation: Dyadic event data (and its challenges)
- ▶ Non-negative (Poisson) tensor decompositions
 - ▶ CP extracts “multilateral” structure [Schein et al., 2015]
 - ▶ Tucker extracts “communities” [Schein et al., 2016]
 - ▶ Why (allocative) Poisson factorization
 - ▶ **AL ℓ_0 CORE** avoids the “exponential blowup” [Hood & Schein, 2024]

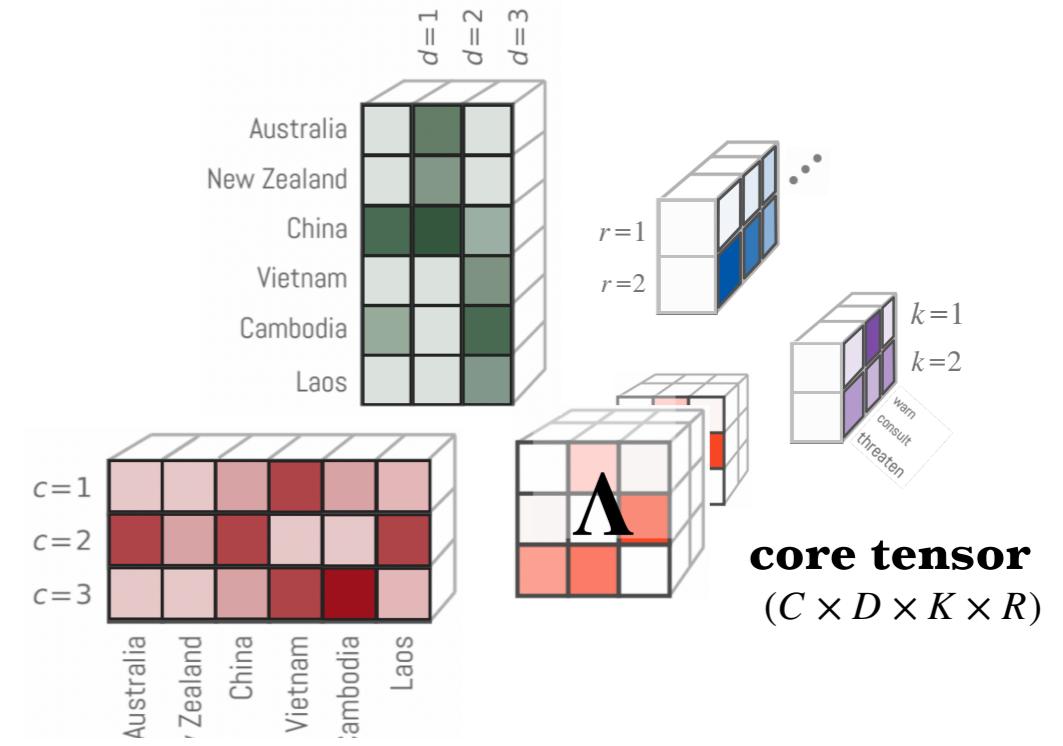
Appendix (*time permitting*)

- ▶ State-space modeling
 - ▶ Gamma state-space models [Schein et al., 2016b; Schein et al., 2019]
 - ▶ Modeling “escalation” with a new matrix prior [Stoehr et al., 2023]

TUCKER: APPEALING

Tucker's **conceptual appeal**

- ▶ Different number of factors in each mode
- ▶ Mode-specific interpretation of factors
 - ▶ e.g., “communities” of countries
 - ▶ e.g., “topics of actions”
- ▶ Factor sharing across classes; less redundancy



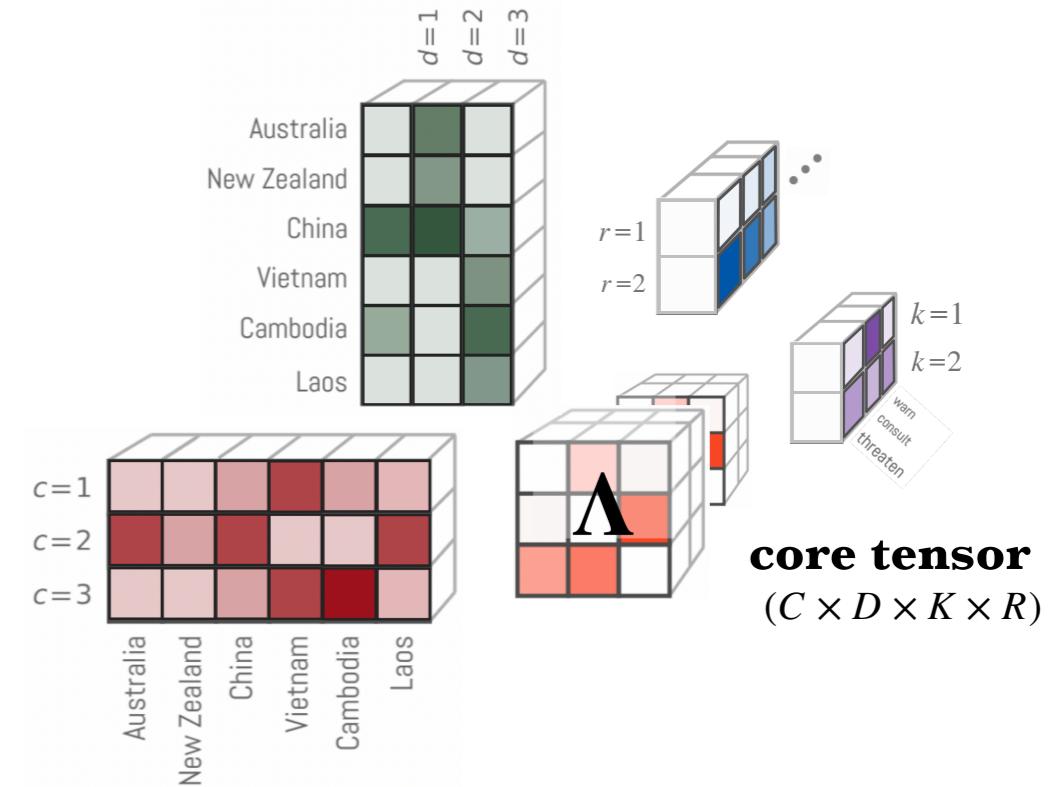
TUCKER: APPEALING

Tucker's **conceptual appeal**

- ▶ Different number of factors in each mode
- ▶ Mode-specific interpretation of factors
 - ▶ e.g., “communities” of countries
 - ▶ e.g., “topics of actions
- ▶ Factor sharing across classes; less redundancy

...is not **practically achievable**:

- ▶ Typically $\mathcal{O}(|\mathbf{Y}| \cdot |\boldsymbol{\Lambda}|)$, sometimes worse
- ▶ “Exponential blowup”: $|\boldsymbol{\Lambda}|$ is **exponential** in M



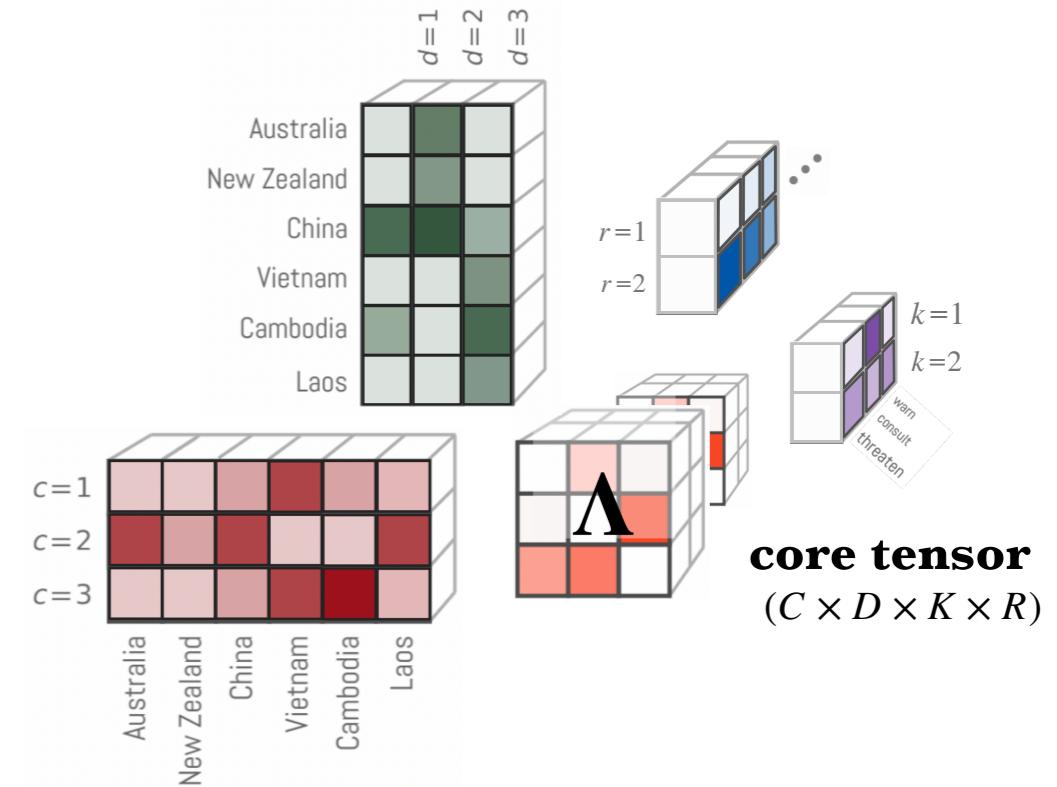
TUCKER: APPEALING

Tucker's **conceptual appeal**

- ▶ Different number of factors in each mode
- ▶ Mode-specific interpretation of factors
 - ▶ e.g., “communities” of countries
 - ▶ e.g., “topics of actions”
- ▶ Factor sharing across classes; less redundancy

...is not **practically achievable**:

- ▶ Typically $\mathcal{O}(|\mathbf{Y}| \cdot |\boldsymbol{\Lambda}|)$, sometimes worse
- ▶ “Exponential blowup”: $|\boldsymbol{\Lambda}|$ is **exponential** in M
- ▶ In practice: small cores e.g., $(3 \times 3 \times 3)$
- ▶ Not consistent with desired interpretation



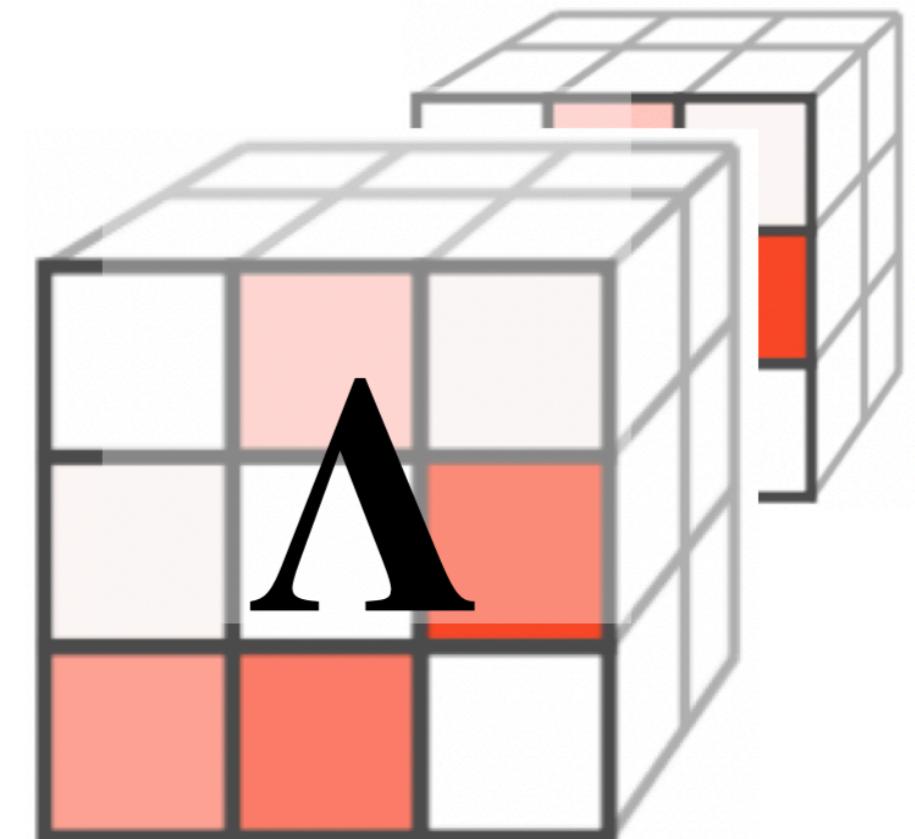
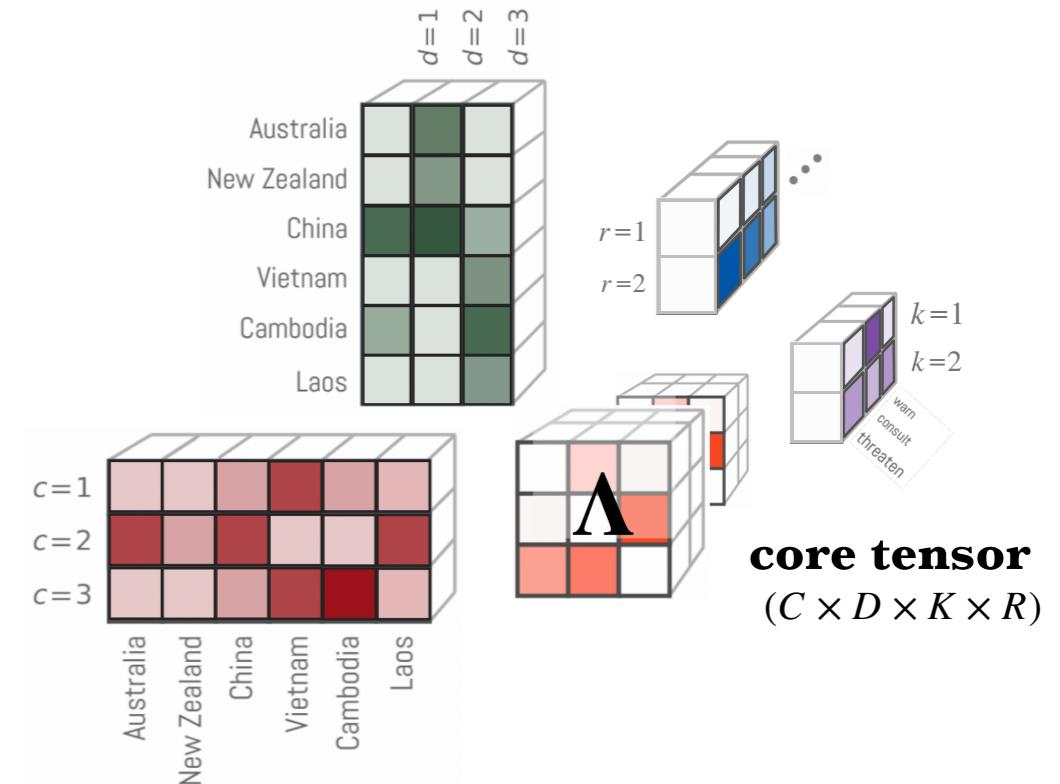
TUCKER: APPEALING

Tucker's **conceptual appeal**

- ▶ Different number of factors in each mode
- ▶ Mode-specific interpretation of factors
 - ▶ e.g., “communities” of countries
 - ▶ e.g., “topics of actions
- ▶ Factor sharing across classes; less redundancy

...is not **practically achievable**:

- ▶ Typically $\mathcal{O}(|\mathbf{Y}| \cdot |\boldsymbol{\Lambda}|)$, sometimes worse
- ▶ “Exponential blowup”: $|\boldsymbol{\Lambda}|$ is **exponential** in M
- ▶ In practice: small cores e.g., $(3 \times 3 \times 3)$
- ▶ Not consistent with desired interpretation
- ▶ e.g., 50 communities, 10 topics, 25 regimes = 625,000 classes



TUCKER: APPEALING

Tucker's **conceptual appeal**

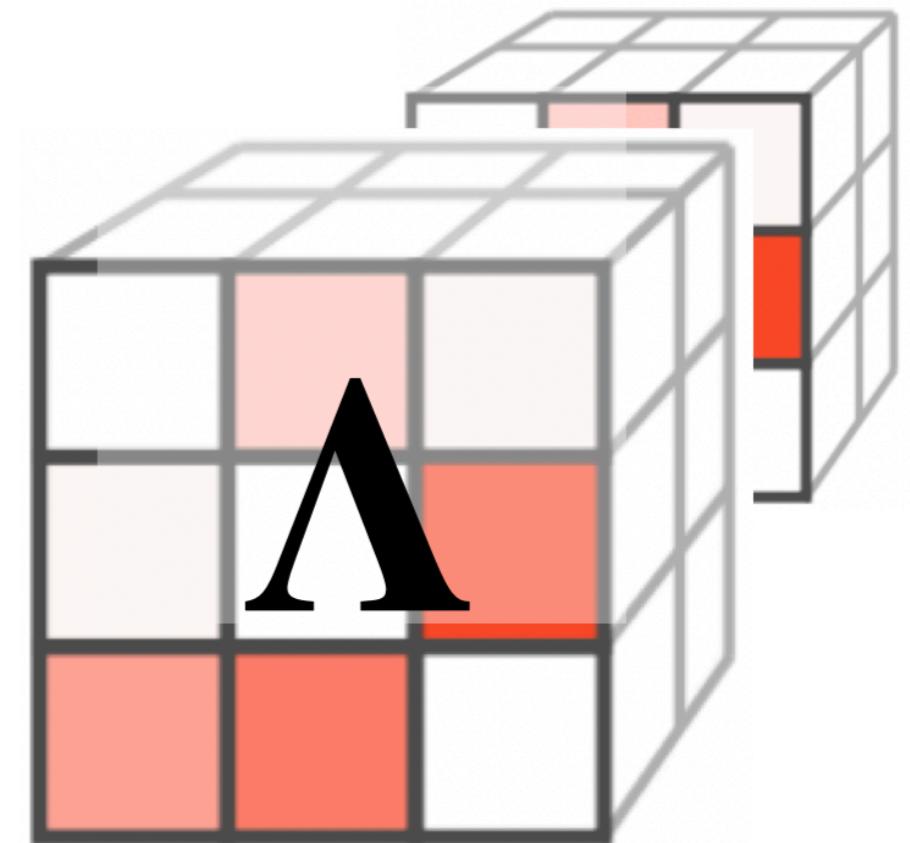
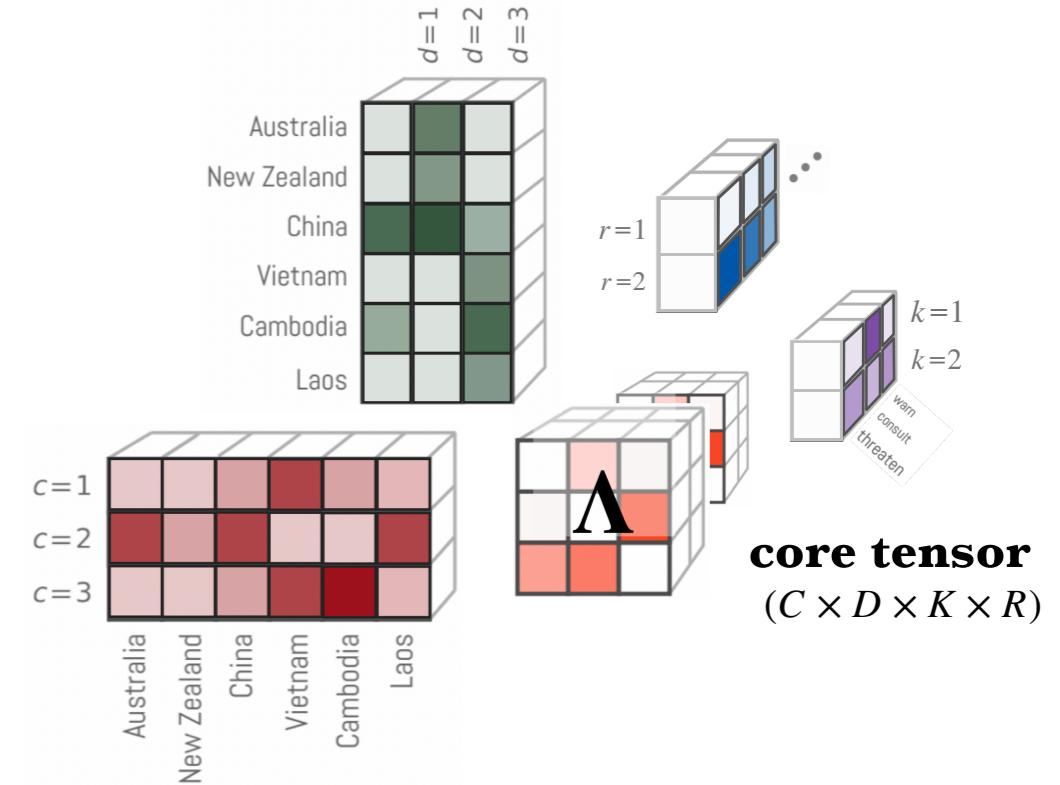
- ▶ Different number of factors in each mode
- ▶ Mode-specific interpretation of factors
 - ▶ e.g., “communities” of countries
 - ▶ e.g., “topics of actions
- ▶ Factor sharing across classes; less redundancy

...is not **practically achievable**:

- ▶ Typically $\mathcal{O}(|\mathbf{Y}| \cdot |\boldsymbol{\Lambda}|)$, sometimes worse
- ▶ “Exponential blowup”: $|\boldsymbol{\Lambda}|$ is **exponential** in M
- ▶ In practice: small cores e.g., $(3 \times 3 \times 3)$
- ▶ Not consistent with desired interpretation
- ▶ e.g., 50 communities, 10 topics, 25 regimes =
625,000 classes

Poisson Tucker better, but still bad:

- ▶ $\mathcal{O}(\|\mathbf{Y}\|_0 \cdot |\boldsymbol{\Lambda}|)$

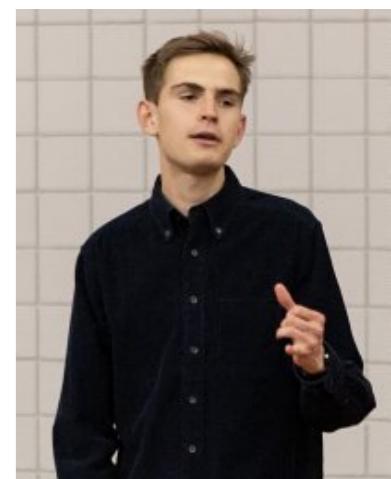


ALL_0CORE [Hood & Schein, 2024]

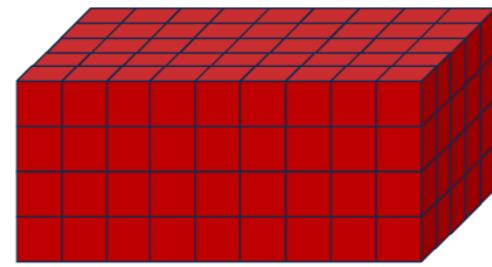
The basic idea: an ℓ_0 -constrained core:

$$||\Lambda||_0 \leq Q$$

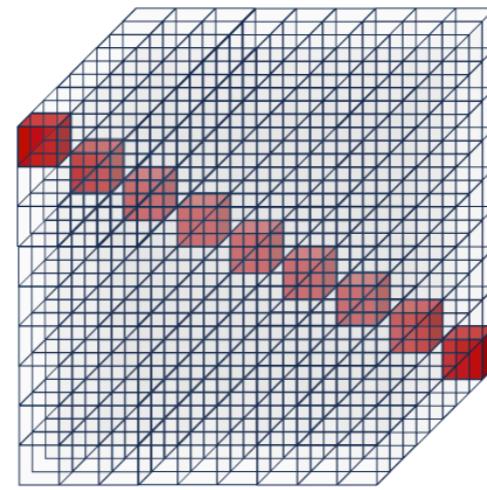
Lead author:



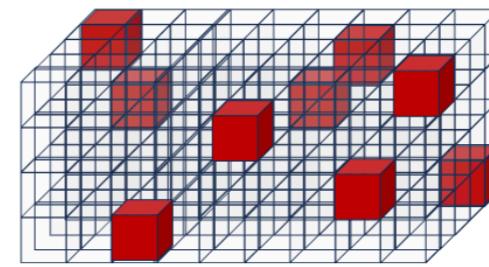
John Hood



(a) Tucker



(b) CP

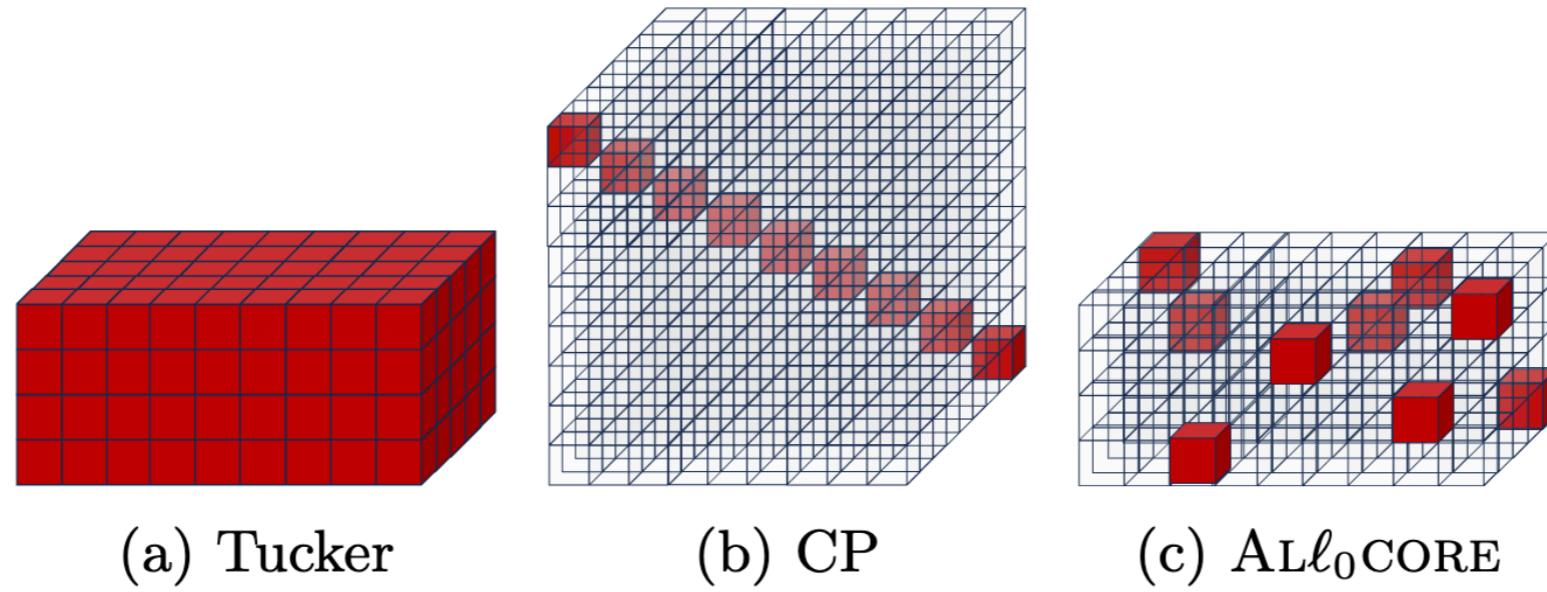


(c) ALL_0CORE

ALL ℓ_0 CORE [Hood & Schein, 2024]

The basic idea: an ℓ_0 -constrained core:

$$||\Lambda||_0 \leq Q$$



Lead author:



John Hood

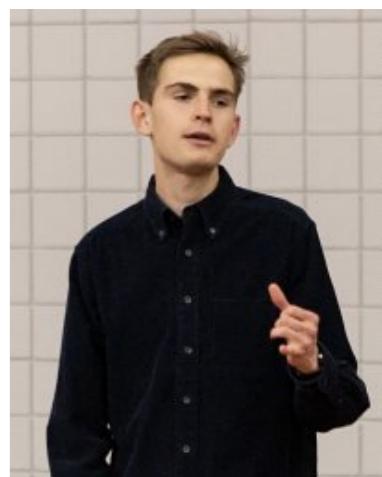
- ▶ Q is a **budget** set by the user (for now)
 - ▶ $\lambda_1, \dots, \lambda_Q$ non-zero values
 - ▶ $\kappa_1, \dots, \kappa_Q$ non-zero locations
 - ▶ $\kappa_q \equiv (c[q], d[q] a[q], r[q])$

$\text{AL}\ell_0\text{CORE}$ [Hood & Schein, 2024]

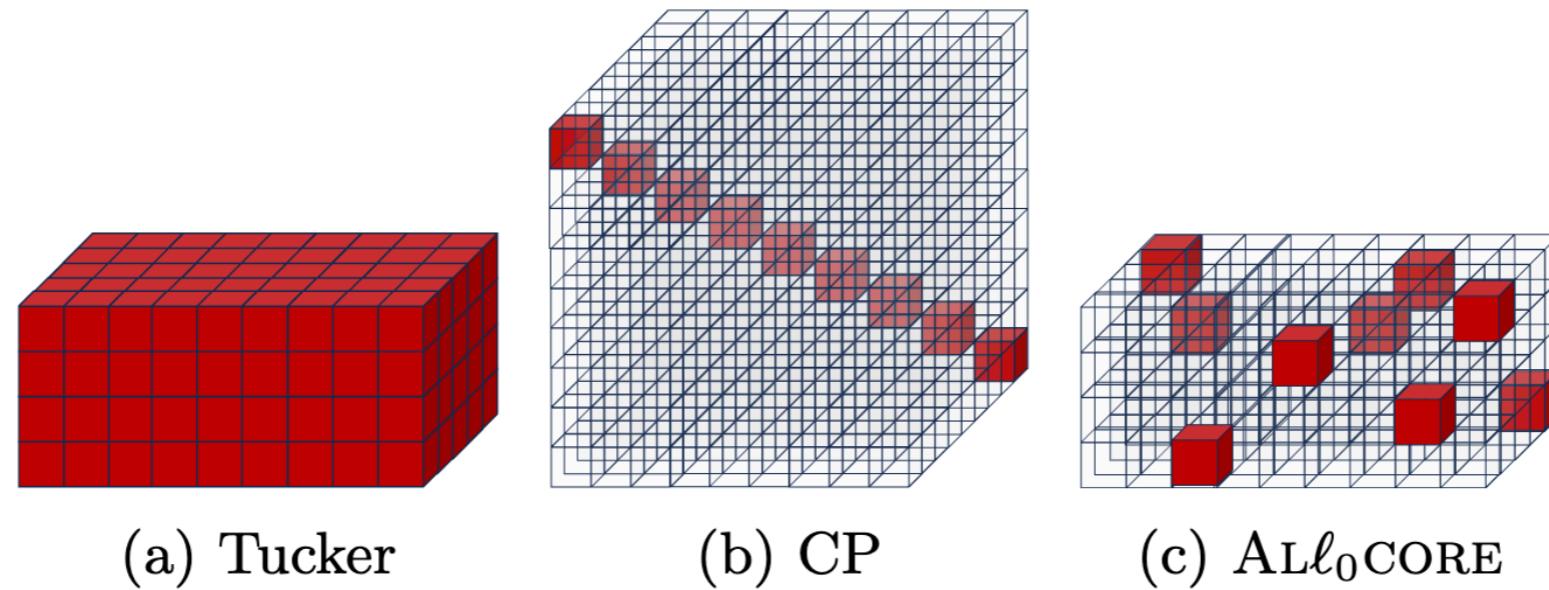
The basic idea: an ℓ_0 -constrained core:

$$\|\Lambda\|_0 \leq Q$$

Lead author:



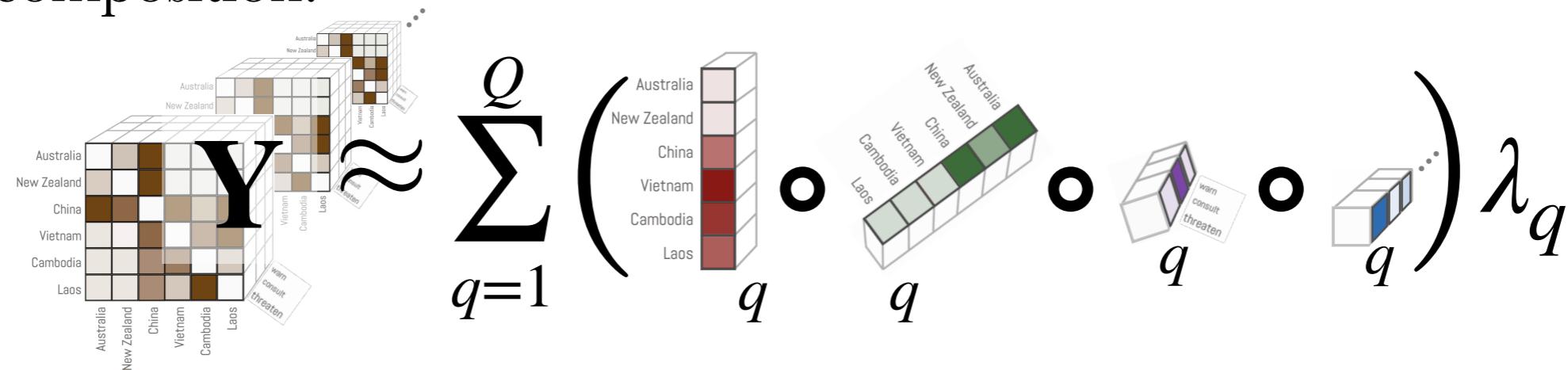
John Hood



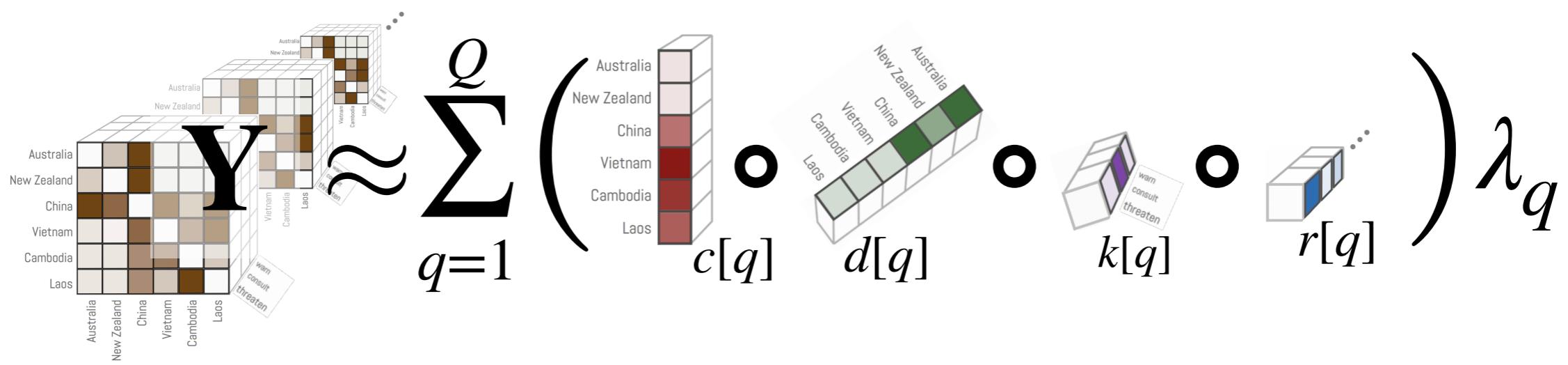
- ▶ Q is a **budget** set by the user (for now)
- ▶ $\lambda_1, \dots, \lambda_Q$ non-zero values
- ▶ $\kappa_1, \dots, \kappa_Q$ non-zero locations
 - ▶ $\kappa_q \equiv (c[q], d[q], a[q], r[q])$
- ▶ Inference involves **allocating non-zeros** across the core
- ▶ $\text{AL}\ell_0\text{CORE} = \text{"allocated } \ell_0\text{-constrained core"}$

COMPARISON OF ALL THREE

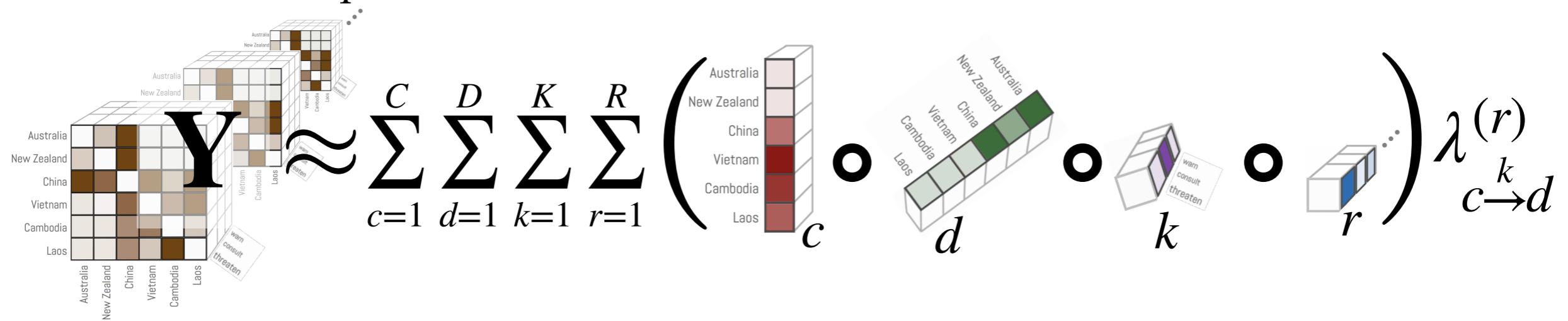
► CP decomposition:



► AL ℓ_0 CORE decomposition:



► Tucker decomposition



SAMPLING-BASED INFERENCE

- ▶ Prior for a $(K_1 \times \dots \times K_M)$ core

$$\kappa_q \sim \text{Categorical}(\Pi)$$

SAMPLING-BASED INFERENCE

- ▶ Prior for a $(K_1 \times \dots \times K_M)$ core

$$\kappa_q \sim \text{Categorical}(\Pi)$$

- ▶ For a rank-1 prior tensor ($\Pi \equiv \pi_1 \circ \dots \circ \pi_M$):

$$\kappa_{q,m} \sim \text{Categorical}(\pi_m)$$

SAMPLING-BASED INFERENCE

- ▶ Prior for a $(K_1 \times \dots \times K_M)$ core

$$\kappa_q \sim \text{Categorical}(\Pi)$$

- ▶ For a rank-1 prior tensor ($\Pi \equiv \pi_1 \circ \dots \circ \pi_M$):

$$\kappa_{q,m} \sim \text{Categorical}(\pi_m)$$

- ▶ Naively sampling the multi-index is exponential

$$\mathcal{O}\left(\prod_{m=1}^M K_m\right)$$

$$P(\kappa_q \mid -) = \frac{\cdots}{\sum_{\kappa} \cdots}$$

SAMPLING-BASED INFERENCE

- ▶ Prior for a $(K_1 \times \dots \times K_M)$ core

$$\kappa_q \sim \text{Categorical}(\Pi)$$

- ▶ For a rank-1 prior tensor ($\Pi \equiv \pi_1 \circ \dots \circ \pi_M$):

$$\kappa_{q,m} \sim \text{Categorical}(\pi_m)$$

- ▶ Naively sampling the multi-index is exponential

$$\mathcal{O}\left(\prod_{m=1}^M K_m\right)$$

$$P(\kappa_q \mid -) = \frac{\cdots}{\sum_{\kappa} \cdots}$$

- ▶ Gibbs **sampling the sub-indices** is not

$$\mathcal{O}\left(\sum_{m=1}^M K_m\right)$$

$$P(\kappa_{q,m} \mid \kappa_{q,\neg m} -) = \frac{\cdots}{\sum_{k_m} \cdots}$$

SAMPLING-BASED INFERENCE

- ▶ Prior for a $(K_1 \times \dots \times K_M)$ core

$$\kappa_q \sim \text{Categorical}(\Pi)$$

- ▶ For a rank-1 prior tensor ($\Pi \equiv \pi_1 \circ \dots \circ \pi_M$):

$$\kappa_{q,m} \sim \text{Categorical}(\pi_m)$$

- ▶ Naively sampling the multi-index is exponential

$$\mathcal{O}\left(\prod_{m=1}^M K_m\right)$$

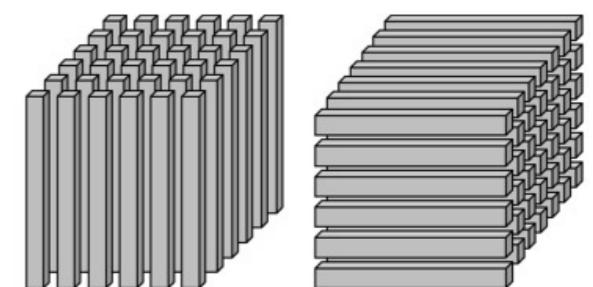
$$P(\kappa_q \mid -) = \frac{\cdots}{\sum_{\kappa} \cdots}$$

- ▶ Gibbs **sampling the sub-indices** is not

$$\mathcal{O}\left(\sum_{m=1}^M K_m\right)$$

$$P(\kappa_{q,m} \mid \kappa_{q,\neg m} -) = \frac{\cdots}{\sum_{k_m} \cdots}$$

- ▶ Each step re-allocates λ_q within a **fiber** of the core



(a) Column fibers

(b) Row fibers

SAMPLING-BASED INFERENCE

- ▶ Prior for a $(K_1 \times \dots \times K_M)$ core

$$\kappa_q \sim \text{Categorical}(\Pi)$$

- ▶ For a rank-1 prior tensor ($\Pi \equiv \pi_1 \circ \dots \circ \pi_M$):

$$\kappa_{q,m} \sim \text{Categorical}(\pi_m)$$

- ▶ Naively sampling the multi-index is exponential

$$\mathcal{O}\left(\prod_{m=1}^M K_m\right)$$

$$P(\kappa_q \mid -) = \frac{\cdots}{\sum_{\kappa} \cdots}$$

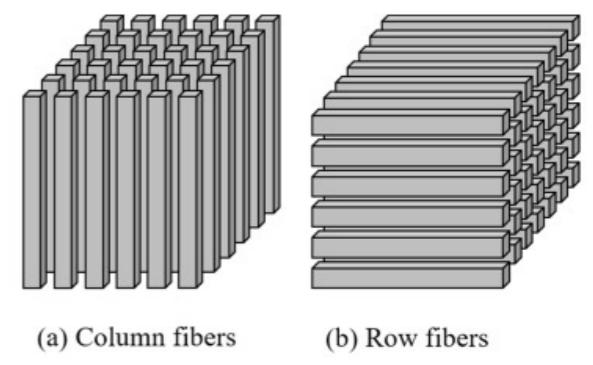
- ▶ Gibbs **sampling the sub-indices** is not

$$\mathcal{O}\left(\sum_{m=1}^M K_m\right)$$

$$P(\kappa_{q,m} \mid \kappa_{q,\neg m} -) = \frac{\cdots}{\sum_{k_m} \cdots}$$

- ▶ Each step re-allocates λ_q within a **fiber** of the core

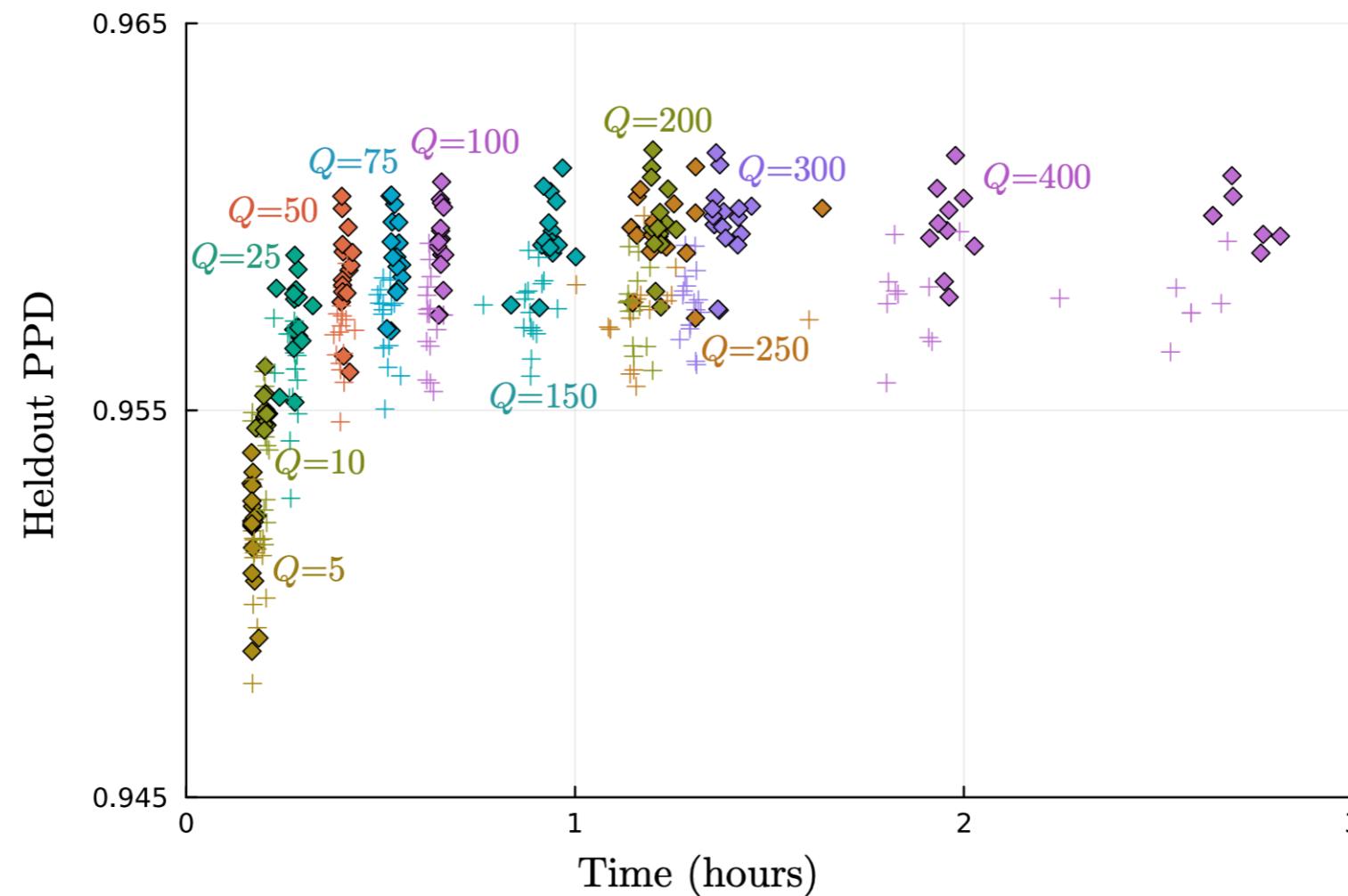
- ▶ (We can do even better with specific priors, but this works surprisingly well.)



