

1. (20 points)

- a) Derive the vibration equation for cantilever beam in Fig. 1 (Ignore gravity). Assuming that only the first mode is considered, that is

$$y(x, t) = \phi(x)q(t) = \frac{3x^2l - x^3}{2l^3}q(t)$$

the parameters of the material are density: ρ , cross-section area A , Young's modulus: E , length: l , area moment: I_z and deflection of free-end: $q(t)$.

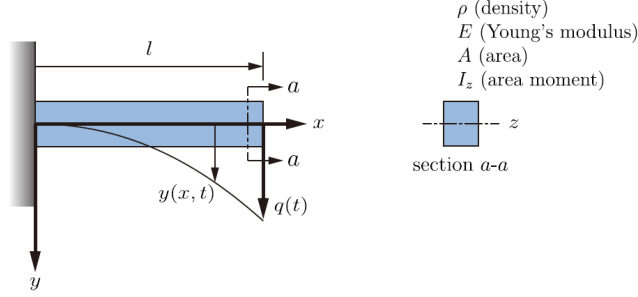


图 1: Figure for Exercise 1.

- b) Release the cantilever beam with +10 mm static deflection at the end. Determine the end-point deflection after 1s. ($\rho = 2(10^3)$ kg/m³, $E = 200(10^9)$ N/m², $A = 1.2(10^{-5})$ m², $I_z = 1.2(10^{-11})$ m⁴ and $l = 2$ m)

a)

$\phi(x)$: shape function $q(t)$: amplitude at free end

$$y(x, t) = \phi(x)q(t) = \frac{3x^2l - x^3}{2l^3}q(t)$$

$$\dot{y} = \frac{dy}{dt} = \phi(x) * \frac{dq}{dt} = \phi(x) * \dot{q}$$

$$y'' = \frac{d^2y}{dx^2} = \frac{d^2\phi}{dx^2} * q(t) = \phi'' * q(t)$$

$$T = \frac{1}{2} \int_0^l \rho A \dot{y}^2 dx = \frac{1}{2} \int_0^l \rho A (\phi(x) * \dot{q})^2 dx = \frac{1}{2} \dot{q}^2 \int_0^l \rho A \phi^2(x) dx = \frac{1}{2} m_e \dot{q}^2$$

$$\text{其中 } m_e = \int_0^l \rho A \phi^2(x) dx = \frac{33}{140} \rho A l$$

$$V = \frac{1}{2} \int_V \sigma_x \epsilon_x dV = \frac{1}{2} \int_0^l \int_A \frac{\sigma_x^2}{E} dA dx = \frac{1}{2} \int_0^l E \int_A y^2 dA (y'')^2 dx = \frac{1}{2} \int_0^l E I_z (y'')^2 dx$$

$$= \frac{1}{2} q^2(t) \int_0^l E I_z \phi''^2 dx = \frac{1}{2} k_e q^2(t)$$

$$k_e = \int_0^l E I_z (\phi'')^2 dx = \frac{3EI_z}{l^3}$$

$$\text{equation of motion: } \dot{E} = \dot{T} + \dot{V} = 0$$

$$m_e \dot{q} \ddot{q} + k_e q \dot{q} = 0$$

$$m_e \ddot{q} + k_e q = 0$$

$$\text{let } \omega_n = \sqrt{\frac{k_e}{m_e}} \quad \ddot{q} + \omega_n^2 q = 0$$

$$\text{Laplace Transform: } s^2 Q(s) - sq(0) - \dot{q}(0) + \omega_n^2 Q(s) = 0$$

$$(s^2 + \omega_n^2)Q(s) = sq(0) + \dot{q}(0)$$

$$Q(s) = \frac{sq(0) + \dot{q}(0)}{s^2 + \omega_n^2} = q(0) \frac{s}{s^2 + \omega_n^2} + \frac{\dot{q}(0)}{\omega_n} \frac{\omega_n}{s^2 + \omega_n^2}$$

$$q(t) = q(0) \cos(\omega_n t) + \frac{\dot{q}(0)}{\omega_n} \sin(\omega_n t)$$

$$\omega_n = \sqrt{\frac{k_e}{m_e}} = \sqrt{\frac{\frac{3EI_z}{l^3}}{\frac{33}{140}\rho A l}} = \sqrt{\frac{3 * 140}{33}} \frac{1}{l^2} \sqrt{\frac{EI_z}{\rho A}} = \frac{3.5675}{l^2} \sqrt{\frac{EI_z}{\rho A}}$$

