Exercise 1-Forecasting Variance

(A) The code of our parameter estimate function is as follow:

```
function [beta] = OLS(x,y)

y is the number of independent variables(step number)

y is the denpendent variable vector: J*1 t—series data

xx is the independent variable matrix: J*n t—series data * n variables

beta is the vestor of parameter: (n+1)*1

x(:,end+1)=1; % adding interception into regression

beta=x'*y\(x'*x);

beta=(x'*x)\(x'*y);

end
```

The input of this function is independent variable data matrix $X = [X1, X2, ..., X_n]$ and the dependent variable vector Y. The output is a vector of parameter $\hat{\beta} \equiv [\beta_1, \beta_2, ..., \beta_n, \beta_0]$. Here β_0 is the parameter of interception.

(B) The function input is [X, Y, J, T, step], where $X = [X1, X2, X3, ..., X_n]$ and Y is the dependent variable vector, T is the latest data we used for estimating, J is the row number of independent variable data and step is the order of model.

If we set estimate window length is 1000, then J=999, $T=1000, 1001, \ldots, T_{All}-1$). For AR1 and HAR1 model, we have step=1.

Here is the table of forecast value and MSE from different models.

Table 1. Wodel Polecast value and MBE (with W=1000)							
Stock	Real $RV_{T_{2769}}$	AR1 HAR1		Non-change			
PG	4.2813×10^{-5}	4.7814×10^{-5}	4.2813×10^{-5}	1.3228×10^{-5}			
DIS	3.1136×10^{-5}	5.6526×10^{-5}	6.7252×10^{-5}	2.9385×10^{-5}			
		MSE_{AR1}	MSE_{HAR1}	MSE_{NC}			
PG		1.2432×10^{-8}	1.1566×10^{-8}	1.6612×10^{-8}			
DIS		1.1391×10^{-8}	9.8089×10^{-9}	1.2085×10^{-8}			

Table 1. Model Forecast value and MSE (with W=1000)

From this table, for both stock, the range of MSE of these three model for PG and DIS is $(1.1566 \times 10^{-8}, 1.6612 \times 10^{-8})$ and $(9.8089 \times 10^{-9}, 1.2085 \times 10^{-8})$, respectively. All three models' MSE is less than 2×10^{-8} and they do well in the forecasting of RV. Among these models, HAR1 model has the smallest MSE and Non-change Model has the largest MSE. HAR1 does best according to MSE criterion.

AR Model

```
function [fc,beta] = AR(X,Y,J,T,step)

yli s the width of data window

T stop day
```

```
%T+1 is forecasting day(newest available data—1)
    %n is forecasting step number
   %Y and X are available total data
 6
   x=zeros(J,step);
8 | y1=zeros(step,1);
     for i=1:step
9
10
        x(:,i)=X(T-J+1-i:T-i);
11
        y1(i)=X(T-i+1);
12
      end
13
    %y is the denpendent variable vector: J*1 t—series data
    %x is the indenpendent variable matrix: J*n t—series data * n variables
15 | %beta is the vestor of parameter: (n+1)*1
16 x=flipud(x);
17 | y=flipud(Y(T—J+1:T));
18 beta=0LS(x,y);
19 %forecasting
20 | y1=[y1;1];
   fc=beta'*v1;
22 \mid \text{if fc} \cdot \text{min}(X(T-J+1-\text{step}:T)) \mid | \text{fc} \cdot \text{max}(X(T-J+1-\text{step}:T))
23
          fc=mean(X(T—J+1—step:T));
24
   end
25
26 | end
```

HAR Model

```
function [fc,beta] = HAR(X,Y,J,T,step)
   %J is the width of X data window
   |%T+1 is forecasting day(newest available data-1)
3
4
   %n is forecasting step number
   %Y and X are available total data
   x=zeros(J,3*step);
 7
   y1=zeros(3*step,1);
8
     for i=1:step
9
       x(:,3*i-2)=X(T-J+1-i:T-i);
10
       x(:,3*i-1)=movmean(X(T-J+1-i:T-i),[4,0]);
11
       x(:,3*i)=movmean(X(T-J+1-i:T-i),[21,0]);
12
       y1(3*i-2)=X(T-i+1);
13
       y1(3*i-1)=mean(X(T-i+1-4:T-i+1));
14
       y1(3*i) = mean(X(T-i+1-21:T-i+1));
15
     end
16 | %y is the denpendent variable vector: J*1 t—series data
   %x is the indenpendent variable matrix: J*n t—series data * n variables
17
18 |%beta is the vestor of parameter: (n+1)*1
19 | x=flipud(x(22:end,:));
```

```
y=flipud(Y(T-J+1+21:T));
20
21
    beta=0LS(x,y);
22
      %forecasting
23
      y1=[y1;1];
24
      fc=beta'*y1;
25
26
    if fc<min(X(T-J+1-step:T)) \mid | fc>max(X(T-J+1-step:T))
27
         fc=mean(X(T—J+1—step:T));
28
    end
29
30
31
32
   end
```

(C) Here is the table of forecasting MSE from different forecasting models.