EXPERIMENTS

How dense does the core need to be?

- ▶ Consider two core shapes: small ($20 \times 20 \times 6 \times 3$) and large ($50 \times 50 \times 6 \times 10$)
- ▶ Run $\text{All}\ell_0\text{CORE}$ with $Q \in \{5, \dots, 400\}$
- ▶ (Note: $Q = 400$ is 5% and 0.25% dense for the small and large cores, respectively)

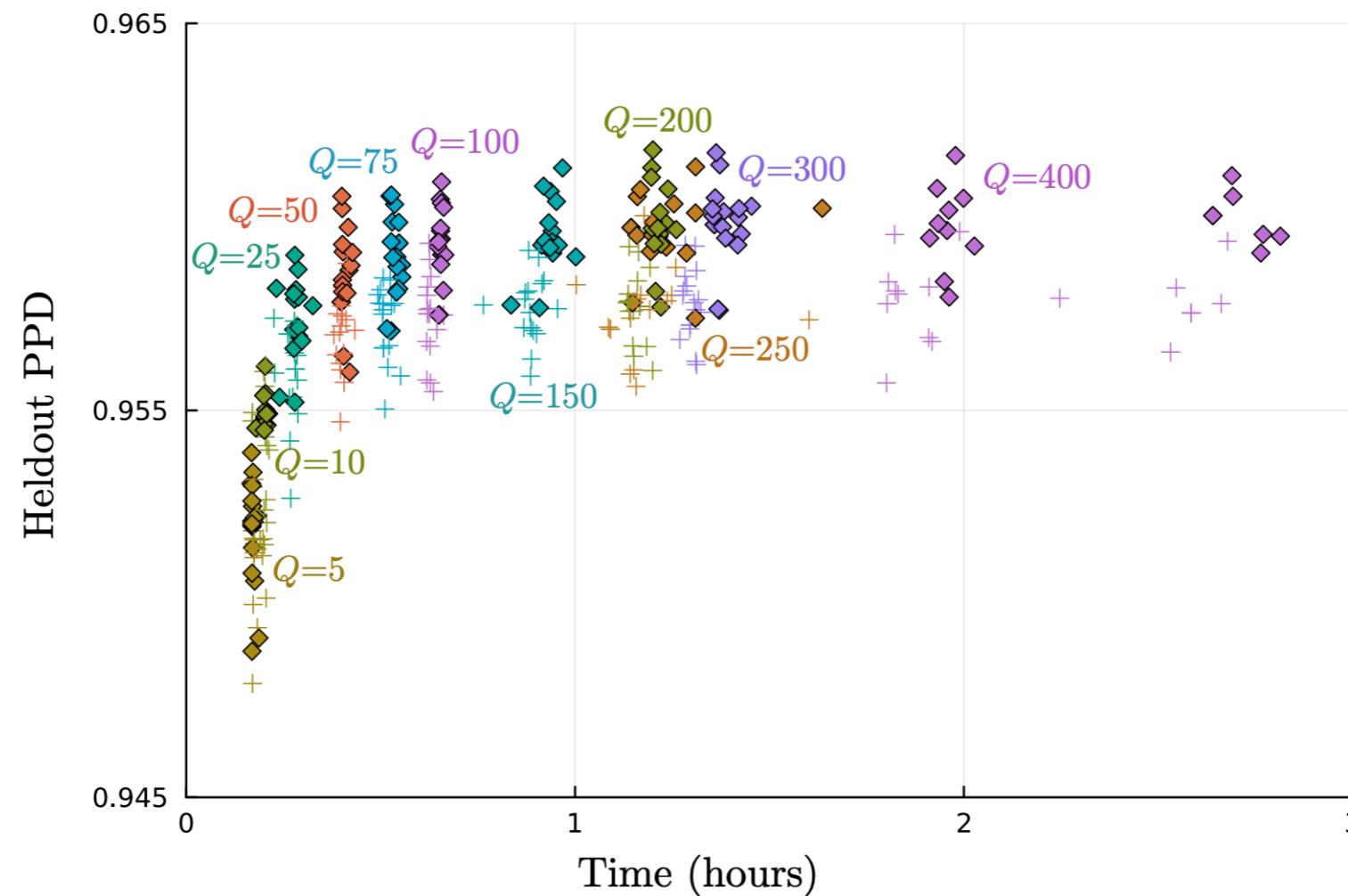


Performance plateaus very early → full Tucker is **wasting computation**.

EXPERIMENTS

How dense does the core need to be?

- ▶ Consider two core shapes: small ($20 \times 20 \times 6 \times 3$) and large ($50 \times 50 \times 6 \times 10$)
- ▶ Run $\text{All}\ell_0\text{CORE}$ with $Q \in \{5, \dots, 400\}$
- ▶ (Note: $Q = 400$ is 5% and 0.25% dense for the small and large cores, respectively)



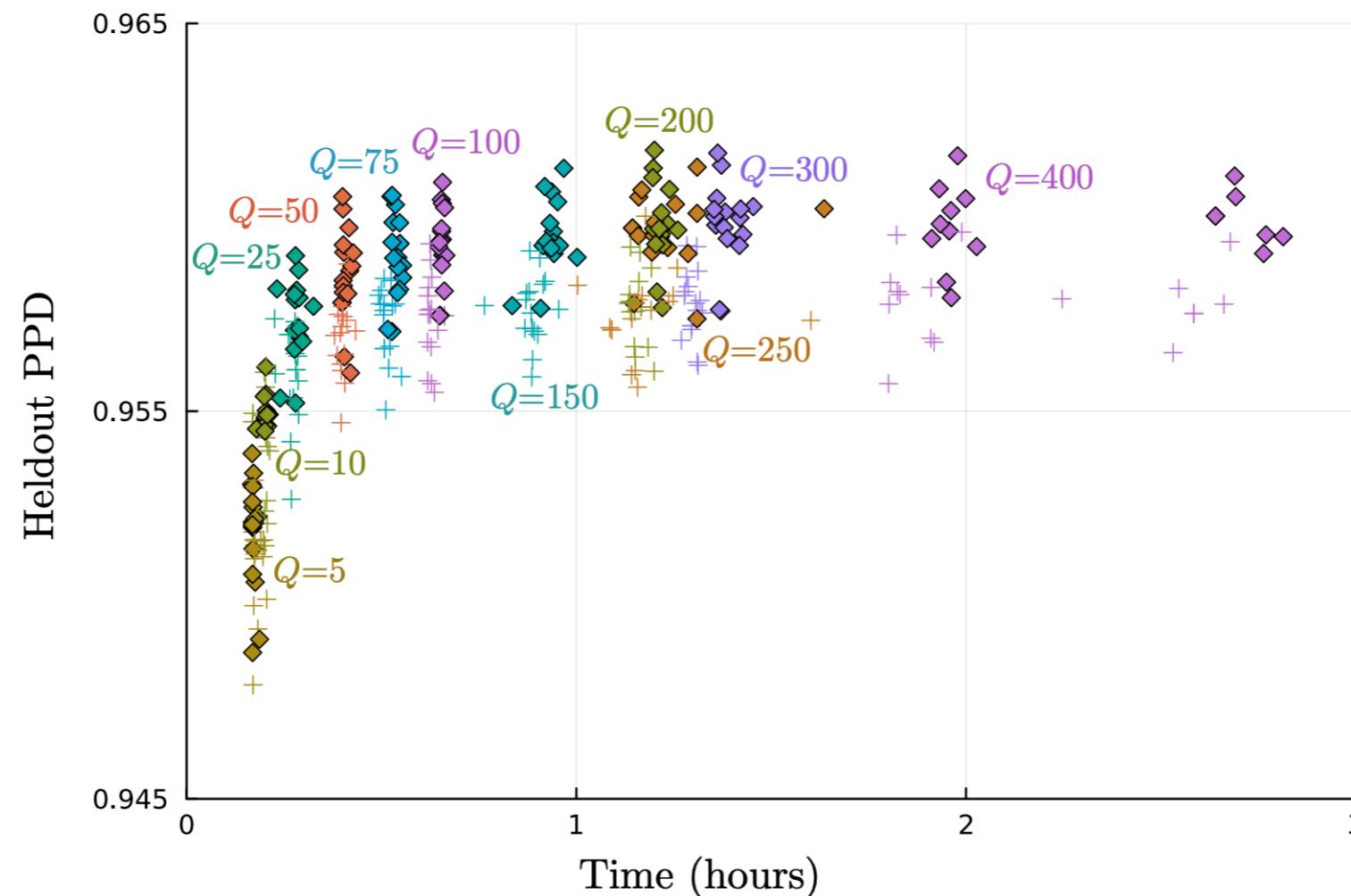
Performance plateaus very early → full Tucker is **wasting computation**.

- ▶ Gibbs sampling for full Tucker on the large core would take an estimated 30 days

EXPERIMENTS

How dense does the core need to be?

- ▶ Consider two core shapes: small ($20 \times 20 \times 6 \times 3$) and large ($50 \times 50 \times 6 \times 10$)
- ▶ Run $\text{All}\ell_0\text{CORE}$ with $Q \in \{5, \dots, 400\}$
- ▶ (Note: $Q = 400$ is 5% and 0.25% dense for the small and large cores, respectively)



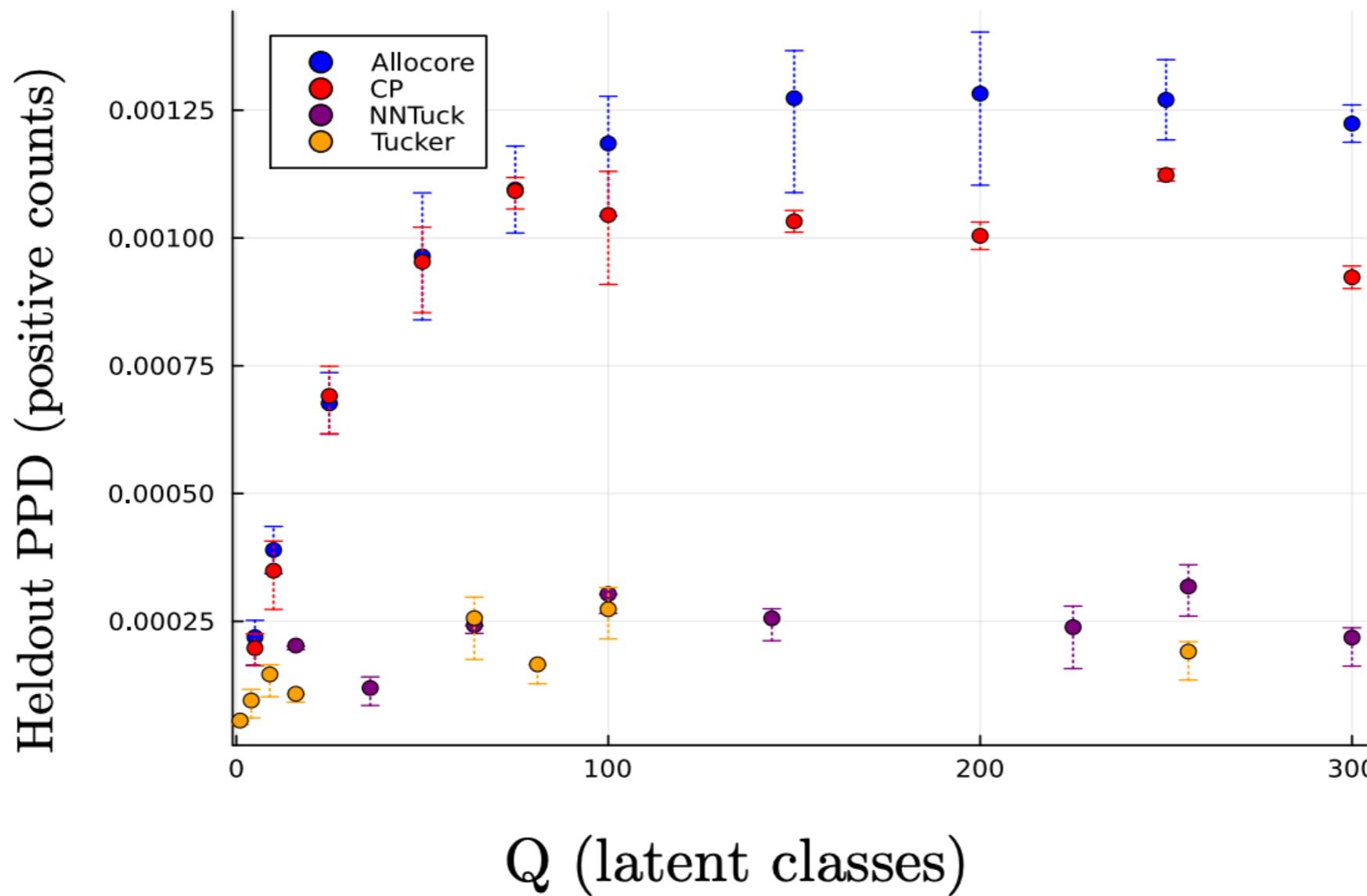
Performance plateaus very early → full Tucker is **wasting computation**.

- ▶ Gibbs sampling for full Tucker on the large core would take an estimated **30 days**
- ▶ EM with NNTUCK [Aguiar et al., 2023] would take an estimated **1.5 days**

EXPERIMENTS

How does it compare to CP and full Tucker with the **same number of parameters**?

- ▶ Set Q and use “**canonical**” All ℓ_0 CORE ($K_1 = \dots K_M = Q$)
- ▶ Use CP decomposition with Q classes
- ▶ Use full Tucker (NNTUCK) with a core size such that $|\Lambda| \approx Q$



More parameter sharing than CP, and larger latent space than full Tucker.

POISSON AL ℓ_0 CORE

how active **country** i is
in (sender) **community** $c[q]$

$$y_{i \xrightarrow{a} j}^{(t)} \sim \text{Pois} \left(\sum_{q=1}^Q \psi_{i,c[q]}^{(\rightarrow)} \psi_{j,d[q]}^{(\leftarrow)} \phi_{a,k[q]} \theta_{r[q]}^{(t)} \lambda_q \right)$$

POISSON AL ℓ_0 CORE

$$y_{i \xrightarrow{a} j}^{(t)} \sim \text{Pois} \left(\sum_{q=1}^Q \psi_{i,c[q]}^{(\rightarrow)} \psi_{j,d[q]}^{(\leftarrow)} \phi_{a,k[q]} \theta_{r[q]}^{(t)} \lambda_q \right)$$

↓
how active **country** j is
in (receiver) **community** $d[q]$

POISSON AL ℓ_0 CORE

$$y_{i \xrightarrow{a} j}^{(t)} \sim \text{Pois} \left(\sum_{q=1}^Q \psi_{i,c[q]}^{(\rightarrow)} \psi_{j,d[q]}^{(\leftarrow)} \phi_{a,k[q]} \theta_{r[q]}^{(t)} \lambda_q \right)$$

↓
how prevalent **action** a is
in **topic** $k[q]$

POISSON AL ℓ_0 CORE

how active **regime** $r[q]$ is
at **time** t

$$y_{i \xrightarrow{a} j}^{(t)} \sim \text{Pois} \left(\sum_{q=1}^Q \psi_{i,c[q]}^{(\rightarrow)} \psi_{j,d[q]}^{(\leftarrow)} \phi_{a,k[q]} \theta_{r[q]}^{(t)} \lambda_q \right)$$

POISSON AL ℓ_0 CORE

$$y_{i \xrightarrow{a} j}^{(t)} \sim \text{Pois} \left(\sum_{q=1}^Q \psi_{i,c[q]}^{(\rightarrow)} \psi_{j,d[q]}^{(\leftarrow)} \phi_{a,k[q]} \theta_{r[q]}^{(t)} \lambda_q \right)$$

allocated **non-zero value** q



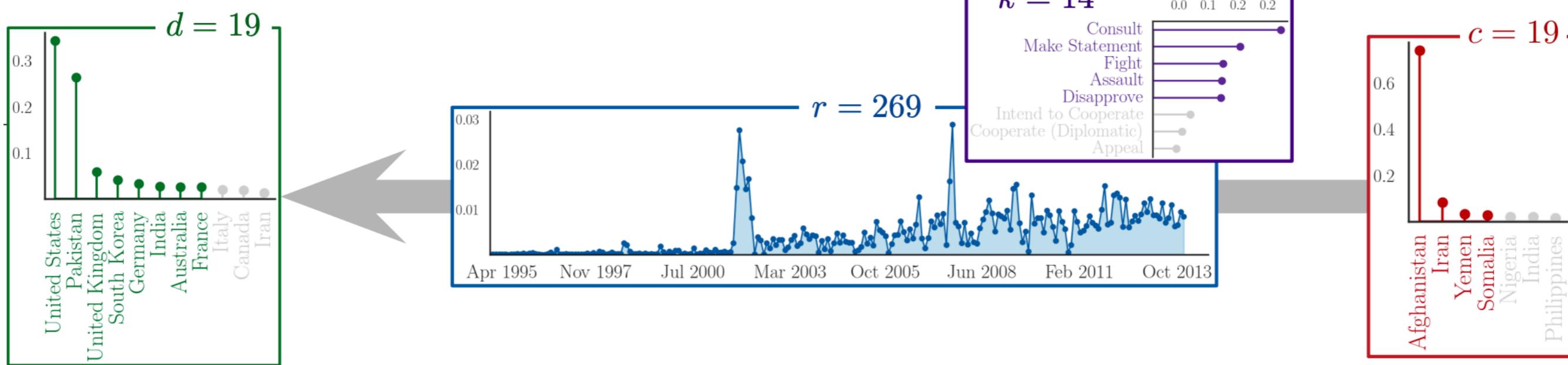
EXAMPLE OF INFERRED LATENT STRUCTURE

Inferred non-zero core elements

rank	$\lambda^{(r)}$ <small>$c \xrightarrow{k} d$</small>	c	d	k	r
1	11.03	2	2	10	252
2	10.36	31	31	9	81
3	10.36	9	9	12	159
4	10.13	33	33	9	233
5	9.58	37	37	12	87
6	9.36	12	12	2	162
7	8.9	43	43	10	43
8	8.57	41	41	2	41
9	8.35	15	15	10	115
10	8.13	11	11	16	61
			
20	6.65	49	49	9	49
21	6.61	14	14	2	14
22	6.55	23	23	9	273
23	6.35	46	46	9	196
24	6.25	22	22	2	222
25	6.24	40	40	19	40
26	6.23	19	19	14	269
27	6.14	43	43	10	143
28	6.14	6	6	19	106
29	5.92	32	32	9	132
30	5.85	47	47	12	62
31	5.77	24	24	14	124
32	5.76	9	9	12	59
33	5.67	13	13	10	252
34	5.62	25	25	9	25
35	5.57	27	27	9	177
36	5.53	17	17	14	67
37	5.42	30	30	9	30
38	5.36	5	5	10	255
39	5.34	3	3	16	3
40	5.24	10	10	10	210
			

- ▶ ICEWS tensor (1995-2013), monthly: (250 x 250 x 20 x 228)
- ▶ Core size: (50 x 50 x 20 x 300) → 15 million (possible) classes
- ▶ $Q = 400$

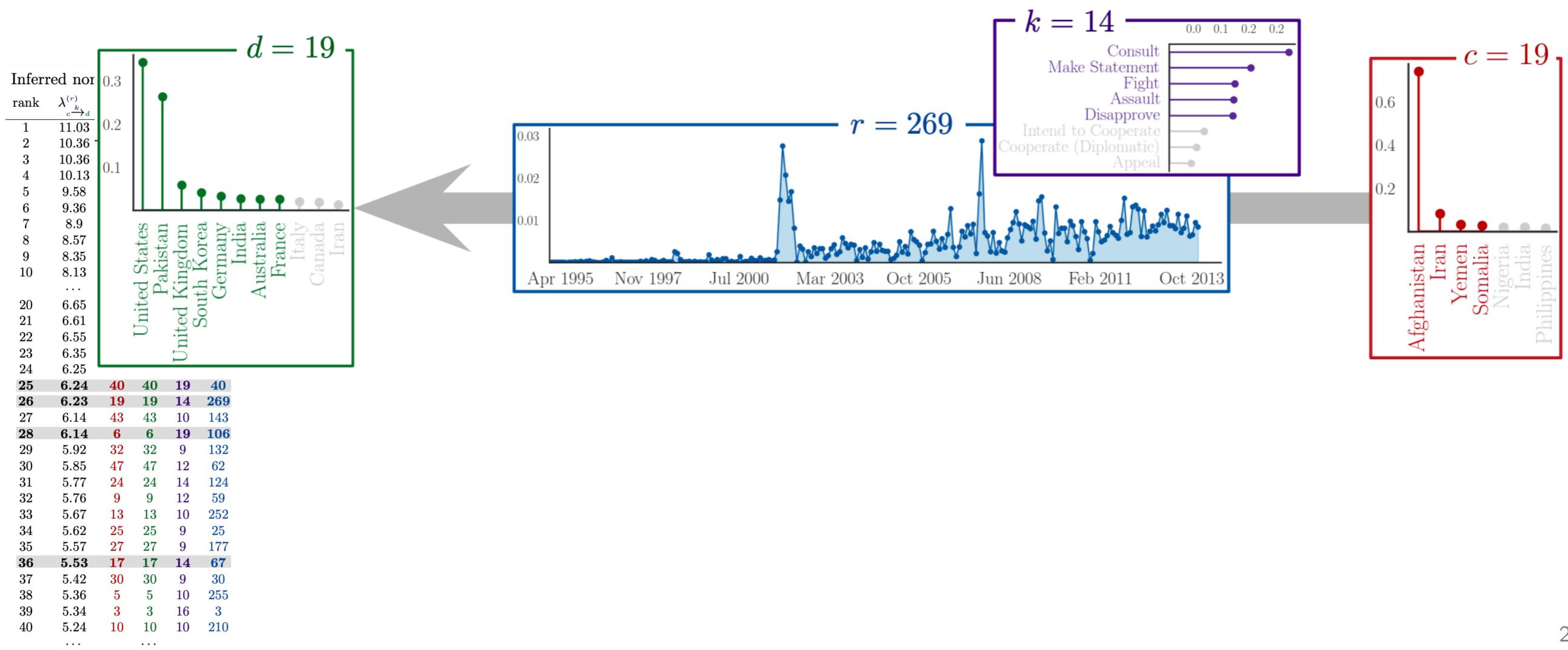
EXAMPLE OF INFERRED LATENT STRUCTURE



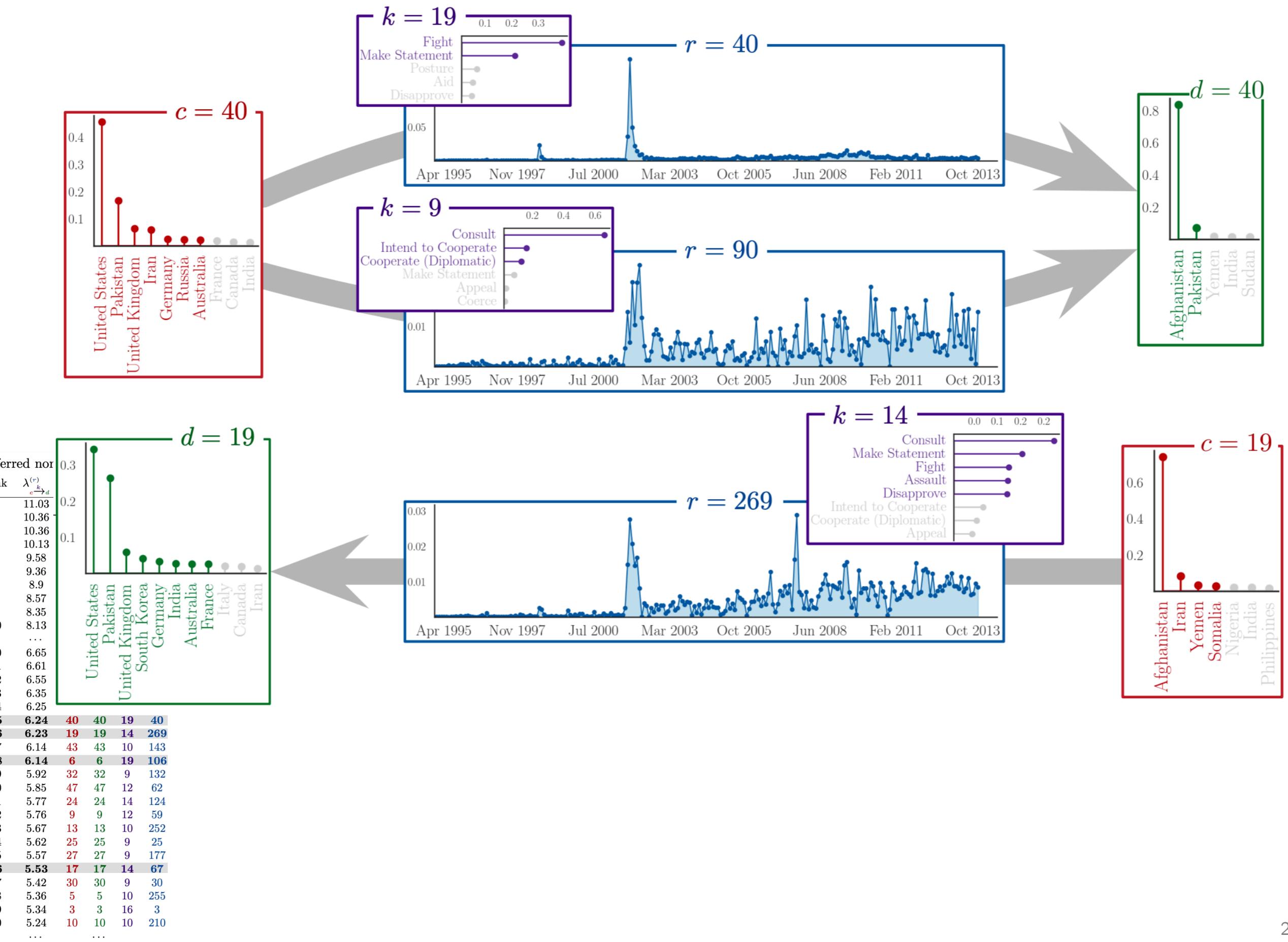
Inferred non-zero core elements

rank	$\lambda_{e \rightarrow d}^{(r)}$	c	d	k	r
1	11.03	2	2	10	252
2	10.36	31	31	9	81
3	10.36	9	9	12	159
4	10.13	33	33	9	233
5	9.58	37	37	12	87
6	9.36	12	12	2	162
7	8.9	43	43	10	43
8	8.57	41	41	2	41
9	8.35	15	15	10	115
10	8.13	11	11	16	61
...	...				
20	6.65	49	49	9	49
21	6.61	14	14	2	14
22	6.55	23	23	9	273
23	6.35	46	46	9	196
24	6.25	22	22	2	222
25	6.24	40	40	19	40
26	6.23	19	19	14	269
27	6.14	43	43	10	143
28	6.14	6	6	19	106
29	5.92	32	32	9	132
30	5.85	47	47	12	62
31	5.77	24	24	14	124
32	5.76	9	9	12	59
33	5.67	13	13	10	252
34	5.62	25	25	9	25
35	5.57	27	27	9	177
36	5.53	17	17	14	67
37	5.42	30	30	9	30
38	5.36	5	5	10	255
39	5.34	3	3	16	3
40	5.24	10	10	10	210
...	...				

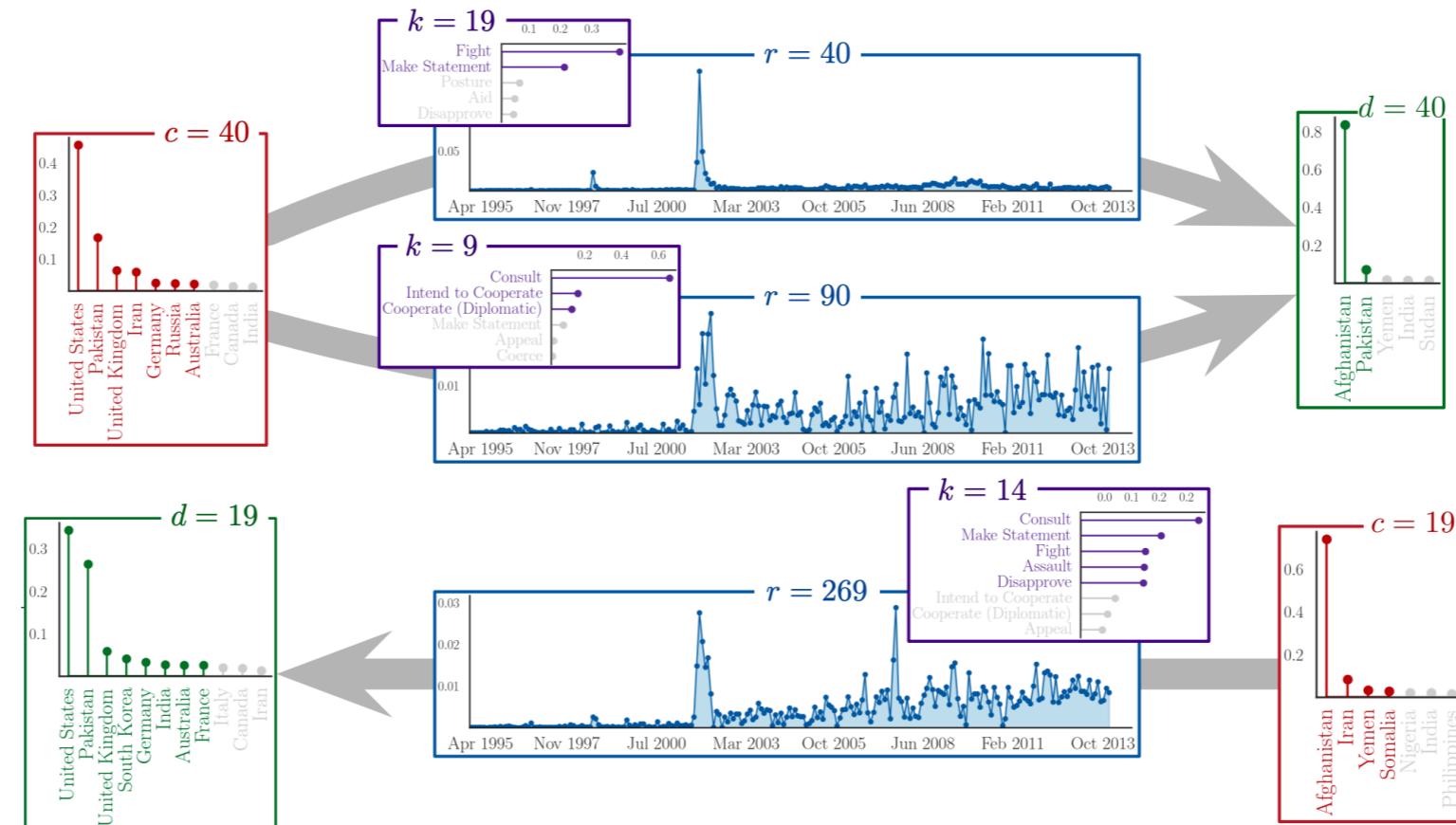
EXAMPLE OF INFERRED LATENT STRUCTURE



EXAMPLE OF INFERRED LATENT STRUCTURE



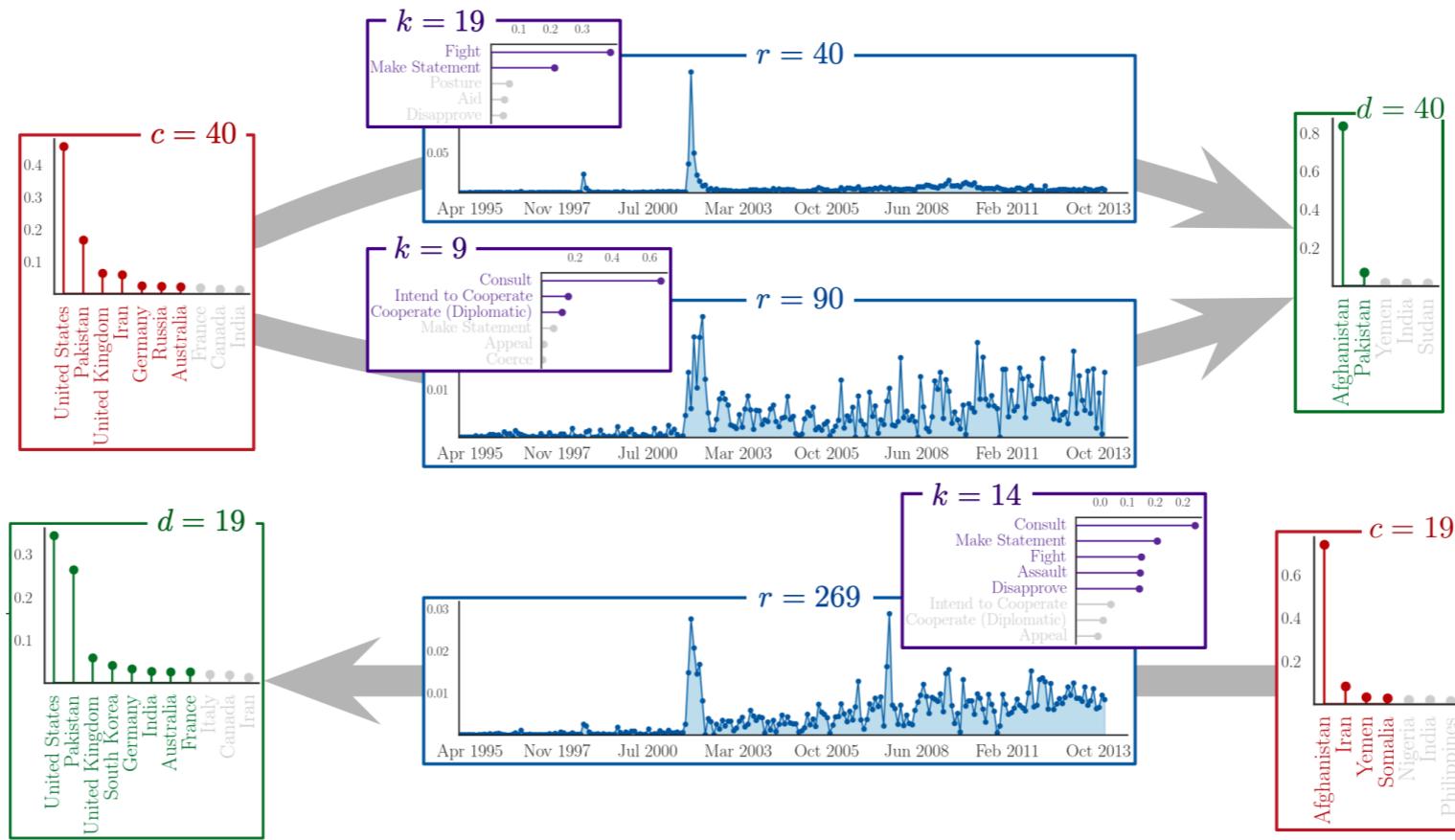
EXAMPLE OF INFERRRED LATENT STRUCTURE



Inferred non-zero core elements

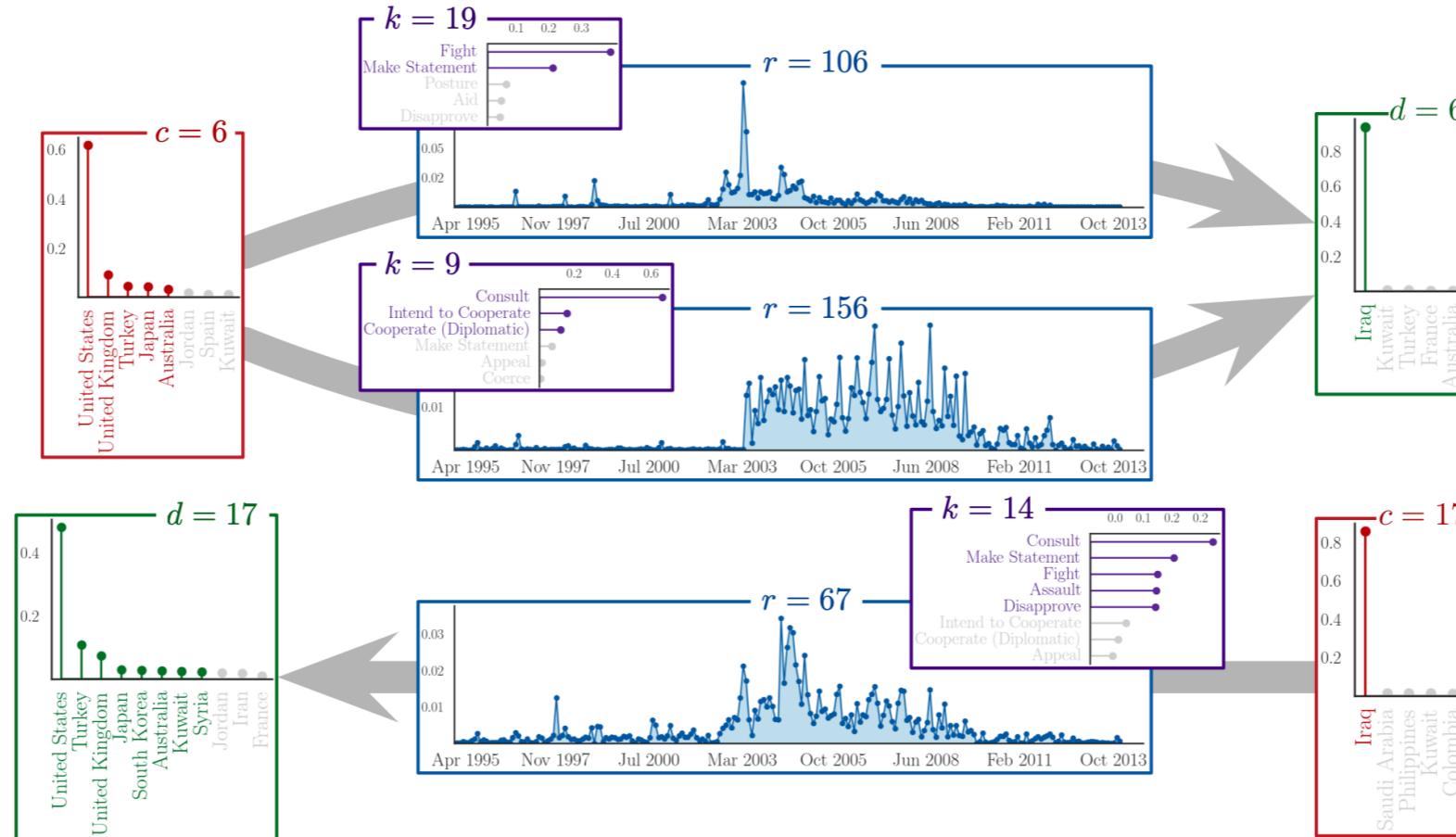
rank	$\lambda_{e \rightarrow d}^{(r)}$	c	d	k	r
1	11.03	2	2	10	252
2	10.36	31	31	9	81
3	10.36	9	9	12	159
4	10.13	33	33	9	233
5	9.58	37	37	12	87
6	9.36	12	12	2	162
7	8.9	43	43	10	43
8	8.57	41	41	2	41
9	8.35	15	15	10	115
10	8.13	11	11	16	61
...	...				
20	6.65	49	49	9	49
21	6.61	14	14	2	14
22	6.55	23	23	9	273
23	6.35	46	46	9	196
24	6.25	22	22	2	222
25	6.24	40	40	19	40
26	6.23	19	19	14	269
27	6.14	43	43	10	143
28	6.14	6	6	19	106
29	5.92	32	32	9	132
30	5.85	47	47	12	62
31	5.77	24	24	14	124
32	5.76	9	9	12	59
33	5.67	13	13	10	252
34	5.62	25	25	9	25
35	5.57	27	27	9	177
36	5.53	17	17	14	67
37	5.42	30	30	9	30
38	5.36	5	5	10	255
39	5.34	3	3	16	3
40	5.24	10	10	10	210
...	...				