$$y(x, t) = \phi(x)q(t) = \frac{3x^2l - x^3}{2l^3} \left(q(0) \cos(\omega_n t) + \frac{\dot{q}(0)}{\omega_n} \sin(\omega_n t) \right) \quad \omega_n = \frac{3.5675}{l^2} \sqrt{\frac{EI_z}{\rho A}}$$

b)

$$q(0) = 10^{-2} m \quad \dot{q}(0) = 0 \text{ m/s}$$

$$\omega_n = \frac{3.5675}{l^2} \sqrt{\frac{EI_z}{\rho A}} = 8.92$$

$$y(l, 1) = q(0) \cos(\omega_n) = -0.008752818770834643 \text{ m}$$

2. (20 points)

- a) Derive the equation of motion for free damped vibration in Fig. 2.
 b) Let the object fall freely at the original length of the spring, determine the position at $t = 2s$. (spring stiffness $k = 1 \text{ N/m}$, mass $m = 1 \text{ kg}$, damping $c = 1 \text{ N/ms}^{-1}$ and acceleration of gravity $g = 10 \text{ m/s}^{-2}$)

□

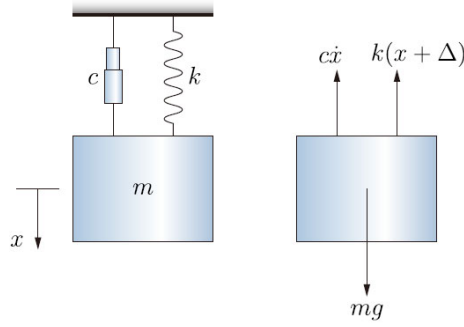


图 2: Figure for Exercise 2.

a)

$$mg - c\dot{x} - k(x + \Delta) = m\ddot{x}$$

$$\text{Initial condition: } x = 0 \quad \dot{x} = 0 \quad k\Delta = mg$$

$$\text{Equation of motion: } m\ddot{x} + c\dot{x} + kx = 0$$

$$\ddot{x} + \dot{x} + x = 0$$

$$\text{Laplace transform: } s^2L(x) - sx(0) - \dot{x}(0) + sL(x) - x(0) + L(x) = 0$$

$$(s^2 + s + 1)L(x) - (s + 1)x(0) - \dot{x}(0) = 0$$

$$L(x) = \frac{(s + 1)x(0) + \dot{x}(0)}{s^2 + s + 1} = \frac{\left(s + \frac{1}{2}\right)x(0) + \frac{1}{2}\dot{x}(0)}{\left(s + \frac{1}{2}\right)^2 + \frac{3}{4}}$$

$$= x(0) \frac{s + \frac{1}{2}}{\left(s + \frac{1}{2}\right)^2 + \frac{3}{4}} + \frac{\frac{1}{2}\dot{x}(0)}{\frac{\sqrt{3}}{2}} \frac{\frac{\sqrt{3}}{2}}{\left(s + \frac{1}{2}\right)^2 + \frac{3}{4}}$$

$$x(t) = x(0)e^{-\frac{1}{2}t} \cos\left(\frac{\sqrt{3}}{2}t\right) + \frac{x(0) + 2\dot{x}(0)}{\sqrt{3}}e^{-\frac{1}{2}t} \sin\left(\frac{\sqrt{3}}{2}t\right)$$

b) $x=0$ 时 弹簧拉力与重力恰好平衡，是物块的平衡点。

以弹簧原长状态作为初始条件，物块由静止释放，则：

$$x(0) = -\Delta = -\frac{mg}{k} = -10$$

$$\dot{x}(0) = 0$$

则运动方程变为

$$x(t) = -10e^{-\frac{1}{2}t} \cos\left(\frac{\sqrt{3}}{2}t\right) + \frac{-10}{\sqrt{3}}e^{-\frac{1}{2}t} \sin\left(\frac{\sqrt{3}}{2}t\right)$$

Position at $t=2s$:

$$x(2) = -10e^{-1} \cos(\sqrt{3}) + \frac{-10}{\sqrt{3}}e^{-1} \sin(\sqrt{3}) = -1.5057436514588765$$

3. (20 points)

