

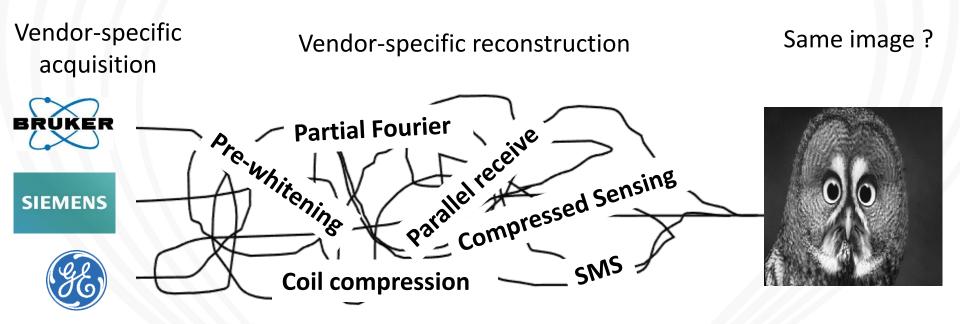
Gadgetron Bordeaux Summer School

MRD format: a necessary step for unified MR reconstruction with Gadgetron

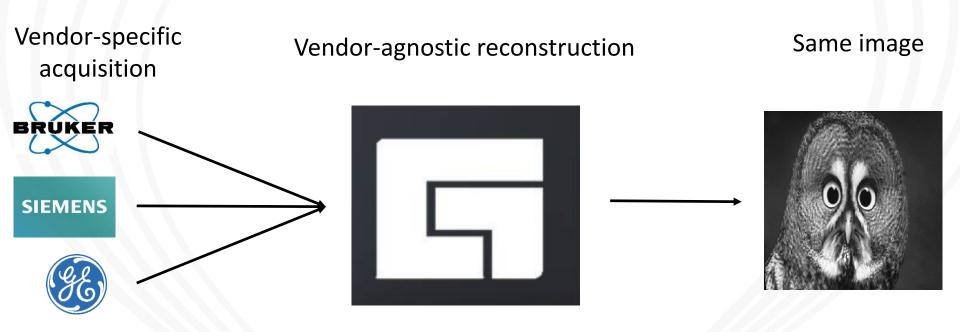
Maxime Yon

LIRYC | Restoring the rhythm of life

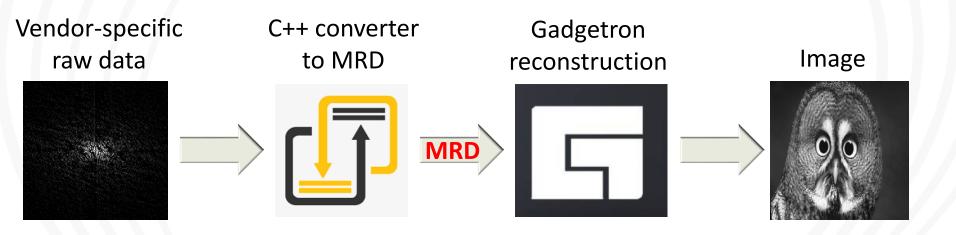
- Nowadays, all MR vendor have their own private reconstruction pipelines
- ➤ The rise of complex MR processing induces variability across vendors
- Only a unified, open source and adaptive reconstruction framework can allow a perfect reproducibility of MR processing



- Nowadays, all MR vendor have their own private reconstruction pipelines
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- A prerequisite for unified magnetic resonance (imaging) reconstruction is a common raw data format
- Gadgetron uses the ISMRM Raw Data format (MRD)



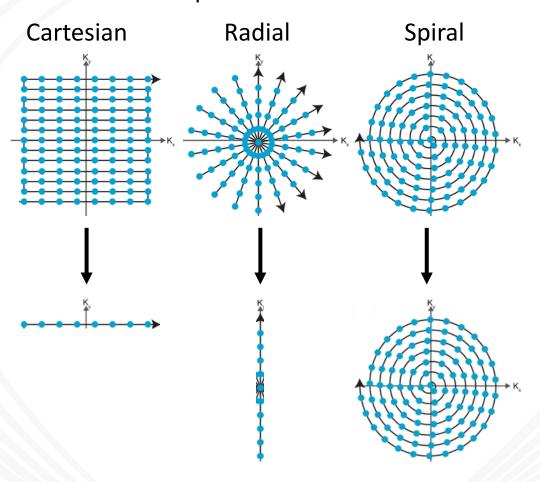
Converters exist for several commercial MRI vendors: Bruker, Siemens, General Electric or Philips.

