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```
%%Lab 3
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% 2012-10-25
lib = make_lib();
% make_lib:
%function lib = make_lib()
 lib.f = (x^5) - (x^4) + x - 1;
 lib.fp = (5 * (x ^4)) - (4 * (x ^3)) + 1';
 lib.the_root = 1;
 lib.accuracy = 5E-6;
%end
```

1.

```
disp(sprintf('\nBisection Method Table:'));
disp(sprintf('Initial Interval \t Approximation \t\t\t Error \t\t Iterations'));
x0 = 0;
x1 = 3;
[it_count, root, xn] = bisect('x^5-x^4+x-1',x0,x1,lib.accuracy,100);
disp(sprintf('%g to %g \t\t\t %0.10f \t\t\ %d', x0, x1, root, lib.the_r)
x0 = 0.5;
x1 = 2;
[it_count, root, xn] = bisect('x^5-x^4+x-1',x0,x1,lib.accuracy,100);
disp(sprintf('%g to %g \t\t\t %0.10f \t\t\ %d', x0, x1, root, lib.the_r)
x0 = 0.9;
x1 = 1.2;
[it_count, root, xn] = bisect('x^5-x^4+x-1',x0,x1,lib.accuracy,100);
disp(sprintf('%g to %g \t\t\t %0.10f \t\t %0.10f \t\t %d', x0, x1, root, lib.the_r
%a. The second interval needs one fewer iteration because, by starting at
%0.5, it reduces the size of the initial interval and makes the initial midpoint c
%b. Yes, there is an advantage to having the root closer to the midpoint of
%the interval. This is because the bisection method works by splitting the
%interval in two and evaluating the function at that midpoint. As
%demonstrated by running the bisect() function, when the midpoint of the
%initial interval was 1.5, 19 iterations were required. When this midpoint
```

%was 1.25, 18 iterations were required. When this midpoint was reduced to

%1.25, only 15 iterations were required.

```
Bisection Method Table:
Initial Interval
                  Approximation
                                     Error
                                              Iterations
                          0.0000009537
                                           19
          0.9999990463
0 to 3
0.5 to 2
             1.0000009537
                             -0.0000009537
                                              18
0.9 to 1.2
               0.9999984741
                               0.0000015259
                                               15
```

2.

```
disp(sprintf('\nNewton Method Table:'));
disp(sprintf('Initial Iterate \t Approximation \t\t Error \t\t Iterations'));
x0 = -100;
[it count, root, xn] = newton('x^5-x^4+x-1','5*x^4-4*x^3+1', x0,1.0e-6,100);
disp(sprintf('%g \t\t\ %0.10f \t\t %0.10f \t\t %d', x0, root, lib.the_root - root
x0 = 0;
[it\_count,root,xn] = newton('x^5-x^4+x-1','5*x^4-4*x^3+1',x0,1.0e-6,100);
disp(sprintf('%g \t\t\ %0.10f \t\t %0.10f \t\t %d', x0, root, lib.the_root - root
x0 = 0.9;
[it count, root, xn] = newton('x^5-x^4+x-1','5*x^4-4*x^3+1', x0,1.0e-6,100);
disp(sprintf('%g \t\t\ %0.10f \t\t %0.10f \t\t %d', x0, root, lib.the_root - root
x0 = 0.99;
[it\_count,root,xn] = newton('x^5-x^4+x-1','5*x^4-4*x^3+1',x0,1.0e-6,100);
disp(sprintf('%g \t\t %0.10f \t\t %0.10f \t\t %d', x0, root, lib.the_root - root
x0 = 1.1;
[it\_count,root,xn] = newton('x^5-x^4+x-1','5*x^4-4*x^3+1',x0,1.0e-6,100);
disp(sprintf('%g \t\t %0.10f \t\t %0.10f \t\t %d', x0, root, lib.the_root - root
[it\_count,root,xn] = newton('x^5-x^4+x-1','5*x^4-4*x^3+1',x0,1.0e-6,100);
disp(sprintf('%g \t\t %0.10f \t\t %0.10f \t\t %d', x0, root, lib.the_root - root
x0 = 1000000;
[it\_count,root,xn] = newton('x^5-x^4+x-1','5*x^4-4*x^3+1',x0,1.0e-6,100);
disp(sprintf('%g \t\t %0.10f \t\t %0.10f \t\t %d', x0, root, lib.the_root - root
% a. The Newton Method is very efficient compared to the Bisection method
% when the initial iterate is close to the root. When it was within .01 of
% the actual root, it only required 3 iterations to find it to the required
% accuracy.
% b. The errors are less than 10^-12 because the Newton method converges
% quadratically, so the number of correct digits roughly at least doubles
% in every step.
% c. For bisection, numIterations >= log((b-a)/epsilon)/log(2).
% This comes to 60 when calculated. This is more efficient than Newton's
% Method, which takes 67 iterations for an initial iterate of 1000000.
       Newton Method Table:
```

Approximation

0.0000000000

0.0000000000

Error

2

28

Iterations

Initial Iterate

1.0000000000

1.0000000000

-100

