

Note for Regularization Paths for Generalized Linear Models

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Instruction: Derivation for two-class classification.

1 Linear regression:

- 1.1 basis
- 1.2 derivation

1.1 definition

$$probability : Pr(y = 1|x) = \frac{1}{1 + e^{-(\beta_0 + \sum_{i=1}^m \beta_i x_i)}}$$

$$likelihood : L = \prod_{i=0}^n p(x_i)^{y_i} * [1 - p(x_i)]^{1-y_i}$$

$$P_{\alpha}(\beta) = \sum_{j=1}^m \left[\frac{1}{2} (1 - \alpha) \beta_j^2 + \alpha |\beta_j| \right]$$

1.2 derivation

Based on definition, penalized log-likelihood can be presented as follow.

$$L = \sum_i^n \{y_i \log(p(x_i)) + (1 - y_i) \log(1 - p(x_i))\} - \sum_{j=1}^m \left[\frac{1}{2} (1 - \alpha) \beta_j^2 + \alpha |\beta_j| \right]$$

Note that the first part can be written as follow.

$$\begin{aligned}
L &= \sum_{i=1}^n [\log(1 - p(x_i)) + y_i \log \frac{p(x_i)}{1 - p(x_i)}] \\
&= \sum_{i=1}^n [y_i(\beta_0 + \sum_{i=1}^m \beta_i x_i) + \log(\frac{e^{-(\beta_0 + \sum_{i=1}^m \beta_i x_i)}}{1 + e^{-(\beta_0 + \sum_{i=1}^m \beta_i x_i)}})] \\
&= \sum_{i=1}^n [y_i(\beta_0 + \sum_{i=1}^m \beta_i x_i) - \log(1 + e^{(\beta_0 + \sum_{i=1}^m \beta_i x_i)})]
\end{aligned}$$

Using quadratic approximation(taylor expansion), The log-likelihood can be written as follow.

$$\begin{aligned}
l_Q &= -\frac{1}{2} \sum_{i=1}^N w_i (z_i - \beta_0 - \sum_{i=1}^m \beta_i x_i)^2 + C(\hat{\beta}_0, \hat{\beta})^2 \\
z_i &= \hat{\beta}_0 + \sum_{i=1}^m \hat{\beta}_i x_i + \frac{y_i - \hat{p}(x_i)}{\hat{p}(x_i)(1 - \hat{p}(x_i))} \\
w_i &= \hat{p}(x_i)(1 - \hat{p}(x_i))
\end{aligned}$$

Using coordinate descent to solve the penalized weighted least-squares problem, which is

$$\min_{\beta_0, \beta} \{-l_q(\beta_0, \beta) + \lambda P_\beta\}$$

derive derivative to solve this problem, for $\beta_j, j \neq 0$:

$$\begin{aligned}
part_1 &= \frac{\partial L}{\partial \beta_j} = \sum_{i=1}^N w_i [z_i - (\beta_0 + \sum_{j=1}^m \beta_j x_{ij})] x_{ij} \\
&= \sum_{i=1}^N w_i [z_i - (\beta_0 + \sum_{k \neq j}^m \beta_k x_k)] x_{ij} - \sum_{i=1}^N w_i x_{ij}^2 \beta_j \\
&= \sum_{i=1}^N w_i [\hat{\beta}_j x_{ij} + \frac{y_i - \hat{p}(x_i)}{\hat{p}(x_i)(1 - \hat{p}(x_i))}] x_{ij} - \sum_{i=1}^N w_i x_{ij}^2 \beta_j \\
&= \sum_{i=1}^N [w_i x_{ij}^2 \hat{\beta}_j + (y_i - \hat{p}(x_i)) x_{ij}] - \sum_{i=1}^N w_i x_{ij}^2 \beta_j \\
\text{denotation, } P &= \sum_{i=1}^N w_i x_{ij}^2, Q = \sum_{i=1}^N x_{ij} (y_i - \hat{p}(x_i)) \\
&= P * \hat{\beta}_j + Q - P * \beta_j
\end{aligned}$$

Now, derive the penalty part.

$$\frac{\partial P_\alpha(\beta)}{\partial \beta_j} = \sum_{j=1}^m [(1 - \alpha) \beta_j + \alpha |\beta_j|]$$