- a) Derive the equation of motion for forced damped vibration in Fig. [3]. The force has the form of $F(t) = F_0 \cos \omega t$.
- b) Let the object start to move from the equilibrium point under force F , determine the position at $t = 2s$. (spring stiffness $k = 400(10^3)$ N/m, mass $m = 1200$ kg, damping

ratio $\zeta = 0.5$, maximum amplitude of the force $F_0 = 6(10^3)$ N, acceleration of gravity $g = 10 \text{ m/s}^{-2}$ and frequency of the force $\omega = 5.8 \text{ rad/s}$)

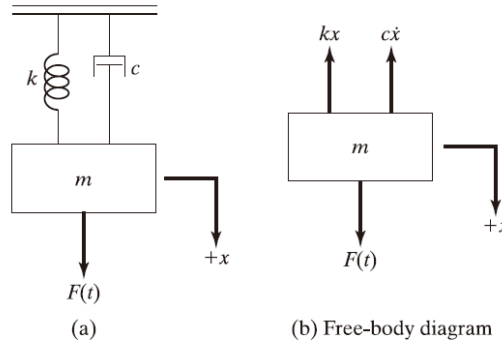


图 3: Figure for Exercise 3.

a)

$$F(t) - kx - c\dot{x} = m\ddot{x}$$

$$F_0 \cos \omega t = kx + c\dot{x} + m\ddot{x}$$

b)

initial condition: $x(0) = 0 \quad \dot{x}(0) = 0$

laplace transform:

$$F_0 \frac{s}{s^2 + \omega^2} = m(s^2 L(x) - sx(0) - \dot{x}(0)) + c(sL(x) - x(0)) + kL(x)$$

$$(ms^2 + cs + k)L(x) = F_0 \frac{s}{s^2 + \omega^2} + (ms + c)x(0) + m\dot{x}(0)$$

$$L(x) = \frac{F_0 \frac{s}{s^2 + \omega^2} + (ms + c)x(0) + m\dot{x}(0)}{ms^2 + cs + k} = \frac{\frac{F_0}{m} \frac{s}{s^2 + \omega^2} + \left(s + \frac{c}{m}\right)x(0) + \dot{x}(0)}{s^2 + \frac{c}{m}s + \frac{k}{m}}$$

$$= \frac{\frac{F_0}{m} \frac{s}{s^2 + \omega^2} + \left(s + \frac{c}{m}\right)x(0) + \dot{x}(0)}{\left(s + \frac{c}{2m}\right)^2 + \frac{k}{m} - \frac{c^2}{4m^2}}$$

$$= \frac{\frac{F_0}{m} \frac{s}{s^2 + \omega^2}}{\left(s + \frac{c}{2m}\right)^2 + \frac{k}{m} - \frac{c^2}{4m^2}} + \frac{\left(s + \frac{c}{2m}\right)x(0)}{\left(s + \frac{c}{2m}\right)^2 + \frac{k}{m} - \frac{c^2}{4m^2}} + \frac{\dot{x}(0) + \frac{c}{2m}x(0)}{\left(s + \frac{c}{2m}\right)^2 + \frac{k}{m} - \frac{c^2}{4m^2}}$$

$$= \frac{\frac{F_0}{m} \frac{s}{s^2 + \omega^2}}{\left(s + \frac{c}{2m}\right)^2 + \frac{k}{m} - \frac{c^2}{4m^2}} + x(0) \frac{\left(s + \frac{c}{2m}\right)}{\left(s + \frac{c}{2m}\right)^2 + \frac{k}{m} - \frac{c^2}{4m^2}}$$

$$+ \frac{\dot{x}(0) + \frac{c}{2m}x(0)}{\sqrt{\frac{k}{m} - \frac{c^2}{4m^2}}} \frac{\sqrt{\frac{k}{m} - \frac{c^2}{4m^2}}}{\left(s + \frac{c}{2m}\right)^2 + \frac{k}{m} - \frac{c^2}{4m^2}}$$

$$\omega_n = \sqrt{\frac{k}{m}} = \frac{10\sqrt{30}}{3} \quad \text{damping ratio } \zeta = \frac{c}{2\sqrt{km}} \quad \zeta\omega_n = \frac{c}{2m}$$