EXAMPLE OF INFERRRED LATENT STRUCTURE

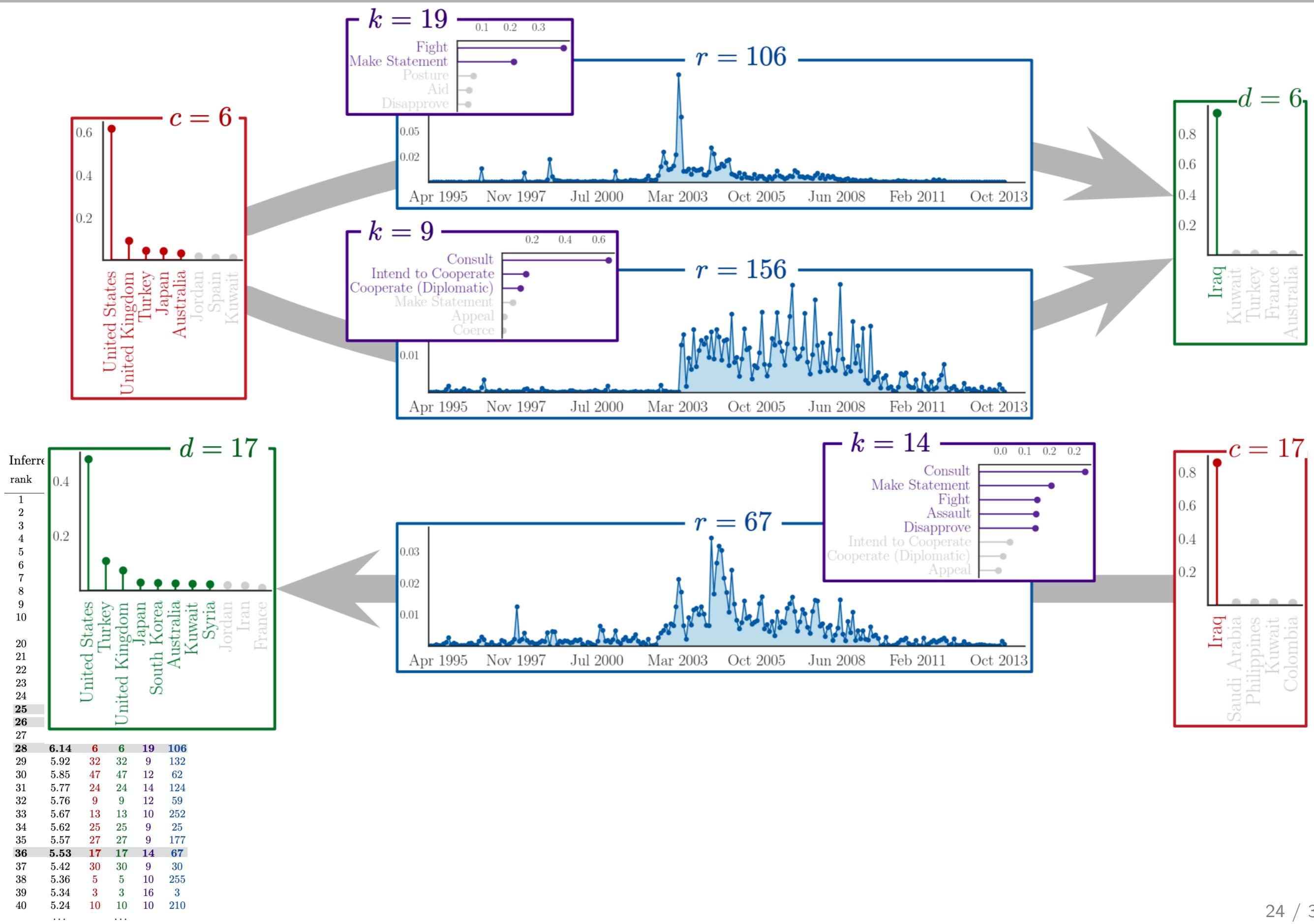


Inferred non-zero core elements

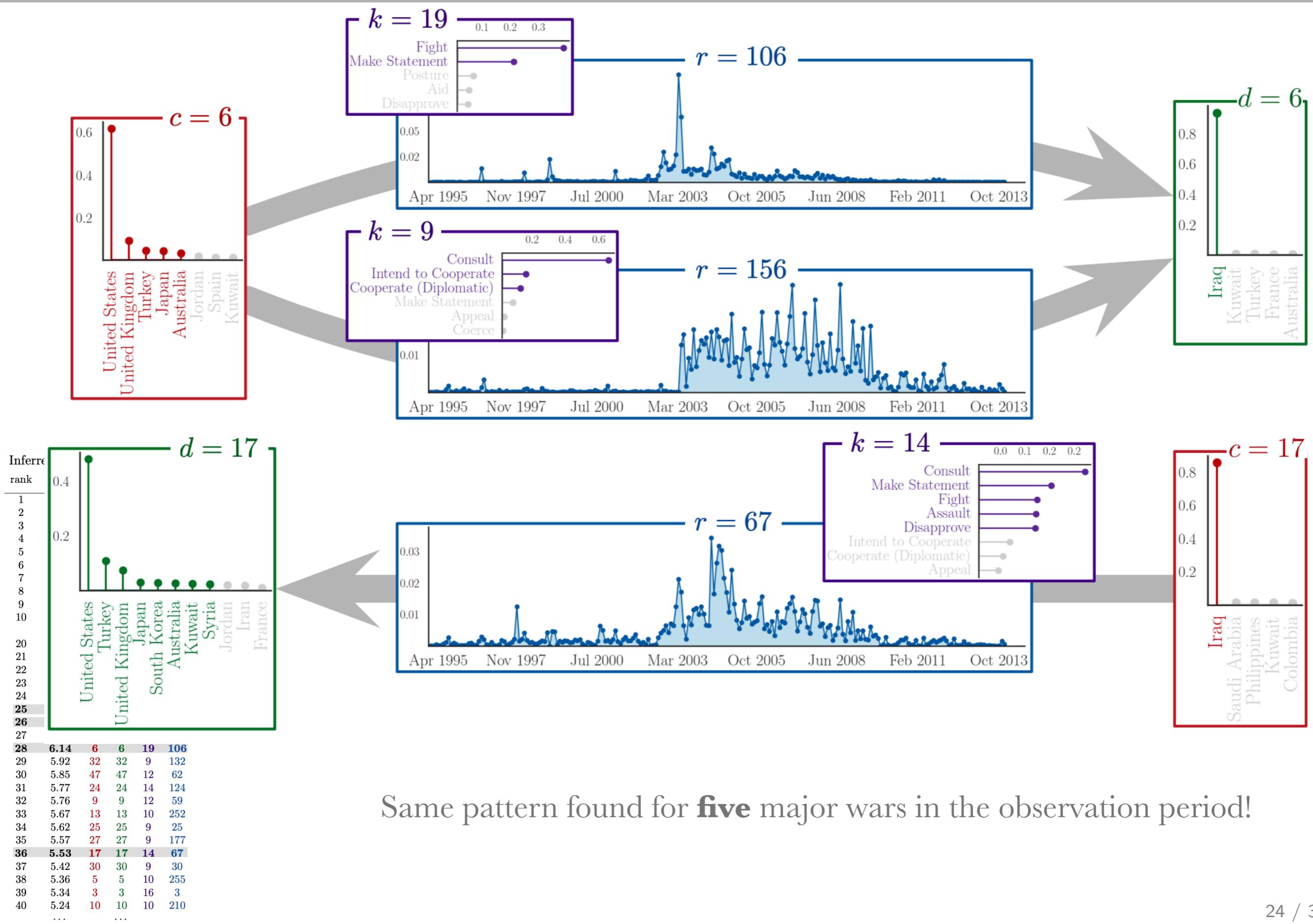
rank	$\lambda_{e \rightarrow k \rightarrow d}^{(r)}$	c	d	k	r
1	11.03	2	2	10	252
2	10.36	31	31	9	81
3	10.36	9	9	12	159
4	10.13	33	33	9	233
5	9.58	37	37	12	87
6	9.36	12	12	2	162
7	8.9	43	43	10	43
8	8.57	41	41	2	41
9	8.35	15	15	10	115
10	8.13	11	11	16	61
...	...				
20	6.65	49	49	9	49
21	6.61	14	14	2	14
22	6.55	23	23	9	273
23	6.35	46	46	9	196
24	6.25	22	22	2	222
25	6.24	40	40	19	40
26	6.23	19	19	14	269
27	6.14	43	43	10	143
28	6.14	6	6	19	106
29	5.92	32	32	9	132
30	5.85	47	47	12	62
31	5.77	24	24	14	124
32	5.76	9	9	12	59
33	5.67	13	13	10	252
34	5.62	25	25	9	25
35	5.57	27	27	9	177
36	5.53	17	17	14	67
37	5.42	30	30	9	30
38	5.36	5	5	10	255
39	5.34	3	3	16	3
40	5.24	10	10	10	210
...	...				



EXAMPLE OF INFERRED LATENT STRUCTURE

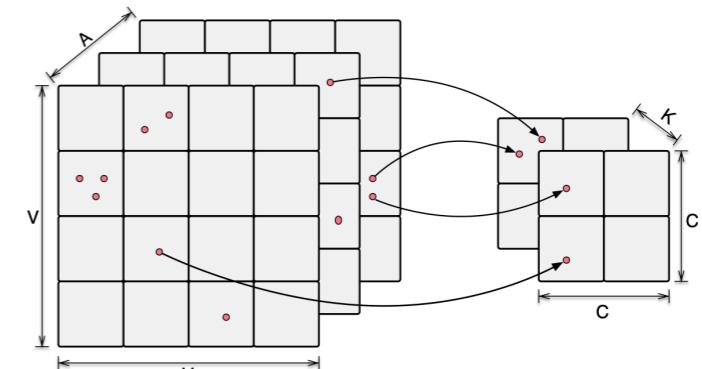


EXAMPLE OF INFERRED LATENT STRUCTURE

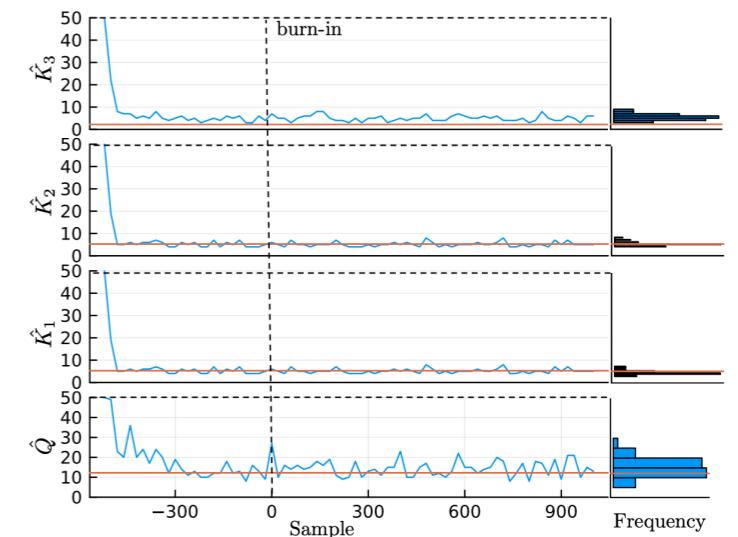


DISCUSSION / FUTURE

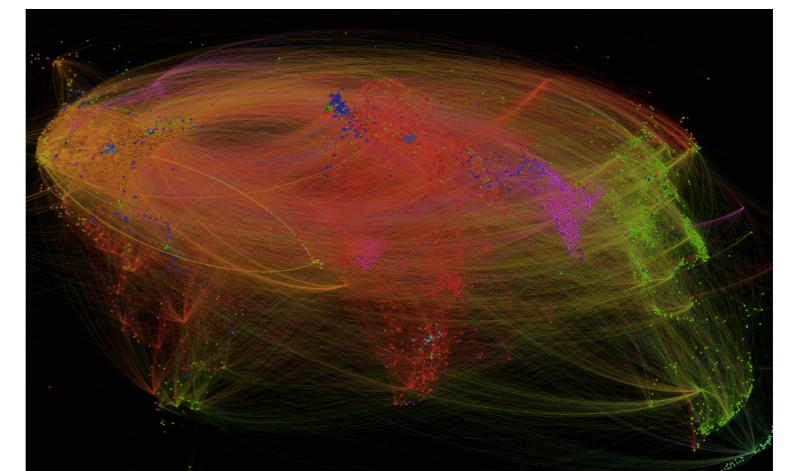
- ▶ **Sparse token allocation** as a principle
(observed or latent)



- ▶ Allocated **sparsity in factor matrices**;
different motivation:
 - ▶ Interpretability (e.g., thresholding)
 - ▶ Identifiability (e.g., anchor features)



- ▶ Didn't talk about: **inferring Q**
- ▶ More on dyadic events:
 - ▶ Modeling everything by **publisher**
 - ▶ Modeling everything by **data set**
- ▶ One current extension / focus: **hypergraphs**
 - ▶ e.g., degree-5 networks → HUGE core tensors



BETTER INFERENCE

- **Dependent** prior for locations and values:

$$\boldsymbol{\Pi} \sim \text{Dirichlet}(1, \dots, 1)$$

$$\kappa_q \sim \text{Categorical}(\boldsymbol{\Pi}) \text{ for } q = 1 \dots Q$$

$$\lambda_{\kappa} \sim \begin{cases} \text{Gamma}(m_{\kappa} 1) & \text{if } m_{\kappa} > 0 \\ \delta_0 & \text{otherwise} \end{cases}$$

BETTER INFERENCE

- ▶ **Dependent** prior for locations and values:

$$m_{\kappa} \triangleq \sum_{q=1}^Q \mathbf{1}(\kappa_q = \kappa)$$

$$\Pi \sim \text{Dirichlet}(1, \dots, 1) \longrightarrow \Pi \sim \text{Dirichlet}(1, \dots, 1)$$

$$\kappa_q \sim \text{Categorical}(\Pi) \text{ for } q = 1 \dots Q \rightarrow \mathbf{M} \sim \text{Multinomial}(Q, \Pi)$$

$$\lambda_{\kappa} \sim \begin{cases} \text{Gamma}(m_{\kappa} 1) & \text{if } m_{\kappa} > 0 \\ \delta_0 & \text{otherwise} \end{cases}$$

BETTER INFERENCE

- ▶ **Dependent** prior for locations and values:

$$m_{\kappa} \triangleq \sum_{q=1}^Q \mathbf{1}(\kappa_q = \kappa)$$

$$\lambda_{\kappa} \triangleq \tilde{\lambda}_{\kappa} \lambda_{\bullet}$$

$$\Pi \sim \text{Dirichlet}(1, \dots, 1) \longrightarrow \Pi \sim \text{Dirichlet}(1, \dots, 1)$$

$$\kappa_q \sim \text{Categorical}(\Pi) \text{ for } q = 1 \dots Q \rightarrow \mathbf{M} \sim \text{Multinomial}(Q, \Pi)$$

Sum-proportion independence of gammas [Lukacs 1956]

“Delta Dirichlet” distribution [Lewy 1996]

$$\lambda_{\kappa} \sim \begin{cases} \text{Gamma}(m_{\kappa} 1) & \text{if } m_{\kappa} > 0 \\ \delta_0 & \text{otherwise} \end{cases} \longrightarrow \tilde{\Lambda} \sim \text{DeltaDirichlet}(\mathbf{M})$$
$$\lambda_{\bullet} \sim \text{Gamma}(Q, 1)$$

BETTER INFERENCE

- **Dependent** prior for locations and values:

$$m_{\kappa} \triangleq \sum_{q=1}^Q \mathbf{1}(\kappa_q = \kappa)$$

$$\lambda_{\kappa} \triangleq \tilde{\lambda}_{\kappa} \lambda_{\bullet}$$

$$\Pi \sim \text{Dirichlet}(1, \dots, 1) \longrightarrow \Pi \sim \text{Dirichlet}(1, \dots, 1)$$

$$\kappa_q \sim \text{Categorical}(\Pi) \text{ for } q = 1 \dots Q \rightarrow \mathbf{M} \sim \text{Multinomial}(Q, \Pi)$$

Sum-proportion independence of gammas [Lukacs 1956]

“Delta Dirichlet” distribution [Lewy 1996]

$$\lambda_{\kappa} \sim \begin{cases} \text{Gamma}(m_{\kappa} 1) & \text{if } m_{\kappa} > 0 \\ \delta_0 & \text{otherwise} \end{cases} \longrightarrow \tilde{\Lambda} \sim \text{DeltaDirichlet}(\mathbf{M})$$
$$\lambda_{\bullet} \sim \text{Gamma}(Q, 1)$$

$$y_{\mathbf{i}, \kappa} \sim \text{Pois} (\lambda_{\kappa} \dots)$$

BETTER INFERENCE

- **Dependent** prior for locations and values:

$$m_{\kappa} \triangleq \sum_{q=1}^Q \mathbf{1}(\kappa_q = \kappa)$$

$$\lambda_{\kappa} \triangleq \tilde{\lambda}_{\kappa} \lambda_{\bullet}$$

$$\Pi \sim \text{Dirichlet}(1, \dots, 1) \longrightarrow \Pi \sim \text{Dirichlet}(1, \dots, 1)$$

$$\kappa_q \sim \text{Categorical}(\Pi) \text{ for } q = 1 \dots Q \rightarrow \mathbf{M} \sim \text{Multinomial}(Q, \Pi)$$

Sum-proportion independence of gammas [Lukacs 1956]

“Delta Dirichlet” distribution [Lewy 1996]

$$\lambda_{\kappa} \sim \begin{cases} \text{Gamma}(m_{\kappa} 1) & \text{if } m_{\kappa} > 0 \\ \delta_0 & \text{otherwise} \end{cases} \longrightarrow \tilde{\Lambda} \sim \text{DeltaDirichlet}(\mathbf{M})$$

“Latent source” representation

$$y_{\mathbf{i}, \kappa} \sim \text{Pois}(\lambda_{\kappa} \dots) \longrightarrow \begin{aligned} y_{\bullet} &\sim \text{Pois}(\lambda_{\bullet} \dots) \\ (y_{\kappa})_{\kappa} &\sim \text{Multinomial}\left(y_{\bullet}, \tilde{\Lambda}\right) \end{aligned}$$

BETTER INFERENCE

- **Dependent** prior for locations and values:

$$m_{\kappa} \triangleq \sum_{q=1}^Q \mathbf{1}(\kappa_q = \kappa)$$

$$\lambda_{\kappa} \triangleq \tilde{\lambda}_{\kappa} \lambda_{\bullet}$$

$$\Pi \sim \text{Dirichlet}(1, \dots, 1) \longrightarrow \Pi \sim \text{Dirichlet}(1, \dots, 1)$$

$$\kappa_q \sim \text{Categorical}(\Pi) \text{ for } q = 1 \dots Q \rightarrow \mathbf{M} \sim \text{Multinomial}(Q, \Pi)$$

Sum-proportion independence of gammas [Lukacs 1956]

“Delta Dirichlet” distribution [Lewy 1996]

$$\lambda_{\kappa} \sim \begin{cases} \text{Gamma}(m_{\kappa} 1) & \text{if } m_{\kappa} > 0 \\ \delta_0 & \text{otherwise} \end{cases} \longrightarrow \tilde{\Lambda} \sim \text{DeltaDirichlet}(\mathbf{M})$$

$$y_{\mathbf{i}, \kappa} \sim \text{Pois}(\lambda_{\kappa} \dots) \longrightarrow \lambda_{\bullet} \sim \text{Gamma}(Q, 1)$$

$$(y_{\kappa})_{\kappa} \sim \text{Multinomial}(y_{\bullet}, \tilde{\Lambda})$$

$\mathbf{M} \sim \text{DirMult}(Q, 1, \dots, 1)$	$\lambda_{\bullet} \sim \text{Gamma}(Q, 1)$
$(y_{\kappa})_{\kappa} \sim \text{DeltaDirMult}(y_{\bullet}, \mathbf{M})$	$y_{\bullet} \sim \text{Pois}(\lambda_{\bullet} \dots)$

BETTER INFERENCE

- ▶ Update to λ_\bullet is conjugate
- ▶ New(?) form of “quasi”-conjugacy:

$$(\mathbf{M} \mid -) = \mathbf{1}(\mathbf{Y} > 0) + \mathbf{M}'$$

$$\mathbf{M}' \sim \text{DirMult}(Q - \|\mathbf{Y}\|_0, 1 + \mathbf{Y})$$

- ▶ We can sample \mathbf{M}' exactly using an urn scheme that is $\mathcal{O}(Q)$

$$\begin{array}{ll} \mathbf{M} \sim \text{DirMult}(Q, 1, \dots, 1) & \lambda_\bullet \sim \text{Gamma}(Q, 1) \\ \left(y_\kappa\right)_\kappa \sim \text{DeltaDirMult}(y_\bullet, \mathbf{M}) & y_\bullet \sim \text{Pois}(\lambda_\bullet \dots) \end{array}$$

OUTLINE

- ▶ Motivation: Dyadic event data (and its challenges)
- ▶ Non-negative (Poisson) tensor decompositions
 - ▶ CP extracts “multilateral” structure [[Schein et al., 2015](#)]
 - ▶ Tucker extracts “communities” [[Schein et al., 2016](#)]
 - ▶ Why (allocative) Poisson factorization
 - ▶ AL ℓ_0 CORE avoids the “exponential blowup” [[Hood & Schein, 2024](#)]

Appendix (*time permitting*)

- ▶ State-space modeling
 - ▶ Gamma state-space models [[Schein et al., 2016b; Schein et al., 2019](#)]
 - ▶ Modeling “escalation” with a new matrix prior [[Stoehr et al., 2023](#)]

OUTLINE

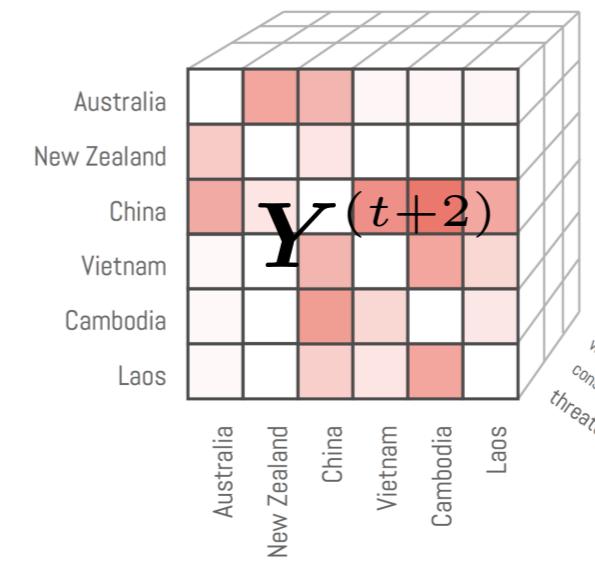
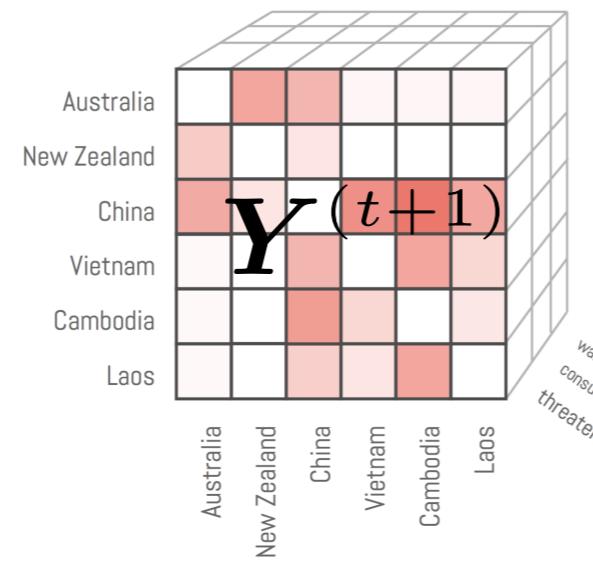
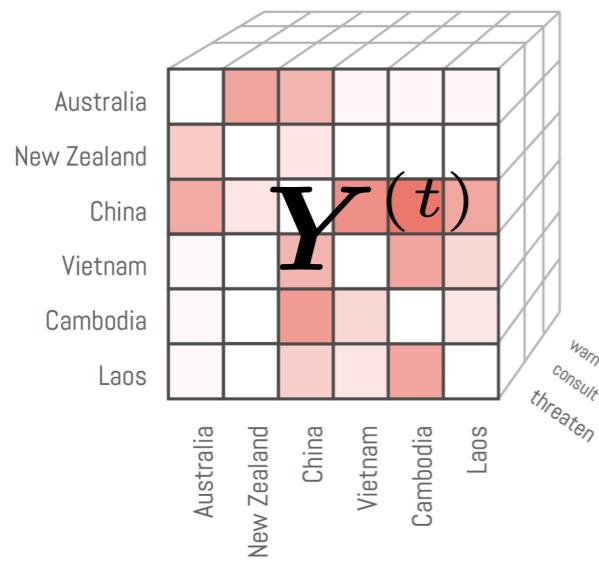
- ▶ Motivation: Dyadic event data (and its challenges)
- ▶ Non-negative (Poisson) tensor decompositions
 - ▶ CP extracts “multilateral” structure [Schein et al., 2015]
 - ▶ Tucker extracts “communities” [Schein et al., 2016]
 - ▶ Why (allocative) Poisson factorization
 - ▶ AL ℓ_0 CORE avoids the “exponential blowup” [Hood & Schein, 2024]

Appendix (*time permitting*)

- ▶ State-space modeling
 - ▶ Gamma state-space models [Schein et al., 2016b; Schein et al., 2019]
 - ▶ Modeling “escalation” with a new matrix prior [Stoehr et al., 2023]

Building in temporal structure

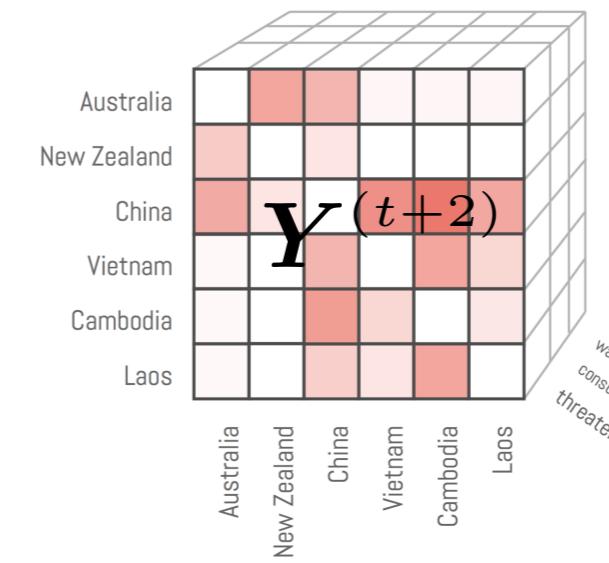
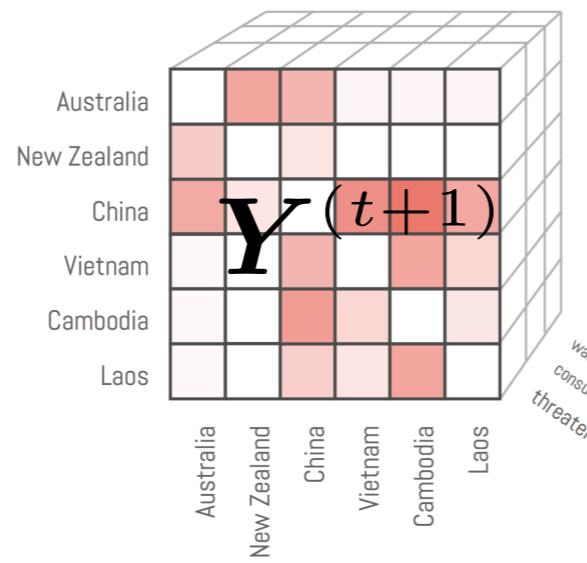
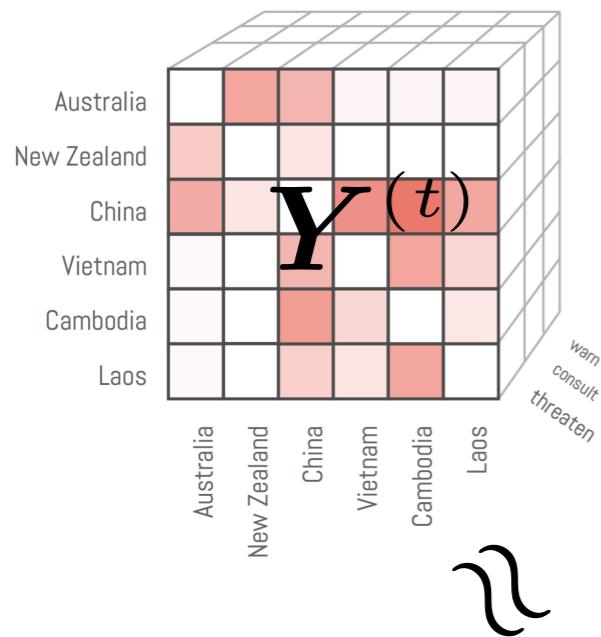
dynamic tensor



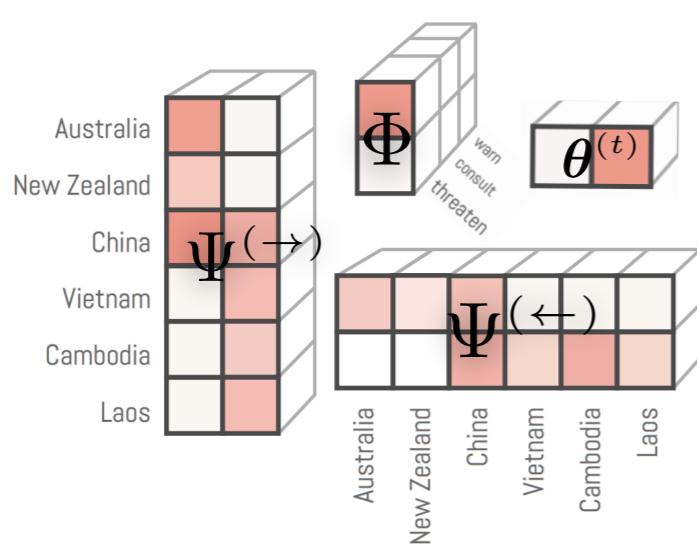
• • •

Building in temporal structure

dynamic tensor

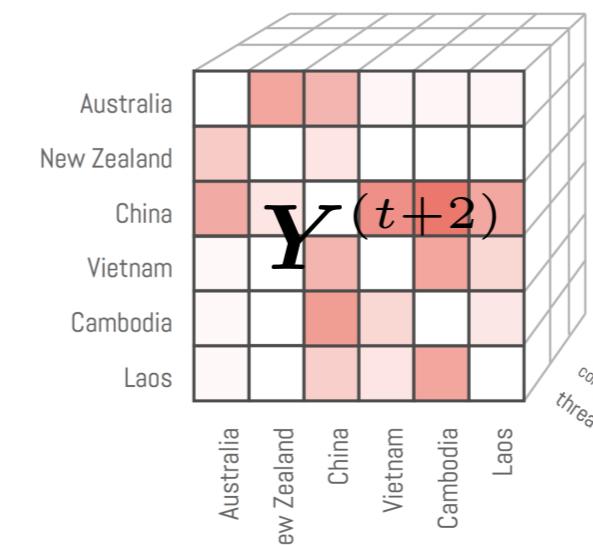
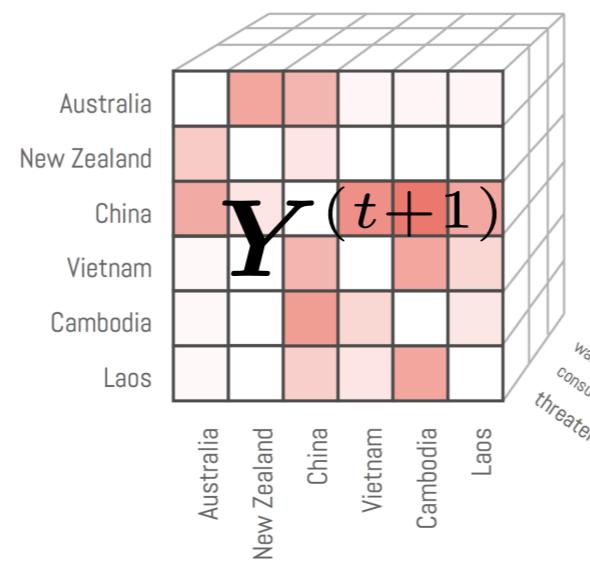
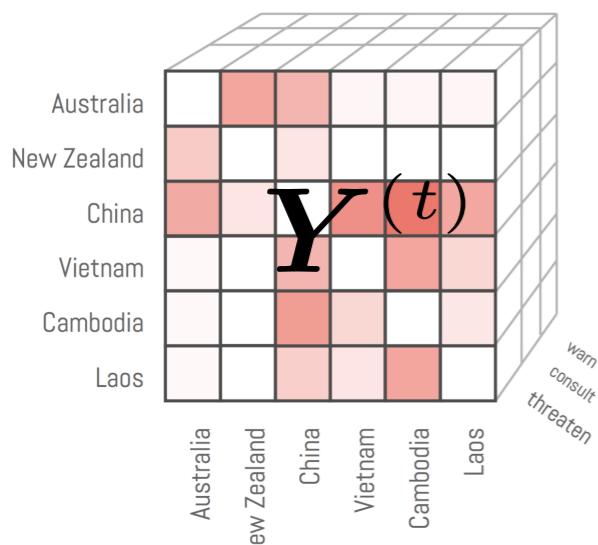


• • •

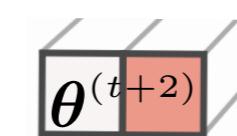
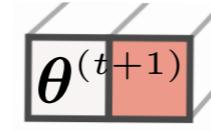
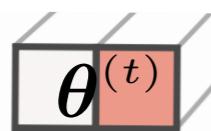


Building in temporal structure

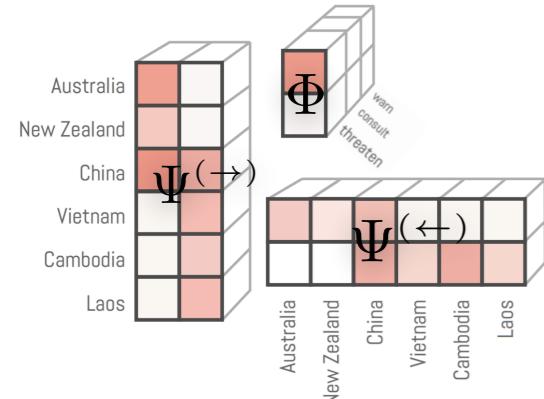
dynamic tensor



• • •

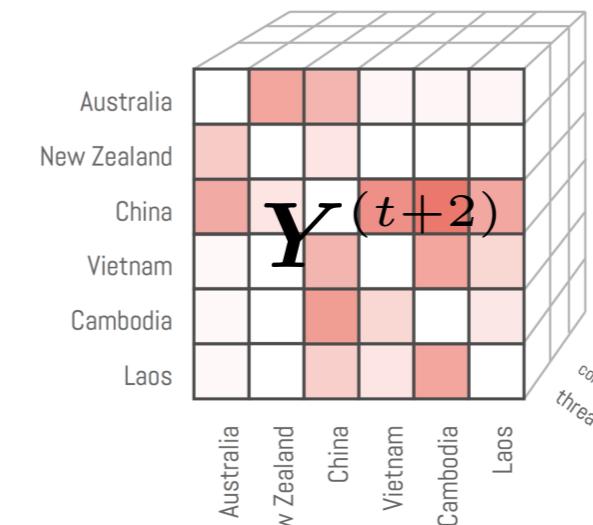
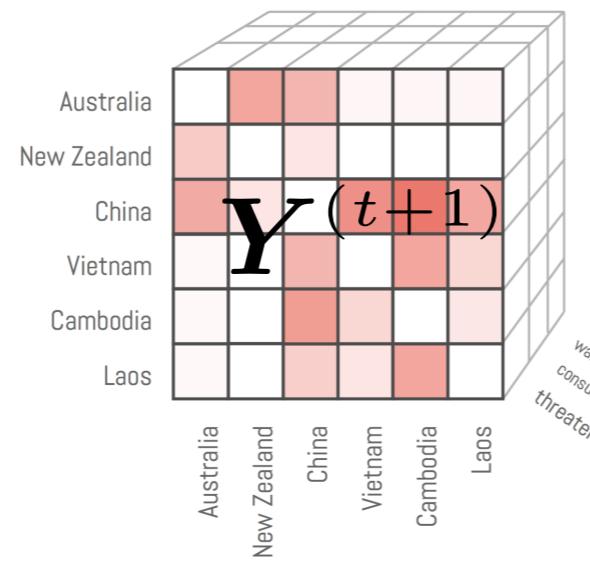
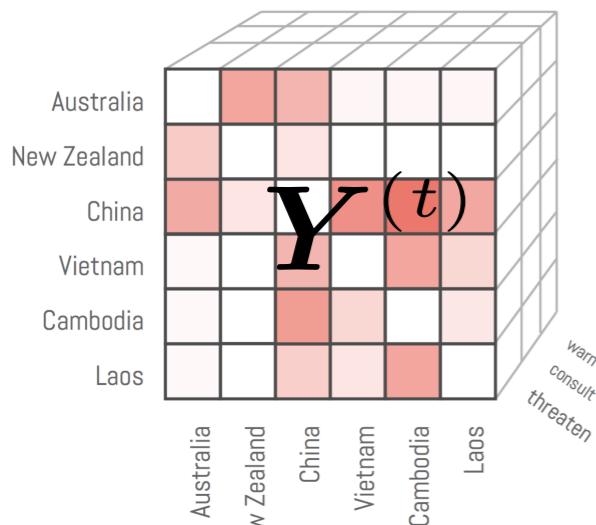


dynamic latent states



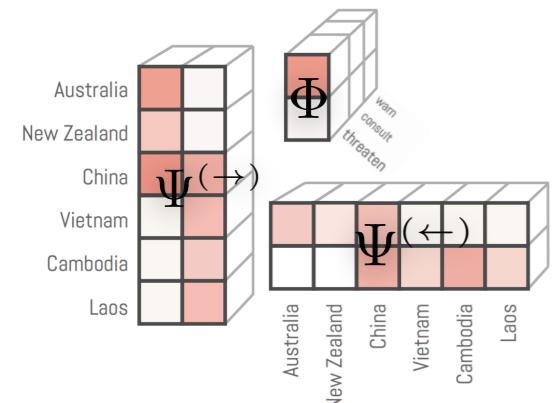
Building in temporal structure

dynamic tensor



• • •

dynamic latent states



Goal: Build in temporal structure.

$$\theta^{(t)} \sim P(\theta^{(t)} | \theta^{(t-1)})$$

Building in temporal structure

Goal: Build in temporal structure.

$$\boldsymbol{\theta}^{(t)} \sim P(\boldsymbol{\theta}^{(t)} | \boldsymbol{\theta}^{(t-1)})$$

Challenge: Stay within *allocative Poisson factorization*

$$y_{\mathbf{i}} \sim \text{Pois}\left(\sum \cdots\right)$$

with APF, good things happen...

