Zirui Liao

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School of Automation Science and Electrical Engineering (SASEE), Beihang University, Beijing 100191, P. R. China

EDUCATION

• School of Automation Science and Electrical Engineering, Beihang University

Sep. 2020 - Present Beijing, China

Ph. D. in Mechanical and Electronic Engineering

• GPA: 93.1/100 (Ranking: 1/93)

• Supervisor: Professor Shaoping Wang (Cheungkong Scholar) and Associate Professor Jian Shi

• Department of Electrical Engineering, Eindhoven University of Tehcnology

Oct. 2022 - Apr. 2024

Joint Supervision Project Supported by China Scholarship Council

Eindhoven, The Netherlands

Supervisor: Assistant Professors Zhiyong Sun and Sofie Haesaert

• College of Engineering, China Agricultural University (Project 985 Institution)

Sep. 2016 - Jun. 2020

B. S. in Mechanical and Electronic Engineering (Double Degree: English)

Beijing, China

GPA: 3.89/4.00 (Ranking: 1/53)Supervisor: Professor Jian Chen

RESEARCH INTEREST

- Resilient coordination for multi-agent systems
- · Resilient distributed optimization for cyber-physical systems
- · Static event-triggering, dynamic event-triggering, and self-triggering resilient algorithms
- Cooperative situational awareness based on multi-source data infusion

PUBLICATIONS AND PATENTS

J=JOURNAL, C=CONFERENCE, S=IN SUBMISSION, P=PATENT

Journal Papers

- [J.1] Z. Liao, S. Wang, J. Shi, S. Haesaert, Y. Zhang, and Z. Sun. Resilient containment under time-varying networks with relaxed graph robustness. *IEEE Transactions on Network Science and Engineering*, 2024, 11(5):4093-4105.
- [J.2] <u>Z. Liao</u>, S. Wang, J. Shi, M. Li, Y. Zhang, and Z. Sun. Resilient distributed optimization for cyber-physical systems under adversarial environments: an event-based method. *ISA Transactions*, 2024, 149:1-15.
- [J.3] Z. Liao, S. Wang, J. Shi, Y. Zhang, and Z. Sun. Resilient consensus through dynamic event-triggered mechanism. *IEEE Transactions on Circuits and Systems II: Express Briefs*, 2024, 71(7):3463-3467.
- [J.4] Z. Liao, S. Wang, J. Shi, Z. Sun, Y. Zhang, and MB. Sial. Cooperative situational awareness of multi-UAV system based on improved D-S evidence theory. *Aerospace Science and Technology*, 2023, 142: 108605.
- [J.5] Z. Liao, S. Wang, J. Shi, D. Liu and R. Chen. Reliability-oriented configuration optimization of more electrical control system. *Aerospace*, 2022, 9(2):85.
- [J.6] <u>Z. Liao</u>, J. Shi, S. Wang, Y. Zhang, R. Mu, and Z. Sun. **Self-triggering secure consensus against adversarial attacks**. *Guidance*, *Navigation and Control* (**Accepted**).
- [J.7] M. Sial, Y. Zhang, S. Wang, S. Ali, X. Wang, X. Yang, <u>Z. Liao</u>, and Z. Yang. <u>Bearing-based distributed</u> formation control of unmanned aerial vehicle swarm by quaternion-based attitude synchronization in three-dimensional space. *Drones*, 2022, 6(9):1-19.

Submitted Papers

- [S.1] Z. Liao, J. Shi, Y. Zhang, S. Wang, R. Chen, and Z. Sun. A leader-follower attack-tolerant algorithm for resilient rendezvous with reduced network redundancy. Manuscript submitted for publication in *IEEE Systems Journal* (Minor Revision).
- [S.2] Z. Liao, J. Shi, S. Wang, Y. Zhang, R. Chen, and Z. Sun. Dynamic event-triggering resilient coordination for time-varying heterogeneous network. Manuscript submitted for publication in *IEEE Transactions on Signal and Information Processing over Networks* (Major Revision).
- [S.3] Z. Liao, J. Shi, S. Wang, Y. Zhang, R. Mu, and Z. Sun. A survey of resilient coordination for cyber-physical systems against malicious attacks. Manuscript submitted for publication in *IEEE Internet of Things Journal* (Under Review).

Conference Papers and Abstracts

- Z. Liao, S. Wang, J. Shi, Z. Li, and MB. Sial. Cooperative situation awareness of multi-UAVs based on multi-sensor information fusion. In Proc. of the International Conference on Guidance, Navigation and Control (ICGNC), 2022, pp. 628-638.
- [C.2] Z. Liao, S. Wang, J. Shi, and Q. Weng. Differential evolution based multi-agent formation fault **reconstruction**. In *Proc. of the International Conference on Guidance, Navigation and Control (ICGNC)*, 2020, pp. 2273-2285.
- [C.3] M. Sial, S. Wang, X. Wang, J. Wyrwa, Z. Liao, and W. Ding. Mission oriented flocking and distributed **formation control of UAVs**. In Proc. of the IEEE Conference on Industrial Electronics and Applications (ICIEA), 2021, pp. 1507-1512.
- Z. Chen, S. Wang, C. Zhang, P. Zhang, and Z. Liao. Anthropomorphic flexible joint design and simulation. [C.4] In Proc. of the IEEE Conference on Industrial Electronics and Applications (ICIEA), 2020, pp. 1673-1678.
- J. Chen, N. Du, Z. Liao, Y. Cao, H. Meng, Y. Han, Y. Zheng, and Y. Tan. Energy storage battery parameters [C.5] identification algorithms of a solar powered communication/remote-sensing UAV. In Proc. of the 5th IFAC *Symposium on Telematics Applications*, 2019, 52(24):41-46.