- MRD format need to capture:
 - the raw k-space data in acquisition order before any transformation
 - the physics parameters of the data acquisition process required for image reconstruction
 - Optionally, the trajectory data or additional waveforms



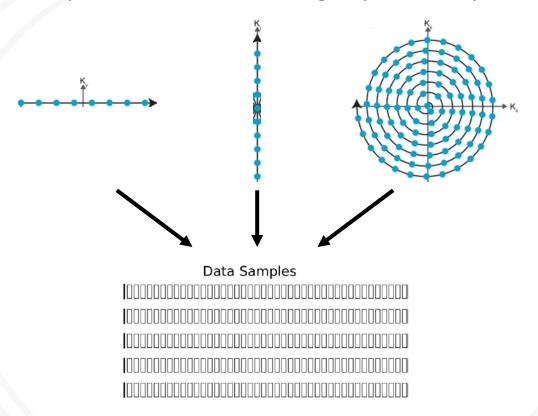
a) The MR unit

In MR acquisition the most simple unit is the readout



a) The MR unit

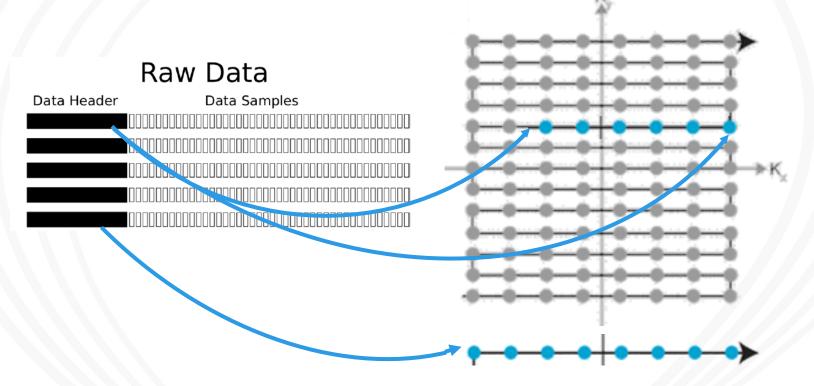
The MRD format captures this unit avoiding any vendor specific operation



- These readout are called « data chunck »
- For multiple coils acquisition, the signal of each coil is saved

b) The data header

Each data item is preceded by a fixed-size Data Header including data type, acquisition flags, encoding numbers...



These data chunks can have different sizes as they include navigator or calibration readout

c) The MRD dataset also contains:

A flexible XML Header containing an arbitrary number of fields accommodating all the parameters that may be meaningful for some experiments but not for others.

ISMRMRD Dataset



MRD dataset = XML general header + N * (data_header + data samples)
Dataset
Encoding Readout * coils parameters
numbers

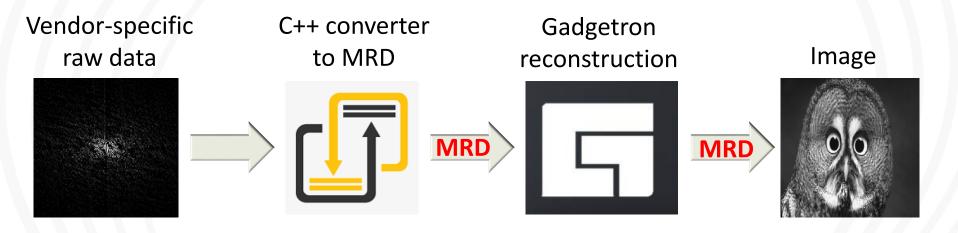
d) Waveforms and contours

- The MRD format also support waveform such as ECG
- It can include contours and landmark making it suitable for AI research



e) Full dataset:

MRD is also used to store images after Gadgetron reconstruction along with image header storing image and user-specified parameters

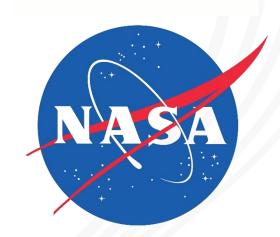


If you prefer DICOM or NIFTI, the conversion need to be performed by the client

f) MRD extension and type

- ➤ MRD uses the Hierarchical Data Format: HDF5
- Its extension is .h5
- Created to store big amount of data
- National Center for Supercomputing Applications in 1987
- Maintained by the HDF group
- ➤ It is Open-source, fast and thus widely used in the research community





a) Library

- ➤ The ISMRMRD library provides C/C++, Python, and MATLAB (Mathworks) interfaces for reading and writing MRD files.
- This library can be compiled on Linux, Windows, and Apple computers as described here: https://ismrmrd.github.io/
- The library is also included in the precompiled packages which you already installed:

```
sudo add-apt-repository ppa:gradient-software/experimental
sudo apt-get update
sudo apt-get install gadgetron-all
pip3 install --user gadgetron
```

b) Phantom generation

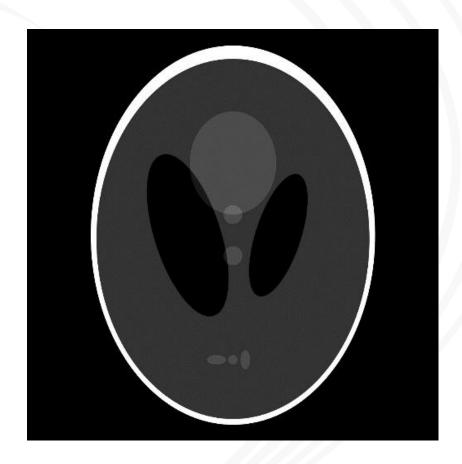
Let's create a shepp logan phantom with the Gadgetron

gadgetron

> In a new tab:

```
mkdir data
cd data
ismrmrd generate cartesian shepp logan
```

The result is the file: testdata.h5



c) ISMRMRD viewer

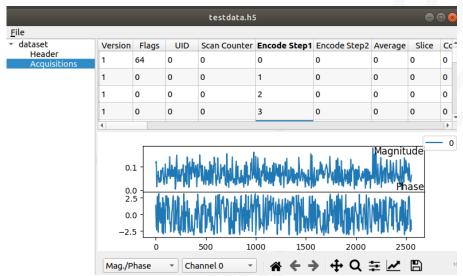
- ➤ ISMRMRDviewer is a convenient tool to explore the MRD dataset
- > It can be installed in a virtual python environment:

```
sudo apt-get install python3-venv
git clone https://github.com/ismrmrd/ismrmrdviewer.git
cd ismrmrdviewer/
python3 -m venv venv
. venv/bin/activate
python3 setup.py --verbose install
deactivate

Eile
Eile
```

- . venv/bin/activate
 python3 ismrmrdviewer
- Or directly with:

pip3 install --user ismrmrdviewer
ismrmrdviewer



d) Open .h5 with Matlab

➤ The ISMRMRD library provides MATLAB functions for reading .h5 file

```
addpath('/usr/local/share/ismrmrd/matlab')
filename = '/home/.../data/testdata.h5';
dset = ismrmrd.Dataset(filename, 'dataset');
header = ismrmrd.xml.deserialize(dset.readxml);
data_struct = dset.readAcquisition();
```

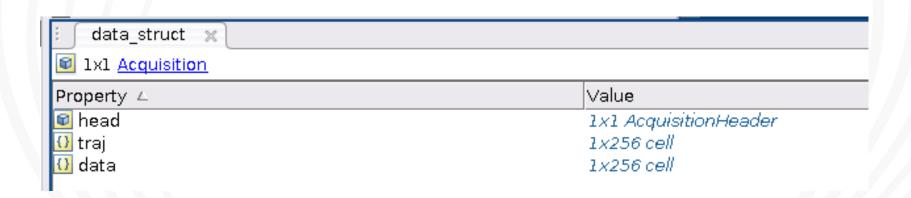
'header' is a structure containing the XML Header fields:

```
header.version 4
header.acquisitionSystemInformation.receiverChannels 8
header.acquisitionSystemInformation.institutionName
ISMRM Synthetic Imaging Lab
header.experimentalConditions.H1resonanceFrequency_Hz 63500000
header.encoding.encodedSpace.matrixSize.x 512
header.encoding.encodedSpace.matrixSize.y 256
header.encoding.encodedSpace.matrixSize.z 1
header.encoding.encodedSpace.fieldOfView_mm.x 600
header.encoding.encodedSpace.fieldOfView_mm.y 300
```