Table 2:	Tabel	of	Model	Forecast	MSE

Stock	Window Size	MSE_{AR1}	MSE_{HAR1}	MSE_{NC}
PG	W = 250	3.2466×10^{-8}	3.3395×10^{-8}	4.5041×10^{-8}
	W = 500	1.7451×10^{-8}	1.6381×10^{-8}	1.9376×10^{-8}
DIS	W = 250	8.6868×10^{-8}	1.0468×10^{-7}	1.2226×10^{-7}
	W = 500	2.9928×10^{-8}	2.4585×10^{-8}	3.3995×10^{-8}

From this table, the range of models' MSE for PG and DIS when W=250 and is $(3.2466 \times 10^{-8}, 4.5041 \times 10^{-8})$ and $(8.6868 \times 10^{-8}, 1.2226 \times 10^{-7})$, respectively; the range of models' MSE for PG and DIS when W=500 and is $(1.6381 \times 10^{-8}, 1.9376 \times 10^{-8})$ and $(2.4585 \times 10^{-8}, 3.3995 \times 10^{-8})$, respectively.

Combine the results in part (B), We can find as the window size decreases from 1000 to 250, the MSE of each model increases. There is no model consistently better than others when evaluated using different window size.

(D) Here is the plot of model MSE with different window size.

(+0.3) nice formatted plot

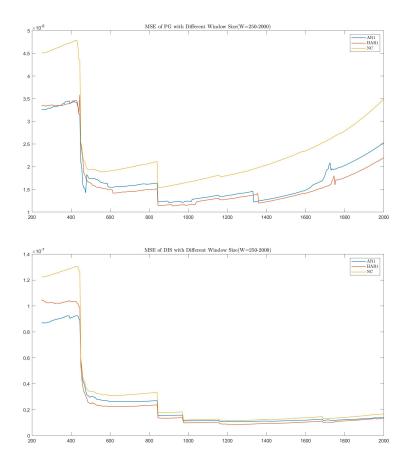


Figure 1: MSE with Different Window Size

From the figure we can see, the MSE of forecast for these three models show a decrease jump at around J=500 and reach the lowest value at around J=1000. After reaching the lowest point, the MSE of PG starts increase, however, the MSE of DIS is persistent for increasing J.

The **MATLAB** code:

Function of Local Variance

Script of Q1

```
addpath('D:\ZM—Documents\MATLAB\data\Stocks5Min','functions','scripts');
[dates_PG,lp_PG]=load_stock('PG.csv','m');
N_PG=sum(floor(dates_PG(1,1))==floor(dates_PG(:,1)));% number of observations per day
T_PG=size(dates_PG,1)/N_PG;
[rdates_PG,lr_PG]=log_return([dates_PG lp_PG],N_PG,1);
```

```
days_PG=unique(floor(rdates_PG));
8
   n=N_PG-1;
9
   a=5;
10 | [lr_c_PG,lr_d_PG]=c_d_log_returns(lr_PG,N_PG,a);
11
12 RV_PG=transpose(sum(lr_PG.^2));
   QIV_PG=transpose(sum((n/3)*(lr_c_PG.^4)));
13
14
15
   %1B
16
  step=1;
17
   X=RV_PG;
18 Y=RV_PG;
19 J=1000—1;%row number of independent variable
20
  fRV_AR1_PG1=zeros(T_PG-J-1,1);%t increase
   fRV_HAR1_PG1=zeros(T_PG-J-1,1);
22
   %fRV_NC_PG=zeros(T_PG-J);
23
24
25
26
   for T=J+1:T_PG-1% the newest data used to estimate beta
27
       fRV_AR1_PG1(T_J)=AR(X,Y,J,T,step);
28
       fRV_HAR1_PG1(T-J)=HAR(X,Y,J,T,step);
29
   end
   ERR\_AR1\_PG1=(mean((Y(J+2:T\_PG)-fRV\_AR1\_PG1).^2));
30
   ERR_HAR1_PG1=(mean((Y(J+2:T_PG)-fRV_HAR1_PG1).^2));
32
   ERR_CN_PG1=(mean((Y(J+2:T_PG)-Y(J+1:T_PG-1)).^2));
33
34
35
   %10
36
   J=250-1;
   fRV_AR1_PG2=zeros(T_PG—J—1,1);%t increase
38
   fRV_HAR1_PG2=zeros(T_PG-J-1,1);
39
   %fRV_NC_PG=zeros(T_PG-J);
40
41
   for T=J+1:T_PG-1
42
       fRV_AR1_PG2(T_J)=AR(X,Y,J,T,step);
43
       fRV_HAR1_PG2(T-J)=HAR(X,Y,J,T,step);
44
   end
   ERR\_AR1\_PG2=(mean((Y(J+2:T\_PG)-fRV\_AR1\_PG2).^2));
45
   ERR_HAR1_PG2=(mean((Y(J+2:T_PG)-fRV_HAR1_PG2).^2));
47
   ERR_CN_PG2=(mean((Y(J+2:T_PG)-Y(J+1:T_PG-1)).^2));
48
49
```

```
J=500-1;
50
51
   fRV_AR1_PG3=zeros(T_PG-J-1,1);%t increase
52 | fRV_HAR1_PG3=zeros(T_PG-J-1,1);
   fRV_NC_PG3=zeros(T_PG-J);
54
   for T=J+1:T_PG-1
56
       fRV_AR1_PG3(T_J)=AR(X,Y,J,T,step);
       fRV_HAR1_PG3(T—J)=HAR(X,Y,J,T,step);
58
   end
59
   ERR_AR1_PG3=(mean((Y(J+2:T_PG)-fRV_AR1_PG3).^2));
   ERR_HAR1_PG3=(mean((Y(J+2:T_PG)-fRV_HAR1_PG3).^2));
   ERR_CN_PG3=(mean((Y(J+2:T_PG)-Y(J+1:T_PG-1)).^2));
62
63
   %1D
64
65
   % ERR_AR1_PG4=zeros(351,1);
66 % ERR_HAR1_PG4=zeros(351,1);
   % ERR_CN_PG4=zeros(351,1);
68
   % for J=250-1:5:2000-1
   % fRV_AR1_PG1=zeros(T_PG-J-1,1);%t increase
70
   % fRV_HAR1_PG1=zeros(T_PG-J-1,1);
71
       for T=J+1:T_PG-1% the newest data used to estimate beta
          fRV_AR1_PG1(T-J)=AR(X,Y,J,T,step);
72
73
   %
         fRV_HAR1_PG1(T-J)=HAR(X,Y,J,T,step);
74
       end
75
   ERR_AR1_PG4((J+1)/5-49)=(mean((Y(J+2:T_PG)-fRV_AR1_PG1).^2));
   % ERR_HAR1_PG4((J+1)/5-49)=(mean((Y(J+2:T_PG)-fRV_HAR1_PG1).^2));
77
   \% ERR_CN_PG4((J+1)/5-49)=(mean((Y(J+2:T_PG)-Y(J+1:T_PG-1)).^2));
78
   % end
79
   %
80 %
81 % figure;
82 |% plot(250:5:2000, ERR_AR1_PG4, 'linewidth', 1);
83 |% hold on;
84 |% plot(250:5:2000,ERR_HAR1_PG4,'linewidth',1);
85 % hold on;
86 |% plot(250:5:2000,ERR_CN_PG4,'linewidth',1);
87 % legend('AR1','HAR1','NC');
88 % title('MSE of PG with Different Window Size(W=250—2000)');
```

