Optimization of Target Values in an Artificial Neural Network

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Recap: Definitions

- Target values → expected output a neural Network is trained to produce for a specific given input
- Class values → values assigned to the correct class position in the target vector
- Non-class values → values used for all incorrect class positions in the target vector

Bi-directional σ -Adaptation

```
\lambda \leftarrow 1 (default), tunable in [0, \infty)
```

Steps:

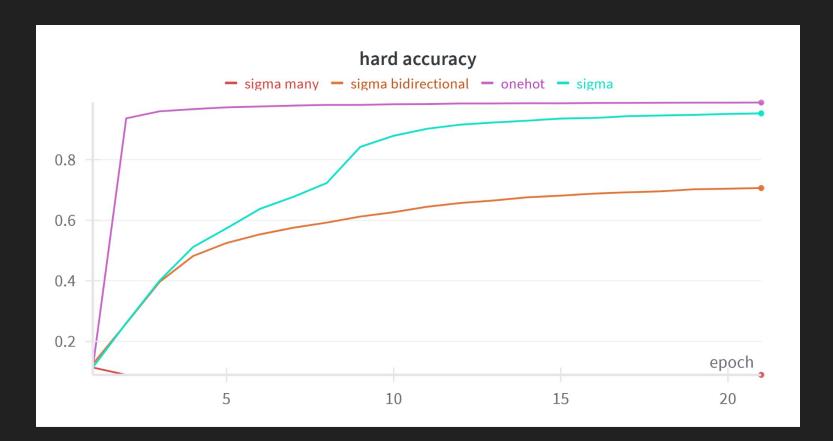
- 1. Compute the sum of standard deviations for current outputs: σ_{sum}
- 2. For every class ensure:
 - All values remain within [0, 1]
 - \circ |class non-class| $\geq \sigma_{\text{sum}}$
- 3. If too close:
 - Adjust non-class output by ±λσ_{sum} (increase if non-class ≥ class, otherwise decrease)
- 4. If this would exceed bounds clip to 0 or 1

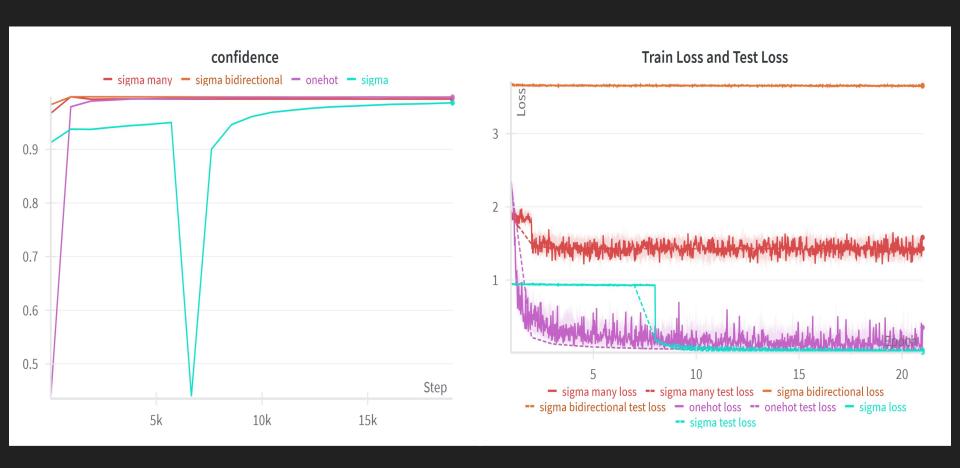
We can define the scaling factor λ separately for the initial pre-training run.

Changes and Challenges

- Each class now has its own non-class value
 - Less values near any non-class value which can cause a shift
 - → too few shifts to allow for training
- Switched to Sigmoid from ReLU
- Disable λ to simplify shifting
 - \circ Shift distance is always $\sigma_{sum} \rightarrow$ shifts that do happen are too small

Results





Next Steps

- Create more space between class and non-class values
 - Push apart initially by some amount?
 - Find a better metric than σ_{sum} ?

- More readable logging for class/non-class values
 - \circ Visualize all class / non-class value pairs + their σ_{sum} individually
 - Plot all distances in one graph

• Force distance to always be exactly σ_{sum} when pushing (?)