• • •

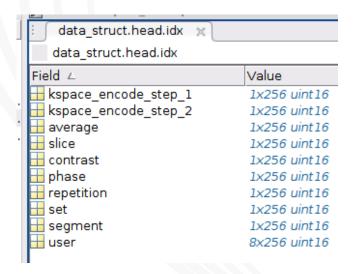
d) Open .h5 with Matlab

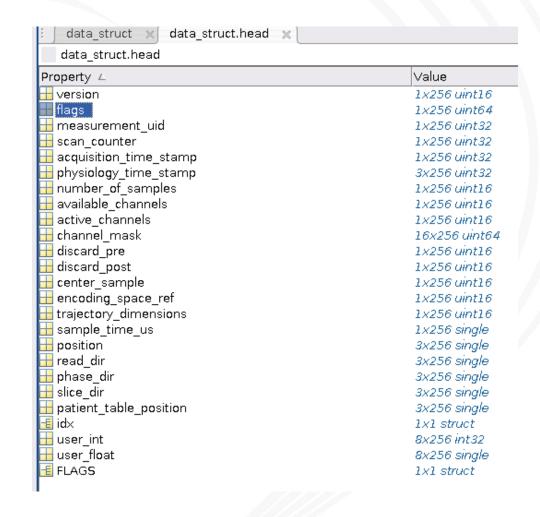
- ➤ The 'data_struct' object contains the acquisition header, the complex data of each coils and optionally the trajectory
- The data are stored in single precision complex values



d) Open .h5 with Matlab

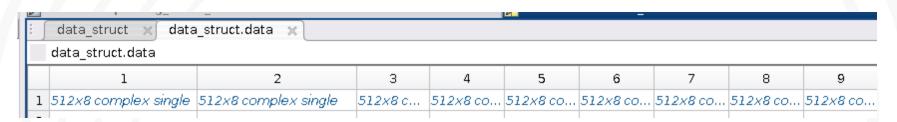
- The 'head object' object contain the fixed-size Data Header including data type, acquisition flags, encoding numbers...
- These parameters are defined for each data chunk, that is why the second dimension is 256 here





d) Open .h5 with Matlab

The 'data_struct' object contain the data chunks: 256 chunks corresponding to phase encode steps, with a readout of 512 points and 8 coils



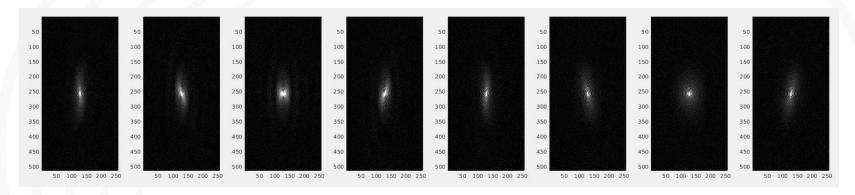
The K-space matrix can be obtained by:

```
for ind=1:size(data_struct.data,2)
    Kspace(:,ind,:) = data_struct.data{1,ind};
end
```