Exercise 2-Errors in Variables (EIV)

(A) The MATLAB code:

```
function [X,Y] = simulation(var1,var2,var3,N,beta)
noise=random('normal',0,sqrt(var3),N,1);
X=random('normal',0,sqrt(var1),N,1)+noise;
u=random('normal',0,sqrt(var2),N,1);
Y=beta'.*X+u;
end
```

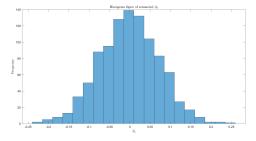
In this function, var1 is the variance of X; var2 is the variance of error term u; var3 is the variance of noise. If var3 = 0, then the noise in X is zero.

(B) Here is the summary table of beta.

Table 3: Summary Table of Parameter

Parameter	β_0	β_1
Value	0.0376	1.0040

(C) Here are the histogram figures of β_0 and β_1 .



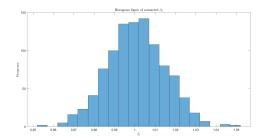


Figure 2: Histogram of β_0 and β_1

From the histogram figure of β_0 and β_1 , we can see the shape of distribution of β_0 and β_1 is very similar to normal distribution.

Specifically, the mean of β_0 showed in the plot is zero and the mean of β_1 is 1. The result satisfies our expectation.

(**D**) Here are the figures of estimated probability density function of β_0 and β_1 .

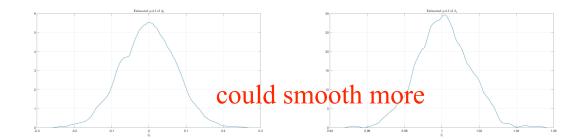


Figure 3: Estimated probability density function of β_0 and β_1

From the figures we can see the p.d.f. of β_0 and β_1 are very similar to normal distribution with mean equals to 0 and 1, respectively.

Compare the distribution shape of β_0 and β_1 we can find: β_0 's distribution with a fatter tail and less peak, which indicates the variance of β_0 is larger than the variance of β_1 .

(E) For regression:

$$\tilde{Y}_i = \tilde{X}_i \beta + \tilde{u}_i$$

we can estimate β by calculate:

$$\hat{\beta}^{ture} = \frac{Cov(\tilde{Y}_i, \tilde{X}_i)}{Var(\tilde{X}_i)} = \frac{Cov(\tilde{X}_i\beta, \tilde{X}_i) + Cov(\tilde{u}_i, \tilde{X}_i)}{Var(\tilde{X}_i)}$$

If some noises are added into \tilde{X}_i , the regression with noise will be:

$$\tilde{Y}_i = \tilde{X}_i^* \beta^* + \tilde{u}_i$$

where $\tilde{X}_i^* = \tilde{X}_i + \eta_i$ is the noise version of \tilde{X}_i , we can estimate β^* by calculate:

$$\hat{\beta}^* = \frac{Cov(\tilde{Y}_i, \tilde{X}_i^*)}{Var(\tilde{X}_i^*)} = \frac{Cov(\tilde{X}_i\beta, \tilde{X}_i) + Cov(\tilde{u}_i, \tilde{X}_i) + Cov(\tilde{X}_i\beta, \eta_i) + Cov(\tilde{u}_i, \eta_i)}{Var(\tilde{X}_i) + Var(\eta) + Cov(\tilde{X}_i, \eta_i)}$$

Assume noises η_i are uncorrelated with \tilde{X}_i , we can simplify $\hat{\beta}^*$ as:

$$\hat{\beta}^* = \frac{Cov(\tilde{X}_i\beta, \tilde{X}_i) + Cov(\tilde{u}_i, \tilde{X}_i)}{Var(\tilde{X}_i) + Var(\eta)}$$

as the $Var(\eta)$ increases, $\hat{\beta}^*$ will decrease and we will get a down-biased estimator of β . For the rest part, noises will be added to X to see how it affect the estimation of parameter β .