Using Subderivative, the equation can be written as follow.

$$part_2 = \frac{\partial P_\alpha(\beta)}{\partial \beta_j} = [(1 - \alpha)\beta_j + \alpha \partial |\beta_j|]$$

$$= \begin{cases} (1 - \alpha)\beta_j + \alpha, & \beta_j > 0 \\ [(1 - \alpha)\beta_j - \alpha, (1 - \alpha)\beta_j + \alpha], & \beta_j = 0 \\ (1 - \alpha)\beta_j - \alpha, & \beta_j < 0 \end{cases}$$

to find the minimum point, $-part_1 + \lambda part_2 = 0$, which is

$$0 = \begin{cases} \lambda[(1 - \alpha)\beta_j + \alpha] - (P\hat{\beta}_j + Q - P\beta_j), & \beta_j > 0 \\ \{\lambda[(1 - \alpha)\beta_j - \alpha] - (P\hat{\beta}_j + Q - P\beta_j), \lambda[(1 - \alpha)\beta_j + \alpha] - (P\hat{\beta}_j + Q - P\beta_j)\}, & \beta_j = 0 \\ \lambda[(1 - \alpha)\beta_j - \alpha] - (P\hat{\beta}_j + Q - P\beta_j), & \beta_j < 0 \end{cases}$$

Take $\beta_j > 0$ as an example.

$$\lambda(1 - \alpha)\beta_j + \alpha\lambda - (P\hat{\beta}_j + Q - P\beta_j) = 0$$

$$\beta_j = \frac{Q - \lambda\alpha + P\hat{\beta}_j}{P + \lambda(1 - \alpha)}$$

$$condition : Q + P\hat{\beta}_j > \lambda\alpha$$

Implmentation as follow

```

1 from joblib import Parallel, delayed
2 import gc
3 import numpy as np
4 import pandas as pd
5
6
7 class Lasso_CR(object):
8     def __init__(self, **kwargs):
9         self.beta = 0
10        self.intercept = 0
11        self.lambda_ = 0
12        self.max_iter = 500
13
14    def standardize(self, data):
15        return (data - data.mean(axis = 0))/data.std(axis = 0)
16
17    def soft_thresholding(self, beta_old, P, Q, threshold):
18        if P * beta_old + Q > threshold:
19            beta_new = beta_old + (Q - threshold)/P
20        elif P * beta_old + Q < - threshold:
21            beta_new = beta_old + (Q + threshold)/P

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22         else:
23             beta_new = 0
24         return beta_new
25     def coordinate_descent(self, x, y, beta, intercept, lambda_):
26         def process_helper(x):
27             x = np.where(x > 1 - 10**-5, 1 - 10**-5, x)
28             x = np.where(x < 10**-5, 10**-5, x)
29             return x
30         for j in range(len(beta)):
31             linear = intercept + np.sum(beta * x, axis = 1)
32             prob = 1/(1 + np.exp(-linear))
33             prob = process_helper(prob)
34             w = prob * (1 - prob)
35             P = np.mean(w * (x[:, j] ** 2))
36             Q = np.mean((y - prob) * x[:, j])
37             beta[j] = self.soft_thresholding(beta[j], P, Q, lambda_)
38
39             linear = intercept + np.sum(beta * x, axis = 1)
40             prob = process_helper(1/(1 + np.exp(-linear)))
41             w_ = prob * (1 - prob)
42             dir_ = y - prob
43             intercept_new = intercept + np.mean(dir_)/np.mean(w)
44         return beta, intercept_new
45
46     def fit(self, X, y):
47         X_std = self.standardize(X)
48         max_iter = 1000
49         self.beta = np.ones(X.shape[1])/X_std.shape[1]
50         self.intercept = 0
51         for iteration in range(max_iter):
52             self.beta, self.intercept = self.coordinate_descent(X_std, y, self.beta, self.intercept, lambda_)
53     def predict_proba(self, X):
54         linear = self.intercept + np.sum(self.beta * X, axis = 1)
55         prob = 1/(1 + np.exp(-linear))
56         return prob
57     def predict(self, X):
58         linear = self.intercept + np.sum(self.beta * X, axis = 1)
59         prob = 1/(1 + np.exp(-linear))
60         return np.where(prob > 0.5, 1, 0)

```