代入初始条件：

$$\begin{aligned} L(x) &= \frac{\frac{F_0}{m} \frac{s}{s^2 + \omega^2}}{\left(s + \frac{c}{2m}\right)^2 + \frac{k}{m} - \frac{c^2}{4m^2}} = \\ &= \frac{F_0}{m} \frac{\frac{s}{s^2 + \omega^2}}{(s + \zeta\omega_n)^2 + (1 - \zeta^2)\omega_n^2} = \frac{6 * 10^3}{1200} \frac{\frac{s}{s^2 + \omega^2}}{\left(s + 0.5 * \sqrt{4 * \frac{10^5}{1200}}\right)^2 + 0.75 * 4 * \frac{10^5}{1200}} \\ &= 5 \frac{s}{(s^2 + \omega^2)(s^2 + 2\zeta\omega_n s + \omega_n^2)} = 5 \frac{s}{(s^2 + \omega^2)(s^2 + \omega_n s + \omega_n^2)} \\ &= 5 \left(\frac{As + B}{s^2 + \omega^2} + \frac{Cs + D}{s^2 + \omega_n s + \omega_n^2} \right) \end{aligned}$$

其中

$$\begin{aligned} A &= \frac{\omega_n^2 - \omega^2}{(2\zeta\omega_n)^2\omega^2 + (\omega_n^2 - \omega^2)^2} & B &= \frac{2\zeta\omega_n\omega^2}{(2\zeta\omega_n)^2\omega^2 + (\omega_n^2 - \omega^2)^2} \\ C &= -\frac{\omega_n^2 - \omega^2}{(2\zeta\omega_n)^2\omega^2 + (\omega_n^2 - \omega^2)^2} & D &= -\frac{2\zeta\omega_n^3}{(2\zeta\omega_n)^2\omega^2 + (\omega_n^2 - \omega^2)^2} \\ A &= \frac{\frac{10\sqrt{30}^2}{3} - 5.8^2}{\frac{10\sqrt{30}^2}{3} * 5.8^2 + \left(\frac{10\sqrt{30}^2}{3} - 5.8^2\right)^2} = \frac{\frac{22477}{75}}{\frac{33640}{3} + \frac{22477^2}{75}} = 3 * 10^{-3} \\ B &= \frac{\frac{10\sqrt{30}}{3} * 5.8^2}{\frac{33640}{3} + \frac{22477^2}{75}} = 6.08 * 10^{-3} \\ C &= -3 * 10^{-3} \\ D &= \frac{\frac{10\sqrt{30}^3}{3}}{\frac{33640}{3} + \frac{22477^2}{75}} = 9.02 * 10^{-4} \end{aligned}$$

$$\begin{aligned} L(x) &= 5 \left(\frac{As + B}{s^2 + \omega^2} + \frac{Cs + D}{s^2 + \omega_n s + \omega_n^2} \right) = 5 \left(A \frac{s}{s^2 + \omega^2} + \frac{B}{\omega} \frac{\omega}{s^2 + \omega^2} + \frac{Cs + D}{\left(s + \frac{1}{2}\omega_n\right)^2 + \frac{3}{4}\omega_n^2} \right) \\ &= 5 \left(A \frac{s}{s^2 + \omega^2} + \frac{B}{\omega} \frac{\omega}{s^2 + \omega^2} + C \frac{\left(s + \frac{1}{2}\omega_n\right)}{\left(s + \frac{1}{2}\omega_n\right)^2 + \frac{3}{4}\omega_n^2} \right. \\ &\quad \left. - \frac{D + \frac{1}{2}C\omega_n}{\frac{\sqrt{3}}{2}\omega_n} \frac{\frac{\sqrt{3}}{2}\omega_n}{\left(s + \frac{1}{2}\omega_n\right)^2 + \frac{3}{4}\omega_n^2} \right) \end{aligned}$$

$$x(t) = 5 \left(A \cos(\omega t) + \frac{B}{\omega} \sin(\omega t) + C e^{-\frac{1}{2}\omega_n t} \cos\left(\frac{\sqrt{3}}{2}\omega_n t\right) - \frac{D + \frac{1}{2}C\omega_n}{\frac{\sqrt{3}}{2}\omega_n} e^{-\frac{1}{2}\omega_n t} \sin\left(\frac{\sqrt{3}}{2}\omega_n t\right) \right)$$

$$x(2) = 0.004116661958302297$$

4. (20 points)

- a) Derive the equation of motion for forced damped vibration in Fig. 4. The force is expressed as $F(t)$ in time domain. Set the position $x(t)$ as output and the force $F(t)$ as input, determine $X(s)/F(s)$ in s-domain.