We first change the variance of noise from 0 to $0.30\sigma_x^2$.

(i) Here is the summary table of estimate value of $\hat{\beta_0}^*$ and $\hat{\beta_1}^*$.

Value

Table 4: Summary Table of Parameter $\hat{\beta_0}^*$ $\hat{\beta_1}^*$ 0.1643 0.9881

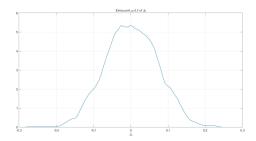
(ii) Here are the histogram figures of $\hat{\beta_0}^*$ and $\hat{\beta_1}^*$.

density should changed after adding noise and beta goes to around 0.75 0.65 respectively, check your results again (-1.5)



Figure 4: Histogram of $\hat{\beta_0}^*$ and $\hat{\beta_1}^*$

(iii) Here are the figures of estimated probability density function of $\hat{\beta_0}^*$ and $\hat{\beta_1}^*$.



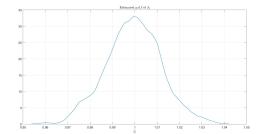


Figure 5: Estimated probability density function of $\hat{\beta_0}^*$ and $\hat{\beta_1}^*$

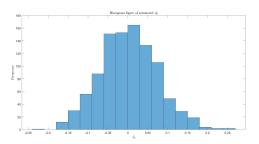
From the figures we can see the shape of distribution of $\hat{\beta_0}^*$ and $\hat{\beta_1}^*$ are still similar to normal distribution, but they show a trend of left skew and the mean of $\hat{\beta_0}^*$ and $\hat{\beta_1}^*$ in the estimated distribution are a little smaller than 0 and 1, respectively.

- (F) We then change the variance of η_i to $0.50\sigma_x^2$.
 - (i) Here is the summary table of estimate value of $\hat{\beta_0}^*$ and $\hat{\beta_1}^*$.

Table 5: Summary Table of Parameter

Parameter	$\hat{eta_0}^*$	$\hat{\beta_1}^*$
Value	0.0338	0.9835

(ii) Here are the histogram figures of $\hat{\beta_0}^*$ and $\hat{\beta_1}^*$.



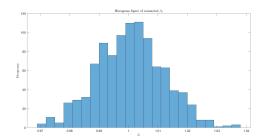
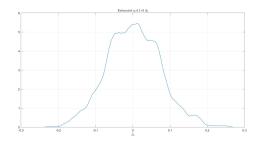


Figure 6: Histogram of $\hat{\beta_0}^*$ and $\hat{\beta_1}^*$

(iii) Here are the figures of estimated probability density function of $\hat{\beta_0}^*$ and $\hat{\beta_1}^*$.



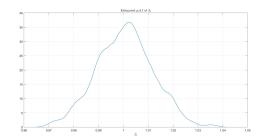


Figure 7: Histogram of $\hat{\beta_0}^*$ and $\hat{\beta_1}^*$

From the figures we can see the shape of distribution of $\hat{\beta_0}^*$ and $\hat{\beta_1}^*$ are little different to normal distribution: they are skewed left and the mean of $\hat{\beta_0}^*$ and $\hat{\beta_1}^*$ in the estimated distribution are smaller than $\hat{\beta_0}^*$ and $\hat{\beta_1}^*$ in part E.

If we keep increasing the variance of noises η_i , the distribution of $\hat{\beta_0}^*$ and $\hat{\beta_1}^*$ will skew much more to the left, and their mean will deviation more from true value of β_0 and β_1 .

The MATLAB:

Scripts of Q2

```
addpath('D:\ZM—Documents\MATLAB\data', 'functions', 'scripts');
2
 3
   %2A
 4
5
   var1=25.2;
   var2=0.5;% noise in Y
   var3=0; % noise in X
8
   beta=1;
9 N=100;
10 [X,Y]=simulation(var1,var2,var3,N,beta);
11 |%2B
12 beta_hat=0LS(X,Y);
13 %3C
14 r=1000;
15 X1=zeros(N,r);
16 | Y1=zeros(N,r);
17 | beta_hat1=zeros(r,2);
18 | for i=1:r
19
    [X1(:,i),Y1(:,i)]=simulation(var1,var2,var3,N,beta);
20
   beta_hat1(i,:)=OLS(X1(:,i),Y1(:,i));
21
   end
22
23 | figure;
24 | histogram(beta_hat1(:,2),20);
25 | xlabel('$\hat{\beta_0}$');
26 | ylabel('Frequency');
27 | title('Histogram figure of estameted $\beta_0$');
28 | figure;
29 histogram(beta_hat1(:,1),20);
30 | xlabel('$\hat{\beta_1}$');
31 | ylabel('Frequency');
32 | title('Histogram figure of estameted $\beta_1$');
33
34
   %2D
   [f_beta0,x_beta0]=ksdensity(beta_hat1(:,2),'Kernel','epanechnikov','Bandwidth
       ',0.01);
36 | figure;
   plot(x_beta0, f_beta0);
38 | xlabel('$\hat{\beta_0}$');
39 grid on;
40 | title('Estimated p.d.f of $\beta_0$');
41
42 [f_beta1,x_beta1]=ksdensity(beta_hat1(:,1),'Kernel','epanechnikov','Bandwidth
       ',0.002);
```

```
figure;
43
44
   plot(x_beta1, f_beta1);
45 | xlabel('$\hat{\beta_1}$');
46 | grid on;
47 | title('Estimated p.d.f of $\beta_1$');
48
49
50 %2E
51 %repeat A
52 | var1=25.2;
53 var2=0.5;
54 | var3=0.3*var1;
55 beta=1;
56 N=100;
57
   [X_hat,Y_hat]=simulation(var1,var2,var3,N,beta);
58 %repeat B
59 %estimate beta_hat
60 beta_hat_1=0LS(X_hat,Y_hat);
   %repeat C
   %estimate different beta_hat
63 r=1000;
64 \mid X2=zeros(N,r);
65 Y2=zeros(N,r);
66 | beta_hat2=zeros(r,2);
67 for i=1:r
68
    [X2(:,i),Y2(:,i)]=simulation(var1,var2,var3,N,beta);
69
    beta_hat2(i,:)=0LS(X2(:,i),Y2(:,i));
70
   end
71
72
73 | figure;
74 | histogram(beta_hat2(:,2));
75 | xlabel('$\hat{\beta_0}$');
76 | ylabel('Frequency');
77 | title('Histogram figure of estameted $\beta_0$');
   figure;
79 histogram(beta_hat2(:,1));
80 | xlabel('$\hat{\beta_1}$');
81 | ylabel('Frequency');
82 | title('Histogram figure of estameted $\beta_1$');
83
84 %repeat C
   %estimate distribution of beta_hat
86
```

```
[f_beta0,x_beta0]=ksdensity(beta_hat2(:,2),'Kernel','epanechnikov','Bandwidth
         ',0.01);
 88
    figure;
    plot(x_beta0, f_beta0);
 90 | xlabel('$\hat{\beta_0}$');
    grid on;
 91
 92 | title('Estimated p.d.f of $\beta_0$');
 93
    [f_beta1,x_beta1]=ksdensity(beta_hat2(:,1),'Kernel','epanechnikov','Bandwidth
 94
        ',0.002);
    figure;
 96 | plot(x_beta1, f_beta1);
 97 | xlabel('$\hat{\beta_1}$');
98 grid on;
99 | title('Estimated p.d.f of $\beta_1$');
100
    %2F
101
102 |%repeat A
103 | var1=25.2;
104 | var2=0.5;
105 | var3=0.5*var1;
106 | beta=1;
107 N=100;
108 [X_hat,Y_hat]=simulation(var1,var2,var3,N,beta);
109 %repeat B
110 %estimate beta_hat
111
    beta_hat_3=0LS(X_hat,Y_hat);
112 %repeat C
113 | %estimate different beta_hat
114 | r=1000;
115 \mid X2=zeros(N,r);
116 | Y2=zeros(N,r);
117 | beta_hat4=zeros(r,2);
118 | for i=1:r
119
    [X2(:,i),Y2(:,i)]=simulation(var1,var2,var3,N,beta);
120
     beta_hat4(i,:)=0LS(X2(:,i),Y2(:,i));
121
    end
122
123
124 | figure;
125 | histogram(beta_hat4(:,2));
126 | xlabel('$\hat{\beta_0}$');
127
    ylabel('Frequency');
128 | title('Histogram figure of estameted $\beta_0$');
```

```
129
    figure;
130
    histogram(beta_hat4(:,1));
    xlabel('$\hat{\beta_1}$');
131
    ylabel('Frequency');
133
    title('Histogram figure of estameted $\beta_1$');
134
135
    %repeat C
136
    %estimate distribution of beta_hat
137
138
    [f_beta0,x_beta0]=ksdensity(beta_hat4(:,2),'Kernel','epanechnikov','Bandwidth
        ',0.01);
    figure;
    plot(x_beta0,f_beta0);
140
    xlabel('$\hat{\beta_0}$');
141
142
    grid on;
143
    title('Estimated p.d.f of $\beta_0$');
144
145
    [f_beta1,x_beta1]=ksdensity(beta_hat4(:,1),'Kernel','epanechnikov','Bandwidth
        ',0.002);
146
    figure;
147
   plot(x_beta1, f_beta1);
    xlabel('$\hat{\beta_1}$');
148
149
    grid on;
150 | title('Estimated p.d.f of $\beta_1$');
```

Exercise 3-Accounting for EIV When Forecasting Variance)

(A) Here is the summary table of MSE of different forecasting model.

Table 6: Summary Table of AR1, HAR1 and Non-change Model Forecasting

Stock	MSE_{AR1}	MSE_{HAR1}	MSE_{QAR1}	MSE_{QHAR1}	MSE_{NC}
PG	$1.2432*10^{-8}$	$1.1566*10^{-8}$	$1.0158 * 10^{-8}$	$1.0085*10^{-8}$	$1.6612 * 10^{-8}$
DIS	$1.1391 * 10^{-8}$	$9.8089 * 10^{-9}$	$1.0507 * 10^{-8}$	$1.0924 * 10^{-8}$	$1.2085 * 10^{-8}$

- (B) According to the MSE table, the model with smallest MSE for PG and DIS is HARQ1 and HAR1 model, respectively. Even though there is no consistently better model for both stock.

 Nice work! (+0.8)
- (C) Here is the summary table of MSE of different forecasting model.

