READ ME

1. There are totally 8 functions, the final letter corresponds to the question letter

```
function obj = change_pos_and_orientation_h_5a(obj) %function for levitate and stay at 2.5...

function obj = change_pos_and_orientation_h_5b(obj) %function for levitate and stay at 2.5 ...

function obj = change_pos_and_orientation_h_5c(obj) %function for levitate and stay at 2.5 noise...

function obj = change_pos_and_orientation_h_5d(obj) %function for levitate and stay at 2.5 wind...

function obj = change_pos_and_orientation_circle_5a(obj) %function for circle trajectory with radius and altitude 2.5...

function obj = change_pos_and_orientation_circle_5b(obj) %function for circle trajectory with radius and altitude 2.5...

function obj = change_pos_and_orientation_circle_5c(obj) %function for circle trajectory with radius and altitude 2.5 noise...

function obj = change_pos_and_orientation_circle_5d(obj) %function for circle trajectory with radius and altitude 2.5 wind...
```

For example, to run 5a, in the orange circle should be "5a", to run 5b, in the orange circle should be "5b". 2 circled letters are required the same all the time.

```
function update(obj)
    %update simulation time
    obj.time = obj.time + obj.time_interval;
%change position and orientation of drone
    if obj.time >= 0 && obj.time <= obj.time2stop
        obj = change_pos_and_orientation_h_5a(obj);
end
    if obj.time > obj.time2stop
        obj = change_pos_and_orientation_circle_5a(obj);
end
```

After the change, leave the "Drone.m" and run the code in "quadcopter_script.m" to see the result.

- 2. For each time of simulation, please allow at least 250s to observe the result as our drone is relative slow.
- 3. Note that you may required to enter "move" twice to let the drone complete the task
- 4. For 5e, in the "Drone.m" function, use 5a function in both places, then exit "Drone.m" and run "quadcopter5e_script.m"
- 5. To increase the computation speed, we comment all the given animation command, if needed please uncomment them.