- **robust** to sparsity, overdispersion, burstiness
- model-fitting **scales with number of non-zeros**

Building in temporal structure

Goal: Build in temporal structure.

$$\boldsymbol{\theta}^{(t)} \sim P(\boldsymbol{\theta}^{(t)} | \boldsymbol{\theta}^{(t-1)})$$

Challenge: Stay within *allocative Poisson factorization*

$$y_{\mathbf{i}} \sim \text{Pois}\left(\sum \cdots\right)$$

with APF, good things happen...

- **robust** to sparsity, overdispersion, burstiness
- model-fitting **scales with number of non-zeros**

...but!

- only **non-negative priors!**
- (no Gaussians.)

Building in temporal structure

Goal: Build in temporal structure.

$$\boldsymbol{\theta}^{(t)} \sim P(\boldsymbol{\theta}^{(t)} | \boldsymbol{\theta}^{(t-1)})$$

Challenge: Stay within *allocative Poisson factorization*

$$y_i \sim \text{Pois}\left(\sum \dots\right)$$

Poisson LDS [Macke et al., 2011]

$$y_i \sim \text{Pois}\left(\exp\left(\sum \dots\right)\right)$$

with APF, good things happen...

- **robust** to sparsity, overdispersion, burstiness
- model-fitting **scales with number of non-zeros**

...but!

- only **non-negative priors!**
- (no Gaussians.)

Gaussian priors:



Building in temporal structure

Goal: Build in temporal structure.

$$\boldsymbol{\theta}^{(t)} \sim P(\boldsymbol{\theta}^{(t)} | \boldsymbol{\theta}^{(t-1)})$$

Challenge: Stay within *allocative Poisson factorization*

$$y_{\mathbf{i}} \sim \text{Pois}\left(\sum \dots\right)$$

with APF, good things happen...

- **robust** to sparsity, overdispersion, burstiness
- model-fitting **scales with number of non-zeros**

...but!

- only **non-negative priors!**
- (no Gaussians.)

Non-negative priors:



OUTLINE

- ▶ Motivation: Dyadic event data (and its challenges)
- ▶ Non-negative (Poisson) tensor decompositions
 - ▶ CP extracts “multilateral” structure [Schein et al., 2015]
 - ▶ Tucker extracts “communities” [Schein et al., 2016]
 - ▶ Why (allocative) Poisson factorization
 - ▶ AL ℓ_0 CORE avoids the “exponential blowup” [Hood & Schein, 2024]

Appendix (*time permitting*)

- ▶ State-space modeling
 - ▶ Gamma state-space models [Schein et al., 2016b; Schein et al., 2019]
 - ▶ Modeling “escalation” with a new matrix prior [Stoehr et al., 2023]

OUTLINE

- ▶ Motivation: Dyadic event data (and its challenges)
- ▶ Non-negative (Poisson) tensor decompositions
 - ▶ CP extracts “multilateral” structure [Schein et al., 2015]
 - ▶ Tucker extracts “communities” [Schein et al., 2016]
 - ▶ Why (allocative) Poisson factorization
 - ▶ AL ℓ_0 CORE avoids the “exponential blowup” [Hood & Schein, 2024]

Appendix (*time permitting*)

- ▶ State-space modeling
 - ▶ Gamma state-space models [Schein et al., 2016b; Schein et al., 2019]
 - ▶ Modeling “escalation” with a new matrix prior [Stoehr et al., 2023]

Poisson—gamma dynamical systems

[NeurIPS '16]

$$\theta_k^{(t)} \sim \text{Gam} \left(\tau_0 \sum_{k'=1}^K \pi_{kk'} \theta_{k'}^{(t-1)}, \tau_0 \right)$$

Poisson—gamma dynamical systems

[NeurIPS '16]

$$\theta_k^{(t)} \sim \text{Gam} \left(\tau_0 \sum_{k'=1}^K \pi_{kk'} \theta_{k'}^{(t-1)}, \tau_0 \right)$$

Poisson—gamma dynamical systems

[NeurIPS '16]

$$\theta_k^{(t)} \sim \text{Gam} \left(\tau_0 \sum_{k'=1}^K \pi_{kk'} \theta_{k'}^{(t-1)}, \tau_0 \right)$$



how active component k'
is at time step $t-1$

Poisson—gamma dynamical systems

[NeurIPS '16]

$$\theta_k^{(t)} \sim \text{Gam} \left(\tau_0 \sum_{k'=1}^K \pi_{kk'} \theta_{k'}^{(t-1)}, \tau_0 \right)$$

the probability of transitioning
from component k' into k

Poisson—gamma dynamical systems

[NeurIPS '16]

$$\theta_k^{(t)} \sim \text{Gam} \left(\tau_0 \sum_{k'=1}^K \pi_{kk'} \theta_{k'}^{(t-1)}, \tau_0 \right)$$

$$\boxed{\sum_{k=1}^K \pi_{kk'} = 1}$$

the probability of transitioning
from component k' into k

Poisson—gamma dynamical systems

[NeurIPS '16]

$$\theta_k^{(t)} \sim \text{Gam} \left(\tau_0 \sum_{k'=1}^K \pi_{kk'} \theta_{k'}^{(t-1)}, \tau_0 \right)$$

Poisson—gamma dynamical systems

[NeurIPS '16]

$$\theta_k^{(t)} \sim \text{Gam} \left(\tau_0 \sum_{k'=1}^K \pi_{kk'} \theta_{k'}^{(t-1)}, \tau_0 \right)$$

concentration
hyperparameter

The diagram illustrates the components of the gamma distribution parameters. It shows the formula for $\theta_k^{(t)}$ as a gamma distribution with parameters τ_0 and $\sum_{k'=1}^K \pi_{kk'} \theta_{k'}^{(t-1)}$. Two red arrows point from the labels 'concentration' and 'hyperparameter' to the respective τ_0 terms in the formula.

Poisson—gamma dynamical systems

[NeurIPS '16]

$$\mathbb{E} \left[\theta_k^{(t)} \right] = \frac{\tau_0 \sum_{k'=1}^K \pi_{kk'} \theta_{k'}^{(t-1)}}{\tau_0}$$

Poisson—gamma dynamical systems

[NeurIPS '16]

$$\mathbb{E} \left[\theta_k^{(t)} \right] = \frac{\cancel{\tau_0} \sum_{k'=1}^K \pi_{kk'} \theta_{k'}^{(t-1)}}{\cancel{\tau_0}}$$

Poisson—gamma dynamical systems

[NeurIPS '16]

$$\mathbb{E} \left[\theta_k^{(t)} \right] = \sum_{k'=1}^K \pi_{kk'} \theta_{k'}^{(t-1)}$$

Poisson—gamma dynamical systems

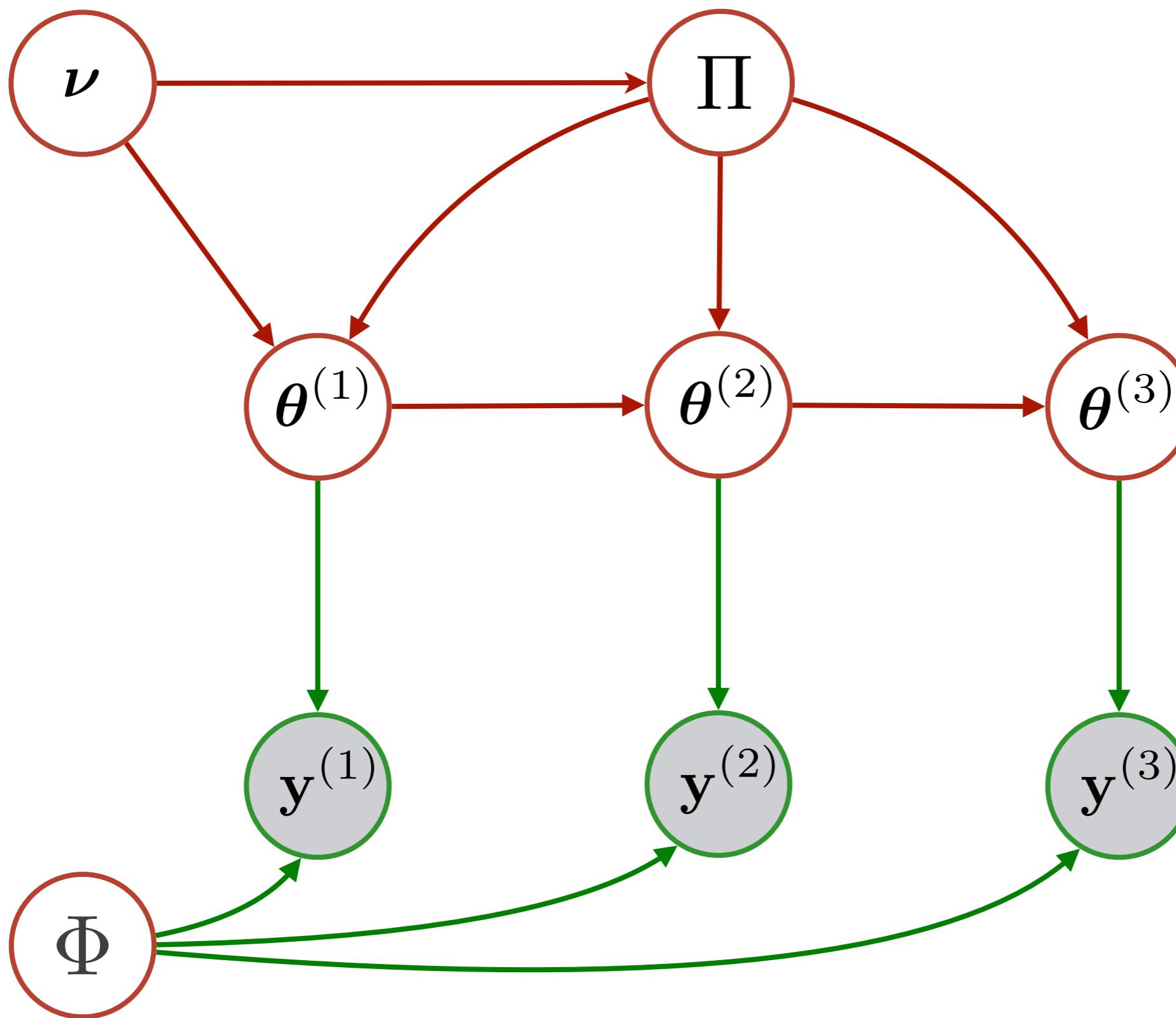
[NeurIPS '16]

$$\mathbb{E} \left[\theta^{(t)} \right] = \Pi \theta^{(t-1)}$$

$$\mathbb{E} \left[y^{(t)} \right] = \Phi \theta^{(t)}$$

(matches linear dynamical systems)

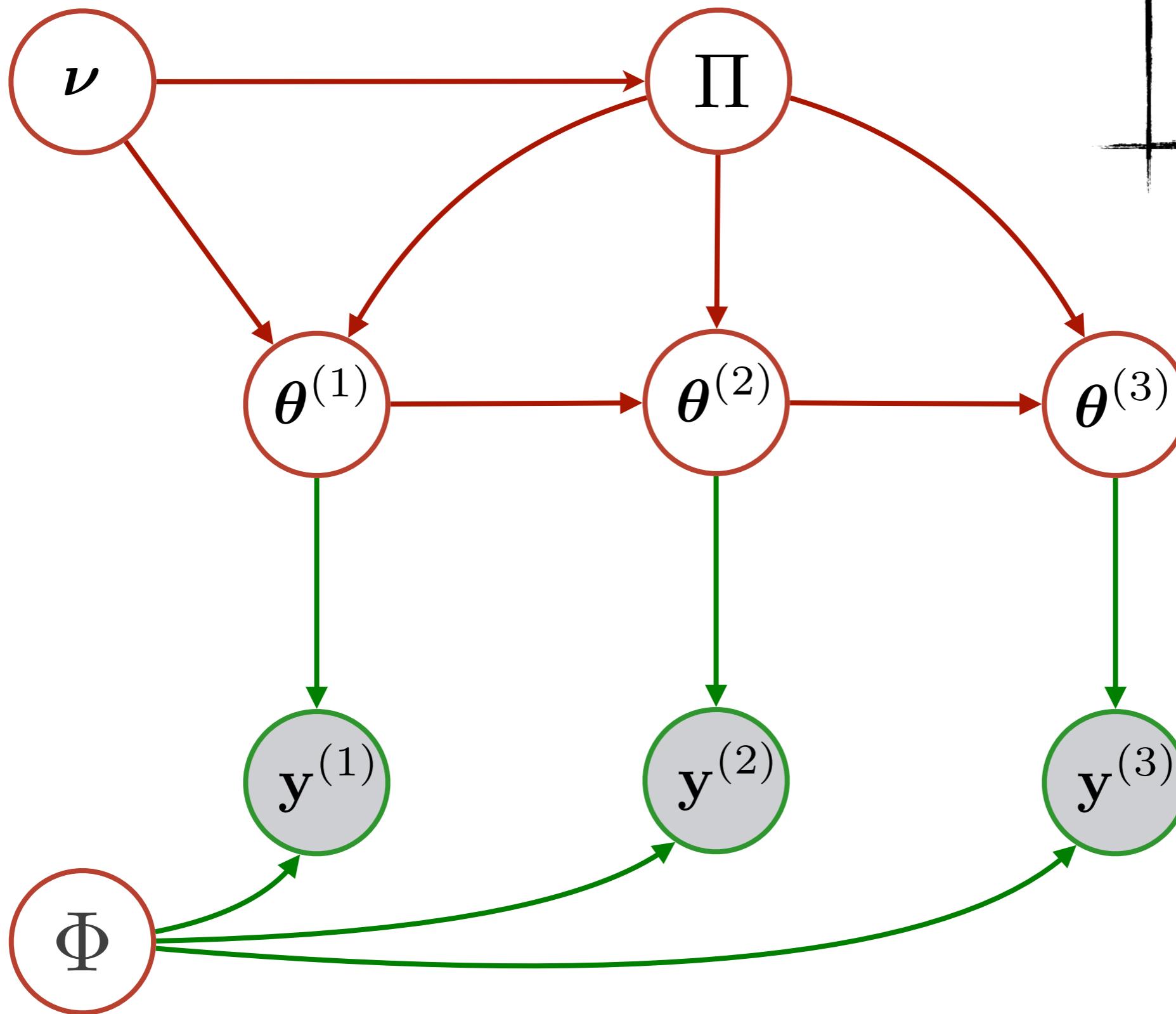
Technical challenge



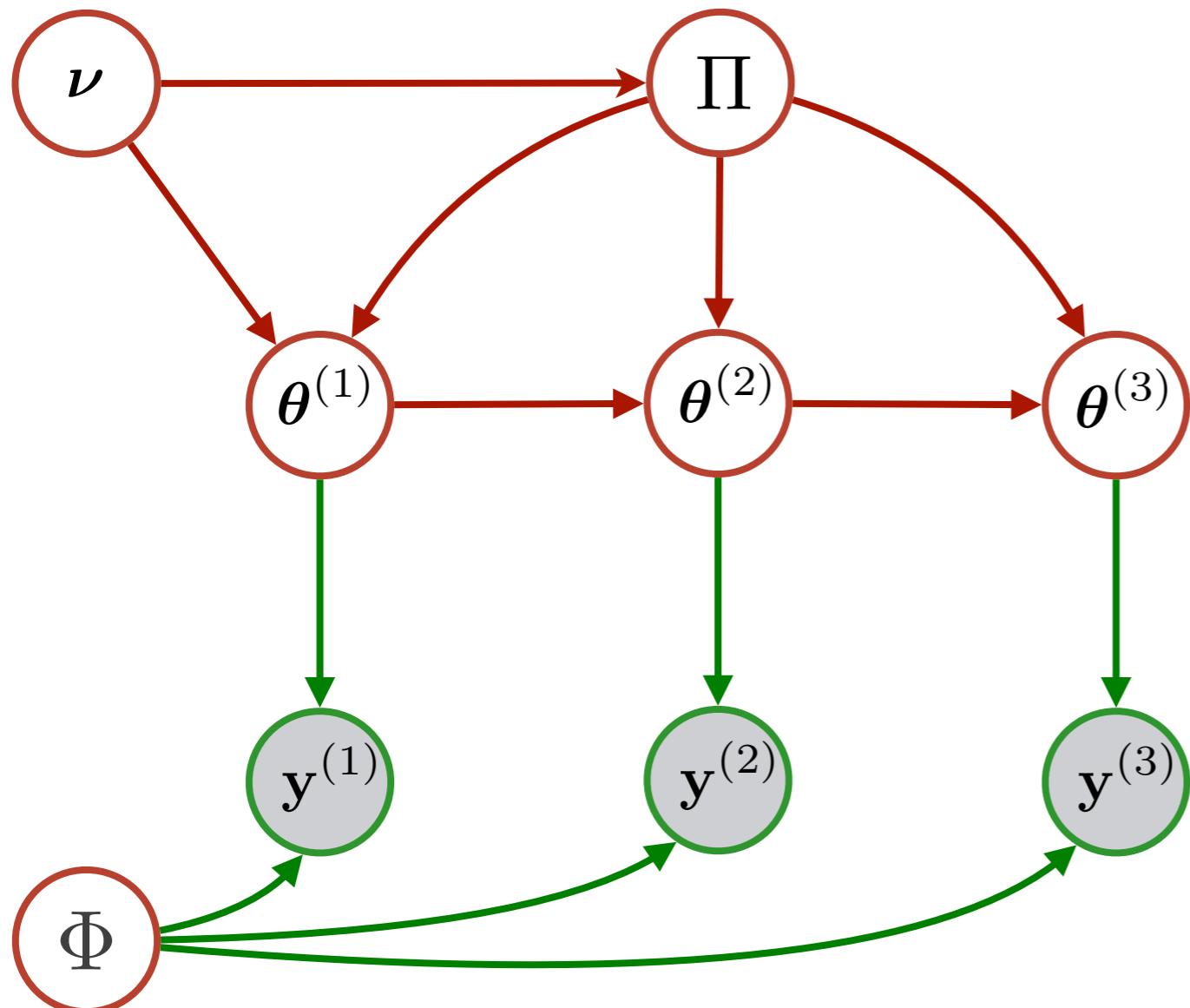
Technical challenge

Legend

- Poisson/Multinomial
- Gamma/Dirichlet



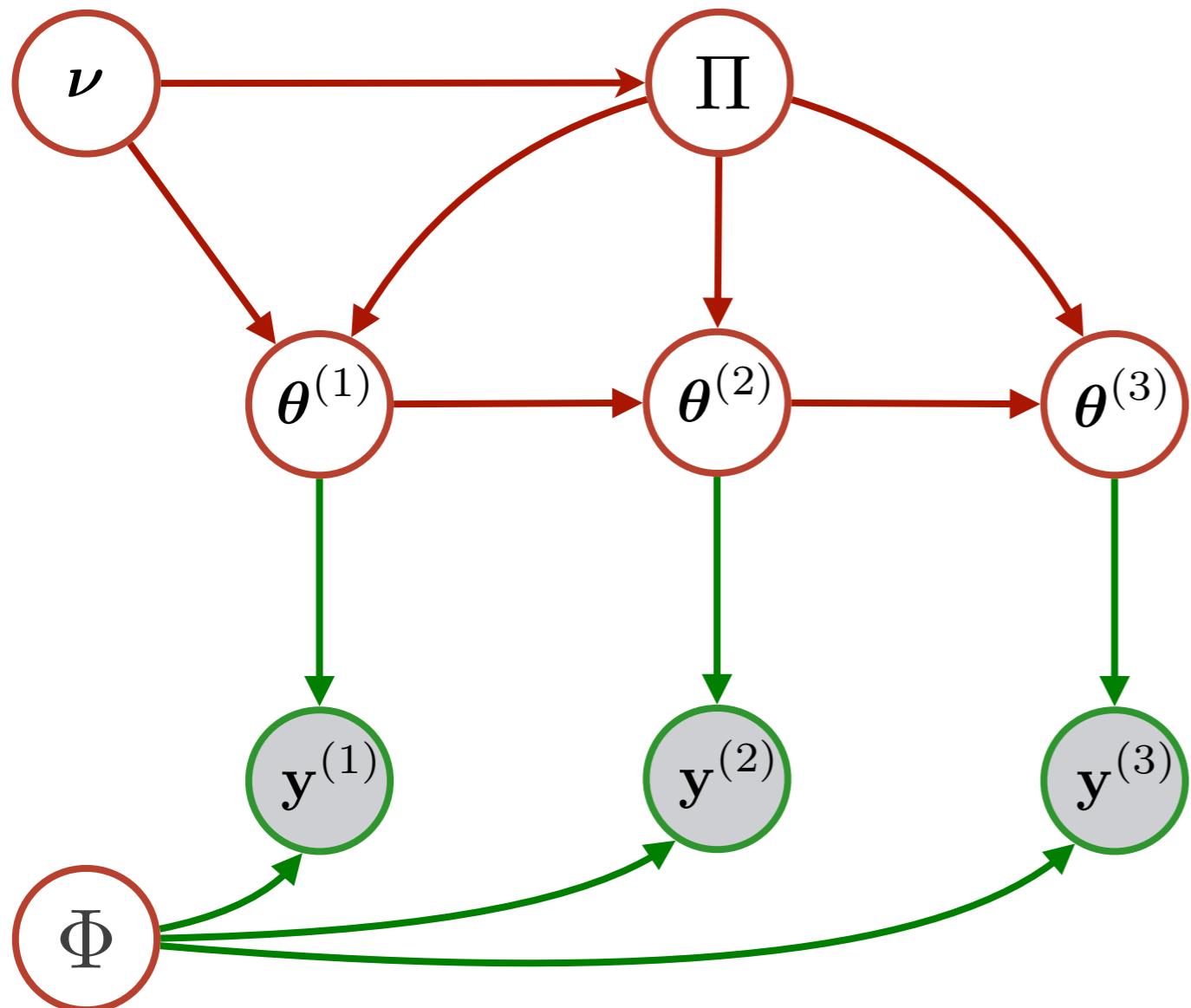
Technical challenge



Legend

- Poisson/Multinomial
- Gamma/Dirichlet

Technical challenge

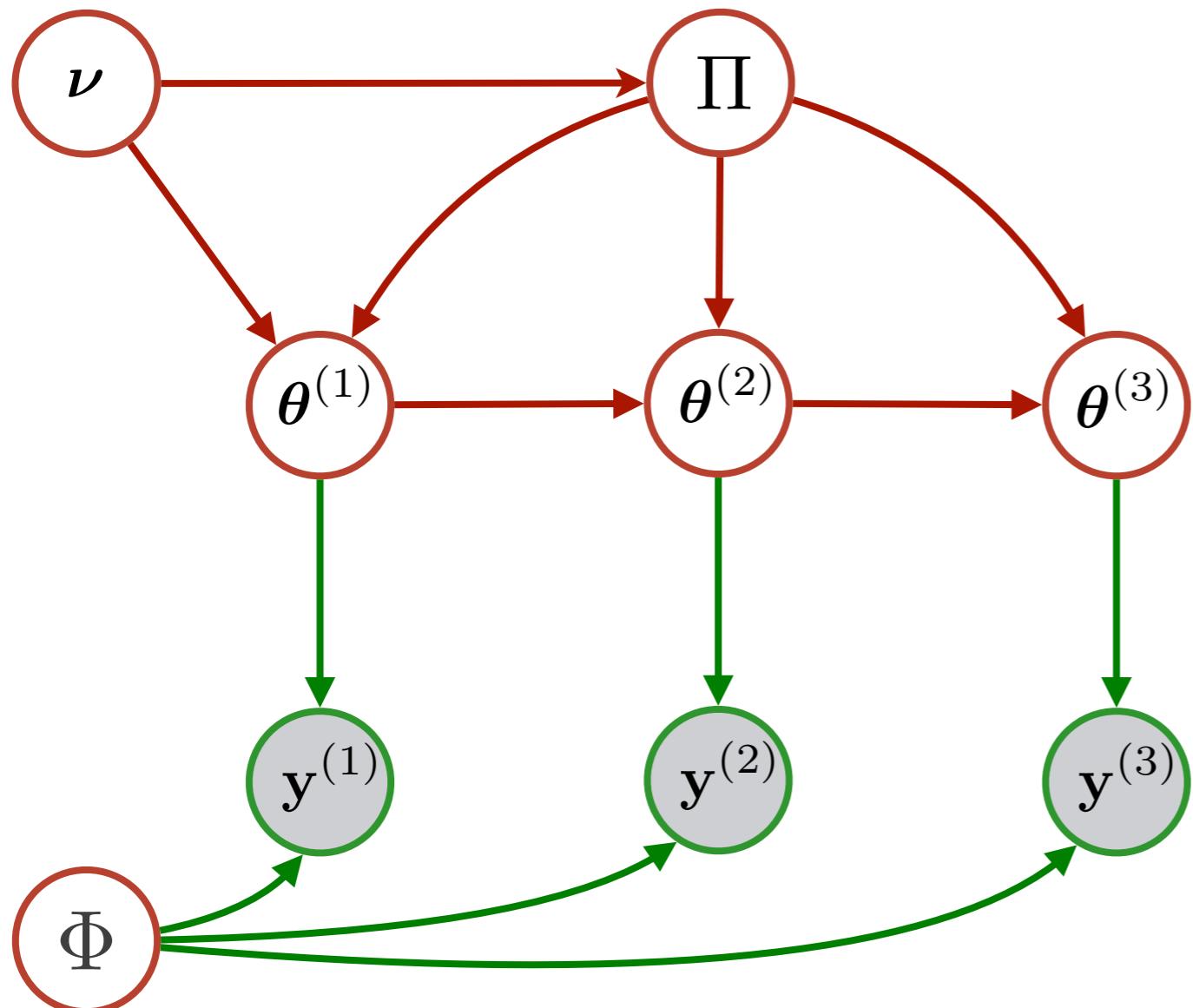


$$P(\Phi | Y)$$

Legend

- Poisson/Multinomial
- Gamma/Dirichlet

Technical challenge



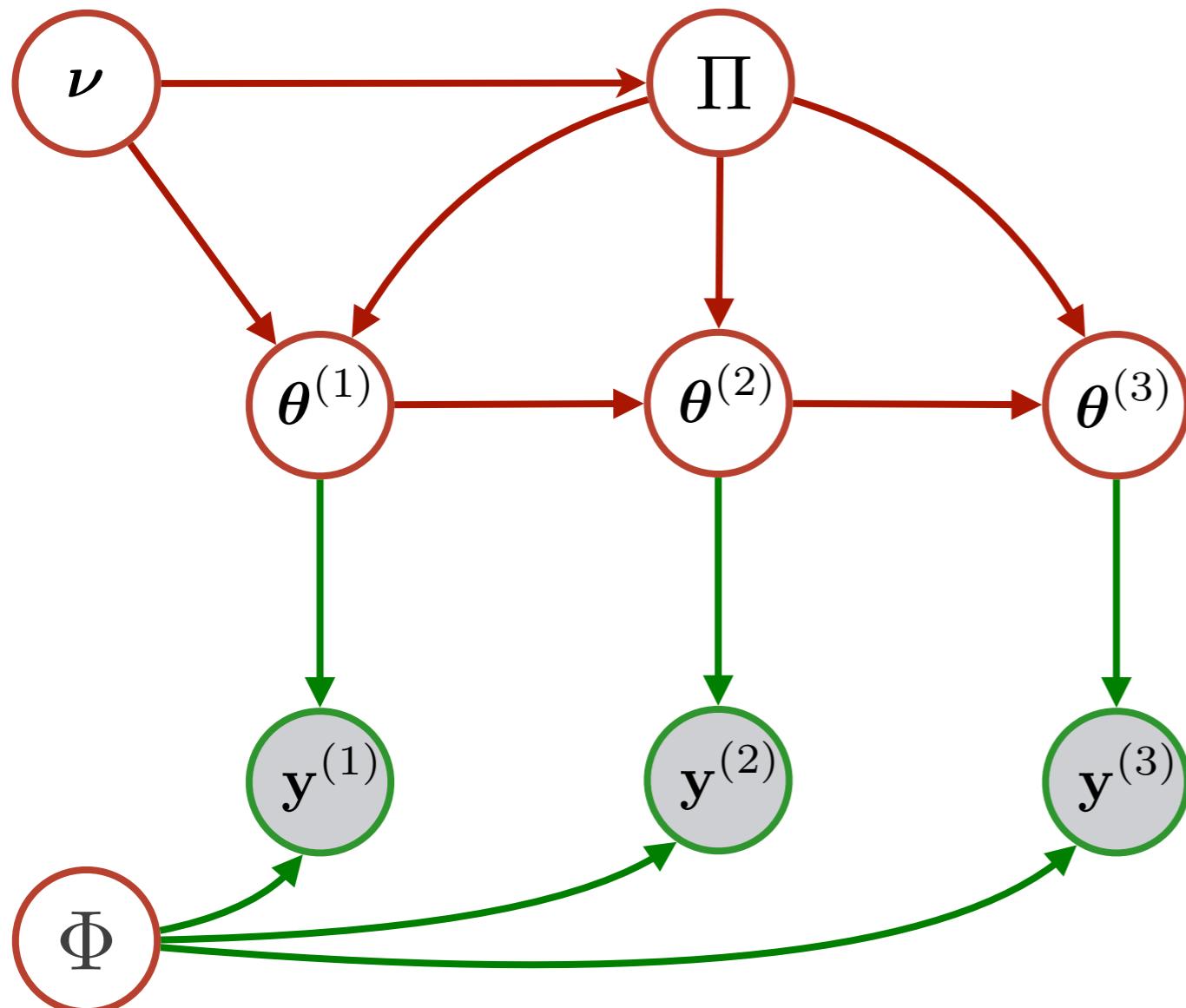
Legend

- Poisson/Multinomial
- Gamma/Dirichlet

$$P(\Phi | Y) \quad \checkmark$$

(conditional posterior has closed form)

Technical challenge



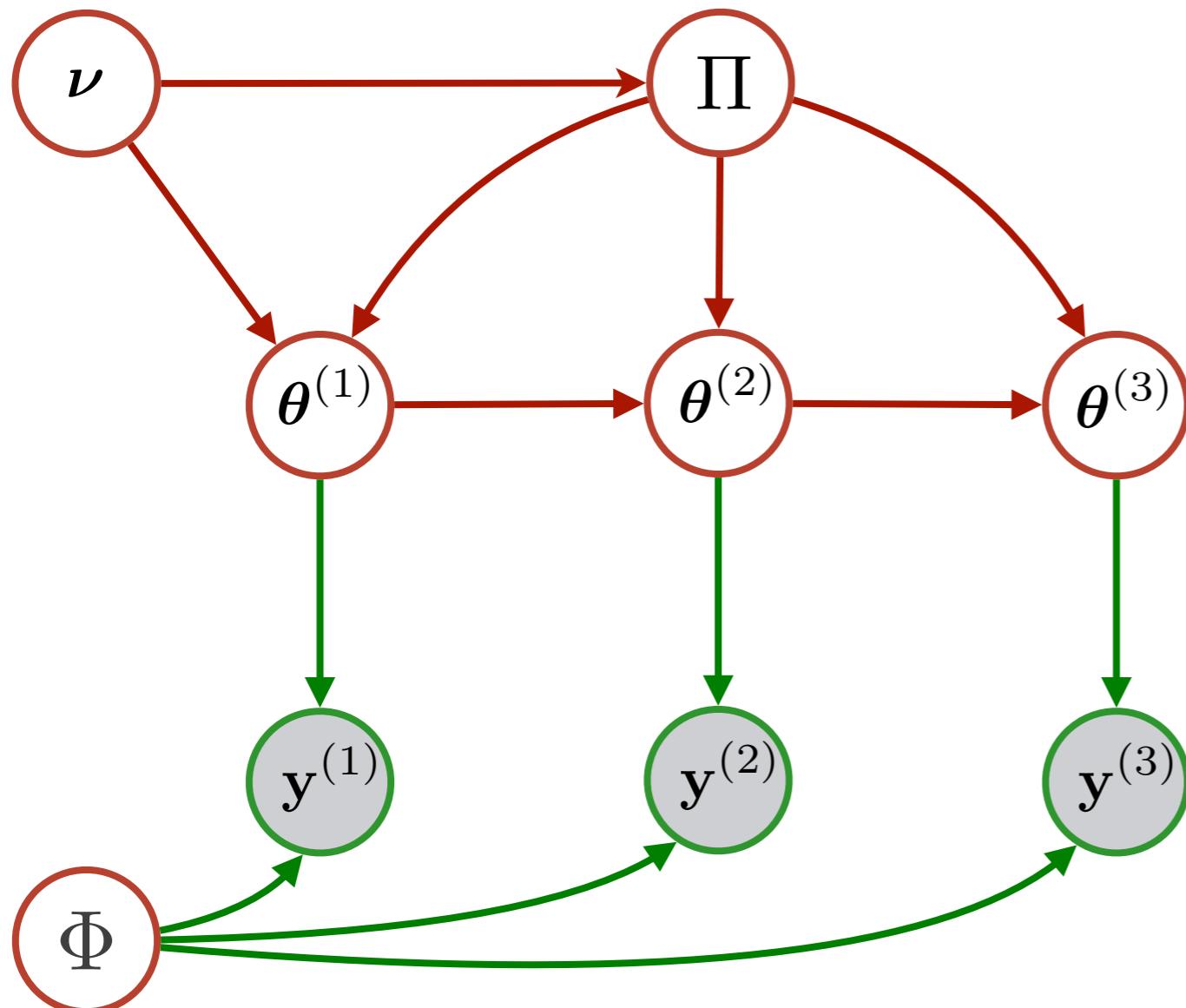
$$\Phi \sim P(\Phi | Y) \quad \checkmark$$

(conditional posterior has closed form)

Legend

- Poisson/Multinomial
- Gamma/Dirichlet

Technical challenge



$$\Pi \sim P(\Pi | Y, \Theta, \nu) \quad \text{X}$$

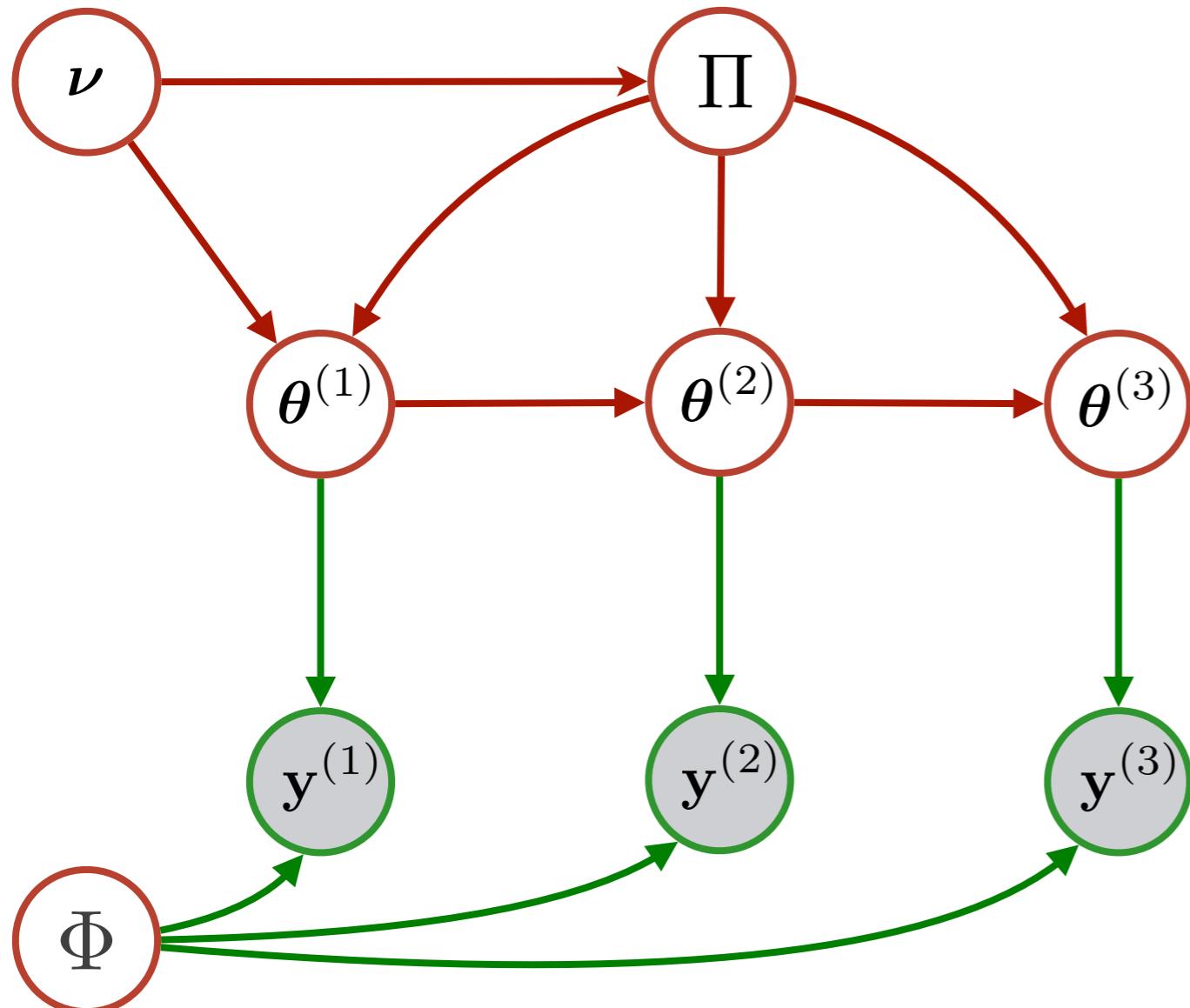
$$\Phi \sim P(\Phi | Y) \quad \checkmark$$

(conditional posterior has closed form)

