

## Zimin Xia

Nationality: Chinese

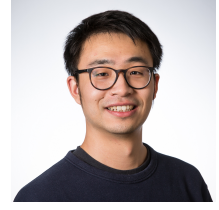
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### RESEARCH INTERESTS

**Visual Localization, Ground-to-Aerial Image Matching, 3D Computer Vision, Representation Learning, Self-Supervised Learning, Environment Perception for Autonomous Driving**

### EXPERIENCE

**EPFL**, Switzerland

Since Mar. 2024

**PostDoc Researcher**, topic: *Visual Localization and Mapping*  
Advisor: Prof. Alexandre Alahi

**Delft University of Technology**, The Netherlands

Oct. 2019 - Mar. 2024

**Ph.D. student**, topic: *Efficient Deep Learning for Robot Localization*

Supervisors: Prof. Julian F. P. Kooij, Prof. Darius M. Gavrila

Collaborate with TomTom, Amsterdam, The Netherlands

Dutch Research Council funded project: Efficient Deep Learning

**University of Stuttgart**, Germany

Oct. 2016 - Jul. 2019

**Master of Science**, Geomatics Engineering

Master Thesis at Carl Zeiss AG, Germany:

*Stereo Reconstruction of Human Faces with Deep Learning*

**Wuhan University**, China

Sep. 2012 - Jun. 2016

**Bachelor of Science**, Geodesy and Geomatics Engineering

### SELECTED PUBLICATIONS

**Convolutional Cross-View Pose Estimation**

Zimin Xia, Olaf Booij, Julian F. P. Kooij

IEEE Transactions on Pattern Analysis and Machine Intelligence (T-PAMI), 2023

Linked to: Paper, Code

**SliceMatch: Geometry-guided Aggregation for Cross-View Pose Estimation**

Ted Lentsch\*, Zimin Xia\*, Holger Caesar, Julian F. P. Kooij

\*: Equal contribution

Conference on Computer Vision and Pattern Recognition (CVPR), 2023

Linked to: Paper, Code, Video

**Visual Cross-View Metric Localization with Dense Uncertainty Estimates**

Zimin Xia, Olaf Booij, Marco Manfredi, Julian F. P. Kooij

European Conference on Computer Vision (ECCV), 2022

Linked to: Paper, Code, Video

**Cross-View Matching for Vehicle Localization by Learning Geographically Local Representations**

Zimin Xia, Olaf Booij, Marco Manfredi, Julian F. P. Kooij

IEEE Robotics and Automation Letters (IEEE RA-L), 2021

Linked to: Paper, Code, Video

**Geographically Local Representation Learning with a Spatial Prior for Visual Localization**

Zimin Xia, Olaf Booij, Marco Manfredi, Julian F. P. Kooij

European Conference on Computer Vision (ECCV), 2020, Workshop on Map-based Localization for Autonomous Driving, Oral Presentation  
Linked to: Paper, Code, Video

## ACADEMIC ACTIVITIES

**Attended International Computer Vision Summer School (ICVSS) 2022**

**Reviewer for T-PAMI, CVPR, ECCV, T-RO, RA-L, ICRA, IV**

## TEACHING ASSISTANT

<b>Machine Learning for Robotics</b>	2020 - 2023
<b>3D Robot Vision</b>	2020 - 2021
<b>Intelligent Vehicles</b>	2019 - 2020

## MSC THESIS SUPERVISION

<b>Cross-View Camera Pose Estimation By Matching Local Features in 3D</b> <i>Sviatoslav Voloshyn</i>	Oct. 2022 - Aug. 2023
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<b>Improving Cross-View Matching with Self-Supervised Learning</b> <i>Jianfeng Cui</i>	Jan. 2022 - Jan. 2023
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<b>SliceNet: Street-to-Satellite Image Metric Localization using Local Feature Matching</b> <i>Ted de Vries Lentsch</i>	Nov. 2021 - Oct. 2022
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## LANGUAGE

**English:** Professional proficiency  
**German:** Elementary proficiency  
**Chinese:** Native

## HOBBIES

In my free time, I enjoy reading and doing sports. I am passionate about playing basketball and swimming. During my high school years in China, I was a national second-grade swimmer.