Table 7: Forecasting MSE of Different Models ($\times 10^{-8}$)

	Table 1. Tolecasting Wibl of Different Worders (×10)							
\mathbf{Stock}	$\mathbf{AR1}$	HAR1	ARQ1	HARQ1	NC			
AAPL	3.2714	2.9762	2.7786	2.6902	3.9421			
\mathbf{AXP}	3.5744	1.5778	1.7709	1.4288	1.8856			
$\mathbf{B}\mathbf{A}$	2.3167	2.1559	2.2445	2.1558	3.3353			
\mathbf{BAC}	12.7604	11.4649	12.1244	11.0409	13.0808			
BLK	2.2313	1.7329	1.7581	1.6140	2.0247			
\mathbf{C}	12.1826	6.3003	6.8755	7.9979	5.7247			
\mathbf{CAT}	2.0648	1.8225	1.9354	1.8075	2.3188			
CSCO	1.0665	0.9177	0.9491	0.8949	1.1621			
\mathbf{CVX}	1.3623	1.2868	1.3603	1.2812	1.4211			
DIS	1.1391	0.9809	1.0507	1.0924	1.2085			
\mathbf{GE}	3.8628	3.3507	2.4765	2.4125	3.8388			
\mathbf{GNTX}	12.9547	11.1596	11.9238	10.9278	18.1811			
\mathbf{GS}	3.3944	2.1976	3.1675	3.5596	2.6432			
HD	3.1479	2.6523	2.3320	2.2735	3.6952			
IBM	0.6825	0.6393	0.5895	0.5903	0.7714			
INTC	1.8806	1.6442	1.5698	1.5234	2.2521			
JNJ	7.7365	8.0818	7.9765	8.1612	8.7594			
\mathbf{JPM}	3.4805	2.3850	2.5029	2.4623	3.0487			
KO	0.3230	0.3134	0.2769	0.2841	0.3632			
MCD	0.8678	0.7321	0.6505	0.6396	0.9998			

Stock	AR1	HAR1	ARQ1	HARQ1	NC
MET	4.7331	3.4626	3.8582	3.3952	4.7734
MMC	1.0222	0.7447	0.7473	0.6641	0.8568
MMM	0.9572	0.7548	0.6677	0.6547	0.9877
MRK	1.3333	0.8740	0.8094	0.7869	1.0468
MS	15.0342	8.9090	47.5674	44.0217	8.9950
\mathbf{MSFT}	1.9402	1.8601	1.6777	1.6693	2.3991
\mathbf{NKE}	3.7374	3.6169	2.7173	2.7401	4.4002
\mathbf{PFE}	1.2692	1.1040	1.2880	1.1690	1.5515
\mathbf{PG}	1.2432	1.1566	1.0158	1.0085	1.6612
PNC	2.2143	1.1236	1.3913	1.2943	1.2884
\mathbf{SPY}	0.5440	0.5224	0.4111	0.4313	0.5580
\mathbf{STT}	26.1304	6.0592	4.7533	3.6078	2.3478
TSLA	3.6171	2.5752	3.4272	2.6248	3.5462
\mathbf{UNH}	9.6769	8.7356	9.0138	8.6044	14.6258
$\mathbf{U}\mathbf{T}\mathbf{X}$	0.7892	0.7204	0.7679	0.7382	0.9246
$\mathbf{V}\mathbf{Z}$	0.7412	0.6082	0.6622	0.6168	0.8915
\mathbf{WMT}	1.6148	1.5385	1.5195	1.5042	2.5851
\mathbf{XOM}	0.9464	0.8874	0.8611	0.8410	0.9395

From the MSE table we cannot find a model that is consistently better than other models for all stocks, however, we can find two models: HAR1 and Non-change, which are more stable than the AR1, ARQ1 and HARQ1 model for all stocks.

If QIV is much large for the data, using HARQ and ARQ model to reduce the estimate error in beta will be a bad idea since the large QIV will bring more biases for estimating.

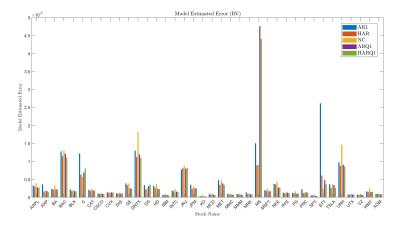


Figure 8: Bar Plot of RV Forecast MSE

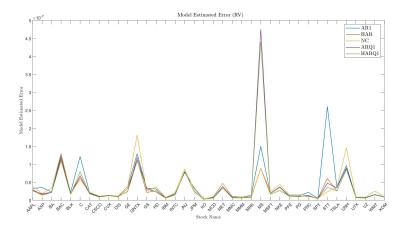


Figure 9: Figure of RV Forecast MSE

From the figures we can clearly find that for most of stocks, the difference of MSE of five models are small, which mean these five models work well in quasi-forecasting. However, for some specific stocks, like MS, QSR1 and QHAR1 work badly and they have about three time MSE as other's. For stock STT, AR1 model works badly and has two times of MSE as others.

In conclusion, HAR1 and Non-change model are the most stable model and work consistently better for all stocks.

(D) Here is the summary table of MSE of different forecasting model.