Legend

- Poisson/Multinomial
- Gamma/Dirichlet

Technical challenge



Legend	
Poisson/Multinomial	(Green circle)
Gamma/Dirichlet	(Red circle)

$$\Pi \sim P(\Pi | Y, \Theta, \nu) \times$$

$$\Theta \sim P(\Theta | Y, \Pi, \nu) \times$$

$$\Phi \sim P(\Phi | Y) \checkmark$$

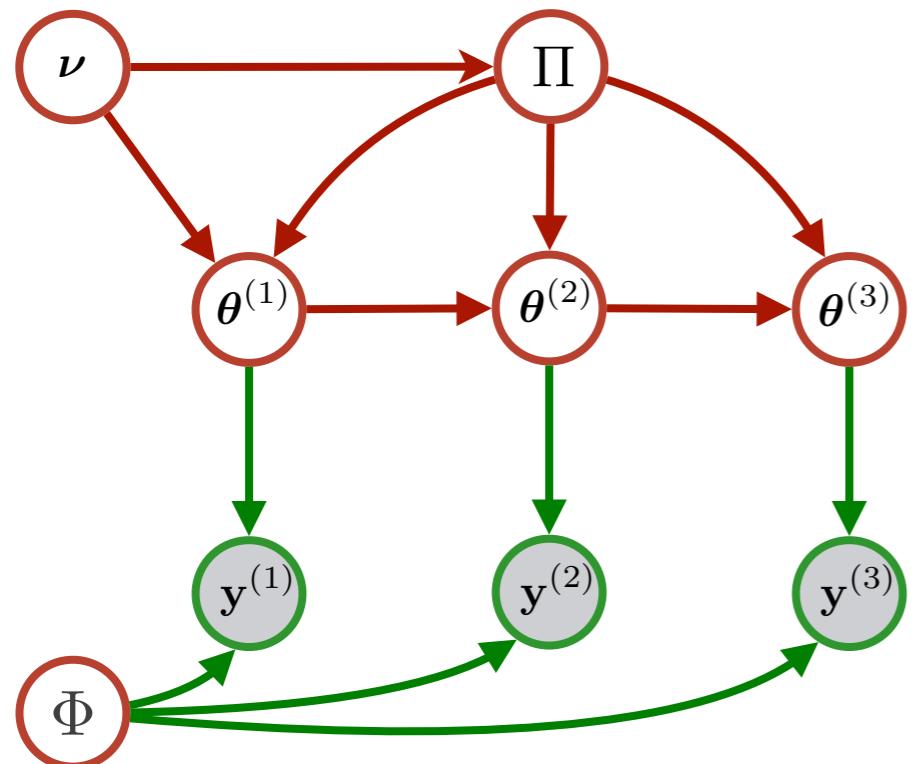
(conditional posterior has closed form)

Augment and Conquer

Legend

- Poisson/Multinomial
- Gamma/Dirichlet

Original model

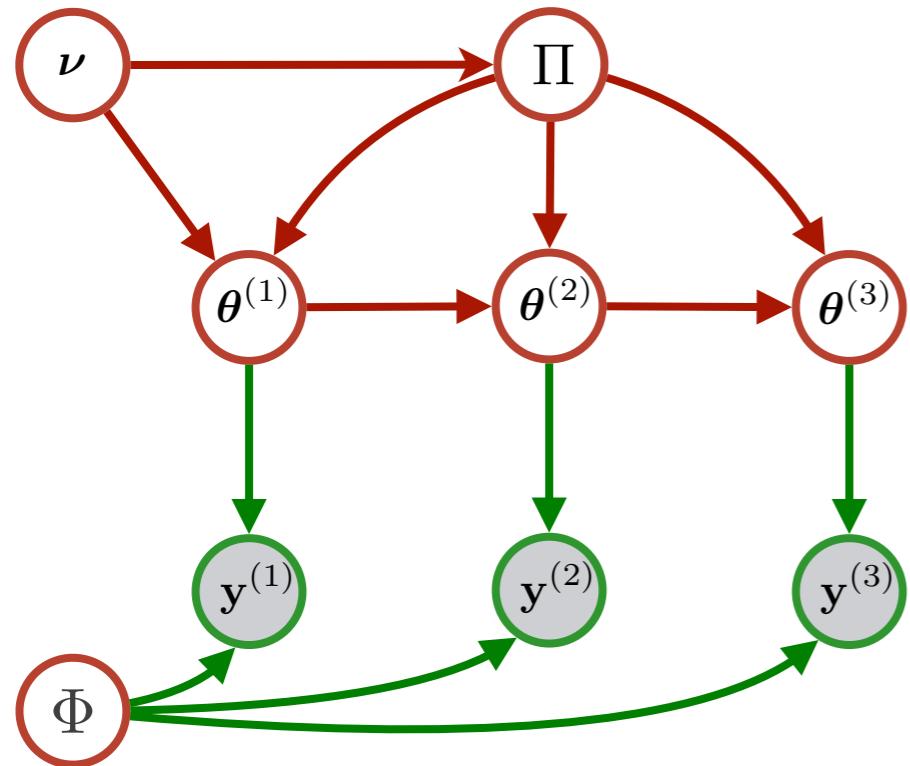


Augment and Conquer

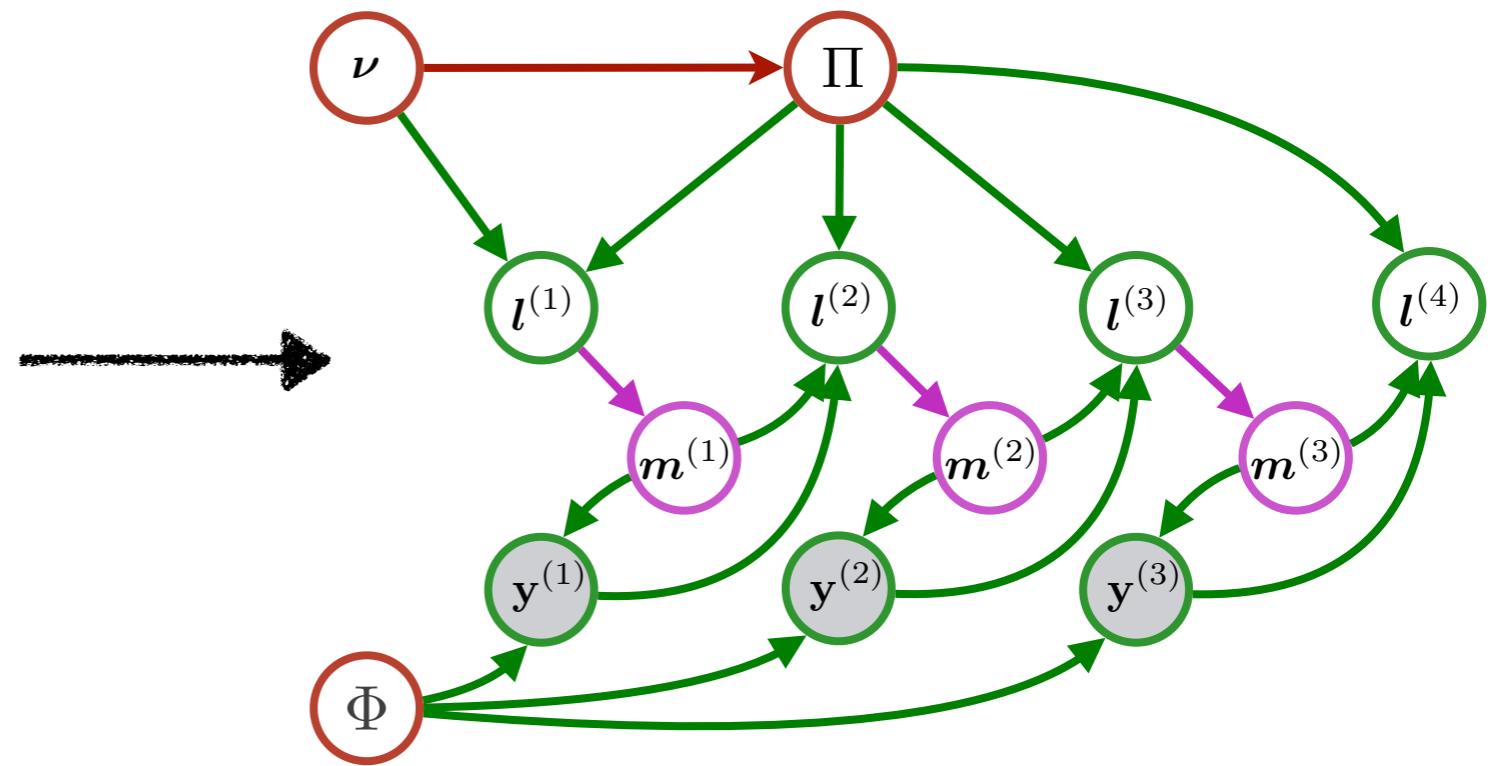
Legend

- Poisson/Multinomial
- Gamma/Dirichlet

Original model



Alternative model

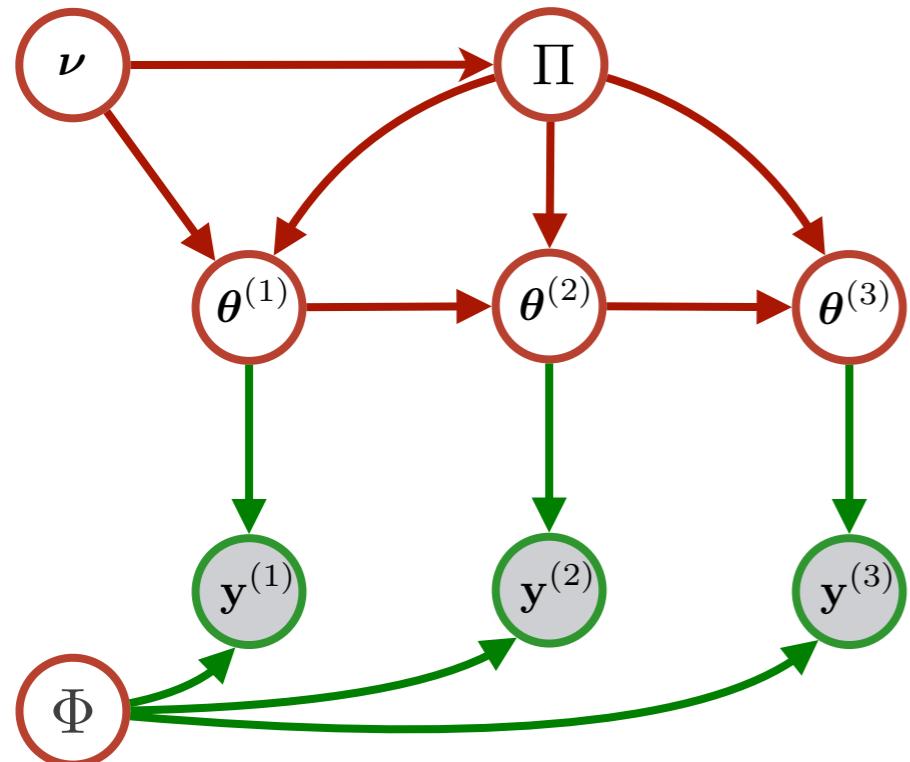


Augment and Conquer

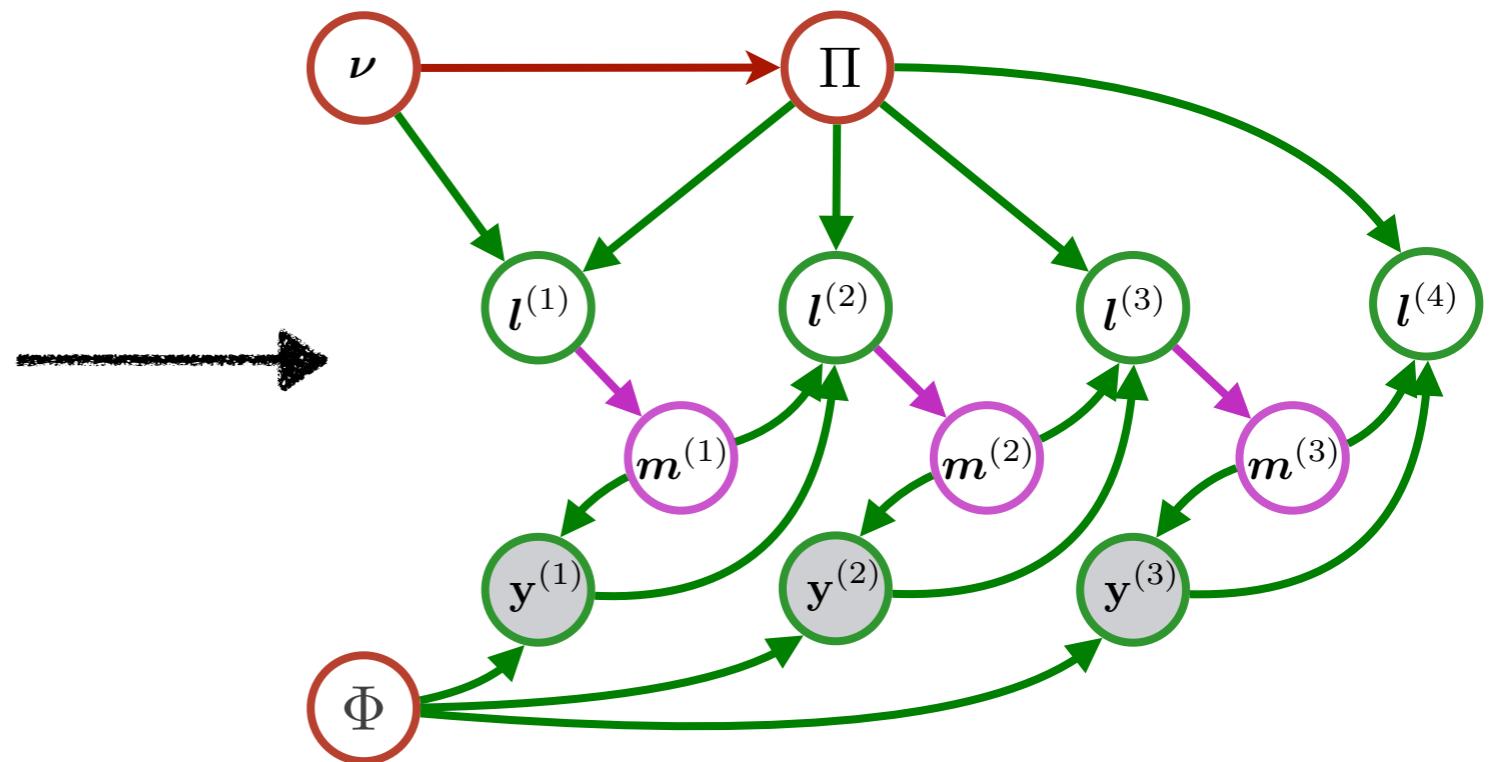
Legend

- Poisson/Multinomial
- Gamma/Dirichlet

Original model



Alternative model



$$\Pi \sim P(\Pi | \mathcal{A}, Y, \nu) \quad \checkmark$$

Poisson—gamma dynamical systems

[NeurIPS '16]

Analogue to linear dynamical systems for
high-dimensional **discrete time-series**

with APF, good things happen...



- **robust** to sparsity, overdispersion, burstiness
- model-fitting **scales with number of non-zeros**

T	\hat{B}	Task	Mean Relative Error (MRE)		
			PGDS	GP-DPFA	LDS
GDELT	365	1.27	S 2.335 ± 0.19	2.951 ± 0.32	3.493 ± 0.53
		F	F 2.173 ± 0.41	2.207 ± 0.42	2.397 ± 0.29
ICEWS	365	1.10	S 0.808 ± 0.11	0.877 ± 0.12	1.023 ± 0.15
		F	F 0.743 ± 0.17	0.792 ± 0.17	0.937 ± 0.31
SOTU	225	1.45	S 0.233 ± 0.01	0.238 ± 0.01	0.260 ± 0.01
		F	F 0.171 ± 0.00	0.173 ± 0.00	0.225 ± 0.01
DBLP	14	1.64	S 0.417 ± 0.03	0.422 ± 0.05	0.405 ± 0.05
		F	F 0.322 ± 0.00	0.323 ± 0.00	0.369 ± 0.06
NIPS	17	0.33	S 0.415 ± 0.07	0.392 ± 0.07	1.609 ± 0.43
		F	F 0.343 ± 0.01	0.312 ± 0.00	0.642 ± 0.14

Poisson-randomized gamma dynamical systems

[NeurIPS '19]

Another analogue to linear dynamical systems
for high-dimensional discrete time-series

with APF, good things happen...



- **robust** to sparsity, overdispersion, burstiness
- model-fitting **scales with number of non-zeros**

Poisson-randomized gamma dynamical systems

[NeurIPS '19]

Another analogue to linear dynamical systems
for high-dimensional discrete time-series

with APF, good things happen...



- **robust** to sparsity, overdispersion, burstiness
- model-fitting **scales with number of non-zeros**

Based on a **sparse discrete** representation...



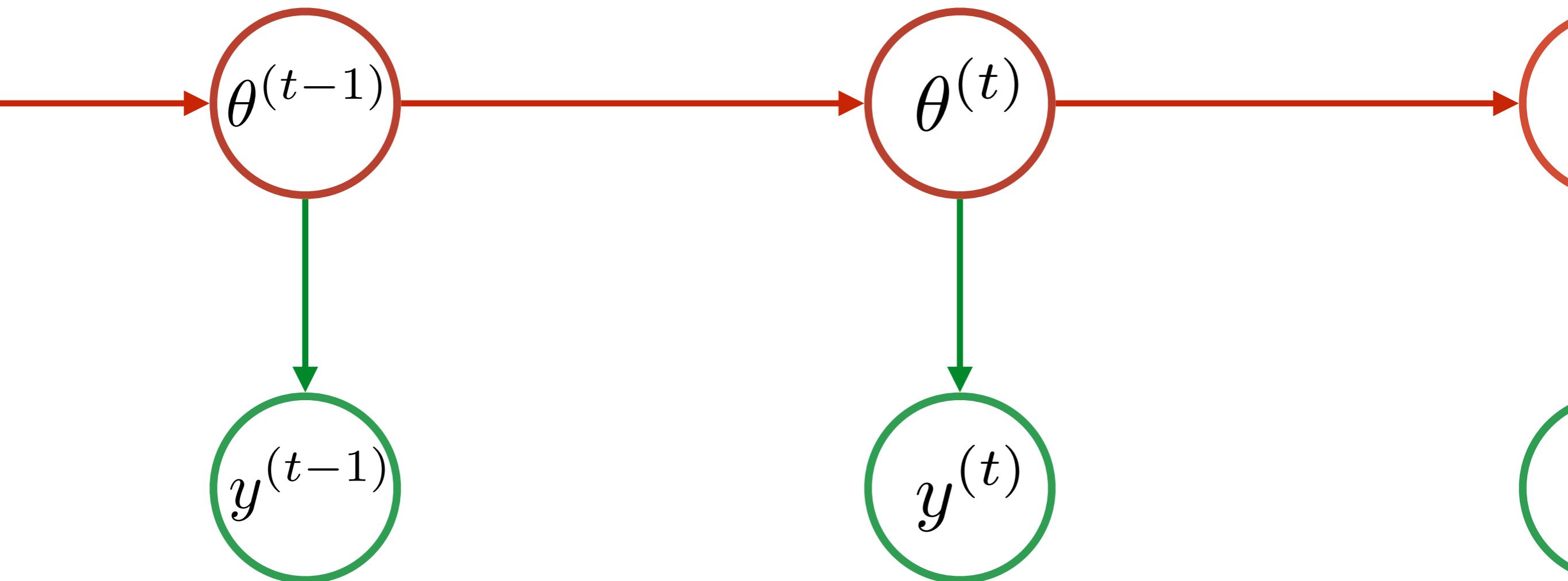
...which lets it “see” things other models can’t.

Legend

- Poisson/Multinomial
- Gamma/Dirichlet

The gamma—Poisson—gamma chain

$$\theta^{(t)} \sim \text{Gam}(\tau \theta^{(t-1)}, \tau)$$

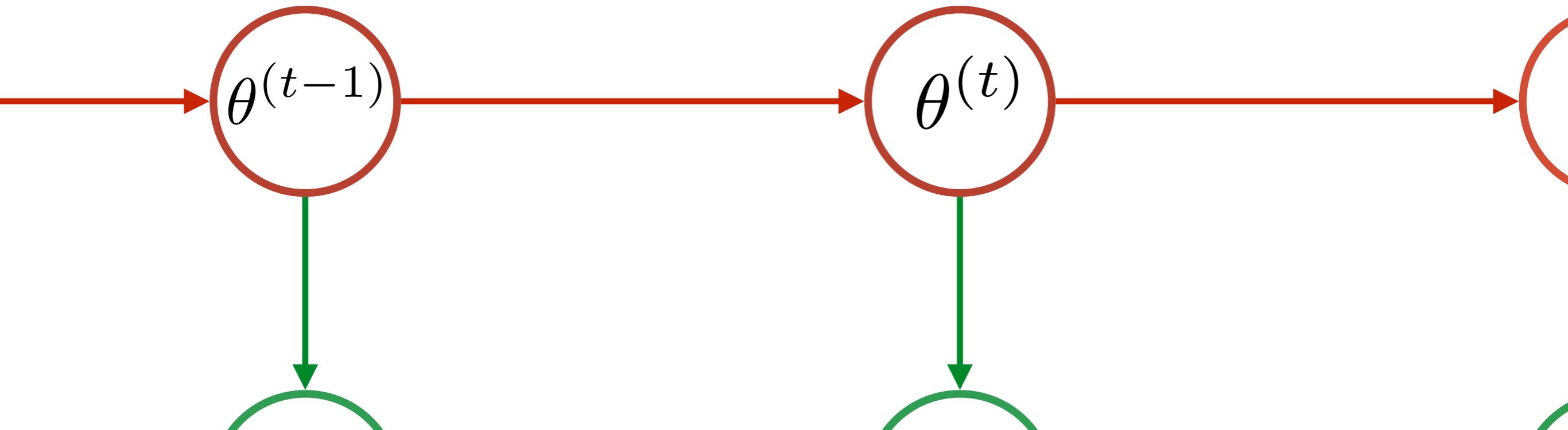


Legend

- Poisson/Multinomial
- Gamma/Dirichlet

The gamma—Poisson—gamma chain

$$\theta^{(t)} \sim \text{Gam}(\tau \theta^{(t-1)}, \tau)$$



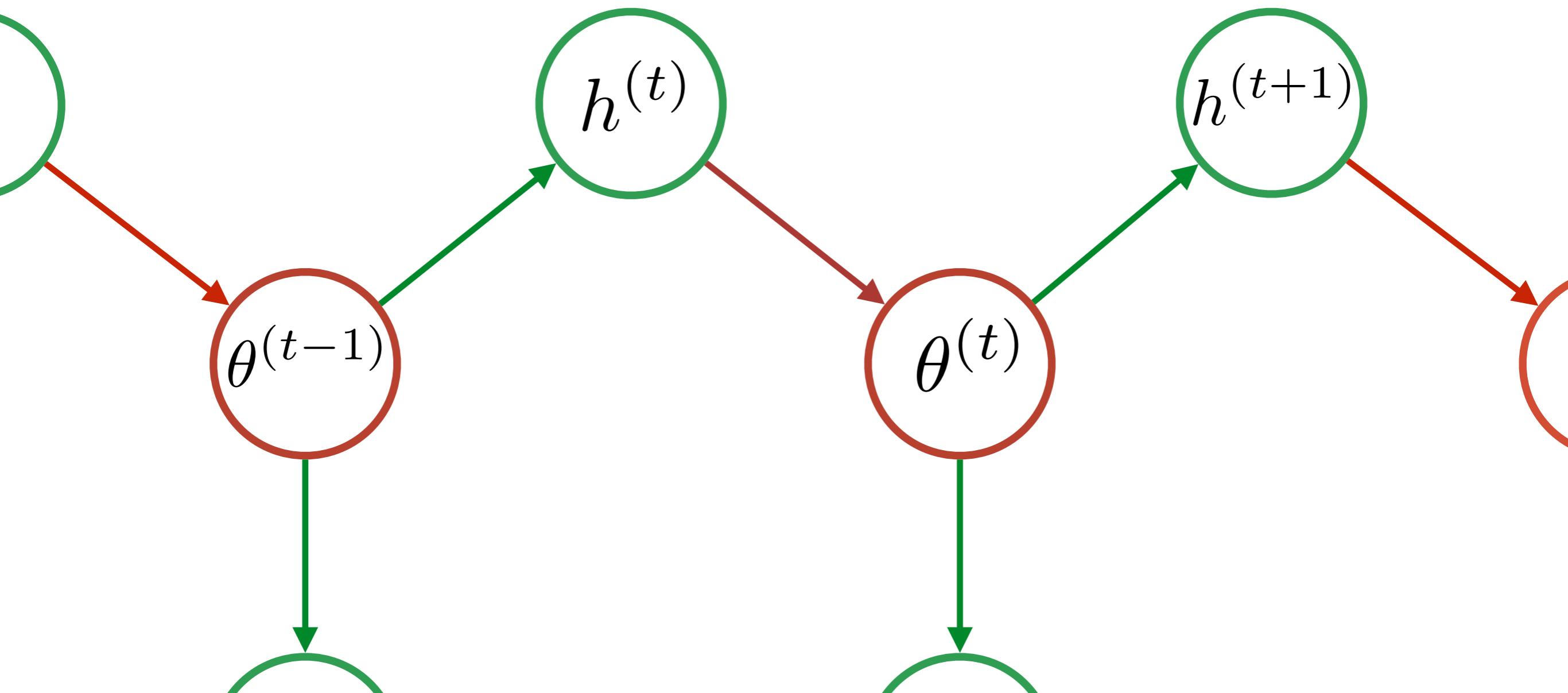
Legend

- Poisson/Multinomial
- Gamma/Dirichlet

The gamma—Poisson—gamma chain

$h^{(t)} \sim \text{Pois}(\tau\theta^{(t-1)})$ **discrete** latent state

$\theta^{(t)} \sim \text{Gam}(h^{(t)}, \tau)$ **continuous** latent state



Legend

- Poisson/Multinomial
- Gamma/Dirichlet

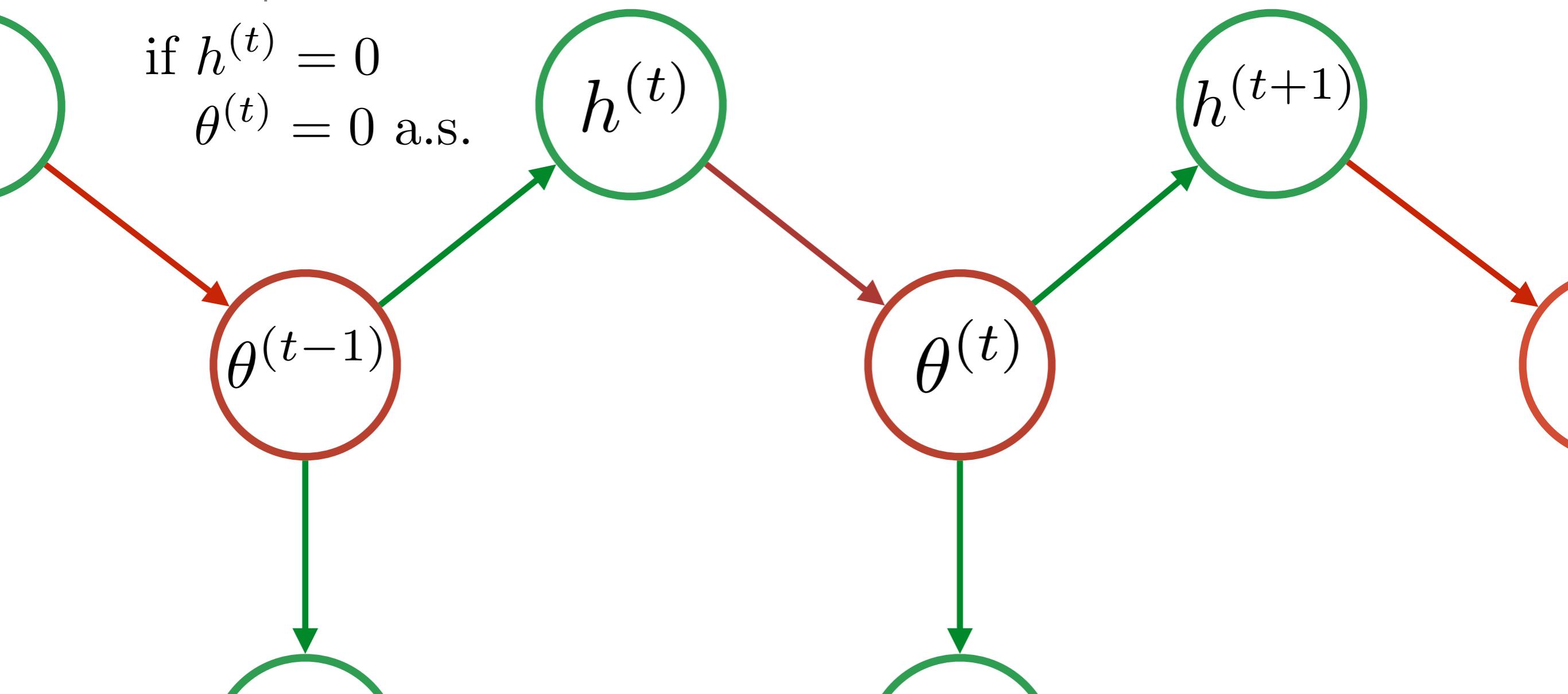
The gamma—Poisson—gamma chain

$h^{(t)} \sim \text{Pois}(\tau\theta^{(t-1)})$ **discrete** latent state

$\theta^{(t)} \sim \text{Gam}(h^{(t)}, \tau)$ **continuous** latent state

sparse representation

if $h^{(t)} = 0$
 $\theta^{(t)} = 0$ a.s.



Poisson-randomized gamma dynamical systems

[NeurIPS '19]

Sparse discrete representation...



...lets it “see” things other models can’t.

Poisson-randomized gamma dynamical systems

[NeurIPS '19]

Sparse discrete representation...



...lets it “see” things other models can’t.

Qualitative study: PGDS [NeurIPS '16] **vs.** PRGDS [NeurIPS '19]

Poisson-randomized gamma dynamical systems

[NeurIPS '19]

Sparse discrete representation...



...lets it “see” things other models can’t.

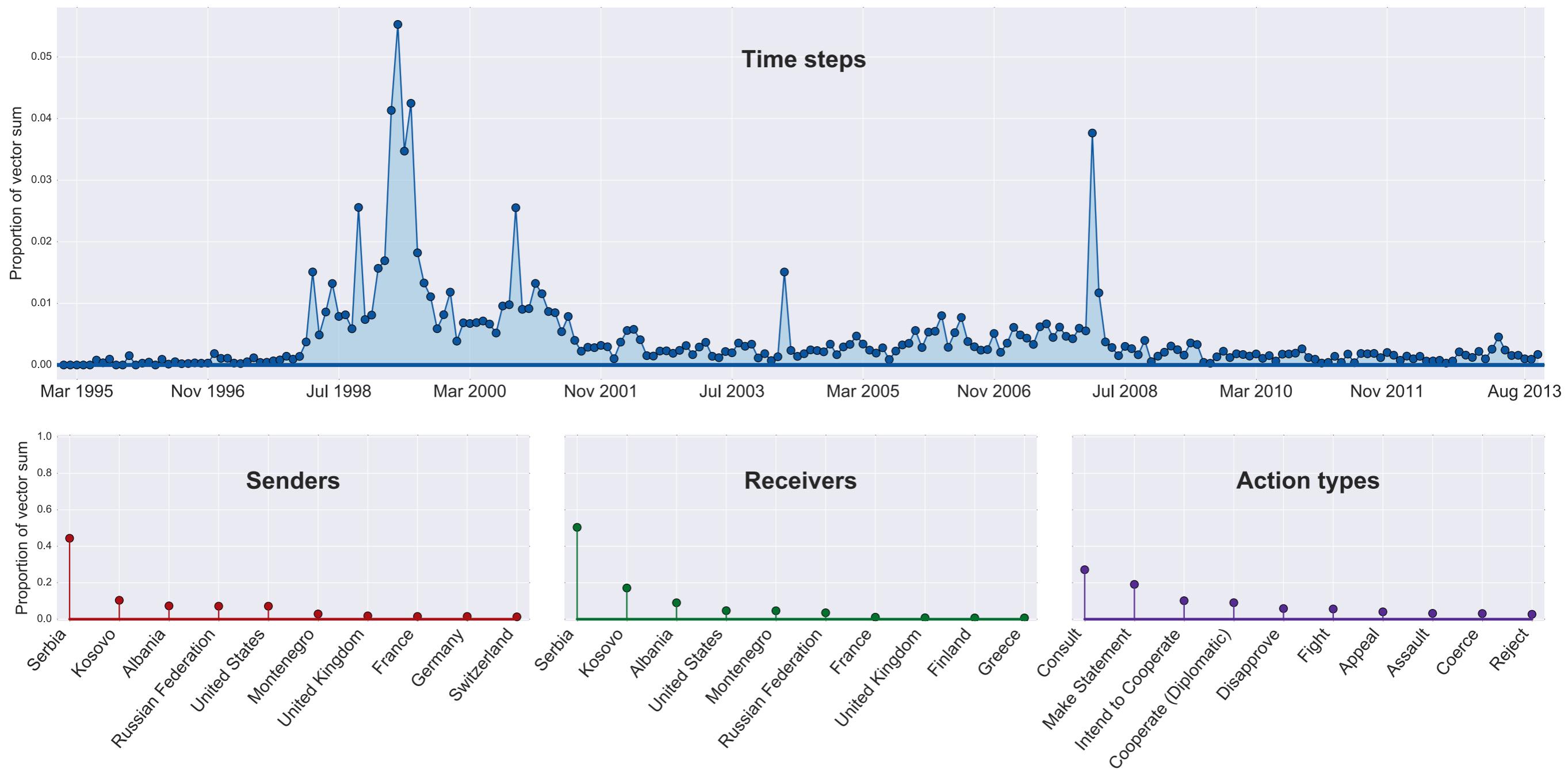
Qualitative study: PGDS [NeurIPS '16] **vs.** PRGDS [NeurIPS '19]

- 1) Fit them both to the same IR data.
- 2) Align their latent components.
- 3) Check for systematic discrepancy.

Aligned component: PGDS

[NeurIPS '16]

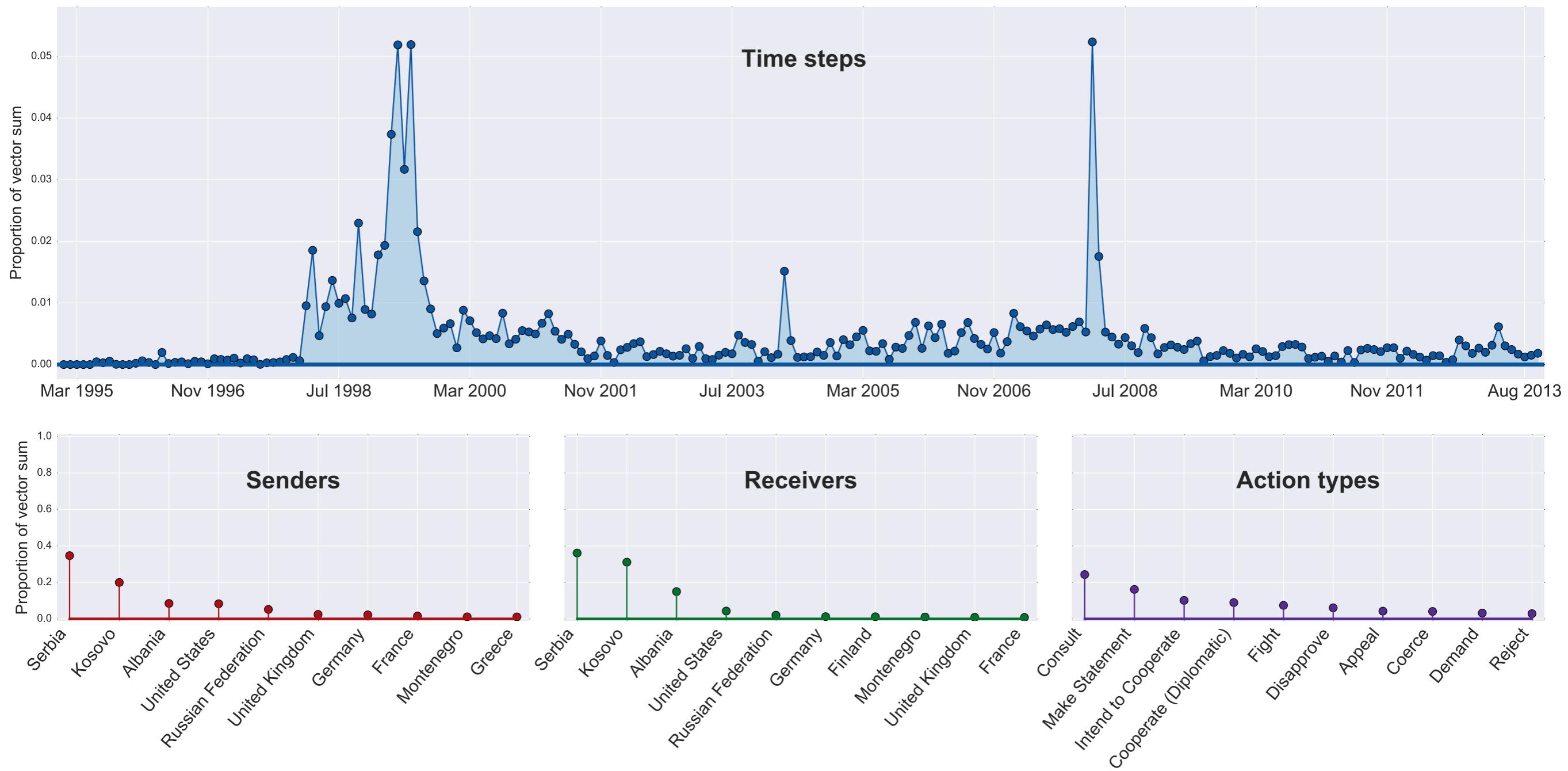
Both models “see” this component...



Aligned component: PRGDS

[NeurIPS '19]

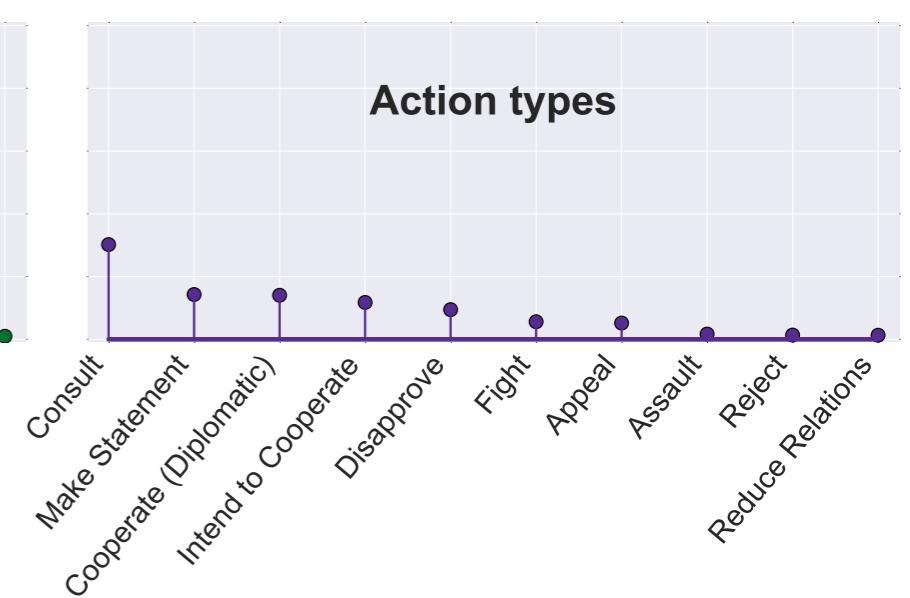
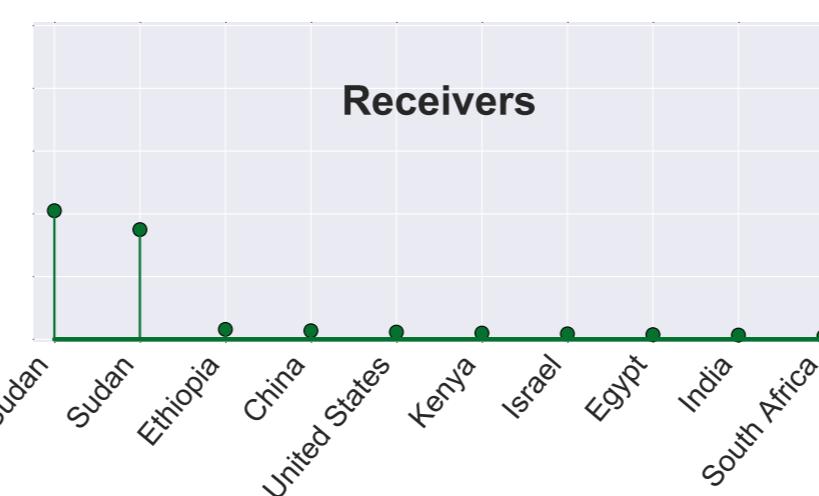
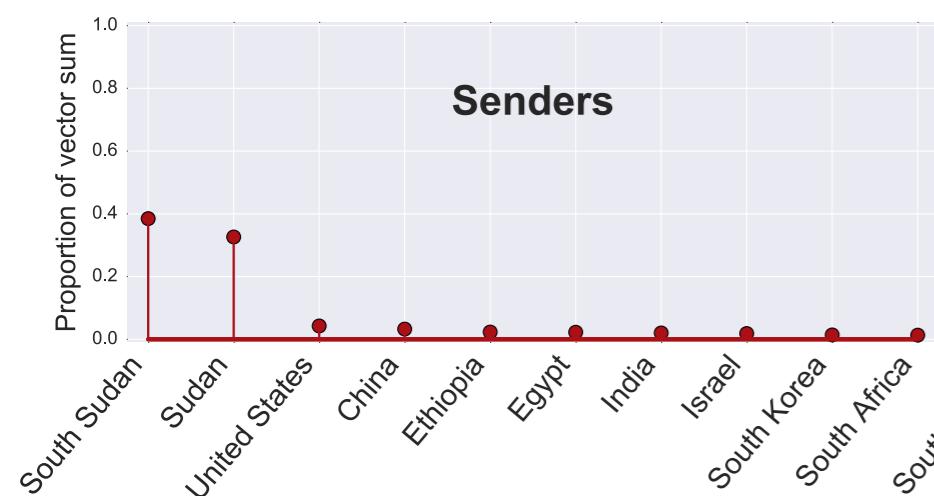
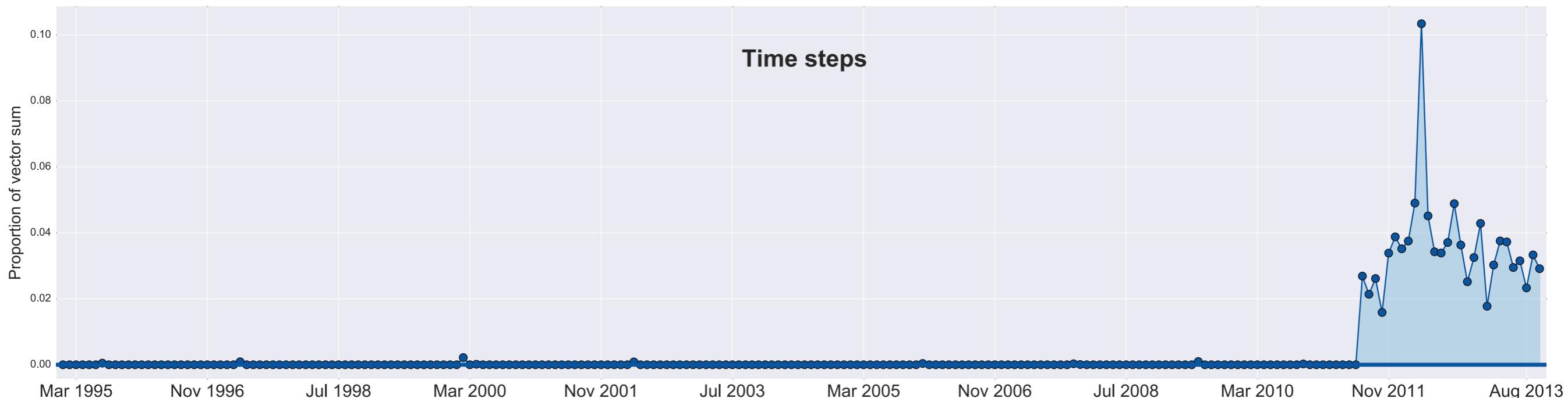
Both models “see” this component...