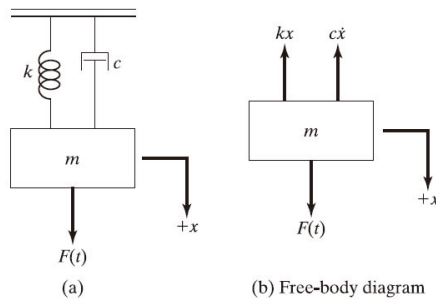


图 4: Figure for Exercise 4.

- b) In fact we call $X(s)/F(s)$ the **Transfer Function** when all initial conditions are zero ($x(0) = 0, \dot{x}(0) = 0, \ddot{x}(0) = 0, \dots$). What kind of input can make the output has the same expression as Transfer Function?

a)

$$F(t) - kx - c\dot{x} = m\ddot{x}$$

$$F(t) = kx + c\dot{x} + m\ddot{x}$$

laplace transform:

$$F(s) = m(s^2 X(s) - sx(0) - \dot{x}(0)) + c(sX(s) - x(0)) + kX(s)$$

$$F(s) = (ms^2 + cs + k)X(s) - (ms + 1)x(0) - m\dot{x}(0)$$

$$1 = (ms^2 + cs + k) \frac{X(s)}{F(s)} - \frac{(ms + 1)x(0)}{F(s)} - \frac{m\dot{x}(0)}{F(s)}$$

$$\frac{X(s)}{F(s)} = \frac{1}{(ms^2 + cs + k)} + \frac{(ms + 1)x(0)}{(ms^2 + cs + k)F(s)} + \frac{m\dot{x}(0)}{(ms^2 + cs + k)F(s)}$$

b)

transfer function: initial condition all equal to 0

$$TransFunc = \frac{X(s)}{F(s)} = \frac{1}{(ms^2 + cs + k)}$$

When input $F(s) = 1$, output $X(s) = TransFunc = \frac{1}{(ms^2 + cs + k)}$

5. (20 points) Fig. 5 shows a simple model of a motor vehicle that can vibrate in the vertical direction while traveling over a rough road. The vehicle has a mass of 1200 kg. The suspension system has a spring constant of 400 kN/m and a damping ratio of $\zeta = 0.5$. If the vehicle speed is 20 km/h, determine the displacement amplitude of the vehicle. The road surface varies sinusoidally with an amplitude of $Y = 0.05$ m and a wavelength of 6 m.

Hint: the equation of motion is

$$m\ddot{x} + c(\dot{x} - \dot{y}) + k(x - y) = 0$$

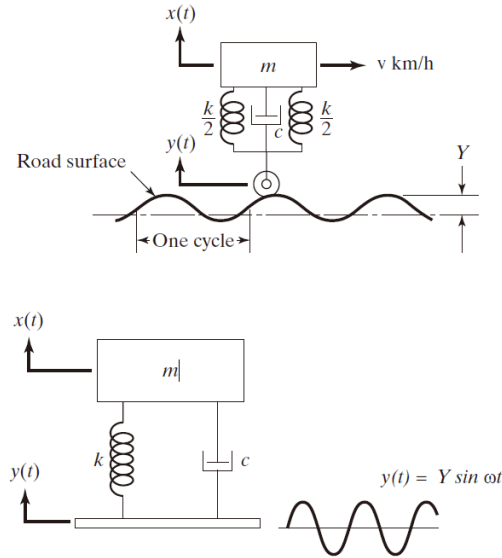


图 5: Figure for Exercise 5.

$$\frac{20km}{h} = \frac{20000}{3600} = \frac{50}{9} m/s$$

$$T = \frac{\lambda}{v} = \frac{6}{\frac{50}{9}} = 1.08s$$

$$\omega = \frac{2\pi}{T} = \frac{2\pi}{1.08}$$

$$y(t) = 0.05 \sin\left(\frac{2\pi}{1.08} t\right)$$

$$Y(s) = Y \frac{s}{s^2 + \omega^2}$$

$$m\ddot{x} + c(\dot{x} - \dot{y}) + k(x - y) = 0$$

$$m(s^2 X(s) - sx_0 - \dot{x}_0) + c(sX(s) - x_0 - sY(s) + y(0)) + k(X(s) - Y(s)) = 0$$