Which gives a 512 x 256 x 8 complex single matrix

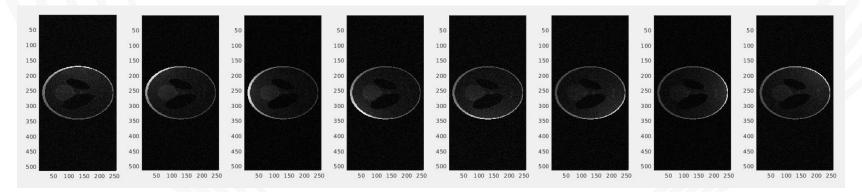
d) Open .h5 with Matlab

> This matrix contain the 8 K-spaces corresponding to the 8 coils



> Their Fourier transform give the images of each of the 8 coils

Images = FFTKSpace2XSpace(FFTKSpace2XSpace(Kspace, 2), 1);



e) Gadgetron recon and output

- Of course, this reconstruction can also be performed with Gadgetron gadgetron
- ➤ In a new tab:

```
gadgetron ismrmrd client -f testdata.h5 -c default.xml -o out.h5
```

- > out.h5 can also be open on Matlab with the functions h5info and h5read
- > It contain the reconstructed image and a basic header

```
filename = '/home/maximey/mount/maxime.yon/Data/out.h5';
hinfo = hdf5info(filename);
Img =single(h5read(filename,hinfo.GroupHierarchy.Groups(1).Groups(1).Datasets(2).Name));
header=h5read(filename,hinfo.GroupHierarchy.Groups(1).Groups(1).Datasets(3).Name);
```

The image header is requiered if the image need to be send back to a scanner and displayed with the correct FOV, orientation...

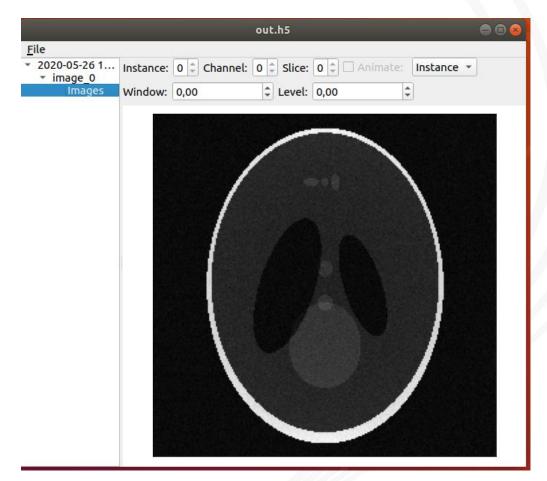
e) Gadgetron recon and output

➤ ISMRMRDviewer can also be used to open the output image

```
cd ismrmrdviewer/
. venv/bin/activate
python3 ismrmrdviewer
```

> Or:

ismrmrdviewer



a) 2D multisclices EPI dataset

Open the MRD EPI Dataset

```
addpath('/usr/local/share/ismrmrd/matlab')
filename = '/home/..../MRD intro hands on training/FID_ep2d_se_noIPAT_3slices.h5';
dset = ismrmrd.Dataset(filename, 'dataset');
header = ismrmrd.xml.deserialize(dset.readxml);
data_struct = dset.readAcquisition();
clearvars dset;
Workspace
Name 4
Value
```

data struct

filename

- header

1x1 Acquisition

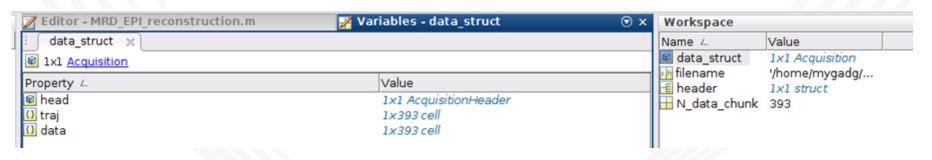
1x1 struct

'/home/mygadg/...

Get the number of data chunk

```
N_data_chunk = size(data_struct.data,2);
```

➤ Here it is 393



b) Exploring encoding limits

➤ In 2D multisclices EPI we expect these data chunk to come from each phase encode (blips) of each sclices

```
N_phase_encode = header.encoding.encodingLimits.kspace_encoding_step_1.maximum + 1;
N slices = header.encoding.encodingLimits.slice.maximum + 1;
```