Discrepant component: PRGDS

[NeurIPS '19]

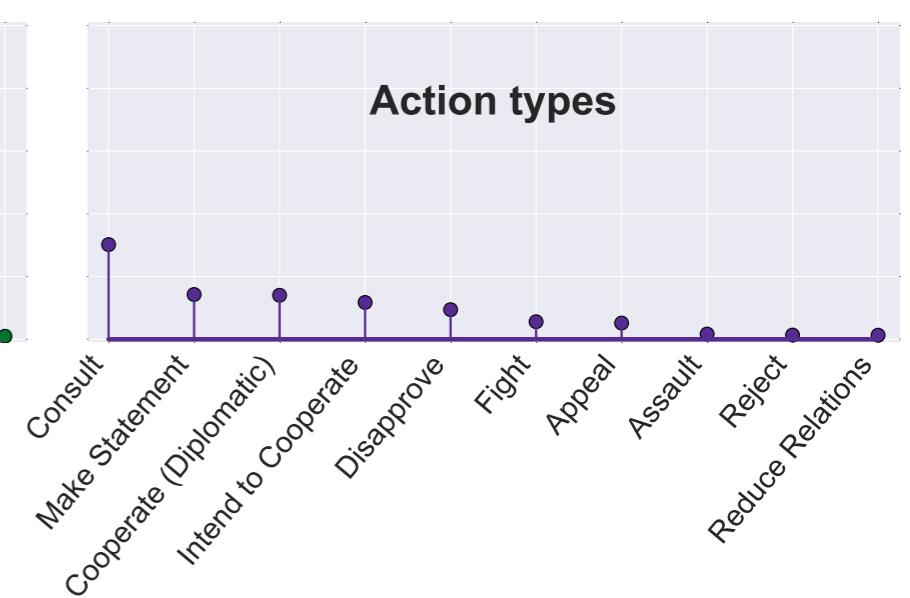
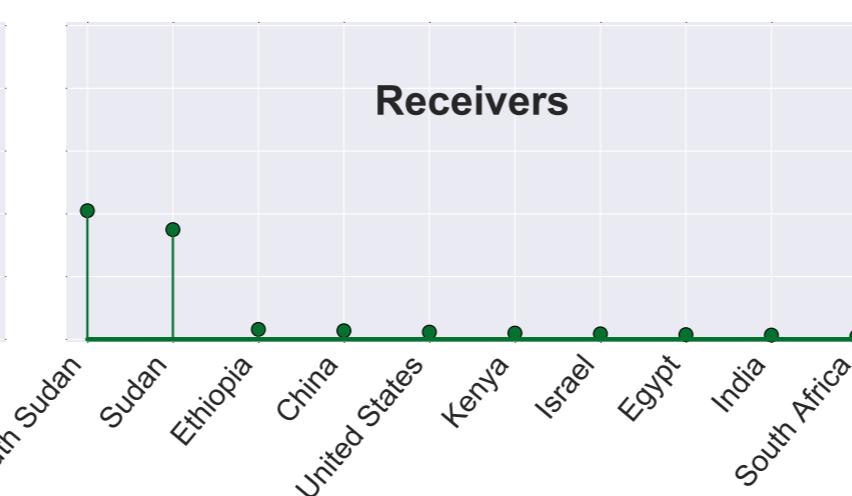
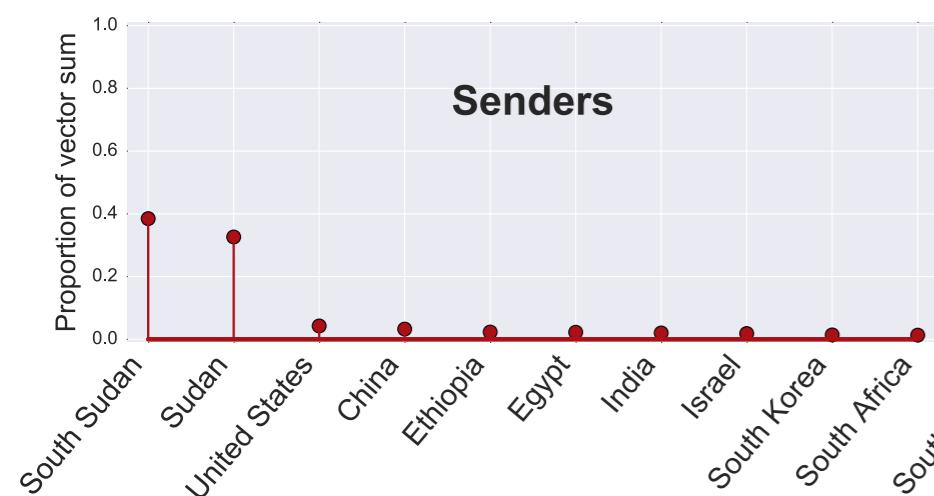
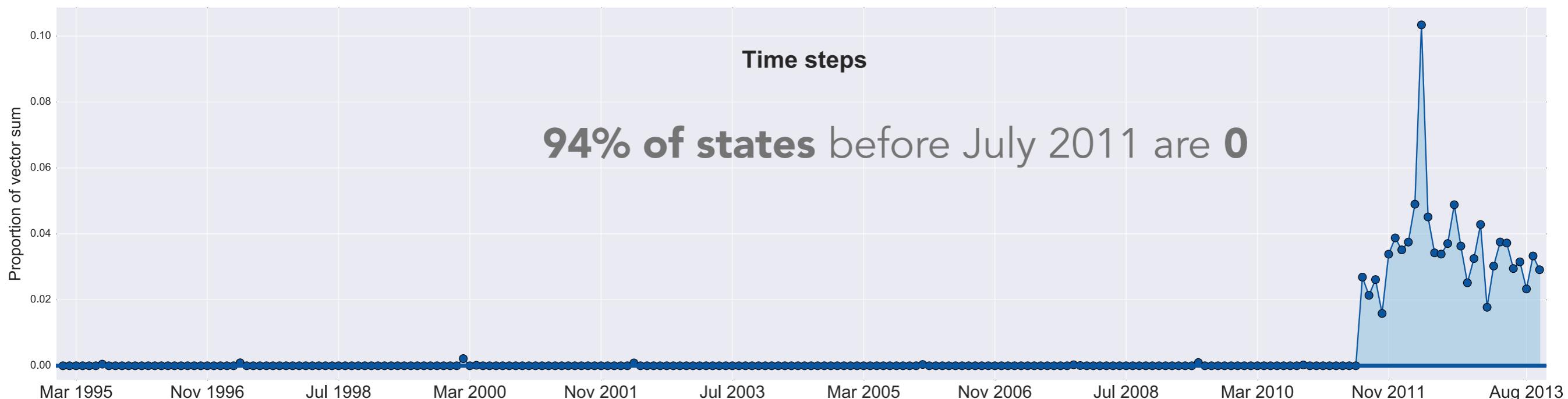
Only PRGDS “sees” this one.



Discrepant component: PRGDS

[NeurIPS '19]

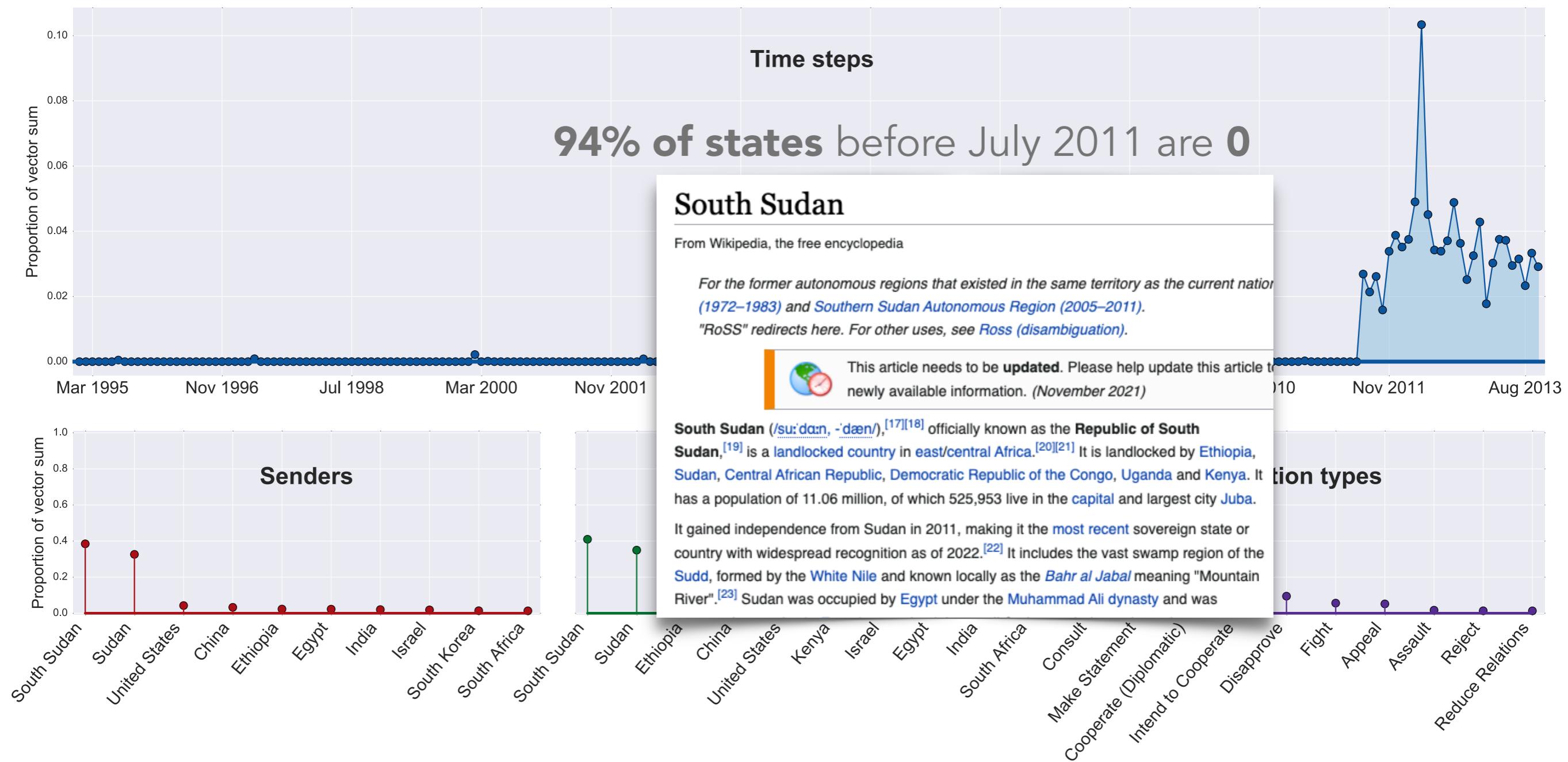
Only PRGDS “sees” this one.



Discrepant component: PRGDS

[NeurIPS '19]

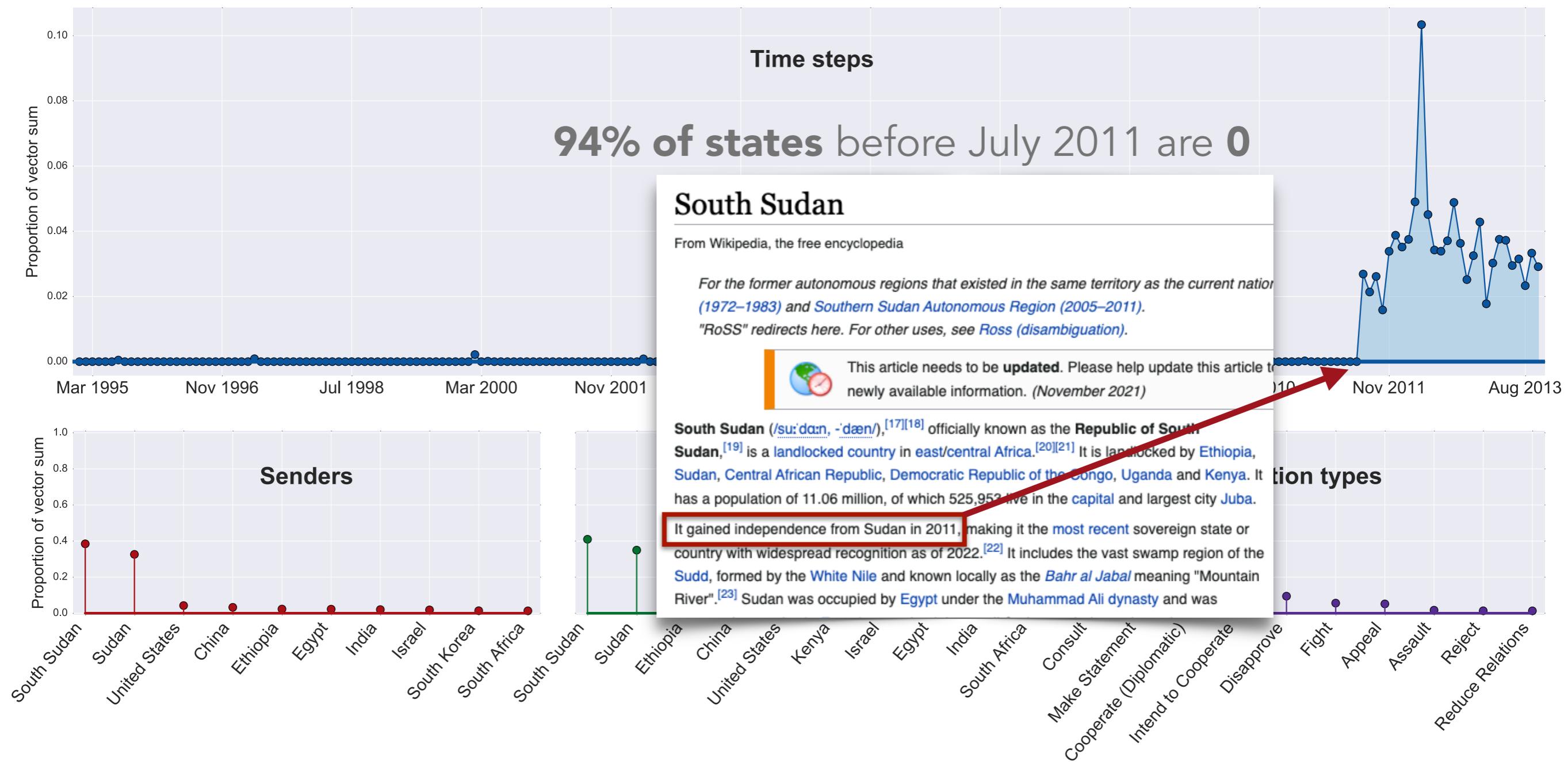
Only PRGDS “sees” this one.



Discrepant component: PRGDS

[NeurIPS '19]

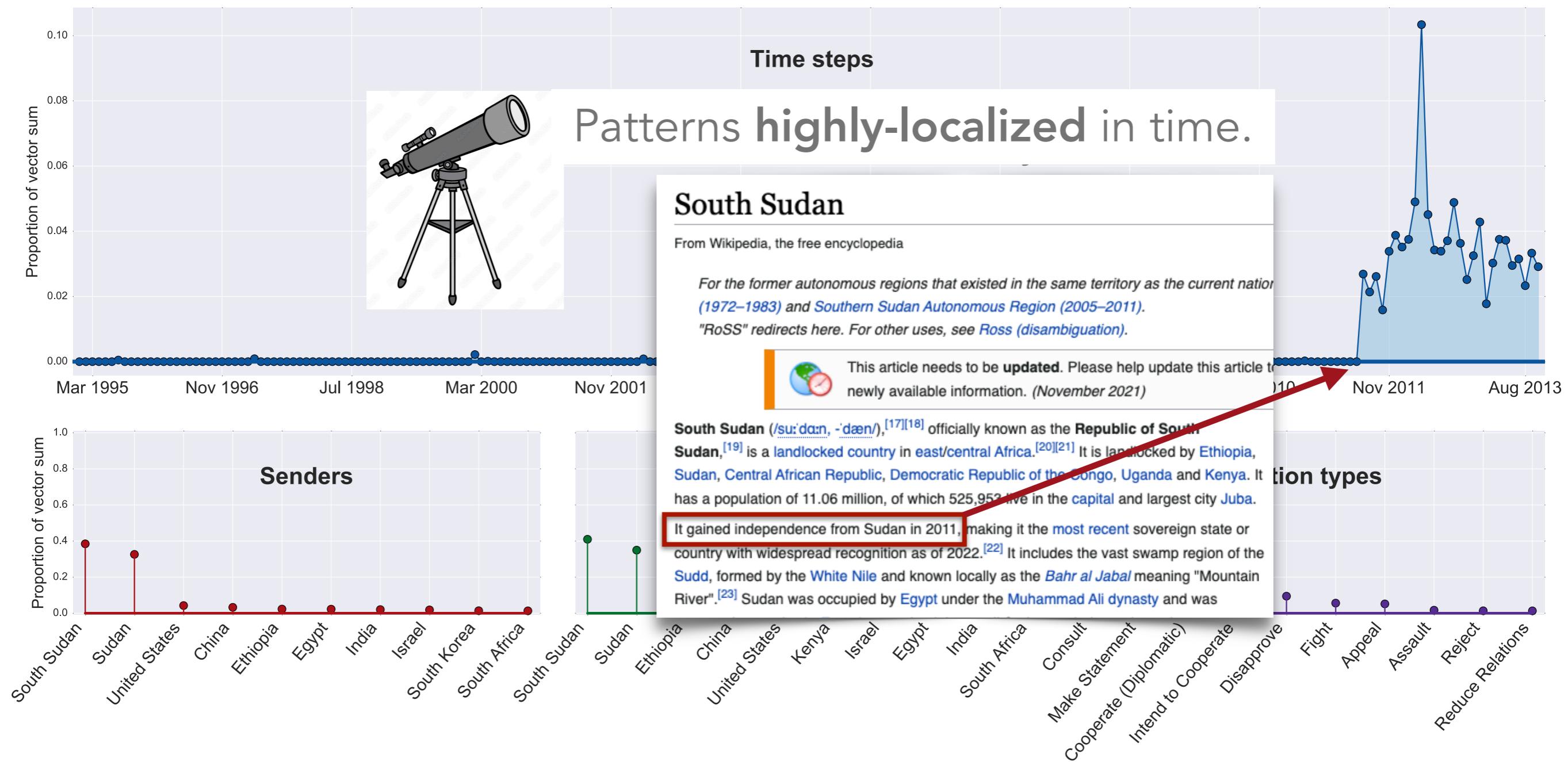
Only PRGDS “sees” this one.



Discrepant component: PRGDS

[NeurIPS '19]

Only PRGDS “sees” this one.



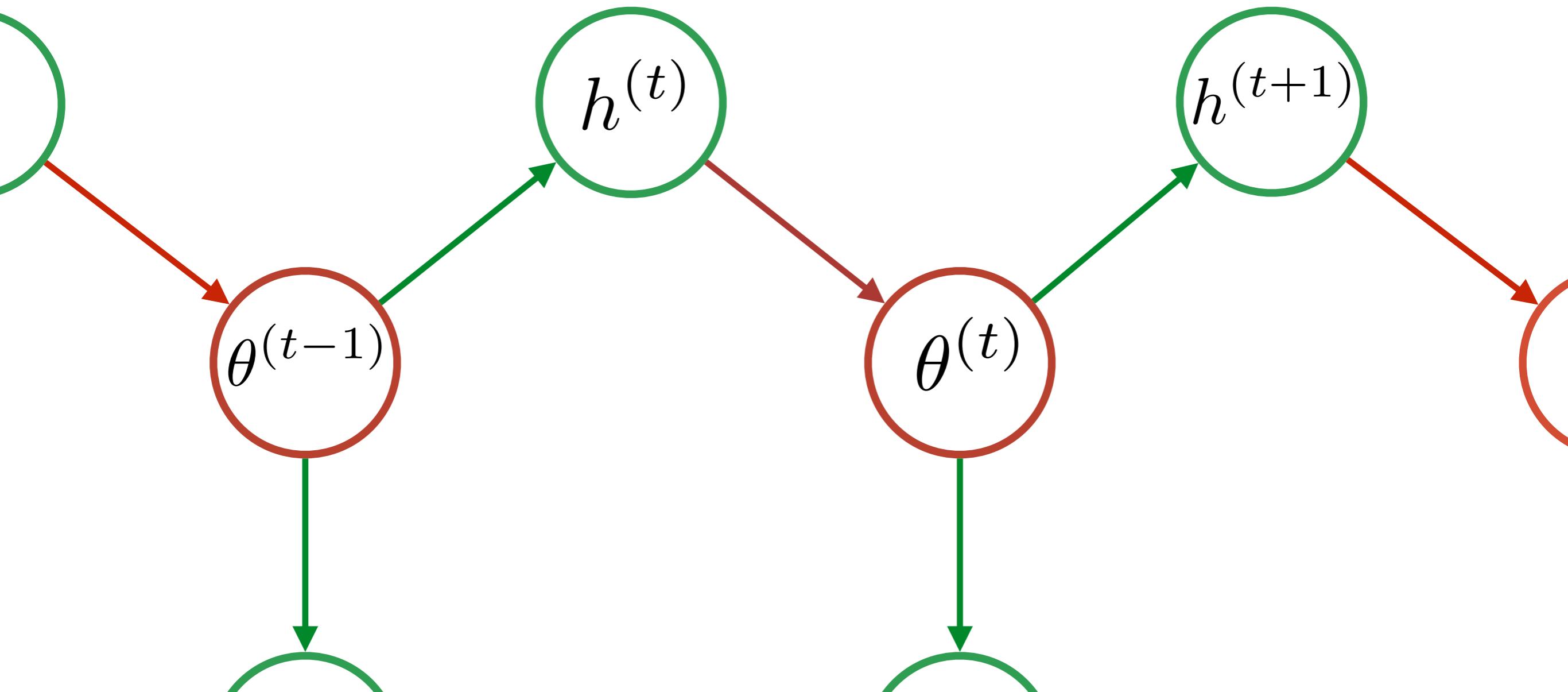
Approximate Bayesian inference

Legend

- Poisson/Multinomial
- Gamma/Dirichlet

Partially conditionally conjugate

$$(\theta^{(t)} | -) \sim P(\theta^{(t)} | h^{(t)}, h^{(t+1)}, -) \checkmark$$



Approximate Bayesian inference

Legend

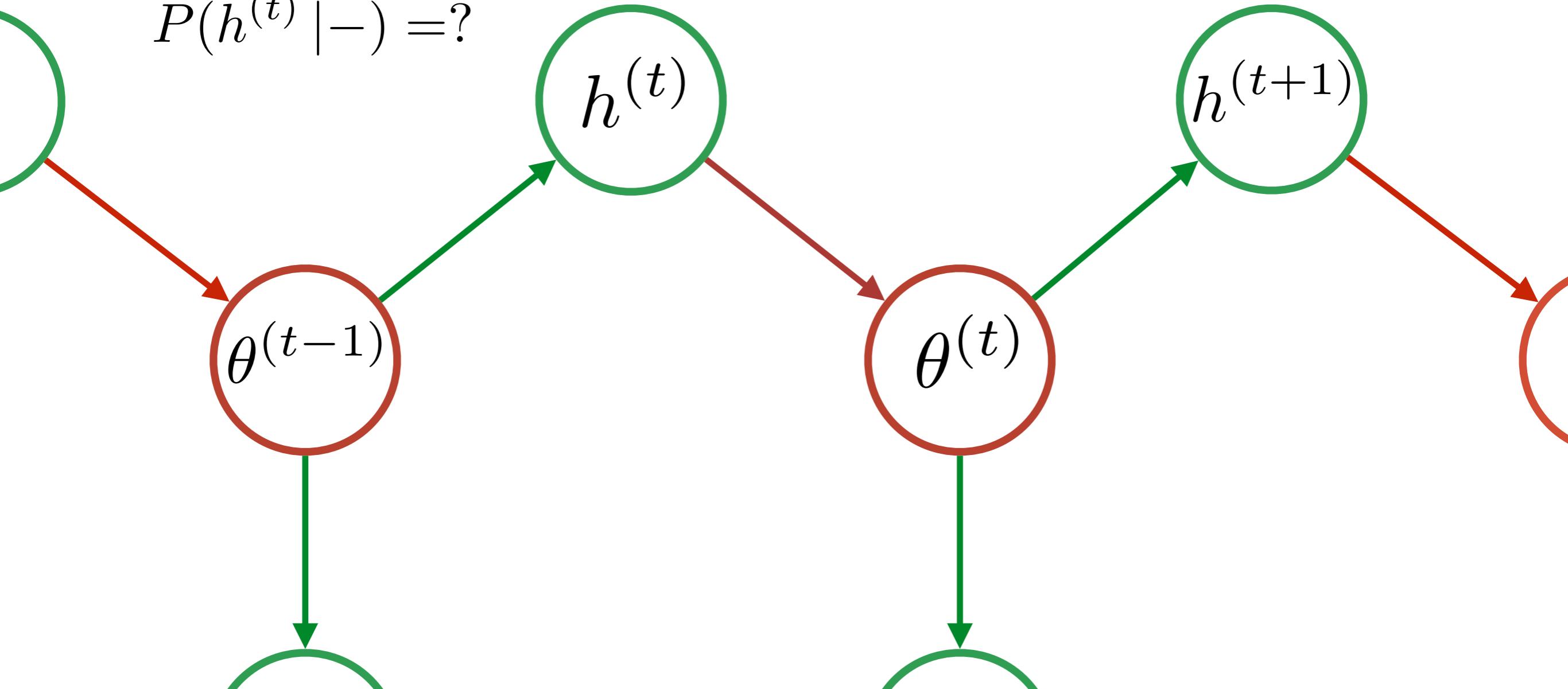
- Poisson/Multinomial
- Gamma/Dirichlet

Partially conditionally conjugate

$$(\theta^{(t)} | -) \sim P(\theta^{(t)} | h^{(t)}, h^{(t+1)}, -) \checkmark$$

Partially not

$$P(h^{(t)} | -) = ?$$



Approximate Bayesian inference

Partially conditionally conjugate

$$\left(\theta^{(t)} | - \right) \sim P \left(\theta^{(t)} | h^{(t)}, h^{(t+1)}, - \right) \checkmark$$

Partially not

$P(h^{(t)} | -) = ?$...but even without conjugacy...
closed-formedness!

Approximate Bayesian inference

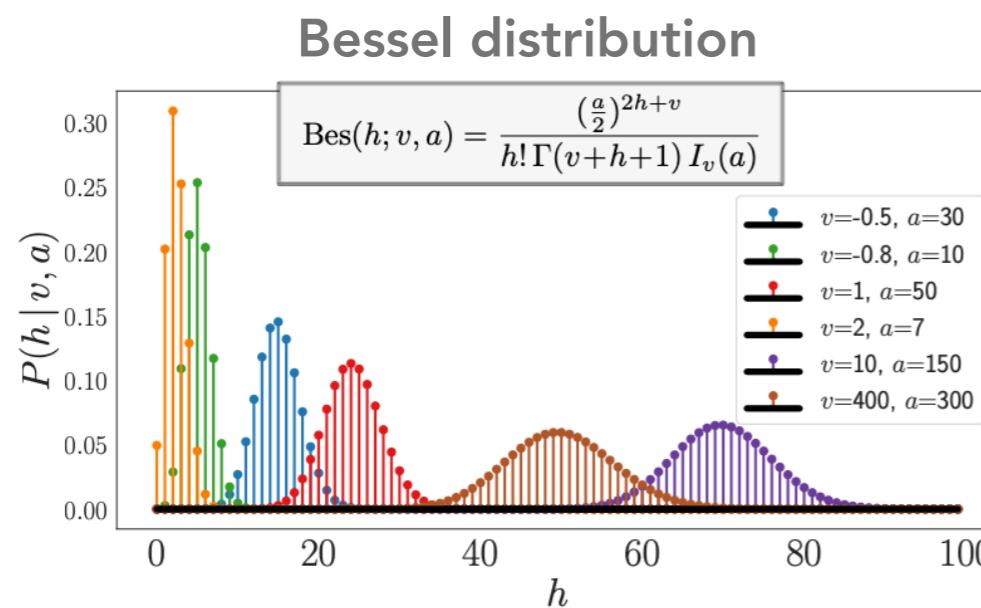
Partially conditionally conjugate

$$(\theta^{(t)} | -) \sim P(\theta^{(t)} | h^{(t)}, h^{(t+1)}, -)$$
 ✓

Partially not

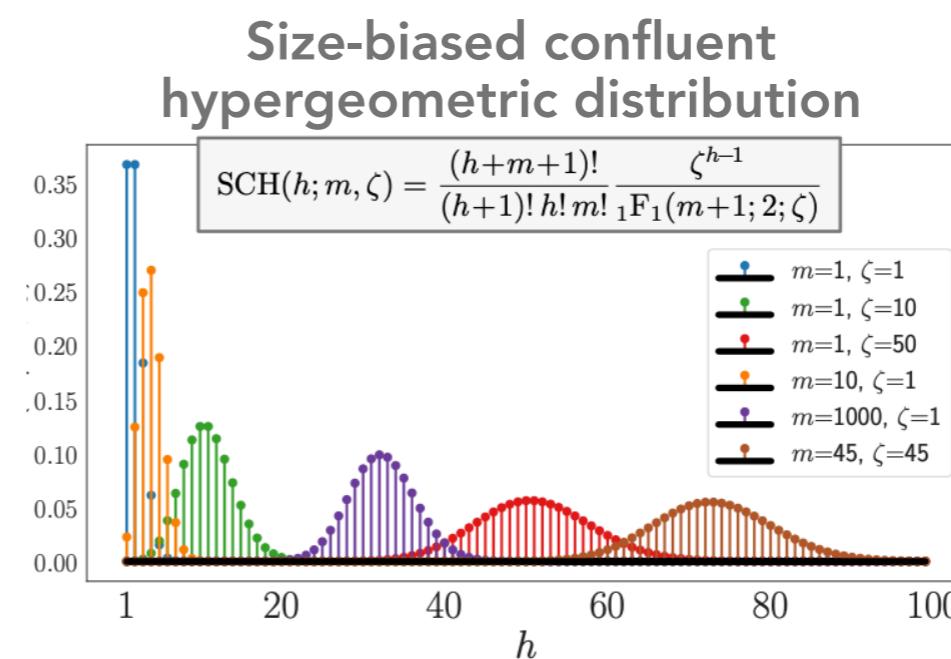
$$P(h^{(t)} | -) =$$
 ✓ ...but even without conjugacy...

closed-formedness!



(Yuan and Kalbfleisch, 2000)

(Devroye 2002)



OUTLINE

- ▶ Motivation: Dyadic event data (and its challenges)
- ▶ Non-negative (Poisson) tensor decompositions
 - ▶ CP extracts “multilateral” structure [Schein et al., 2015]
 - ▶ Tucker extracts “communities” [Schein et al., 2016]
 - ▶ Why (allocative) Poisson factorization
 - ▶ AL ℓ_0 CORE avoids the “exponential blowup” [Hood & Schein, 2024]

Appendix (*time permitting*)

- ▶ State-space modeling
 - ▶ Gamma state-space models [Schein et al., 2016b; Schein et al., 2019]
 - ▶ Modeling “escalation” with a new matrix prior [Stoehr et al., 2023]

OUTLINE

- ▶ Motivation: Dyadic event data (and its challenges)
- ▶ Non-negative (Poisson) tensor decompositions
 - ▶ CP extracts “multilateral” structure [Schein et al., 2015]
 - ▶ Tucker extracts “communities” [Schein et al., 2016]
 - ▶ Why (allocative) Poisson factorization
 - ▶ AL ℓ_0 CORE avoids the “exponential blowup” [Hood & Schein, 2024]

Appendix (*time permitting*)

- ▶ State-space modeling
 - ▶ Gamma state-space models [Schein et al., 2016b; Schein et al., 2019]
 - ▶ Modeling “escalation” with a new matrix prior [Stoehr et al., 2023]

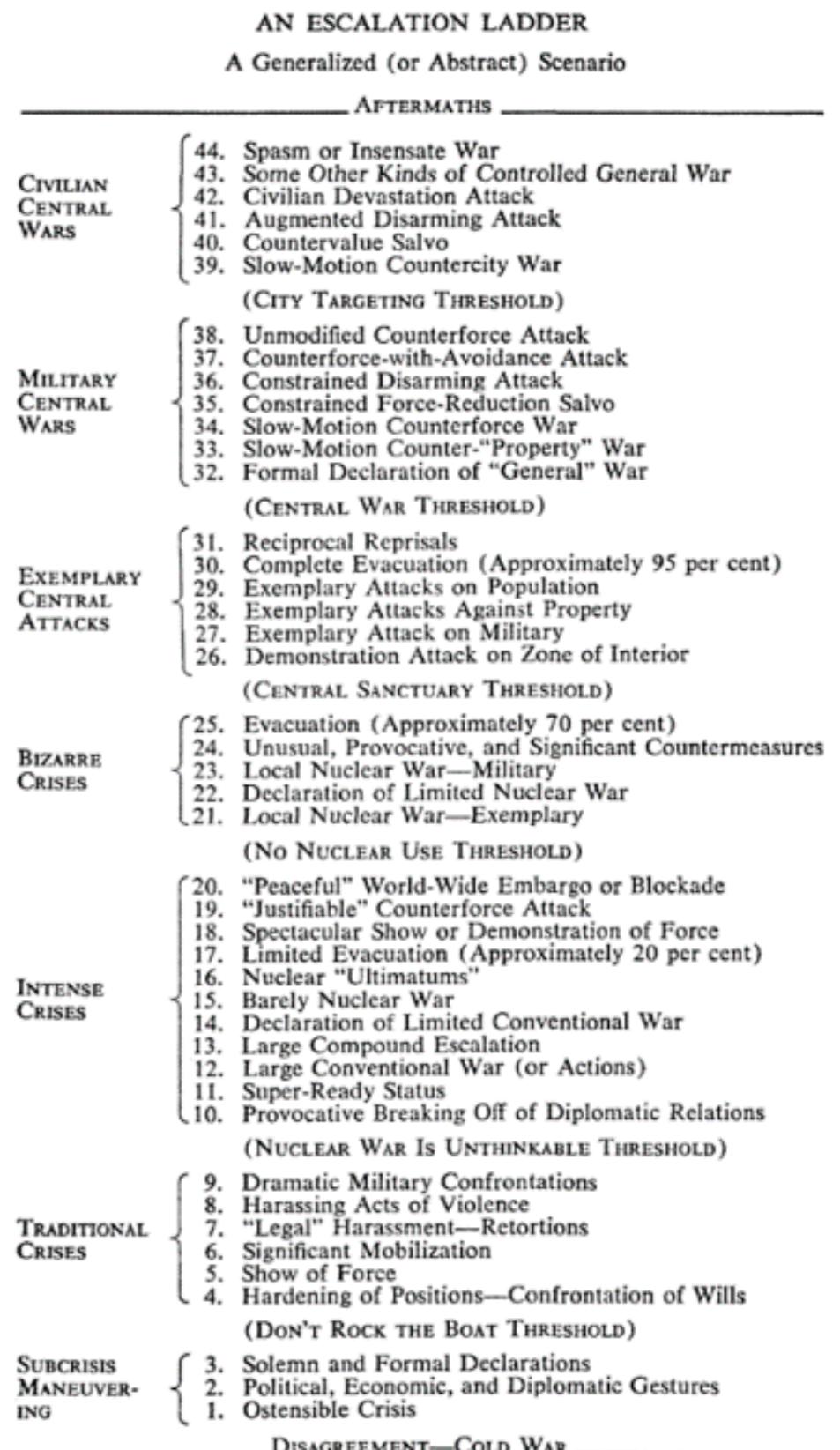
Escalation in international relations

Escalation is a central **concept** in IR...

