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CS 261, Winter 2012

3/14/12

Assignment 7

1.

```
1 //Dynamic array implementation
2 //Function that removes the key before inserting new one.
3
4 void putMap (struct hashMap * ht, KeyType k, ValueType v){
5     int idx;
6
7     //check to see if map contains key. If so, remove it.
8     if(containsKey(ht, k)){
9         removeKey(ht, k);
10    }
11
12    idx = stringHash1(k) % ht->tableSize;
13
14    if(idx < 0){
15        idx += ht->tableSize;
16    }
17
18    //Iterate through values in the loop to find the correct spot.
19    while(ht->table[idx] != 0){
20        idx++;
21    }
22
23    ht->table[idx] = v;
24    ht->count++;
25 }
26
27 //Function that replaces value
28
29 void putMap (struct hashMap * ht, KeyType k, ValueType v){
30     if(!containsKey(ht, k)){ //If it doesn't contain the key, find the correct spot
31         int idx = stringHash1(k) % ht->tableSize;
32
33         if(idx < 0){
34             idx += ht->tableSize;
35         }
36         while(ht->table[idx] != 0)
37             idx++;
38         ht->table[idx] = v;
39         ht->count++;
40     } else {
41         int* value = atMap(&hashTable, word);
42         *value = v;
43     }
44 }
```

The first implementation is easier to understand, but the second will be faster because it potentially doesn't iterate through the table as many times.

2. In a table with a vector size of 6, Alan's name would hash to the same key (0) as Amy's, causing a hash collision. If the size were increased to 7, "Amy" and "Andy" would both hash to 3.

3. a)

Name	Third letter	Hash value (mod 6)
Abel	E	4
Adam	A	0
Albert	B	1
Amanda	A	0
Angela	G	0
Arnold	N	1
Abigail	I	2
Adrian	R	5
Alex	E	4
Amy	Y	0
Anita	I	2
Arthur	T	1
Abraham	R	5
Adrienne	R	5
Alfred	F	5
Andrew	D	3
Anne	N	1
Audrey	D	3
Ada	A	0
Agnes	N	1
Alice	I	2
Andy	D	3
Antonia	T	1

b) Table with 5 Buckets:

Index	0	1	2	3	4
Assigned values	afkpuz	bglqv	chmrw	dinsx	Eqoty
Number of elements assigned to bucket	4	2	3	9	5

Table with 11 Buckets

Index	0	1	2	3	4	5	6	7	8	9	10
Assigned values	alw	bmx	cny	doz	ep	fq	gr	hs	it	ju	kv
Number of elements assigned to bucket	3	1	4	3	2	1	4		5		

c) Load factor (table with size 5) = $5/5 = 1$. Load factor (table with size 11) = $8/11 = .73$.

4. `int index = (int) Math.sin(value)` is a bad choice because, due to the constraints of being cast as an integer, “index” will always be either 0, -1, or 1 (but will usually be 0). This will most definitely cause hash collisions (and segmentation faults in the event of trying to access a negative integer position in a table after the function returns -1).

5. (Almost) Perfect hash functions for days of week and months of year:

Day of week	First letter value (x)	Second letter value (y)	First letter value (z)	Word length (len)	Hash function: $(1x + 2y + 3z + \text{len}) \% 10$
Sunday	18	20	13	6	3
Monday	12	14	13	6	5
Tuesday	19	20	4	7	8
Wednesday	22	4	3	9	8
Thursday	19	7	20	8	1
Friday	5	17	8	6	9
Saturday	18	0	19	8	3

Month	First letter value (x)	Second letter value (y)	Third letter value (z)	Hash function: $(1x + 2y + 3z) \% 15$
January	9	0	13	3
February	5	4	1	1
March	12	0	17	3
April	0	15	17	6
May	12	0	24	9
June	9	20	13	13
July	9	20	11	7
August	0	20	6	13
September	18	4	15	11
October	14	2	19	0
November	13	14	21	14
December	3	4	2	2

6. Adjacency Matrix

Node	1	2	3	4	5	6	7	8
1	1	1	0	1	0	0	0	0
2	0	1	1	0	0	0	0	0
3	0	0	1	0	1	1	0	0
4	0	0	0	1	1	0	0	0
5	0	0	0	0	1	0	0	0
6	0	0	0	0	0	1	1	1
7	0	0	0	0	1	0	1	0
8	0	0	0	0	0	0	0	1

Edge List:

1: {2, 4}

2: {3}

3: {5, 6}

4: {5}

5: {}

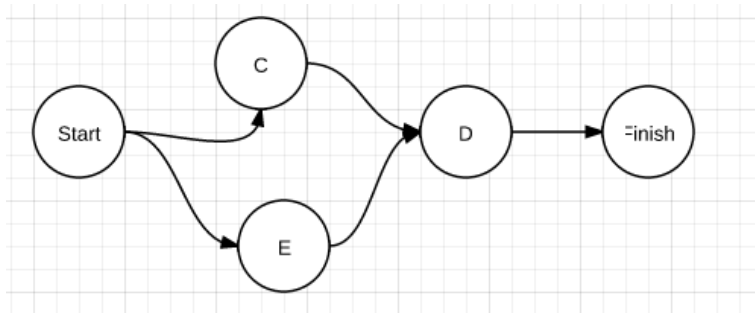
6: {7, 8}

7: {5}

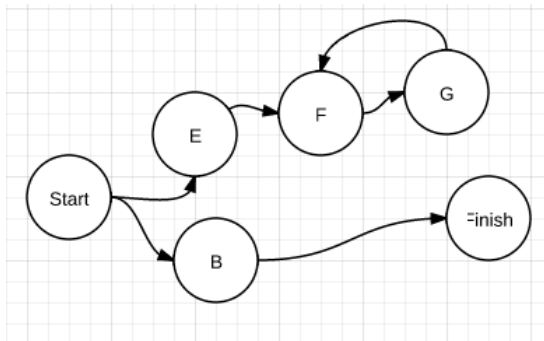
8: {}

7. In these graphs, assume DFS visits next vertex in order of greatest alphabetical position.

DFS will finish before BFS:



BFS will finish before DFS:



8. DFS

Step	Stack	Reachable
0	1	
1	6,2	1
2	11,2	1, 6
3	16, 12, 2	1, 6, 11
4	21, 12, 2	1, 6, 11, 16
5	22, 12, 2	1, 6, 11, 16, 21
6	23, 17, 12, 2	1, 6, 11, 16, 21, 22
7	17, 12, 2	1, 6, 11, 16, 21, 22, 23
8	12, 12, 2	1, 6, 11, 16, 21, 22, 23, 17
9	13, 12, 2	1, 6, 11, 16, 21, 22, 23, 17, 12
10	18, 8, 12, 2	1, 6, 11, 16, 21, 22, 23, 17, 12, 13
11	8, 12, 2	1, 6, 11, 16, 21, 22, 23, 17, 12, 13, 18
12	Continues this way...	Continues this way...

BFS

Step	Queue	Reachable
0	1	
1	2, 6	1
2	6, 3, 7	1, 2
3	3, 7, 11	1, 2, 6
4	7, 11, 4, 8	1, 2, 6, 3
5	11, 4, 8	1, 2, 6, 3, 7
6	4, 8, 12, 16	1, 2, 6, 3, 7, 11
7	8, 12, 16, 5, 9	1, 2, 6, 3, 7, 11, 4
8	12, 16, 5, 9, 13	1, 2, 6, 3, 7, 11, 4, 8
9	16, 5, 9, 13, 13, 17	1, 2, 6, 3, 7, 11, 4, 8, 12
10	5, 9, 13, 13, 17, 21	1, 2, 6, 3, 7, 11, 4, 8, 12, 16
11	9, 13, 13, 17, 21, 10, 14	1, 2, 6, 3, 7, 11, 4, 8, 12, 16, 5
12	13, 13, 17, 21, 10, 14	1, 2, 6, 3, 7, 11, 4, 8, 12, 16, 5, 9
13	13, 17, 21, 10, 14, 18	1, 2, 6, 3, 7, 11, 4, 8, 12, 16, 5, 9, 13
14	Continues this way...	Continues this way...

9.

<u>Queue</u>	<u>Reachable</u>
Pensacola: 0	
Phoenix: 5	Pensacola: 0
Pueblo: 8, Peoria: 9, Pittsburgh: 15	Phoenix: 5
Peoria: 9, Pierre: 11, Pittsburgh: 15	Pueblo: 8
Pierre: 11, Pueblo: 12, Pittsburgh: 14, Pittsburgh: 15	Peoria: 9
Pueblo: 12, Pendleton: 13, Pittsburgh: 14, Pittsburgh: 15	Pierre: 11
Pendleton: 13, Pittsburgh: 14, Pittsburgh: 15	
Pittsburgh: 14, Pittsburgh: 15, Phoenix: 19, Pueblo: 21	Pendleton: 13
Pittsburgh: 15, Pensacola: 18, Phoenix: 19, Pueblo: 21	Pittsburgh: 14
Pensacola: 18, Phoenix: 19, Pensacola: 19, Pueblo: 21	
Phoenix: 19, Pensacola: 19, Pueblo: 21	
Pensacola: 19, Pueblo: 21	
Pueblo: 21	

10. The purpose of Dijkstra's algorithm is to find the shortest path to various vertices. This can only be done if the next-shortest path is chosen from a prioritized queue that orders path lengths from least-to-greatest, not in any arbitrary stack or queue.

11. Assuming e , the number of edges, is greater than the number of vertices, an edge-list representation of a graph requires $O(e)$ storage.

12. An adjacency matrix of a graph with V vertices requires $O(V^2)$ spaces.

13. A breadth-first search is guaranteed to find the solution. A depth-first search will run until it reaches a dead-end. In this case, that may mean that it will run through an infinite path toward that dead end. A breadth-first search, on the other hand, explores all paths simultaneously. Accordingly, if there is a finite path to the end, the breadth-first search will find it.