```
0.9
       1.0000000000
                        0.0000000000
0.99
        1.0000000000
                        -0.0000000000
                                          3
        1.0000000000
                       -0.0000000000
1.1
                                         4
1.4
       1.0000000000
                        -0.0000000000
1e+06
         1.0000000000
                         -0.0000000000
                                          67
```

3.

```
disp(sprintf('\nSecant Method Table:'));
disp(sprintf('Interval \t Approximation \t\t Error \t\t Iterations'));
x0 = 0;
x1 = 3;
[it_count,root,xn] = secant('x^5-x^4+x-1',x0,x1,1.0e-6,100);
disp(sprintf('%g to %g \t\t\t %0.10f \t\t\ %0.10f \t\t\ %d', x0, x1, root, lib.the_r
x0 = 0.5;
x1 = 2.0;
[it\_count,root,xn] = secant('x^5-x^4+x-1',x0,x1,1.0e-6,100);
disp(sprintf('%g to %g \t\t\t %0.10f \t\t %0.10f \t\t %d', x0, x1, root, lib.the_r
x0 = 0.9;
x1 = 1.2;
[it_count, root, xn] = secant('x^5-x^4+x-1', x0, x1, 1.0e-6, 100);
disp(sprintf('%g to %g \t\t\t %0.10f \t\t\ %0.10f \t\t\ %d', x0, x1, root, lib.the_r
% a. The Secant Method is more efficient than the Bisection Method when the
% initial interval is closer to the root, but less efficient than the
% Newton Method.
% b. No. The interval from 0-3 and .9-1.2 both take 6 iterations to find
% the root in the Secant Method where the Bisection Method took 19 and 15
% iterations on the respective intervals.
```

Secant Method Table:

```
Interval Approximation Error Iterations
0 to 3    1.0000000000   -0.0000000000 6
0.5 to 2    1.0000000000    0.0000000000 10
0.9 to 1.2    1.0000000000    -0.0000000000 6
```

4.

```
disp(roots(poly(1:21))); 
 % The poly() function creates a polynomial whose coefficients correspond to 
 % the input values. In this case, this polynomial is (x-1)(x-2)...(x-21). 
 % Roots finds the roots of this polynomial. It finds the first 6 roots 
 % correctly, but then gradually becomes less and less accurate. This is 
 % because at the lower-order variables of the polynomial, the function and 
 % the derivative will be close together, producing low error. At the higher 
 % order variables, the function and derivative will be further apart, 
 % producing high error when evaluated using Newton's Method.
```

20.9968 20.0300 18.8029

```
18.3718
16.5702 + 0.5780i
16.5702 - 0.5780i
14.4596 + 0.6308i
14.4596 - 0.6308i
12.4147 + 0.3075i
12.4147 - 0.3075i
10.8665
10.0537
 8.9869
 8.0028
 6.9996
 6.0000
 5.0000
 4.0000
 3.0000
 2.0000
 1.0000
```

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