Table 2
WEIS Coding of 1990 Iraq-Kuwait Crisis

Date	Source	Target	Type of Action
900717	IRQ	KUW	CHARGE
900725	IRQ	EGY	ASSURE
900727	IRQ	KUW	WARN
900731	IRQ	KUW	MOBILIZATION
900801	KUW	IRQ	REFUSE
900802	IRQ	KUW	MILITARY FORCE

...but **not observed** directly



Stoehr et al. [AISTATS 2023]

The Ordered Matrix Dirichlet for State-Space Models

Niklas Stoehr^f

^fETH Zurich

Benjamin J. Radford^g

^gUNC Charlotte

Ryan Cotterell^f

^fThe University of Chicago

Aaron Schein^a

^aschein@uchicago.edu

niklas.stoehr@inf.ethz.ch bradfor7@uncc.edu ryan.cotterell@inf.ethz.ch schein@uchicago.edu

State-space models to measure (de-)escalation in dyadic event data

Niklas Werner Stöhr

Lead author:



Address

ETH Zürich
Doctorate at D-INFK
Niklas Werner Stöhr
Professur für Informatik
OAT W 14
Andreasstrasse 5
8092 Zürich
Switzerland

Ordinal action types

action type <i>a</i>	action name	Goldstein value
0	provide aid	7.0
1	engage material cooperation	6.0
2	yield	5.0
3	express intent cooperate	4.0
4	engage diplomatic cooperation	3.5
5	appeal	3.0
6	consult	1.0
7	make public statement	0.0
9	investigate	-2.0
10	disapprove	-2.0
11	reject	-4.0
12	reduce relations	-4.0
13	demand	-5.0
14	threaten	-6.0
15	protest	-6.5
16	coerce	-7.0
17	exhibit force posture	-7.2
18	assault	-9.0
19	fight	-10.0
20	unconventional mass violence	-10.0

State-space model

$$\mathbb{E} \left[y_{i \rightarrow j}^{(t)} \right] = \sum_{k=1}^K \lambda_{i \rightarrow j}^{(t)} \phi_{ka}$$

State-space model

how much **dyad** $i \rightarrow j$
is in **state** k at time t

$$\mathbb{E} \left[y_{i \rightarrow j}^{(t)} \right] = \sum_{k=1}^K \lambda_{i \rightarrow j}^{(t)} \phi_{ka}$$

↓
how much **state** k
emits **action** a

State-space model

how much **dyad** $i \rightarrow j$
is in **state** k at time t

$$\mathbb{E} \left[y_{i \rightarrow j}^{(t)} \right] = \sum_{k=1}^K \lambda_{i \rightarrow j}^{(t)} \phi_{ka}$$

how much **state** k
emits **action** a

$$\mathbb{E} \left[\lambda_{i \rightarrow j}^{(t)} \right] = \sum_{k'=1}^K \pi_{k'k} \lambda_{i \rightarrow j}^{(t-1)}$$

State-space model

how much **dyad** $i \rightarrow j$
is in **state** k at time t

$$\mathbb{E} \left[y_{i \rightarrow j}^{(t)} \right] = \sum_{k=1}^K \lambda_{i \rightarrow j}^{(t)} \phi_{ka}$$

how much **state** k
emits **action** a

how much **state** k'
transitions to **state** k

$$\mathbb{E} \left[\lambda_{i \rightarrow j}^{(t)} \right] = \sum_{k'=1}^K \pi_{k'k} \lambda_{i \rightarrow j}^{(t-1)}$$

State-space model

how much **dyad** $i \rightarrow j$
is in **state** k at time t

$$\mathbb{E} \left[y_{i \rightarrow j}^{(t)} \right] = \sum_{k=1}^K \lambda_{i \rightarrow j}^{(t)} \phi_{ka}$$

how much **state** k
emits **action** a

Φ is the $K \times A$ **emission matrix**

how much **state** k'
transitions to **state** k

$$\mathbb{E} \left[\lambda_{i \rightarrow j}^{(t)} \right] = \sum_{k'=1}^K \pi_{k'k} \lambda_{i \rightarrow j}^{(t-1)}$$

Π is the $K \times K$ **transition matrix**

State-space model

how much **dyad** $i \rightarrow j$
is in **state** k at time t

$$\mathbb{E} \left[y_{i \rightarrow j}^{(t)} \right] = \sum_{k=1}^K \lambda_{i \rightarrow j}^{(t)} \phi_{ka}$$

how much **state** k
emits **action** a

Φ is the $K \times A$ **emission matrix**
(row-stochastic)

$$\sum_{a=1}^A \phi_{ka} = 1$$

how much **state** k'
transitions to **state** k

$$\mathbb{E} \left[\lambda_{i \rightarrow j}^{(t)} \right] = \sum_{k'=1}^K \pi_{k'k} \lambda_{i \rightarrow j}^{(t-1)}$$

Π is the $K \times K$ **transition matrix**
(row-stochastic)

$$\sum_{k'=1}^K \pi_{kk'} = 1$$

State-space model

how much **dyad** $i \rightarrow j$
is in **state** k at time t

$$\mathbb{E} \left[y_{i \rightarrow j}^{(t)} \right] = \sum_{k=1}^K \lambda_{i \rightarrow j}^{(t)} \phi_{ka}$$

how much **state** k
emits **action** a

Φ is the $K \times A$ **emission matrix**

how much **state** k'
transitions to **state** k

$$\mathbb{E} \left[\lambda_{i \rightarrow j}^{(t)} \right] = \sum_{k'=1}^K \pi_{k'k} \lambda_{i \rightarrow j}^{(t-1)}$$

Idea: Impose ordering on states:
 k^{th} state is more conflictual than $(k - 1)^{\text{th}}$

Π is the $K \times K$ **transition matrix**

State-space model

how much **dyad** $i \rightarrow j$
is in **state** k at time t

$$\mathbb{E} \left[y_{i \rightarrow j}^{(t)} \right] = \sum_{k=1}^K \lambda_{i \rightarrow j}^{(t)} \phi_{ka}$$

how much **state** k
emits **action** a

Φ is the $K \times A$ **emission matrix**
(row-stochastic) $\sum_{a=1}^A \phi_{ka} = 1$

how much **state** k'
transitions to **state** k

$$\mathbb{E} \left[\lambda_{i \rightarrow j}^{(t)} \right] = \sum_{k'=1}^K \pi_{k'k} \lambda_{i \rightarrow j}^{(t-1)}$$

Idea: Impose ordering on states:
 k^{th} state is more conflictual than $(k-1)^{\text{th}}$

Π is the $K \times K$ **transition matrix**
(row-stochastic) $\sum_{k'=1}^K \pi_{kk'} = 1$

Ordered state-space model

Idea: Impose ordering on states:

k^{th} state is more conflictual than $(k - 1)^{\text{th}}$

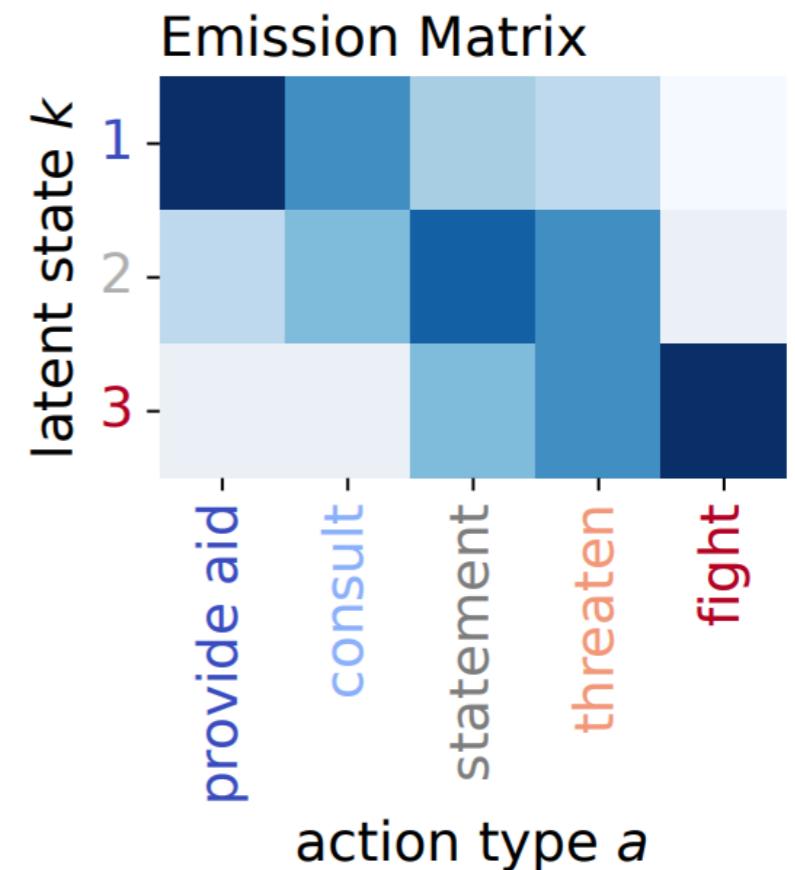
Ordered state-space model

Idea: Impose ordering on states:

k^{th} state is more conflictual than $(k - 1)^{\text{th}}$

Each state k defines a distribution over actions $(\phi_{k1}, \dots, \phi_{kA})$

(k^{th} row of the emission matrix Φ)



Ordered state-space model

Idea: Impose ordering on states:

k^{th} state is more conflictual than $(k - 1)^{\text{th}}$

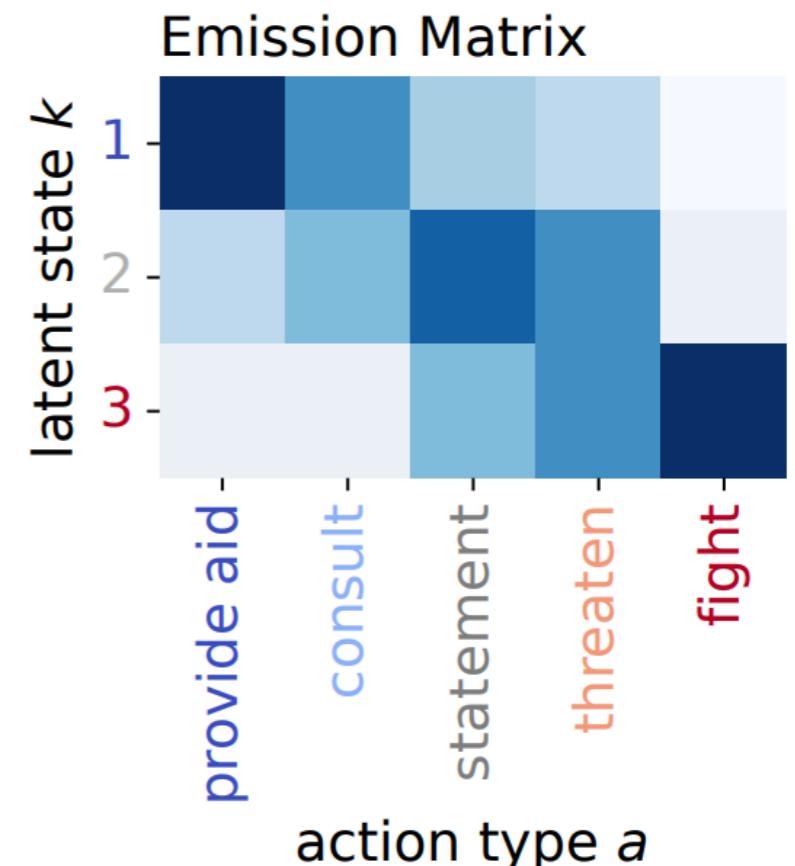
Each state k defines a distribution over actions $(\phi_{k1}, \dots, \phi_{kA})$

$(k^{\text{th}}$ row of the emission matrix Φ)

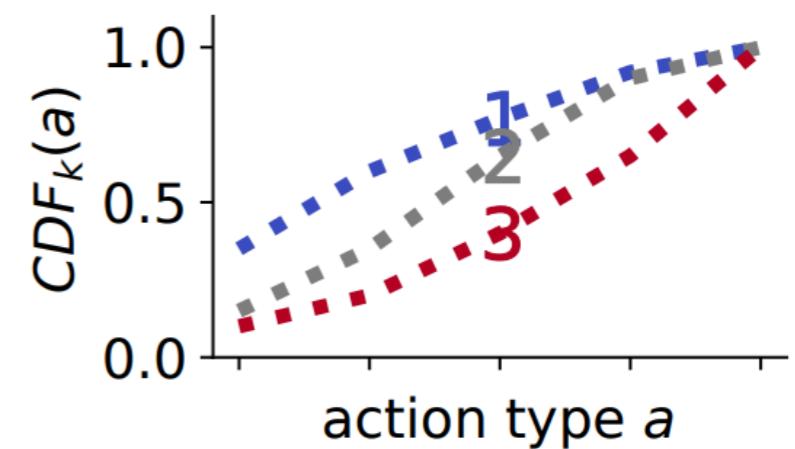
Operationalization:

k^{th} row stochastically dominates $(k - 1)^{\text{th}}$

$$\sum_{a' \leq a} \phi_{ka'} \geq \sum_{a' \leq a} \phi_{k'a'} \text{ for any } a \text{ and } k < k'$$



Emission Matrix Row CDFs



Ordered state-space model

Idea: Impose ordering on states:

k^{th} state is more conflictual than $(k - 1)^{\text{th}}$

Each state k defines a distribution over actions $(\phi_{k1}, \dots, \phi_{kA})$

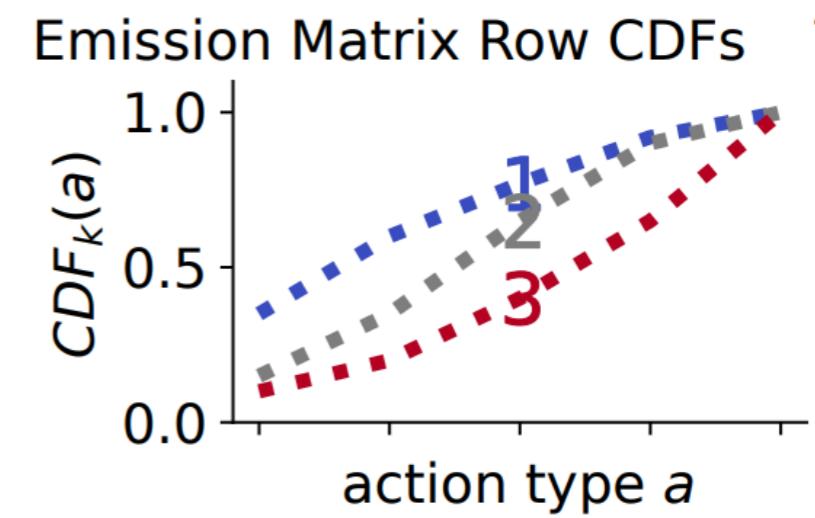
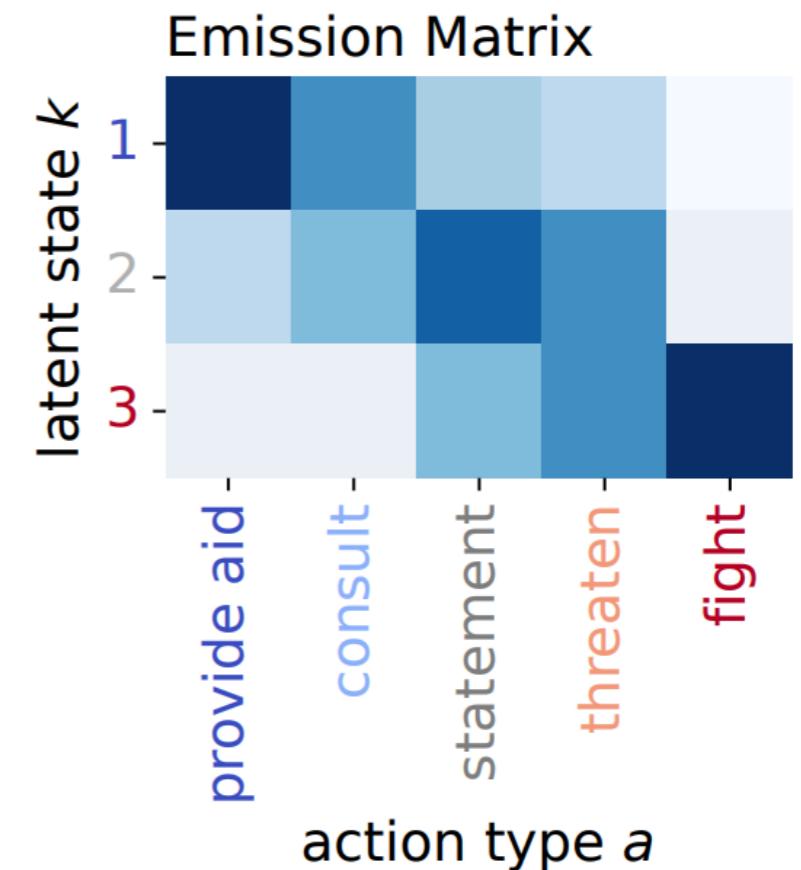
(k^{th} row of the emission matrix Φ)

Operationalization:

k^{th} row stochastically dominates $(k - 1)^{\text{th}}$

$$\sum_{a' \leq a} \phi_{ka'} \geq \sum_{a' \leq a} \phi_{k'a'} \quad \text{for any } a \text{ and } k < k'$$

“well-ordered stochastic matrix”
(probability mass shifts down and right)

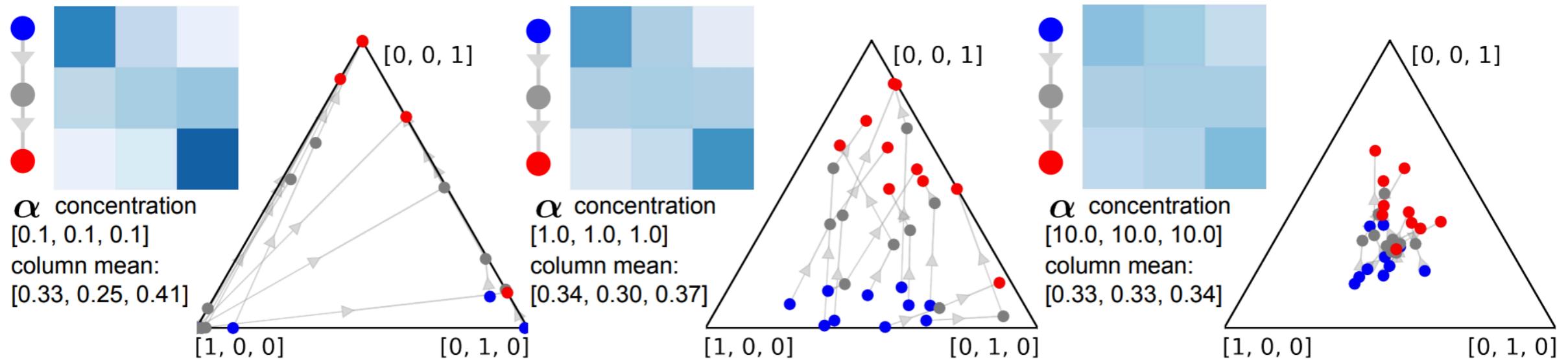


Ordered Matrix Dirichlet

A distribution over “well-ordered” row-stochastic matrices

$$\Phi \sim \text{OMD}(\alpha)$$

Defined implicitly using a **stick-breaking construction**



Ordered transitions

how much **state** k'
transitions to **state** k

$$\mathbb{E} \left[\lambda_{i \xrightarrow{k} j}^{(t)} \right] = \sum_{k'=1}^K \pi_{k'k} \downarrow \lambda_{i \xrightarrow{k'} j}^{(t-1)}$$

Π is the $K \times K$ **transition matrix**
(row-stochastic)

Ordered transitions

how much **state k'**
transitions to **state k**

$$\mathbb{E} \left[\lambda_{i \rightarrow j}^{(t)} \right] = \sum_{k'=1}^K \pi_{k'k} \lambda_{i \rightarrow j}^{(t-1)}$$

Π is the $K \times K$ transition matrix
(row-stochastic)

Ladder of escalation: *Allies do not become enemies overnight*

AN ESCALATION LADDER	
A Generalized (or Abstract) Scenario	
AFTERMATHS	
CIVILIAN CENTRAL WARS	44. Spasm or Insensate War 43. Some Other Kinds of Controlled General War 42. Civilian Devastation Attack 41. Augmented Disarming Attack 40. Countervalue Salvo 39. Slow-Motion Countercity War (CITY TARGETING THRESHOLD) 38. Unmodified Counterforce Attack 37. Counterforce with Avoidance Attack 36. Constrained Disarming Attack 35. Constrained Force-Reduction Salvo Slow-Motion Counterforce War 34. Slow-Motion Counter-“Property” War 33. Slow-Motion Counter-“General” War 32. Formal Declaration of “General” War (CENTRAL WAR THRESHOLD) 31. Reciprocal Reprisals 30. Complete Evacuation (Approximately 95 per cent) 29. Exemplary Attacks on Population 28. Exemplary Attacks Against Property 27. Exemplary Attack on Military 26. Demonstration Attack on Zone of Interior (CENTRAL SANCTUARY THRESHOLD) 25. Evacuation (Approximately 70 per cent) 24. Unusual, Provocative, and Significant Countermeasures 23. Local Nuclear War—Military 22. Declaration of Limited Nuclear War 21. Local Nuclear War—Exemplary (No NUCLEAR USE THRESHOLD) 20. “Peaceful” World-Wide Embargo or Blockade 19. “Justifiable” Counterforce Attack 18. Spectacular Show or Demonstration of Force 17. Limited Evacuation (Approximately 20 per cent) 16. Nuclear “Ultimatum” 15. Nuclear Nuclear War 14. Declaration of Limited Conventional War 13. Large Compound Escalation 12. Large Conventional War (or Actions) 11. Super-Ready Status 10. Provocative Breaking Off of Diplomatic Relations (NUCLEAR WAR IS UNTHINKABLE THRESHOLD) 9. Dramatic Military Confrontations 8. Hostile Acts of Violence 7. “Legal” Harassment—Retortions 6. Significant Mobilization 5. Show of Force 4. Hardening of Positions—Confrontation of Wills (DON’T ROCK THE BOAT THRESHOLD) 3. Solemn and Formal Declarations 2. Political, Economic, and Diplomatic Gestures 1. Ostensible Crisis
TRADITIONAL CRISES	
SUBCRISIS- MANEUVER- ING	
DISAGREEMENT—COLD WAR	

Ordered transitions

how much **state k'**
transitions to **state k**

$$\mathbb{E} \left[\lambda_{i \rightarrow j}^{(t)} \right] = \sum_{k'=1}^K \pi_{k'k} \lambda_{i \rightarrow j}^{(t-1)}$$

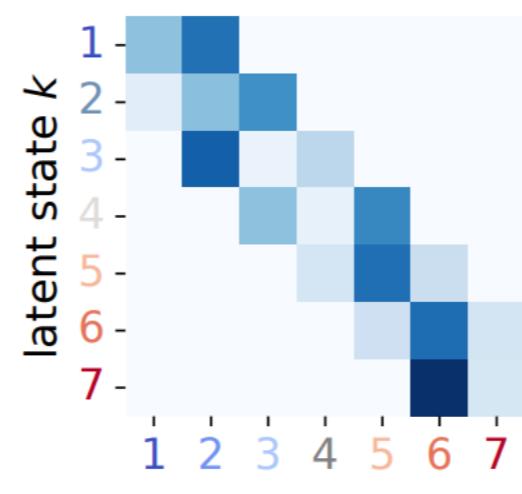
Π is the $K \times K$ transition matrix
(row-stochastic)

Ladder of escalation: *Allies do not become enemies overnight*

AN ESCALATION LADDER	
A Generalized (or Abstract) Scenario	
<u>AFTERMATHS</u>	
CIVILIAN CENTRAL WARS	44. Spasm or Insensate War 43. Some Other Kinds of Controlled General War 42. Civilian Devastation Attack 41. Augmented Disarming Attack 40. Countervalue Salvo 39. Slow-Motion Countercity War (CITY TARGETING THRESHOLD) 38. Unmodified Counterforce Attack 37. Counterforce with Avoidance Attack 36. Constrained Disarming Attack 35. Constrained Force-Reduction Salvo Slow-Motion Counterforce War 33. Slow-Motion Counter-“Property” War 32. Formal Declaration of “General” War
MILITARY CENTRAL WARS	31. Reciprocal Reprisals 30. Complete Evacuation (Approximately 95 per cent) 29. Exemplary Attacks on Population 28. Exemplary Attacks Against Property 27. Exemplary Attack on Military 26. Demonstration Attack on Zone of Interior (CENTRAL SANCTUARY THRESHOLD) 25. Evacuation (Approximately 70 per cent) 24. Unusual, Provocative, and Significant Countermeasures 23. Local Nuclear War—Military 22. Declaration of Limited Nuclear War 21. Local Nuclear War—Exemplary (No NUCLEAR USE THRESHOLD) 20. “Peaceful” World-Wide Embargo or Blockade 19. “Justifiable” Counterforce Attack 18. Spectacular Show or Demonstration of Force 17. Limited Evacuation (Approximately 20 per cent) 16. Nuclear “Ultimatum” 15. Nuclear War 14. Declaration of Limited Conventional War 13. Large Compound Escalation 12. Large Conventional War (or Actions) 11. Super-Ready Status 10. Provocative Breaking Off of Diplomatic Relations (NUCLEAR WAR IS UNTHINKABLE THRESHOLD) 9. Dramatic Military Confrontations 8. Hostile Acts of Violence 7. “Legal” Harassment—Retortions 6. Significant Mobilization 5. Show of Force 4. Hardening of Positions—Confrontation of Wills (DON’T ROCK THE BOAT THRESHOLD)
BIZARRE CRISES	3. Solemn and Formal Declarations 2. Political, Economic, and Diplomatic Gestures 1. Ostensible Crisis DISAGREEMENT—COLD WAR

Traditional way to operationalize this:

Banded transition matrix



Ordered transitions

how much **state k'**
transitions to **state k**

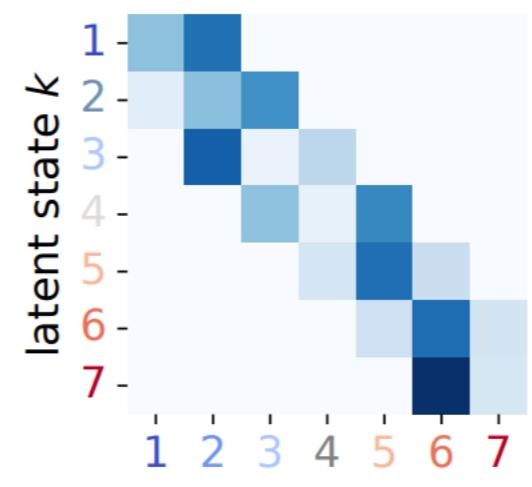
$$\mathbb{E} \left[\lambda_{i \rightarrow j}^{(t)} \right] = \sum_{k'=1}^K \pi_{k'k} \lambda_{i \rightarrow j}^{(t-1)}$$

Π is the $K \times K$ **transition matrix**
(row-stochastic)

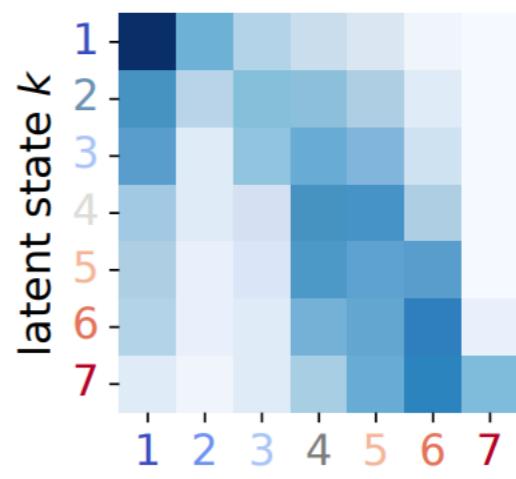
Ladder of escalation: *Allies do not become enemies overnight*

AN ESCALATION LADDER	
A Generalized (or Abstract) Scenario	
<u>AFTERMATHS</u>	
CIVILIAN CENTRAL WARS	44. Spasm or Insensate War 45. Some Other Kinds of Controlled General War 46. Civilian Devastation Attack 41. Augmented Disarming Attack 40. Countervalue Salvo 39. Slow-Motion Countercity War (CITY TARGETING THRESHOLD)
MILITARY CENTRAL WARS	38. Unmodified Counterforce Attack 37. Counterforce with Avoidance Attack 36. Constrained Disarming Attack 35. Constrained Force-Reduction Salvo Slow-Motion Counterforce War 33. Slow-Motion Counter-“Property” War 32. Formal Declaration of “General” War (CENTRAL WAR THRESHOLD)
EXEMPLARY CENTRAL ATTACKS	31. Reciprocal Reprisals 30. Complete Evacuation (Approximately 95 per cent) 29. Exemplary Attacks on Population 28. Exemplary Attacks Against Property 27. Exemplary Attack on Military 26. Demonstration Attack on Zone of Interior (CENTRAL SANCTUARY THRESHOLD)
BIZARRE CRIMES	25. Evacuation (Approximately 70 per cent) 24. Unusual, Provocative, and Significant Countermeasures 23. Local Nuclear War—Military 22. Declaration of Limited Nuclear War 21. Local Nuclear War—Exemplary (No NUCLEAR USE THRESHOLD)
INTENSE CRIMES	20. “Peaceful” World-Wide Embargo or Blockade 19. “Justifiable” Counterforce Attack 18. Spectacular Show or Demonstration of Force 17. Limited Evacuation (Approximately 20 per cent) 16. Nuclear “Ultimatum” 15. Nuclear War 14. Declaration of Limited Conventional War 13. Large Compound Escalation 12. Large Conventional War (or Actions) 11. Super-Ready Status 10. Provocative Breaking Off of Diplomatic Relations (NUCLEAR WAR IS UNTHINKABLE THRESHOLD)
TRADITIONAL CRIMES	9. Dramatic Military Confrontations 8. Hostile Acts of Violence 7. “Legal” Harassment—Retortions 6. Significant Mobilization 5. Show of Force 4. Hardening of Positions—Confrontation of Wills (DON’T ROCK THE BOAT THRESHOLD)
SUBCRISIS— MANEUVER- ING	3. Solemn and Formal Declarations 2. Political, Economic, and Diplomatic Gestures 1. Ostensible Crisis DISAGREEMENT—COLD WAR

Traditional way to operationalize this:
Banded transition matrix

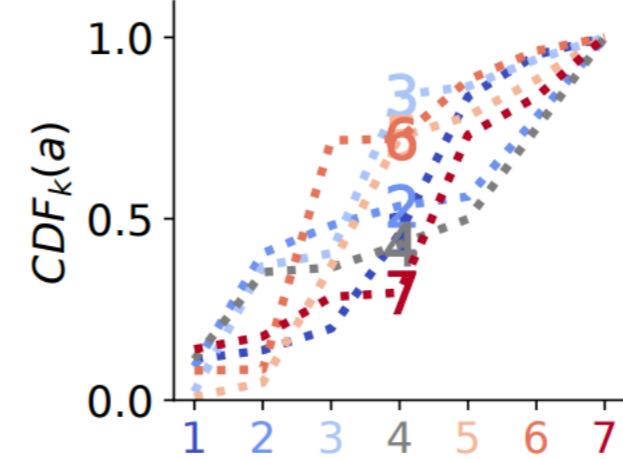
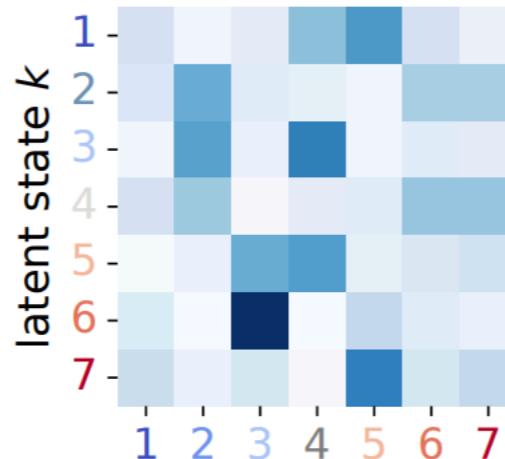


New way: $\Pi \sim \text{OMD}(\alpha)$
OMD transition matrix

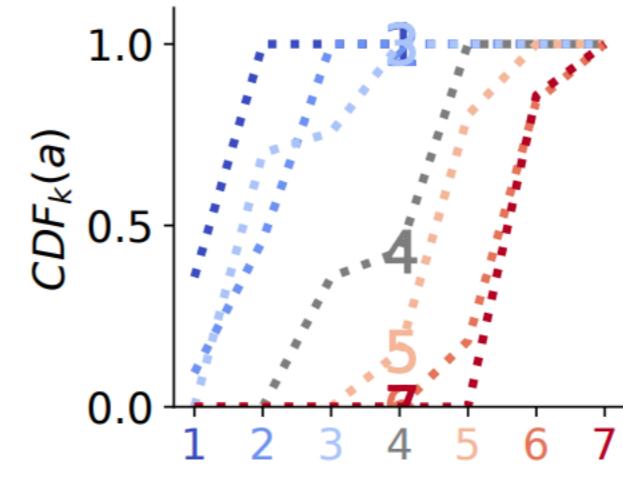
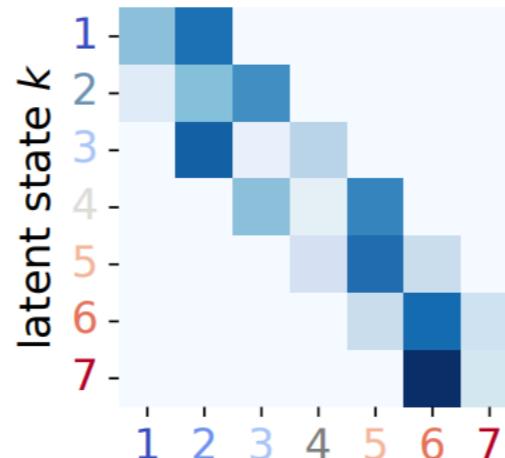


Ordered transitions

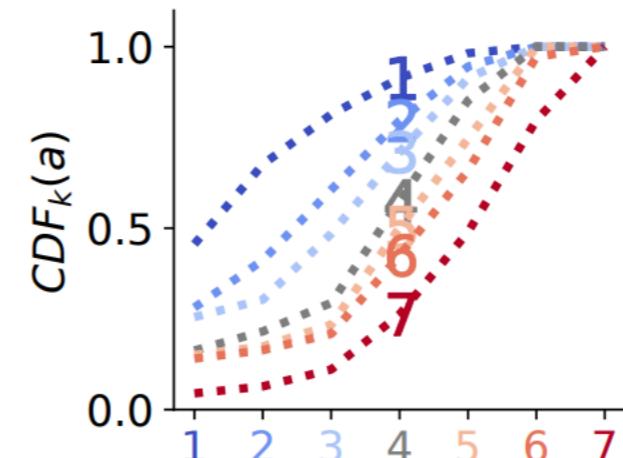
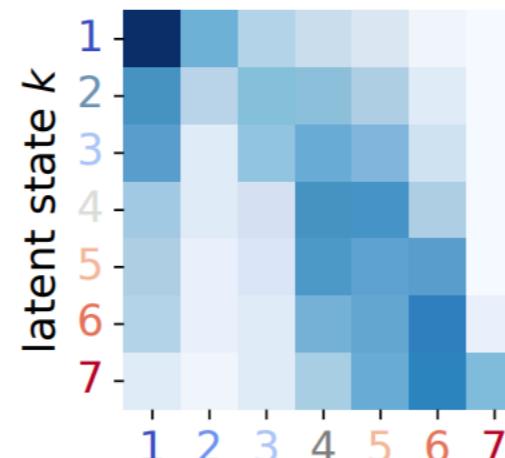
Standard Matrix Dirichlet (SMD)



Banded Matrix Dirichlet (BMD)



Ordered Matrix Dirichlet (OMD)



Putting it all together: **full model**

well-ordered **emission** matrix

$$\Phi \sim \text{OMD}(\alpha)$$

well-ordered **transition** matrix

$$\Pi \sim \text{OMD}(\alpha)$$

$$\mathbb{E} \left[y_{i \rightarrow j}^{(t)} \right] = \sum_{k=1}^K \lambda_{i \rightarrow j}^{(t)} \phi_{ka}$$

$$\mathbb{E} \left[\lambda_{i \rightarrow j}^{(t)} \right] = \sum_{k'=1}^K \pi_{k'k} \lambda_{i \rightarrow j}^{(t-1)}$$

Putting it all together: **full model**

well-ordered **emission** matrix

$$\Phi \sim \text{OMD}(\alpha)$$

well-ordered **transition** matrix

$$\Pi \sim \text{OMD}(\alpha)$$

$$\mathbb{E} \left[y_{i \rightarrow j}^{(t)} \right] = \sum_{k=1}^K \lambda_{i \rightarrow j}^{(t)} \phi_{ka}$$

$$\mathbb{E} \left[\lambda_{i \rightarrow j}^{(t)} \right] = \sum_{k'=1}^K \pi_{k'k} \lambda_{i \rightarrow j}^{(t-1)}$$

One extra piece...

$$\lambda_{i \rightarrow j}^{(t)} \equiv \sum_{c=1}^C \sum_{d=1}^C \psi_{ic} \psi_{jd} \lambda_{c \rightarrow d}^{(t)}$$

Putting it all together: **full model**

well-ordered **emission** matrix

$$\Phi \sim \text{OMD}(\alpha)$$

$$\mathbb{E} \left[y_{i \rightarrow j}^{(t)} \right] = \sum_{k=1}^K \lambda_{i \rightarrow j}^{(t)} \phi_{ka}$$

well-ordered **transition** matrix

$$\Pi \sim \text{OMD}(\alpha)$$

$$\mathbb{E} \left[\lambda_{i \rightarrow j}^{(t)} \right] = \sum_{k'=1}^K \pi_{k'k} \lambda_{i \rightarrow j}^{(t-1)}$$

One extra piece...

$$\lambda_{i \rightarrow j}^{(t)} \equiv \sum_{c=1}^C \sum_{d=1}^C \psi_{ic} \psi_{jd} \lambda_{c \rightarrow d}^{(t)}$$

how much **countries** i and j
participate in **communities** c and d

Putting it all together: **full model**

well-ordered **emission** matrix

$$\Phi \sim \text{OMD}(\alpha)$$

$$\mathbb{E} \left[y_{i \rightarrow j}^{(t)} \right] = \sum_{k=1}^K \lambda_{i \rightarrow j}^{(t)} \phi_{ka}$$

well-ordered **transition** matrix

$$\Pi \sim \text{OMD}(\alpha)$$

$$\mathbb{E} \left[\lambda_{i \rightarrow j}^{(t)} \right] = \sum_{k'=1}^K \pi_{k'k} \lambda_{i \rightarrow j}^{(t-1)}$$

One extra piece...

$$\lambda_{i \rightarrow j}^{(t)} \equiv \sum_{c=1}^C \sum_{d=1}^C \psi_{ic} \psi_{jd} \lambda_{c \rightarrow d}^{(t)}$$

how much **countries** i and j participate in **communities** c and d

how much **dyad** $c \rightarrow d$ is in **state** k at **time** t

```
graph TD; A["\lambda_{i \rightarrow j}^{(t)} \equiv \sum_{c=1}^C \sum_{d=1}^C \psi_{ic} \psi_{jd} \lambda_{c \rightarrow d}^{(t)}"] --> B["\psi_{ic}"]; B --> C["\psi_{jd}"]; C --> D["\lambda_{c \rightarrow d}^{(t)}"]
```

Putting it all together: **full model**

well-ordered **emission** matrix

$$\Phi \sim \text{OMD}(\alpha)$$

$$\mathbb{E} \left[y_{i \rightarrow j}^{(t)} \right] = \sum_{k=1}^K \sum_{c=1}^C \sum_{d=1}^C \psi_{ic} \psi_{jd} \lambda_{c \rightarrow d}^{(t)} \phi_{ka}$$

well-ordered **transition** matrix

$$\Pi \sim \text{OMD}(\alpha)$$

$$\mathbb{E} \left[\lambda_{c \rightarrow d}^{(t)} \right] = \sum_{k'=1}^K \pi_{k'k} \lambda_{c \rightarrow d}^{(t-1)}$$

One extra piece...

$$\lambda_{i \rightarrow j}^{(t)} \equiv \sum_{c=1}^C \sum_{d=1}^C \psi_{ic} \psi_{jd} \lambda_{c \rightarrow d}^{(t)}$$

how much **countries** i and j participate in **communities** c and d

how much **dyad** $c \rightarrow d$ is in **state** k at **time** t

The diagram consists of two sets of arrows. One set of arrows points from the summation indices c and d in the equation to the text "how much countries i and j participate in communities c and d ". The other set of arrows points from the state index k in the equation to the text "how much dyad $c \rightarrow d$ is in state k at time t ".