$$(ms^2 + cs + k)X(s) - (ms + c)x_0 - m\dot{x}_0 - (cs + k)Y(s) = 0$$

$$\begin{aligned}
X(s) &= \frac{\left(s + \frac{c}{m}\right)x_0 + \dot{x}_0 + \left(\frac{c}{m}s + \frac{k}{m}\right)Y(s)}{\left(s^2 + \frac{c}{m}s + \frac{k}{m}\right)} = \frac{(s + 2\zeta\omega_n)x_0 + \dot{x}_0 + (2\zeta\omega_n s + \omega_n^2)Y(s)}{s^2 + 2\zeta\omega_n s + \omega_n^2} \\
&= \frac{(s + 2\zeta\omega_n)x_0 + \dot{x}_0}{s^2 + 2\zeta\omega_n s + \omega_n^2} + \frac{Y(2\zeta\omega_n s + \omega_n^2)}{s^2 + 2\zeta\omega_n s + \omega_n^2} * \frac{s}{s^2 + \omega^2} \\
&= \frac{(s + 2\zeta\omega_n)x_0 + \dot{x}_0}{s^2 + 2\zeta\omega_n s + \omega_n^2} + \left(\frac{as + b}{s^2 + 2\zeta\omega_n s + \omega_n^2} + \frac{cs + d}{s^2 + \omega^2}\right) \\
&\quad \left(\omega_n = \sqrt{\frac{k}{m}} \quad \zeta = \frac{c}{2\sqrt{mk}}\right)
\end{aligned}$$

$$(as + b)(s^2 + \omega^2) + (cs + d)(s^2 + 2\zeta\omega_n s + \omega_n^2) = Y(2\zeta\omega_n s^2 + \omega_n^2 s)$$

$$[a + c + 2c\zeta\omega_n \quad b + d + 2d\zeta\omega_n \quad a\omega^2 + c\omega_n^2 \quad b\omega^2 + d\omega_n^2] \begin{bmatrix} s^3 \\ s^2 \\ s \\ 1 \end{bmatrix}$$

$$= [0 \quad 2Y\zeta\omega_n \quad Y\omega_n^2 \quad 0] \begin{bmatrix} s^3 \\ s^2 \\ s \\ 1 \end{bmatrix}$$

$$[a + c + 2c\zeta\omega_n \quad b + d + 2d\zeta\omega_n \quad a\omega^2 + c\omega_n^2 \quad b\omega^2 + d\omega_n^2] = [0 \quad 2Y\zeta\omega_n \quad Y\omega_n^2 \quad 0]$$

$$\begin{bmatrix} 1 & 0 & 1 + 2\zeta\omega_n & 0 \\ 0 & 1 & 0 & 1 + 2\zeta\omega_n \\ \omega^2 & 0 & \omega_n^2 & 0 \\ 0 & \omega^2 & 0 & \omega_n^2 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} 0 \\ 2Y\zeta\omega_n \\ Y\omega_n^2 \\ 0 \end{bmatrix}$$

$$\text{solution: } \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} \frac{Y\omega_n^2(1 + 2\zeta\omega_n)}{-\omega_n^2 + \omega^2(1 + 2\zeta\omega_n)} \\ -\frac{2Y\zeta\omega_n^3}{-\omega_n^2 + \omega^2(1 + 2\zeta\omega_n)} \\ \frac{Y\omega_n^2}{\omega_n^2 - \omega^2(1 + 2\zeta\omega_n)} \\ -\frac{2Y\zeta\omega^2\omega_n}{-\omega_n^2 + \omega^2(1 + 2\zeta\omega_n)} \end{bmatrix}$$

steady - state solution

$$X_s(s) = \frac{cs + d}{s^2 + \omega^2} = c \frac{s}{s^2 + \omega^2} + \frac{d}{\omega} \frac{\omega}{s^2 + \omega^2}$$

$$x_s(t) = c * \cos(\omega t) + \frac{d}{\omega} \sin(\omega t)$$

$$\text{Amplitude} = \sqrt{c^2 + \left(\frac{d}{\omega}\right)^2} = \sqrt{\frac{Y^2\omega_n^2(4\zeta^2\omega^2 + \omega_n^2)}{(\omega_n^2 - \omega^2(1 + 2\zeta\omega_n))^2}}$$

$$Y = 0.05 \quad \omega = \frac{2\pi}{1.08} \quad \omega_n = \sqrt{\frac{400000}{1200}} = \frac{10\sqrt{30}}{3} \quad \zeta = 0.5$$

$$\text{Amplitude} = 0.05492790607337223$$