

## Zimin Xia

Nationality: Chinese  
Date of birth: 1994.02.21  
Email: z.xia@tudelft.nl  
Address: Delft, the Netherlands



Google Scholar

- 
- EDUCATION**
- Delft University of Technology**, the Netherlands    Oct. 2019 - (EXP) Jan. 2024  
*Ph.D. student*, topic: Efficient Deep Learning for Localization and Mapping  
Supervisors: Dr. Julian F. P. Kooij, Prof. Darius M. Gavrilă
- University of Stuttgart**, Germany    Oct. 2016 - Jul. 2019  
*Master of Science*, Geomatics Engineering (Grade: 1.3)
- Wuhan University**, China    Sep. 2012 - Jun. 2016  
*Bachelor of Science*, Geodesy and Geomatics Engineering
- PROJECTS**
- Ph.D. Project: Efficient Deep Learning for Localization and Mapping**  
Intelligent Vehicles Group, Cognitive Robotics Department, TU Delft  
TomTom, Amsterdam, the Netherlands    Oct. 2019 - present
- Visual localization for autonomous driving
  - Ground-to-aerial image matching
  - Map representation learning
- Master Thesis: Stereo Reconstruction of Human Faces with Deep Learning**  
Corporate Research & Technology, Carl Zeiss AG, Germany    Oct. 2018 - Jun. 2019
- Deep learning-based disparity estimation
- AI Music Project**  
Ping An Technology, Shenzhen, China    Mar. 2018 - Jul. 2018
- RNN/LSTM for music generation
- Integrated Fieldwork**  
University of Stuttgart    Apr. 2017 - Aug. 2017
- Multi-sensor landfill site monitoring:  
UAV photogrammetry, Leveling, GNSS positioning, Tachymeter surveying
- SELECTED PUBLICATIONS**
- Convolutional Cross-View Pose Estimation**  
Zimin Xia, Olaf Booij, Julian F. P. Kooij  
(Under revision at IEEE Transactions on Pattern Analysis and Machine Intelligence)
- SliceMatch: Geometry-guided Aggregation for Cross-View Pose Estimation**  
Ted Lentsch\*, Zimin Xia\*, Holger Caesar, Julian F. P. Kooij  
\*: Equal contribution  
Conference on Computer Vision and Pattern Recognition (CVPR), 2023
- Visual Cross-View Metric Localization with Dense Uncertainty Estimates**  
Zimin Xia, Olaf Booij, Marco Manfredi, Julian FP Kooij  
European Conference on Computer Vision (ECCV), 2022
- Cross-View Matching for Vehicle Localization by Learning Geographically Local Representations**  
Zimin Xia, Olaf Booij, Marco Manfredi, Julian FP Kooij  
IEEE Robotics and Automation Letters (IEEE RA-L), 2021
- Geographically Local Representation Learning with a Spatial Prior for Visual Localization**

**Zimin Xia**, Olaf Booij, Marco Manfredi, Julian FP Kooij  
European Conference on Computer Vision, 2020, Workshop on Map-based Localization for Autonomous Driving

<b>TEACHING ASSISTANT</b>	<b>Machine Learning for Robotics</b>	Sep. 2023 - Nov. 2023
	<b>Machine Learning for Robotics</b>	Sep. 2022 - Nov. 2022
	<b>Machine Learning for Robotics</b>	Sep. 2021 - Nov. 2021
	<b>Machine Learning for Robotics</b>	Sep. 2020 - Nov. 2020
	<b>3D Robot Vision</b>	Feb. 2020 - Apr. 2020
	<b>Intelligent Vehicles</b>	Nov. 2019 - Jan. 2020

<b>MSC THESIS SUPERVISION</b>	<b>Cross-View Camera Pose Estimation By Matching Local Features in 3D</b>
-------------------------------	---

Oct. 2022 - Aug. 2023

**Improving Cross-View Matching with Self-Supervised Learning**

Jan. 2022 - Jan. 2023

**SliceNet: Street-to-Satellite Image Metric Localization using Local Feature Matching**

Nov. 2021 - Oct. 2022

<b>RESEARCH INTERESTS</b>	<b>Visual Localization, Ground-to-Aerial Image Matching, 3D Computer Vision, Representation Learning, Self-Supervised Learning</b>
---------------------------	--

<b>LANGUAGE</b>	<b>English:</b> Professional proficiency
	<b>German:</b> Elementary proficiency
	<b>Chinese:</b> Native

<b>HOBBIES</b>	Swimming, Playing basketball, Reading
----------------	---------------------------------------