Putting it all together: **full model**

well-ordered **emission** matrix

$$\Phi \sim \text{OMD}(\alpha)$$

$$\mathbb{E} \left[y_{i \xrightarrow{a} j}^{(t)} \right] = \sum_{k=1}^K \sum_{c=1}^C \sum_{d=1}^C \psi_{ic} \psi_{jd} \lambda_{c \xrightarrow{k} d}^{(t)} \phi_{ka}$$

Tucker decomposition

well-ordered **transition** matrix

$$\Pi \sim \text{OMD}(\alpha)$$

$$\mathbb{E} \left[\lambda_{c \xrightarrow{k} d}^{(t)} \right] = \sum_{k'=1}^K \pi_{k'k} \lambda_{c \xrightarrow{k'} d}^{(t-1)}$$

state-space model over
the **core tensor**

Putting it all together: **full model**

well-ordered **emission** matrix

$$\Phi \sim \text{OMD}(\alpha)$$

$$\mathbb{E} \left[y_{i \rightarrow j}^{(t)} \right] = \sum_{k=1}^K \sum_{c=1}^C \sum_{d=1}^C \psi_{ic} \psi_{jd} \lambda_{c \rightarrow d}^{(t)} \phi_{ka}$$

Tucker decomposition

well-ordered **transition** matrix

$$\Pi \sim \text{OMD}(\alpha)$$

$$\mathbb{E} \left[\lambda_{c \rightarrow d}^{(t)} \right] = \sum_{k'=1}^K \pi_{k'k} \lambda_{c \rightarrow d}^{(t-1)}$$

state-space model over
the **core tensor**

$$y_{i \rightarrow j}^{(t)} \sim \text{Pois} \left(\sum_{k=1}^K \sum_{c=1}^C \sum_{d=1}^C \psi_{ic} \psi_{jd} \lambda_{c \rightarrow d}^{(t)} \phi_{ka} \right)$$

$$\lambda_{c \rightarrow d}^{(t)} \sim \text{Gamma} \left(\tau_0 \sum_{k'=1}^K \pi_{k'k} \lambda_{c \rightarrow d}^{(t-1)}, \tau_0 \right)$$

Poisson Tucker decomposition
[ICML '16]

Poisson-Gamma dynamical system
[NeurIPS '16]

Putting it all together: **full model**

well-ordered **emission** matrix

$$\Phi \sim \text{OMD}(\alpha)$$

$$\mathbb{E} \left[y_{i \rightarrow j}^{(t)} \right] = \sum_{k=1}^K \sum_{c=1}^C \sum_{d=1}^C \psi_{ic} \psi_{jd} \lambda_{c \rightarrow d}^{(t)} \phi_{ka}$$

Tucker decomposition

well-ordered **transition** matrix

$$\Pi \sim \text{OMD}(\alpha)$$

$$\mathbb{E} \left[\lambda_{c \rightarrow d}^{(t)} \right] = \sum_{k'=1}^K \pi_{k'k} \lambda_{c \rightarrow d}^{(t-1)}$$

state-space model over
the **core tensor**

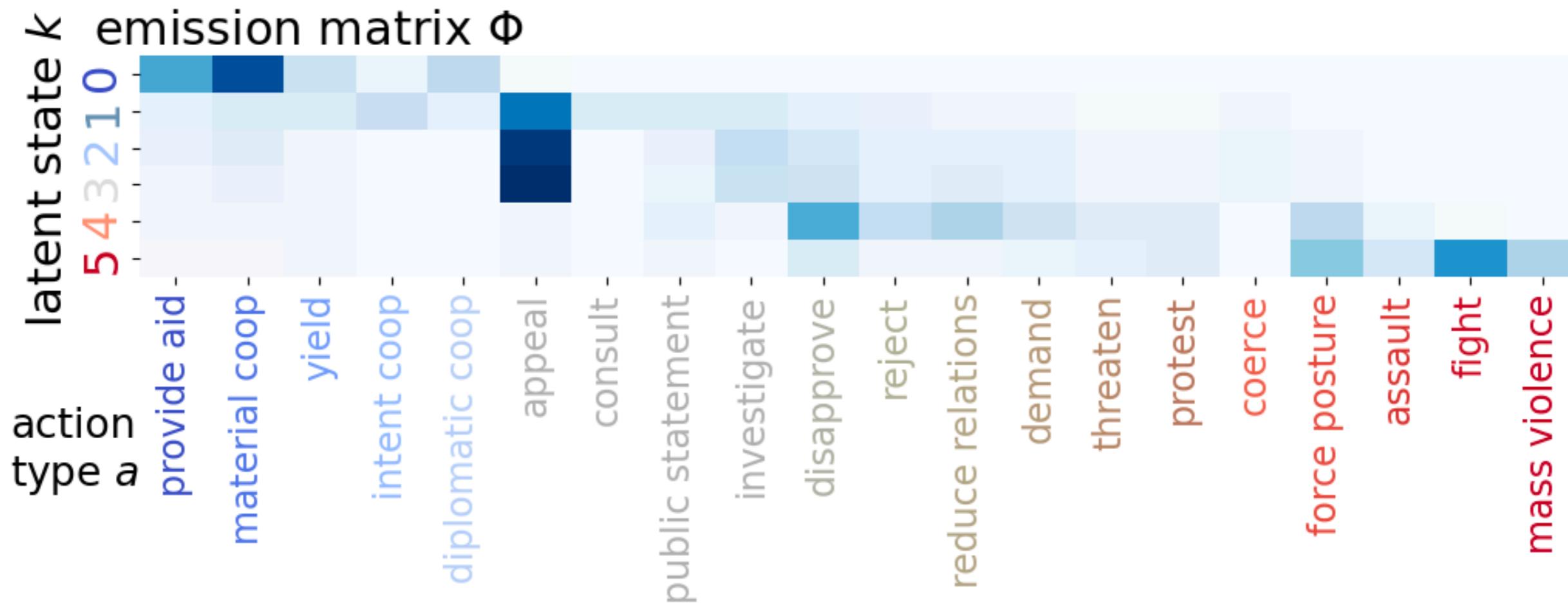
$$y_{i \rightarrow j}^{(t)} \sim \text{Pois} \left(\sum_{k=1}^K \sum_{c=1}^C \sum_{d=1}^C \psi_{ic} \psi_{jd} \lambda_{c \rightarrow d}^{(t)} \phi_{ka} \right)$$

$$\lambda_{c \rightarrow d}^{(t)} \sim \text{Gamma} \left(\tau_0 \sum_{k'=1}^K \pi_{k'k} \lambda_{c \rightarrow d}^{(t-1)}, \tau_0 \right)$$

Poisson Tucker decomposition
[ICML '16]

Poisson-Gamma dynamical system
[NeurIPS '16]

Results: ICEWS 2020 data



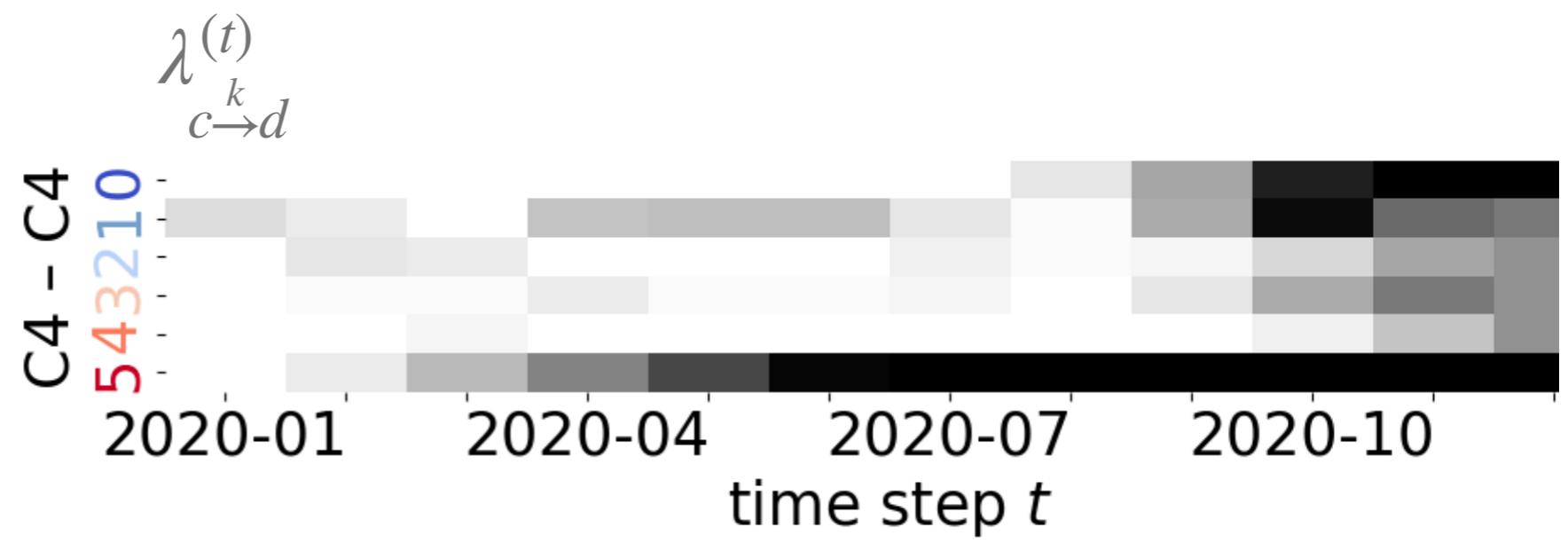
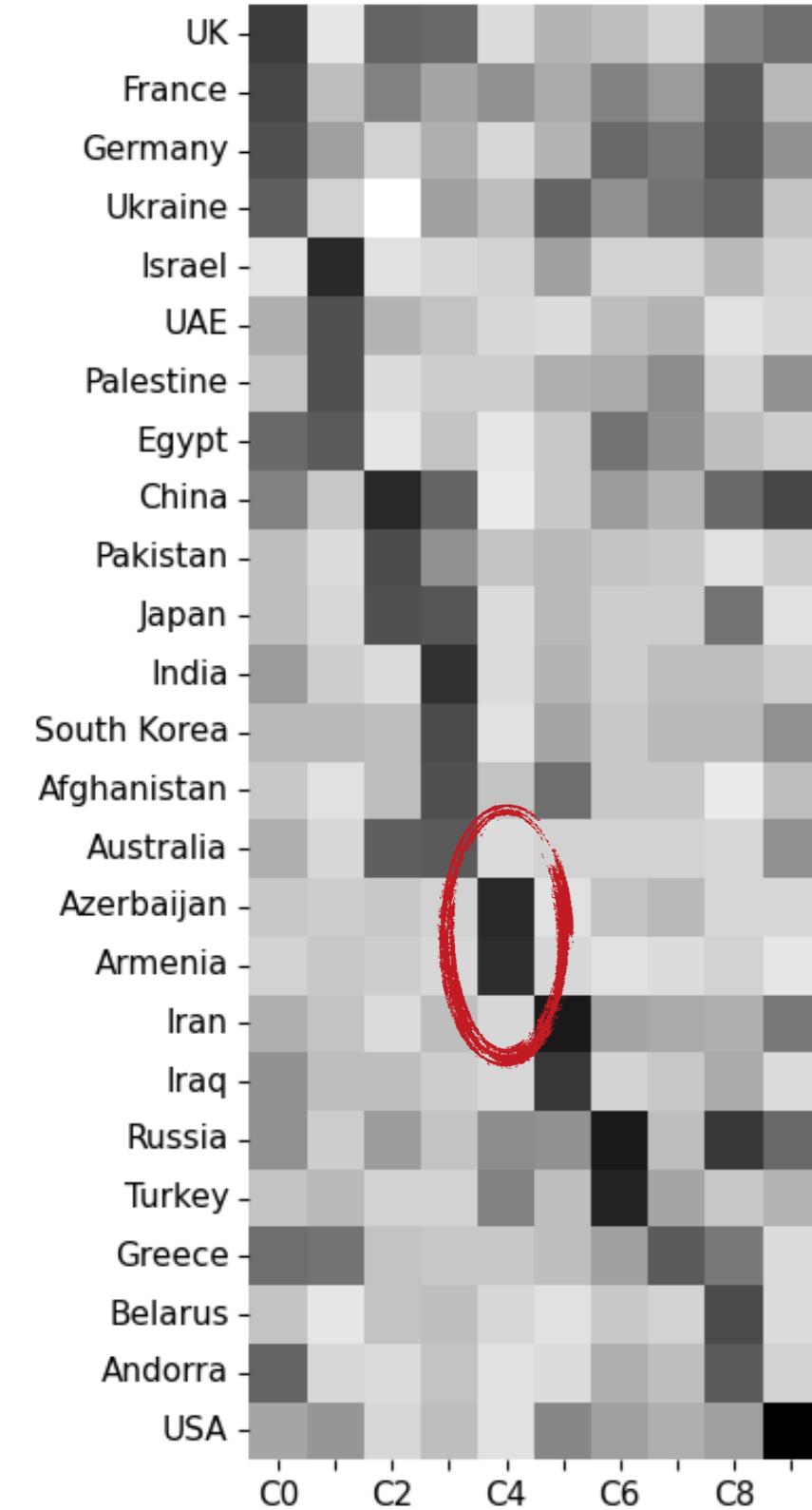
Results: ICEWS 2020 data

Country-Community Activity Ψ



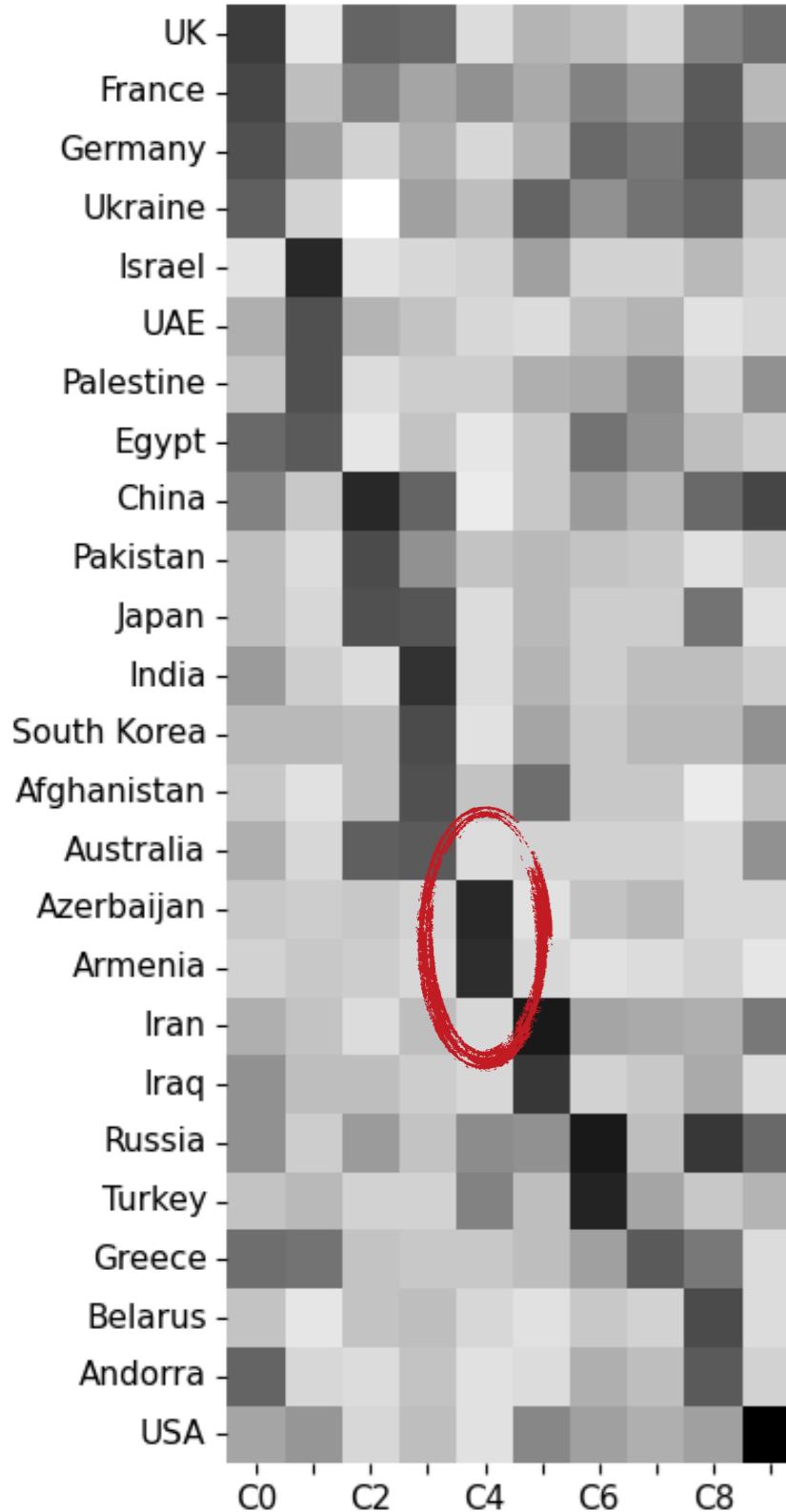
Results: ICEWS 2020 data

Country-Community Activity Ψ



Results: ICEWS 2020 data

Country-Community Activity Ψ



Second Nagorno-Karabakh War

Part of the Nagorno-Karabakh conflict



Date

27 September 2020 – 10 November 2020
(1 month and 2 weeks)^[30]

Belligerents

Azerbaijan

Artsakh

Armenia

Syrian

mercenaries^{[a][4][5][6][7][8]}

Armenian diaspora

$$\lambda_{c \rightarrow d}^{(t)}$$

$$C4 - C4$$

$$543210$$

2020-01

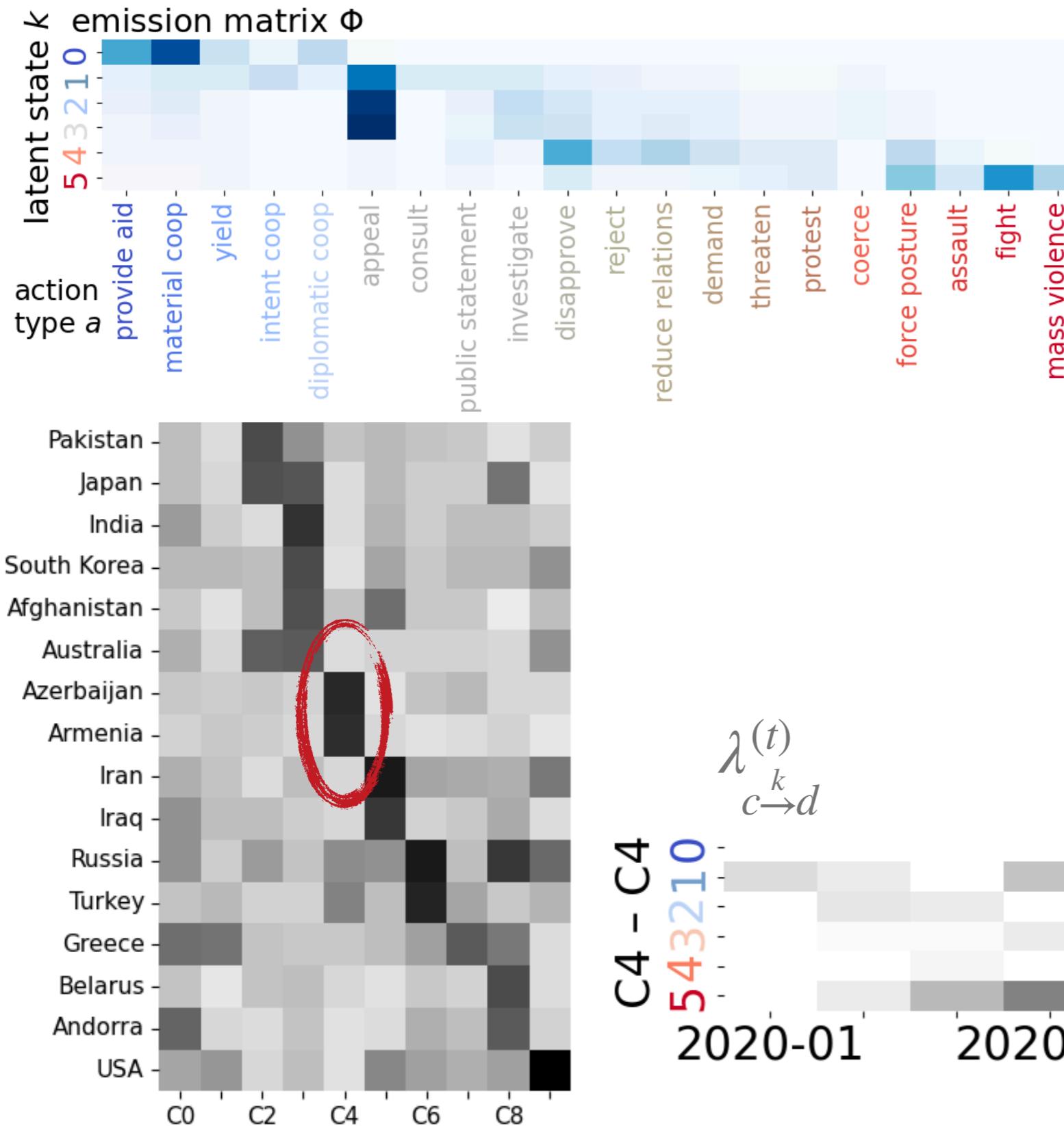
2020-04

2020-07

2020-10

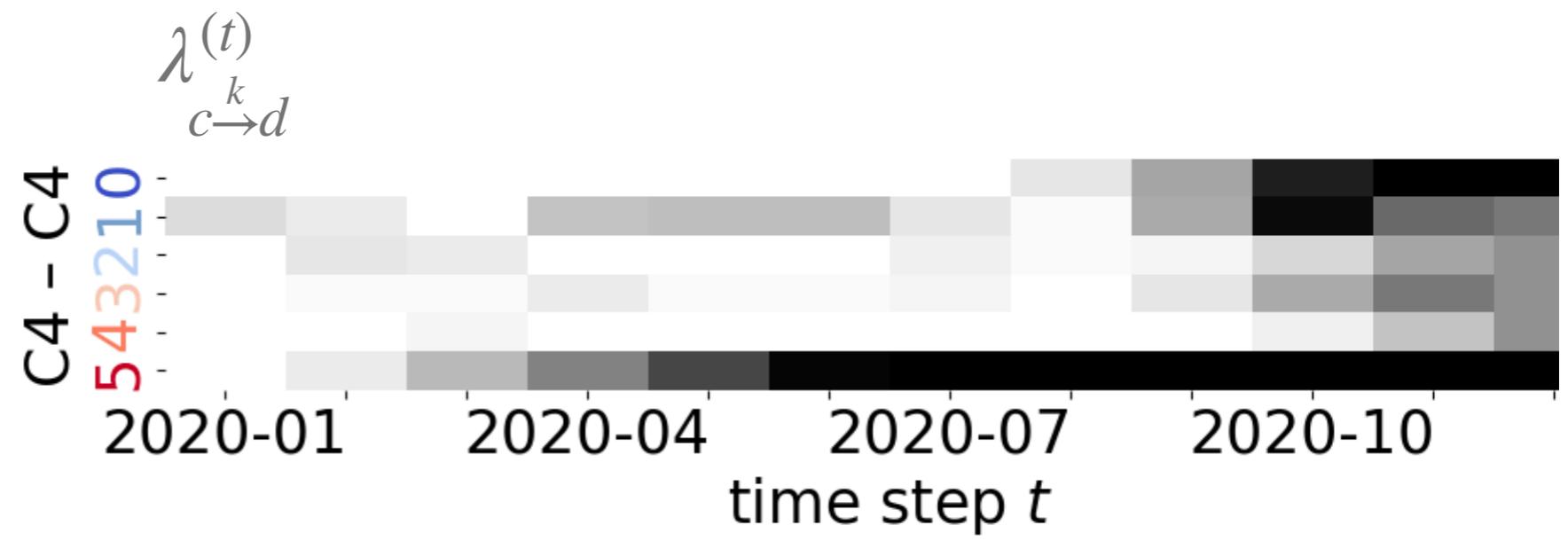
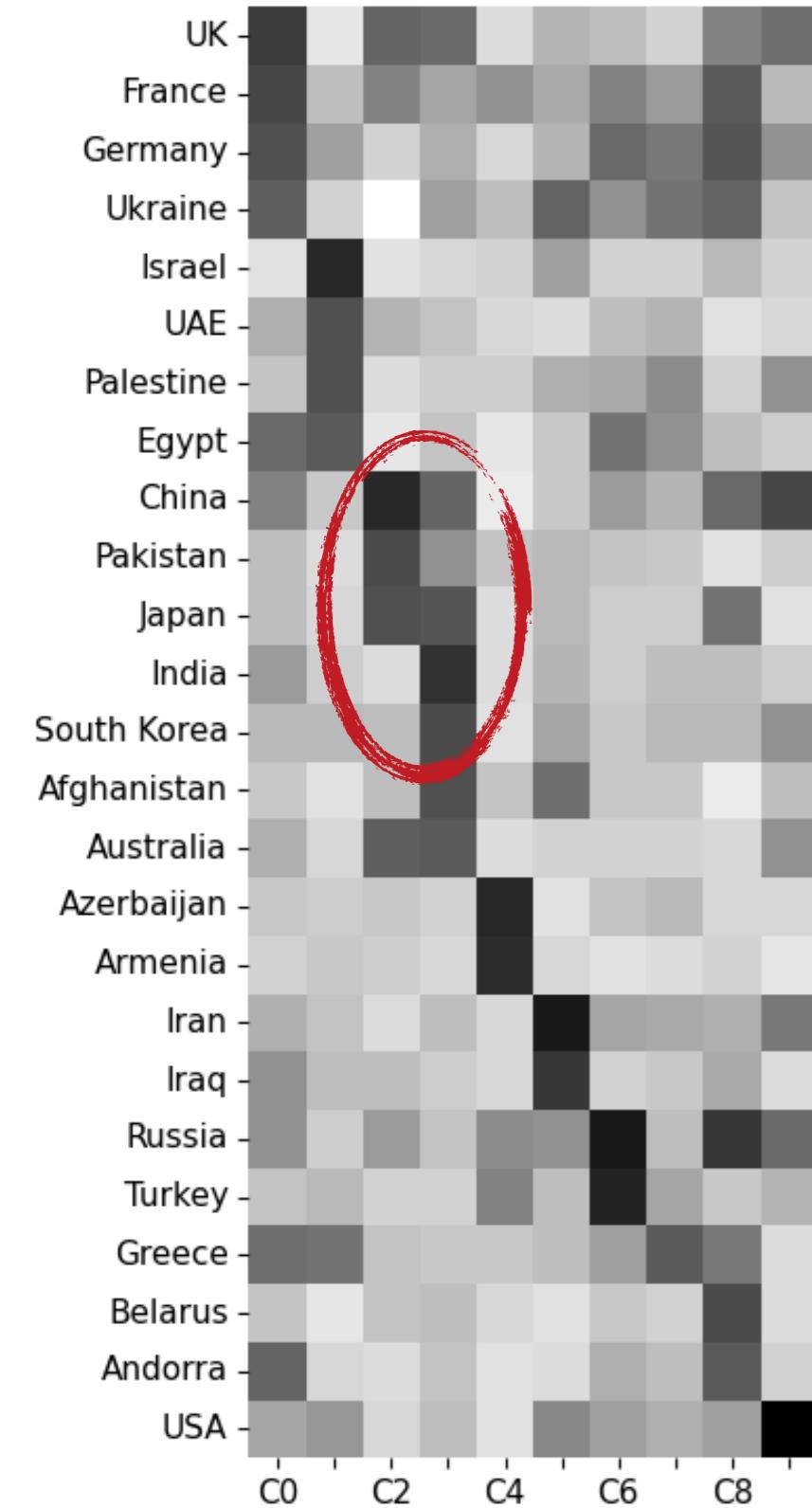
time step t

Results: ICEWS 2020 data



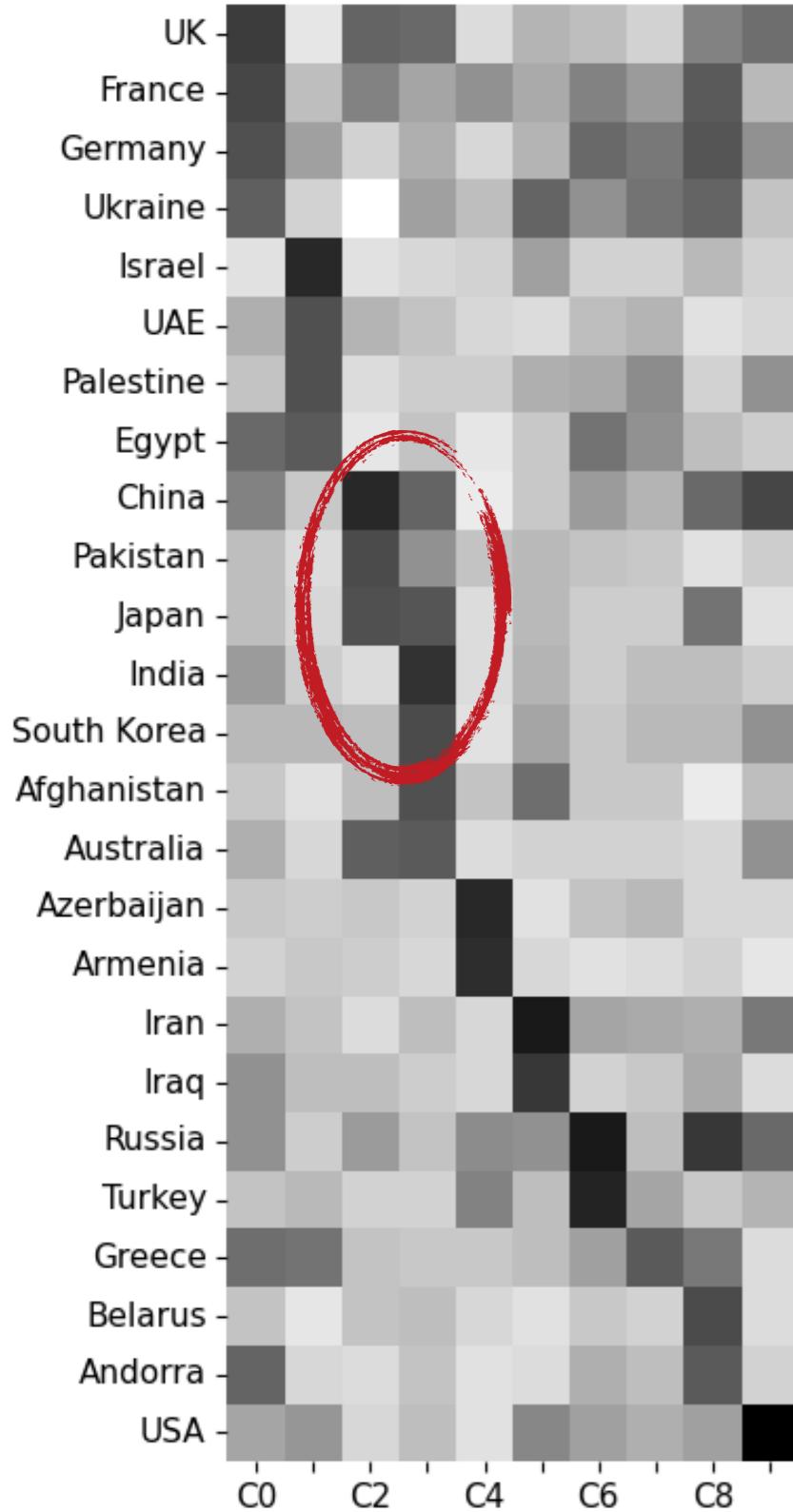
Results: ICEWS 2020 data

Country-Community Activity Ψ

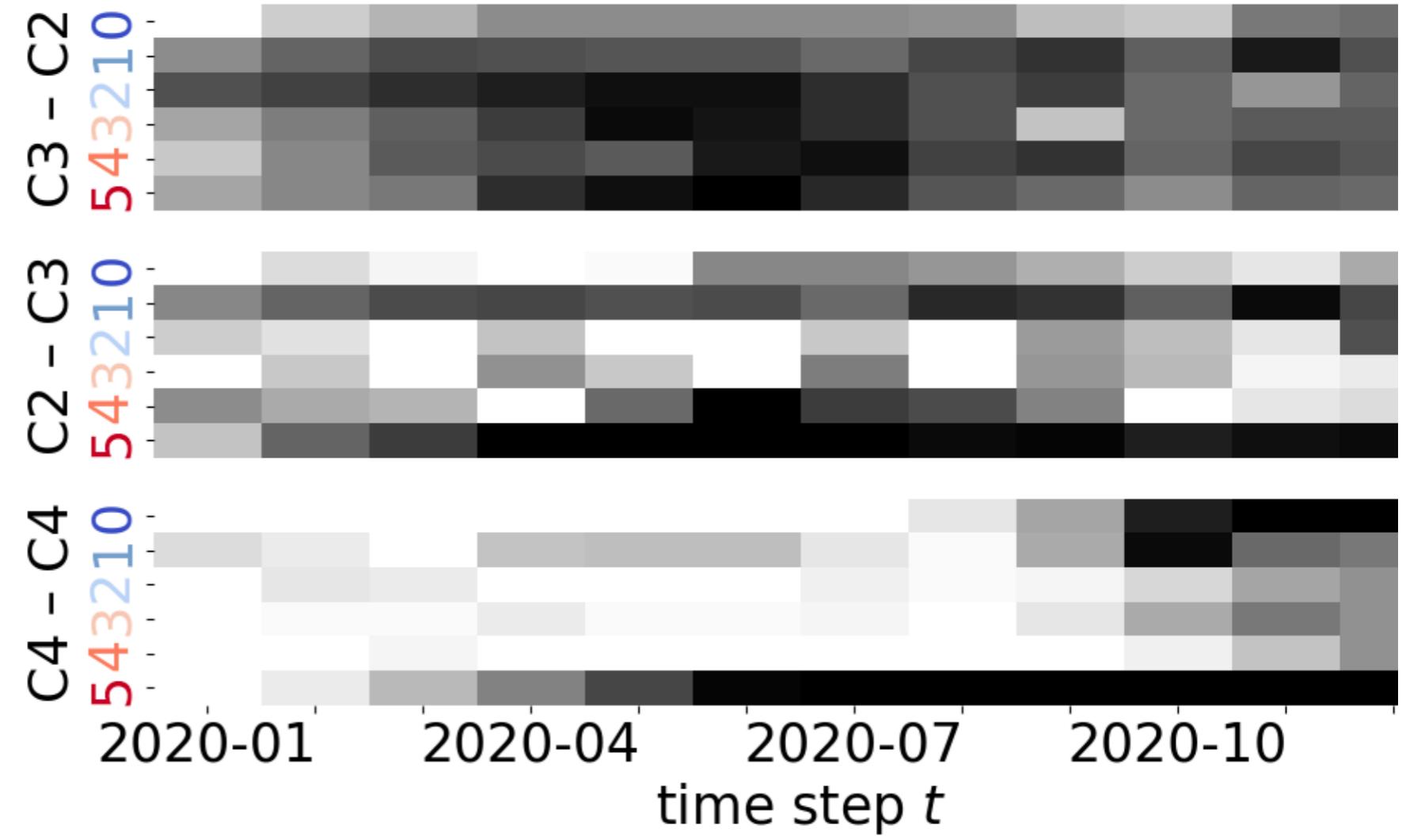


Results: ICEWS 2020 data

Country-Community Activity Ψ



$\lambda_{c \rightarrow d}^{(t)}$



Results: ICEWS

Country-Community Activity Ψ



2020–2021 China–India skirmishes

Part of the Sino-Indian border dispute



Date 5 May 2020 – 20 January 2021

(8 months, 2 weeks and 1 day)

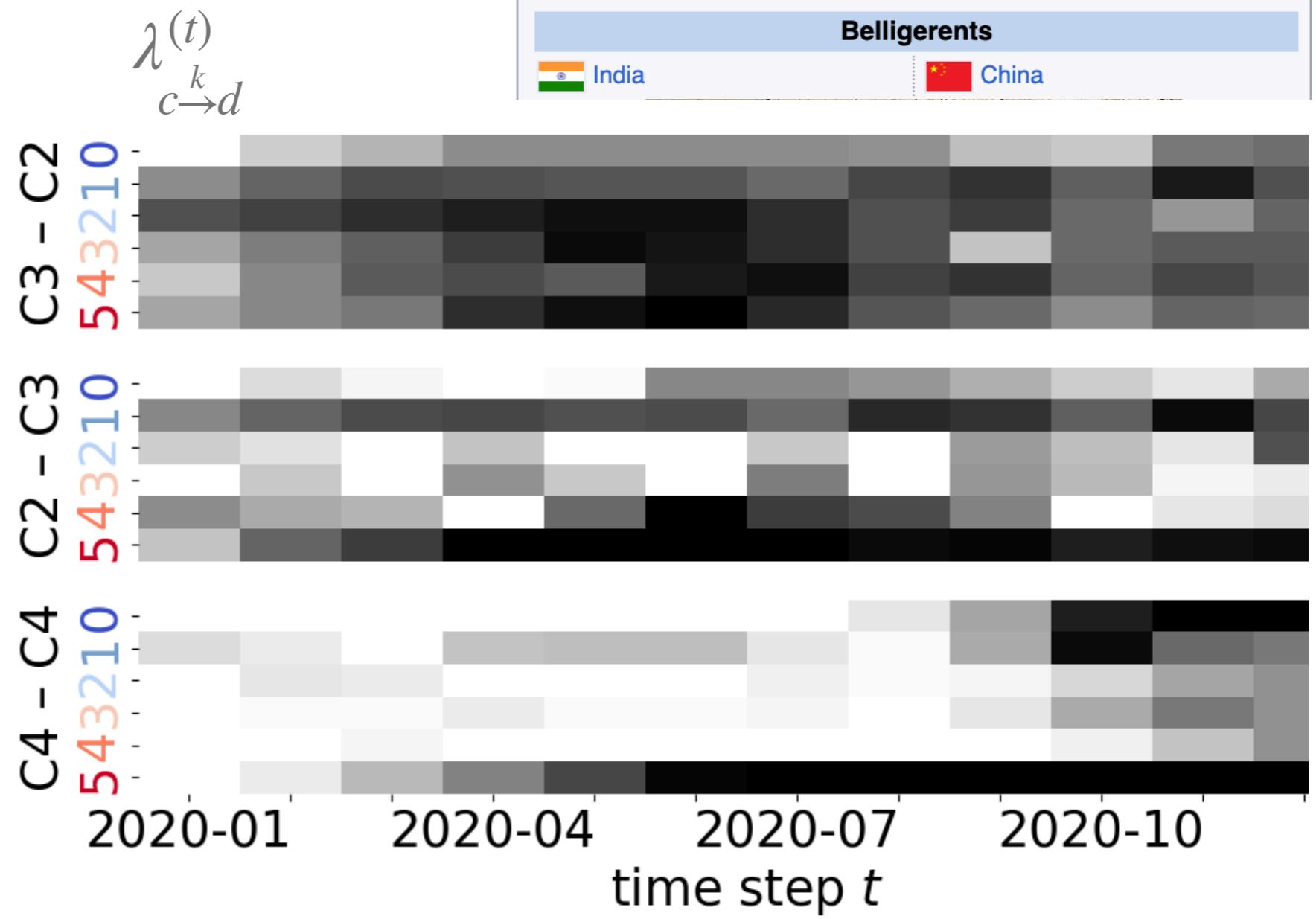
Location Line of Actual Control (LAC), Sino-Indian border

- Change in status quo of ground positions [1][2][3][4][5][6]
- Disengagement and de-escalation in progress [7][8][9]

Belligerents

India

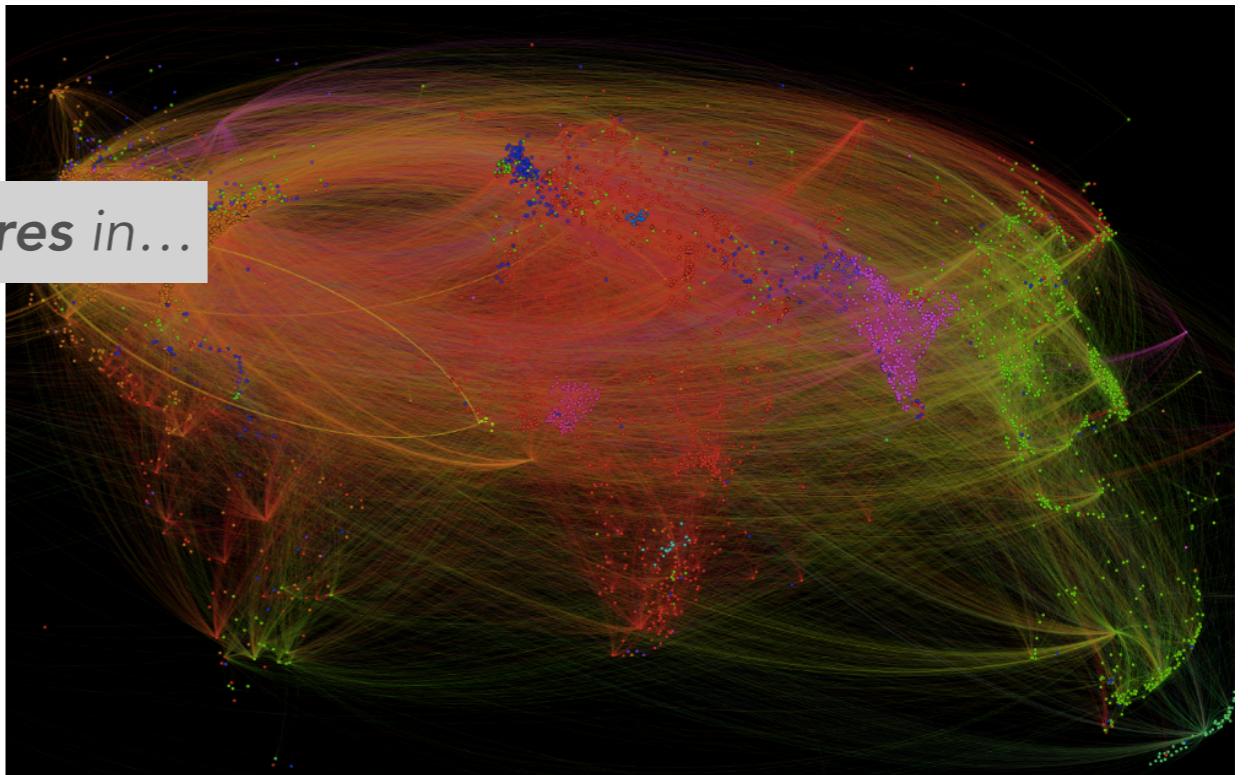
China



Summary and conclusion

Mission:

Models to **measure complex dependence structures** in...



Requires:

- **Blending** methodological frameworks:
 - Contingency table analysis
 - Tensor decomposition
 - Bayesian (ad)mixture / block modeling
- **New modeling motifs** for discrete and non-negative distributions
- **New techniques, theorems, tricks** for inference

...**high-dimensional discrete data**.

(sparse, bursty, overdispersed)

Data like this is **everywhere** e.g.,

- Genomics
- Neuroscience
- Demography

Broader data science goal:

Develop the **toolkit** for measuring scientifically-interesting complex structure in ^^