Table 8: Forecasting MSE of Different Models(TV)($\times 10^{-8}$)

Stock	AR1	HAR1	\overline{ARQ}	HARQ1	NC
AAPL	3.2091	2.9623	2.7051	2.6453	3.8653
\mathbf{AXP}	3.2987	1.4093	1.4958	1.2628	1.5763
$\mathbf{B}\mathbf{A}$	2.2521	2.0966	2.1955	2.1188	3.1431
\mathbf{BAC}	12.5713	11.2341	12.0602	10.9838	13.0232
\mathbf{BLK}	2.1816	1.7107	1.7118	1.5942	1.9908
${f C}$	12.6278	6.3383	6.5516	6.7494	5.6320
\mathbf{CAT}	1.9681	1.7371	1.8305	1.7161	2.1880
\mathbf{CSCO}	1.0136	0.9145	1.0763	0.9932	1.1534
\mathbf{CVX}	1.3352	1.2672	1.3759	1.2812	1.3838
DIS	0.9758	0.8681	0.8626	0.8295	1.0034
\mathbf{GE}	3.8282	3.3438	2.4326	2.3894	3.8257
\mathbf{GNTX}	10.1214	8.6838	8.9482	8.3329	13.7327
\mathbf{GS}	3.1909	2.1473	3.7833	3.8295	2.6105

- C+ 1	4 D 1	TT A D 4	ADO	TT A DO1	N TC
Stock	AR1	HAR1	ARQ	HARQ1	NC
HD	3.1849	2.7063	2.3773	2.2965	3.6689
\mathbf{IBM}	0.6501	0.6276	0.5924	0.5829	0.7544
INTC	1.4487	1.2924	1.2410	1.2159	1.7189
JNJ	0.2685	0.2613	0.2680	0.2580	0.2929
\mathbf{JPM}	3.3475	2.3436	2.4872	2.4502	2.9863
KO	0.3173	0.3107	0.2783	0.2787	0.3566
MCD	0.8562	0.7186	0.6378	0.6286	0.9823
\mathbf{MET}	4.1713	2.9094	3.2422	2.7849	3.7956
MMC	0.8604	0.7131	0.6189	0.6163	0.8430
MMM	0.8988	0.7535	0.7127	0.6753	0.9757
MRK	1.0049	0.7948	0.7572	0.7199	1.0017
MS	14.9350	8.3848	29.7105	29.0690	8.8612
\mathbf{MSFT}	1.9118	1.8309	1.6274	1.6255	2.3419
\mathbf{NKE}	3.6420	3.5443	2.5999	2.6164	4.2373
\mathbf{PFE}	0.8766	0.7866	0.9020	0.8401	1.0316
\mathbf{PG}	1.2324	1.1541	0.9917	0.9857	1.5692
PNC	2.1834	1.0978	1.3494	1.2580	1.2398
\mathbf{SPY}	0.5394	0.5299	0.4119	0.4260	0.5483
\mathbf{STT}	25.2062	5.9830	4.1699	3.3472	2.1732
TSLA	3.3020	2.3677	3.1266	2.4557	3.2622
\mathbf{UNH}	9.4701	8.5657	8.7695	8.4156	14.3376
$\mathbf{U}\mathbf{T}\mathbf{X}$	0.7187	0.6631	0.7325	0.6962	0.8210
$\mathbf{V}\mathbf{Z}$	0.7014	0.5765	0.6413	0.6027	0.8256
\mathbf{WMT}	1.5999	1.5231	1.4871	1.4766	2.5414
XOM	0.9264	0.9125	0.8453	0.8185	0.9100

From the TV MSE table we can find, the range of TV forecast MSE is $(0.2929 \times 10^{-8}, 2.9711 \times 10^{-7})$, which is just a half of the range of RV MSE. Since TV just consider the diffusive return of stocks' log return, this will reduce the effects of jump returns and increase the accuracy of forecast.

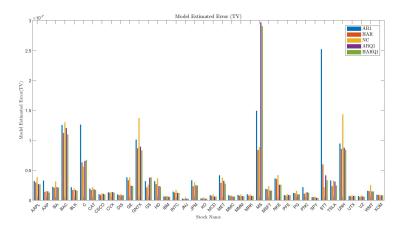


Figure 10: Bar Plot of TV Forecast MSE

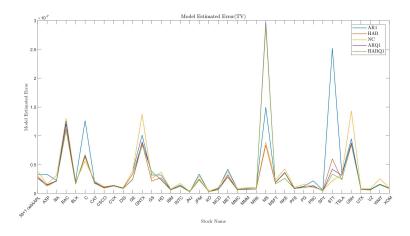


Figure 11: Figure of TV Forecast MSE

From the figures we can find that for most of stocks, these five models all work well and the difference between different models' MSE is very small. However, the same as the case in forecasting RV, there are stocks that some kind of models works badly. For example, HARQ and ARQ have large MSE for stock MS and AR1 model has the largest MSE for stock STT.

In conclusion, the MSE is smaller when forecasts RV and HAR1 and Non-change model are the most stable model and work consistently better for all stocks.

The MATLAB: Scripts of Q3 A-B

```
addpath('D:\ZM—Documents\MATLAB\data','functions','scripts');
   [dates_PG,lp_PG]=load_stock('PG.csv','m');
3
   N_PG=sum(floor(dates_PG(1,1))==floor(dates_PG(:,1))); number of observations
        per day
4
   T_PG=size(dates_PG,1)/N_PG;
   [rdates_PG,lr_PG]=log_return([dates_PG lp_PG],N_PG,1);
6
   days_PG=unique(floor(rdates_PG));
8
   n=N_PG-1;
9
   a=5;
   [lr_c_PG,lr_d_PG]=c_d_log_returns(lr_PG,N_PG,a);
10
11
12
   RV_PG=transpose(sum(lr_PG.^2));
13
   QIV_PG=transpose(sum((n/3)*(lr_c_PG.^4)));
14
15
   %3A
16
   step=1;
17
  X=RV_PG;
18
   Y=RV_PG;
19
  Qiv=QIV_PG;
20 J=1000-1;
   fRV_adjAR1_PG=zeros(T_PG-J-1,1);%t increase
22
   fRV_adjHAR1_PG=zeros(T_PG-J-1,1);
   %fRV_NC_PG=zeros(T_PG-J);
24
25
   for T=J+1:T_PG-1
26
       fRV_adjAR1_PG(T—J)=adjAR(X,Y,Qiv,J,T,step);
27
       fRV_adjHAR1_PG(T—J)=adjHAR(X,Y,Qiv,J,T,step);
28
   end
29
   ERR_adjAR1_PG=(mean((Y(J+2:T_PG)-fRV_adjAR1_PG).^2));
30
   ERR_adjHAR1_PG=(mean((Y(J+2:T_PG)-fRV_adjHAR1_PG).^2));
   ERR_CN_PG=(mean((Y(J+2:T_PG)-Y(J+1:T_PG-1)).^2));
```