 \triangleright 128 x 3 = 384, we have 9 additional data chunk

Workspace	
Name △	Value
data_struct	1x1 Acquisition
🕩 filename	'/home/mygadg/
🕕 header	1x1 struct
H N_data_chunk	393
H N_phase_en	128
H N_slices	3

b) Exploring encoding limits

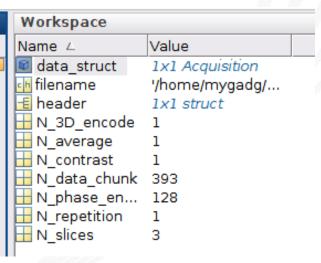
➤ In 2D multisclices EPI we expect these data chunk to come from each phase encode (blips) of each sclices

```
N_phase_encode = header.encoding.encodingLimits.kspace_encoding_step_1.maximum + 1;
N slices = header.encoding.encodingLimits.slice.maximum + 1;
```

> 128 x 3 = 384, we have 9 additional data chunk

```
N_3D_encode = header.encoding.encodingLimits.kspace_encoding_step_2.maximum + 1;
N_average = header.encoding.encodingLimits.average.maximum + 1;
N_repetition = header.encoding.encodingLimits.repetition.maximum + 1;
N_contrast = header.encoding.encodingLimits.contrast.maximum + 1;
```

Not coming from additional encoding steps



c) Looking at Flags

➤ The additional data chunk can also come from parallel calibration, navigation data or phase correction data

```
parallel_calibration = data_struct.head.flagIsSet('ACQ_IS_PARALLEL_CALIBRATION');
navigation_data = data_struct.head.flagIsSet('ACQ_IS_NAVIGATION_DATA');
phase_corr_data = data_struct.head.flagIsSet('ACQ_IS_PHASECORR_DATA');

N_parallel_calibration = sum(parallel_calibration);
N_navigation_data = sum(navigation_data);
N_phase_corr_data = sum(phase_corr_data);
```

The 9 additional data chunk are phase correction readout used for ghost correction in EPI processing

Workspace		
Name ∠	Value	
data_struct	1x1 Acquisition	
🕩 filename	'/home/mygadg/	
🕕 header	1x1 struct	
H N_data_chunk	393	
N_navigation_data	0	
N_parallel_calibration	0	
N_phase_corr_data	9	
□ navigation_data	1x393 double	
→ parallel_calibration	1x393 double	
phase_corr_data	1x393 double	

d) Create kspace matrix

Here we will simply discard them and create a matrix with the image readout only

The size of the kspace matrix is: 256 readout points

128 phase encode

26 coils

3 slices

Command Window

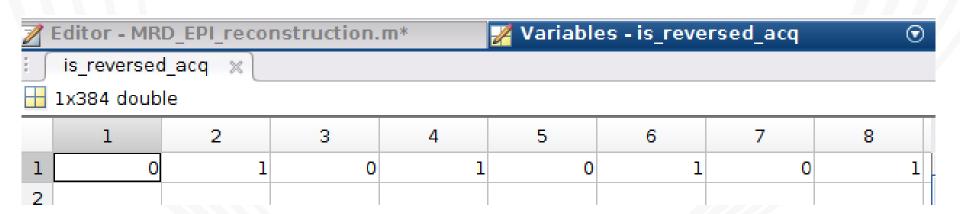
```
K>> size(kspace)
ans =
    256    128    26    3
```

e) is reversed flag

> In EPI the odd and even echoes are acquired in opposite direction

```
is_reversed_acq = data_struct.head.flagIsSet('ACQ_IS_REVERSE');
is_reversed_acq = is_reversed_acq(image_data);
kspace_flip = kspace;
kspace_flip (:,is_reversed_acq+1,:,:) = flip(kspace_flip (:,is_reversed_acq+1,:,:),1);
```

➤ This information is stored in the 'ACQ_IS_REVERSE' Flag and can be used to flip the readout



f) Fourier transform and oversampling

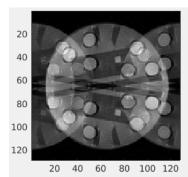
➤ A first approximation of the EPI images can be obtained by simple 2D Fourier transform

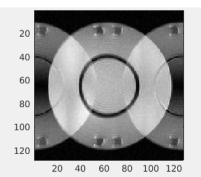
```
image_noRegrid = FFTKSpace2XSpace(FFTKSpace2XSpace(kspace_flip,1),2);
image_noRegrid = squeeze(sum(abs(image_noRegrid),3));
```