Patents

- [P.1] Z. Liao, J. Shi, Z. Li, S. Wang, and Y. Qiao. A method and system for multi-UAV cooperative situation awareness based on information fusion, 2024, Patent No. ZL202210170253.8.
- J. Chen, S. Wang, Y. Han, Z. Zhang, G. Wang, N. Du, Y. Cao, H. Meng, Z. Liao, Y Wang, and Y Zheng. A device [P.2] and method for delivering multiple biological agents on UAV. 2019, Patent No. CN201910720188.X.
- J. Chen, S. Wang, Y. Han, G. Wang, Z. Zhang, N. Du, Y. Cao, H. Meng, Y Wang, Z. Liao, and Y Zheng. A UAV [P.3] airborne multi biological agent delivery device. 2019, Patent No. CN201921259931.8.

PROJECTS

- Project A: Resilient Coordination and Optimization for Multi-Agent Systems (MASs) Oct. 2022 - Apr. 2024 Support: Chinese Scholarship Council (Co-Supervised by Assistant Professors Zhiyong Sun and Sofie Haesaert)
 - Motivated by the critical security concern of MASs caused by distributed property and simple hardware, as well as being in open environments.
 - Developed attack-tolerant algorithms to address resilient consensus problems for heterogeneous MASs.
 - Optimized the network robustness with the introduction of trusted nodes and time-varying digraphs.
- Mitigated the communication burden with the introduction of dynamic event-triggering mechanism.
- Validated the effectiveness of the proposed method on multi-microgrid systems.
- Published 4 SCI journal papers ([J.1], [J.2], [J.3], [J.6]) and submitted 3 SCI journal papers ([S.1], [S.2], [S.3]) as the first author.
- Project B: Cooperative Situational Awareness for Multi-UAV Systems based on Data Fusion Dec. 2022 - Present Support: Outstanding Research Funding of Shenyuan Honors College (Project Leader)
 - · Motivated by the low detection accuracy of a single drone and the inability of existing data fusion methods to handle evidence conflicts.
- Developed a centralized cooperative situational awareness scheme based on D-S evidence theory.
- Improved the traditional D-S evidence theory to handle the high conflict between evidence.
- Prepare to validate the effectiveness of the proposed method on a practical multi depth camera platform.
- Published 1 SCI journal paper ([J.4]), 1 EI conference paper ([C.1]), and authorized a Chinese invention patent ([P.1]) as the first author.

HONORS AND AWARDS

• National Scholarship for Doctoral Students (Chinese Highest honor for University Students, Top 1%)	Oct. 2024
• Yuyuan Star (Highest Honor in the School of Automation Science and Electrical Engineering, Top 5%)	Oct. 2024

• President Scholarship for Outstanding Student Cadre (Highest Honor in Beihang University, Top 1%) Dec. 2022

 Outstanding Student Scholarship of Shenyuan Honors College *Mar.* 2023

Sept. 2021 and Sept. 2022 • First-class Academic Scholarship (Twice)

• First-class Freshman Scholarship Aug. 2020

• Outstanding Graduates of Beijing Municipality Jun. 2020

• Outstanding Graduation Project of Beijing Municipality *Jun.* 2020

• National Scholarship for Undergraduates (Twice, Top 1%) Nov. 2018 and Nov. 2019

• Outstanding Student Scholarship of China Agricultural University Nov. 2017

• First-class Academic Scholarship (Three Times) Nov. 2017, Nov. 2018, and Nov. 2019

• Second Prize of the National **Mathematics Competition** for College Students Nov. 2017 • First Prize of the Provincial and Ministerial Physics Competition for College Students Dec. 2017

• Third Prize of the National **English Competition** for College Students (Twice) Dec. 2018 and Dec. 2019

CONFERENCE PRESENTATIONS

• 9th International Conference on Guidance, Navigation, and Control (Oral Presentation in English)	Oct. 2020
• 10th International Conference on Guidance, Navigation, and Control (Oral Presentation in English)	Aug. 2022
• 42nd Benelux Meeting on Systems and Control (Oral Presentation in English)	Mar. 2023
• 43rd Benelux Meeting on Systems and Control (Oral Presentation in English)	Mar. 2024
• 43rd Chinese Control Conference (Oral Presentation in English)	Jul. 2024

ADDITIONAL INFORMATION

Languages: Chinese (native), English (CET-4: 582, CET-6: 579, double degree)

Interests: Badminton, Frisbee, Table Tennis

ACADEMIC SERVICE

• Journal and Conference Reviewer

Active reviewer for several journal and conferences, such as:

- ISA Transactions
- American Control Conference (ACC)
- International Conference on Guidance, Navigation, and Control (ICGNC)
- CSAA/IET International Conference on Aircraft Utility Systems (AUS)

• Conference Volunteer

• 9th International Conference on Guidance, Navigation, and Control

REFEREES

1. Shaoping Wang

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Beihang University, Beijing 100191, P. R. China

Email: shaopingwang@buaa.edu.cn Relationship: Doctoral Supervisor

2. Jian Shi

Associate Professor, School of Automation Science and Electrical Engineering

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Email: shijian@buaa.edu.cn Relationship: Doctoral Co-Supervisor

3. Zhiyong Sun

Assistant Professor, College of Engineering

Peking University, Beijing 100091, P. R. China

Email: zhiyong.sun@pku.edu.cn Relationship: Project Supervisor

4. Sofie Haesaert

Assistant Professor, Department of Electrical Engineering

Eindhoven University of Technology, Eindhoven 5600 MB, The Netherlands

Email: S.Haesaert@tue.nl Relationship: Project Supervisor

5. Jian Chen

Professor, College of Engineering

China Agricultural University, Beijing 100083, P. R. China

Email: jchen@cau.edu.cn

Relationship: Undergraduate Supervisor