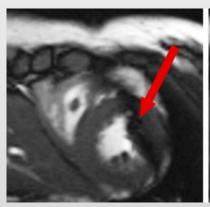
Constrained Model-based Relaxation Parameter Mapping using Balanced Steady State Free Precession

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• The bSSFP sequence is widely used due to its high signal-to-noise ratio (SNR) efficiency. However, it suffers from signal losses in regions with large B₀ field inhomogeneity, resulting in banding artifacts.



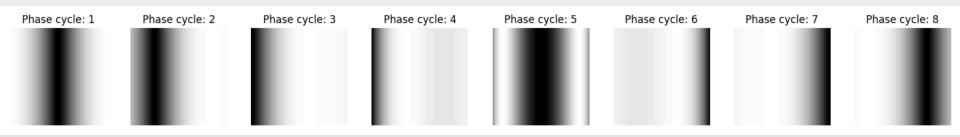


Highly interesting from a methodological standpoint

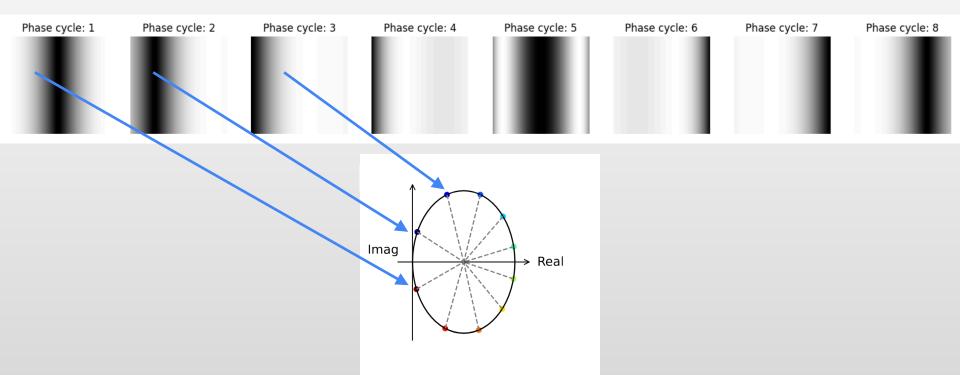
- Parameter mapping
- Super-resolution¹, and
- Parallel imaging²

- 1. Lally, P. Unbalanced SSFP for super-resolution in MRI. MRM
- 2. Berkin, B. Joint Reconstruction of Phase-Cycled Balanced SSFP with Constrained Parallel Imaging. ISMRM 2017

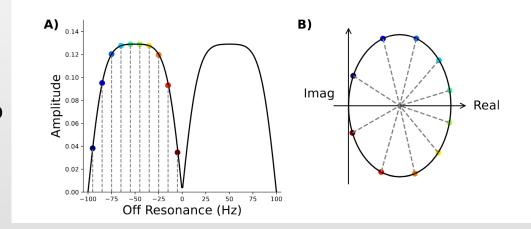
• To mitigate these artifacts, typical bSSFP sequences acquire multiple linear phase-cycled images, each with a different linear RF phase increment, leading to the displacement of the banding artifacts in the spatial domain



• The real and imaginary components of the steady-state transverse magnetization form an ellipse across phase cycles on the complex plane.



 Quantitative parameters may be derived using analytical expressions based on the geometric properties of this ellipse using a method referred to as PLANET¹. However, voxel-wise fitting is sensitive to additive noise, leading to inaccuracies.



Theory

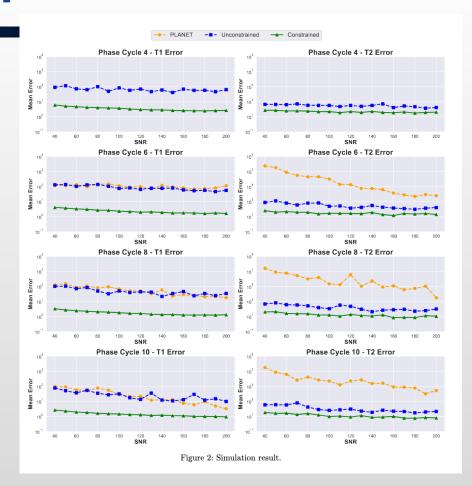
- We propose estimating relaxation parameters as a constrained nonlinear least square problem subject to data consistency costs in *k*-space to improve its noise robustness.
- Unlike traditional methods that extract quantitative relaxation parameters pixel by pixel, our approach leverages global information by jointly estimating T₁ and T₂ across the entire image and assessing reconstruction errors in k-space. Additionally, it supports flexible regularization options, such as total variation, which further mitigates noise sensitivity

Methods

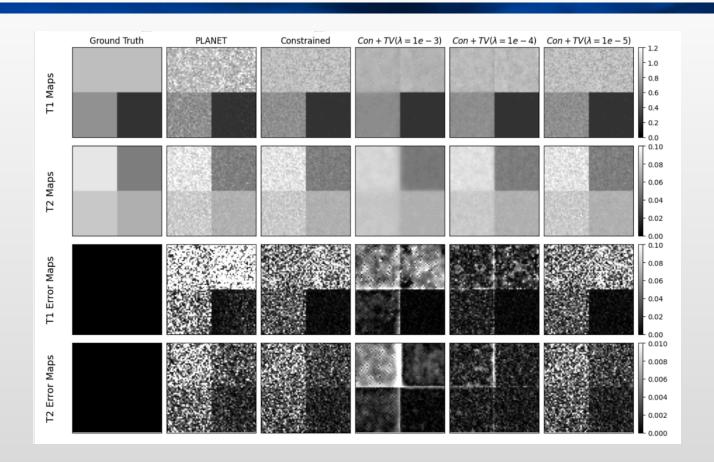
- To evaluate noise sensitivity, we perform a Monte Carlo simulation by randomly generating T₁, T₂, and M₀ on a 16 by 16 image patch.
- T₁ is generated from 100 ms to 3000 ms, T₂ ranges from 1 ms and is upper bounded by the generated T₁ value, and M₀ values range from 0 to 2.
- B₀ map is generated based on low frequency noise in k-space to create smooth and slowly varying modulations in the image domain.
- We used a flip angle of 30 degrees, TR of 10 ms, TE of 5 ms.

Results: simulation

- The conventional approach fits each pixel individually across the phase cycle dimension (e.g., fitting through 6 complex data points for 6 phase cycles).
- In contrast, our method simultaneously fits the entire image by utilizing the entire kspace data across all phase cycles.



Results: simulation (TV on T₁ and T₂)



Discussion

- The proposed method can be extended to multiple coils for parallel imaging. A key advantage is
 its ability to jointly solve for parameter maps by leveraging information across phase cycles and
 coils, effectively utilizing data redundancy.
- One limitation is the assumption of an ideal single-component relaxation model. Factors like diffusion, multi-compartment, and magnetization transfer can cause deviation and the steady state equation used in this work cannot fully capture this complexity².
- It is possible, at least partially, to include these secondary effects into the model.
- Future work will include phantom and in vivo acquisitions to validate the results.

Conclusion

- The proposed constrained model-based fitting approach demonstrates robustness to noise across various phase cycles and SNR levels and outperforms the gold standard PLANET method.
- This is due to
 - 1. jointly solving parameter maps over an image,
 - 2. constraining the search space, and
 - 3. allowing additional regularizations.