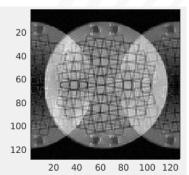
Oversampling can then be removed by cropping the image

```
if size(image_noRegrid,1)/header.encoding.encodedSpace.matrixSize.x(1,1) == 2
   image_noRegrid = image_noRegrid(round(size(image_noRegrid,1).*0.25)+1:
    round(size(image_noRegrid,1).*0.75),:,:);
end
```

```
figure()
subplot(1,3,1)
imagesc(image_noRegrid(:,:,1));
axis image
subplot(1,3,2)
imagesc(image_noRegrid(:,:,2));
axis image
subplot(1,3,3)
imagesc(image_noRegrid(:,:,3));
axis image
colormap gray
```







g) Regridding

- Readout acquisition is performed during the ramp time
- Gradient shape parameters are stored in user parameters

```
for ind = 1:size(header.encoding.trajectoryDescription.userParameterLong,2)
    parameters.(header.encoding.trajectoryDescription.userParameterLong(1,ind).name) =
header.encoding.trajectoryDescription.userParameterLong(1,ind).value;
end
for ind = 1:size(header.encoding.trajectoryDescription.userParameterDouble,2)
    parameters. (header.encoding.trajectoryDescription.userParameterDouble(1,ind).name)
= header.encoding.trajectoryDescription.userParameterDouble(1,ind).value;
end
parameters.readout = readout size;
parameters. N phase encode = N phase encode;
parameters.N phase recon = header.encoding.reconSpace.matrixSize.x(1,1);
parameters.N slices = N slices;
parameters.position = data struct.head.position(:,image data(1,1));
parameters.read dir = data struct.head.read dir(:,image data(1,1));
parameters.FOV 1 = header.encoding.encodedSpace.fieldOfView mm.x(1,1);
parameters.is reversed acq = is reversed acq;
```

g) Regridding

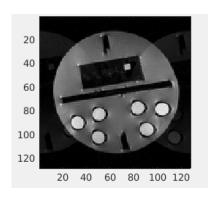
- RampUpTime, rampDownTime, flatTopTime are used to perform the regridding
- > The 'ACQ_IS_REVERSE' flag and the readout size will also be used

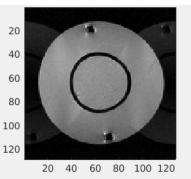
parameters × 1x1 struct with 16 fields		
☐ etl	128	
→ numberOfNavigators → numberOfNavigat	3	
⊞ ramp∪pTime	160	
☐ rampDownTime	160	
HatTopTime	370	
→ acqDelayTime	102	
→ numSamples	256	
dwellTime	1.9000	
⊞ readout	256	
■ N_phase_encode	128	
■ N_phase_recon	128	
☐ N_slices	3	
→ position	[19.6126;-12.5666;-6.5375]	
⊞ read_dir	[0;5.9605e-08;-1.0000]	
⊞ FOV_1	250	
⊞ is_reversed_acq	1x384 double	

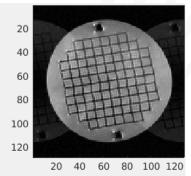
g) Regridding

- The function: EPI trapezoid regridding perform regridding, Fourier transform in dimension 1 and remove oversampling
- This allows to decrease ghost artefacts

```
[kspace corr] = EPI trapezoid regridding(parameters, kspace);
image Regrid = FFTKSpace2XSpace(kspace corr,2);
image Regrid = squeeze(sum(abs(image Regrid),3));
figure()
subplot(1,3,1)
imagesc(image Regrid(:,:,1));
axis image
subplot(1,3,2)
imagesc(image Regrid(:,:,2));
axis image
subplot(1,3,3)
imagesc(image Regrid(:,:,3));
axis image
colormap gray
```







Conclusion

- MRD is a versatile format for storing raw MR data and the parameters required for reconstruction
- It support large datasets
- ➤ The HDF file format allows easy interfacing with C/C++ python or Matlab reconstruction code
- ➤ ISMRMRD library provides tools for opening or viewing MRD datasets