Scripts of Q3 C

```
addpath('D:\ZM—Documents\MATLAB\data\Stocks5Min','functions','scripts');
Name=char('AAPL.csv','AXP.csv','BA.csv','BAC.csv','BLK.csv','C.csv','CAT.csv',...

'CSCO.csv','CVX.csv','DIS.csv','GE.csv','GNTX.csv','GS.csv','HD.csv','IBM .csv','INTC.csv',...
'JNJ.csv','JPM.csv','KO.csv','MCD.csv','MET.csv','MMC.csv','MMM.csv','MRK .csv','MS.csv','MSFT.csv','NKE.csv',...
'PFE.csv','PG.csv','PNC.csv','SPY.csv','STT.csv','TSLA.csv','UNH.csv','
UTX.csv','VZ.csv','WMT.csv','XOM.csv');
```

```
J=1000-1;
    6
              step=1;
   8
   9
10 | ERR_AR=zeros(size(Name, 1), 1);
11 | ERR_HAR=zeros(size(Name,1),1);
12 | ERR_adjAR=zeros(size(Name,1),1);
13 | ERR_adjHAR=zeros(size(Name,1),1);
14 | ERR_NC=zeros(size(Name, 1), 1);
15
16 | for i=1:size(Name,1)
              [ERR\_AR(i), ERR\_HAR(i), ERR\_adjAR(i), ERR\_adjHAR(i), ERR\_NC(i)] = MSE(strtrim(i), ERR\_NC(i), ERR\_
17
                             Name(i,:)),J,step);
18
              end
19
20 | ERR=[ERR_AR, ERR_HAR, ERR_NC, ERR_adjAR, ERR_adjHAR];
21 | figure;
22 | bar(ERR);
23
              xlabel('Stock Name');
              ylabel('Model Estimated Error');
25 | title('Model Estimated Error');
             legend('AR1','HAR','NC','ARQ1','HARQ1');
26
27
28 | figure;
29 | plot(1:38, ERR, 'linewidth', 1);
30 | xlabel('Stock Name');
31 |xlim([1,38]);
32 | ylabel('Model Estimated Error');
33 | title('Model Estimated Error');
34 | legend('AR1','HAR','NC','ARQ1','HARQ1');
```

Scripts of Q3 D

```
addpath('D:\ZM—Documents\MATLAB\data\Stocks5Min','functions','scripts');
2
  Name=char('AAPL.csv','AXP.csv','BAC.csv','BAK.csv','C.csv','CAT.csv'
3
       'CSCO.csv','CVX.csv','DIS.csv','GE.csv','GNTX.csv','GS.csv','HD.csv','IBM
          .csv','INTC.csv',...
       'JNJ.csv','JPM.csv','KO.csv','MCD.csv','MET.csv','MMC.csv','MMM.csv','MRK
4
          .csv','MS.csv','MSFT.csv','NKE.csv',...
      'PFE.csv', 'PG.csv', 'PNC.csv', 'SPY.csv', 'STT.csv', 'TSLA.csv', 'UNH.csv', '
          UTX.csv','VZ.csv','WMT.csv','X0M.csv');
  J=1000-1;
6
7
  step=1;
8
```

```
9
10
  ERR_AR_T=zeros(size(Name,1),1);
11
  ERR_HAR_T=zeros(size(Name,1),1);
12 | ERR_adjAR_T=zeros(size(Name,1),1);
13 | ERR_adjHAR_T=zeros(size(Name, 1), 1);
14
   ERR_NC_T=zeros(size(Name,1),1);
15
16 | for i=1:size(Name,1)
17
   [ERR\_AR\_T(i), ERR\_HAR\_T(i), ERR\_adjAR\_T(i), ERR\_adjHAR\_T(i), ERR\_NC\_T(i)] =
       MSE_TV(strtrim(Name(i,:)),J,step);
18
   end
19
20
   ERR=[ERR_AR_T,ERR_HAR_T,ERR_NC_T,ERR_adjAR_T,ERR_adjHAR_T];
21 | figure;
22
   bar(ERR);
   xlabel('Stock Name');
24
   ylabel('Model Estimated Error(TV)');
   title('Model Estimated Error');
26
   legend('AR1','HAR','NC','ARQ1','HARQ1');
27
28 | figure;
   plot(ERR, 'linewidth',1);
30 | xlabel('Stock Name');
31 |xlim([1,38]);
32 | ylabel('Model Estimated Error');
   title('Model Estimated Error(TV)');
33
   legend('AR1','HAR','NC','ARQ1','HARQ1');
```